## BIRLA INSTITUTE OF TECHNOLOGY AND SCIENCE, PILANI

# HYDERABAD CAMPUS SECOND SEMESTER 2017-2018

#### **Course Handout**

07-01-2019

Course No. : INSTR F343

Course Title : Industrial Instrumentation & Control

Instructor-in-charge : Balasubramanian M Instructor : Balasubramanian M

# 1. Scope and Objective of the course

This course offers study of various aspects of automatic control for industrial processes, including some recent developments in the field of process control.

# 2. Course Description:

Introduction to process control; Elements of process loop; Controller principle; Hydraulic, pneumatic, electronic controllers; Controller tuning; Final control elements; Control loop characteristics; Complex control systems; Intelligent controllers; Programmable logic controllers; Distributed control systems; Digital control principles;

### 3. Text Book:

Surekha Bhanot, *Process Control: Principles and Applications*, Oxford University press, Fourth Impression 2010

#### 4. Reference Book:

R1 C.D. Johnson, *Process Control Instrumentation Technology*, Prentice Hall of India, New Delhi , 1993

R2 Liptak B.G., *Process Control: Instrument Engineer's handbook*, Butterworth Heinemann

R3 Krishan Kant, *Computer Based Industrial Control*, Prentice Hall of India, New Delhi, 1997

R4 Stephanopoulos George, *Chemical Process Control*, Prentice Hall of India R5 Ogata K., *Modern Control Engineering*, Pearson Education Asia

## 5. Course plan

Lecture No.	Learning Objective	Topics to be covered	Chapter in the Text Book
1,2	To appreciate the needs,	Basic Control loop,	T-CH1
	objectives of process control	variables, requirements,	R4(1.9)
		aims, parameters,	
		dynamics of the process	
3	To understand the dynamics of	Terms, concepts used in	T-CH2
	processes	process dynamics	
4	To understand/review the	Transfer functions, block	R5-CH4
	concepts of Transfer function	diagram and signal flow	
		representation	
5	To understand need and	Model of lumped and	T-CH2, R3 –

	concept of mathematical modeling	distributed parameter systems	CH11, R5- CH2,3&4	
6,7	To understand steady state and transient analysis	Transient and steady state analysis of first order, second order and higher order systems and numerical to highlight concepts	R5-CH5	
8	To understand different controller modes	On-off, on-off with neutral zone	T-CH3 , R4(9), R3 – CH1	
9,10	To understand different controller modes	Proportional, Integral, derivative, PI, PD, PID	T-CH3, R4(9), R3 – CH1	
11,12	To learn dynamic behavior of feedback controlled systems	Effect on dynamic behavior of process with different controller modes in closed loop with	T-CH4, R4(14)	
13	To learn about controller tuning	Ziegler, Cohen-Coon, Integral performance	T-CH4, R4	
14	To learn about DDC loop	Sampling and reconstruction, DDC structure, position & velocity algorithm	T-CH5	
15	To realize controller modes in pneumatic controllers	To realize controller modes in Controller modes in		
16	To realize controller modes in hydraulic controllers	Controller modes in Hydraulic controllers	T-CH6, R5 (4.4)	
17	To realize controller modes in electronic controllers	Controller modes in Electronic controllers	T- CH7, R1(10.3)	
18,19	To learn the evolution, hardware of Programmable Logic Controllers	PLC vs relay Logic, PLC vs PCs, hardware components	T-CH13, R3(5),R2	
20,21	To learn ladder diagram programming	Ladder diagram, selection of PLCs	T-CH13, R3(5),R2	
22	To learn application of AI techniques in process control	Role of AI	T-CH14, R3(13),R2	
23,24	To learn ES structure & Application	ES structure, Design & Applications	T-CH15, R3(13)	
25,26	To ANN concepts	Neural networks – structure, applications	T-CH16, R3(18), R2	
27,28	Learning algorithms	BPA, learning	T-CH16, R3,	
29	Case studies			
30,31	To learn concept & applications of FLC			
32	To learn about different final control elements	Functions of control valves, Types of control	R3(13),R2 T-CH8, R3 – CH4	

		valves, actuators	
33	To understand P&I diagrams	Draw P&I diagrams	Т-СН9
34,35	To understand complex control	Cascade control, Ratio	T-CH10,
	schemes	control,	R4(20, 21)
36	To understand complex control	Feedforward, Adaptive	T-CH10, R4
	schemes	control, Inferential, Model	(21)
		reference adaptive control,	
		Self tuning regulator	
37-38	To understand complex control	Override, Auctioneering,	T1-CH11,
	schemes	Split Range	R4(22)
39-40	To understand interaction and	Design of cross controllers	T-CH12,
	decoupling of control loops	and selection of loops	R4(24)
		using RGA	
41-42	To understand distributed	History, functional	T-CH18,
	1 1 2 1 1 1	roquiromonto evetom	R3(6),R2
	digital control systems	requirements, system	K3(0),K2

## 6. Evaluation Scheme

Components	Duration	Weightage	Marks	Date&Time	Remarks
Mid-Sem Test	90 mts	30%	75		Closed
				14/3 9.00 - 10.30AM	Book
Surprise Quiz	-	10%	30	3.00 10.30/11/1	Closed
_					Book
Assignment	-	20%	60		Open Book
Comprehensive	3 Hrs	40%	120		Closed
					Book
Total		100%	300	08/05 FN	

- 7. **Chamber Consultation Hour** : To be announced in the class.
- 8. **Course Notices:** Notices will be displayed in CMS.
- 9. **Make-up Examination**: Make-up will be given on extremely genuine grounds only. Prior application and approval should be made for seeking the make-up examination
- 10. **Academic Honesty and Integrity Policy:** Academic honesty and integrity are to be maintained by all the students throughout the semester and no type of academic dishonesty is acceptable.

Instructor-in-charge INSTR F343