## EE25BTECH11003 - Adharvan Kshathriya Bommagani

### **Question:**

Equations of the lines through the point (3,2) and making an angle of  $40^{\circ}$  with the line x - 2y = 3 are.

#### **Solution:**

First, we express the given point and line using column vectors.

The line passes through the point (3,2). We can represent this with a position vector  $\mathbf{h}$ :

$$\mathbf{h} = \begin{pmatrix} 3 \\ 2 \end{pmatrix}$$

The given line is x - 2y = 3. From the formula  $\mathbf{n}^{\mathsf{T}}\mathbf{x} = c$ , we can identify the **normal** vector to this line, which we'll call  $\mathbf{n}_1$ :

$$\mathbf{n_1} = \begin{pmatrix} 1 \\ -2 \end{pmatrix}$$

The **direction vector** of a line,  $\mathbf{m_1}$ , is orthogonal to its normal vector, meaning  $\mathbf{m_1}^{\mathsf{T}}\mathbf{n_1} = 0$ . A simple choice is:

$$\mathbf{m_1} = \begin{pmatrix} 2 \\ 1 \end{pmatrix}$$

We need to find the direction vectors,  $\mathbf{m_2}$  and  $\mathbf{m_3}$ , for the new lines by rotating the known direction vector  $\mathbf{m_1}$  by both +40° and -40°. The rotation matrix  $R(\theta)$  is:

$$R(\theta) = \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix}$$

For the first line (rotation by  $+40^{\circ}$ ):

$$\mathbf{m_2} = R(40^\circ)\mathbf{m_1} = \begin{pmatrix} \cos(40^\circ) & -\sin(40^\circ) \\ \sin(40^\circ) & \cos(40^\circ) \end{pmatrix} \begin{pmatrix} 2 \\ 1 \end{pmatrix}$$
$$= \begin{pmatrix} 2\cos(40^\circ) - \sin(40^\circ) \\ 2\sin(40^\circ) + \cos(40^\circ) \end{pmatrix}$$

For the second line (rotation by  $-40^{\circ}$ ):

$$\mathbf{m_3} = R(-40^\circ)\mathbf{m_1} = \begin{pmatrix} \cos(40^\circ) & \sin(40^\circ) \\ -\sin(40^\circ) & \cos(40^\circ) \end{pmatrix} \begin{pmatrix} 2 \\ 1 \end{pmatrix}$$
$$= \begin{pmatrix} 2\cos(40^\circ) + \sin(40^\circ) \\ -2\sin(40^\circ) + \cos(40^\circ) \end{pmatrix}$$

We use the vector equation of a line,  $\mathbf{x} = \mathbf{h} + \kappa \mathbf{m}$ , and convert it to Cartesian form.

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The normal form is  $\mathbf{n}^{\mathsf{T}}\mathbf{x} = c$ , where  $c = \mathbf{n}^{\mathsf{T}}\mathbf{h}$ . A normal vector  $\mathbf{n}$  can be obtained from a direction vector  $\mathbf{m} = \begin{pmatrix} u \\ v \end{pmatrix}$  as  $\mathbf{n} = \begin{pmatrix} -v \\ u \end{pmatrix}$ .

#### First Line in Normal Form:

The normal vector  $\mathbf{n_2}$  from  $\mathbf{m_2}$  is:

$$\mathbf{n_2} = \begin{pmatrix} -(2\sin(40^\circ) + \cos(40^\circ)) \\ 2\cos(40^\circ) - \sin(40^\circ) \end{pmatrix}$$

The constant  $c_2 = \mathbf{n_2}^{\mathsf{T}} \mathbf{h}$  is:

$$c_2 = \left[ -(2\sin(40^\circ) + \cos(40^\circ)), \quad 2\cos(40^\circ) - \sin(40^\circ) \right] \begin{pmatrix} 3\\2 \end{pmatrix}$$
  
=  $-3(2\sin(40^\circ) + \cos(40^\circ)) + 2(2\cos(40^\circ) - \sin(40^\circ))$   
=  $\cos(40^\circ) - 8\sin(40^\circ)$ 

The equation is:

$$\begin{pmatrix} -(2\sin(40^\circ) + \cos(40^\circ)) \\ 2\cos(40^\circ) - \sin(40^\circ) \end{pmatrix}^\top \begin{pmatrix} x \\ y \end{pmatrix} = \cos(40^\circ) - 8\sin(40^\circ)$$

### **Second Line in Normal Form:**

The normal vector  $\mathbf{n_3}$  from  $\mathbf{m_3}$  is:

$$\mathbf{n_3} = \begin{pmatrix} -(-2\sin(40^\circ) + \cos(40^\circ)) \\ 2\cos(40^\circ) + \sin(40^\circ) \end{pmatrix} = \begin{pmatrix} 2\sin(40^\circ) - \cos(40^\circ) \\ 2\cos(40^\circ) + \sin(40^\circ) \end{pmatrix}$$

The constant  $c_3 = \mathbf{n_3}^{\mathsf{T}} \mathbf{h}$  is:

$$c_3 = [2\sin(40^\circ) - \cos(40^\circ), \quad 2\cos(40^\circ) + \sin(40^\circ)] \binom{3}{2}$$
  
= 3(2\sin(40^\circ) - \cos(40^\circ)) + 2(2\cos(40^\circ) + \sin(40^\circ))  
= \cos(40^\circ) + 8\sin(40^\circ)

The equation is:

$$\begin{pmatrix} 2\sin(40^\circ) - \cos(40^\circ) \\ 2\cos(40^\circ) + \sin(40^\circ) \end{pmatrix}^{\mathsf{T}} \begin{pmatrix} x \\ y \end{pmatrix} = \cos(40^\circ) + 8\sin(40^\circ)$$

# Plot of the Lines:

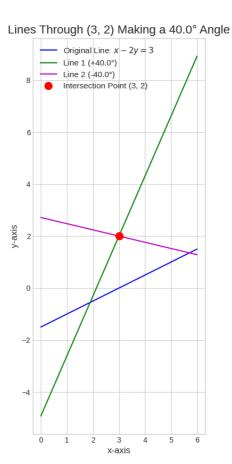


Fig. 0: Figure for 4.9.5