

4.11.36

Vaishnavi - EE25BTECH11059

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Question

Find the coordinates of the point where the line through the points $(3, -4, -5)$ and $(2, -3, 1)$ crosses the plane determined by the points $(1, 2, 3)$, $(4, 2, -3)$ and $(0, 4, 3)$.

Variable	Value
A	$(3, -4, -5)$
B	$(2, -3, 1)$
P	$(1, 2, 3)$
Q	$(4, 2, -3)$
R	$(0, 4, 3)$

Table: Variables Used

Solution

Let eq of plane be

$$\mathbf{n}^T \mathbf{x} = 1 \quad (1)$$

As $\mathbf{P}, \mathbf{Q}, \mathbf{R}$ lie on the plane

$$\mathbf{n}^T \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix} = 1 \quad (2)$$

$$\mathbf{n}^T \begin{pmatrix} 4 \\ 2 \\ -3 \end{pmatrix} = 1 \quad (3)$$

$$\mathbf{n}^T \begin{pmatrix} 0 \\ 4 \\ 3 \end{pmatrix} = 1 \quad (4)$$

From eq (0.2), (0.3) and (0.4)

$$\left(\begin{array}{ccc|c} 1 & 2 & 3 & 1 \\ 4 & 2 & -3 & 1 \\ 0 & 4 & 3 & 1 \end{array} \right) \xrightarrow{R_2 \rightarrow R_2 - 4R_1} \left(\begin{array}{ccc|c} 1 & 2 & 3 & 1 \\ 0 & -6 & -15 & -3 \\ 0 & 4 & 3 & 1 \end{array} \right) \quad (5)$$

$$\xrightarrow{R_2 \rightarrow -\frac{1}{3}R_2} \left(\begin{array}{ccc|c} 1 & 2 & 3 & 1 \\ 0 & 2 & 5 & 1 \\ 0 & 4 & 3 & 1 \end{array} \right) \quad (6)$$

$$\xrightarrow{R_3 \rightarrow R_3 - 2R_2} \left(\begin{array}{ccc|c} 1 & 2 & 3 & 1 \\ 0 & 2 & 5 & 1 \\ 0 & 0 & -7 & -1 \end{array} \right) \quad (7)$$

$$\xrightarrow{R_3 \rightarrow -\frac{1}{7}R_3} \left(\begin{array}{ccc|c} 1 & 2 & 3 & 1 \\ 0 & 2 & 5 & 1 \\ 0 & 0 & 1 & \frac{1}{7} \end{array} \right) \quad (8)$$

$$\xrightarrow{R_2 \rightarrow R_2 - 5R_3} \left(\begin{array}{ccc|c} 1 & 2 & 3 & 1 \\ 0 & 2 & 0 & \frac{2}{7} \\ 0 & 0 & 1 & \frac{1}{7} \end{array} \right) \quad (9)$$

$$\xrightarrow{R_2 \rightarrow \frac{1}{2}R_2} \left(\begin{array}{ccc|c} 1 & 2 & 3 & 1 \\ 0 & 1 & 0 & \frac{1}{7} \\ 0 & 0 & 1 & \frac{1}{7} \end{array} \right) \quad (10)$$

$$\xrightarrow{R_1 \rightarrow R_1 - 3R_3} \left(\begin{array}{ccc|c} 1 & 2 & 0 & \frac{4}{7} \\ 0 & 1 & 0 & \frac{1}{7} \\ 0 & 0 & 1 & \frac{1}{7} \end{array} \right) \quad (11)$$

$$\xrightarrow{R_1 \rightarrow R_1 - 2R_2} \left(\begin{array}{ccc|c} 1 & 0 & 0 & \frac{2}{7} \\ 0 & 1 & 0 & \frac{1}{7} \\ 0 & 0 & 1 & \frac{1}{7} \end{array} \right) \quad (12)$$

$$\mathbf{n} = \begin{pmatrix} \frac{2}{7} \\ \frac{1}{7} \\ \frac{1}{7} \end{pmatrix} \quad (13)$$

hence eq of plane is

$$\left(\frac{2}{7} \quad \frac{1}{7} \quad \frac{1}{7} \right) \mathbf{x} = 1 \quad (14)$$

let a point on line **AB** be

$$\mathbf{c} = k\mathbf{A} + (1 - k)\mathbf{B} \quad (15)$$

$$\mathbf{c} = \begin{pmatrix} 2 + k \\ -3 - k \\ 1 - 6k \end{pmatrix} \quad (16)$$

$$\begin{pmatrix} \frac{2}{7} & \frac{1}{7} & \frac{1}{7} \end{pmatrix} \begin{pmatrix} 2 + k \\ -3 - k \\ 1 - 6k \end{pmatrix} = 14 + 2k - 3 - k + 1 - 6k = 7 \quad (17)$$

$$2 - 5k = 7 \quad (18)$$

$$k = -1 \quad (19)$$

The point \mathbf{c} is

$$\mathbf{c} = \begin{pmatrix} 1 \\ -2 \\ 7 \end{pmatrix} \quad (20)$$

Graph

Refer to Figure

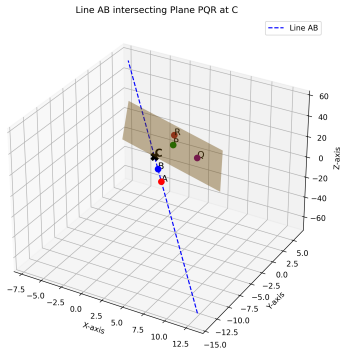


Figure:

Python Code

```
import numpy as np
import matplotlib.pyplot as plt
from mpl_toolkits.mplot3d import Axes3D

# Given points
A = np.array([3, -4, -5])
B = np.array([2, -3, 1])
P = np.array([1, 2, 3])
Q = np.array([4, 2, -3])
R = np.array([0, 4, 3])

# Direction vector of line AB
AB = B - A

# Normal vector to plane PQR = (Q-P) x (R-P)
n = np.cross(Q-P, R-P)

# Solve for intersection: A + t*AB lies in plane
t = np.dot(n, P-A) / np.dot(n, AB)
```

Python Code

```
plane_points = P.reshape(3,1,1) + (Q-P).reshape(3,1,1)
               *U + (R-P).reshape(3,1,1)*V

# Create plot
fig = plt.figure(figsize=(10, 8))
ax = fig.add_subplot(111, projection='3d')

# Extended line AB
t_vals = np.linspace(-10, 10, 200)
line_points = A.reshape(3,1) + np.outer(AB, t_vals)
ax.plot(line_points[0], line_points[1], line_points
        [2], 'b--', label= 'Line AB ')

# Plot plane
ax.plot_surface(plane_points[0], plane_points[1],
               plane_points[2], alpha=0.4, color='orange')

# Plot points
ax.scatter(*A, color='red', s=60)
```

Python Code

```
ax.scatter(*P, color='green', s=60)
ax.text(*P, P, fontsize=12)

ax.scatter(*Q, color='purple', s=60)
ax.text(*Q, Q, fontsize=12)

ax.scatter(*R, color='brown', s=60)
ax.text(*R, R, fontsize=12)

ax.scatter(*C, color='black', s=100, marker='X')
ax.text(*C, C, fontsize=14, color='black', weight='
    bold')

# Labels
ax.set_xlabel( X-axis )
ax.set_ylabel( Y-axis )
ax.set_zlabel( Z-axis )
ax.set_title( Line AB intersecting Plane PQR at C )
```

```
#include <stdio.h>
#include <math.h>

#define N 3

// Gaussian elimination solver
void gaussElimination(double A[N][N], double b[N],
    double x[N]) {
    int i, j, k;
    double ratio;

    // Forward elimination
    for (i = 0; i < N - 1; i++) {
        for (j = i + 1; j < N; j++) {
            if (fabs(A[i][i]) < 1e-12) return;
```

```
ratio = A[j][i] / A[i][i];
    for (k = 0; k < N; k++) {
        A[j][k] -= ratio * A[i][k];
    }
    b[j] -= ratio * b[i];
}
}

// Back substitution
for (i = N - 1; i >= 0; i--) {
    x[i] = b[i];
    for (j = i + 1; j < N; j++) {
        x[i] -= A[i][j] * x[j];
    }
    x[i] /= A[i][i];
}
}
```



```
// Exposed function for Python
void solve_plane(double *out) {
    double A[N][N] = {
        {1, 2, 3},
        {4, 2, -3},
        {0, 4, 3}
    };
    double b[N] = {1, 1, 1};
    double n[N];

    gaussElimination(A, b, n);

    for (int i = 0; i < N; i++) {
        out[i] = n[i];
    }
}
```

Python and C Code

```
import ctypes
import numpy as np

# Load shared library
lib = ctypes.CDLL( './code.so' )

# Define function signature: void solve_plane(double *
    out)
lib.solve_plane.argtypes = [ctypes.POINTER(ctypes.
    c_double)]
lib.solve_plane.restype = None

# Prepare output array
out = (ctypes.c_double * 3)()
lib.solve_plane(out)

# Convert to numpy for convenience
normal_vec = np.array([out[i] for i in range(3)])
print( 'Normal vector: ', normal_vec)
```