

## 2.8.25

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# Question

If **A**, **B**, **C** are mutually perpendicular vectors of equal magnitudes, show that **A** + **B** + **C** is equally inclined to **A**, **B** and **C**.

# Theoretical Solution

Given:

$$\mathbf{A}^\top \mathbf{B} = 0 \quad (1)$$

$$\mathbf{B}^\top \mathbf{C} = 0 \quad (2)$$

$$\mathbf{C}^\top \mathbf{A} = 0 \quad (3)$$

$$\|\mathbf{A}\| = \|\mathbf{B}\| = \|\mathbf{C}\| = k \quad (4)$$

# Theoretical Solution

This implies:

$$\mathbf{A}^\top \mathbf{A} = \|\mathbf{A}\|^2 = k^2 \quad (5)$$

$$\mathbf{B}^\top \mathbf{B} = \|\mathbf{B}\|^2 = k^2 \quad (6)$$

$$\mathbf{C}^\top \mathbf{C} = \|\mathbf{C}\|^2 = k^2 \quad (7)$$

Let

$$\mathbf{R} = (\mathbf{A} + \mathbf{B} + \mathbf{C}) \quad (8)$$

The cosine of the angle  $\theta$  between two vectors  $\mathbf{X}$  and  $\mathbf{Y}$  is given by:

$$\cos \theta = \frac{\mathbf{X}^\top \mathbf{Y}}{\|\mathbf{X}\| \|\mathbf{Y}\|} \quad (9)$$

# Theoretical Solution

$$\|\mathbf{R}\|^2 = \mathbf{R}^\top \mathbf{R} \quad (10)$$

$$= (\mathbf{A} + \mathbf{B} + \mathbf{C})^\top (\mathbf{A} + \mathbf{B} + \mathbf{C}) \quad (11)$$

$$= \mathbf{A}^\top \mathbf{A} + \mathbf{A}^\top \mathbf{B} + \mathbf{A}^\top \mathbf{C} + \mathbf{B}^\top \mathbf{A} + \mathbf{B}^\top \mathbf{B} + \mathbf{B}^\top \mathbf{C} + \mathbf{C}^\top \mathbf{A} + \mathbf{C}^\top \mathbf{B} + \mathbf{C}^\top \mathbf{C} \quad (12)$$

$$= \|\mathbf{A}\|^2 + 0 + 0 + 0 + \|\mathbf{B}\|^2 + 0 + 0 + 0 + \|\mathbf{C}\|^2 \quad (13)$$

$$= k^2 + k^2 + k^2 \quad (14)$$

$$= 3k^2 \quad (15)$$

Therefore,  $\|\mathbf{R}\| = \sqrt{3}k$ .

# Theoretical Solution

Now, let  $\alpha$  be the angle between  $\mathbf{R}$  and  $\mathbf{A}$ .

$$\cos \alpha = \frac{\mathbf{R}^T \mathbf{A}}{\|\mathbf{R}\| \|\mathbf{A}\|} \quad \text{using (9)} \quad (16)$$

$$= \frac{(\mathbf{A} + \mathbf{B} + \mathbf{C})^T \mathbf{A}}{\|\mathbf{R}\| \|\mathbf{A}\|} \quad (17)$$

$$= \frac{\mathbf{A}^T \mathbf{A} + \mathbf{B}^T \mathbf{A} + \mathbf{C}^T \mathbf{A}}{\|\mathbf{R}\| \|\mathbf{A}\|} \quad (18)$$

$$= \frac{\|\mathbf{A}\|^2 + 0 + 0}{\|\mathbf{R}\| \|\mathbf{A}\|} \quad (19)$$

# Theoretical Solution

$$= \frac{k^2}{(\sqrt{3}k)(k)} \quad (20)$$

$$= \frac{k^2}{\sqrt{3}k^2} \quad (21)$$

$$= \frac{1}{\sqrt{3}} \quad (22)$$

Let  $\beta$  be the angle between  $\mathbf{R}$  and  $\mathbf{B}$ .

$$\cos \beta = \frac{\mathbf{R}^\top \mathbf{B}}{\|\mathbf{R}\| \|\mathbf{B}\|} \quad \text{using (9)} \quad (23)$$

$$= \frac{(\mathbf{A} + \mathbf{B} + \mathbf{C})^\top \mathbf{B}}{\|\mathbf{R}\| \|\mathbf{B}\|} \quad (24)$$

$$= \frac{\mathbf{A}^\top \mathbf{B} + \mathbf{B}^\top \mathbf{B} + \mathbf{C}^\top \mathbf{B}}{\|\mathbf{R}\| \|\mathbf{B}\|} \quad (25)$$

$$= \frac{0 + \|\mathbf{B}\|^2 + 0}{\|\mathbf{R}\| \|\mathbf{B}\|} \quad (26)$$

$$= \frac{k^2}{(\sqrt{3}k)(k)} \quad (27)$$

$$= \frac{k^2}{\sqrt{3}k^2} \quad (28)$$

$$= \frac{1}{\sqrt{3}} \quad (29)$$



# Theoretical Solution

Let  $\gamma$  be the angle between  $\mathbf{R}$  and  $\mathbf{C}$ .

$$\cos \gamma = \frac{\mathbf{R}^T \mathbf{C}}{\|\mathbf{R}\| \|\mathbf{C}\|} \quad \text{using (9)} \quad (30)$$

$$= \frac{(\mathbf{A} + \mathbf{B} + \mathbf{C})^T \mathbf{C}}{\|\mathbf{R}\| \|\mathbf{C}\|} \quad (31)$$

$$= \frac{\mathbf{A}^T \mathbf{C} + \mathbf{B}^T \mathbf{C} + \mathbf{C}^T \mathbf{C}}{\|\mathbf{R}\| \|\mathbf{C}\|} \quad (32)$$

# Theoretical Solution

$$= \frac{0 + 0 + \|\mathbf{C}\|^2}{\|\mathbf{R}\| \|\mathbf{C}\|} \quad (33)$$

$$= \frac{k^2}{(\sqrt{3}k)(k)} \quad (34)$$

$$= \frac{k^2}{\sqrt{3}k^2} \quad (35)$$

$$= \frac{1}{\sqrt{3}} \quad (36)$$

Since  $\cos \alpha = \cos \beta = \cos \gamma = \frac{1}{\sqrt{3}}$ , it implies  $\alpha = \beta = \gamma$ .

Thus,  $\mathbf{A} + \mathbf{B} + \mathbf{C}$  is equally inclined to  $\mathbf{A}$ ,  $\mathbf{B}$  and  $\mathbf{C}$ .

```
#include <stdio.h>
#include <math.h>

// Function to calculate the dot product of two 3D vectors
double dot_product(double v1x, double v1y, double v1z,
                  double v2x, double v2y, double v2z) {
    return v1x * v2x + v1y * v2y + v1z * v2z;
}

// Function to calculate the magnitude of a 3D vector
double magnitude(double vx, double vy, double vz) {
    return sqrt(vx * vx + vy * vy + vz * vz);
}
```

# C Code

```
// Function to calculate the cosines of angles between (A+B+C)
// and A, B, C
// Arguments:
// ax, ay, az: Components of vector A
// bx, by, bz: Components of vector B
// cx, cy, cz: Components of vector C
// cos_angle_result: Pointer to an array to store the results
void calculate_angles_cosines(double ax, double ay, double az,
                             double bx, double by, double bz,
                             double cx, double cy, double cz,
                             double* cos_angle_result) {
    // Calculate the resultant vector R = A + B + C
    double rx = ax + bx + cx;
    double ry = ay + by + cy;
    double rz = az + bz + cz;
```

```
// Calculate magnitudes
double mag_A = magnitude(ax, ay, az);
double mag_B = magnitude(bx, by, bz);
double mag_C = magnitude(cx, cy, cz);
double mag_R = magnitude(rx, ry, rz);

// Calculate dot products
double dot_R_A = dot_product(rx, ry, rz, ax, ay, az);
double dot_R_B = dot_product(rx, ry, rz, bx, by, bz);
double dot_R_C = dot_product(rx, ry, rz, cx, cy, cz);

cos_angle_result[0] = dot_R_A / (mag_R * mag_A);
cos_angle_result[1] = dot_R_B / (mag_R * mag_B);
cos_angle_result[2] = dot_R_C / (mag_R * mag_C);
}
```

# Python Code through shared output

```
import ctypes
import numpy as np
import matplotlib.pyplot as plt
from mpl_toolkits.mplot3d import Axes3D

# Load the shared library
lib_angles = ctypes.CDLL('./code4.so')

# Define the argument types and return type for the C function
lib_angles.calculate_angles_cosines.argtypes = [
    ctypes.c_double, ctypes.c_double, ctypes.c_double, # A_x, A_y
    , A_z
    ctypes.c_double, ctypes.c_double, ctypes.c_double, # B_x, B_y
    , B_z
    ctypes.c_double, ctypes.c_double, ctypes.c_double, # C_x, C_y
    , C_z
    ctypes.POINTER(ctypes.c_double * 3) # Pointer to an array of
    3 doubles for results
```

# Python Code through shared output

```
lib_angles.calculate_angles_cosines.restype = None
# Define mutually perpendicular vectors of equal magnitude
magnitude = 5.0
A = np.array([magnitude, 0.0, 0.0])
B = np.array([0.0, magnitude, 0.0])
C = np.array([0.0, 0.0, magnitude])

# Resultant vector R = A + B + C
R = A + B + C
# Create a C array to hold the three cosine results
cos_angles_c_array = (ctypes.c_double * 3)()

# Call the C function
lib_angles.calculate_angles_cosines(
    A[0], A[1], A[2],
    B[0], B[1], B[2],
    C[0], C[1], C[2],
    ctypes.byref(cos_angles_c_array)
)
```

# Python Code through shared output

```
# Retrieve the results from the C array
cos_theta_RA = cos_angles_c_array[0]
cos_theta_RB = cos_angles_c_array[1]
cos_theta_RC = cos_angles_c_array[2]

# Convert cosines to angles in degrees
theta_RA_deg = np.degrees(np.arccos(cos_theta_RA))
theta_RB_deg = np.degrees(np.arccos(cos_theta_RB))
theta_RC_deg = np.degrees(np.arccos(cos_theta_RC))

print(fVectors A = {A}, B = {B}, C = {C})
print(fResultant vector R = A + B + C = {R})
```



# Python Code through shared output

```
print(fCosine of angle between R and A: {cos_theta_RA:.6f})
print(fAngle between R and A: {theta_RA_deg:.2f} degrees)
print(fCosine of angle between R and B: {cos_theta_RB:.6f})
print(fAngle between R and B: {theta_RB_deg:.2f} degrees)
print(fCosine of angle between R and C: {cos_theta_RC:.6f})
print(fAngle between R and C: {theta_RC_deg:.2f} degrees)

if np.isclose(theta_RA_deg, theta_RB_deg) and np.isclose(
    theta_RB_deg, theta_RC_deg):
    print(\nConclusion: The angles are approximately equal,
        showing that A+B+C is equally inclined to A, B, and C.)
else:
    print(\nConclusion: The angles are not equal. There might be
        an issue with the input vectors or calculation.)
```

# Python Code through shared output

```
# --- Visualization ---
fig = plt.figure(figsize=(10, 8))
ax = fig.add_subplot(111, projection='3d')

origin = [0, 0, 0]

# Plot vectors A, B, C
ax.quiver(*origin, *A, color='r', linewidth=2, arrow_length_ratio
          =0.1, label='Vector A')
ax.quiver(*origin, *B, color='g', linewidth=2, arrow_length_ratio
          =0.1, label='Vector B')
ax.quiver(*origin, *C, color='b', linewidth=2, arrow_length_ratio
          =0.1, label='Vector C')

# Plot resultant vector R
ax.quiver(*origin, *R, color='purple', linewidth=3,
          arrow_length_ratio=0.08, label='Vector A+B+C')
```

# Python Code through shared output

```
# Set labels and title
ax.set_xlabel('X-axis')
ax.set_ylabel('Y-axis')
ax.set_zlabel('Z-axis')
ax.set_title('Mutually Perpendicular Vectors and Their Sum')
ax.legend()

# Set limits for a better view
max_coord = max(np.max(np.abs(A)), np.max(np.abs(B)), np.max(np.
    abs(C)), np.max(np.abs(R))) * 1.2
ax.set_xlim([-max_coord, max_coord])
ax.set_ylim([-max_coord, max_coord])
ax.set_zlim([-max_coord, max_coord])

# Add grid
ax.grid(True)
plt.savefig('fig1.png') # Save the plot
plt.show()
```

# Python Code

```
import numpy as np
import numpy.linalg as LA
import matplotlib.pyplot as plt
from mpl_toolkits.mplot3d import Axes3D # For 3D plotting

# --- 1. Define vectors A, B, C ---
# Mutually perpendicular vectors of equal magnitude
magnitude = 3.0 # You can change the magnitude
A = np.array([magnitude, 0.0, 0.0])
B = np.array([0.0, magnitude, 0.0])
C = np.array([0.0, 0.0, magnitude])

print(fGiven Vectors:)
print(fA = {A})
print(fB = {B})
print(fC = {C})
```

# Python Code

```
# --- 2. Calculate the resultant vector  $R = A + B + C$  ---
R = A + B + C
print(f"\nResultant vector  $R = A + B + C = \{R\}$ ")

# --- 3. Calculate angles using dot products ---
def angle_between_vectors(v1, v2):
    dot_product = np.dot(v1, v2)
    magnitude_v1 = LA.norm(v1)
    magnitude_v2 = LA.norm(v2)

    # Handle potential division by zero for zero vectors
    if magnitude_v1 < 1e-9 or magnitude_v2 < 1e-9:
        if magnitude_v1 < 1e-9 and magnitude_v2 < 1e-9:
            return 0.0 # Both are zero, angle is 0
        else:
            return np.pi / 2 # One is zero, other non-zero, angle
                               # is 90 degrees (pi/2 radians)
```

# Python Code

```
cosine_angle = dot_product / (magnitude_v1 * magnitude_v2)
# Ensure cosine_angle is within [-1, 1] due to potential
    floating point inaccuracies
cosine_angle = np.clip(cosine_angle, -1.0, 1.0)
return np.arccos(cosine_angle) # Returns angle in radians
```

```
# Calculate angles
```

```
angle_RA_rad = angle_between_vectors(R, A)
angle_RB_rad = angle_between_vectors(R, B)
angle_RC_rad = angle_between_vectors(R, C)
```

```
angle_RA_deg = np.degrees(angle_RA_rad)
angle_RB_deg = np.degrees(angle_RB_rad)
angle_RC_deg = np.degrees(angle_RC_rad)
```

```
print(\n--- Calculated Angles ---)
print(fAngle between R and A: {angle_RA_deg:.2f} degrees)
print(fAngle between R and B: {angle_RB_deg:.2f} degrees)
print(fAngle between R and C: {angle_RC_deg:.2f} degrees)
```

```
# Conclusion
if np.isclose(angle_RA_deg, angle_RB_deg) and np.isclose(
    angle_RB_deg, angle_RC_deg):
    print(\nConclusion: The angles are approximately equal. This
        shows that A+B+C is equally inclined to A, B, and C.)
else:
    print(\nConclusion: The angles are not equal. Please check
        the input vectors to ensure they are mutually
        perpendicular and have equal magnitudes.)

# --- 5. Generate a 3D plot to visualize these vectors ---
fig = plt.figure(figsize=(10, 8))
ax = fig.add_subplot(111, projection='3d')

origin = [0, 0, 0]
```

# Python Code

```
# Plot vectors A, B, C
ax.quiver(*origin, *A, color='r', linewidth=2, arrow_length_ratio
         =0.1, label='Vector A')
ax.quiver(*origin, *B, color='g', linewidth=2, arrow_length_ratio
         =0.1, label='Vector B')
ax.quiver(*origin, *C, color='b', linewidth=2, arrow_length_ratio
         =0.1, label='Vector C')

# Plot resultant vector R
ax.quiver(*origin, *R, color='purple', linewidth=3,
         arrow_length_ratio=0.08, label='Vector A+B+C')

# Set labels and title
ax.set_xlabel('X-axis')
ax.set_ylabel('Y-axis')
ax.set_zlabel('Z-axis')
ax.set_title('Mutually Perpendicular Vectors and Their Sum')
ax.legend()
```



# Python Code (Direct) - Visualization

```
# Set limits for a better view
all_coords = np.concatenate((A, B, C, R))
max_coord = np.max(np.abs(all_coords)) * 1.2 # Add some padding
ax.set_xlim([-max_coord, max_coord])
ax.set_ylim([-max_coord, max_coord])
ax.set_zlim([-max_coord, max_coord])

# Add grid
ax.grid(True)

plt.savefig(fig2.png)
plt.show()

print(\nFigure saved as fig2.png)
```

# Plot by Python using shared output from C

Mutually Perpendicular Vectors and Their Sum

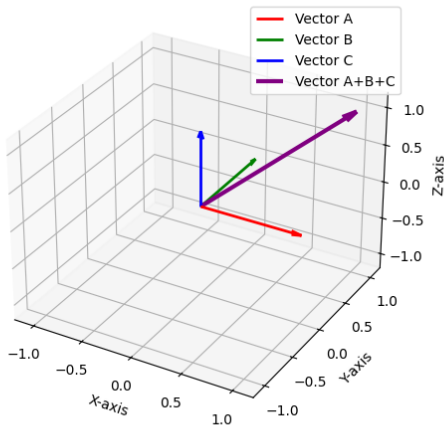


Figure:

Mutually Perpendicular Vectors and Their Sum

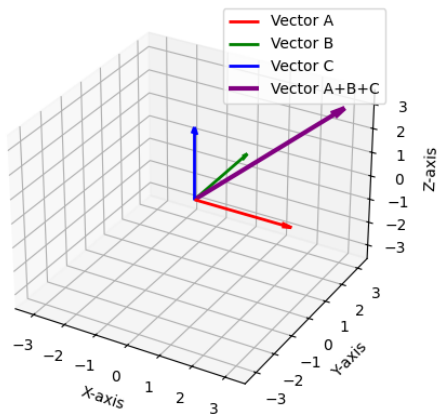


Figure: