2.8.19

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Problem Statement

lf

$$\mathbf{r} \cdot \mathbf{a} = 0$$
, $\mathbf{r} \cdot \mathbf{b} = 0$, $\mathbf{r} \cdot \mathbf{c} = 0$

for some non-zero vector \mathbf{r} , find

$$\mathbf{a} \cdot (\mathbf{b} \times \mathbf{c})$$
.

Solution: Step 1 – Orthogonality

From

$$\mathbf{r} \cdot \mathbf{a} = 0, \tag{1}$$

$$\mathbf{r} \cdot \mathbf{b} = 0, \tag{2}$$

$$\mathbf{r} \cdot \mathbf{c} = 0, \tag{3}$$

we see that $\mathbf{a}, \mathbf{b}, \mathbf{c}$ lie in the subspace orthogonal to \mathbf{r} :

$$\mathbf{a}, \mathbf{b}, \mathbf{c} \in \operatorname{span}\{\mathbf{r}\}^{\perp}.$$
 (4)

Step 2 – Dimension Argument

Since $\mathbf{r} \neq \mathbf{0}$, the orthogonal subspace has dimension at most 2:

$$\dim(\operatorname{span}\{\mathbf{r}\}^{\perp}) = 2. \tag{5}$$

Thus, any three vectors in this atmost 2D subspace are linearly dependent:

$$\mathbf{c} = \lambda_1 \mathbf{a} + \lambda_2 \mathbf{b}$$
, for some scalars λ_1, λ_2 . (6)

Step 3 – Scalar Triple Product

The scalar triple product of linearly dependent vectors is zero:

$$\mathbf{a} \cdot (\mathbf{b} \times \mathbf{c}) = \det \begin{pmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{pmatrix}$$
(7)
= 0.

Final Answer

$$\mathbf{a} \cdot (\mathbf{b} \times \mathbf{c}) = 0$$

Reasoning: The vectors lie in a plane perpendicular to \mathbf{r} and are therefore linearly dependent, making the scalar triple product vanish.

C Code

Python code through shared output

```
import ctypes
 import matplotlib.pyplot as plt
 import numpy as np
 from mpl_toolkits.mplot3d import Axes3D
 # Load the shared library
 lib = ctypes.CDLL(./libstp.so)
 lib.scalar_triple.restype = ctypes.c_double
 # Define vectors
 a = (\text{ctypes.c\_double} * 3)(1, 0, 0)
 b = (\text{ctypes.c\_double} * 3)(0, 1, 0)
 c = (ctypes.c double * 3)(1, 1, 0)
 # Call the C function
 result = lib.scalar triple(a, b, c)
print(Scalar triple product =, result)
 # Convert to numpy arrays for plotting
 a \text{ vec} = np.array([a[0], a[1], a[2]])
 b_vec = np.array([b[0], b[1], b[2]])
 c_{vec} = np.array([c[0], c[1], c[2]])
```

Python code through shared output

```
# Plot vectors in 3D
fig = plt.figure()
ax = fig.add subplot(111, projection='3d')
origin = np.array([0, 0, 0])
ax.quiver(*origin, *a vec, color='r', label='a')
ax.quiver(*origin, *b vec, color='g', label='b')
ax.quiver(*origin, *c vec, color='b', label='c')
ax.set_xlim([0, 1.5])
ax.set_ylim([0, 1.5])
ax.set zlim([0, 1.5])
ax.set_xlabel(X)
ax.set_ylabel(Y)
ax.set_zlabel(Z)
ax.set_title(fScalar Triple Product = {result})
ax.legend()
plt.show()
```

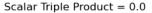
Only Python code

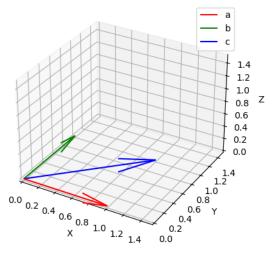
```
import numpy as np
import matplotlib.pyplot as plt
from mpl toolkits.mplot3d import Axes3D
# Define 3 coplanar vectors (lying in xy-plane)
a = np.array([1, 1, 0])
b = np.array([1, 0, 0])
c = np.array([0, 1, 0])
# Cross product b x c
b_cross_c = np.cross(b, c)
# Scalar triple product a . (b x c)
scalar_triple = np.dot(a, b_cross_c)
# Print the scalar triple product (should be 0)
print(fScalar triple product: {scalar_triple:.2f})
# Plotting
fig = plt.figure()
ax = fig.add_subplot(111, projection='3d')
```

Only Python code

```
# Plot origin
 origin = np.array([0, 0, 0])
 # Plot vectors
 ax.quiver(*origin, *a, color='r', label='Vector a', linewidth=2)
 ax.quiver(*origin, *b, color='g', label='Vector b', linewidth=2)
 ax.quiver(*origin, *c, color='b', label='Vector c', linewidth=2)
 # Plot b x c
 ax.quiver(*origin, *b_cross_c, color='orange', linestyle='dashed'
     , label='b x c', linewidth=2)
 ax.set_xlim([0, 1.5])
 ax.set_ylim([0, 1.5])
 ax.set zlim([0, 1.5])
ax.set xlabel('X')
ax.set ylabel('Y')
 ax.set zlabel('Z')
 ax.set_title(f'Scalar Triple Product = {scalar_triple:.2f}')
 ax.legend()
 ax.grid(True)
plt.show()
```

PLOTS





PLOTS



