

## 5.13.7

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September 28,2025

## Question 5.13.7

Let  $A$  and  $B$  be two symmetric matrices of order 3.

**Statement 1:**  $A(BA)$  and  $(AB)A$  are symmetric matrices.

**Statement 2:**  $AB$  is symmetric if  $A$  and  $B$  commute ( $AB = BA$ ).

Determine the correct option.

## Step 1: Symmetry property

A matrix  $M$  is symmetric if

$$M^T = M \quad (1)$$

## Step 2: Check $A(BA)$

Let

$$M = A(BA)$$

Then,

$$M^T = (A(BA))^T \quad (2)$$

$$= (BA)^T A^T \quad (3)$$

$$= A^T B^T A^T \quad (4)$$

$$= ABA \quad (\text{since } A^T = A, B^T = B) \quad (5)$$

$$= A(BA) = M \quad (6)$$

Hence,  $A(BA)$  is symmetric.

## Step 3: Check $(AB)A$

Let

$$N = (AB)A$$

Then,

$$N^T = ((AB)A)^T \quad (7)$$

$$= A^T (AB)^T \quad (8)$$

$$= A^T B^T A^T \quad (9)$$

$$= ABA \quad (10)$$

$$= (AB)A = N \quad (11)$$

Hence,  $(AB)A$  is symmetric.

## Step 4: Condition for $AB$ to be symmetric

$$(AB)^T = B^T A^T \quad (12)$$

$$= BA \quad (\text{since } A^T = A, B^T = B) \quad (13)$$

Thus,

$$AB \text{ is symmetric} \iff AB = BA \quad (14)$$

Conclusion: Statement 1 is true, Statement 2 is true but not the correct explanation for Statement 1.

Correct option: (a)

# C Code (Part 1)

```
#include <stdio.h>

int main() {
    int A[3][3] = {{1,2,3},{4,5,6},{7,8,9}};
    int B[3][3] = {{9,8,7},{6,5,4},{3,2,1}};
    int AB[3][3], ABt[3][3], BtAt[3][3], i, j, k;

    for(i=0;i<3;i++){
        for(j=0;j<3;j++){
            AB[i][j]=0;
            for(k=0;k<3;k++){
                AB[i][j]+=A[i][k]*B[k][j];
            }
        }
    }

    for(i=0;i<3;i++){
        for(j=0;j<3;j++){
            ABt[i][j]=AB[j][i];
```

## C Code (Part 2)

```
int At[3][3], Bt[3][3];
for(i=0;i<3;i++){
    for(j=0;j<3;j++){
        At[i][j]=A[j][i];
        Bt[i][j]=B[j][i];
    }
}

for(i=0;i<3;i++){
    for(j=0;j<3;j++){
        BtAt[i][j]=0;
        for(k=0;k<3;k++){
            BtAt[i][j]+=Bt[i][k]*At[k][j];
        }
    }
}

printf(Transpose of AB:\n);
for(i=0;i<3;i++){
```



# Python Code

```
import numpy as np

A = np.array([[1,2,3],[4,5,6],[7,8,9]])
B = np.array([[9,8,7],[6,5,4],[3,2,1]])

AB = np.dot(A, B)
ABt = AB.T
BtAt = np.dot(B.T, A.T)

print(Transpose of AB:)
print(ABt)
print(Product B^T A^T:)
print(BtAt)
```