8.2.52

AI25BTECH11014 - Gooty Suhas

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Problem

Given:

- Eccentricity $e = \frac{2}{3}$
- Latus rectum I=5
- Centre at origin $\begin{pmatrix} 0 \\ 0 \end{pmatrix}$

Find the equation of the conic in matrix form using matrix algebra.

Ellipse Setup

Let the conic be:

$$\mathbf{x}^T \mathbf{V} \mathbf{x} = 1$$
 where $\mathbf{V} = \begin{pmatrix} a & 0 \\ 0 & b \end{pmatrix}$

Choose two points:

$$\mathbf{P}_1 = \begin{pmatrix} 4 \\ 3 \end{pmatrix}, \quad \mathbf{P}_2 = \begin{pmatrix} 6 \\ 2 \end{pmatrix}$$

Substitute:

$$\mathbf{P}_1^T \mathbf{V} \mathbf{P}_1 = 1, \quad \mathbf{P}_2^T \mathbf{V} \mathbf{P}_2 = 1$$

Matrix System

From substitution:

$$16a + 9b = 1$$
, $36a + 4b = 1$

Write as matrix equation:

$$\begin{pmatrix} 16 & 9 \\ 36 & 4 \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

Row Reduction

Augmented matrix:

$$\begin{pmatrix} 16 & 9 & | & 1 \\ 36 & 4 & | & 1 \end{pmatrix} \xrightarrow{R_2 \to R_2 - \frac{9}{4}R_1} \begin{pmatrix} 16 & 9 & | & 1 \\ 0 & -\frac{61}{4} & | & -\frac{5}{4} \end{pmatrix}$$

Solution

Choose
$$a = \frac{4}{81} \Rightarrow 16a = \frac{64}{81}$$

Then:

$$\frac{64}{81} + 9b = 1 \Rightarrow b = \frac{17}{81}$$

So:

$$\mathbf{V} = \begin{pmatrix} \frac{4}{81} & 0\\ 0 & \frac{17}{81} \end{pmatrix}$$

Final Answer

$$\left| \mathbf{x}^T \begin{pmatrix} \frac{4}{81} & 0 \\ 0 & \frac{17}{81} \end{pmatrix} \mathbf{x} = 1 \right|$$
 is the equation of the ellipse

Python Code

```
from sympy import Rational, symbols, solve, Eq
e = Rational(2, 3)
l = 5
a = symbols('a')
b2 = a**2 * (1 - e**2)
eq = Eq(2 * b2 / a, I)
a val = solve(eq, a)[0]
b2 val = a val**2 * (1 - e**2)
print("a_{\sqcup}=", a_{\underline{\square}}val)
print("b_{\parallel}=", b2 val)
print("V_{||}=||[\{:.6f\},||0],||[0,||\{:.6f\}]]".format(
     1 / a val**2, 1 / b2 val))
```

C Code

```
#include <math.h>
#include <stdio.h>
void solve_matrix(float* V) {
  float e = 2.0 / 3.0;
  float 1 = 5.0:
  float a = 9.0 / 2.0;
 float b2 = a * a * (1 - e * e);
 V[0] = 1 / (a * a);
 V[1] = 1 / b2;
```

Python Wrapper Code

```
import ctypes
lib = ctypes.CDLL('./libellipse.so')
lib.solve_matrix.argtypes = [ctypes.POINTER(ctypes.c_float)]
lib.solve_matrix.restype = None
V = (\text{ctypes.c\_float} * 2)()
lib.solve matrix(V)
print("Ellipse_equation:_{\square}x_{\square}V_{\square}x_{\square}=_{\square}1")
print(f''V_{\sqcup} =_{\sqcup}[[\{V[0]:.6f\},_{\sqcup}0],_{\sqcup}[0,_{\sqcup}\{V[1]:.6f\}]]'')
```

Diagram

