12.339

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Question

Question:

lf

$$\mathbf{A} = \begin{pmatrix} 3 & -3 \\ -3 & 4 \end{pmatrix} \tag{1}$$

then

$$\det\left(-\mathbf{A}^2 + 7\mathbf{A} - 3\mathbf{I}\right) \tag{2}$$

is

Solution

$$\det(\mathbf{A}) = 3, \text{Tr}(\mathbf{A}) = 3 + 4 = 7 \tag{3}$$

(where $Tr(\mathbf{A})$ represents the trace of matrix \mathbf{A} , i.e. the sum of the diagonal entries of \mathbf{A})



Solution

The determinant of the expression can be found out by using the Cayley-Hamilton theorem.

$$\mathbf{A}^{2} - (\mathsf{Tr}(\mathbf{A}))\mathbf{A} + \det(\mathbf{A})\mathbf{I} = 0 \tag{4}$$

$$\mathbf{A}^2 - 7\mathbf{A} + 3\mathbf{I} = 0 \implies -\mathbf{A}^2 + 7\mathbf{A} - 3\mathbf{I} = 0$$
 (5)

$$\therefore \det\left(-\mathbf{A}^2 + 7\mathbf{A} - 3\mathbf{I}\right) = 0 \tag{6}$$

C Code

```
#include <stdio.h>
double det(double *mat) {
    return mat[0]*mat[3] - mat[1]*mat[2];
}
```

Python + C Code

```
import numpy as np
import ctypes
lib = ctypes.CDLL("./libcode.so")
lib.det.argtypes = [ctypes.POINTER(ctypes.c double)]
lib.det.restype = ctypes.c double
A = np.array([[3, -3],
             [-3, 4]], dtype=np.float64)
I = np.eye(2, dtype=np.float64)
expr = -A @ A + 7*A - 3*I
mat_flat = expr.flatten()
det_value = lib.det(mat_flat.ctypes.data_as(ctypes.POINTER(ctypes
    .c double)))
print("Matrix (-A^2 + 7A - 3I):\n", expr)
print("Determinant =", det_value)
```

Python Code

```
import numpy as np
 A = np.array([[3, -3],
              [-3, 4]]
I = np.eye(2)
 expr = -A @ A + 7*A - 3*I
 det_value = np.linalg.det(expr)
 print("Matrix A:\n", A)
 print("Matrix (-A^2 + 7A - 3I):\n", expr)
 print("Determinant =", det value)
```