2.5.34

AI25BTECH11001 - ABHISEK MOHAPATRA

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Question: Show that the lines

$$\frac{x-a+d}{\alpha-\delta} = \frac{y-a}{\alpha} = \frac{z-a-d}{\alpha+\delta}$$

$$\frac{x-b+c}{\beta-\delta} = \frac{y-b}{\beta} = \frac{z-b-c}{\beta+\delta}$$

are coplanar.

Solution: Given:

$$\mathbf{L_1} = \mathbf{A} + \lambda \mathbf{m_1}$$

$$\mathbf{L_1} = \begin{pmatrix} a - d \\ a \\ a + d \end{pmatrix} + \lambda \begin{pmatrix} \alpha - \delta \\ \alpha \\ \alpha + \delta \end{pmatrix}$$

And,

$$L_2 = B + \lambda m_2$$

(0.5)

(0.1)

(0.2)

(0.3)

(0.4)

$$\mathbf{L_2} = \begin{pmatrix} b - c \\ b \\ b + c \end{pmatrix} + \lambda \mathbf{m_2} \begin{pmatrix} \beta - \delta \\ \beta \\ \beta + \delta \end{pmatrix} \tag{0.6}$$
 If the lines lie in a plane, then they satisfy,

If the lines lie in a plane, then they satisfy,

$$nullity egin{pmatrix} m{m_1} & m{m_2} & m{B} - m{A} \end{pmatrix} \geq 1$$
 $nullity egin{pmatrix} lpha - \delta & eta - \delta & a - b + c - d \ lpha & eta & a - b \ lpha + \delta & eta + \delta & 3 - b - c + d \end{pmatrix} \geq 1$

$$(\alpha + \delta \quad \beta + \delta \quad a - b - c + d)$$

$$(\alpha + \delta \quad \beta + \delta \quad a - b + c - d)$$

$$\xrightarrow{R_2 \leftrightarrow R_3} \begin{pmatrix} \alpha - \delta & \beta - \delta & a - b + c - d \\ \alpha + \delta & \beta + \delta & a - b - c + d \\ \alpha & \beta & a - b \end{pmatrix}$$

$$\frac{R_3 \to R_3 - \frac{R_1 + R_2}{2}}{\longrightarrow} \begin{pmatrix} \alpha - \delta & \beta - \delta & a - b + c - d \\ \alpha + \delta & \beta + \delta & a - b - c + d \end{pmatrix}$$

(0.7)

(8.0)

(0.9)

(0.10)

$$\xrightarrow{R_2 \to R_2 - R_1} \begin{pmatrix} \alpha - \delta & \beta - \delta & a - b + c - d \\ 2\delta & 2\delta & -2c + 2d \\ 0 & 0 & 0 \end{pmatrix} \tag{0.11}$$

$$\frac{C_1 \rightarrow C_1 - C_2}{\longrightarrow} \begin{pmatrix} \alpha - \beta & \beta - \delta & a - b + c - d \\ 0 & 2\delta & -2c + 2d \\ 0 & 0 & 0 \end{pmatrix} \tag{0.12}$$

The matrix is in echelon form and the rank of the matrix is two. And, thus the lines are co-planer.

Graph(using some random values for the variables):

