

1.11.16

AI25BTECH11014 - Suhas

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Question

The Cartesian equation of a line AB is

$$\frac{x-1}{2} = \frac{y+2}{2} = \frac{z-3}{3}$$

Find the direction cosines of a line parallel to line AB.

Solution

Extract the direction vector from the denominators:

$$\mathbf{D} = \begin{pmatrix} 2 \\ 2 \\ 3 \end{pmatrix} \quad (1)$$

Compute the magnitude of \mathbf{D} :

$$\|\mathbf{D}\| = \sqrt{2^2 + 2^2 + 3^2} = \sqrt{17} \quad (2)$$

Normalize the direction vector:

$$\mathbf{L} = \frac{1}{\sqrt{17}} \cdot \mathbf{D} = \frac{1}{\sqrt{17}} \cdot \begin{pmatrix} 2 \\ 2 \\ 3 \end{pmatrix} \quad (3)$$

Matrix Form

Let the point vector be:

$$\mathbf{P} = \begin{pmatrix} 1 \\ -2 \\ 3 \end{pmatrix} \quad (4)$$

Then the line can be expressed in matrix form as:

$$\mathbf{R} = \mathbf{P} + \lambda \cdot \mathbf{D} \quad (5)$$

Where $\lambda \in \mathbb{R}$ is a scalar parameter.

Conclusion

The direction cosines of a line parallel to AB are:

$$\mathbf{L} = \frac{1}{\sqrt{17}} \cdot \begin{pmatrix} 2 \\ 2 \\ 3 \end{pmatrix}$$

The line can be expressed in matrix form as:

$$\mathbf{R} = \begin{pmatrix} 1 \\ -2 \\ 3 \end{pmatrix} + \lambda \cdot \begin{pmatrix} 2 \\ 2 \\ 3 \end{pmatrix}$$

C Code: Solve Direction Cosines

```
#include <stdio.h>
#include <math.h>

int main() {
    double D[3] = {2.0, 1.0, 3.0};
    double mag = sqrt(D[0]*D[0] +
                      D[1]*D[1] +
                      D[2]*D[2]);
    printf("Magnitude: %f\n", mag);
}
```

C Code: Solve Direction Cosines (2/2)

```
printf("Direction Cosines:\n");  
for (int i = 0; i < 3; i++) {  
    printf("%.5f\n", D[i]/mag);  
}  
return 0;  
}
```

C Code: Formula Library (1/2)

```
#include <math.h>

void direction_cosines(double* D,
                      double* L) {
    double mag = sqrt(D[0]*D[0] +
                      D[1]*D[1] +
                      D[2]*D[2]);
```


C Code: Formula Library (2/2)

```
for (int i = 0; i < 3; i++) {  
    L[i] = D[i] / mag;  
}  
}
```

Python Code: Using .so (1/2)

```
import ctypes
import numpy as np
from sympy import Matrix, sqrt

lib = ctypes.CDLL('./libdircos.so')
dir_cos = lib.direction_cosines
dir_cos.argtypes = [
    ctypes.POINTER(ctypes.c_double),
    ctypes.POINTER(ctypes.c_double)
]
```

Python Code: Using .so (2/2)

```
D = np.array([2.0, 2.0, 3.0])
L = np.zeros(3)

dir_cos(D.ctypes.data_as(ctypes.POINTER(
    ctypes.c_double)),
        L.ctypes.data_as(ctypes.POINTER(
            ctypes.c_double)))

print("Direction Cosines:", L)
```

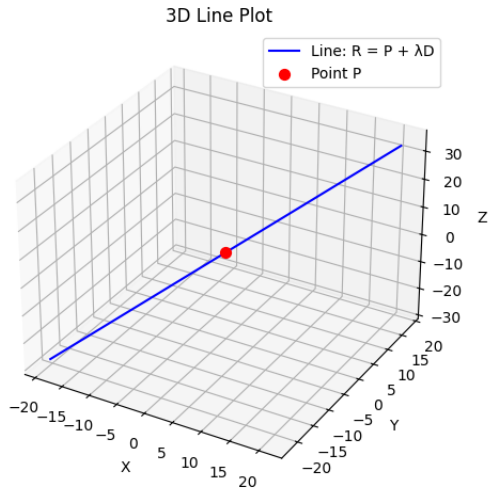


Figure: Line AB