

7.4.8

EE25BTECH11001 - Aarush Dilawri

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Question:

For each natural number k , let C_k denote the circle with radius k centimetres and centre at the origin. On the circle C_k , a particle moves k centimetres in the counter-clockwise direction. After completing its motion on C_k , the particle moves to C_{k+1} in the radial direction. The motion of the particle continues in this manner. The particle starts at $(1, 0)$. If the particle crosses the positive direction of the X axis for the first time on the Circle C_n , then $n =$ _

Solution:

$$\text{Let } \mathbf{p}_0 = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \quad (1)$$

We model a rotation by an angle θ using the rotation matrix

$$R(\theta) = \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix} \quad (2)$$

Note the group property of rotations:

$$R(\theta_1) R(\theta_2) = R(\theta_1 + \theta_2), \quad R(\theta)^k = R(k\theta). \quad (3)$$

On the circle C_k the particle moves an arc of length k on a circle of radius k , so the angular increment on C_k is

$$\Delta\theta_k = \frac{\text{arc length}}{\text{radius}} = \frac{k}{k} = 1 \quad (\text{radian}). \quad (4)$$

Thus each circular motion rotates the particle by 1 radian. We track the position of the particle at the instant it finishes its motion on C_k (that is, after the arc motion but before the radial jump to C_{k+1}).

Starting at \mathbf{p}_0 on C_1 , after finishing C_1 the position is

$$\mathbf{P}_1 = 1 R(1) \mathbf{p}_0. \quad (5)$$

Then the particle moves radially to C_2 , scaling the radius from 1 to 2, so just before moving on C_2 the vector is $2R(1)\mathbf{p}_0$. After moving on C_2 (an additional rotation by 1) the particle is at

$$\mathbf{P}_2 = 2 R(1)R(1) \mathbf{p}_0 = 2 R(2) \mathbf{p}_0. \quad (6)$$

By induction, after finishing its motion on C_k the particle is at

$$\mathbf{P}_k = k R(k) \mathbf{p}_0. \quad (7)$$

Therefore the angular coordinate of the particle after completing C_k is exactly k radians. The motion on C_n runs the angle from $(n - 1)$ to n (radians). Hence the particle crosses the positive x -axis during the motion on C_n precisely when some integer multiple of 2π lies in the interval $(n - 1, n]$, i.e. when there exists $m \in \mathbb{N}$ such that

$$n - 1 < 2\pi m \leq n. \quad (8)$$

Solution

We look for the smallest natural number n for which this happens. Take $m = 1$ (the first positive multiple of 2π). Compute

$$2\pi \approx 6.283185307 \dots \quad (9)$$

and observe

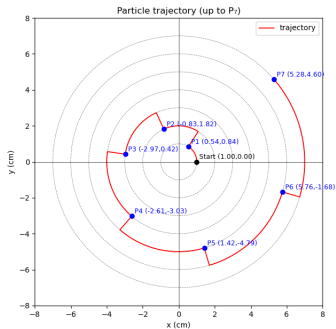
$$6 < 2\pi \leq 7. \quad (10)$$

Thus 2π lies in the interval $(6, 7]$, so the condition holds for $n = 7$ (with $m = 1$). For any $n \leq 6$ the interval $(n - 1, n]$ is contained in $[0, 6]$ and cannot contain $2\pi \approx 6.283 \dots$

Therefore the particle crosses the positive x -axis for the first time while moving on C_n with

$$\boxed{n = 7.} \quad (11)$$

Graphical Representation



C Code (code.c)

```
#include <stdio.h>
#include <math.h>

void particle_endpoints(int n, double *px, double *py, double *theta_out) {
    double theta = 0.0;
    for (int k = 1; k <= n; ++k) {
        double r = (double)k;
        // Arc length on C_k = k = 1 rad
        double delta = 1.0;
        theta += delta;
        px[k-1] = r * cos(theta);
        py[k-1] = r * sin(theta);
        if (theta_out != NULL) theta_out[k-1] = theta;
    }
}
```

Python Code (code.py)

```
import numpy as np
import matplotlib.pyplot as plt
```

```
# ----- Parameters
```

```
n = 7
arc_samples = 120
radial_samples = 30
```

```
# ----- Compute endpoints and angles
```

```
px, py, thetas = np.zeros(n), np.zeros(n), np.zeros(n)
theta = 0.0
for k in range(1, n + 1):
    theta += 1.0 # 1 rad per circle
```

Python Code (code.py)

```
path_x, path_y = [], []
theta_prev = 0.0
r_prev = 1.0
path_x.append(r_prev * np.cos(theta_prev))
path_y.append(r_prev * np.sin(theta_prev))

for k in range(1, n + 1):
    theta_curr = float(thetas[k - 1])
    r_curr = float(k)

    if k == 1:
        # Arc on C1
        angles = np.linspace(theta_prev, theta_curr, arc_samples + 1)[1:]
        for ang in angles:
            path_x.append(r_curr * np.cos(ang))
            path_y.append(r_curr * np.sin(ang))
```

else:

Radial outward

`radii = np.linspace(r_prev, r_curr, radial_samples + 1)[1:]`

for `rad` **in** `radii`:

`path_x.append(rad * np.cos(theta_prev))`

`path_y.append(rad * np.sin(theta_prev))`

Arc on C_k

`angles = np.linspace(theta_prev, theta_curr, arc_samples + 1)[1:]`

for `ang` **in** `angles`:

`path_x.append(r_curr * np.cos(ang))`

`path_y.append(r_curr * np.sin(ang))`

`theta_prev, r_prev = theta_curr, r_curr`

Python Code (code.py)

```
fig, ax = plt.subplots(figsize=(7, 7))
ax.set_aspect("equal")
ax.set_title("Particle-trajectory-(pure-Python)")

# Circles
theta_full = np.linspace(0, 2 * np.pi, 400)
for k in range(1, n + 1):
    ax.plot(k * np.cos(theta_full), k * np.sin(theta_full),
            linestyle="--", color="gray", linewidth=0.6)

# Trajectory
ax.plot(path_x, path_y, color="red", linewidth=1.3, label="trajectory")

# Points  $P..P$  with coordinates
ax.scatter(px, py, color="blue", zorder=5)
```

Python Code (code.py)

```
for i in range(n):
    label = f"P{i+1}-{px[i]:.2f},{py[i]:.2f})"
    ax.text(px[i] + 0.15, py[i] + 0.15, label, fontsize=9, color="blue")
ax.scatter([1.0], [0.0], color="black", zorder=6)
ax.text(1.0 + 0.15, 0.0 + 0.15, "Start-(1.00,0.00)", fontsize=9, color="
    black")
ax.axhline(0, color="k", linewidth=0.5)
ax.axvline(0, color="k", linewidth=0.5)
lim = n + 1
ax.set_xlim(-lim, lim)
ax.set_ylim(-lim, lim)
ax.set_xlabel("x-(cm)")
ax.set_ylabel("y-(cm)")
ax.legend()
plt.show()
```

Python Code (nativecode.py)

```
import ctypes
import numpy as np
import matplotlib.pyplot as plt
lib = ctypes.CDLL("./code.so")
lib.particle_endpoints.argtypes = [
    ctypes.c_int,
    np.ctypeslib.ndpointer(dtype=np.double, ndim=1, flags="
        C_CONTIGUOUS"),
    np.ctypeslib.ndpointer(dtype=np.double, ndim=1, flags="
        C_CONTIGUOUS"),
    np.ctypeslib.ndpointer(dtype=np.double, ndim=1, flags="
        C_CONTIGUOUS")
]
lib.particle_endpoints.restype = None
n = 7
arc_samples = 120
radial_samples = 30
```

Python Code (nativecode.py)

```
px = np.zeros(n, dtype=np.double)
py = np.zeros(n, dtype=np.double)
thetas = np.zeros(n, dtype=np.double)
lib.particle_endpoints(n, px, py, thetas)

# ----- Build continuous trajectory
-----

path_x, path_y = [], []
theta_prev = 0.0
r_prev = 1.0
path_x.append(r_prev * np.cos(theta_prev))
path_y.append(r_prev * np.sin(theta_prev))

for k in range(1, n + 1):
    theta_curr = float(thetas[k - 1])
    r_curr = float(k)
```


Python Code (nativecode.py)

```
if k == 1:
    # Only arc on C1
    angles = np.linspace(theta_prev, theta_curr, arc_samples + 1)[1:]
    for ang in angles:
        path_x.append(r_curr * np.cos(ang))
        path_y.append(r_curr * np.sin(ang))
else:
    # Radial outward line
    radii = np.linspace(r_prev, r_curr, radial_samples + 1)[1:]
    for rad in radii:
        path_x.append(rad * np.cos(theta_prev))
        path_y.append(rad * np.sin(theta_prev))

# Arc motion on C_k
```

Python Code (nativecode.py)

```
angles = np.linspace(theta_prev, theta_curr, arc_samples + 1)[1:]  
for ang in angles:  
    path_x.append(r_curr * np.cos(ang))  
    path_y.append(r_curr * np.sin(ang))
```

```
theta_prev, r_prev = theta_curr, r_curr
```

```
# ----- Plotting
```

```
fig, ax = plt.subplots(figsize=(7, 7))  
ax.set_aspect("equal")  
ax.set_title("Particle-trajectory-(up-to-P)")
```

```
# Draw circles C..C
```

```
theta_full = np.linspace(0, 2 * np.pi, 400)
```

Python Code (nativecode.py)

```
for k in range(1, n + 1):
    cx = k * np.cos(theta_full)
    cy = k * np.sin(theta_full)
    ax.plot(cx, cy, linestyle="--", color="gray", linewidth=0.6)

# Plot trajectory
ax.plot(path_x, path_y, color="red", linewidth=1.3, label="trajectory")

# Points  $P..P$  with coordinates
ax.scatter(px, py, color="blue", zorder=5)
for i in range(n):
    label = f"P{i+1}-{px[i]:.2f},{py[i]:.2f}"
    ax.text(px[i] + 0.15, py[i] + 0.15, label, fontsize=9, color="blue")
```

Python Code (nativecode.py)

```
ax.scatter([1.0], [0.0], color="black", zorder=6)
ax.text(1.0 + 0.15, 0.0 + 0.15, "Start-(1.00,0.00)", fontsize=9, color="
black")
```

Axes and formatting

```
ax.axhline(0, color="k", linewidth=0.5)
ax.axvline(0, color="k", linewidth=0.5)
lim = n + 1
ax.set_xlim(-lim, lim)
ax.set_ylim(-lim, lim)
ax.set_xlabel("x-(cm)")
ax.set_ylabel("y-(cm)")
ax.legend()
plt.show()
```