

## 4.13.6

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# Problem Statement

## Question:

Given the points **A**  $(0, 4)$  and **B**  $(0, -4)$ , the equation of the locus of the point **p**  $(x, y)$ , such that  $(AP - BP)^2 = 6^2$

## Step 1: Define Vectors

$$\mathbf{A}, \mathbf{B}, \mathbf{P} \in \mathbb{R}^n \quad (1)$$

Let the given scalar be  $\delta \geq 0$

$$(r_1 - r_2)^2 = \delta^2, \quad (2)$$

where  $r_1 = \|\mathbf{P} - \mathbf{A}\|$  and  $r_2 = \|\mathbf{P} - \mathbf{B}\|$ .

## Step 2: Taking Square root

Taking square root,

$$|r_1 - r_2| = \pm \delta \quad (3)$$

Let's define

$$D = s \delta \quad (4)$$

where  $s \in \{+1, -1\}$  such that

$$r_1 - r_2 = s\delta = D \quad (5)$$

## Step 3: Difference of Squares

Let's find  $r_1^2 - r_2^2$

$$\|\mathbf{P} - \mathbf{A}\|^2 - \|\mathbf{P} - \mathbf{B}\|^2 = (\mathbf{P} - \mathbf{A})^\top (\mathbf{P} - \mathbf{A}) - (\mathbf{P} - \mathbf{B})^\top (\mathbf{P} - \mathbf{B}) \quad (6)$$

$$= -2\mathbf{P}^\top \mathbf{u} + \mathbf{A}^\top \mathbf{A} - \mathbf{B}^\top \mathbf{B} = -2\mathbf{P}^\top \mathbf{u} + \alpha. \quad (7)$$

where

$$\mathbf{u} = \mathbf{A} - \mathbf{B} \quad \text{and} \quad \alpha = \mathbf{A}^\top \mathbf{A} - \mathbf{B}^\top \mathbf{B}. \quad (8)$$

## Step 4: Using $r_1^2 - r_2^2$ Identity

Use  $(r_1 - r_2)(r_1 + r_2) = r_1^2 - r_2^2$  and  $r_1 - r_2 = D$  to get

$$D(r_1 + r_2) = -2\mathbf{P}^\top \mathbf{u} + \alpha \implies r_1 + r_2 = \frac{-2\mathbf{P}^\top \mathbf{u} + \alpha}{D}. \quad (9)$$

Hence

$$r_1 = \frac{(r_1 - r_2) + (r_1 + r_2)}{2} = \frac{D}{2} + \frac{\alpha}{2D} - \frac{\mathbf{P}^\top \mathbf{u}}{D}. \quad (10)$$

## Step 5: Quadratic Form

Square this expression and equate to the explicit quadratic form for  $r_1^2$ :

$$\left( \frac{D}{2} + \frac{\alpha}{2D} - \frac{\mathbf{P}^\top \mathbf{u}}{D} \right)^2 = (\mathbf{P} - \mathbf{A})^\top (\mathbf{P} - \mathbf{A}) = \mathbf{P}^\top \mathbf{P} - 2\mathbf{P}^\top \mathbf{A} + \mathbf{A}^\top \mathbf{A}. \quad (11)$$

Multiply both sides by  $D^2$  and simplify to get the general quadratic (conic) equation:

$$\mathbf{P}^\top (\mathbf{u}\mathbf{u}^\top - D^2 \mathbf{I}) \mathbf{P} + (-(D^2 + \alpha)\mathbf{u} + 2D^2 \mathbf{A})^\top \mathbf{P} + \frac{(D^2 + \alpha)^2}{4} - D^2 \mathbf{A}^\top \mathbf{A} \quad (12)$$

## Step 6: Substitute Values

Substitute  $\mathbf{A} = \begin{pmatrix} 0 \\ 4 \end{pmatrix}$ ,  $\mathbf{B} = \begin{pmatrix} 0 \\ -4 \end{pmatrix}$  and  $\delta = 6$ .

$$\mathbf{u} = \mathbf{A} - \mathbf{B} = \begin{pmatrix} 0 \\ 8 \end{pmatrix} \quad (13)$$

$$\alpha = \mathbf{A}^\top \mathbf{A} - \mathbf{B}^\top \mathbf{B} = 16 - 16 = 0 \quad (14)$$

$$D = s\delta = \pm 6 \quad \Rightarrow \quad D^2 = 36 \quad (15)$$



## Step 7: Quadratic Matrix Equation

$$\mathbf{P}^T(\mathbf{u}\mathbf{u}^T - 36I)\mathbf{P} + (-D^2\mathbf{u} + 2D^2\mathbf{A})^T\mathbf{P} + \frac{D^4}{4} - 36\mathbf{A}^T\mathbf{A} = 0 \quad (16)$$

Compute each term:

$$\mathbf{u}\mathbf{u}^T = \begin{pmatrix} 0 & 0 \\ 0 & 64 \end{pmatrix}, \quad I = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \quad (17)$$

$$\mathbf{u}\mathbf{u}^T - 36I = \begin{pmatrix} -36 & 0 \\ 0 & 28 \end{pmatrix} \quad (18)$$

## Step 8: Linear and Constant Terms

Linear coefficient:

$$-D^2\mathbf{u} + 2D^2\mathbf{A} = -36 \begin{pmatrix} 0 \\ 8 \end{pmatrix} + 72 \begin{pmatrix} 0 \\ 4 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \quad (19)$$

Constant term:

$$\frac{D^4}{4} - 36\mathbf{A}^\top \mathbf{A} = 324 - 576 = -252 \quad (20)$$

## Step 9: Locus Equation

The locus is

$$\mathbf{P}^T \begin{pmatrix} -36 & 0 \\ 0 & 28 \end{pmatrix} \mathbf{P} - 252 = 0 \implies -36x^2 + 28y^2 = 252 \quad (21)$$

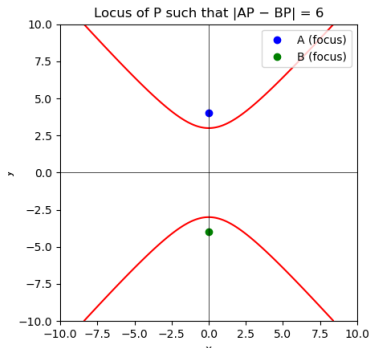
Dividing through:

$$\frac{y^2}{9} - \frac{x^2}{7} = 1 \quad (22)$$

Thus, the locus is a hyperbola centered at the origin:

$$\frac{y^2}{9} - \frac{x^2}{7} = 1 \quad (23)$$

# Figure



# C Code (code.c)

```
#include <stdio.h>
#include <math.h>
double inner_product(int n, double *u, double *v) {
    double sum = 0.0;
    for(int i=0; i<n; i++) {
        sum += u[i]*v[i];
    }
    return sum;
}

double locus_value(int n, double *A, double *B, double *P, double D)
{
    // Compute  $u = A - B$ 
    double u[10]; // assume dimension  $\leq 10$  for simplicity
    for(int i=0; i<n; i++) {
        u[i] = A[i] - B[i];
    }
}
```

## C Code (code.c)

```
double alpha = inner_product(n, A, A) - inner_product(n, B, B);  
double uuT_P[n];  
for(int i=0; i<n; i++) {  
    uuT_P[i] = u[i]*inner_product(n, u, P);  
}  
double quad = inner_product(n, P, uuT_P);  
quad -= D*D * inner_product(n, P, P);  
double coeff[n];  
for(int i=0; i<n; i++) {  
    coeff[i] = -(D*D+alpha)*u[i] + 2*D*D*A[i];  
}  
double lin = inner_product(n, coeff, P);  
double constant = ((D*D+alpha)*(D*D+alpha))/4.0 - D*D*  
    inner_product(n, A, A);  
  
return quad + lin + constant;  
}
```

# Python Code (code.py)

```
import numpy as np
import matplotlib.pyplot as plt

def inner_product(u, v):
    return np.dot(u, v)

def locus_value(A, B, P, D):
    u = A - B
    alpha = inner_product(A, A) - inner_product(B, B)
    quad = (np.dot(P, u))**2 - D*D*inner_product(P, P)
    coeff = -(D*D+alpha)*u + 2*D*D*A
    lin = inner_product(coeff, P)
    constant = ((D*D+alpha)**2)/4.0 - D*D*inner_product(A, A)

    return quad + lin + constant
```

# Python Code (code.py)

```
# Example: A=(0,4), B=(0,-4), delta=6  
A = np.array([0.0, 4.0])  
B = np.array([0.0, -4.0])  
D = 6.0  
  
x = np.linspace(-10, 10, 400)  
y = np.linspace(-10, 10, 400)  
X, Y = np.meshgrid(x, y)  
Z = np.zeros_like(X)
```



# Python Code (code.py)

```
for i in range(X.shape[0]):  
    for j in range(X.shape[1]):  
        P = np.array([X[i,j], Y[i,j]])  
        Z[i,j] = locus_value(A, B, P, D)  
  
plt.contour(X, Y, Z, levels=[0], colors="red")  
plt.axhline(0, color="k", linewidth=0.5)  
plt.axvline(0, color="k", linewidth=0.5)  
plt.gca().set_aspect("equal")  
plt.title("Locus-using-pure-Python")  
plt.show()
```

# Python Code (nativecode.py)

```
import ctypes
import numpy as np
import matplotlib.pyplot as plt

# Load the shared library
lib = ctypes.CDLL("./code.so")

# Define function signature
lib.locus_value.argtypes = [
    ctypes.c_int, # dimension
    np.ctypeslib.ndpointer(dtype=np.double), # A
    np.ctypeslib.ndpointer(dtype=np.double), # B
    np.ctypeslib.ndpointer(dtype=np.double), # P
    ctypes.c_double # D
]
lib.locus_value.restype = ctypes.c_double
```

# Python Code (nativecode.py)

```
# Example:  $A=(0,4)$ ,  $B=(0,-4)$ ,  $\delta=6$   
A = np.array([0.0, 4.0], dtype=np.double)  
B = np.array([0.0, -4.0], dtype=np.double)  
D = 6.0  
  
# Create grid and evaluate locus  
x = np.linspace(-10, 10, 400)  
y = np.linspace(-10, 10, 400)  
X, Y = np.meshgrid(x, y)  
Z = np.zeros_like(X)
```

## Python Code (nativecode.py)

```
for i in range(X.shape[0]):  
    for j in range(X.shape[1]):  
        P = np.array([X[i,j], Y[i,j]], dtype=np.double)  
        Z[i,j] = lib.locus_value(2, A, B, P, D)  
  
# Plot contour Z=0 (the locus)  
plt.contour(X, Y, Z, levels=[0], colors="blue")  
plt.axhline(0, color="k", linewidth=0.5)  
plt.axvline(0, color="k", linewidth=0.5)  
plt.gca().set_aspect("equal")  
plt.title("Locus-using-C-library")  
plt.show()
```