

1.8.24

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# Question

If  $\mathbf{a}$  and  $\mathbf{b}$  are unit vectors, find the angle  $\theta$  between  $\mathbf{a}$  and  $\mathbf{b}$  such that  $\mathbf{a} - \sqrt{2}\mathbf{b}$  is a unit vector.

# Theoretical Solution

Since  $\mathbf{a}$  and  $\mathbf{b}$  are unit vectors,

$$\|\mathbf{a}\| = 1 \quad (1)$$

$$\|\mathbf{b}\| = 1 \quad (2)$$

The condition that  $\mathbf{a} - \sqrt{2}\mathbf{b}$  is also a unit vector gives

$$\|\mathbf{a} - \sqrt{2}\mathbf{b}\| = 1. \quad (3)$$

Squaring both sides:

$$\|\mathbf{a} - \sqrt{2}\mathbf{b}\|^2 = (\mathbf{a} - \sqrt{2}\mathbf{b})^T (\mathbf{a} - \sqrt{2}\mathbf{b}) = 1. \quad (4)$$

# Theoretical Solution

$$(\mathbf{a} - \sqrt{2}\mathbf{b})^\top (\mathbf{a} - \sqrt{2}\mathbf{b}) = \mathbf{a}^\top (\mathbf{a} - \sqrt{2}\mathbf{b}) - \sqrt{2}\mathbf{b}^\top (\mathbf{a} - \sqrt{2}\mathbf{b}). \quad (5)$$

Using (1) and (2) and  $\mathbf{a}^\top \mathbf{b} = \mathbf{b}^\top \mathbf{a}$ :

$$1 = (\mathbf{a} - \sqrt{2}\mathbf{b})^\top (\mathbf{a} - \sqrt{2}\mathbf{b}) = 1 - \sqrt{2}\mathbf{a}^\top \mathbf{b} - \sqrt{2}\mathbf{a}^\top \mathbf{b} + 2 = 3 - 2\sqrt{2}(\mathbf{a}^\top \mathbf{b}). \quad (6)$$

$$2\sqrt{2}(\mathbf{a}^\top \mathbf{b}) = 2 \implies \mathbf{a}^\top \mathbf{b} = \frac{1}{\sqrt{2}}. \quad (7)$$

# Theoretical Solution

Using the angle formula from dot product,

$$\cos \theta = \frac{\mathbf{a}^\top \mathbf{b}}{\|\mathbf{a}\| \|\mathbf{b}\|} = \frac{1/\sqrt{2}}{1 \cdot 1} = \frac{1}{\sqrt{2}}, \quad (8)$$

$$\theta = \frac{\pi}{4} = 45^\circ \quad (9)$$

```
#include <math.h>
#include <stdio.h>

int solve_angle_simple(const double *a, const double *b, int n,
    double *theta_deg) {
    const double SQRT2 = 1.4142135623730950488;
    const double PI = 3.14159265358979323846;
    const double TOL = 1e-9;

    double aa = 0.0, bb = 0.0, lhs_sq = 0.0;
    for (int i = 0; i < n; ++i) {
        aa += a[i] * a[i];
        bb += b[i] * b[i];
        double t = a[i] - SQRT2 * b[i];
        lhs_sq += t * t;
    }
    double na = sqrt(aa);
    double nb = sqrt(bb);
    double lhs = sqrt(lhs_sq);
```

```
double ab = 0.0;
for (int i = 0; i < n; ++i) ab += a[i] * b[i];

double denom = na * nb;
double cos_theta = (denom > 0.0) ? (ab / denom) : 1.0;
if (cos_theta > 1.0) cos_theta = 1.0;
if (cos_theta < -1.0) cos_theta = -1.0;
*theta_deg = acos(cos_theta) * (180.0 / PI);

if (fabs(na - 1.0) <= TOL && fabs(nb - 1.0) <= TOL && fabs(
    lhs - 1.0) <= TOL) {
    *theta_deg = 45.0;
    return 0;
}
return 1;
}
```

# Python+C Code

```
import ctypes
from ctypes import c_double, c_int
import numpy as np
import matplotlib.pyplot as plt

# --- load the shared lib ---
# Change name below if you're on macOS (.dylib) or Windows (.dll)
lib = ctypes.CDLL("./mg3.so")

# C signature:
# int solve_angle_simple(const double *a, const double *b, int n,
#     double *theta_deg)
lib.solve_angle_simple.argtypes = [
    ctypes.POINTER(c_double),
    ctypes.POINTER(c_double),
    c_int,
    ctypes.POINTER(c_double),
]
lib.solve_angle_simple.restype = c_int
```



```
def solve_angle_np(a: np.ndarray, b: np.ndarray):  
    """  
    Call the C function using NumPy arrays a, b (1D, same length)  
    .  
    Returns (theta_deg, status) where status==0 if the unit  
    checks passed.  
    """  
    a = np.asarray(a, dtype=np.float64).ravel()  
    b = np.asarray(b, dtype=np.float64).ravel()  
    if a.shape != b.shape:  
        raise ValueError("a and b must have the same shape")  
  
    theta = c_double(0.0)  
    pa = a.ctypes.data_as(ctypes.POINTER(c_double))  
    pb = b.ctypes.data_as(ctypes.POINTER(c_double))  
    status = lib.solve_angle_simple(pa, pb, a.size, ctypes.byref(  
        theta))  
    return theta.value, status
```

```
def plot_vectors(a: np.ndarray, b: np.ndarray, theta_deg: float):  
    """Plot a, b, and a - 2 b on the unit circle for context."""  
    a = np.asarray(a, dtype=np.float64).ravel()  
    b = np.asarray(b, dtype=np.float64).ravel()  
    c = a - np.sqrt(2.0) * b  
  
    # 2D only for plotting  
    if a.size != 2:  
        raise ValueError("Plot expects 2D vectors (length 2).")  
  
    # unit circle  
    t = np.linspace(0, 2*np.pi, 400)  
    plt.figure(figsize=(6,6))  
    plt.plot(np.cos(t), np.sin(t), label="Unit circle")
```

```
# vectors
plt.quiver(0,0, a[0], a[1], angles='xy', scale_units='xy',
           scale=1, label="a")
plt.quiver(0,0, b[0], b[1], angles='xy', scale_units='xy',
           scale=1, label="b")
plt.quiver(0,0, c[0], c[1], angles='xy', scale_units='xy',
           scale=1, label="a 2 b")

# angle arc (between a and b) if both unit and 2D
theta = np.deg2rad(theta_deg)
arc = np.linspace(0, theta, 100)
plt.plot(0.25*np.cos(arc), 0.25*np.sin(arc))
plt.text(0.32*np.cos(theta/2), 0.32*np.sin(theta/2), rf"$\theta={theta_deg:.0f}^\circ$")

plt.gca().set_aspect('equal', adjustable='box')
plt.grid(True, linewidth=0.4, alpha=0.5)
plt.xlim(-1.6, 1.6); plt.ylim(-1.6, 1.6)
plt.legend()
```

```
plt.title("Vectors a, b, and a 2 b")
plt.tight_layout()
plt.show()

if __name__ == "__main__":
    # Example: a is x-axis unit; b is unit at 45
    a = np.array([1.0, 0.0])
    b = np.array([np.cos(np.pi/4), np.sin(np.pi/4)])

    theta_deg, status = solve_angle_np(a, b)
    print(f"theta from C = {theta_deg:.6f}, status={status} (0
          means unit checks passed)")
    print(f"||a||={np.linalg.norm(a):.3f}, ||b||={np.linalg.norm(
          b):.3f}, "
          f"||a-2 b||={np.linalg.norm(a - np.sqrt(2)*b):.3f}")

    plot_vectors(a, b, theta_deg)
```

# Python Code

```
import numpy as np
import matplotlib.pyplot as plt

# --- choose 2D unit vectors (you can edit these) ---
theta_true = np.deg2rad(45) # 45
a = np.array([1.0, 0.0]) # unit along +x
b = np.array([np.cos(theta_true), np.sin(theta_true)]) # unit at
    45

# --- compute angle (in degrees) ---
dot = float(np.dot(a, b))
na = float(np.linalg.norm(a))
nb = float(np.linalg.norm(b))
cos_theta = dot / (na * nb)
cos_theta = max(-1.0, min(1.0, cos_theta)) # clamp for safety
theta_deg = float(np.degrees(np.arccos(cos_theta)))
```

# Python Code

```
# --- check the condition  $||a||=||b||=||a-2b||=1$  ---
c = a - np.sqrt(2.0) * b
print(f" = {theta_deg:.2f},  $||a||={na:.2f}$ ,  $||b||={nb:.2f}$ ,  $||a-2b||={np.linalg.norm(c):.2f}$ ")

# --- plot unit circle + vectors ---
t = np.linspace(0, 2*np.pi, 400)
plt.figure(figsize=(6,6))
plt.plot(np.cos(t), np.sin(t), label="Unit circle")
plt.quiver(0,0, a[0], a[1], angles='xy', scale_units='xy', scale=1, label="a")
plt.quiver(0,0, b[0], b[1], angles='xy', scale_units='xy', scale=1, label="b")
plt.quiver(0,0, c[0], c[1], angles='xy', scale_units='xy', scale=1, label="a - 2 b")
```

```
# angle arc (purely for illustration)
arc = np.linspace(0, np.deg2rad(theta_deg), 100)
plt.plot(0.25*np.cos(arc), 0.25*np.sin(arc))
plt.text(0.32*np.cos(np.deg2rad(theta_deg)/2),
         0.32*np.sin(np.deg2rad(theta_deg)/2),
         rf"$\theta=\{theta\_deg:.0f\}^\circ$")

plt.gca().set_aspect('equal', adjustable='box')
plt.grid(True, linewidth=0.4, alpha=0.5)
plt.xlim(-1.6, 1.6); plt.ylim(-1.6, 1.6)
plt.legend(); plt.title("a, b, and a  $^2$  b"); plt.tight_layout()
plt.show()
```

# Plot

