## 2.10.73

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## Question

Let **A**, **B** and **C** be unit vectors. Suppose that  $\mathbf{A} \cdot \mathbf{B} = \mathbf{A} \cdot \mathbf{C} = 0$ , and that the angle between **B** and **C** is  $\frac{\pi}{6}$ . Then  $\mathbf{A} = \pm 2(\mathbf{B} \times \mathbf{C})$ 

#### Theoretical Solution

Let us solve the given equation theoretically and then verify the solution computationally.

Since  $\mathbf{A} \cdot \mathbf{B} = \mathbf{A} \cdot \mathbf{C} = 0$ , it follows that  $\mathbf{A}$  is perpendicular to both  $\mathbf{B}$  and  $\mathbf{C}$ . Therefore A is parallel(or anti-parallel) to the cross product of  $\mathbf{B}$  and  $\mathbf{C}$ .

$$\mathbf{A} = \lambda(\mathbf{B} \times \mathbf{C}) \tag{1}$$

From the given question,

$$\mathbf{B}^{\top}\mathbf{C} = \cos\left(\frac{\pi}{6}\right) \tag{2}$$

We know that,

$$\left(\mathbf{B}^{\mathsf{T}}\mathbf{C}\right)^{2} + ||\mathbf{B} \times \mathbf{C}||^{2} = ||\mathbf{B}||^{2}||\mathbf{C}||^{2}$$
(3)

## Theoretical Solution

$$\implies ||\mathbf{B} \times \mathbf{C}||^2 = \frac{1}{4} \tag{4}$$

$$\implies ||\mathbf{B} \times \mathbf{C}|| = \frac{1}{2} \tag{5}$$

As **A** is a unit vector, from(1)

$$||\mathbf{A}|| = ||\lambda(\mathbf{B} \times \mathbf{C})|| \tag{6}$$

$$1 = |\lambda| \frac{1}{2} \tag{7}$$

Hence

$$\lambda = \pm 2 \tag{8}$$

$$\therefore \mathbf{A} = \pm 2(\mathbf{B} \times \mathbf{C}) \tag{9}$$

#### C code

```
#include <stdio.h>
#include <math.h>
int main() {
   // Define B and C as given
   double B[3] = \{0.5, sqrt(3)/2, 0\};
   double C[3] = \{0.5, -sqrt(3)/2, 0\};
   double cross[3], A1[3], A2[3];
   // Cross product B x C
    cross[0] = B[1]*C[2] - B[2]*C[1]:
    cross[1] = B[2]*C[0] - B[0]*C[2]:
    cross[2] = B[0]*C[1] - B[1]*C[0];
   // A = 2(B \times C)
   for (int i=0; i<3; i++) {
       A1[i] = 2 * cross[i];
       A2[i] = -2 * cross[i]:
```

#### C code

```
// Print results
printf("Vector B = (\%.2f, \%.2f, \%.2f)n", B[0], B[1], B[2]);
printf("Vector C = (\%.2f, \%.2f, \%.2f) \n", C[0], C[1], C[2]);
printf("Cross Product (B x C) = (\%.2f, \%.2f, \%.2f)\n", cross
    [0], cross[1], cross[2]);
printf("A1 = +2(B \times C) = (\%.2f, \%.2f, \%.2f) \n", A1[0], A1[1],
     A1[2]);
printf("A2 = -2(B \times C) = (\%.2f, \%.2f, \%.2f) \n", A2[0], A2[1],
     A2[2]):
return 0;
```

# CallC.py

```
import ctypes
import numpy as np
import matplotlib.pyplot as plt
# Load shared library
lib = ctypes.CDLL("./vectors.so") # use "vectors.dll" on Windows
# Define argument and return types
lib.compute_vectors.argtypes = [
   np.ctypeslib.ndpointer(dtype=np.float64, ndim=1, flags="
       C CONTIGUOUS").
   np.ctypeslib.ndpointer(dtype=np.float64, ndim=1, flags="
       C CONTIGUOUS"),
   np.ctypeslib.ndpointer(dtype=np.float64, ndim=1, flags="
       C CONTIGUOUS").
   np.ctypeslib.ndpointer(dtype=np.float64, ndim=1, flags="
       C CONTIGUOUS"),
```

# CallC.py

```
# Input vectors
|B = np.array([0.5, np.sqrt(3)/2, 0.0], dtype=np.float64)
C = np.array([0.5, -np.sqrt(3)/2, 0.0], dtype=np.float64)
# Output arrays
A1 = np.zeros(3, dtype=np.float64)
A2 = np.zeros(3, dtype=np.float64)
# Call C function
lib.compute vectors(B, C, A1, A2)
# --- Plot ---
fig = plt.figure()
ax = fig.add subplot(111, projection="3d")
```

# CallC.py

```
vectors = {"B": B, "C": C, "A1": A1, "A2": A2}
colors = {"B": "r", "C": "g", "A1": "b", "A2": "m"}
for name, vec in vectors.items():
    ax.quiver(0,0,0, vec[0], vec[1], vec[2], color=colors[name],
        label=name)
    ax.text(vec[0], vec[1], vec[2], f"{name}{tuple(vec.round(2))}
ax.set_xlabel("X")
ax.set ylabel("Y")
ax.set zlabel("Z")
ax.set title("Vectors from C + Python (ctypes)")
ax.legend()
plt.show()
```

## Plot.py

```
import numpy as np
 import matplotlib.pyplot as plt
 from mpl_toolkits.mplot3d import Axes3D
 # Define vectors
B = np.array([1, 0, 0])
 C = np.array([np.cos(np.pi/6), np.sin(np.pi/6), 0])
cross_BC = np.cross(B, C)
 A1 = 2 * cross_BC
 A2 = -2 * cross BC
 # Plotting
 fig = plt.figure()
 ax = fig.add subplot(111, projection='3d')
 # Function to draw vectors
 def draw vector(ax, vec, color, label):
     ax.quiver(0, 0, 0, vec[0], vec[1], vec[2], color=color, label
         =label)
```

## Plot.py

```
# Draw vectors
draw_vector(ax, B, 'r', 'B')
draw_vector(ax, C, 'g', 'C')
draw_vector(ax, A1, 'b', 'A = +2(BC)')
draw_vector(ax, A2, 'm', 'A = -2(BC)')
# Axes settings
ax.set_xlim([-2, 2])
ax.set_ylim([-2, 2])
ax.set_zlim([-2, 2])
ax.set xlabel('X')
ax.set_ylabel('Y')
ax.set_zlabel('Z')
ax.legend()
ax.set title("Vectors A, B, C in 3D")
plt.show()
```

### **Plot**

To verify the solution computationally let us assume the vectors  ${\bf B}$  and  ${\bf C}$  as

$$\mathbf{B} = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \text{ and } \mathbf{C} = \begin{pmatrix} \frac{\sqrt{3}}{2} \\ \frac{1}{2} \\ 0 \end{pmatrix}$$



## Plot

