5.8.8

Application problem

EE25BTECH11010 - Arsh Dhoke

Question

Places A and B are 100km apart on a highway. One car starts from A and another from B at the same time. If the cars travel in the same direction at different speeds, they meet in 5 hrs. If they travel towards each other, they meet in 1 hr. What are the speeds of the two cars?

Solution: Step 1

Cars meet in 1 hr when moving towards each other:

$$v_1 + v_2 = \frac{100}{1} \tag{1}$$

Cars meet in 5 hr when moving in the same direction:

$$v_1 - v_2 = \frac{100}{5} \tag{2}$$

Solution: Matrix Form

$$\begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = \begin{pmatrix} 100 \\ 20 \end{pmatrix} \tag{3}$$

$$\begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix}^{-1} \begin{pmatrix} 100 \\ 20 \end{pmatrix} \tag{4}$$

Solution: Augmented Matrix Steps

$$\begin{pmatrix} 1 & 1 & 1 & 0 \\ 1 & -1 & 0 & 1 \end{pmatrix} \xrightarrow[R_2 \to R_2 - R_1]{} \begin{pmatrix} 1 & 1 & 1 & 0 \\ 0 & -2 & -1 & 1 \end{pmatrix}$$
 (5)

$$\stackrel{\longleftarrow}{\underset{R_2 \to -\frac{1}{2}R_2}{\longrightarrow}} \begin{pmatrix} 1 & 1 & 1 & 0 \\ 0 & 1 & \frac{1}{2} & -\frac{1}{2} \end{pmatrix}$$
(6)

$$\longleftrightarrow_{R_1 \to R_1 - R_2} \begin{pmatrix} 1 & 0 & \frac{1}{2} & \frac{1}{2} \\ 0 & 1 & \frac{1}{2} & -\frac{1}{2} \end{pmatrix}$$
(7)

Solution: Inverse Matrix

$$\begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = \begin{pmatrix} 60 \\ 40 \end{pmatrix}$$
 (10)

Graphical Representation

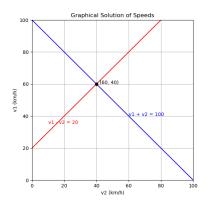


Figure: Graphical solution of speeds

C Code

```
#include <stdio.h>

void solve_car_speeds(double distance, double time_same_dir,
    double time_towards, double *v1, double *v2) {
    double sum_speeds = distance / time_towards;
    double diff_speeds = distance / time_same_dir;

    *v1 = (sum_speeds + diff_speeds) / 2.0;
    *v2 = sum_speeds - *v1;
}
```

Python Code

```
import matplotlib.pyplot as plt
import numpy as np
# Define v2 range
v2 = np.linspace(0, 100, 200)
# Equations
v1_towards = 100 - v2 # v1 + v2 = 100
v1 \text{ same} = 20 + v2 \# v1 - v2 = 20
# Plot
plt.figure(figsize=(6,6))
plt.plot(v2, v1 towards, color='blue')
plt.plot(v2, v1 same, color='red')
# Intersection point
v2 \text{ meet} = 40
v1 \text{ meet} = 60
```

Python Code

```
plt.plot(v2_meet, v1_meet, 'ko') # solution point
# Annotate the lines
plt.text(60, 40, 'v1 + v2 = 100', color='blue')
plt.text(10, 35, v1 - v2 = 20', color='red')
# Annotate solution point
plt.text(v2_meet + 2, v1_meet, '(60, 40)', color='black')
plt.xlabel('v2 (km/h)')
plt.ylabel('v1 (km/h)')
plt.title('Graphical Solution of Speeds')
plt.xlim(0, 100)
plt.ylim(0, 100)
plt.grid(True)
plt.savefig("/home/arsh-dhoke/ee1030-2025/ee25btech11010/matgeo
    /5.8.8/figs/speed.png")
plt.show()
```

Python+ C Code

```
import ctypes
import numpy as np
import matplotlib.pyplot as plt
# Load the shared library
lib = ctypes.CDLL('./code.so')
# Define argument and return types
lib.solve_car_speeds.argtypes = [
   ctypes.c_double, ctypes.c_double, ctypes.c_double,
   ctypes.POINTER(ctypes.c double), ctypes.POINTER(ctypes.
       c double)
# Function to call C function
def get speeds(distance, time same dir, time towards):
   v1 = ctypes.c double()
   v2 = ctypes.c double()
```

Python+ C Code

```
lib.solve_car_speeds(distance, time_same_dir, time_towards,
                                         ctypes.byref(v1), ctypes.byref(v2))
                     return v1.value, v2.value
  # Example
  distance = 100.0
time_same_dir = 5.0
  time_towards = 1.0
v1, v2 = get_speeds(distance, time_same_dir, time_towards)
print(f''v1 = \{v1\}, v2 = \{v2\}'')
  # Plot the lines v1 + v2 = distance / time towards and <math>v1 - v2 = distance / time towards and v1 - v2 = distance / time towards and v1 - v2 = distance / time towards and v1 - v2 = distance / time towards and v1 - v2 = distance / time towards and v1 - v2 = distance / time towards and v1 - v2 = distance / time towards and v1 - v2 = distance / time towards and v1 - v2 = distance / time towards and v1 - v2 = distance / time towards and v1 - v2 = distance / time towards and v1 - v2 = distance / time towards and v1 - v2 = distance / time towards and v1 - v2 = distance / time towards and v1 - v2 = distance / time towards and v1 - v2 = distance / time towards and v1 - v2 = distance / time towards and v1 - v2 = distance / time towards and v1 - v2 = distance / time towards and v1 - v2 = distance / time towards and v1 - v2 = distance / time towards and v1 - v2 = distance / time towards and v1 - v2 = distance / time towards and v1 - v2 = distance / time towards and v1 - v2 = distance / time towards and v1 - v2 = distance / time towards and v1 - v2 = distance / time towards and v1 - v2 = distance / time towards and v1 - v2 = distance / time towards and v1 - v2 = distance / time towards and v1 - v2 = distance / time towards and v1 - v2 = distance / time towards and v1 - v2 = distance / time towards and v1 - v2 = distance / time towards and v1 - v2 = distance / time towards and v1 - v2 = distance / time towards and v1 - v2 = distance / time towards and v1 - v2 = distance / time towards and v1 - v2 = distance / time towards and v1 - v2 = distance / time towards and v1 - v2 = distance / time towards and v1 - v2 = distance / time towards and v1 - v2 = distance / time towards and v1 - v2 = distance / time towards and v1 - v2 = distance / time towards and v1 - v2 = distance / time towards and v1 - v2 = distance / time towards and v1 - v2 = distance / time towards and v1 - v2 = distance / time towards and v1 - v2 = distance / time towards and v1 - v2 = distance / time towards and v1 - v2 = distance / time towards and v1 - v2 = di
                      distance / time same dir
 v2 \text{ vals} = np.linspace(0, 100, 200)
  v1 towards = distance / time towards - v2 vals
  v1 same = distance / time same dir + v2 vals
```

Python+ C Code