### 2.8.19

M Chanakya Srinivas- EE25BTECH11036

#### Problem Statement

Suppose for some non-zero vector  $\mathbf{r}$  we have:

$$\mathbf{r} \cdot \mathbf{a} = 0, \quad \mathbf{r} \cdot \mathbf{b} = 0, \quad \mathbf{r} \cdot \mathbf{c} = 0$$

Show that the scalar triple product  $(\mathbf{a} \ \mathbf{b} \ \mathbf{c}) = 0$ .

### Step 1: Write as Matrix Equation

The three scalar equations can be written as:

$$\mathbf{r}^{\mathsf{T}}\mathbf{a} = \mathbf{0} \tag{1}$$

$$\mathbf{r}^{\mathsf{T}}\mathbf{b} = 0 \tag{2}$$

$$\mathbf{r}^{\mathsf{T}}\mathbf{c} = 0 \tag{3}$$

Stacked together:

$$\begin{pmatrix} \mathbf{a}^{\top} \\ \mathbf{b}^{\top} \\ \mathbf{c}^{\top} \end{pmatrix} \mathbf{r} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \tag{4}$$

### Step 2: Define the Matrix

Define the  $3 \times 3$  matrix with columns **a**, **b**, **c**:

$$A = [\mathbf{a} \ \mathbf{b} \ \mathbf{c}] \tag{5}$$

Then the stacked matrix equation becomes:

$$A^{\top}\mathbf{r} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \tag{6}$$

# Step 3: Deduce Singularity

Since  $\mathbf{r} \neq \mathbf{0}$  and

$$A^{ op}\mathbf{r} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix},$$

the matrix  $A^{\top}$  is singular. Therefore:

$$\det(A^{\top}) = 0 \tag{7}$$

### Step 4: Relate to Scalar Triple Product

But  $det(A^{\top}) = det(A)$ , and the determinant of A is the scalar triple product:

$$(\mathbf{a} \ \mathbf{b} \ \mathbf{c}) = \det \left[ \mathbf{a} \ \mathbf{b} \ \mathbf{c} \right] = \det(A) = 0 \tag{8}$$

#### Conclusion

$$\boxed{(\mathbf{a}\;\mathbf{b}\;\mathbf{c})=0}$$

This completes the proof \*\*non-zero r orthogonal to all three vectors\*\*.

#### C Code

# Python code through shared output

```
import ctypes
 import matplotlib.pyplot as plt
 import numpy as np
 from mpl_toolkits.mplot3d import Axes3D
 # Load the shared library
 lib = ctypes.CDLL(./libstp.so)
 lib.scalar_triple.restype = ctypes.c_double
 # Define vectors
 a = (\text{ctypes.c\_double} * 3)(1, 0, 0)
 b = (\text{ctypes.c\_double} * 3)(0, 1, 0)
 c = (ctypes.c double * 3)(1, 1, 0)
 # Call the C function
 result = lib.scalar triple(a, b, c)
print(Scalar triple product =, result)
 # Convert to numpy arrays for plotting
 a \text{ vec} = np.array([a[0], a[1], a[2]])
 b_vec = np.array([b[0], b[1], b[2]])
 c_{vec} = np.array([c[0], c[1], c[2]])
```

# Python code through shared output

```
# Plot vectors in 3D
fig = plt.figure()
ax = fig.add subplot(111, projection='3d')
origin = np.array([0, 0, 0])
ax.quiver(*origin, *a vec, color='r', label='a')
ax.quiver(*origin, *b vec, color='g', label='b')
ax.quiver(*origin, *c vec, color='b', label='c')
ax.set_xlim([0, 1.5])
ax.set_ylim([0, 1.5])
ax.set zlim([0, 1.5])
ax.set_xlabel(X)
ax.set_ylabel(Y)
ax.set_zlabel(Z)
ax.set_title(fScalar Triple Product = {result})
ax.legend()
plt.show()
```

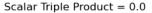
### Only Python code

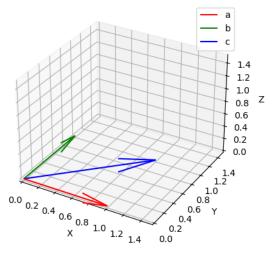
```
import numpy as np
import matplotlib.pyplot as plt
from mpl toolkits.mplot3d import Axes3D
# Define 3 coplanar vectors (lying in xy-plane)
a = np.array([1, 1, 0])
b = np.array([1, 0, 0])
c = np.array([0, 1, 0])
# Cross product b x c
b_cross_c = np.cross(b, c)
# Scalar triple product a . (b x c)
scalar_triple = np.dot(a, b_cross_c)
# Print the scalar triple product (should be 0)
print(fScalar triple product: {scalar_triple:.2f})
# Plotting
fig = plt.figure()
ax = fig.add_subplot(111, projection='3d')
```

### Only Python code

```
# Plot origin
 origin = np.array([0, 0, 0])
 # Plot vectors
 ax.quiver(*origin, *a, color='r', label='Vector a', linewidth=2)
 ax.quiver(*origin, *b, color='g', label='Vector b', linewidth=2)
 ax.quiver(*origin, *c, color='b', label='Vector c', linewidth=2)
 # Plot b x c
 ax.quiver(*origin, *b_cross_c, color='orange', linestyle='dashed'
     , label='b x c', linewidth=2)
 ax.set_xlim([0, 1.5])
 ax.set_ylim([0, 1.5])
 ax.set zlim([0, 1.5])
ax.set xlabel('X')
ax.set ylabel('Y')
 ax.set zlabel('Z')
 ax.set_title(f'Scalar Triple Product = {scalar_triple:.2f}')
 ax.legend()
 ax.grid(True)
plt.show()
```

### **PLOTS**





### **PLOTS**



