

4.12.26

Abhiram Reddy-AI25BTECH11021

September 24,2025

Question

Locus of the Foot of the Perpendicular

The line $\frac{x}{a} + \frac{y}{b} = 1$ moves in such a way that the condition

$$\frac{1}{a^2} + \frac{1}{b^2} = \frac{1}{c^2}$$

is satisfied, where c is a constant.

Prove that the locus of the foot of the perpendicular from the origin on the given line is $x^2 + y^2 = c^2$, using vector algebra with matrix notation and transpose.

Step 1: Vector Representation

Vector and Perpendicularity Conditions

- ① **Line Equation:** The line L is $\frac{x}{a} + \frac{y}{b} = 1$.

$$L : \mathbf{r}^T \mathbf{n} = 1, \quad \text{where } \mathbf{r} = \begin{pmatrix} x \\ y \end{pmatrix}, \mathbf{n} = \begin{pmatrix} 1/a \\ 1/b \end{pmatrix} \quad (\text{Equation 1})$$

- ② **Foot of Perpendicular P :** Let $P(x_0, y_0)$ have position vector $\mathbf{p} = \begin{pmatrix} x_0 \\ y_0 \end{pmatrix}$.

- ③ **Perpendicularity $\mathbf{p} \parallel \mathbf{n}$:** The vector \mathbf{p} is parallel to the normal \mathbf{n} .

$$\mathbf{p} = \lambda \mathbf{n} \quad \text{for some scalar } \lambda \quad (\text{Equation 2})$$

This gives the component relations:

$$\frac{1}{a} = \frac{x_0}{\lambda} \quad \text{and} \quad \frac{1}{b} = \frac{y_0}{\lambda} \quad (\text{Equation 3})$$

Steps 3 & 4: Locus Derivation

Substituting into the Line and Constraint Equations

- 4 **P lies on L:** Substitute \mathbf{p} into the line equation (Eq. 1):

$$\mathbf{p}^T \mathbf{n} = 1 \implies \frac{x_0}{a} + \frac{y_0}{b} = 1$$

Substitute (Eq. 3) into the above:

$$\frac{x_0^2}{\lambda} + \frac{y_0^2}{\lambda} = 1 \implies x_0^2 + y_0^2 = \lambda \quad (\text{Equation 4})$$

In matrix form: $\mathbf{p}^T \mathbf{p} = \lambda$.

- 5 **Apply the Constraint:** Substitute (Eq. 3) into the given condition $\frac{1}{a^2} + \frac{1}{b^2} = \frac{1}{c^2}$:

$$\left(\frac{x_0}{\lambda}\right)^2 + \left(\frac{y_0}{\lambda}\right)^2 = \frac{1}{c^2}$$
$$\frac{x_0^2 + y_0^2}{\lambda^2} = \frac{1}{c^2} \quad (\text{Equation 5})$$

- 6 **Solve for Locus:** Substitute λ from (Eq. 4) into (Eq. 5):

$$\frac{\lambda}{\lambda^2} = \frac{1}{c^2}$$

C Code: Locus Verification Function

Main Formula: $x^2 + y^2 = c^2$

The main formula is the equation of the locus. The C function verifies if a given point (x, y) lies on this locus for a constant c .

```
#include <stdio.h>
#include <math.h>

int verify_locus(double x, double y, double c) {
    double lhs = (x * x) + (y * y);
    double rhs = c * c;
    double tolerance = 1e-9;

    if (fabs(lhs - rhs) < tolerance) {
        return 1;
    } else {
        return 0;
    }
}
```

C Code: Main Execution

Testing the Locus Formula

```
int main() {  
    double constant_c = 5.0; // Locus is  $x^2 + y^2 = 25$   
  
    double x1 = 3.0; // Point (3, 4) is on the locus  
    double y1 = 4.0;  
  
    if (verify_locus(x1, y1, constant_c)) {  
        printf(Point (%.2f, %.2f) IS on the locus  $x^2 + y^2 = %.2$   
            f\n,  
            x1, y1, constant_c * constant_c);  
    } else {  
        printf(Point (%.2f, %.2f) is NOT on the locus.\n, x1, y1)  
            ;  
    }  
  
    double x2 = 1.0; // Point (1, 1) is not on the locus  
    double y2 = 1.0;
```

Python Code: Setup and Locus Data

Generating Data for the Plot

We use $c = 5$ and an example line with intercepts $a = 25/3$ and $b = 25/4$.

```
import numpy as np
import matplotlib.pyplot as plt

# 1. Define the constant c and the locus ( $x^2 + y^2 = c^2$ )
c = 5.0
c_squared = c * c

# Generate points for the circle (Locus)
theta = np.linspace(0, 2 * np.pi, 100)
x_locus = c * np.cos(theta)
y_locus = c * np.sin(theta)

# 2. Define a specific variable line and its foot of the
    perpendicular P(x0, y0)
x0 = 3.0
y0 = 4.0
```

Python Code: Plotting the Graphs

Visualization of the Locus and an Example Line

3. Create the plot

```
plt.figure(figsize=(8, 8))
```

Plot the Locus (Circle)

```
plt.plot(x_locus, y_locus, 'r--', label=f'Locus:  $x^2 + y^2 = \{c\_squared:.0f\}$ ')  
c_squared:.0f}
```

Plot the Variable Line L

```
plt.plot(x_line, y_line, 'b-', label=f'Variable Line L:  $\frac{x}{\{a:.2f\}} + \frac{y}{\{b:.2f\}} = 1$ ')  
x}\{\{a:.2f\}\} + \frac{y}{\{b:.2f\}} = 1$')
```

Plot the Foot of the Perpendicular P and Origin O

```
plt.plot(x0, y0, 'go', markersize=8, label=f'Foot P(\{x0:.0f\}, \{y0:.0f\})')  
:0f\})')
```

```
plt.plot([0, x0], [0, y0], 'g-', linestyle=':', linewidth=2,  
label='Perpendicular Segment  $\mathbf{OP}$ ')  
label='Perpendicular Segment  $\mathbf{OP}$ ')
```

```
plt.plot(0, 0, 'kx', markersize=8, label='Origin O(0, 0)')  
label='Origin O(0, 0)')
```


Plot

`figs/python_plot.png`