#### 1

# 12.371

## Puni Aditya - EE25BTECH11046

## **Question:**

Let  $T: P_3[0, 1] \to P_2[0, 1]$  be defined by (Tp)(x) = p''(x) + p'(x). Then the matrix representation of T with respect to the bases  $\{1, x, x^2, x^3\}$  and  $\{1, x, x^2\}$  of  $P_3[0, 1]$  and  $P_2[0, 1]$  respectively is

### **Solution:**

The transformation is

$$T(p)(x) = p''(x) + p'(x)$$
 (1)

The domain basis is

$$\mathcal{B} = \{1, x, x^2, x^3\} = \{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3, \mathbf{v}_4\}$$
 (2)

The codomain basis is

$$C = \{1, x, x^2\} = \{\mathbf{w}_1, \mathbf{w}_2, \mathbf{w}_3\}$$
 (3)

The matrix representation A is given by

$$\mathbf{A} = \begin{pmatrix} [T(\mathbf{v}_1)]_C & [T(\mathbf{v}_2)]_C & [T(\mathbf{v}_3)]_C & [T(\mathbf{v}_4)]_C \end{pmatrix}$$
(4)

The columns of **A** are computed by applying the transformation (1) to each basis vector in  $\mathcal{B}$ .

$$T(\mathbf{v}_1) = T(1) = 0(1) + 0(x) + 0(x^2) \Longrightarrow [T(\mathbf{v}_1)]_C = \begin{pmatrix} 0\\0\\0 \end{pmatrix}$$
 (5)

$$T(\mathbf{v}_2) = T(x) = 1(1) + 0(x) + 0(x^2) \implies [T(\mathbf{v}_2)]_C = \begin{pmatrix} 1\\0\\0 \end{pmatrix}$$
 (6)

$$T(\mathbf{v}_3) = T(x^2) = 2(1) + 2(x) + 0(x^2) \implies [T(\mathbf{v}_3)]_C = \begin{pmatrix} 2\\2\\0 \end{pmatrix}$$
 (7)

$$T(\mathbf{v}_4) = T(x^3) = 0(1) + 6(x) + 3(x^2) \implies [T(\mathbf{v}_4)]_C = \begin{pmatrix} 0 \\ 6 \\ 3 \end{pmatrix}$$
 (8)

This gives

$$\mathbf{A} = \begin{pmatrix} 0 & 1 & 2 & 0 \\ 0 & 0 & 2 & 6 \\ 0 & 0 & 0 & 3 \end{pmatrix} \tag{9}$$

The correct option is **2**).