1.4.16

EE25BTECH11001 - Aarush Dilawri

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Question

Find the coordinates of the points which trisect the line segment joining the points

$$P(4,2,-6)$$
 and $Q(10,-16,6)$.

Vectors

Let the vectors be

$$\mathbf{P} = \begin{pmatrix} 4 \\ 2 \\ -6 \end{pmatrix},\tag{1}$$

$$\mathbf{Q} = \begin{pmatrix} 10 \\ -16 \\ 6 \end{pmatrix}. \tag{2}$$

We want to find the points which divide PQ in the ratio 2:1 and 1:2.

Section Formula

Section formula: If a point divides the line joining **A** and **B** in the ratio k:1, then

$$\mathbf{P} = \frac{k\mathbf{B} + \mathbf{A}}{k+1}.$$

First Trisection Point

Using section formula for ratio 2:1,

$$\mathbf{S} = \frac{2\mathbf{Q} + \mathbf{P}}{3}$$

$$= \frac{\begin{pmatrix} 20 \\ -32 \\ 12 \end{pmatrix} + \begin{pmatrix} 4 \\ 2 \\ -6 \end{pmatrix}}{3}$$

$$(3)$$

$$=\frac{\begin{pmatrix} 24\\-30\\6 \end{pmatrix}}{3} \tag{5}$$

$$= \begin{pmatrix} 8 \\ -10 \\ 2 \end{pmatrix}. \tag{6}$$

Second Trisection Point

Using section formula for ratio 1:2,

$$\mathbf{R} = \frac{\mathbf{Q} + 2\mathbf{P}}{3}$$

$$= \frac{\begin{pmatrix} 10 \\ -16 \\ 6 \end{pmatrix} + \begin{pmatrix} 8 \\ 4 \\ -12 \end{pmatrix}}{3}$$

$$= \frac{\begin{pmatrix} 18 \\ -12 \end{pmatrix}}{3}$$

$$(8)$$

$$=\frac{\begin{pmatrix} 10\\-12\\-6\end{pmatrix}}{3} \tag{9}$$

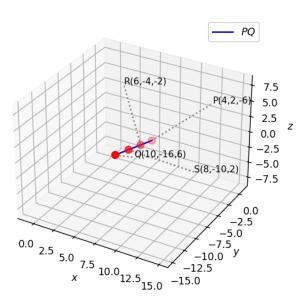
$$= \begin{pmatrix} 6 \\ -4 \\ -2 \end{pmatrix}. \tag{10}$$

Final Answer

Therefore, the points of trisection of PQ are

$$\mathbf{S} = \begin{pmatrix} 8 \\ -10 \\ 2 \end{pmatrix}, \quad \mathbf{R} = \begin{pmatrix} 6 \\ -4 \\ -2 \end{pmatrix}.$$

Plot



C Code (code.c)

```
\label{eq:float} \begin{tabular}{ll} \#include < stdio.h> \\ \hline $float \ findM(float \ Ax, \ float \ Ay, \ float \ Bx, \ float \ By, \ float \ Px) \ \{ \\ \hline $float \ k = (Px - Ax) \ / \ (Bx - Px); \\ \hline $float \ m = (k*By + Ay) \ / \ (k+1); \\ \hline $return \ m; \ \} \\ \end{tabular}
```

```
# Code by Aarush
# August 28, 2025
# Released under GNU GPL
# Section Formula — Trisection of a Line Segment in 3D
import numpy as np
import matplotlib.pyplot as plt
from mpl_toolkits.mplot3d import Axes3D
# Given points
P = np.array(([4, 2, -6])).reshape(-1,1)
Q = np.array(([10, -16, 6])).reshape(-1,1)
# Points dividing PQ in 1:2 and 2:1 (Trisection points)
R = (2*P + Q)/3 \# Point closer to P
S = (P + 2*Q)/3 \# Point closer to Q
```

```
# Plotting
fig = plt.figure()
ax = fig.add\_subplot(111, projection='3d')
# Line PQ
x_{vals} = [P[0,0], Q[0,0]]
y_{vals} = [P[1,0], Q[1,0]]
z_{\text{vals}} = [P[2,0], Q[2,0]]
ax.plot(x_vals, y_vals, z_vals, label='$PQ$', color="blue")
# All points
points = np.block([[P,Q,R,S]])
ax.scatter(points[0,:], points[1,:], points[2,:], color="red", s=50)
```

```
# Labels with offsets
labels = ['P', 'Q', 'R', 'S']
offsets = [(5,5,5), (5,-5,5), (-5,5,5), (5,5,-5)]
for i, txt in enumerate(labels):
    dx, dy, dz = offsets[i]
    ax.text(points[0,i]+dx, points[1,i]+dy, points[2,i]+dz,
             f'{txt}({points[0,i]:.0f},{points[1,i]:.0f},{points[2,i]:.0f})',
             fontsize=9, color="black")
    ax.plot([points[0,i], points[0,i]+dx],
              [points[1,i], points[1,i]+dy],
              [points[2,i], points[2,i]+dz],
             color="gray", linestyle="dotted")
```

```
# Equal axis scaling
max\_range = np.array([points[0,:].max()-points[0,:].min(),
                       points[1,:].max()-points[1,:].min(),
                       points[2,:].max()-points[2,:].min()]).max() / 2.0
mid_x = (points[0,:].max()+points[0,:].min()) * 0.5
mid_y = (points[1,:].max()+points[1,:].min()) * 0.5
mid_z = (points[2,:].max()+points[2,:].min()) * 0.5
ax.set_x lim(mid_x - max_range, mid_x + max_range)
ax.set_ylim(mid_y - max_range, mid_y + max_range)
ax.set_z lim(mid_z - max_range, mid_z + max_range)
ax.set_xlabel('$x$')
ax.set_ylabel('$y$')
ax.set_zlabel('$z$')
ax.legend()
ax.grid(True)
plt.show()
```

```
import ctypes
import numpy as np
import matplotlib.pyplot as plt
from mpl_toolkits.mplot3d import Axes3D
# --- Load shared library ---
lib = ctypes.CDLL("./code.so")
# Configure ctypes function signature
lib.findM.argtypes = [ctypes.c_float, ctypes.c_float,
                       ctypes.c_float, ctypes.c_float, ctypes.c_float]
lib.findM.restype = ctypes.c_float
```

```
def point_on_line(A, B, Px):
    """Compute (x,y,z) for given Px using the C function findM"""
    Ax, Ay, Az = A
    Bx, By, Bz = B
    y = lib.findM(Ax, Ay, Bx, By, Px)
    z = lib.findM(Ax, Az, Bx, Bz, Px)
    return np.array([Px, y, z], dtype=float)
# --- Given points ---
P = np.array([4.0, 2.0, -6.0])
Q = np.array([10.0, -16.0, 6.0])
# Trisection (1:2 and 2:1 ratios)
Rx = (2*P[0] + Q[0]) / 3
Sx = (P[0] + 2*Q[0]) / 3
```

```
# --- Plotting ---
fig = plt.figure()
ax = fig.add_subplot(111, projection='3d')
# Line PQ
ax.plot([P[0],Q[0]], [P[1],Q[1]], [P[2],Q[2]], label='$PQ$', color="blue")
# Collect points
points = np.stack([P,Q,R,S], axis=1)
ax.scatter(points[0,:], points[1,:], points[2,:], color="red", s=50)
# Labels with offsets + dotted connectors
labels = ['P', 'Q', 'R', 'S']
offsets = [(5,5,5), (5,-5,5), (-5,5,5), (5,5,-5)]
```

```
for i, txt in enumerate(labels):
    dx, dy, dz = offsets[i]
    ax.text(points[0,i]+dx, points[1,i]+dy, points[2,i]+dz,
             f'{txt}({points[0,i]:.0f},{points[1,i]:.0f},{points[2,i]:.0f})',
             fontsize=9, color="black")
    ax.plot([points[0,i], points[0,i]+dx],
             [points[1,i], points[1,i]+dy],
             [points[2,i], points[2,i]+dz],
             color="gray", linestyle="dotted")
# Equal axis scaling
max\_range = np.array([points[0,:].max()-points[0,:].min(),
                        points[1::].max()-points[1::].min(),
                        points[2,:].max()-points[2,:].min()]).max() / 2.0
```

```
mid_x = (points[0,:].max()+points[0,:].min()) * 0.5
mid_y = (points[1,:].max()+points[1,:].min()) * 0.5
mid_z = (points[2,:].max()+points[2,:].min()) * 0.5
ax.set_x lim(mid_x - max_range, mid_x + max_range)
ax.set_ylim(mid_y - max_range, mid_y + max_range)
ax.set_z lim(mid_z - max_range, mid_z + max_range)
ax.set_xlabel('$x$')
ax.set_ylabel('$y$')
ax.set_zlabel('$z$')
ax.legend()
ax.grid(True)
plt.show()
```