1. Note that according to the schematic there is one error, the connection made to PIN no. 7 on the Arduino board needs to be done to Pin No.3 because Pin No. 3 is capable of PWM signals.

2. However, the code already has Pin No.3 mention in the servo\_motor.attach() function on Line No. 27.

3. The 3D view of the Maze:

https: //collaborate.shapr3d.com/v/X0Y1zKj0ExaJTZhE\_Q\_wt

4. The 3D view of a robot similar to our robot: <https://collaborate.shapr3d.com/v/FQUXx87Ym8ulhwN100Ehz>

5. PPT link  <https://www.canva.com/design/DAFLuaQ3shk/MwbPBWT8HPmvjLdlb3w2zA/edit?utm_content=DAFLuaQ3shk&utm_campaign=designshare&utm_medium=link2&utm_source=sharebutton>