Concept Learning, Version Space learning, Candidate Elimination Algorithm

By

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General Terms

- Concept learning: Concept learning is basically learning task of the machine (Learn by Train data)
- General Hypothesis: Not Specifying features to learn the machine.

- $G = \{`?', `?', ?', ?', ?' ... \}$: Number of attributes
- Specific Hypothesis: Specifying features to learn machine (Specific feature)
- S= {'pi','pi','pi'...}: Number of pi depends on number of attributes.
- Version Space: It is intermediate of general hypothesis and Specific hypothesis. It not only just written one hypothesis but a set of all possible hypothesis based on training data-set.

Candidate elimination algorithm

Space obj(X, Y, Z)

Concept

obj(X, Y, ball) obj(X, red, Z) obj(small, Y, Z)

```
obj(X, red, ball) obj(small, Y, ball) obj(small, orange, ball)
```

obj(small, red, ball)

4. Learning in version space

Generalization operators in version space

- Replace constants with variables color(ball, red) color(X, red)
- Remove literals from conjunctions shape(X, round) \land size(X, small) \land color(X, red)

3

```
shape(X, round) \land color(X, red)
```

Add disjunctions

```
shape(X, round) \land size(X, small) \land color(X, red) shape(X, round) \land size(X, small) \land (color(X, red) \lor color(X, blue))
```

■ Replace an class with the superclass in is-a relations is-a(tom, cat) is-a(tom, animal)

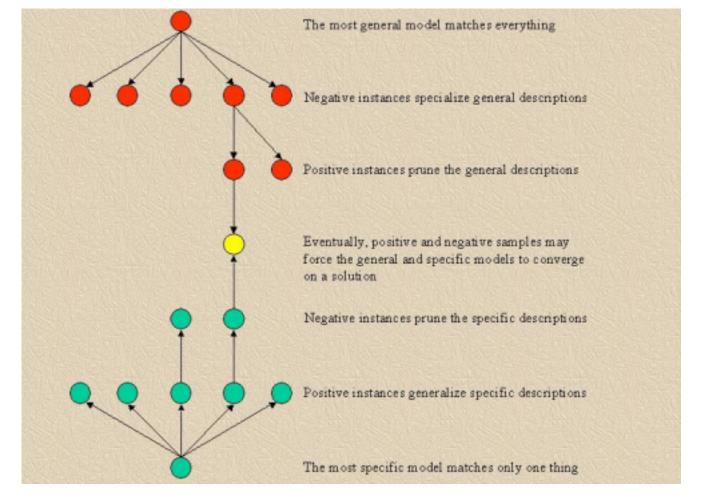
Candidate elimination algorithm

Version space

- Version space = the set of all concept descriptions which are consistent with the learning/training examples.
- What is the idea? = reduce the version space based on learning examples

- 1 algorithm from specific to general
- 1 algorithm from general to specific
- 1 algorithm bidirectional search = candidate elimination algorithm

Candidate elimination algorithm



Version Space Diagram

Generalization and specialization

• Ideally, the learned concept must be general enough to cover all positive examples and also must be specific enough to

- exclude all negative examples.
- one concept that would cover all sets of exclusively positive instances would simply be obj(X, Y, Z). However, this concept is probably too general, because it implies that all instances belong to the target concept.
 - One way to avoid overgeneralization is to generalize as little as possible to cover positive examples; another is to use negative instances to eliminate overly general concepts

Generalization and

specialization

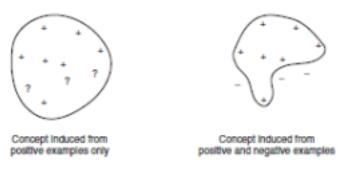


Figure 10.6 The role of negative examples in preventing overgeneralization.

negative instances prevent overgeneralization by forcing the learner to specialize concepts in order to exclude negative instances.

Algorithm for searching from specific to general

- 1. Initialize S with the first ex+
- 2. Initialize \mathbf{N} with the empty set
- 3. for every learning example repeat
 - 3.1 if ex+, p, then
 for each s ∈ S repeat
 - if s does not cover p then replace s with

the most specific generalization which covers ${m p}$ - Remove from ${m S}$ all hypothesis more general than other hypothesis from ${m S}$

- Remove from ${\bf S}$ all hypothesis which cover an ex- from ${\bf N}$
- 3.2 if ex-, n, then
 - Remove from ${\bf S}$ all hypothesis which cover ${\bf n}$
- Add \boldsymbol{n} to \boldsymbol{N} (to check for overgeneralization) end

Algorithm for searching from specific to general

S: { }

11

S: { obj(small, red, ball) } S: { obj(small, Y, ball) } S: { obj(X, Y, ball) }

Positive: obj(small, red, ball) Positive: obj(small, white, ball) Positive:

obj(large, blue, ball)

- 1. Initialize ${\bf G}$ with the most general description 2. Initialize ${\bf P}$ with the empty set
- 3. for every learning example repeat
 - 3.1 if ex-, n, then

for each $g \in G$ repeat

- if ${\it g}$ covers ${\it n}$ then replace ${\it g}$ with the most general specialization which does not cover ${\it n}$ Remove from ${\it G}$ all the hypothesis more specific than other hypothesis in ${\it G}$
- Remove from ${\bf G}$ all hypothesis which does not cover the positive examples from ${\bf P}$
- 3.2 if ex+, p, then
- Remove from ${\bf G}$ all the hypothesis that does not cover ${m p}$
- Add \boldsymbol{p} to \boldsymbol{P} (to check for overspecialization) **end**

G: { obj(X, Y, Z) }

(X, white, Z),

G: { obj(large, Y, Z), obj(X, white, Z), obj(X, Y, ball) }

G: { obj(large, Y, Z), obj(X, white, Z), Negative: obj(small, red, brick)

G: {obj(X, white, Z), obj(X, Y, ball) }

Positive: obj(large, white,

G: obj(X, Y, ball)

ball)

Negative: obj(large, blue, cube) Positive:

obj(X, blue, Z), obj(X, Y, ball), obj(X, Y, cube) }

Algorithm for searching in version space

- 1. Initialize **G** with the most general description 2. Initialize **S** with the first ex+
- 3. for every learning example repeat
 - 3.1 if ex+, p, then
 - ${\bf 3.1.1}$ Remove from ${\bf G}$ all the elements that does not cover ${m p}$
 - 3.1.2 for each $s \in S$ repeat
 - if ${\boldsymbol s}$ does not cover ${\boldsymbol p}$ then replace ${\boldsymbol s}$ with the most specific generalization which covers ${\boldsymbol p}$ Remove from ${\boldsymbol S}$ all hypothesis more general than other hypothesis in ${\boldsymbol S}$
 - Remove from **S** all hypothesis more general

Algorithm for searching in version space - cont

- 3.2 if ex-, n, then
- ${\bf 3.2.1}$ Remove from ${\bf S}$ all the hypothesis that cover ${\bf n}$
 - 3.2.2 for each $q \in G$ repeat

consistent with all hypothesis

- if ${m g}$ covers ${m n}$ then replace ${m g}$ with the most general specialization which does not cover ${m n}$ Remove from ${m G}$ all hypthesis more specific than other hypothesis in ${m G}$
- Remove from ${\bf G}$ all hypthesis more specific than other hypothesis in ${\bf S}$
- 4. if G = S and card(S) = 1 then a concept is found
 5. if G = S = { } then there is no concept

Algorithm for searching in version space

```
G: { obj(X, Y, Z) }
S: { }
G: { obj(X, red, ball) }
S: { obj(X, red, ball) }
Positive: obj(small, red, ball) }
G: { obj(x, red, ball) }
G: { obj(x, red, ball) }
Negative: obj(small, blue, ball) Positive: S: { obj(small, red, ball) }
```

G: { obj(X, red, Z) } S: { obj(X, red, ball) } obj(large, red, ball)

Negative: obj(large, red, cube)

17

Example

		AirTemp	Humidity	Wind	Water	Forecast	EnjoySport
1 S	Sunny	Warm	Normal	Strong	Warm	Same	Yes
2 S	Sunny	Warm	High	Strong	Warm	Same	Yes
3 F	Rain	Cold	High	Strong	Warm	Change	No
4 S	Sunny	Warm	High	Strong	Cool	Change	Yes



• First example is positive, we go to generic boundary and check If the

hypothesis at the generic boundary is consistent with the input/training sample or not. If consistent, we will retain the generic hypothesis else we have to write the next general hypothesis

- ☐ Compare G0 with first sample , All question marks matches with sample1, hence the classification is positive(yes) which is consistent with the label of the sample1. G1 same as G0
- Now go to specific boundary and check if the hypothesis at the specific boundary is consistent with the input/training sample or not \(\text{Compare S0} \) with first sample. S0 has all null. No match hence negative classification which is not consistent with the label of sample1 (positive/yes). Replice null with sample1



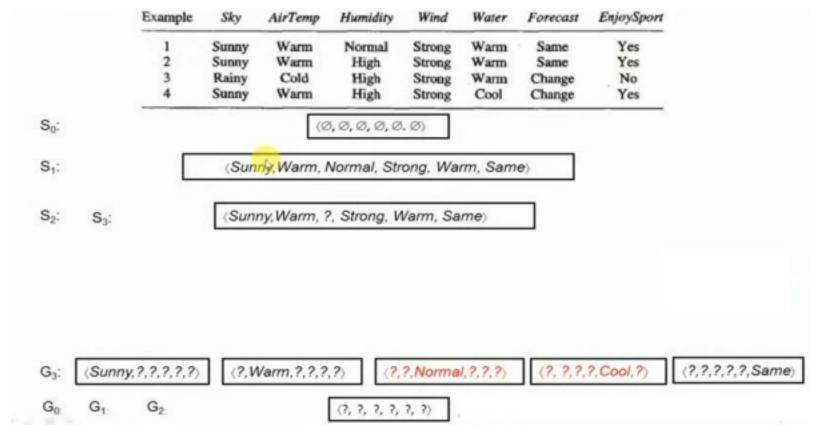
 Second example is positive, we go to generic boundary and check If the hypothesis at the generic boundary is consistent with the

- input/training sample or not. If consistent, we will retain the generic hypothesis else we have to write the next general hypothesis
 - ☐ Compare G1 with second sample , All question marks matches with sample2, hence the classification is positive(yes) which is consistent with the label of the sample2. G2 same as G1
- Now go to specific boundary and check if the hypothesis at the specific boundary is consistent with the input/training sample or not ☐ Compare S1 with second sample. Retain Sunny and warm as they are matching with sample2. Normal not matching with High, negative classification. Expected is positive. Replace Normal with ?. Strong, warm and same matching, hence consistent. Retain



 Third example is negative, we go to specific boundary and check If the hypothesis at the specific boundary is consistent with the input/training sample or not. If consistent, we will retain the specific hypothesis else we have to write the next specific hypothesis

- □ Compare S2 with third sample , Sunny not matching with rainy, hence negative classification which is consistent with the label of sample3.
 Retain. S3=S2
- Now go to generic boundary and check if the hypothesis at the specific boundary is consistent with the input/training sample or not. If yes, retain. If No, we will write all hypothesis which are consistent with all the training examples/samples seen till now
 - ☐ G2 is all ?s. Matches with sample3. Positive classification. Expected is negative (label of sample3). Not consistent. Hence write all hypothesis which are consistent with sample1, sample2 and sample3. For this consider one ? at a time. Ex first ?. The first attribute is Rainy in sample3. Substitute opposite of Rainy in place of first ? Which is Sunny and rest all ? Will be retain. Now consider second ? And repeat same. Now for all hypothesis formed so, check for consistency with Sample1, sample2 and sample3 (samples seen till now). Retain consistent. Remove inconsistent (red ones)



• Fourth example is positive, we go to generic boundary and check If the hypothesis at the generic boundary is consistent with the input/training sample or not. If consistent, we will retain the generic hypothesis else we have to write the next general hypothesis

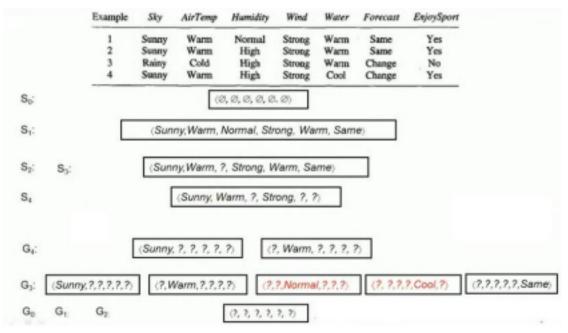
Compare all hypothesis in G3 with the training sample4. Retain those ones in G4 which are consistent with Sample4 and remove other inconsistent hypothesis

Now go to specific boundary and check if the hypothesis at the specific boundary is consistent with the input/training sample or not

Compare S3 with sample4. Sunny, warm matches. ? matches with high. Warm

not matching with Cool and Same not matching with change. Replace Warm and

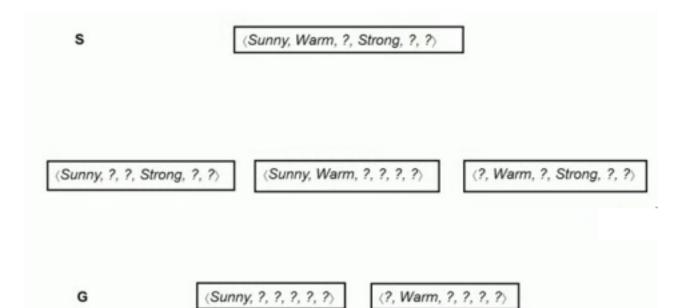
Same in S3 with ? to get S4.



- All training samples are over
- S4 and G4 not same. There are more than one hypothesis. So we need to write few more hypothesis considering S4 and G4. If S4 would have been same as G4, it would have been perfect classification and we would not have written more hypothesis

Learned Version Space by Candidate Elimination Algorithm (Sunny, Warm, ?, Strong, ?, ?) (?, Warm, ?, ?, ?, ?) (Sunny, ?, ?, ?, ?, ?) G

- All training samples are over
- S4 and G4 not same. There are more than one hypothesis. So we need to write few more hypothesis considering S4 and G4. If S4 would have been same as G4, it would have been perfect classification and we would not have written more hypothesis. Compare S4 with all hypothesis in G4 one by one. Warm and ? not matching so replace ? By Warm etc. Here consistent hypothesis are 6



Candidate Elimination Algo Ex

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Candidate Elimination Algorithm

Color

Red

Red

Red

Blue

Blue

S1: (0, 0, 0)

S2: (0, 0, 0)

S3: (Small, Red, Circle)

S4: (Small, Red, Circle)

S5: (Small, ?, Circle)

S: G: (Small, ?, Circle)

G5: (Small, ?, Circle)

G4: (Small, ?, Circle)

G3: (Small, ?, Circle)

G2: (Small, Blue, ?) (Small, ?, Circle)

(?, Blue, ?)

Size

Big

Small

Small

Small

Big

(Big, ?, Triangle)

(?, Blue, Triangle)

Shape

Circle

Circle

Circle

Circle

Triangle

Class / Label

No

No

Yes

No

Yes

G1: (Small, ?, ?)

(?, Blue, ?)

(?, ?, Triangle)

G0: (?, ?, ?)

2