### **Gradient Descent**

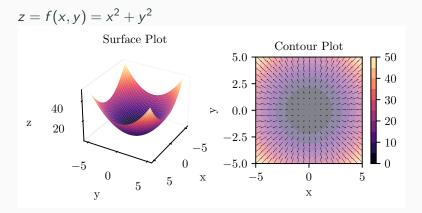
Nipun Batra

February 3, 2024

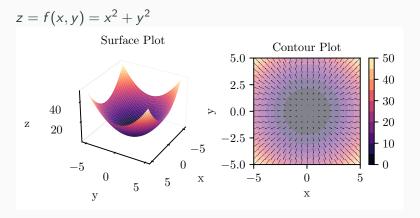
IIT Gandhinagar

# **Revision**

#### **Contour Plot And Gradients**



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Gradient denotes the direction of steepest ascent or the direction in which there is a maximum increase in f(x,y)

#### **Contour Plot And Gradients**

$$z = f(x, y) = x^{2} + y^{2}$$
Surface Plot
$$z = 40$$

$$z = 20$$

$$z = 50$$

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Gradient denotes the direction of steepest ascent or the direction in which there is a maximum increase in f(x,y)

$$\nabla f(x,y) = \begin{bmatrix} \frac{\partial f(x,y)}{\partial x} \\ \frac{\partial f(x,y)}{\partial y} \end{bmatrix} = \begin{bmatrix} 2x \\ 2y \end{bmatrix}$$

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ullet Note, here heta is the parameter vector

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- Goal:

$$\theta^* = \underset{\theta}{\operatorname{arg\,min}} f(\theta) \tag{2}$$

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- It is a local search algorithm/greedy

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The vector form of the above equation is given by:

$$f(\vec{x}) = f(\vec{x_0}) + \nabla f(\vec{x_0})^T (\vec{x} - \vec{x_0}) + \frac{1}{2} (\vec{x} - \vec{x_0})^T \nabla^2 f(\vec{x_0}) (\vec{x} - \vec{x_0}) + \dots$$
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• where  $\nabla^2 f(\vec{x_0})$  is the Hessian matrix and  $\nabla f(\vec{x_0})$  is the gradient vector

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- We can write the second order Taylor's series as:
- $f(x) = 1 + 0(x 0) + \frac{-1}{2!}(x 0)^2 = 1 \frac{x^2}{2}$

• Let us consider another example:  $f(x) = x^2 + 2$  and  $x_0 = 2$ 

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- Question: How does the first order Taylor's series approximation look like?
- First order Taylor's series approximation is given by:

• 
$$f(x) = f(x_0) + f'(x_0)(x - x_0) = 6 + 4(x - 2) = 4x - 2$$

• We have:

$$f(x) = f(x_0) + \frac{f'(x_0)}{1!}(x - x_0) + \frac{f''(x_0)}{2!}(x - x_0)^2 + \dots$$
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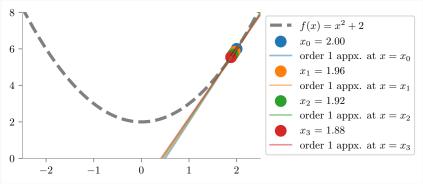
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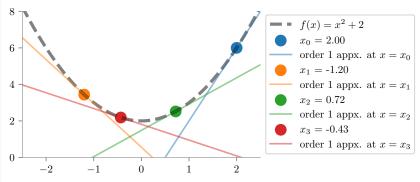
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- This happens when  $\Delta \vec{x} = -\alpha \nabla f(\vec{x_0})$  where  $\alpha$  is a scalar
- This is the gradient descent algorithm:  $\vec{x_1} = \vec{x_0} \alpha \nabla f(\vec{x_0})$

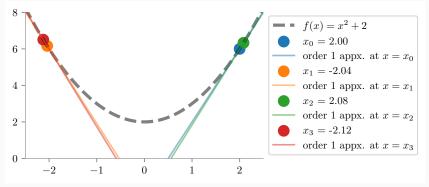
Low learning rate  $\alpha = 0.01$ : Converges slowly



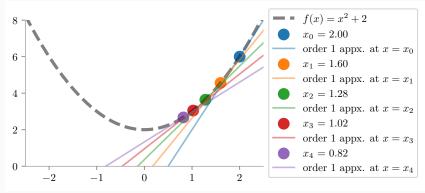
High learning rate  $\alpha = 0.8$ : Converges quickly, but might overshoot



Very high learning rate  $\alpha = 1.01$ : Diverges



#### Appropriate learning rate $\alpha = 0.1$



# **Gradient Descent for linear** regression

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- Mean Squared Error  $MSE(\theta) = \frac{1}{N} \sum_{i=1}^{N} (f(x_i|\theta) y_i)^2$

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- Mean Squared Error  $MSE(\theta) = \frac{1}{N} \sum_{i=1}^{N} (f(x_i|\theta) y_i)^2$
- **Objective function** is the most general term for any function that you optimize during training.

Learn  $y=\theta_0+\theta_1x$  on following dataset, using gradient descent where initially  $(\theta_0,\theta_1)=(4,0)$  and step-size,  $\alpha=0.1$ , for 2 iterations.

x	у
1	1
2	2
3	3

Our predictor, 
$$\hat{y} = \theta_0 + \theta_1 x$$

Error for 
$$i^{th}$$
 datapoint,  $\epsilon_i = y_i - \hat{y}_i$   
 $\epsilon_1 = 1 - \theta_0 - \theta_1$   
 $\epsilon_2 = 2 - \theta_0 - 2\theta_1$   
 $\epsilon_3 = 3 - \theta_0 - 3\theta_1$ 

$$\mathsf{MSE} = \frac{\epsilon_1^2 + \epsilon_2^2 + \epsilon_3^2}{3} = \frac{14 + 3\theta_0^2 + 14\theta_1^2 - 12\theta_0 - 28\theta_1 + 12\theta_0\theta_1}{3}$$

#### Difference between SSE and MSE

$$\sum \epsilon_i^2$$
 increases as the number of examples increase

So, we use MSE

$$MSE = \frac{1}{n} \sum_{i} \epsilon_i^2$$

Here n denotes the number of samples

$$\frac{\partial \textit{MSE}}{\partial \theta_0} = \frac{2\sum\limits_{i} \left(y_i - \theta_0 - \theta_1 x_i\right) \left(-1\right)}{\textit{N}} = \frac{2\sum\limits_{i} \epsilon_i \left(-1\right)}{\textit{N}}$$

$$\frac{\partial \textit{MSE}}{\partial \theta_1} = \frac{2\sum\limits_{i} \left(y_i - \theta_0 - \theta_1 x_i\right) \left(-x_i\right)}{N} = \frac{2\sum\limits_{i} \epsilon_i \left(-x_i\right)}{N}$$

$$\theta_0 = \theta_0 - \alpha \frac{\partial MSE}{\partial \theta_0}$$

$$\theta_1 = \theta_1 - \alpha \frac{\partial MSE}{\partial \theta_1}$$

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$$\theta_{0} = 4 - 0.2 \frac{((1 - (4 + 0))(-1) + (2 - (4 + 0))(-1) + (3 - (4 + 0))(-1))}{3}$$

$$\theta_{0} = 3.6$$

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$$\theta_1 = 0 - 0.2 \frac{((1 - (4+0))(-1) + (2 - (4+0))(-2) + (3 - (4+0))(-3))}{3}$$

$$\theta_1 = -0.67$$

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$$\theta_0 = 3.6 - 0.2 \frac{((1 - (3.6 - 0.67))(-1) + (2 - (3.6 - 0.67 \times 2))(-1) + (3 - (3.6 - 0.67 \times 3))(-1))}{3}$$

$$\theta_0 = 3.54$$

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$$\theta_0 = 3.6 - 0.2 \frac{((1 - (3.6 - 0.67))(-1) + (2 - (3.6 - 0.67 \times 2))(-1) + (3 - (3.6 - 0.67 \times 3))(-1))}{3}$$

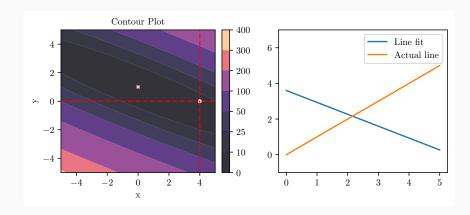
$$\theta_0 = 3.54$$

$$\theta_1 = \theta_1 - \alpha \frac{\partial MSE}{\partial \theta_1}$$

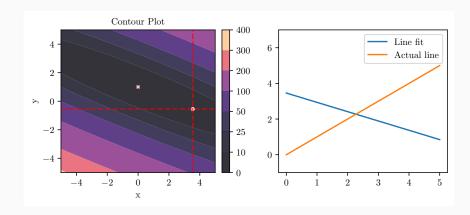
$$\theta_0 = 3.6 - 0.2 \frac{((1 - (3.6 - 0.67))(-1) + (2 - (3.6 - 0.67 \times 2))(-2) + (3 - (3.6 - 0.67 \times 3))(-3))}{3}$$

$$\theta_0 = -0.55$$

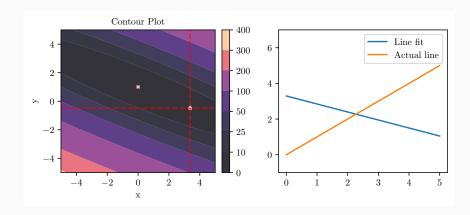
# **Gradient Descent : Example (Iteraion 0)**



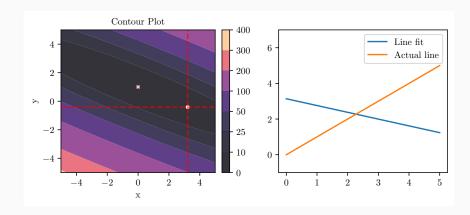
# **Gradient Descent : Example (Iteraion 2)**



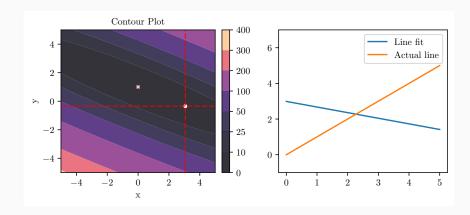
# **Gradient Descent : Example (Iteraion 4)**



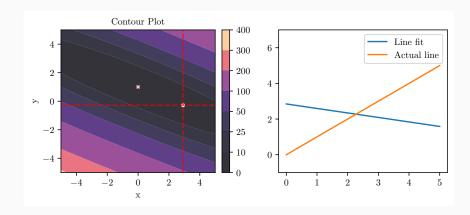
# Gradient Descent : Example (Iteraion 6)



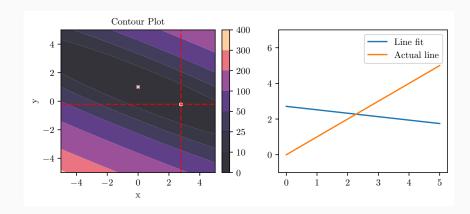
# Gradient Descent : Example (Iteraion 8)



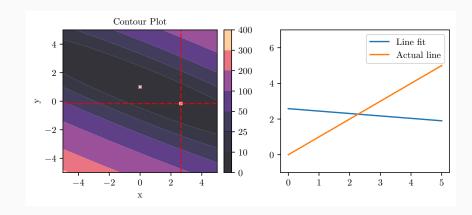
# Gradient Descent : Example (Iteraion 10)



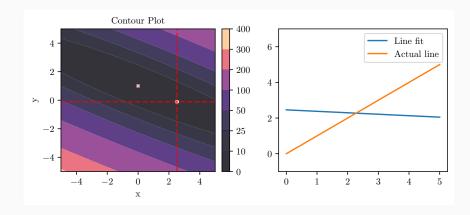
# Gradient Descent : Example (Iteraion 12)



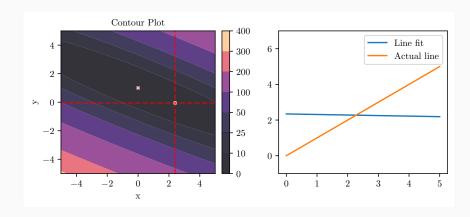
# **Gradient Descent: Example (Iteraion 14)**



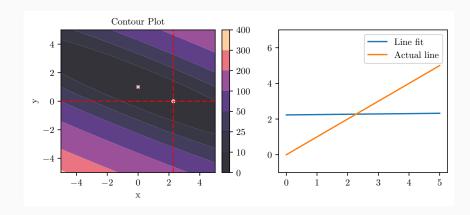
# Gradient Descent : Example (Iteraion 16)



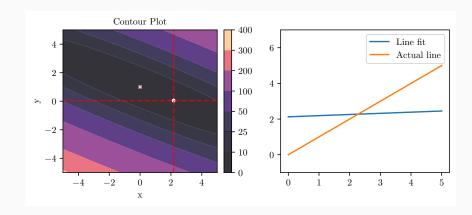
# Gradient Descent : Example (Iteraion 18)



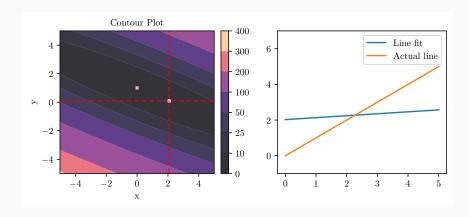
# Gradient Descent : Example (Iteraion 20)



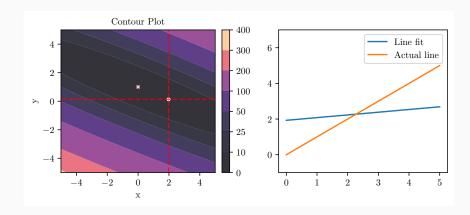
# Gradient Descent : Example (Iteraion 22)



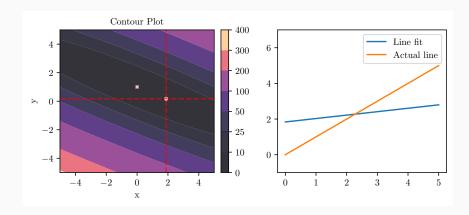
# Gradient Descent : Example (Iteraion 24)



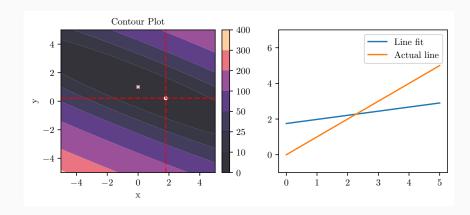
# Gradient Descent : Example (Iteraion 26)



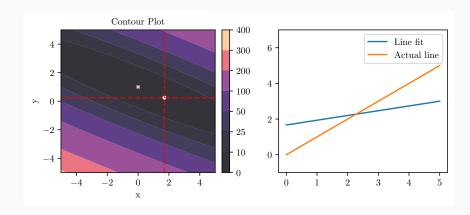
# Gradient Descent : Example (Iteraion 28)



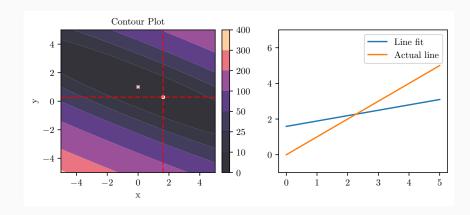
# Gradient Descent : Example (Iteraion 30)



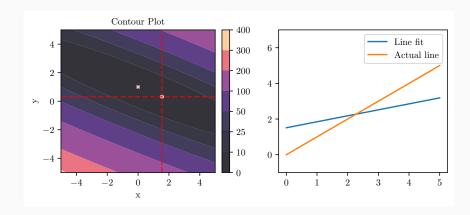
# **Gradient Descent : Example (Iteraion 32)**



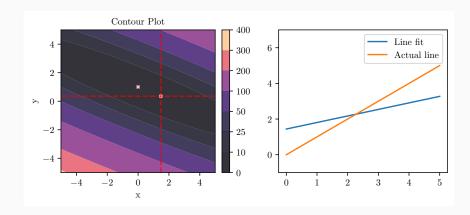
# **Gradient Descent : Example (Iteraion 34)**



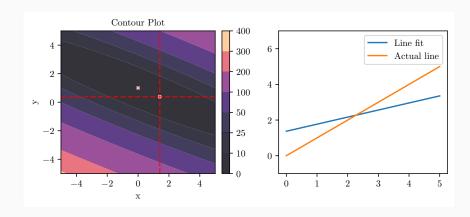
# **Gradient Descent : Example (Iteraion 36)**



# **Gradient Descent : Example (Iteraion 38)**



# Gradient Descent : Example (Iteraion 40)



# Iteration v/s Epcohs for gradient descent

• Iteration: Each time you update the parameters of the model

## Iteration v/s Epcohs for gradient descent

- Iteration: Each time you update the parameters of the model
- Epoch: Each time you have seen all the set of examples

## **Gradient Descent (GD)**

- Dataset:  $D = \{(X, y)\}$  of size N
- Initialize  $\theta$
- For epoch *e* in [1, *E*]
  - Predict  $\hat{y} = pred(X, \theta)$
  - Compute loss:  $J(\theta) = loss(y, \hat{y})$
  - Compute gradient:  $\nabla J(\theta) = grad(J)(\theta)$
  - Update:  $\theta = \theta \alpha \nabla J(\theta)$

## Stochastic Gradient Descent (SGD)

- Dataset:  $D = \{(X, y)\}$  of size N
- Initialize  $\theta$
- For epoch e in [1, E]
  - Shuffle D
  - For *i* in [1, *N*]
    - Predict  $\hat{y}_i = pred(X_i, \theta)$
    - Compute loss:  $J(\theta) = loss(y_i, \hat{y}_i)$
    - Compute gradient:  $\nabla J(\theta) = grad(J)(\theta)$
    - Update:  $\theta = \theta \alpha \nabla J(\theta)$

## Mini-Batch Gradient Descent (MBGD)

- Dataset:  $D = \{(X, y)\}$  of size N
- Initialize  $\theta$
- For epoch e in [1, E]
  - Shuffle D
  - Batches = make\_batches(D, B)
  - For b in Batches
    - $X_{-}b, y_{-}b = b$
    - Predict  $\hat{y_b} = pred(X_b, \theta)$
    - Compute loss:  $J(\theta) = loss(y_b, \hat{y_b})$
    - Compute gradient:  $\nabla J(\theta) = grad(J)(\theta)$
    - Update:  $\theta = \theta \alpha \nabla J(\theta)$

### Vanilla Gradient Descent

• in Vanilla (Batch) gradient descent: We update params after going through all the data

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#### Stochastic Gradient Descent

• In SGD, we update parameters after seeing each each point

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- in Vanilla (Batch) gradient descent: We update params after going through all the data
- Smooth curve for Iteration vs Cost
- For a single update, it needs to compute the gradient over all the samples. Hence takes more time

#### Stochastic Gradient Descent

- In SGD, we update parameters after seeing each each point
- Noisier curve for iteration vs cost
- For a single update, it computes the gradient over one example. Hence lesser time

Learn  $y = \theta_0 + \theta_1 x$  on following dataset, using SGD where initially  $(\theta_0, \theta_1) = (4, 0)$  and step-size,  $\alpha = 0.1$ , for 1 epoch (3 iterations).

X	у
2	2
3	3
1	1

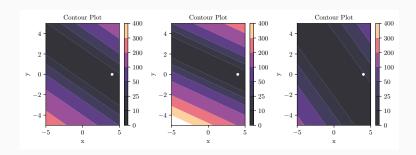
Our predictor, 
$$\hat{y} = \theta_0 + \theta_1 x$$

Error for 
$$i^{th}$$
 datapoint,  $e_i = y_i - \hat{y}_i$   
 $\epsilon_1 = 2 - \theta_0 - 2\theta_1$   
 $\epsilon_2 = 3 - \theta_0 - 3\theta_1$   
 $\epsilon_3 = 1 - \theta_0 - \theta_1$ 

While using SGD, we compute the MSE using only 1 datapoint per iteration.

So MSE is  $\epsilon_1^2$  for iteration 1 and  $\epsilon_2^2$  for iteration 2.

### Contour plot of the cost functions for the three datapoints



#### For Iteration i

$$\frac{\partial MSE}{\partial \theta_0} = 2(y_i - \theta_0 - \theta_1 x_i)(-1) = 2\epsilon_i(-1)$$

$$\frac{\partial MSE}{\partial \theta_1} = 2(y_i - \theta_0 - \theta_1 x_i)(-x_i) = 2\epsilon_i(-x_i)$$

$$\theta_0 = \theta_0 - \alpha \frac{\partial MSE}{\partial \theta_0}$$

$$\theta_1 = \theta_1 - \alpha \frac{\partial MSE}{\partial \theta_1}$$

$$\theta_0 = \theta_0 - \alpha \frac{\partial MSE}{\partial \theta_0}$$

$$\theta_0 = 4 - 0.1 \times 2 \times (2 - (4 + 0))(-1)$$

$$\theta_0 = 3.6$$

$$\theta_1 = \theta_1 - \alpha \frac{\partial MSE}{\partial \theta_1}$$

### Iteration 1

 $\theta_1 = -0.8$ 

$$\theta_0 = \theta_0 - \alpha \frac{\partial MSE}{\partial \theta_0}$$

$$\theta_0 = 4 - 0.1 \times 2 \times (2 - (4 + 0))(-1)$$

$$\theta_0 = 3.6$$

$$\theta_1 = \theta_1 - \alpha \frac{\partial MSE}{\partial \theta_1}$$

$$\theta_1 = 0 - 0.1 \times 2 \times (2 - (4 + 0))(-2)$$

$$\theta_0 = \theta_0 - \alpha \frac{\partial MSE}{\partial \theta_0}$$

$$\theta_1 = \theta_1 - \alpha \frac{\partial MSE}{\partial \theta_1}$$

$$\theta_0 = \theta_0 - \alpha \frac{\partial MSE}{\partial \theta_0}$$

$$\theta_0 = 3.6 - 0.1 \times 2 \times (3 - (3.6 - 0.8 \times 3))(-1)$$

$$\theta_0 = 3.96$$

$$\theta_1 = \theta_1 - \alpha \frac{\partial MSE}{\partial \theta_1}$$

$$\theta_0 = \theta_0 - \alpha \frac{\partial MSE}{\partial \theta_0}$$

$$\theta_0 = 3.6 - 0.1 \times 2 \times (3 - (3.6 - 0.8 \times 3))(-1)$$

$$\theta_0 = 3.96$$

$$\theta_1 = \theta_1 - \alpha \frac{\partial MSE}{\partial \theta_1}$$

$$\theta_0 = -0.8 - 0.1 \times 2 \times (3 - (3.6 - 0.8 \times 3))(-3)$$

$$\theta_1 = 0.28$$

$$\theta_0 = \theta_0 - \alpha \frac{\partial MSE}{\partial \theta_0}$$

$$\theta_1 = \theta_1 - \alpha \frac{\partial MSE}{\partial \theta_1}$$

$$\theta_0 = \theta_0 - \alpha \frac{\partial MSE}{\partial \theta_0}$$

$$\theta_0 = 3.96 - 0.1 \times 2 \times (1 - (3.96 + 0.28 \times 1))(-1)$$

$$\theta_0 = 3.312$$

$$\theta_1 = \theta_1 - \alpha \frac{\partial MSE}{\partial \theta_1}$$

$$\theta_{0} = \theta_{0} - \alpha \frac{\partial MSE}{\partial \theta_{0}}$$

$$\theta_{0} = 3.96 - 0.1 \times 2 \times (1 - (3.96 + 0.28 \times 1)) (-1)$$

$$\theta_{0} = 3.312$$

$$\theta_{1} = \theta_{1} - \alpha \frac{\partial MSE}{\partial \theta_{1}}$$

$$\theta_{0} = 0.28 - 0.1 \times 2 \times (1 - (3.96 + 0.28 \times 1)) (-1)$$

$$\theta_{1} = -0.368$$