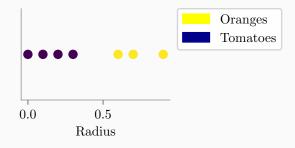
# **Logistic Regression**

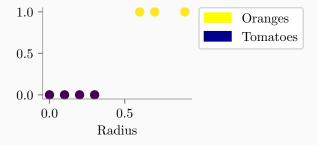
Nipun Batra

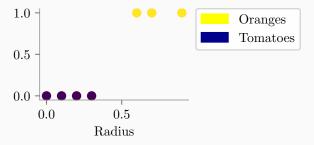
February 27, 2024

IIT Gandhinagar

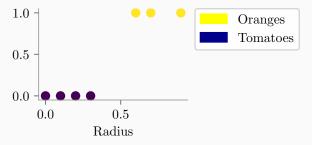
# **Problem Setup**



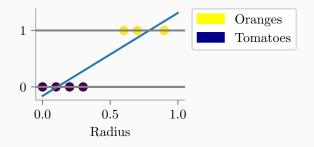




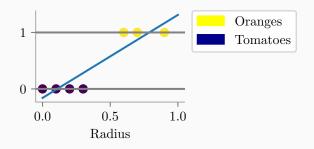
 $\label{eq:Aim: Probability (Tomatoes \mid Radius) ? or } Aim: Probability (Tomatoes \mid Radius) ? or \\$ 



Aim: Probability(Tomatoes | Radius) ? or More generally, P(y = 1|X = x)?



$$P(X = Orange|Radius) = \theta_0 + \theta_1 \times Radius$$



$$P(X = Orange|Radius) = \theta_0 + \theta_1 \times Radius$$

Generally,

$$P(y=1|x)=X\theta$$

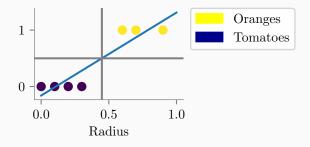
#### Prediction:

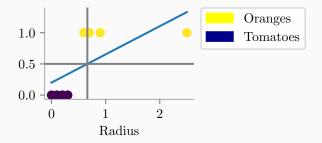
$$\begin{array}{c} \text{If } \theta_0 + \theta_1 \times \textit{Radius} > 0.5 \rightarrow \mathsf{Orange} \\ & \text{Else} \rightarrow \mathsf{Tomato} \end{array}$$

#### Problem:

Range of 
$$X\theta$$
 is  $(-\infty, \infty)$ 

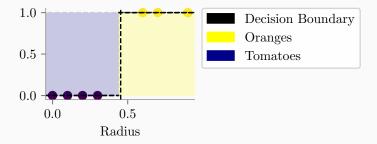
But 
$$P(y = 1 | ...) \in [0, 1]$$





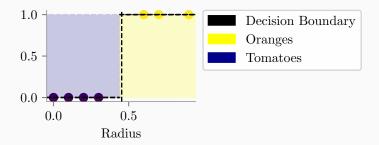
Linear regression for classification gives a poor prediction!

# **Ideal boundary**

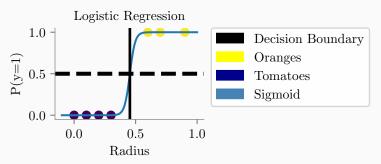


 Have a decision function similar to the above (but not so sharp and discontinuous)

# **Ideal boundary**



- Have a decision function similar to the above (but not so sharp and discontinuous)
- Aim: use linear regression still!



Question. Can we still use Linear Regression? Answer. Yes! Transform  $\hat{y} \rightarrow [0,1]$ 

$$\hat{y} \in (-\infty, \infty)$$

$$\phi = \text{Sigmoid / Logistic Function } (\sigma)$$

$$\phi(\hat{y}) \in [0, 1]$$

$$\sigma(z) = \frac{1}{1 + e^{-z}}$$

$$0.0$$



$$z \to \infty$$
  
 $\sigma(z) \to 1$ 

$$z \to \infty$$

$$\sigma(z) \to 1$$

$$z \to -\infty$$

$$z \to \infty$$
 $\sigma(z) \to 1$ 
 $z \to -\infty$ 
 $\sigma(z) \to 0$ 

$$z \to \infty$$

$$\sigma(z) \to 1$$

$$z \to -\infty$$

$$\sigma(z) \to 0$$

$$z = 0$$

$$z \to \infty$$
 $\sigma(z) \to 1$ 
 $z \to -\infty$ 
 $\sigma(z) \to 0$ 
 $z = 0$ 
 $\sigma(z) = 0.5$ 

Question. Could you use some other transformation  $(\phi)$  of  $\hat{y}$  s.t.

$$\phi(\hat{y}) \in [0,1]$$

Yes! But Logistic Regression works.

$$P(y = 1|X) = \sigma(X\theta) = \frac{1}{1 + e^{-X\theta}}$$

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$$P(y = 0|X) = 1 - P(y = 1|X) = 1 - \frac{1}{1 + e^{-X\theta}} = \frac{e^{-X\theta}}{1 + e^{-X\theta}}$$

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$$P(y = 0|X) = 1 - P(y = 1|X) = 1 - \frac{1}{1 + e^{-X\theta}} = \frac{e^{-X\theta}}{1 + e^{-X\theta}}$$

$$\therefore \frac{P(y=1|X)}{1-P(y=1|X)} = e^{X\theta} \implies X\theta = \log \frac{P(y=1|X)}{1-P(y=1|X)}$$

# Odds (Used in betting)

$$\frac{P(win)}{P(loss)}$$

Here,

$$Odds = \frac{P(y=1)}{P(y=0)}$$

$$log-odds = log \frac{P(y=1)}{P(y=0)} = X\theta$$

# **Logistic Regression**

 $\ensuremath{\mathsf{Q}}.$  What is decision boundary for Logistic Regression?

# **Logistic Regression**

Q. What is decision boundary for Logistic Regression? Decision Boundary: P(y=1|X)=P(y=0|X) or  $\frac{1}{1+e^{-X\theta}}=\frac{e^{-X\theta}}{1+e^{-X\theta}}$  or  $e^{X\theta}=1$  or  $X\theta=0$ 

## **Learning Parameters**

Could we use cost function as:

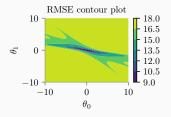
$$J(\theta) = \sum (y_i - \hat{y}_i)^2$$
$$\hat{y}_i = \sigma(X\theta)$$

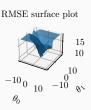
Answer: No (Non-Convex)
(See Jupyter Notebook)

**Maximum Likelihood Estimation** 

**Deriving Cost Function via** 

# **Cost function convexity**





# **Learning Parameters**

Likelihood = 
$$P(D|\theta)$$
  
 $P(y|X,\theta) = \prod_{i=1}^{n} P(y_i|x_i,\theta)$   
where y = 0 or 1

## **Learning Parameters**

 $\mathsf{Likelihood} = P(D|\theta)$ 

$$P(y|X,\theta) = \prod_{i=1}^{n} P(y_i|x_i,\theta)$$

$$= \prod_{i=1}^{n} \left\{ \frac{1}{1 + e^{-x_i^T \theta}} \right\}^{y_i} \left\{ 1 - \frac{1}{1 + e^{-x_i^T \theta}} \right\}^{1 - y_i}$$

[Above: Similar to  $P(D|\theta)$  for Linear Regression;

Difference Bernoulli instead of Gaussian]

$$-\log P(y|X,\theta) = \text{Negative Log Likelihood}$$
  
= Cost function will be minimising  
=  $J(\theta)$ 

#### Aside on Bernoulli Likelihood

 Assume you have a coin and flip it ten times and get (H, H, T, T, T, H, H, T, T, T).

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- We might think it to be: 4/10 = 0.4. But why?

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- Answer 2: What is likelihood of seeing the above sequence when the p(Head)=θ?

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- ullet Idea find MLE estimate for heta

• 
$$p(H) = \theta$$
 and  $p(T) = 1 - \theta$ 

- $p(H) = \theta$  and  $p(T) = 1 \theta$
- What is the PMF for first observation  $P(D_1 = x | \theta)$ , where x = 0 for Tails and x = 1 for Heads?

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- $P(D_1, D_2, ..., D_n | \theta) = \theta^{n_h} (1 \theta)^{n_t}$
- Log-likelihood =  $\mathcal{LL}(\theta) = n_h \log(\theta) + n_t \log(1 \theta)$
- $\frac{\partial \mathcal{LL}(\theta)}{\partial \theta} = 0 \implies \frac{n_h}{\theta} + \frac{n_t}{1-\theta} = 0 \implies \theta_{MLE} = \frac{n_h}{n_h + n_t}$

# **Cross Entropy Cost Function**

$$J(\theta) = -\log\left\{\prod_{i=1}^{n}\left\{\frac{1}{1 + e^{-x_i^T\theta}}\right\}^{y_i}\left\{1 - \frac{1}{1 + e^{-x_i^T\theta}}\right\}^{1 - y_i}\right\}$$

$$J(\theta) = -\left\{\sum_{i=1}^{n}y_i\log(\sigma_{\theta}(x_i)) + (1 - y_i)\log(1 - \sigma_{\theta}(x_i))\right\}$$

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This cost function is called cross-entropy.

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Why?

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Let us try to write the cost function for a single example:

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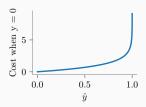
$$J(\theta) = -y_i \log \hat{y}_i - (1 - y_i) \log(1 - \hat{y}_i)$$

What is the interpretation of the cost function?

Let us try to write the cost function for a single example:

$$J(\theta) = -y_i \log \hat{y}_i - (1 - y_i) \log(1 - \hat{y}_i)$$

First, assume  $y_i$  is 0, then if  $\hat{y}_i$  is 0, the loss is 0; but, if  $\hat{y}_i$  is 1, the loss tends towards infinity!



Notebook: logits-usage

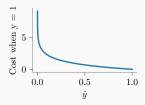
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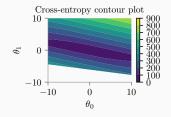
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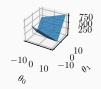
Now, assume  $y_i$  is 1, then if  $\hat{y}_i$  is 0, the loss is huge; but, if  $\hat{y}_i$  is 1, the loss is zero!



## **Cost function convexity**



#### Cross-entropy surface plot



$$\frac{\partial J(\theta)}{\partial \theta_j} = -\frac{\partial}{\partial \theta_j} \left\{ \sum_{i=1}^n y_i \log(\sigma_{\theta}(x_i)) + (1 - y_i) \log(1 - \sigma_{\theta}(x_i)) \right\} 
= -\sum_{i=1}^n \left[ y_i \frac{\partial}{\partial \theta_j} \log(\sigma_{\theta}(x_i)) + (1 - y_i) \frac{\partial}{\partial \theta_j} \log(1 - \sigma_{\theta}(x_i)) \right]$$

$$\frac{\partial J(\theta)}{\partial \theta_j} = -\sum_{i=1}^n \left[ y_i \frac{\partial}{\partial \theta_j} \log(\sigma_{\theta}(x_i)) + (1 - y_i) \frac{\partial}{\partial \theta_j} \log(1 - \sigma_{\theta}(x_i)) \right]$$

$$=-\sum_{i=1}^{n}\left[\frac{y_{i}}{\sigma_{\theta}(x_{i})}\frac{\partial}{\partial\theta_{j}}\sigma_{\theta}(x_{i})+\frac{1-y_{i}}{1-\sigma_{\theta}(x_{i})}\frac{\partial}{\partial\theta_{j}}(1-\sigma_{\theta}(x_{i}))\right] (1)$$

Aside:

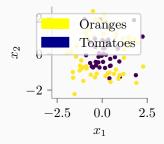
$$\begin{split} \frac{\partial}{\partial z} \sigma(z) &= \frac{\partial}{\partial z} \frac{1}{1 + e^{-z}} = -(1 + e^{-z})^{-2} \frac{\partial}{\partial z} (1 + e^{-z}) \\ &= \frac{e^{-z}}{(1 + e^{-z})^2} = \left(\frac{1}{1 + e^{-z}}\right) \left(\frac{e^{-z}}{1 + e^{-z}}\right) = \sigma(z) \left\{\frac{1 + e^{-z}}{1 + e^{-z}} - \frac{1}{1 + e^{-z}}\right\} \\ &= \sigma(z) (1 - \sigma(z)) \end{split}$$

Resuming from (1)

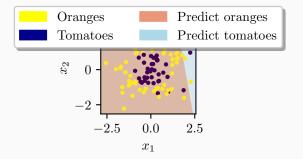
$$\frac{\partial J(\theta)}{\partial \theta_{j}} = -\sum_{i=1}^{n} \left[ \frac{y_{i}}{\sigma_{\theta}(x_{i})} \frac{\partial}{\partial \theta_{j}} \sigma_{\theta}(x_{i}) + \frac{1 - y_{i}}{1 - \sigma_{\theta}(x_{i})} \frac{\partial}{\partial \theta_{j}} (1 - \sigma_{\theta}(x_{i})) \right] 
= -\sum_{i=1}^{n} \left[ \frac{y_{i}\sigma_{\theta}(x_{i})}{\sigma_{\theta}(x_{i})} (1 - \sigma_{\theta}(x_{i})) \frac{\partial}{\partial \theta_{j}} (x_{i}\theta) + \frac{1 - y_{i}}{1 - \sigma_{\theta}(x_{i})} (1 - \sigma_{\theta}(x_{i})) \frac{\partial}{\partial \theta_{j}} (1 - \sigma_{\theta}(x_{i})) \right] 
= -\sum_{i=1}^{n} \left[ y_{i} (1 - \sigma_{\theta}(x_{i})) x_{i}^{j} - (1 - y_{i}) \sigma_{\theta}(x_{i}) x_{i}^{j} \right] 
= -\sum_{i=1}^{n} \left[ (y_{i} - y_{i}\sigma_{\theta}(x_{i}) - \sigma_{\theta}(x_{i}) + y_{i}\sigma_{\theta}(x_{i})) x_{i}^{j} \right] 
= \sum_{i=1}^{n} \left[ \sigma_{\theta}(x_{i}) - y_{i} \right] x_{i}^{j}$$

$$\frac{\partial J(\theta)}{\theta_j} = \sum_{i=1}^{N} \left[ \sigma_{\theta}(x_i) - y_i \right] x_i^j$$

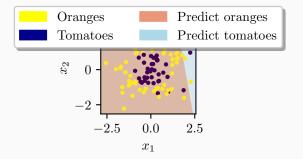
Now, just use Gradient Descent!



What happens if you apply logistic regression on the above data?



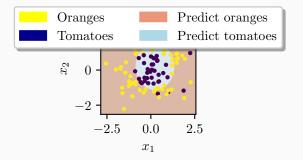
Linear boundary will not be accurate here. What is the technical name of the problem?



Linear boundary will not be accurate here. What is the technical name of the problem? Bias!

$$\phi(x) = \begin{bmatrix} \phi_0(x) \\ \phi_1(x) \\ \vdots \\ \phi_{K-1}(x) \end{bmatrix} = \begin{bmatrix} 1 \\ x \\ x^2 \\ x^3 \\ \vdots \\ x^{K-1} \end{bmatrix} \in \mathbb{R}^K$$

# Logistic Regression with feature transformation



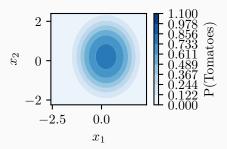
Using  $x_1^2, x_2^2$  as additional features, we are able to learn a more accurate classifier.

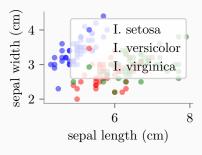
# Logistic Regression with feature transformation

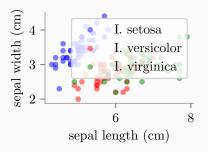
How would you expect the probability contours look like?

## Logistic Regression with feature transformation

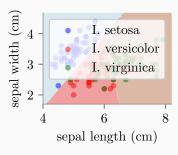
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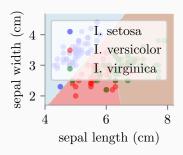




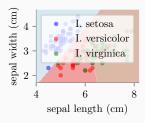


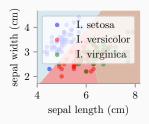
How would you learn a classifier? Or, how would you expect the classifier to learn decision boundaries?



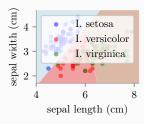


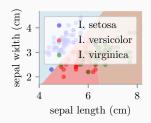
- 1. Use one-vs.-all on Binary Logistic Regression
- 2. Use one-vs.-one on Binary Logistic Regression
- 3. Extend <u>Binary</u> Logistic Regression to <u>Multi-Class</u> Logistic Regression





- 1. Learn P(setosa (class 1)) =  $\mathcal{F}(X\theta_1)$
- 2. P(versicolor (class 2)) =  $\mathcal{F}(X\theta_2)$
- 3.  $P(\text{virginica (class 3)}) = \mathcal{F}(X\theta_3)$
- 4. Goal: Learn  $\theta_i \forall i \in \{1, 2, 3\}$
- 5. Question: What could be an  $\mathcal{F}$ ?





- 1. Question: What could be an  $\mathcal{F}$ ?
- 2. Property:  $\sum_{i=1}^{3} \mathcal{F}(X\theta_i) = 1$
- 3. Also  $\mathcal{F}(z) \in [0,1]$
- 4. Also,  $\mathcal{F}(z)$  has squashing proprties:  $R\mapsto [0,1]$

## Softmax

$$Z \in \mathbb{R}^d$$
 $\mathcal{F}(z_i) = \frac{e^{z_i}}{\sum_{i=1}^d e^{z_i}}$ 
 $\therefore \sum \mathcal{F}(z_i) = 1$ 

 $\mathcal{F}(z_i)$  refers to probability of class <u>i</u>

# Softmax for Multi-Class Logistic Regression

$$k = \{1, \dots, k\} \text{classes}$$

$$\theta = \begin{bmatrix} \vdots & \vdots & \vdots & \vdots \\ \theta_1 & \theta_2 & \cdots & \theta_k \\ \vdots & \vdots & \vdots & \vdots \end{bmatrix}$$

$$P(y = k | X, \theta) = \frac{e^{X\theta_k}}{\sum_{k=1}^K e^{X\theta_k}}$$

## Softmax for Multi-Class Logistic Regression

For K = 2 classes,

$$P(y = k|X, \theta) = \frac{e^{X\theta_k}}{\sum_{k=1}^K e^{X\theta_k}}$$

$$P(y = 0|X, \theta) = \frac{e^{X\theta_0}}{e^{X\theta_0} + e^{X\theta_1}}$$

$$P(y = 1|X, \theta) = \frac{e^{X\theta_1}}{e^{X\theta_0} + e^{X\theta_1}} = \frac{e^{X\theta_1}}{e^{X\theta_1}\{1 + e^{X(\theta_0 - \theta_1)}\}}$$

$$= \frac{1}{1 + e^{-X\theta'}}$$

$$= \text{Sigmoid!}$$

Assume our prediction and ground truth for the three classes for  $i^{th}$  point is:

$$\hat{y}_i = \begin{bmatrix} 0.1\\0.8\\0.1 \end{bmatrix} = \begin{bmatrix} \hat{y}_i^1\\\hat{y}_i^2\\\hat{y}_i^3 \end{bmatrix}$$

$$y_i = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} y_i^1 \\ y_i^2 \\ y_i^3 \end{bmatrix}$$

meaning the true class is Class #2

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Let us calculate 
$$-\sum_{k=1}^{3} y_i^k \log \hat{y}_i^k$$

$$= -(0 \times \log(0.1) + 1 \times \log(0.8) + 0 \times \log(0.1))$$

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Let us calculate  $-\sum_{k=1}^{3} y_i^k \log \hat{y}_i^k$ 

$$= -(0\times\log(0.1)+1\times\log(0.8)+0\times\log(0.1))$$

Tends to zero

Assume our prediction and ground truth for the three classes for  $i^{th}$  point is:

$$\hat{y}_i = \begin{bmatrix} 0.3 \\ 0.4 \\ 0.3 \end{bmatrix} = \begin{bmatrix} \hat{y}_i^1 \\ \hat{y}_i^2 \\ \hat{y}_i^3 \end{bmatrix}$$

$$y_i = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} y_i^1 \\ y_i^2 \\ y_i^3 \end{bmatrix}$$

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meaning the true class is Class #2

Let us calculate  $-\sum_{k=1}^{3} y_i^k \log \hat{y}_i^k$ 

$$= -(0 \times \log(0.1) + 1 \times \log(0.4) + 0 \times \log(0.1))$$

High number! Huge penalty for misclassification!

For 2 class we had:

$$J(\theta) = -\left\{\sum_{i=1}^{n} y_i \log(\sigma_{\theta}(x_i)) + (1 - y_i) \log(1 - \sigma_{\theta}(x_i))\right\}$$

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More generally,

For 2 class we had:

$$J(\theta) = -\left\{\sum_{i=1}^{n} y_i \log(\sigma_{\theta}(x_i)) + (1 - y_i) \log(1 - \sigma_{\theta}(x_i))\right\}$$

More generally,

$$J(\theta) = -\left\{ \sum_{i=1}^{n} y_i \log(\hat{y}_i) + (1 - y_i) \log(1 - \hat{y}_i) \right\}$$

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Extend to K-class:

$$J(\theta) = -\left\{ \sum_{i=1}^{n} \sum_{k=1}^{K} y_{i}^{k} \log(\hat{y}_{i}^{k}) \right\}$$

#### Now:

$$\frac{\partial J(\theta)}{\partial \theta_k} = \sum_{i=1}^n \left[ x_i \left\{ I(y_i = k) - P(y_i = k | x_i, \theta) \right\} \right]$$

#### **Hessian Matrix**

The Hessian matrix of f(.) with respect to  $\theta$ , written  $\nabla_{\theta}^2 f(\theta)$  or simply as  $\mathbb{H}$ , is the  $d \times d$  matrix of partial derivatives,

$$\nabla_{\theta}^{2} f(\theta) = \begin{bmatrix} \frac{\partial^{2} f(\theta)}{\partial \theta_{1}^{2}} & \frac{\partial^{2} f(\theta)}{\partial \theta_{1} \partial \theta_{2}} & \cdots & \frac{\partial^{2} f(\theta)}{\partial \theta_{1} \partial \theta_{n}} \\ \frac{\partial^{2} f(\theta)}{\partial \theta_{2} \partial \theta_{1}} & \frac{\partial^{2} f(\theta)}{\partial \theta_{2}^{2}} & \cdots & \frac{\partial^{2} f(\theta)}{\partial \theta_{2} \partial \theta_{n}} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial^{2} f(\theta)}{\partial \theta_{n} \partial \theta_{1}} & \frac{\partial^{2} f(\theta)}{\partial \theta_{n} \partial \theta_{2}} & \cdots & \frac{\partial^{2} f(\theta)}{\partial \theta_{n}^{2}} \end{bmatrix}$$

## **Newton's Algorithm**

The most basic second-order optimization algorithm is Newton's algorithm, which consists of updates of the form,

$$\theta_{k+1} = \theta_k - \mathbb{H}^1_k g_k$$

where  $g_k$  is the gradient at step k. This algorithm is derived by making a second-order Taylor series approximation of  $f(\theta)$  around  $\theta_k$ :

$$f_{quad}(\theta) = f(\theta_k) + g_k^T(\theta - \theta_k) + \frac{1}{2}(\theta - \theta_k)^T \mathbb{H}_k(\theta - \theta_k)$$

differentiating and equating to zero to solve for  $\theta_{k+1}$ .

# **Learning Parameters**

Now assume:

$$g(\theta) = \sum_{i=1}^{n} \left[ \sigma_{\theta}(x_i) - y_i \right] x_i^j = \mathbf{X}^{\mathsf{T}} (\sigma_{\theta}(\mathbf{X}) - \mathbf{y})$$
$$\pi_i = \sigma_{\theta}(x_i)$$

Let  $\mathbb{H}$  represent the Hessian of  $J(\theta)$ 

$$\mathbb{H} = \frac{\partial}{\partial \theta} g(\theta) = \frac{\partial}{\partial \theta} \sum_{i=1}^{n} \left[ \sigma_{\theta}(x_{i}) - y_{i} \right] x_{i}^{j}$$

$$= \sum_{i=1}^{n} \left[ \frac{\partial}{\partial \theta} \sigma_{\theta}(x_{i}) x_{i}^{j} - \frac{\partial}{\partial \theta} y_{i} x_{i}^{j} \right]$$

$$= \sum_{i=1}^{n} \sigma_{\theta}(x_{i}) (1 - \sigma_{\theta}(x_{i})) x_{i} x_{i}^{T}$$

$$= \mathbf{X}^{\mathsf{T}} \operatorname{diag}(\sigma_{\theta}(x_{i}) (1 - \sigma_{\theta}(x_{i}))) \mathbf{X}$$

# Iteratively reweighted least squares (IRLS)

For binary logistic regression, recall that the gradient and Hessian of the negative log-likelihood are given by:

$$g(\theta)_k = \mathbf{X}^{\mathsf{T}}(\pi_{\mathbf{k}} - \mathbf{y})$$

$$\mathbf{H}_k = \mathbf{X}^{\mathsf{T}} S_k \mathbf{X}$$

$$\mathbf{S}_k = diag(\pi_{1k}(1 - \pi_{1k}), \dots, \pi_{nk}(1 - \pi_{nk}))$$

$$\pi_{ik} = sigm(\mathbf{x}_i \theta_{\mathbf{k}})$$

The Newton update at iteraion k + 1 for this model is as follows:

$$\theta_{k+1} = \theta_k - \mathbb{H}^{-1} g_k$$

$$= \theta_k + (X^T S_k X)^{-1} X^T (y - \pi_k)$$

$$= (X^T S_k X)^{-1} [(X^T S_k X) \theta_k + X^T (y - \pi_k)]$$

$$= (X^T S_k X)^{-1} X^T [S_k X \theta_k + y - \pi_k]$$

# Regularized Logistic Regression

Unregularised:

$$J_1(\theta) = -\left\{\sum_{i=1}^n y_i \log(\sigma_{\theta}(x_i)) + (1 - y_i) \log(1 - \sigma_{\theta}(x_i))\right\}$$

L2 Regularization:

$$J(\theta) = J_1(\theta) + \lambda \theta^T \theta$$

L1 Regularization:

$$J(\theta) = J_1(\theta) + \lambda |\theta|$$