

TM

# Turing Machine

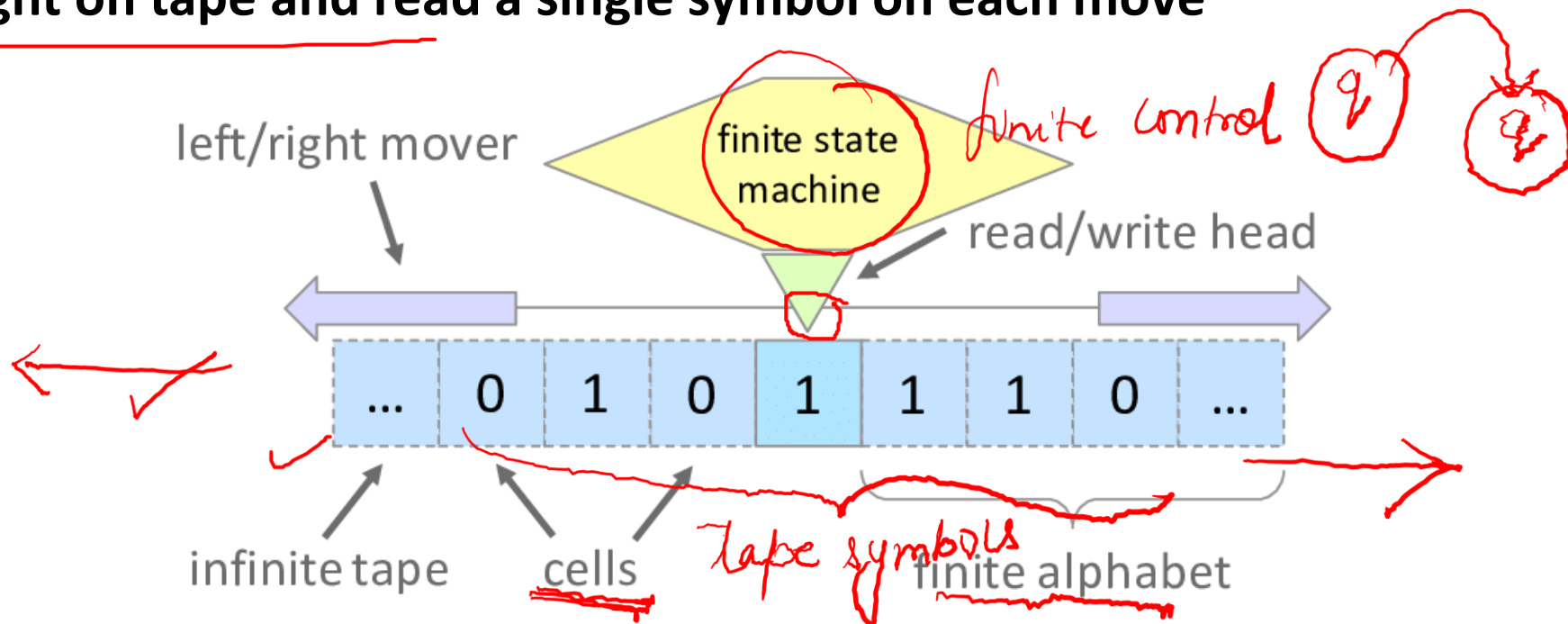
Consists of:-

- A Tape

Tape is infinite extending on either sides, divided into cells, each cell capable of holding one symbol

- ~~Head-~~

✓ Associated with tape is read-write head that can travel left or right on tape and read a single symbol on each move



# Turing Machine

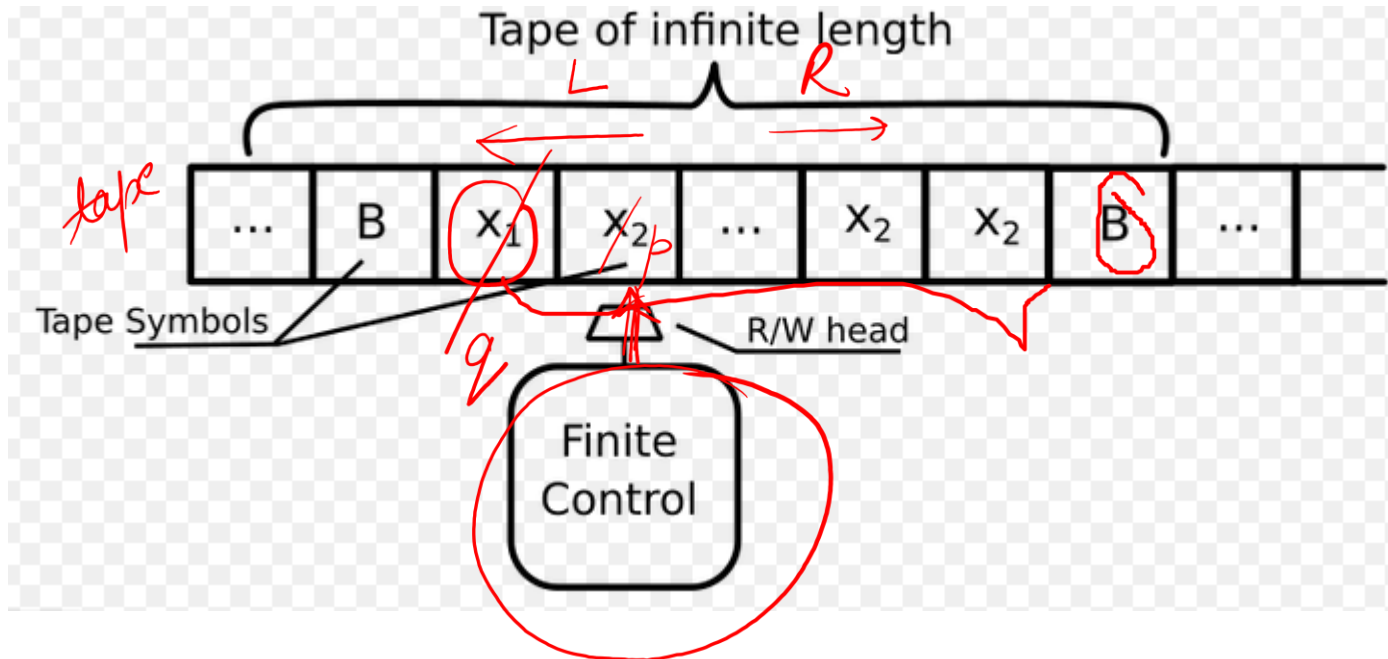
## Consists of:-

## Tape Symbols-

**Finite set of symbols, consists of lowercase letters, digits, usual punctuation marks and the Blank B**

- **States-**

## Set of states in which the machine can reside



# Turing Machine

**A Turing machine is a mathematical model of computation that defines an abstract machine[1] that manipulates symbols on a strip of tape according to a table of rules**

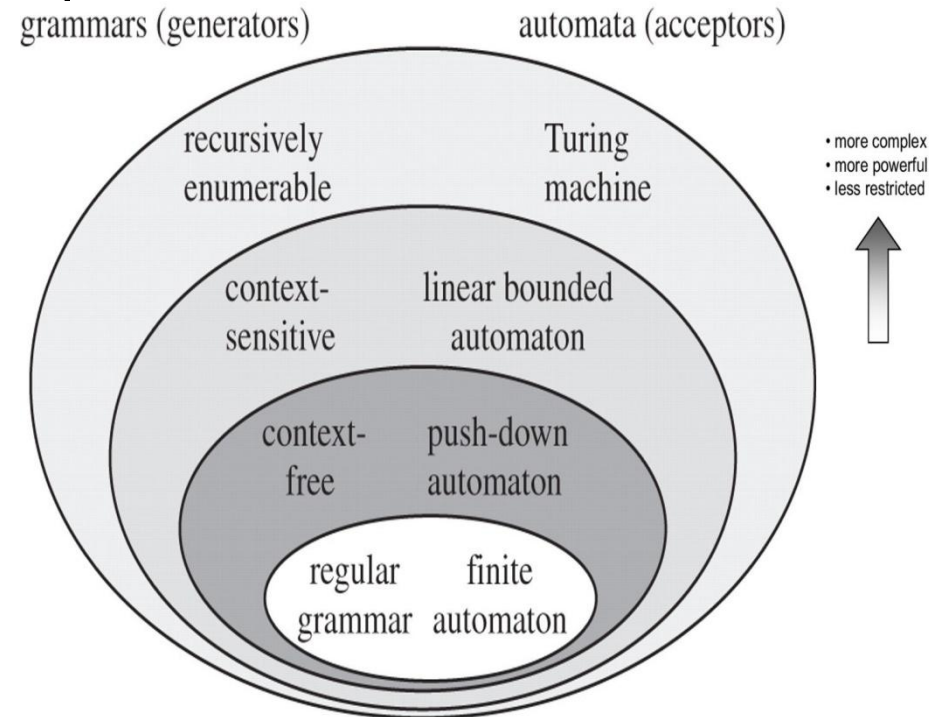
**-Wikipedia**

# Turing Machine

- Turing Machine was invented by Alan Turing in 1936
- Accepts Recursive Enumerable Languages (generated by Type-0 Grammar).

## The Hierarchy

Class	Grammars	Languages	Automaton
Type-0	Unrestricted	Recursive Enumerable	Turing Machine
Type-1	Context Sensitive	Context Sensitive	Linear-Bound
Type-2	Context Free	Context Free	Pushdown
Type-3	Regular	Regular	Finite



# TM: Formal Definition

PDA is denoted by 7 Tuple:  $M = (Q, \Sigma, \Gamma, \delta, q_0, B, F)$  where

•  $Q$ : Finite set of Internal states of the Control Unit

•  $\Sigma$ : Finite input alphabet

•  $\Gamma$ : Finite Set of Tape Symbols

•  $\delta: Q \times \Gamma \rightarrow Q \times \Gamma \times \{L, R, N\}$ : Transition function(TF)

•  $q_0$ : Start state of Control Unit,  $q_0 \in Q$

•  $B$ : Blank Symbol

•  $F$ : Set of Final States/ Accept State,  $F \subseteq Q$

•  $\Sigma \subseteq \Gamma - \{B\}$

PDA  $(Q, \Sigma, \Gamma, \delta, q_0, z_0, F)$

PDA / Pushdown Stack Symbols

# $\delta$ Function

$\delta$  Function:-

- $\delta: Q \times \Gamma \rightarrow Q \times \Gamma \times \{L, R, N\}$ : Transition function(TF)

If  $\delta(q, X) = (p, Y, L)$

- If present state is  $q$  and the next symbol on the tape is  $X$  then the Turing Machine changes the state to  $p$ , replaces the symbol  $X$  by symbol  $Y$  and moves the tape head one position left.

$$\delta(q, X) = (p, Y, \textcircled{N})$$

If  $\delta(q, X) = (p, Y, R)$

- If present state is  $q$  and the next symbol on the tape is  $X$  then the Turing Machine changes the state to  $p$ , replaces the symbol  $X$  by symbol  $Y$  and moves the tape head one position right.

# TM Example 1

Transition Rules

Construct a TM to replace each occurrence of 'a' by 'b' for the strings over  $\Sigma=\{a,b\}$

$$M = (Q, \Sigma, \Gamma, \delta, q_0, B, F)$$

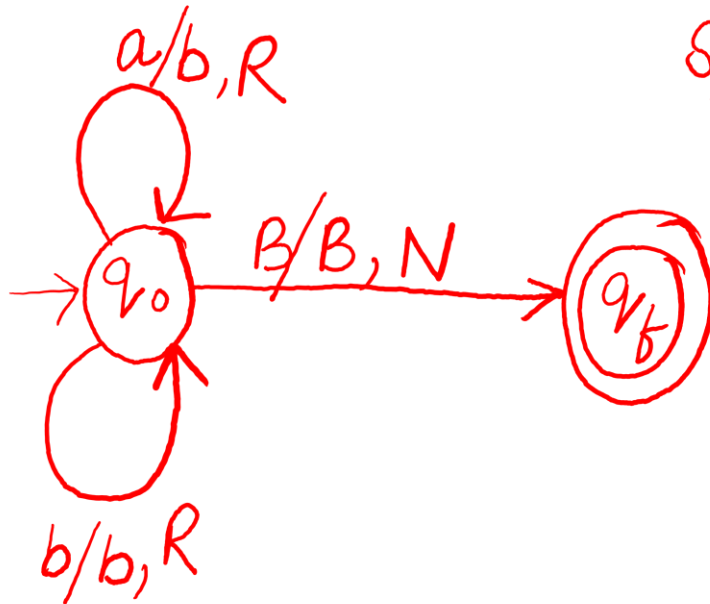
$\delta$  Rules

$$\delta(q_0, a) = (q_0, b, R) \quad \text{Move Right}$$

$$\delta(q_0, b) = (q_0, b, R) \quad \text{Move Right}$$

$$\delta(q_0, B) = (q_f, B, N) \quad \text{No Movement}$$

$\delta$  diag



Stable

States	Tape Symbols		
	a	b	B
$q_0$	$(q_0, b, R)$	$(q_0, b, R)$	$(q_f, B, N)$
$q_f$	—	—	—

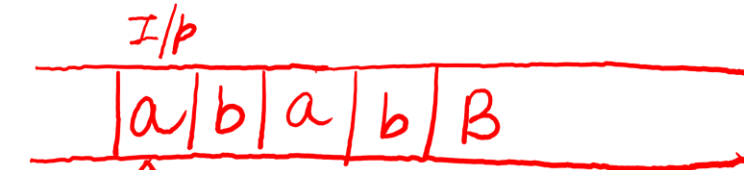


# TM Example 1

Simulation

Construct a TM to replace each occurrence of 'a' by 'b' for the strings over  $\Sigma=\{a,b\}$

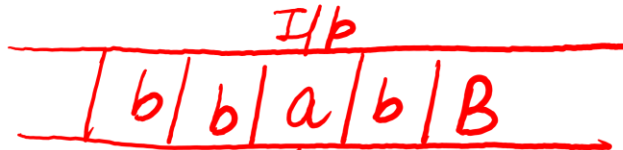
String = "abab"



$q_0 \rightarrow$   
I/p



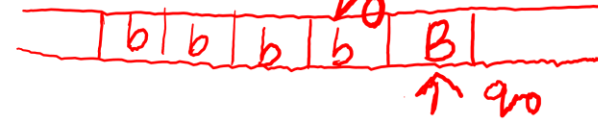
$q_0 \rightarrow$



$q_0 \rightarrow$

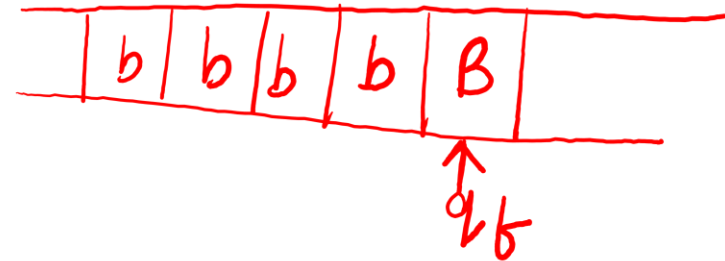


$q_0 \rightarrow$



$$\delta(q_0, a) = (q_0, b, R)$$

$$\delta(q_0, b) = (q_0, b, R)$$



$$\delta(q_0, a) = (q_0, b, R)$$

$$\delta(q_0, b) = (q_0, b, R)$$

$$\delta(q_0, B) = (q_f, \underline{B}, N)$$

✓ 0111

# TM Example 2

Transition Rules and Simulation

Design a TM to replace all occurrences of '111' by '101' over  $\Sigma=\{0,1\}$

$$\checkmark \delta(q_0, 0) = (q_0, 0, R)$$

$$\checkmark \delta(q_0, 1) = (q_1, 1, R)$$

$$\checkmark \delta(q_0, \underline{B}) = (q_f, \underline{B}, N)$$

$$\checkmark \delta(q_1, 0) = (q_0, 0, R)$$

$$\checkmark \delta(q_1, 1) = (q_2, 1, R)$$

$$\checkmark \delta(q_1, \underline{B}) = (q_f, \underline{B}, N)$$

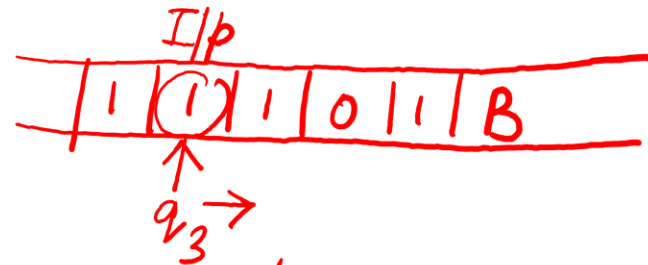
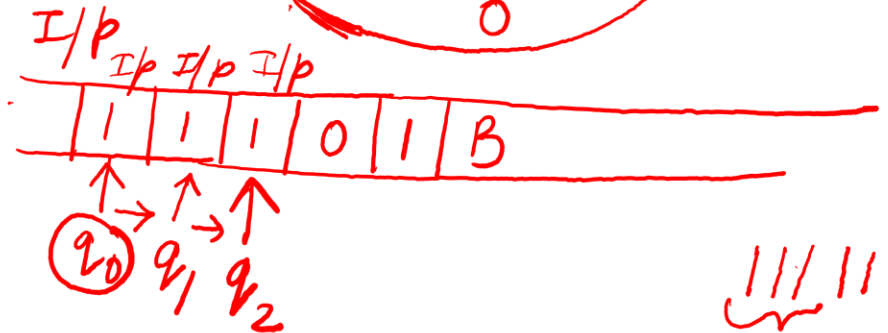
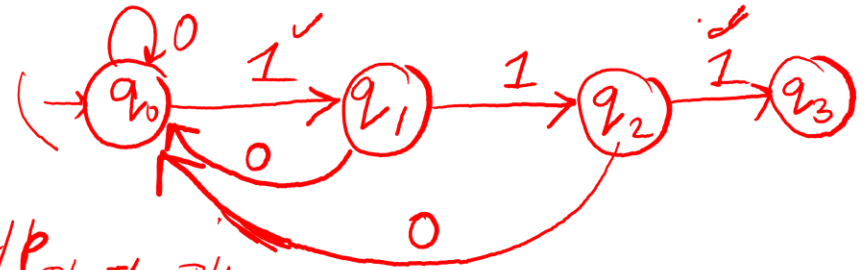
$$\checkmark \delta(q_2, \underline{0}) = (q_0, 0, R)$$

$$\checkmark \delta(q_2, 1) = (q_3, 1, L) \checkmark$$

$$\delta(q_2, \underline{B}) = (q_f, \underline{B}, N)$$

$$\delta(q_3, 1) = (q_4, 0, R) \checkmark$$

$$\delta(q_4, 1) = (q_0, 1, R)$$



111 111  
101 111

# TM Example 2

Transition Diagram ,Table

Design a TM to replace all occurrences of '111' by '101' over  $\Sigma=\{0,1\}$

# TM Example 3

Design a TM accept the language containing substring “aba” over  $\Sigma=\{a,b\}$

Logic-

During the process if TM discovers “aba” on the tape, it halts and thereby accepts entire input string

$M=(Q, \Sigma, \Gamma, \delta, q_0, B, F)$

# TM Example 3

Design a TM accept the language containing substring “aba”  
over  $\Sigma=\{a,b\}$

$\delta(q_0,a)=(q_1,a,R)$

$\delta(q_0,b)=(q_0,b,R)$  self loop

$\delta(q_1,a)=(q_1,a,R)$  self loop

$\delta(q_1,b)=(q_2,b,R)$

$\delta(q_2,b)=(q_0,b,R)$  go back

$\delta(q_2,a)=(q_f,a,N)$

# TM Example 4

## Transition Rules

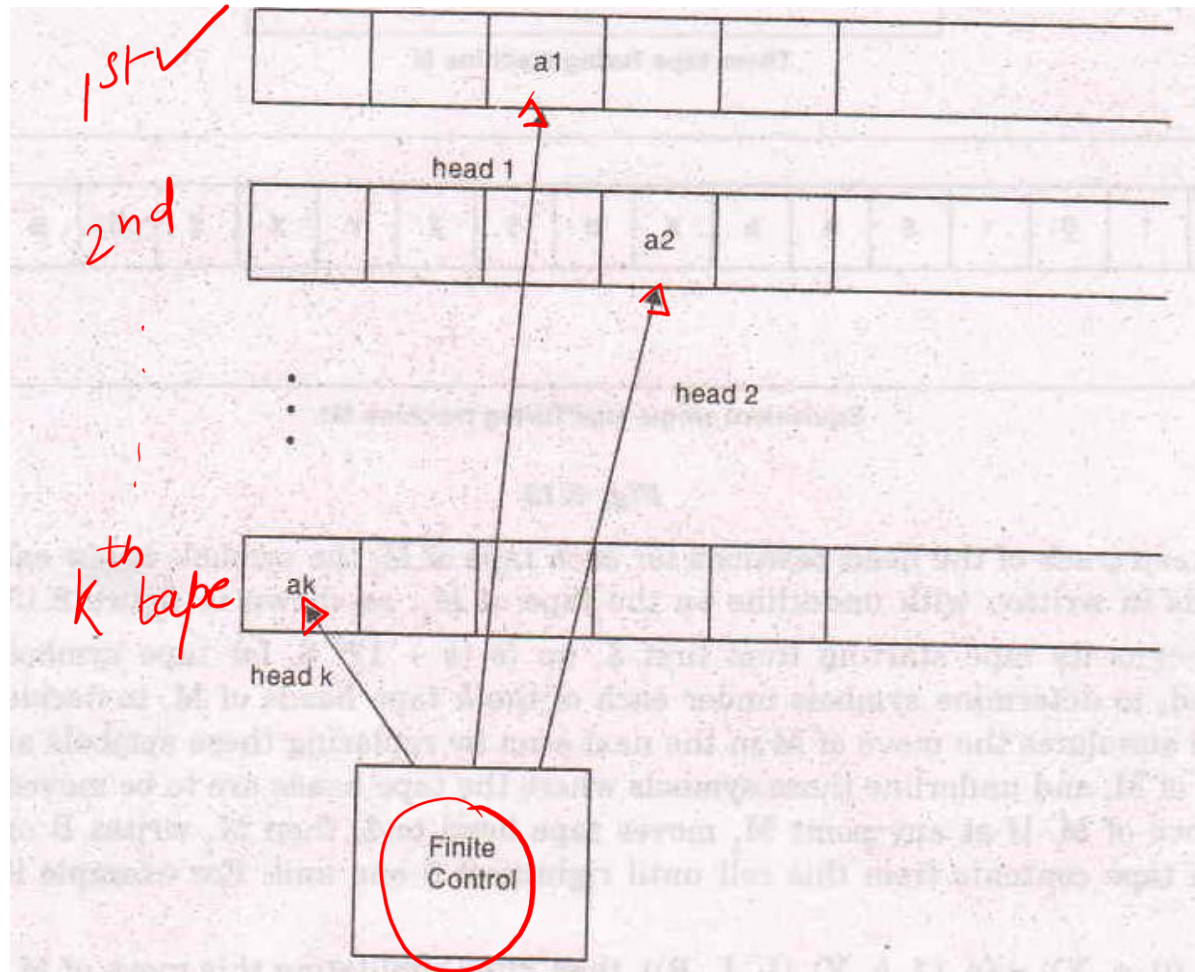
Design a TM to replace all occurrences of '101' by '011' over  $\Sigma=\{0,1\}$

# **Modifications of Turing Machines or Variants of Turing Machines**

- **Multi Tape Turing Machine**
- **Non-Deterministic Turing Machine**

# Multi Tape Turing Machine

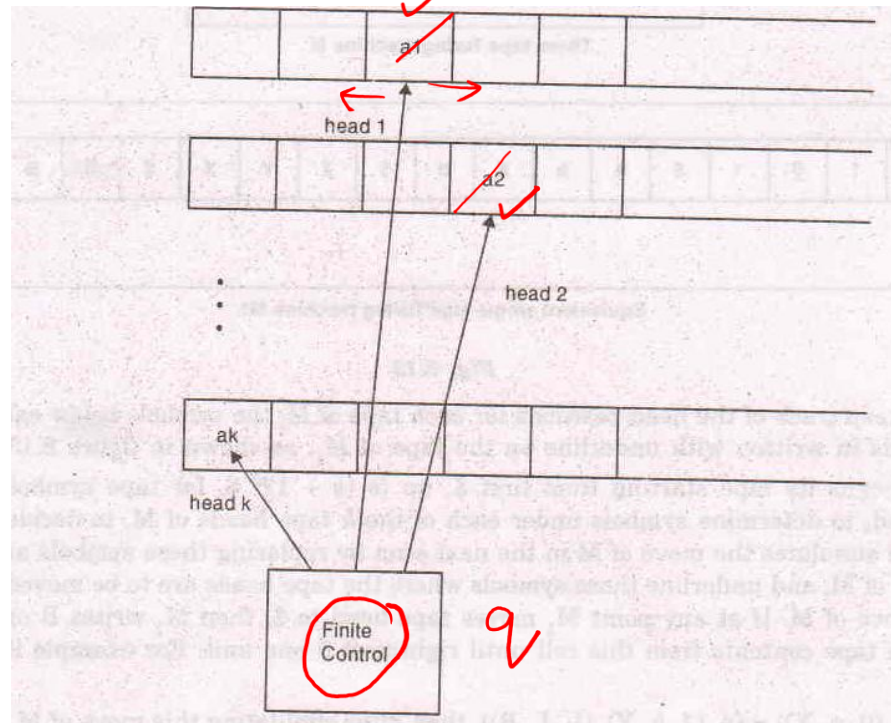
- A Multitape Turing Machine-





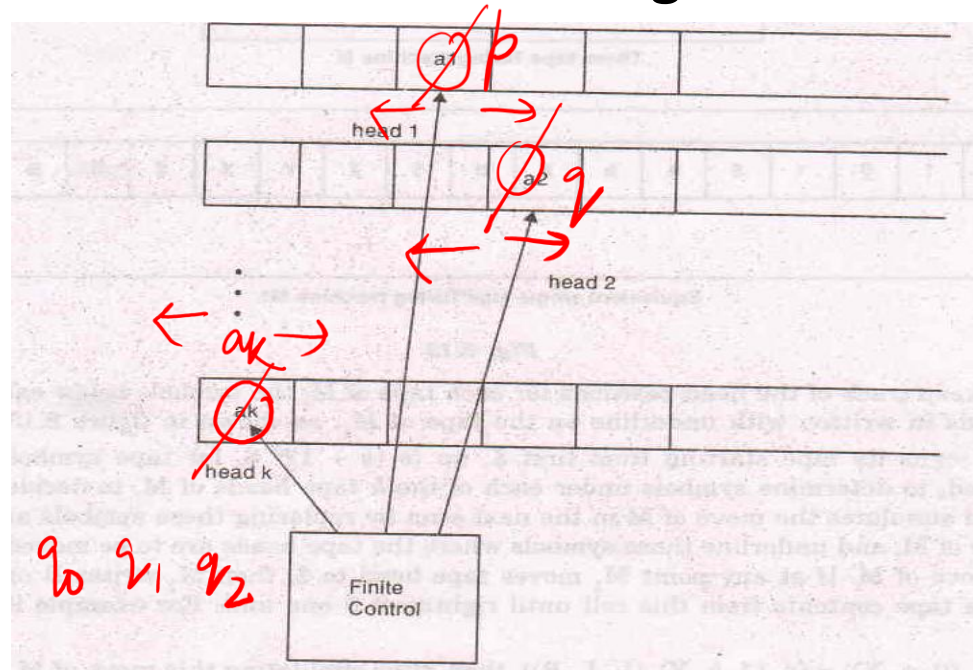
# Multi Tape Turing Machine

- It is a Turing Machine with several tapes , each has its own tape heads
- It consists of a finite control with k tape heads and k tapes ( $k > 1$ )
- The move of this Turing machine depends on the present state of the finite control and the symbol scanned by each of the tape heads.



## Multi Tape Turing Machine

- In each move, depending on the present state and the symbols scanned by each of the tape heads , the machine can
  - ~~change~~ state of the finite control
  - print a new symbol on each of cells scanned by each of the tape heads
  - move each tape one cell left or one cell right independently



$$\delta: Q \times \Gamma \rightarrow Q \times \Gamma \times \{L, R, N\}$$

i/p from tapes

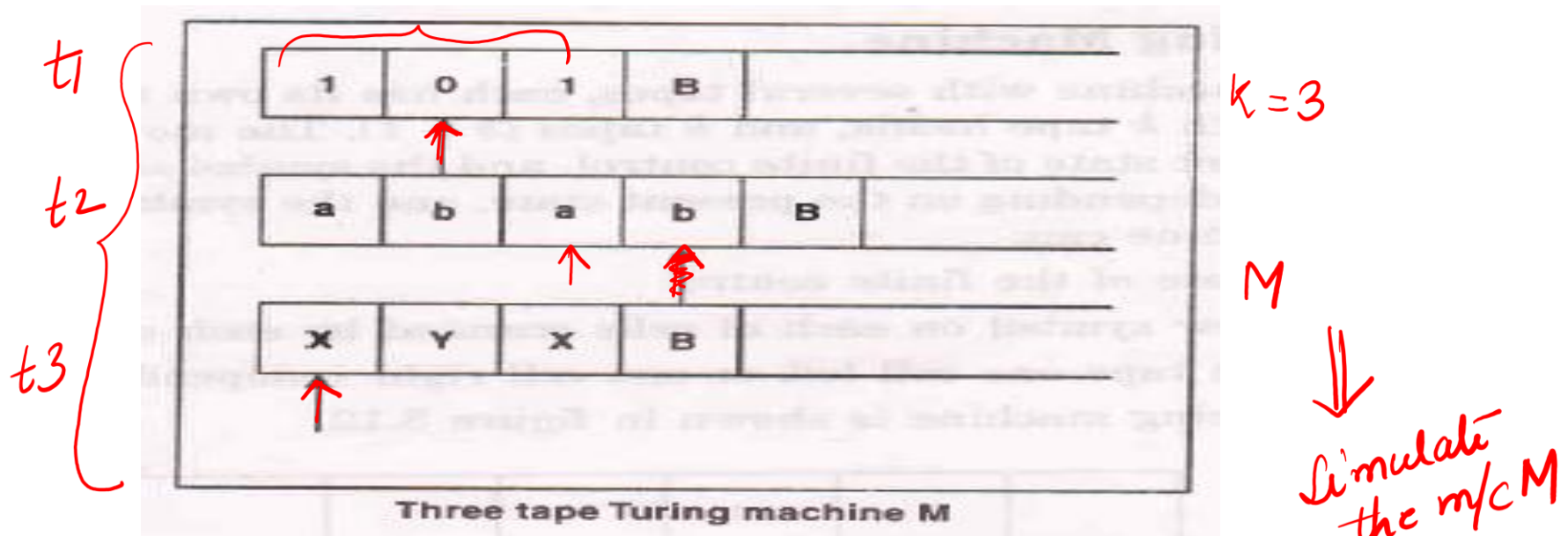
- 
- Diagram illustrating the construction of a sequence of partitions for a proof. It shows three horizontal lines representing a space. The first line has a point  $a_1$  marked with a vertical line and a double arrow above it pointing left, labeled  $L$ . The second line has a point  $a_2$  marked with a vertical line and a double arrow above it pointing right, labeled  $R$ . The third line has a point  $a_3$  marked with a vertical line and a double arrow above it pointing left, labeled  $L$ . Below the third line, there is a box containing  $a_k$  with an arrow pointing to  $b_k$ . The bottom of the diagram shows the general case  $a_k | b_k$ .

# Multi Tape Turing Machine

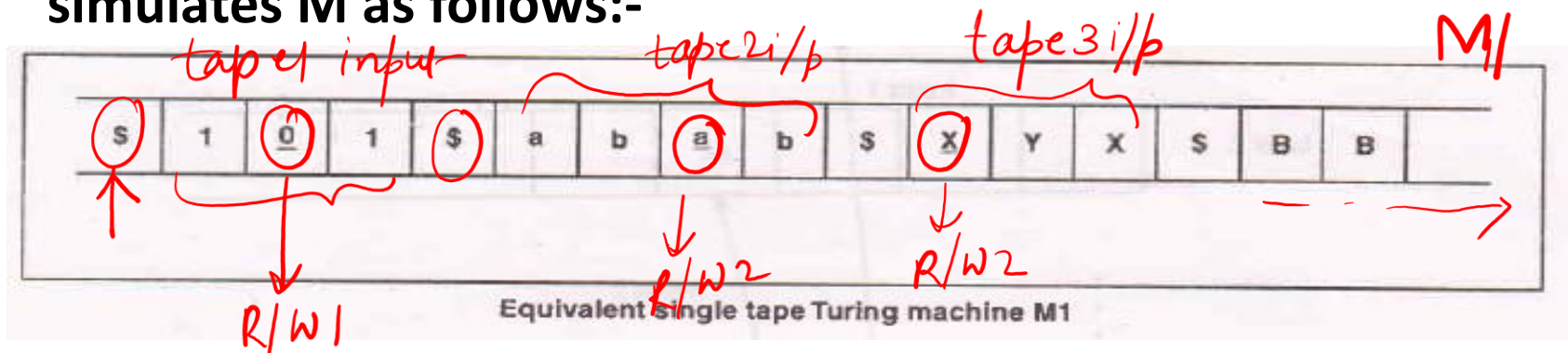
- ✓ • All Variants have same power, every multitape turing machine has an equivalent single tape Turing machine

# Multi Tape Turing Machine

- Let  $M$  be a  $k$  tape Turing Machine ( $k > 1$ )



- Let us construct a single tape turing machine  $M_1$ , which simulates  $M$  as follows:-

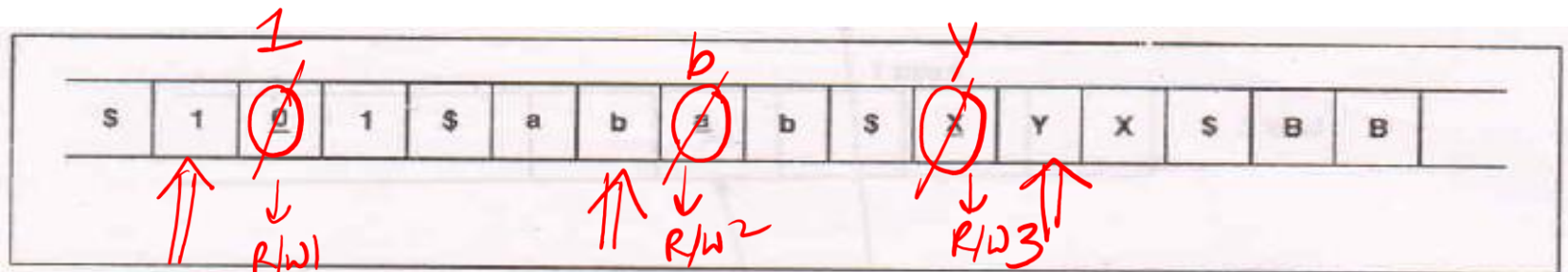


# Multi Tape Turing Machine

$$\delta(q(0, a, x)) = (p, (1, b, y), (L, L, R))$$

$\uparrow \quad \uparrow$

- M1 stores the information available on the k tapes of M on its tape, using a symbol \$ as delimiter
- To keep a track of the head positions for each tape of M, the symbols below each of these tape heads are written with underline on the tape of M1



Equivalent single tape Turing machine M1

# Multi Tape Turing Machine

- M1 scans its tape starting from first \$ up to (k+1)st \$ for tape symbols that are underlined to simulate the move by replacing these symbols according to the move of M
- $\delta(q, (0, a, X)) = (p, (\underline{1}, b, Y), (\underline{L}, L, R))$
- After this move the contents of the tape are-

\$	1	1	1	\$	a	<u>b</u>	b	b	\$	Y	<u>Y</u>	X	\$	B	B
----	---	---	---	----	---	----------	---	---	----	---	----------	---	----	---	---

Contents of tape of M1 after simulating the move of M





# Non-Deterministic Turing Machine

- Turing Machine which at any point while carrying out computation, may proceed according to several possibilities
- For a tape symbol scanned, The machine has a finite number of choices of next move
- The transition function defines mapping from

- $Q \times \Gamma$  to a finite subset of  $Q \times \Gamma \times \{L, R, N\}$

- It accepts input, if some sequence of choices of moves lead to an accepting state

$$\delta(q_0, a) = (q_1, a, N)$$

$$\delta(q_0, a) = (q_1, b, R)$$

$$\delta(q_0, a) = (q_2, a, L)$$

$$(q, \Gamma) \rightarrow (q, \Gamma, \{L, R, N\})$$

3 choices  $\Rightarrow$  out of these 3 choices, for 1 choice  
multiple moves  
non-determinism

we reach final state  
acceptance by final



# Non-Deterministic Turing Machine

- All variants have the same power, thus Every Non-Deterministic Turing Machine has an equivalent deterministic Turing machine

$$P(DTM) = P(NDTM)$$

# Non-Deterministic Turing Machine

- For a Non-Deterministic Turing machine M,
- It is always possible to construct a turing machine M1, which tries all possible sequences of computations or branches of computations of M
- If M enters into an accept state on any of these branches, M1 accepts otherwise continues to simulate M without termination
- Thus, M1 is accepting the same language as M

$\Rightarrow$  NDTM = M  
DTM = M<sub>1</sub>

either it enters into  $q_f \Rightarrow$  string is accepted

else, goes on simulating without termination

# TM Example 5

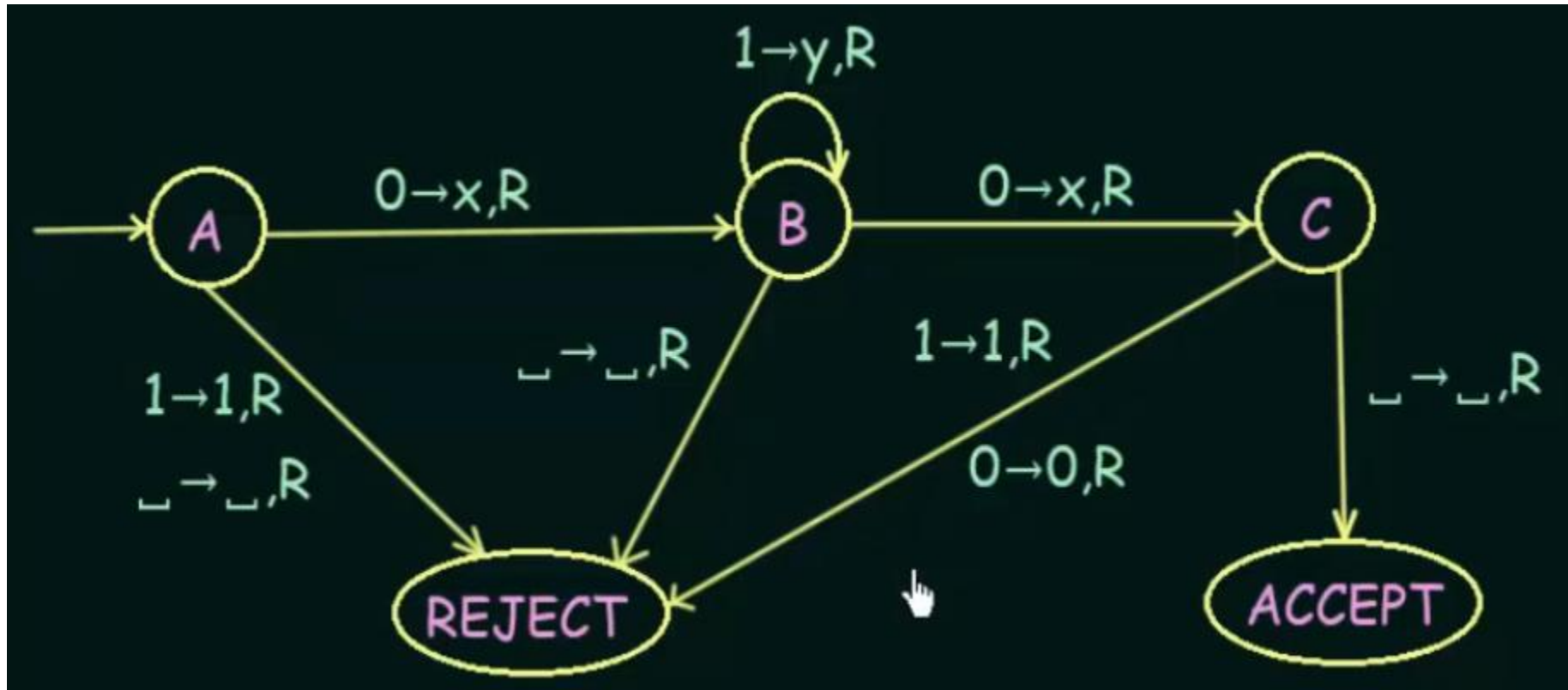
## Transition Rules

Design a TM which recognizes the language  $L=01^*0$  for  $\Sigma=\{0,1\}$

Lets take string 0110

# TM Example 5

Design a TM which recognizes the language  $L=01^*0$  for  $\Sigma=\{0,1\}$



0	1	1	0	B
X	Y	Y	X	B

# TM Example 5

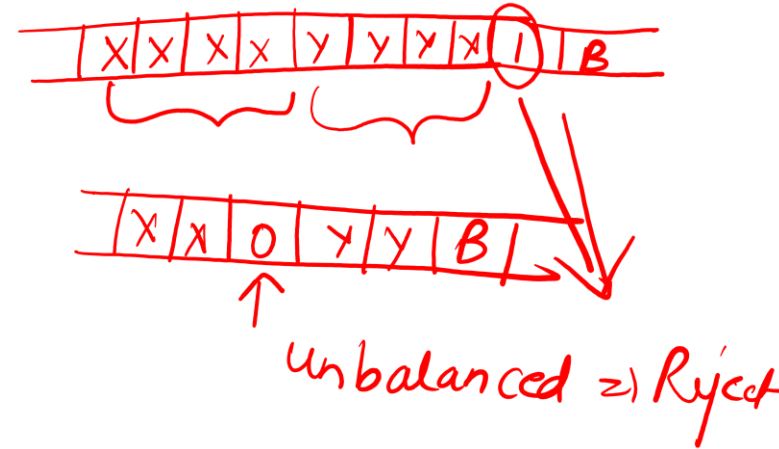
Design a TM which recognizes the language  $L=0^N1^N$  for  $\Sigma=\{0,1\}$

# TM Example 5

Design a TM which recognizes the language  $L=0^N1^N$  for  $\Sigma=\{0,1\}$

Algorithm-

- Change 0 to X
- Move Right to first "1"
- If None:Reject
- Change "1" to "y"
- Move LEFT to Leftmost "0"
- Repeat the above steps until no more "0"s
- Make sure no more "1"s remain



# TM Example 5

Simulation for  $L=0^N1^N$ , String 00001111

0	0	0	0	1	1	1	1	B
---	---	---	---	---	---	---	---	---

X	0	0	0	1	1	1	1	B
---	---	---	---	---	---	---	---	---

X	0	0	0	Y	1	1	1	1	B
---	---	---	---	---	---	---	---	---	---

X	0	<del>0</del>	0	Y	1	1	1	1	B
---	---	--------------	---	---	---	---	---	---	---

Algorithm-

- Change 0 to X ✓
- Move Right to first "1"
- If None:Reject
- Change "1" to "y"
- Move LEFT to Leftmost "0"
- Repeat the above steps until no more "0"s
- Make sure no more "1"s remain

X	X	0	0	Y	1	1	1	1	B
---	---	---	---	---	---	---	---	---	---

no change  $\rightarrow 0/0, R$   
no change  $\rightarrow Y/Y, R$

X	X	0	0	Y	Y	1	1	1	B
---	---	---	---	---	---	---	---	---	---

X	X	X	0	Y	Y	1	1	1	B
---	---	---	---	---	---	---	---	---	---

$0/0, R$

$Y/Y, R$

$1/Y, L$

X	X	X	X	Y	Y	Y	1	1	B
---	---	---	---	---	---	---	---	---	---

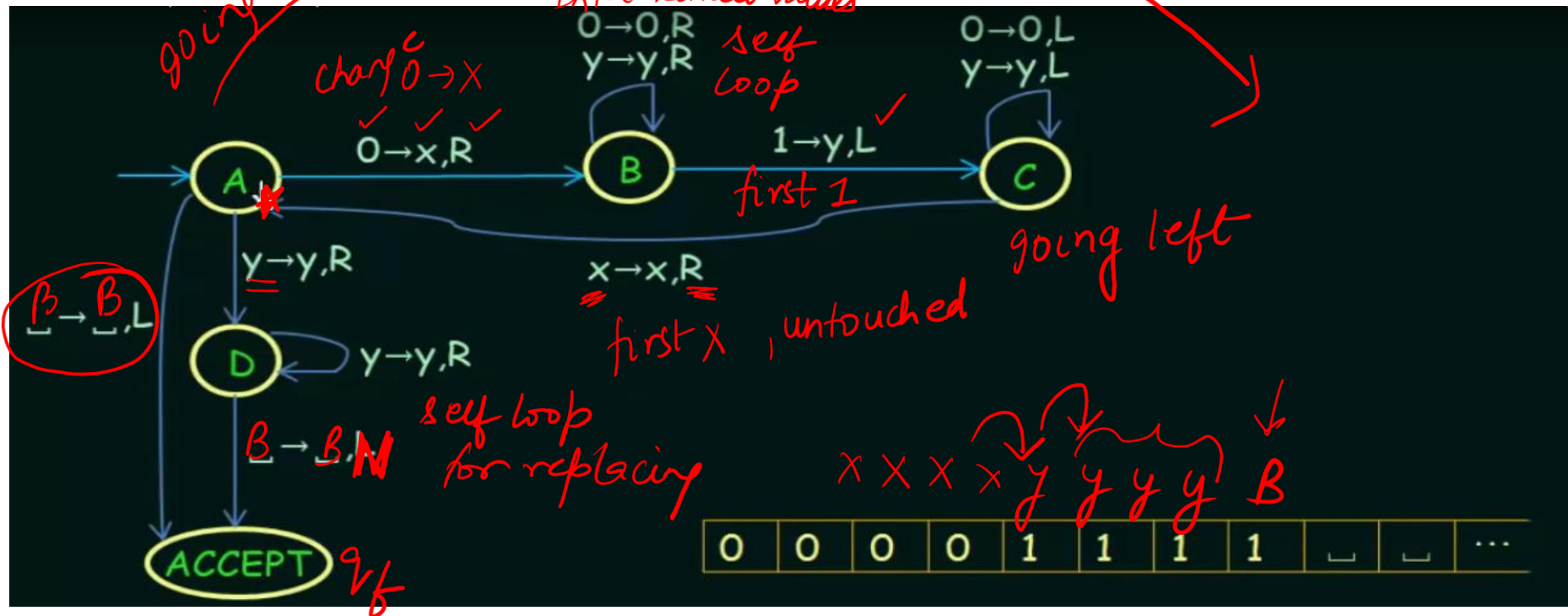
all 0's finished  $\rightarrow Y/Y, R$

X	X	X	X	Y	Y	Y	Y	B
---	---	---	---	---	---	---	---	---

accept  $\rightarrow B/B, N$

# TM Example 5

Design a TM which recognizes the language  $L=0^N 1^N$  for  $\Sigma=\{0,1\}$



Algorithm-

Change 0 to X

Move Right to first "1"

If None:Reject

Change "1" to "y"

Move LEFT to Leftmost "0"

Repeat the above steps until no more "0"s

Make sure no more "1"s remain

$a^n b^n \Rightarrow n=0$   
 $\Leftarrow \Rightarrow$  empty string