

TM

Turing Machine

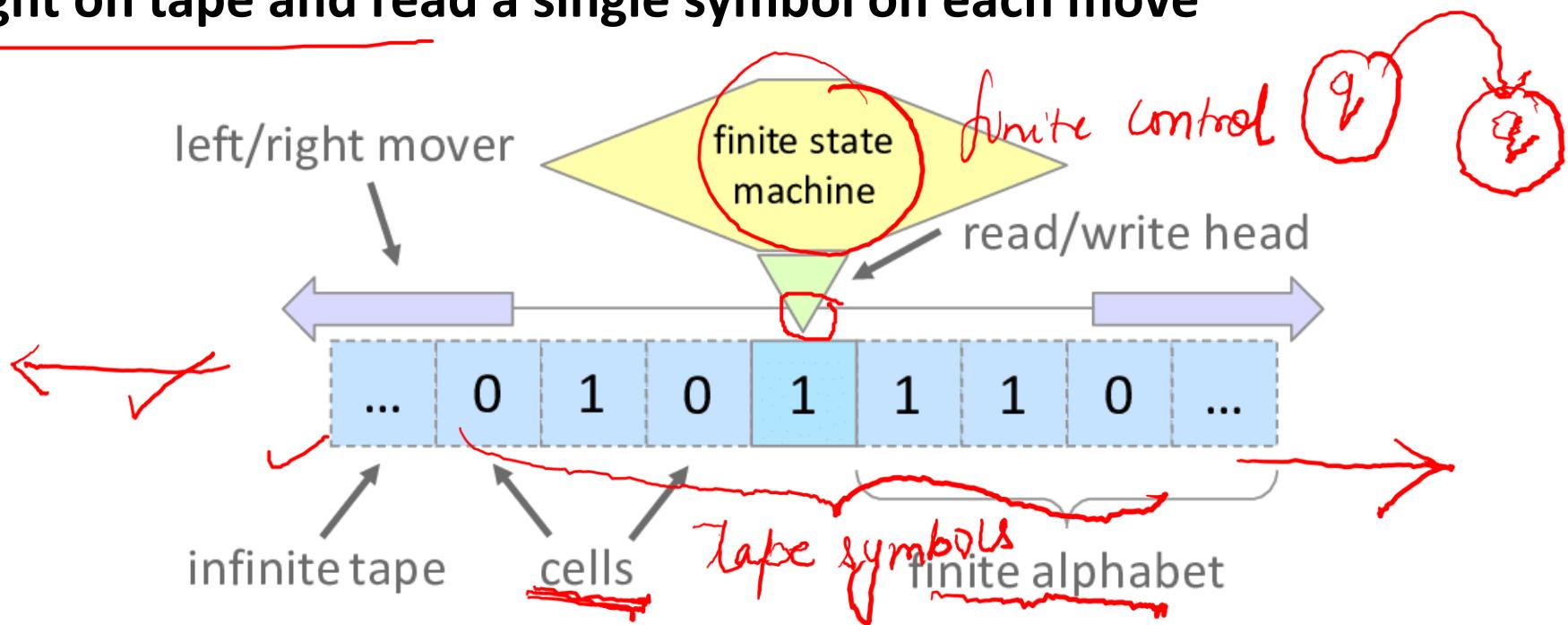
Consists of:-

- A Tape

Tape is infinite extending on either sides, divided into cells, each cell capable of holding one symbol

- Head-

Associated with tape is read-write head that can travel left or right on tape and read a single symbol on each move



Turing Machine

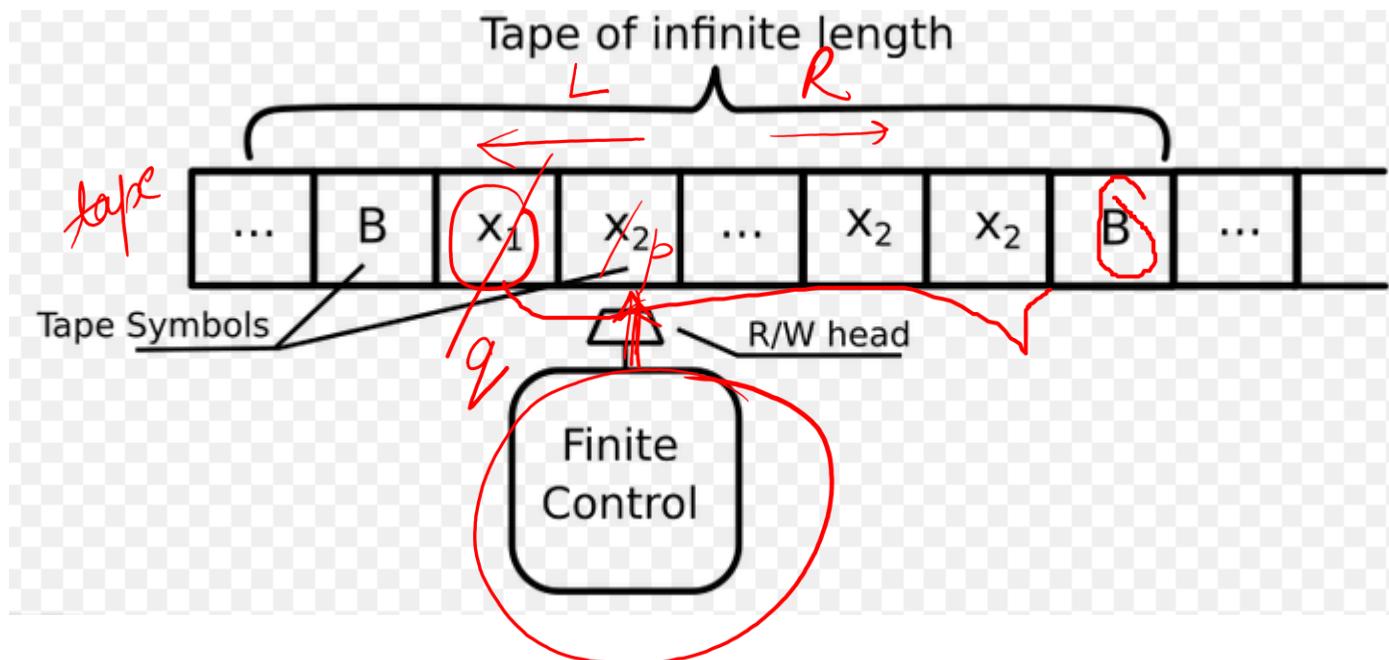
Consists of:-

- ✓ Tape Symbols-

Finite set of symbols, consists of lowercase letters, digits, usual punctuation marks and the Blank B

- ✓ States-

Set of states in which the machine can reside



Turing Machine

A Turing machine is a mathematical model of computation that defines an abstract machine[1] that manipulates symbols on a strip of tape according to a table of rules

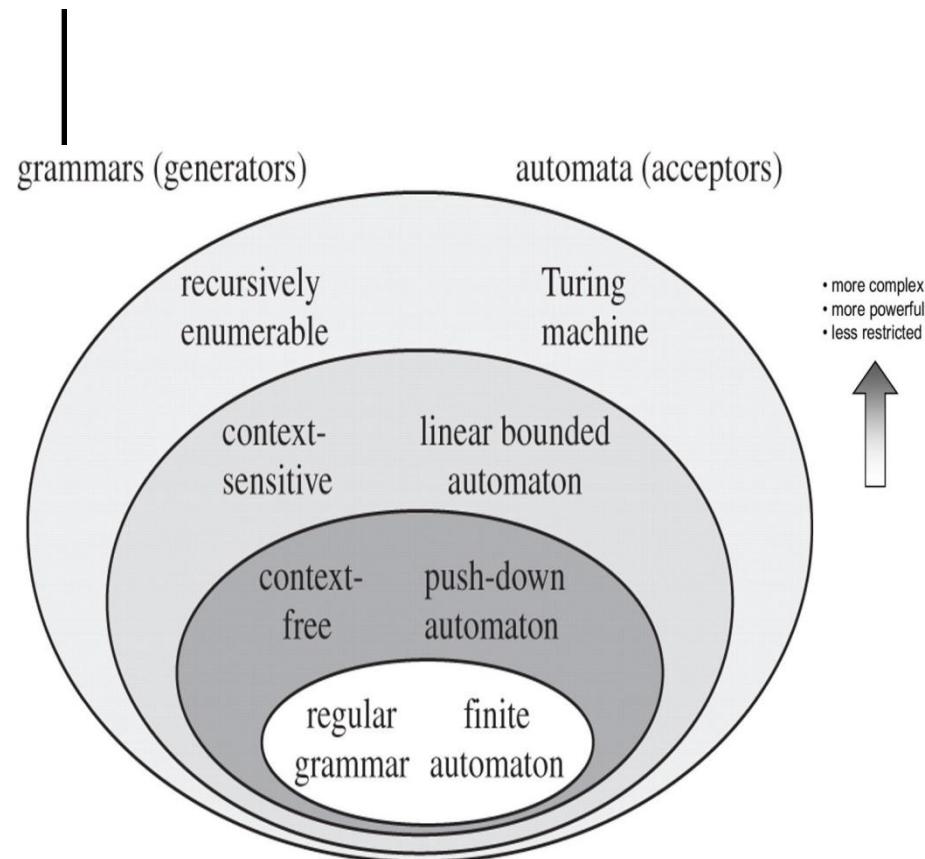
-Wikipedia

Turing Machine

- Turing Machine was invented by Alan Turing in 1936
- Accepts Recursive Enumerable Languages (generated by Type-0 Grammar).

The Hierarchy

Class	Grammars	Languages	Automaton
Type-0	Unrestricted	Recursive Enumerable	Turing Machine
Type-1	Context Sensitive	Context Sensitive	Linear-Bound
Type-2	Context Free	Context Free	Pushdown
Type-3	Regular	Regular	Finite



TM: Formal Definition

PDA is denoted by 7 Tuple: $M = (Q, \Sigma, \Gamma, \delta, q_0, B, F)$ where

$\begin{matrix} PDA \\ (Q, \Sigma, \Gamma, \delta, q_0, z_0, F) \end{matrix}$

• ✓ Q : Finite set of Internal states of the Control Unit

• ✓ Σ : Finite input alphabet

✓ Γ : Finite Set of Tape Symbols

✓ $\delta: Q \times \Gamma \rightarrow Q \times \Gamma \times \{L, R, N\}$: Transition function(TF)

• q_0 : Start state of Control Unit, $q_0 \in Q$

✓ B : Blank Symbol

• F : Set of Final States/ Accept State, $F \subseteq Q$

• $\Sigma \subseteq \Gamma - \{B\}$

$\begin{matrix} PDA \\ Pushdown \\ Stack \\ Symbols \end{matrix}$

δ Function

δ Function:-

- $\delta: Q \times \Gamma \rightarrow Q \times \Gamma \times \{L, R, N\}$: Transition function(TF)

✓ If $\delta(q, X) = (p, Y, L)$

- If present state is q and the next symbol on the tape is X then the Turing Machine changes the state to p , replaces the symbol X by symbol Y and moves the tape head one position left.

$$\delta(q, X) = (p, Y, L)$$

✓ If $\delta(q, X) = (p, Y, R)$

- If present state is q and the next symbol on the tape is X then the Turing Machine changes the state to p , replaces the symbol X by symbol Y and moves the tape head one position right.

TM Example 1

Transition Rules

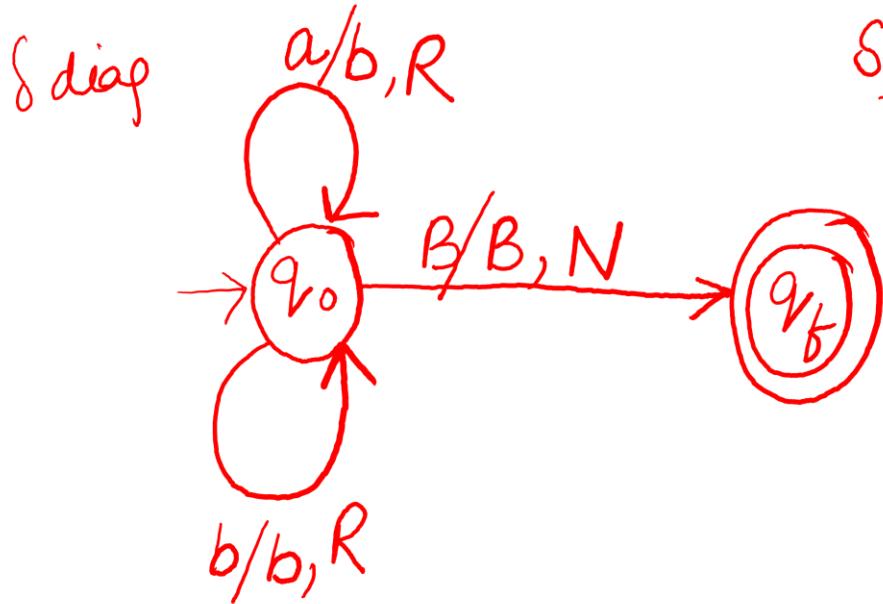
Construct a TM to replace each occurrence of 'a' by 'b' for the strings over $\Sigma = \{a, b\}$

$$\delta \text{ rules} \quad M = (Q, \Sigma, \Gamma, \delta, q_0, B, F)$$

$$\delta(q_0, a) = (q_0, b, R) \quad \text{Move Right}$$

$$\delta(q_0, b) = (q_0, b, R) \quad \text{Move Right}$$

$$\delta(q_0, B) = (q_f, B, N) \quad \text{No Movement}$$



Stable Tape Symbols

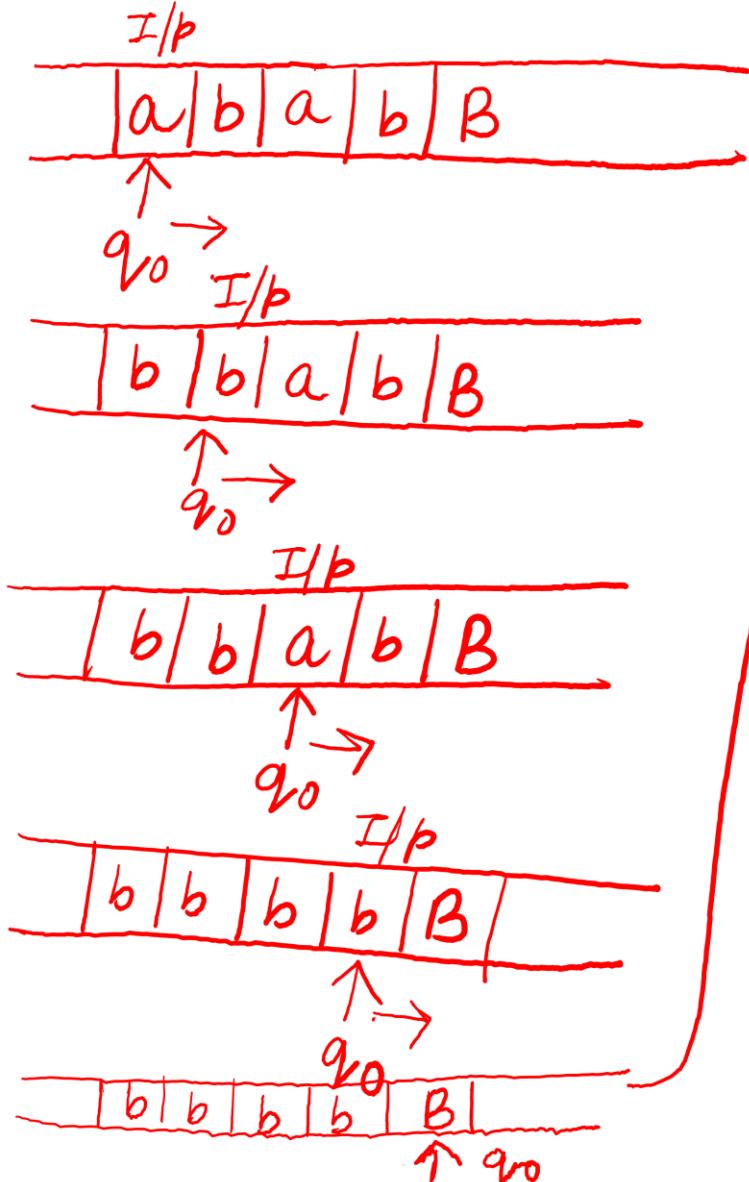
States	a	b	B
q_0	(q_0, b, R)	(q_0, b, R)	(q_f, B, N)
q_f	-	-	-

TM Example 1

Simulation

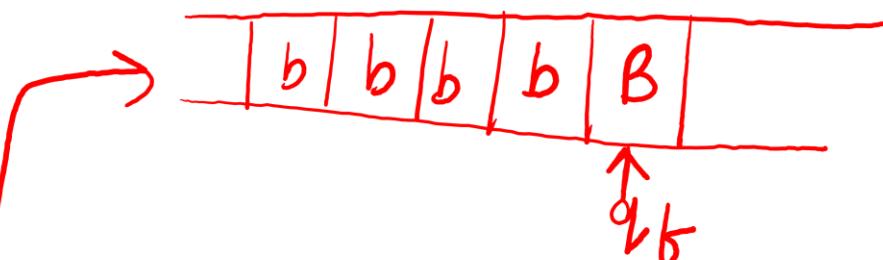
Construct a TM to replace each occurrence of 'a' by 'b' for the strings over $\Sigma = \{a, b\}$

String = "ab ab"



$$\delta(q_0, a) = (q_0, b, R)$$

$$\delta(q_0, b) = (q_0, b, R)$$



$$\delta(q_0, a) = (q_0, b, R)$$

$$\delta(q_0, b) = (q_0, b, R)$$

$$\delta(q_0, B) = (q_f, \underline{B}, N)$$

10111

TM Example 2

Transition Rules and Simulation

Design a TM to replace all occurrences of '111' by '101' over

 $\Sigma = \{0, 1\}$

$$\checkmark \quad \delta(q_0, 0) = (q_0, 0, R)$$

$$\checkmark \quad \delta(q_0, 1) = (q_1, 1, R)$$

$$\checkmark \quad \underline{\delta(q_0, B) = (q_f, B, N)}$$

$$\checkmark \quad \delta(q_1, 0) = (q_0, 0, R)$$

$$\checkmark \quad \delta(q_1, 1) = (q_2, 1, R)$$

$$\checkmark \quad \underline{\delta(q_1, B) = (q_f, B, N)}$$

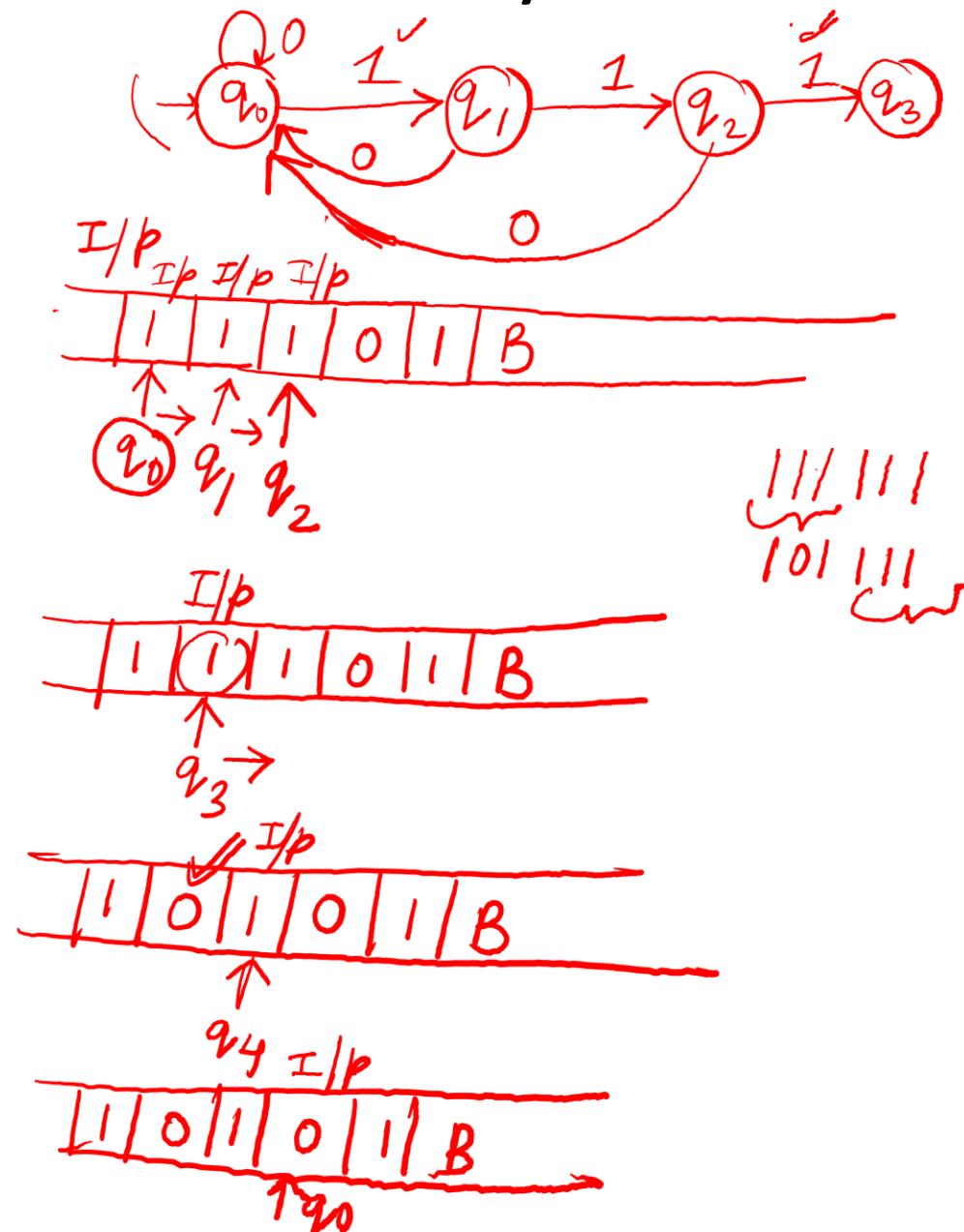
$$\checkmark \quad \delta(q_2, 0) = (q_0, 0, R)$$

$$\checkmark \quad \delta(q_2, 1) = (q_3, 1, L)$$

$$\delta(q_2, B) = (q_f, B, N)$$

$$\delta(q_3, 1) = (q_4, 0, R)$$

$$\delta(q_4, 1) = (q_0, 1, R)$$



TM Example 2

Transition Diagram ,Table

Design a TM to replace all occurrences of '111' by '101' over $\Sigma=\{0,1\}$

TM Example 3

Design a TM accept the language containing substring “aba” over $\Sigma=\{a,b\}$

Logic-

During the process if TM discovers “aba” on the tape, it halts and thereby accepts entire input string

$$M=(Q, \Sigma, \Gamma, \delta, q_0, B, F)$$

TM Example 3

Design a TM accept the language containing substring “aba” over $\Sigma=\{a,b\}$

$\delta(q_0,a)=(q_1,a,R)$

$\delta(q_0,b)=(q_0,b,R)$ self loop

$\delta(q_1,a)=(q_1,a,R)$ self loop

$\delta(q_1,b)=(q_2,b,R)$

$\delta(q_2,b)=(q_0,b,R)$ go back

$\delta(q_2,a)=(q_f,a,N)$

TM Example 4

Transition Rules

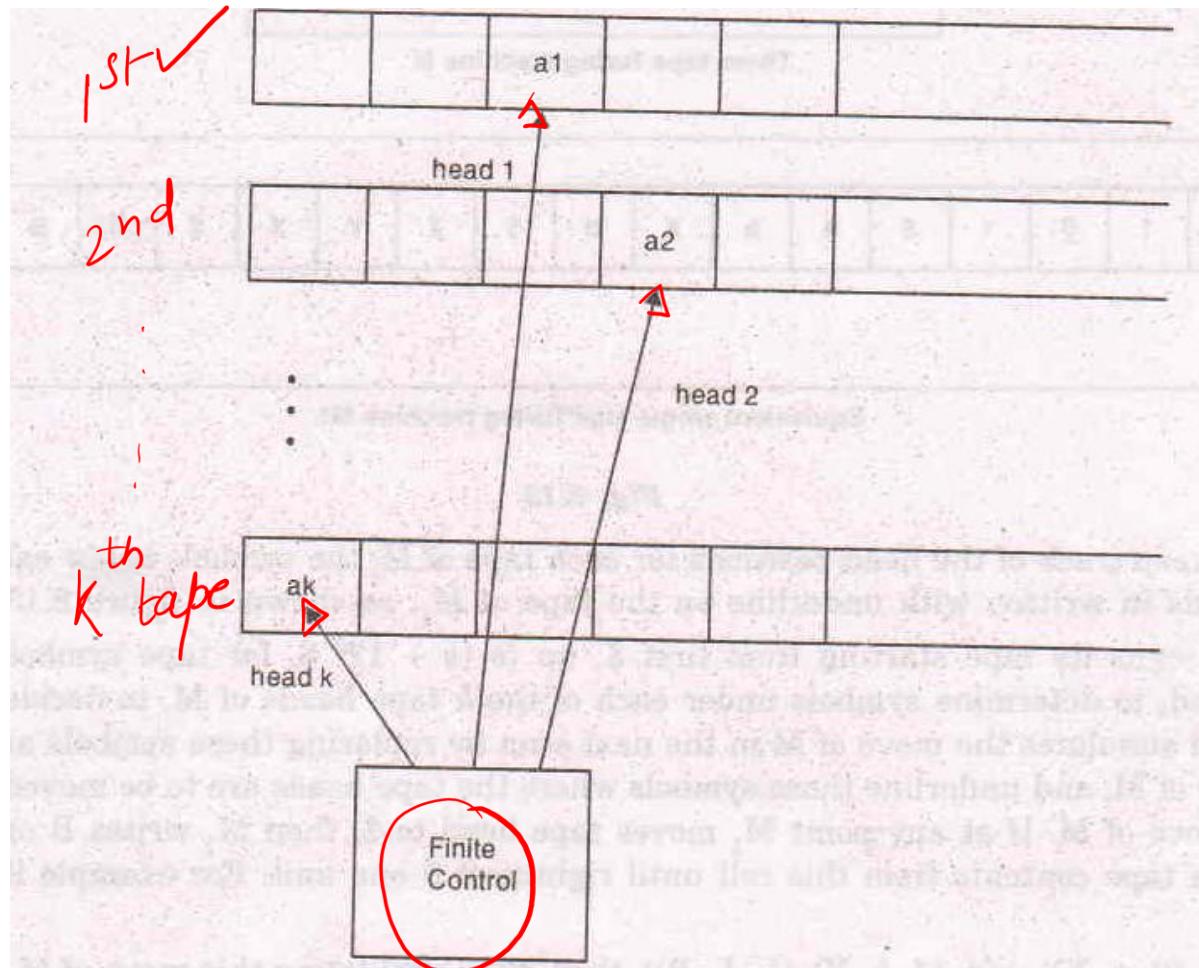
Design a TM to replace all occurrences of '101' by '011' over $\Sigma=\{0,1\}$

Modifications of Turing Machines or Variants of Turing Machines

- **Multi Tape Turing Machine**
- **Non-Deterministic Turing Machine**

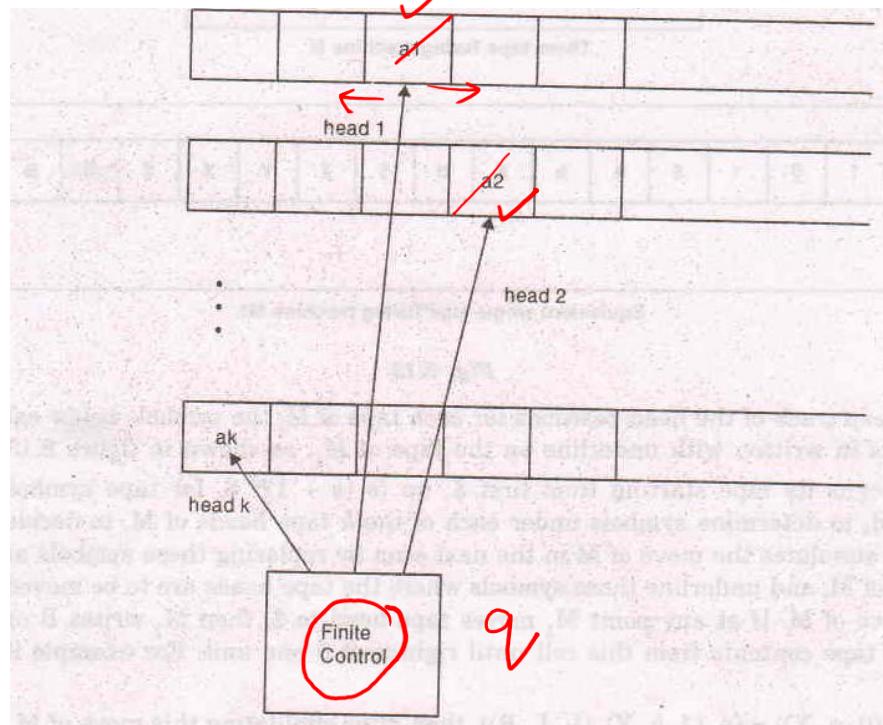
Multi Tape Turing Machine

- A Multitape Turing Machine-



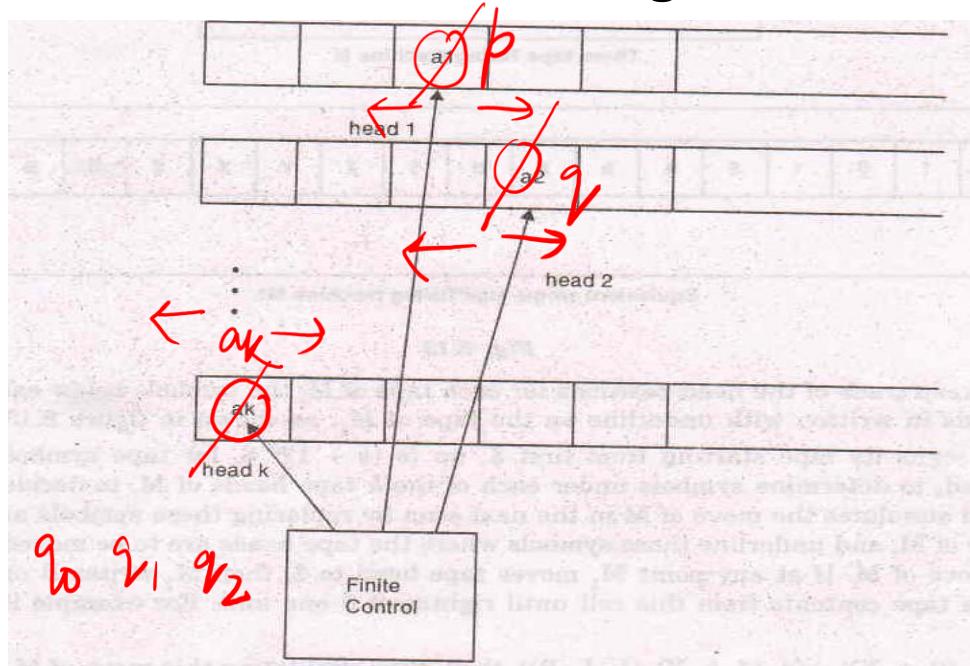
Multi Tape Turing Machine

- It is a Turing Machine with several tapes , each has its own tape heads
- It consists of a finite control with k tape heads and k tapes ($k > 1$)
- The move of this Turing machine depends on the present state of the finite control and the symbol scanned by each of the tape heads.



Multi Tape Turing Machine

- In each move, depending on the present state and the symbols scanned by each of the tape heads , the machine can
 - ~~change state of the finite control~~
 - print a new symbol on each of cells scanned by each of the tape heads
 - move each tape one cell left or one cell right independently



Multi Tape Turing Machine

$$\delta: Q \times \Gamma \rightarrow Q \times \Gamma^k \times \{L, R, N\}$$

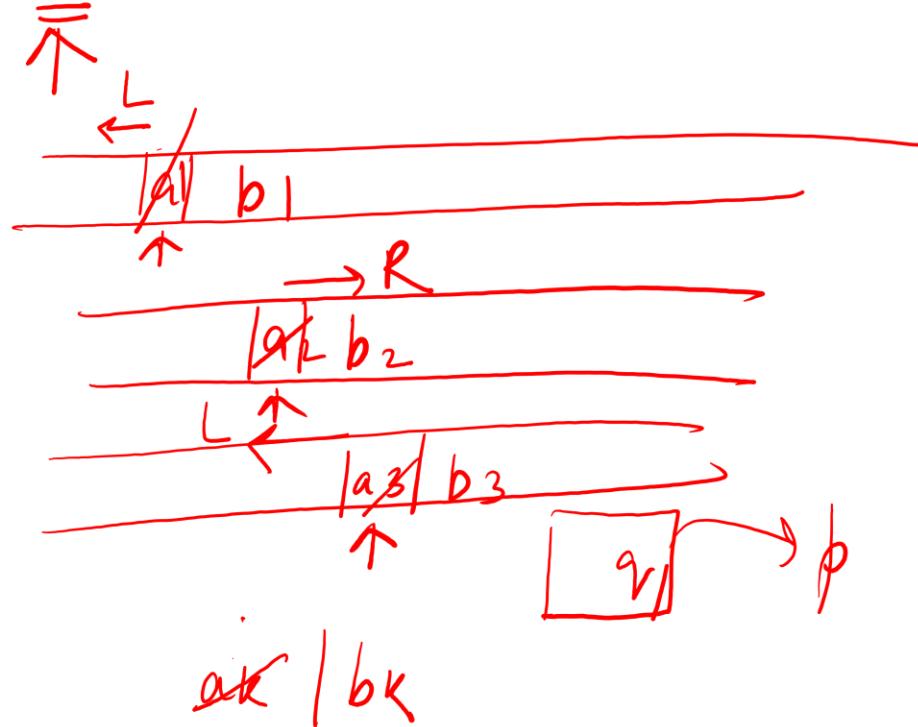
i/p from tapes

- The transition function of Multitape turing machine is :

✓ $\delta: Q \times \underbrace{\{r_1 \times r_2 \times \dots \times r_k\}}_{\text{tapes}} \rightarrow Q \times \underbrace{\{r_1 \times r_2 \times \dots \times r_k\}}_{\text{tapes}} \times \{ \underbrace{\{L, R, N\} \times \{L, R, N\} \times \dots \times \{L, R, N\}}_{\text{k times}} \}$

$\downarrow \quad \downarrow \quad \downarrow$
tape 1 tape 2 tape k

- $\delta(q_1, (a_1, a_2, \dots, a_k)) = (p, (b_1, b_2, \dots, b_k), (L, R, L, R, \dots, L \text{ k times}))$

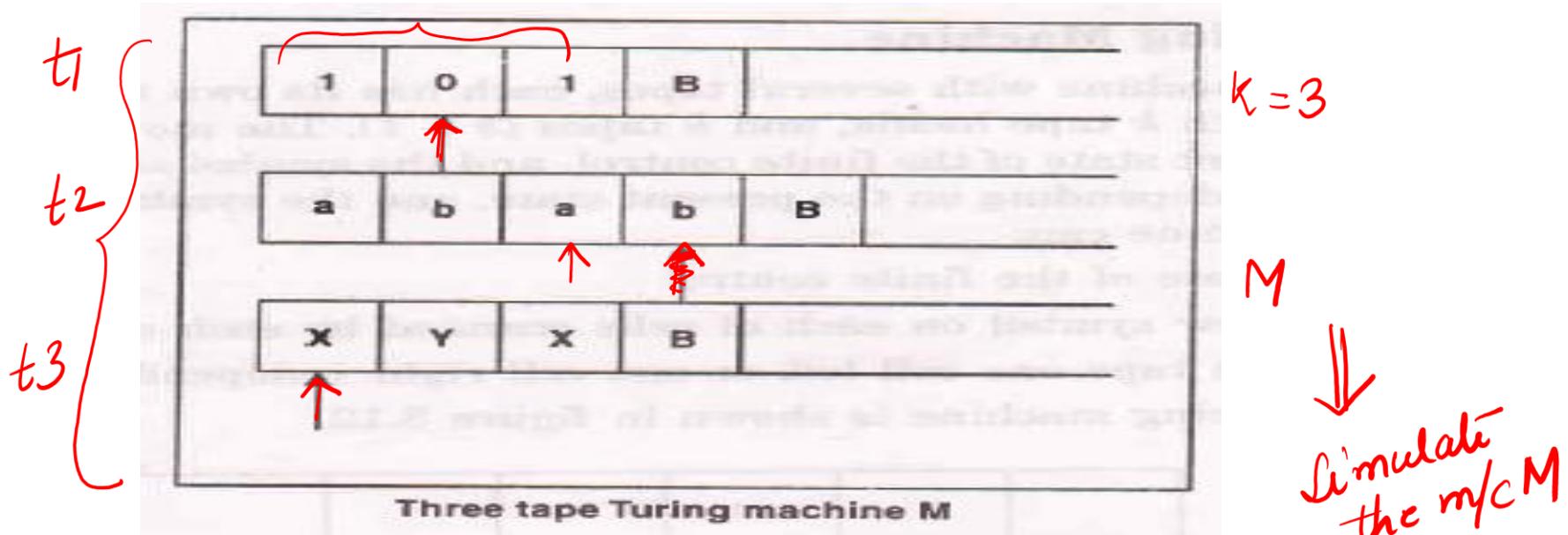


Multi Tape Turing Machine

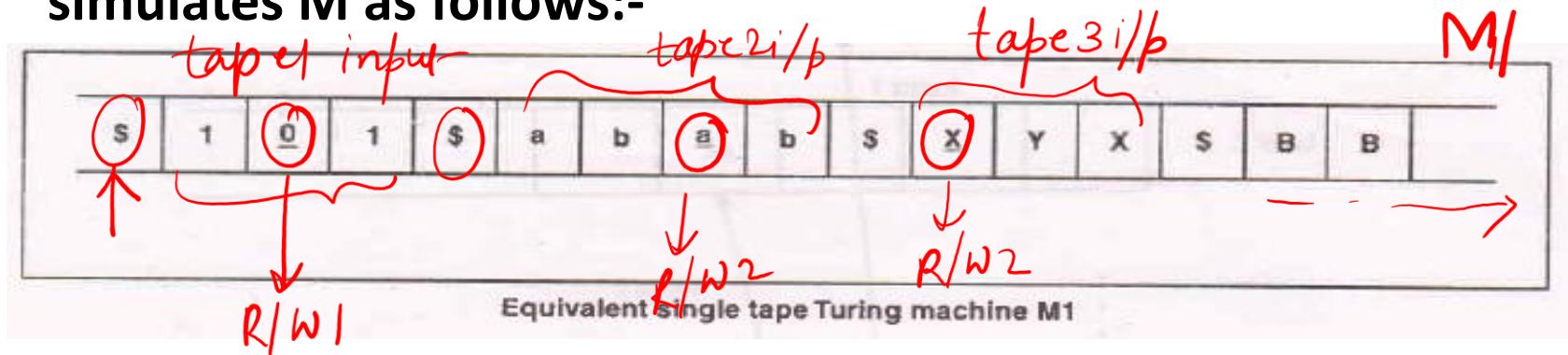
- ✓ All Variants have same power, every multtape turing machine has an equivalent single tape Turing machine

Multi Tape Turing Machine

- Let M be a k tape Turing Machine ($k > 1$)



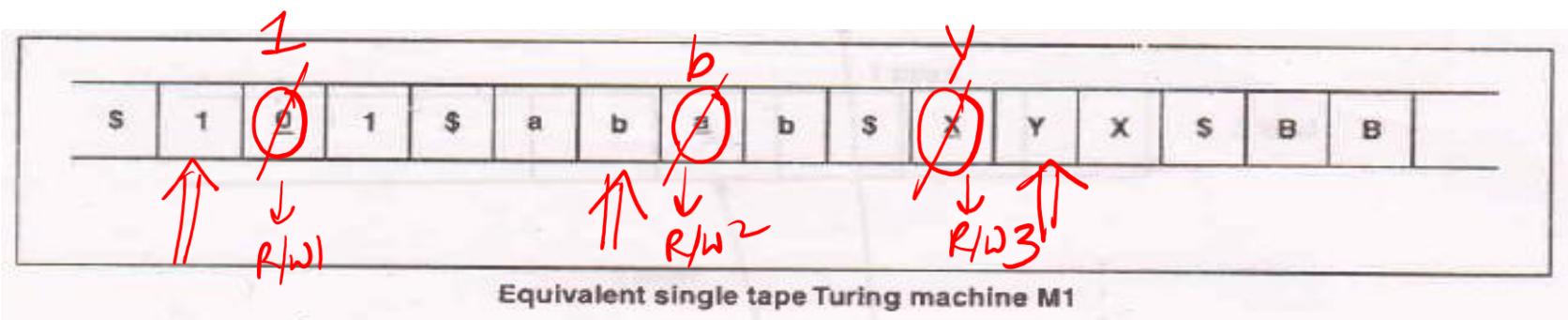
- Let us construct a single tape turing machine M_1 , which simulates M as follows:-



Multi Tape Turing Machine

$$\delta(q(0, a, x)) = (\rho, (\overline{y}, \overline{b}, \overline{y}), (\overline{L}, \overline{L}, \overline{R}))$$

- M1 stores the information available on the k tapes of M on its tape, using a symbol $\$$ as delimiter
- To keep a track of the head positions for each tape of M, the symbols below each of these tape heads are written with underline on the tape of M1



Multi Tape Turing Machine

- M1 scans its tape starting from first \$ up to $(k+1)$ st \$ for tape symbols that are underlined to simulate the move by replacing these symbols according to the move of M

- ✓ $\delta(q, (0, a, X)) = (p, (\underline{1}, \underline{b}, Y), (\underline{L}, \underline{L}, R))$
- After this move the contents of the tape are-

\$	1	1	1	\$	a	<u>b</u>	b	b	\$	Y	Y	X	\$	B	B
----	---	---	---	----	---	----------	---	---	----	---	---	---	----	---	---

Contents of tape of M1 after simulating the move of M

✓ Non-Deterministic Turing Machine

- Turing Machine which at any point while carrying out computation , may proceed according to several possibilities
- For a tape symbol scanned, The machine has a finite number of choices of next move
- The transition function defines mapping from
- $Q \times \Gamma$ to a finite subset of $Q \times \Gamma \times \{L,R,N\}$
- It accepts input, if some sequence of choices of moves lead to an accepting state

$$\delta(q_0, a) = (q_f, a, N)$$
$$\delta(q_0, a) = (q_1, b, R)$$

$$\delta(q_0, a) = (q_2, a, L)$$
$$(q, \Gamma) \rightarrow (q, \Gamma, \{L, R, N\})$$

3 choices \Rightarrow out of these 3 choices, for 1 choice
multiple moves non-determinism

we reach final state acceptance by final

Non-Deterministic Turing Machine

- All variants have the same power, thus Every Non-Deterministic Turing Machine has an equivalent
deterministic Turing machine

$$P(DTM) = P(NDTM)$$

Non-Deterministic Turing Machine

- For a Non-Deterministic Turing machine M,
- It is always possible to construct a turing machine M₁, which tries all possible sequences of computations or branches of computations of M
- If M enters into an accept state on any of these branches, M₁ accepts otherwise continues to simulate M without termination
- Thus, M₁ is accepting the same language as M

$\rightarrow \text{NDTM} = M$

$\text{DTM} = M_1$

either it enters into $q_f \Rightarrow$ string is accepted
else, goes on simulating without termination

TM Example 5

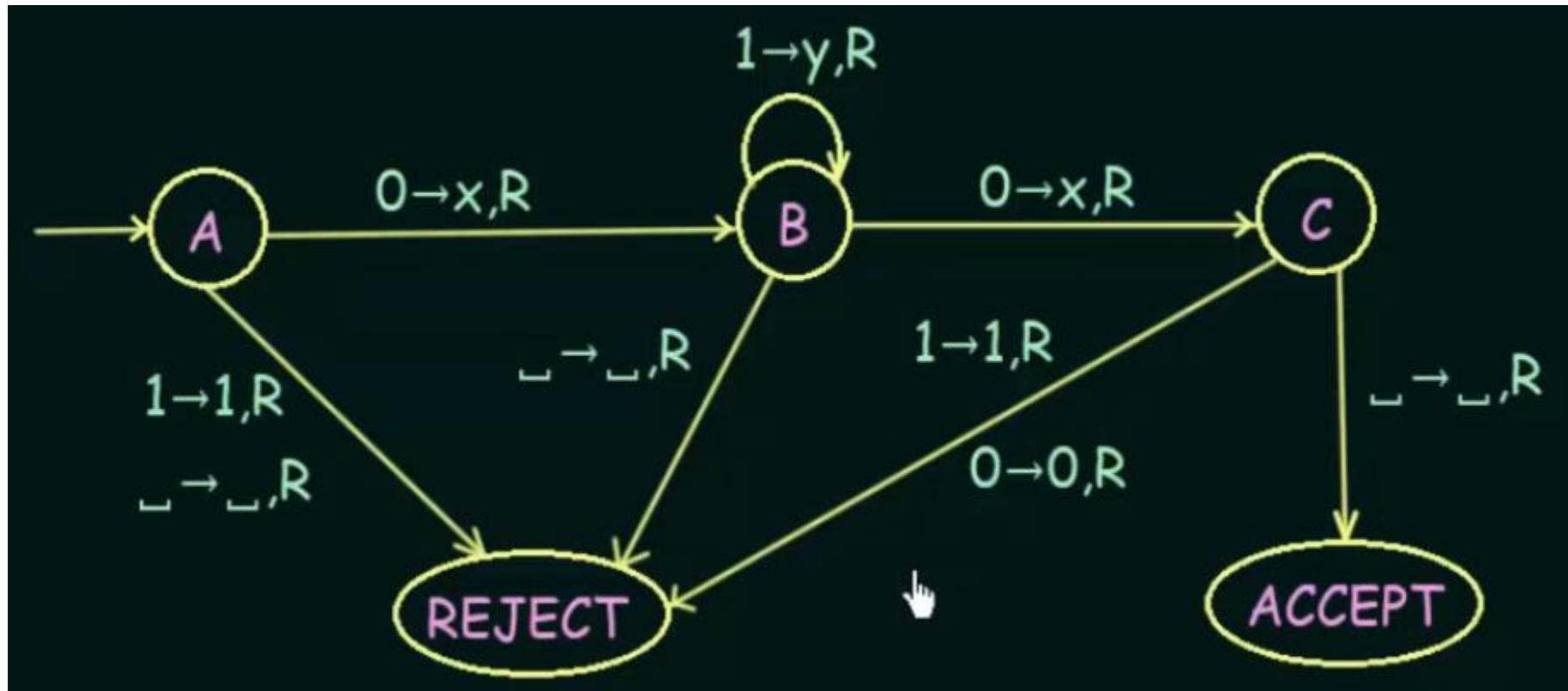
Transition Rules

Design a TM which recognizes the language $L=01^*0$ for $\Sigma=\{0,1\}$

Lets take string 0110

TM Example 5

Design a TM which recognizes the language $L=01^*0$ for $\Sigma=\{0,1\}$



0	1	1	0	B
X	Y	Y	X	B

TM Example 5

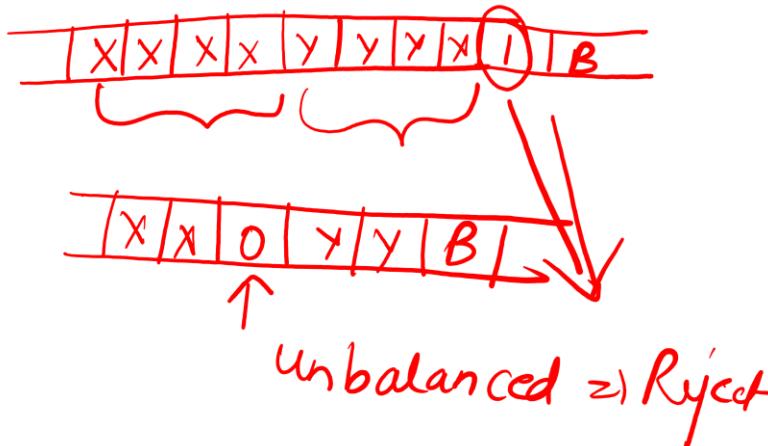
Design a TM which recognizes the language $L=0^N1^N$ for $\Sigma=\{0,1\}$

TM Example 5

Design a TM which recognizes the language $L=0^N 1^N$ for $\Sigma=\{0,1\}$

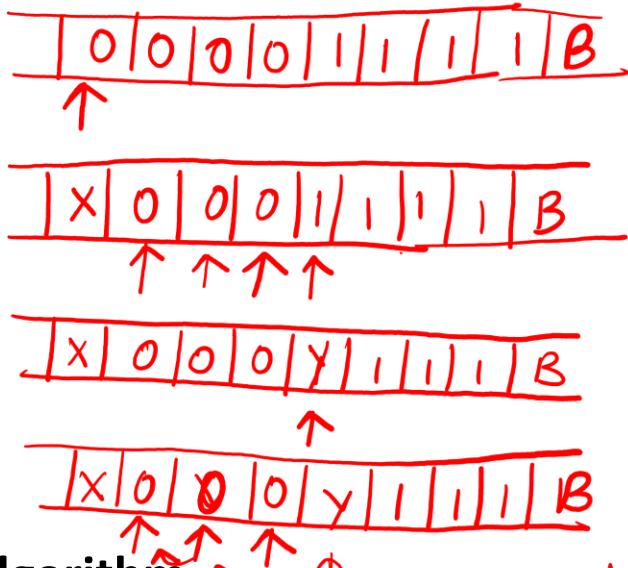
Algorithm-

- Change 0 to X
- Move Right to first “1”
- If None: Reject
- Change “1” to “y”
- Move LEFT to Leftmost “0”
- Repeat the above steps until no more “0”s
- Make sure no more “1”s remain



TM Example 5

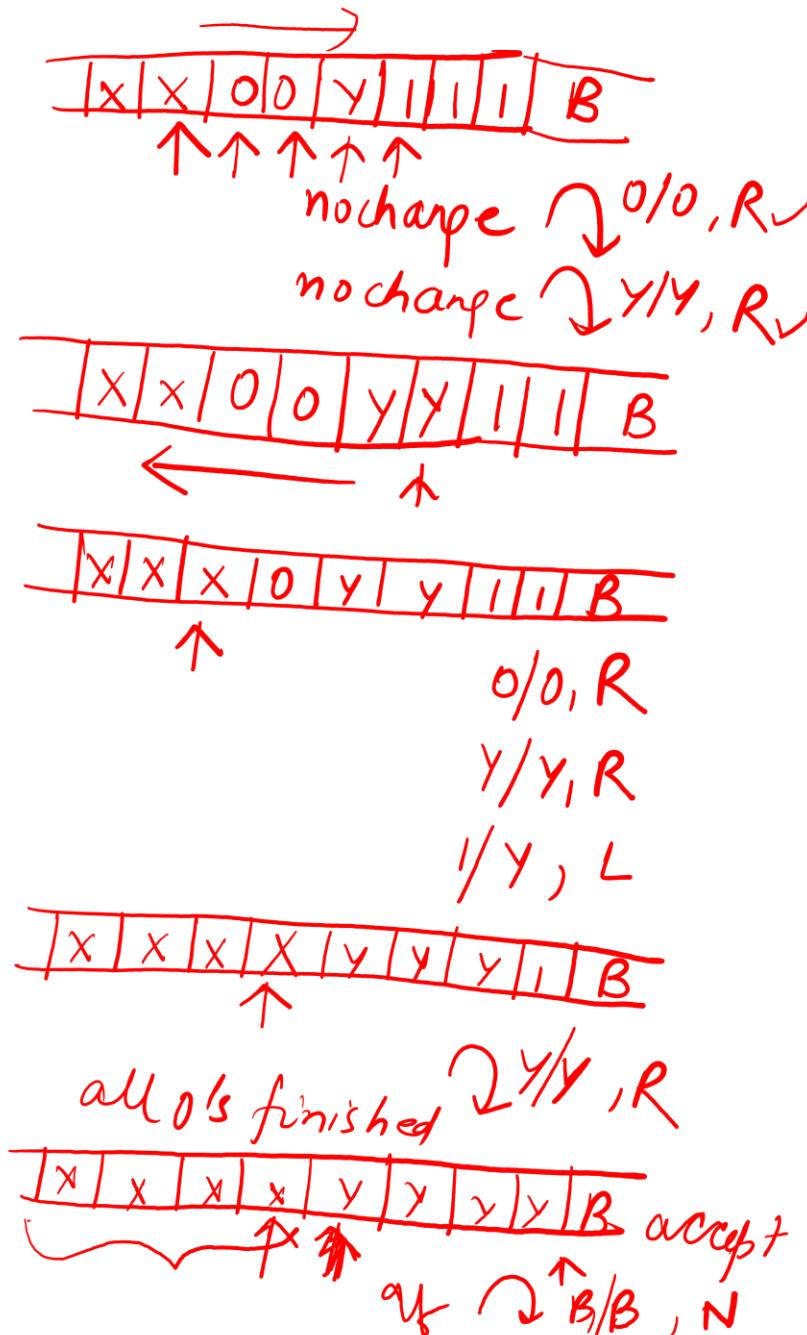
Simulation for $L=0^N 1^N$, String 00001111



Algorithm-

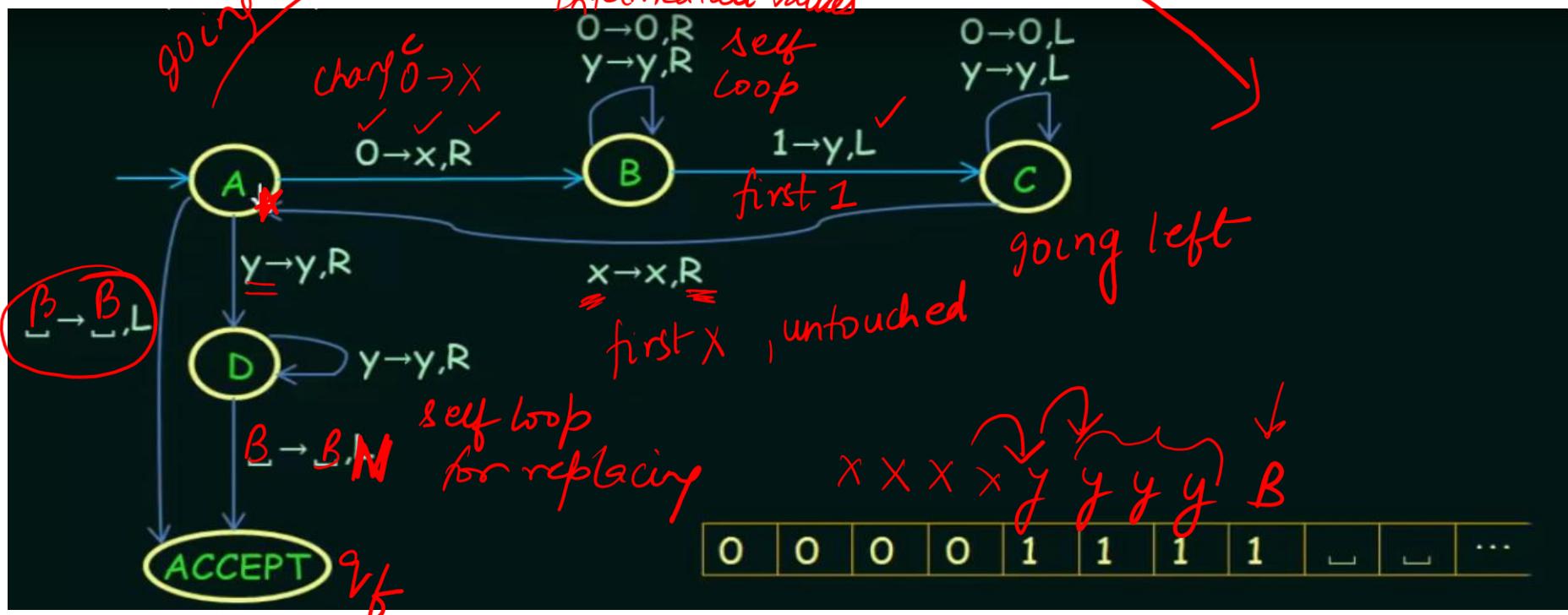
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TM Example 5

~~Design a TM which recognizes the language $L=0^N 1^N$ for $\Sigma=\{0,1\}$~~



Algorithm-

Change 0 to X

Move Right to first "1"

If None: Reject

Change "1" to "y"

Move LEFT to Leftmost "0"

Repeat the above steps until no more "0"s

Make sure no more "1"s remain

$$a^n b^n \Rightarrow \begin{cases} n=0 \\ \leftarrow \Rightarrow \text{empty string} \end{cases}$$