

Machine Learning Foundations

Week 4

Lecture - 1 : Linear & Polynomial Regression

feature matrix (A):

$$A = \begin{bmatrix} \text{Age} & \text{Education} & \text{Experience} \\ \text{01} & 35 & 15 \\ \text{02} & 45 & 15 \\ \text{03} & 35 & 16 \end{bmatrix}$$

\hat{Y}

$$Y = \begin{bmatrix} \text{Income} \\ 100000 \\ 150000 \\ 200000 \end{bmatrix}$$

$$x_1 = \begin{bmatrix} 35 \\ 15 \\ 3 \end{bmatrix}$$

$$x_2 = \begin{bmatrix} 45 \\ 15 \\ 8 \end{bmatrix}$$

$$x_3 = \begin{bmatrix} 35 \\ 16 \\ 5 \end{bmatrix}$$

$$Y = \begin{bmatrix} 100000 \\ 150000 \\ 200000 \end{bmatrix}$$

$$E = \frac{1}{n} \sum_{i=1}^n (y_i - \hat{y}_i)^2$$

$$= \frac{1}{3} \times \frac{(100000 - 100000)^2 + (150000 - 150000)^2 + (200000 - 200000)^2}{3}$$

$$= \frac{1}{3} \times 0 = 0$$

$$MSE = \frac{1}{n} \times E$$

$$= \frac{1}{3} \times 0 = 0$$

$$(\text{predicted}) \hat{y} = \theta_0 + \theta_1 x_1 + \theta_2 x_2 + \theta_3 x_3 \quad \leftarrow \text{Model (Linear Reg)}$$

Estimate: $\theta = \begin{bmatrix} \theta_0 \\ \theta_1 \\ \theta_2 \\ \theta_3 \end{bmatrix}$ $\rightarrow \text{parameters}$

$$\frac{1}{2} \times E$$

$$\text{Error}^2 = (\text{actual} - \text{predicted})^2 = (\text{predicted} - \text{actual})^2$$

$$e_i^2 = (\hat{y}_i - y_i)^2$$

$$E = \frac{1}{2} \sum_{i=1}^n e_i^2$$

$$\begin{aligned} a \cdot a &= a^T a \\ &= a^2 \end{aligned}$$

$$E = \frac{1}{2} (A\theta - Y)^T (A\theta - Y)$$

$A\theta \rightarrow \text{predicted}$
 $Y \rightarrow \text{actual}$

$$(A\theta - Y) \cdot (A\theta - Y)$$

To find best θ E should be minimum

$$\Rightarrow \nabla E = 0$$

We did this derivation in week 4 live session

$$A^T A \theta = A^T b$$

$$\Delta E = 0$$

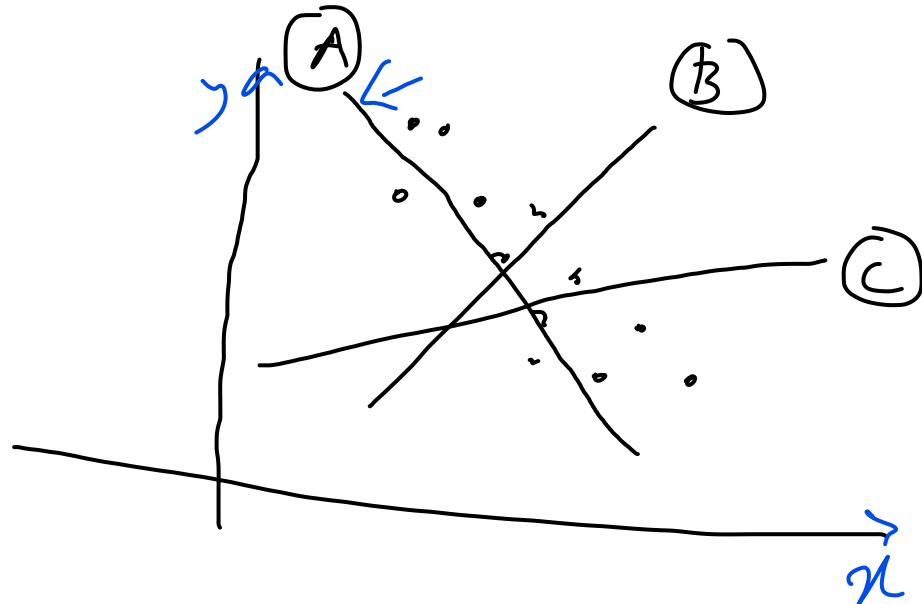
$$A^T (A\theta - y) = 0$$

$$\nabla E = 0$$

$$A^T A \theta - A^T y = 0$$

$$\underline{\theta} = (A^T A)^{-1} A^T y$$

Maximum Likelihood of \hat{X}



→ which line is most likely to represent data points? (A)

→ How were we finding that line?

→ least square

Polynomial Regression: We do feature transformation depending on model we want.

For one feature: $\{1, x_1\}$, $\{1, x_1, x_1^2\}$

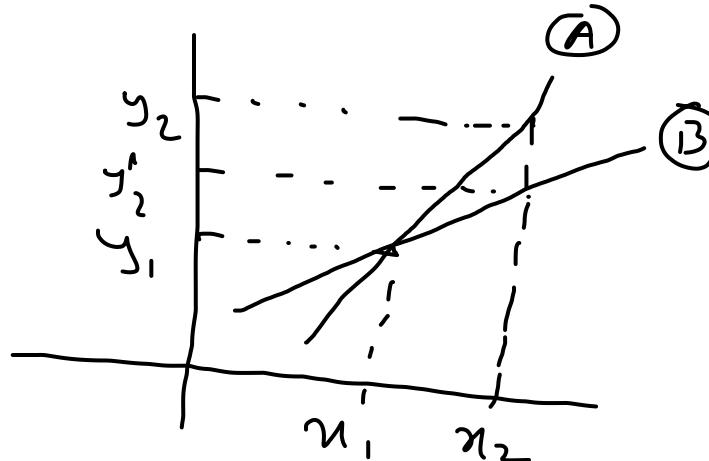
$$y = c + mx_1 \rightarrow$$
$$y = a + bx_1 + cx_1^2$$

for two features: $\{1, x_1, x_2\}$, $\{1, x_1^2, x_2^2\}$, $\{1, x_1, x_2, x_1^2, x_2^2\}$

* first do transformation then apply linear Reg resion

$$y = \theta_0 + \theta_1 x_1 + \theta_2 x_1^2$$

Regularization: To reduce sensitivity (wide variation) with input (layman)



→ which line is more sensitive to change in input?

→ why $(A^T A + \lambda I)$ is invertible even if $A^T A$ is not.

e.g.

$$\underline{A^T A} = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 5 & 7 \\ 3 & 7 & 10 \end{bmatrix}$$

$$A^T A + \lambda I = \begin{bmatrix} 3 & 2 & 3 \\ 2 & 7 & 7 \\ 3 & 7 & 12 \end{bmatrix}$$

Full
rank
invert

Lec 2: Eigen Value & Eigen Vector

When you apply a linear transformation on a vector then if

$$\boxed{A x = \lambda x}$$

where

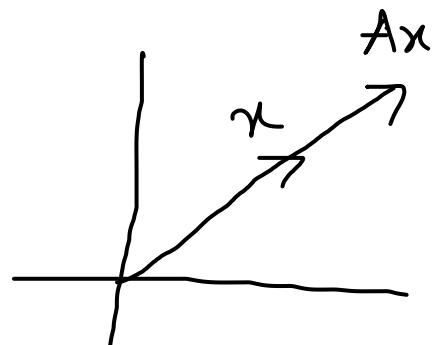
x = vector

λ = scalar

A = matrix

$x \rightarrow$ eigen vector

$\lambda \rightarrow$ eigen value



Motivation was derived in live session of week 4 ~~#~~

$$\begin{aligned}|(A - \lambda I)| &= 0 && \text{To find } \lambda's \\ A\mathbf{x} = \lambda\mathbf{x} && \text{To find } \mathbf{x}'s\end{aligned}$$

Lec 3: Diagonalization

We did derivation in live session

$n \times n$

Steps: 1. Find eigen Value $(\lambda_1, \lambda_2, \lambda_3)$ 3×3

2. Find eigen vector $(\mathbf{x}_1, \mathbf{x}_2, \mathbf{x}_3)$

3. $S = \begin{bmatrix} | & | & | \\ \mathbf{x}_1 & \mathbf{x}_2 & \mathbf{x}_3 \\ | & | & | \end{bmatrix}$ $S^{-1}AS = \Lambda$

$$4. \quad S^{-1}AS = \Lambda \rightarrow$$

$$\Lambda = \begin{bmatrix} \lambda_1 & 0 & 0 \\ 0 & \lambda_2 & 0 \\ 0 & 0 & \lambda_3 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 1 & 1 \\ n_1 & n_2 & n_3 \\ 1 & 1 & 1 \end{bmatrix}^{-1} \begin{bmatrix} A \end{bmatrix} \begin{bmatrix} 1 & 1 & 1 \\ n_1 & n_2 & n_3 \\ 1 & 1 & 1 \end{bmatrix} = \begin{bmatrix} \lambda_1 & 0 & 0 \\ 0 & \lambda_2 & 0 \\ 0 & 0 & \lambda_3 \end{bmatrix}$$

Imp property: $S^{-1}AS = \Lambda$ ————— ①

$$\text{eqn(1)} \times \text{eqn(1)}$$
$$S^{-1}AS \cdot S^{-1}AS = \Lambda^2$$
$$\Rightarrow S^{-1}A^2S = \Lambda^2$$

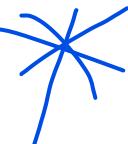
eqn(1) \times eqn(1) - - - k times

$$S^{-1}A^kS = \Lambda^k$$

Lec4: Fibonacci Sequence:

- * Derived Completely in Live Session
- * Not as imp from exam point of view

Lec5: Orthogonally diagonalizable matrices

- * when A is real symmetric
- * we know $S^{-1}AS = \Lambda$
 $A = S\Lambda S^{-1}$
- * for real Symmetric case we have
 $S S^T = S^T S = I$ 
i.e., S is orthogonal

$$\therefore S^T A S = \Lambda$$

or

$$A = S \Lambda S^T$$

$$A = Q \Lambda Q^T$$

- Steps:
- ① Find eigen values
 - ② Find eigen vectors
 - ~~③ Normalize eigen vectors~~
 - ④ Rest steps same as diagonalization.

$$A = \begin{bmatrix} 1 & 2 \\ 0 & 3 \end{bmatrix} \quad \lambda_1 = 1 \quad \lambda_2 = 3$$

For $\lambda_1 = 1$ $(A - \lambda I) u = 0$

$$\begin{bmatrix} 1-1 & 2 \\ 0 & 3-1 \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 0 & 2 \\ 0 & 2 \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$6u_1 + 2u_2 = 0 \quad u_2 = 0 \quad u_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$u_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

For $\lambda_2 = 3$

$$\begin{bmatrix} -2 & 2 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} n_1 \\ n_2 \end{bmatrix} \neq \begin{bmatrix} -2n_1 + 2n_2 = 0 \\ 0 \end{bmatrix}$$
$$n_2 = [1] \quad n_1 = n_2$$

$$S = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}$$

$$S^{-1} = \frac{1}{1-0} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix}$$

$$\frac{1}{ad-bc}$$

$$\begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$$

$$\frac{1}{1-0} \begin{bmatrix} 1 & -1 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & -1 \\ 0 & 1 \end{bmatrix}$$

$$S^{-1} AS = \begin{bmatrix} 1 & -1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 0 & 3 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 6 \\ 0 & 3 \end{bmatrix}$$

$$\xrightarrow{\text{adj } A} \underline{\underline{AA^{-1}}} = \underline{\underline{I}}$$

$$\boxed{A^{-1} = \frac{1}{|A|} \text{adj } A}$$

$$y = mx + c$$

$$m = 0 \quad c = 2$$

$y = 0x + 2$

$y = 2$

residual

| n | y | \hat{y} | $\hat{y} - y$ | $(\hat{y} - y)^2$ |
|-----|-----|-----------|---------------|-------------------|
| 1 | 2 | 2 | 0 | 0 |
| 2 | 4 | 2 | -2 | 4 |
| 3 | 1 | 2 | -1 | 1 |
| 4 | 3 | 2 | -1 | 1 |

Sum of residual = 0

$$SSE = \frac{6}{2} = 3$$

$$MSE = \frac{6}{4} //$$

y_i 2nd degree model fit

$$y = \theta_0 + \theta_1 x + \theta_2 x^2$$

$$\begin{matrix} y \\ 1 \end{matrix} \quad x$$

$$y_1 = \theta_0 + \theta_1 x_1 + \theta_2 x_1^2$$

$$\begin{matrix} y \\ 2 \end{matrix} \quad x$$

$$y_2 = \theta_0 + \theta_1 x_2 + \theta_2 x_2^2$$

$$\begin{matrix} y \\ 3 \end{matrix} \quad x$$

$$y_3 = \theta_0 + \theta_1 x_3 + \theta_2 x_3^2$$

$$y = \theta_0 + \theta_1 + \theta_2$$

$$16 = \theta_0 + 2\theta_1 + 4\theta_2$$

$$19 = \theta_0 + 4\theta_1 + 16\theta_2$$

$$\begin{bmatrix} 4 \\ 16 \\ 19 \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ -1 & 1 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} 1 & 1 & 1 \\ 2 & 4 & 4 \\ 4 & 16 & 16 \end{bmatrix} \begin{bmatrix} \theta_0 \\ \theta_1 \\ \theta_2 \end{bmatrix}$$

$$\begin{bmatrix} \theta_0 \\ \theta_1 \\ \theta_2 \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 \\ -1 & 1 & 1 \\ 1 & -1 & 1 \end{bmatrix}^{-1} \begin{bmatrix} 4 \\ 16 \\ 19 \end{bmatrix} = \boxed{\quad}$$

