

Divergence

$$\vec{B} = \frac{\mu_0 I}{2\pi r} \hat{\phi}$$

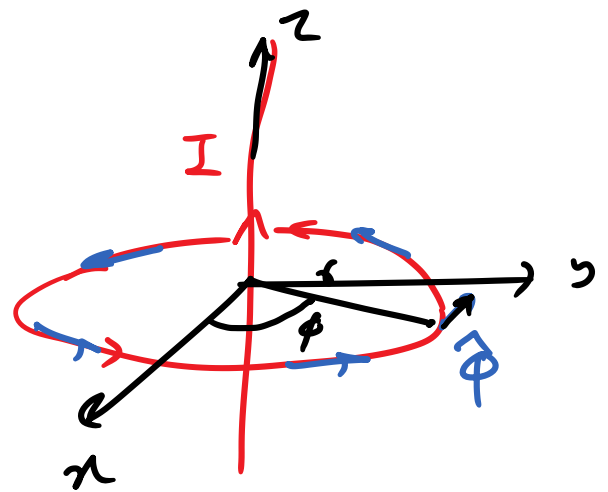
$$r = (x^2 + y^2)^{1/2}$$

$$\hat{\phi} = -\sin\phi \hat{x} + \cos\phi \hat{y}$$

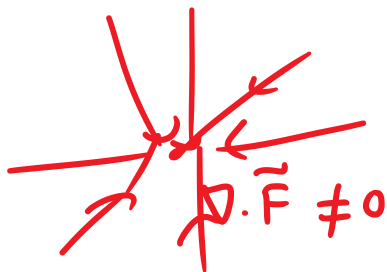
$$x = r \cos\phi ; \quad y = r \sin\phi$$

$$\hat{\phi} = -\frac{y \hat{x}}{r} + \frac{x \hat{y}}{r} = \frac{1}{r} (-y \hat{x} + x \hat{y})$$

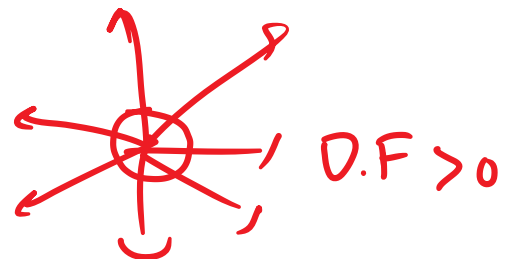
$$\boxed{\vec{B} = \frac{\mu_0 I}{2\pi (x^2 + y^2)} (-y \hat{x} + x \hat{y})}$$



$$\nabla \cdot \vec{B} = \frac{\partial B_x}{\partial x} + \frac{\partial B_y}{\partial y} + \frac{\partial B_z}{\partial z} = 0$$



$$\nabla \cdot \vec{F} < 0$$

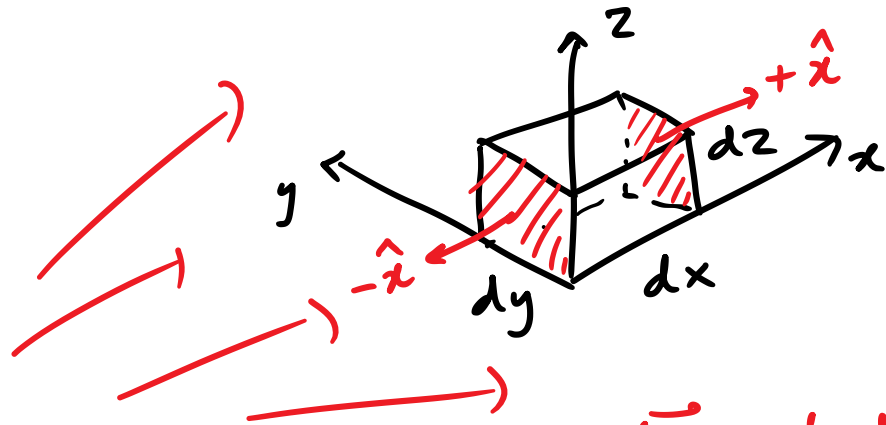


$$\vec{F} = xy\hat{x} + 2yz\hat{y} + 3xz\hat{z}$$

$$\nabla \cdot \vec{F} = y + 2z + 3x \neq 0$$

$$\vec{F}_2 = x^2\hat{x} + 3xz^2\hat{y} - 2xz\hat{z}$$

$$\nabla \cdot \vec{F}_2 = 0$$

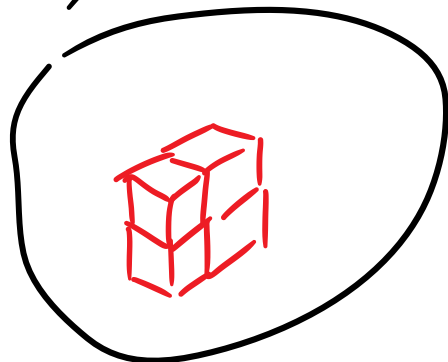


$$d\vec{S}_1 = -dydz\hat{x}$$

$$\vec{F} \cdot d\vec{S}_1$$

$$\nabla \cdot \vec{F} \, dx \, dy \, dz = \oint \vec{F} \cdot d\vec{A}$$

$$\nabla \cdot \vec{F} = \lim_{\Delta V \rightarrow 0} \left(\frac{\oint \vec{F} \cdot d\vec{A}}{\Delta V} \right)$$



$$\iiint \nabla \cdot \vec{F} \, dV = \oint \vec{F} \cdot d\vec{A}$$

GAUSS'S
Theorem

$dV = dx \, dy \, dz$ Volume element

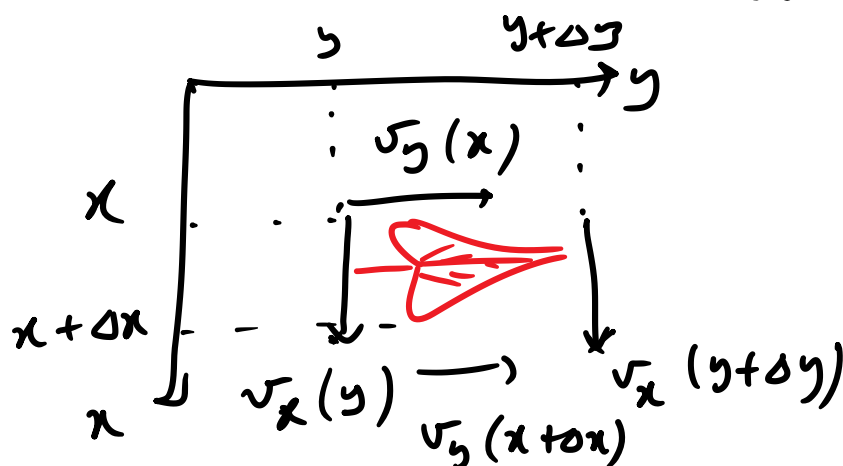
$d\vec{A} = dA \, \hat{n} =$ Surface element

Divergence theorem

CURL

$\nabla \times \vec{F}$: Curl of \vec{F}

$$\begin{aligned} \nabla \times \vec{F} &= \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ F_x & F_y & F_z \end{vmatrix} \\ &= \hat{x} \left(\frac{\partial F_z}{\partial y} - \frac{\partial F_y}{\partial z} \right) + \hat{y} \left(\frac{\partial F_x}{\partial z} - \frac{\partial F_z}{\partial x} \right) \\ &\quad + \hat{z} \left(\frac{\partial F_y}{\partial x} - \frac{\partial F_x}{\partial y} \right) \end{aligned}$$



$$\begin{aligned} v_x(y + \Delta y) - v_x(y) &= v_x(y) + \frac{\partial v_x}{\partial y} \Delta y - v_x(y) \\ &= \frac{\partial v_x}{\partial y} \Delta y \end{aligned}$$

$$v_y(x + \Delta x) - v_y(x) = \frac{\partial v_y}{\partial x} \Delta x$$

$$\left| \begin{pmatrix} \frac{\partial v_y}{\partial x} - \frac{\partial v_x}{\partial y} \end{pmatrix} \right|$$

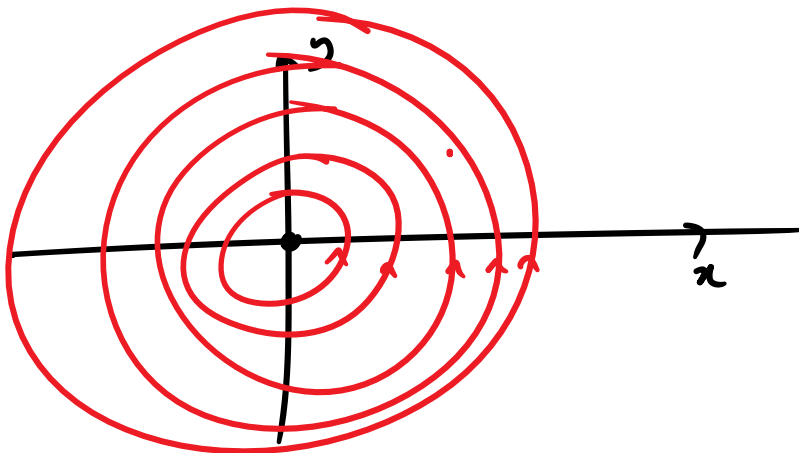
$$\vec{B} = \frac{\mu_0 I}{2\pi (x^2 + y^2)} (-y \hat{x} + x \hat{y}) \checkmark$$

$$\nabla \times \vec{B} =$$

$$\uparrow$$

$$r \neq 0$$

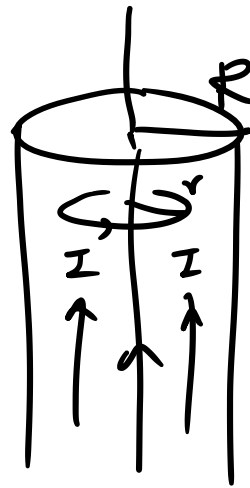
$$\begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ -\frac{y}{x^2 + y^2} & \frac{x}{x^2 + y^2} & 0 \end{vmatrix} = 0$$



$$\oint \vec{B} \cdot d\vec{u} = \mu_0 I_{enc}$$

$$2\pi r \cdot B = \mu_0 \frac{I}{\pi R^2} \cdot \pi r^2$$

$$\boxed{\vec{B} = \frac{\mu_0 I r}{2\pi R^2} \hat{\phi}}$$



$$\nabla \times \vec{B} = \frac{\mu_0 I}{\pi R^2} \hat{z} = \mu_0 \vec{J}$$

$$\vec{J} = \frac{I}{\pi R^2} \hat{z}$$

$$\boxed{\nabla \times \vec{B} = \mu_0 \vec{J}}$$

$$\vec{E} = \frac{Q}{4\pi\epsilon_0 r^2} \hat{r} = \frac{Q \vec{r}}{4\pi\epsilon_0 r^3} = \frac{Q (x\hat{x} + y\hat{y} + z\hat{z})}{4\pi\epsilon_0 (x^2 + y^2 + z^2)^{3/2}}$$

$$\nabla \times \vec{E} = ? \quad (r \neq 0)$$



$$\iiint_{\text{Surface}} (\nabla \times \vec{F}) \cdot d\vec{A} = \oint_{\text{line}} \vec{F} \cdot d\vec{l}$$

STOKES
THEOREM

$$\iiint \nabla \cdot \vec{F} \, dV = \oiint \vec{F} \cdot d\vec{A}$$

GAUSS'S
THEOREM