Laplace Transforms(EMAT102L) (Lecture-18 and 19)



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Learning Outcome of the Lecture

We will learn

- Inverse Laplace Transforms
- Application of Laplace Transforms in DE

Inverse Laplace Transform

If $\mathcal{L}{f(t)} = F(s)$, then f(t) is said to be the **inverse Laplace transform** of F(s). We then write

$$\mathcal{L}^{-1}\{F(s)\} = f(t).$$

$$\mathcal{L}{1} = \frac{1}{s} \Rightarrow \mathcal{L}^{-1} \left\{ \frac{1}{s} \right\} = 1.$$

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$$\mathcal{L}\{t^n\} = \frac{n!}{s^{n+1}} \Rightarrow \mathcal{L}^{-1}\left\{\frac{1}{s^{n+1}}\right\} = \frac{t^n}{n!} \text{ (If n is an integer) }.$$

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Properties of Inverse Laplace Transforms

Linearity

The inverse Laplace transform is linear, i.e.,

$$\mathcal{L}^{-1}\{a_1F_1(s) \pm a_2F_2(s)\} = a_1\mathcal{L}^{-1}\{F_1(s)\} + a_2\mathcal{L}^{-1}\{F_2(s)\}$$

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Theorem

If
$$\mathcal{L}^{-1}{F(s)} = f(t)$$
, then $\mathcal{L}^{-1}{F(s-a)} = e^{at}f(t)$.

Example

Find
$$\mathcal{L}^{-1}\left\{\frac{s-2}{s^2+4s+13}\right\}$$
.

Example

Find
$$\mathcal{L}^{-1}\left\{\frac{s-2}{s^2+4s+13}\right\}$$
.

Solution:

We can write

$$\frac{s-2}{s^2+4s+13} = \frac{s-2}{(s+2)^2+3^2} = \frac{s+2-4}{(s+2)^2+3^2} = \frac{s+2}{(s+2)^2+3^2} - \frac{4}{(s+2)^2+3^2}.$$

$$\mathcal{L}^{-1}\left\{\frac{s-2}{s^2+4s+13}\right\} = e^{-2t}\cos 3t - e^{-2t}\frac{4}{3}\sin 3t = \frac{e^{-2t}}{3}[3\cos 3t - 4\sin 3t].$$

Example

Find
$$\mathcal{L}^{-1}\left\{\frac{s^2}{(s+3)^3}\right\}$$
.

Example

Find
$$\mathcal{L}^{-1}\left\{\frac{s^2}{(s+3)^3}\right\}$$
.

Solution: Using the partial fractions, we have

$$\frac{s^2}{(s+3)^3} = \frac{1}{s+3} - \frac{6}{(s+3)^2} + \frac{9}{(s+3)^3}.$$

Therefore,

$$\mathcal{L}^{-1}\left\{\frac{s^2}{(s+3)^3}\right\} = e^{-3t} - 6te^{-3t} + \frac{9}{2}t^2e^{-3t}.$$

Convolution of Functions

Convolution of Functions

Let f(t) and g(t) be two smooth functions. The convolution f * g is a function defined by

$$(f*g)(t) = \int_0^t f(\tau)g(t-\tau)d\tau.$$

Note: f * g = g * f.

Convolution Theorem

Theorem

If
$$\mathcal{L}{f(t)} = F(s)$$
 and $\mathcal{L}{g(t)} = G(s)$, then

$$\mathcal{L}\{f(t) * g(t)\} = \mathcal{L}\left\{\int_0^t f(\tau)g(t-\tau)d\tau\right\} = \mathcal{L}\{f(t)\}.\mathcal{L}\{g(t)\}.$$
$$\Rightarrow \mathcal{L}\{f(t) * g(t)\} = F(s).G(s).$$

or

$$\Rightarrow \mathcal{L}^{-1}\{F(s).G(s)\} = f(t) * g(t) = \int_0^t f(\tau)g(t-\tau)d\tau.$$

Example based on Convolution Theorem

Example

Find
$$\mathcal{L}^{-1}\left\{\frac{s}{(s^2+1)(s-2)}\right\}$$
.

Example based on Convolution Theorem

Example

Find
$$\mathcal{L}^{-1}\left\{\frac{s}{(s^2+1)(s-2)}\right\}$$
.

Solution: Let
$$F(s) = \frac{1}{s-2}$$
 and $G(s) = \frac{s}{s^2+1}$.
 $\mathcal{L}^{-1}\{F(s)\} = f(t) = e^{2t}$ and $\mathcal{L}^{-1}\{G(s)\} = g(t) = \cos t$.

Using the convolution theorem, we get

$$\mathcal{L}^{-1}\{F(s).G(s)\} = f(t) * g(t)$$

$$\mathcal{L}^{-1}\left\{\frac{s}{(s^2+1)(s-2)}\right\} = e^{2t} * \cos t$$

$$= \int_0^t e^{2\tau} \cos(t-\tau)d\tau$$

$$= \frac{2}{5}e^{2t} + \frac{1}{5}(\sin t - 2\cos t).$$

Application of Laplace transform in solving differential equations

ODEs with constant coefficients

Example (First Order ODE)

Solve the differential equation

$$\frac{dx}{dt} + 3x = 0, x(0) = 1.$$

Application of Laplace transform in solving differential equations

ODEs with constant coefficients

Example (First Order ODE)

Solve the differential equation

$$\frac{dx}{dt} + 3x = 0, x(0) = 1.$$

Solution: By taking Laplace transform on both sides of the equation,

$$\mathcal{L}\left\{\frac{dx}{dt}\right\} + \mathcal{L}\{3x\} = 0$$

$$\Rightarrow s\mathcal{L}\{x\} - x(0) + 3\mathcal{L}\{x\} = 0$$

$$\Rightarrow (s+3)\mathcal{L}\{x\} = 1$$

$$\Rightarrow \mathcal{L}\{x\} = \frac{1}{s+3}$$

Taking inverse Laplace transform on both sides, we get

$$x=e^{-3t}.$$

Applications of Laplace transforms in solving differential equations

Example

Consider the problem

$$y' - 3y = 4e^{5t}, y(0) = 6.$$

Applications of Laplace transforms in solving differential equations

Example

Consider the problem

$$y' - 3y = 4e^{5t}, y(0) = 6.$$

Solution: Given DE is

$$y'-3y=4e^{5t}.$$

Taking Laplace transform on both sides, we get

$$\mathcal{L}\{y'(t)\} - 3\mathcal{L}\{y(t)\} = 4\mathcal{L}\{e^{5t}\}.$$

$$s\mathcal{L}\{y(t)\} - y(0) - 3\mathcal{L}\{y(t)\} = \frac{4}{s-5}.$$

$$\Rightarrow (s-3)\mathcal{L}\{y(t)\} - 6 = \frac{4}{s-5}.$$

$$\Rightarrow \mathcal{L}\{y(t)\} = \frac{6}{s-3} + \frac{4}{(s-3)(s-5)} = \frac{6}{s-3} - \frac{2}{s-3} + \frac{2}{s-5}.$$

$$\Rightarrow \mathcal{L}\{y(t)\} = \frac{4}{s-3} + \frac{2}{s-5}.$$

Taking inverse Laplace transform on both sides, we get

$$y(t) = 4e^{3t} + 2e^{5t}.$$

Application of Laplace transform in solving ODEs

ODEs with constant coefficients

Example (Second Order ODE)

Solve the following differential equation

$$\frac{d^2x}{dt^2} + x = t, x(0) = 1, \frac{dx}{dt}(0) = -2.$$

Application of Laplace transform in solving ODEs

ODEs with constant coefficients

Example (Second Order ODE)

Solve the following differential equation

$$\frac{d^2x}{dt^2} + x = t, x(0) = 1, \frac{dx}{dt}(0) = -2.$$

Solution: By taking Laplace transform on both sides of the equation,

$$\mathcal{L}\left\{\frac{d^{2}x}{dt^{2}}\right\} + \mathcal{L}\{x\} = \mathcal{L}\{t\}$$

$$\Rightarrow s^{2}\mathcal{L}\{x\} - sx(0) - x'(0) + \mathcal{L}\{x\} = \frac{1}{s^{2}}$$

$$\Rightarrow (s^{2} + 1)\mathcal{L}\{x\} = \frac{1}{s^{2}} + s - 2$$

$$\Rightarrow \mathcal{L}\{x\} = \frac{1}{s^{2}(s^{2} + 1)} + \frac{s - 2}{s^{2} + 1} = \frac{1}{s^{2}} + \frac{s}{s^{2} + 1} - \frac{3}{s^{2} + 1}.$$

Taking inverse transform on both sides, we get

$$x(t) = t + \cos t - 3\sin t.$$

Application of Laplace transform in solving System of differential Equations

System of Differential Equations

Example (First Order)

$$\frac{dx}{dt} = 2x - 3y,
 \frac{dy}{dt} = y - 2x,$$

$$x(0) = 8, y(0) = 3$$

Application of Laplace transform in solving System of differential Equations

System of Differential Equations

Example (First Order)

$$\frac{dx}{dt} = 2x - 3y,
 \frac{dy}{dt} = y - 2x,$$

$$x(0) = 8, y(0) = 3$$

Solution: Taking Laplace transform on both sides of the first equation,

$$(s-2)\mathcal{L}{x} + 3\mathcal{L}{y} = 8.$$

Similarly, taking Laplace transform on both sides of the second equation,

$$2\mathcal{L}{x} + (s-1)\mathcal{L}{y} = 3.$$

Solving the above equations, we get

$$\mathcal{L}\{x\} = \frac{5}{s+1} + \frac{3}{s-4}, \mathcal{L}\{y\} = \frac{5}{s+1} - \frac{2}{s-4}.$$

By taking the inverse Laplace transform, we have

$$x(t) = 5e^{-t} + 3e^{4t}, \quad y(t) = 5e^{-t} - 2e^{4t}.$$

Application of Laplace transform in System of Differential Equations

System of Differential Equations

Example 5(Second Order)

$$\frac{d^2x}{dt^2} - x + 5\frac{dy}{dt} = t,
\frac{d^2y}{dt^2} - 4y - 2\frac{dx}{dt} = -2$$

$$x(0) = 0, x'(0) = 0, y(0) = 1, y'(0) = 0$$

Application of Laplace transform in System of Differential Equations

System of Differential Equations

Example 5(Second Order)

$$\frac{d^2x}{dt^2} - x + 5\frac{dy}{dt} = t, \frac{d^2y}{dt^2} - 4y - 2\frac{dx}{dt} = -2$$

$$x(0) = 0, x'(0) = 0, y(0) = 1, y'(0) = 0$$

Solution: Taking Laplace transform on both sides of the first equation,

$$(s^{2} - 1)\mathcal{L}\{x\} + 5s\mathcal{L}\{y\} - 5 = \frac{1}{s^{2}}$$
$$-2s\mathcal{L}\{x\} + (s^{2} - 4)\mathcal{L}\{y\} - s = \frac{-2}{s}$$

Eliminating $\mathcal{L}\{x\}$ from the above equations, we get

$$\mathcal{L}{y} = \frac{1}{s} - \frac{2}{3} \frac{s}{s^2 + 4} + \frac{2}{3} \frac{s}{s^2 + 1}$$

Example(cont.)

Taking inverse Laplace transform on both sides, we get

$$y(t) = 1 - \frac{2}{3}\cos 2t + \frac{2}{3}\cos t$$

Substituting back into the second original equation, we get

$$x(t) = -t - \frac{5}{3}\sin t + \frac{4}{3}\sin 2t.$$

Laplace Transform: General Formulas

Formula	Name, Comments
$F(s) = \mathcal{L}\lbrace f(t)\rbrace = \int_0^\infty e^{-st} f(t) dt$ $f(t) = \mathcal{L}^{-1}\lbrace F(s)\rbrace$	Definition of Transform Inverse Transform
$\mathcal{L}\{af(t) + bg(t)\} = a\mathcal{L}\{f(t)\} + b\mathcal{L}\{g(t)\}$	Linearity
$\mathcal{L}\lbrace e^{at}f(t)\rbrace = F(s-a)$ $\mathcal{L}^{-1}\lbrace F(s-a)\rbrace = e^{at}f(t)$	s-Shifting (First Shifting Theorem)
$\mathcal{L}(f') = s\mathcal{L}(f) - f(0)$ $\mathcal{L}(f'') = s^2\mathcal{L}(f) - sf(0) - f'(0)$ $\mathcal{L}(f^{(n)}) = s^n\mathcal{L}(f) - s^{(n-1)}f(0) - \cdots$ $\cdots - f^{(n-1)}(0)$	Differentiation of Function
$\mathcal{L}\left\{\int_{0}^{t} f(\tau) d\tau\right\} = \frac{1}{s} \mathcal{L}(f)$	Integration of Function

