

Consider the set $\mathbb{C} = \{x+iy : x, y \in \mathbb{R}\}$ of complex numbers.
 $\{z : z \in \mathbb{C}\}$

(a) For $x_1+iy_1, x_2+iy_2 \in \mathbb{C}$ & $\alpha \in \mathbb{R}$, define

$$(x_1+iy_1) \oplus (x_2+iy_2) = (x_1+x_2) + i(y_1+y_2)$$

$$\alpha \odot (x_1+iy_1) = \alpha x_1 + i \alpha y_1$$

Then \mathbb{C} is a real vector space.

(b) For $x_1+iy_1, x_2+iy_2 \in \mathbb{C}$ & $\alpha+i\beta \in \mathbb{C}$, define

$$(x_1+iy_1) \oplus (x_2+iy_2) = (x_1+x_2) + i(y_1+y_2)$$

$$(\alpha+i\beta) \odot (x_1+iy_1) = (\alpha x_1 - \beta y_1) + i(\alpha y_1 + \beta x_1)$$

Then \mathbb{C} forms a complex vector space.

$V = \mathbb{C}^n = \{(z_1, z_2, \dots, z_n) : z_i \in \mathbb{C}, 1 \leq i \leq n\}$.

$$(z_1, z_2, \dots, z_n) \oplus (w_1, w_2, \dots, w_n) = (z_1+w_1, \dots, z_n+w_n)$$

$$\alpha \odot (z_1, z_2, \dots, z_n) = (\alpha z_1, \alpha z_2, \dots, \alpha z_n)$$

(a) If the set IF is the set \mathbb{C} of complex numbers, then \mathbb{C}^n is a complex vector space having n -tuple of complex numbers as its vectors.

(b) If the set IF is the set \mathbb{R} of real numbers, then \mathbb{C}^n is a real vector space having n -tuple of complex numbers as its vectors.

Remark:- In (a), the scalars are complex numbers & hence $i(1,0) = (i,0)$.
 whereas in (b), the scalars are real numbers & hence we cannot write $i(1,0) = (i,0)$.

Subspace

Assume V is a vector space over \mathbb{F} .

Definition \rightarrow Let S be a nonempty subset of V .

S is said to be subspace of V if

$$\alpha u + \beta v \in S \text{ whenever } u, v \in S \text{ \& } \alpha, \beta \in \mathbb{F},$$

where the vector addition & scalar multiplication are same as that of V .

Remark \therefore Any subspace is a vector space in its own right with respect to vector addition and scalar multiplication that is defined for V .

2) a) $S = \{0\}$, then consisting of the zero vector.

b) $S = V$

are vector subspaces of V , are called TRIVIAL SUBSPACE.

Example $\therefore V = \mathbb{R}^3$, $\mathbb{F} = \mathbb{R}$

$$S = \{ (x, y, z) \in \mathbb{R}^3 : \{x = y = z\} \} = \left\{ x(1, 1, 1) \in \mathbb{R}^3 : x \in \mathbb{R} \right\}$$

Then S is a subspace of \mathbb{R}^3 .

Proof \therefore Let $\alpha, \beta \in \mathbb{R}$, $u \in S$. i.e. $u = (x_1, y_1, z_1)$, $v = (x_2, y_2, z_2)$
s.t. $x_1 = y_1 = z_1$
& $x_2 = y_2 = z_2$

$$\alpha u + \beta v = \alpha(x_1, y_1, z_1) + \beta(x_2, y_2, z_2)$$

$$= (\alpha x_1, \alpha y_1, \alpha z_1) + (\beta x_2, \beta y_2, \beta z_2)$$

$$= (\underbrace{\alpha x_1 + \beta x_2}_{\in \mathbb{R}}, \underbrace{\alpha y_1 + \beta y_2}_{\in \mathbb{R}}, \underbrace{\alpha z_1 + \beta z_2}_{\in \mathbb{R}})$$

Thus $\alpha u + \beta v \in S$. $\therefore \alpha x_1 + \beta x_2 = \alpha y_1 + \beta y_2 = \alpha z_1 + \beta z_2$

Hence S is a subspace of \mathbb{R}^3 .

Geometrically, S is a line through the origin and the point $(1, 1, 1)$.

(b) let $S = \{ (x, y, z) \in \mathbb{R}^3 : x + y - 2z = 0 \}$. Then S is a subspace of \mathbb{R}^3 .

Proof: Let $X = (x_1, y_1, z_1) \in S \Rightarrow x_1 + y_1 - 2z_1 = 0$
 $Y = (x_2, y_2, z_2) \in S \Rightarrow x_2 + y_2 - 2z_2 = 0$

Then for $\alpha, \beta \in \mathbb{R}$
 $\alpha X + \beta Y = (\alpha x_1 + \beta x_2, \alpha y_1 + \beta y_2, \alpha z_1 + \beta z_2)$

Consider.

$$\begin{aligned} \alpha x_1 + \beta x_2 + \alpha y_1 + \beta y_2 - 2\alpha z_1 - 2\beta z_2 \\ = \alpha (x_1 + y_1 - 2z_1) + \beta (x_2 + y_2 - 2z_2) \\ = \alpha \cdot 0 + \beta \cdot 0 = 0. \end{aligned}$$

i.e. $\alpha X + \beta Y \in S$.

Hence S is a subspace of \mathbb{R}^3 .

Geometrically, S is a plane passes through the origin.

(c) $S = \{ (x, y, z) \in \mathbb{R}^3 : x + y + z = 1 \}$. Then S is not a subspace of \mathbb{R}^3 .

Solⁿ: $(0, 0, 0) \notin S$ as $0 + 0 + 0 \neq 1$.

Geometrically, S is a plane in \mathbb{R}^3 which does not pass through origin.

The vector space $P_n(\mathbb{R})$ is a subspace of the vector space $P(\mathbb{R})$.

Let $S = \{f \in C([-1, 3]) : f(2) = 0\}$. Then S is subspace of $C([-1, 3])$.

Solⁿ Let $\alpha, \beta \in \mathbb{R}$ & $f, g \in C([-1, 3])$. Then $f(2) = 0$
 $g(2) = 0$

To show:- $\alpha f + \beta g \in S$.
i.e. need to show $\alpha f + \beta g \in C([-1, 3])$ &

$$(\alpha f + \beta g)(2) = 0$$

i.e. $\alpha f(2) + \beta g(2) = 0$.

Now, f is cts, g is cts. $\therefore \alpha f + \beta g$ is cts.

As. $f(2) = 0, g(2) = 0 \Rightarrow \alpha f(2) + \beta g(2) = 0$
 $\Rightarrow (\alpha f + \beta g)(2) = 0$

i.e. $\alpha f + \beta g \in C([-1, 3])$

Hence S is a subspace of $C([-1, 3])$

$S = \{A \in M_{n \times n}(\mathbb{R}) : \text{trace } A = 0\}$. Then S is a subspace of $M_{n \times n}(\mathbb{R})$.

Solⁿ Verify! (Hint - $\text{trace}(\alpha A + \beta B) = \alpha \text{trace}(A) + \beta \text{trace}(B) = \alpha \cdot 0 + \beta \cdot 0 = 0$)

$S = \{X \in \mathbb{R}^{n \times 1} : AX = 0, A \in M_{m \times n}\}$ is a subspace of $\mathbb{R}^{n \times 1}$.

$X \in \mathbb{R}^{n \times 1}$ i.e. $X = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}$.

The following are the examples of subspaces of $M_{n \times n}(\mathbb{R})$.

1) Set of all upper triangular matrices

2) Set of all lower triangular matrices

3) Set of all diagonal matrices

4) Set of all symmetric matrices

5) Set of all skew-symmetric matrices.

Solⁿ: TRY YOURSELF!

2) Which of the following are subspace of $\mathbb{R}^n(\mathbb{R})$?

(a) $U = \{ (x_1, x_2, \dots, x_n) : x_1 \geq 0 \}$

(No, $\because \alpha = -1$, Then in U ,
 $(\alpha x_1, \dots, \alpha x_n)$, $-x_1 \leq 0$)

(b) $\{ (x_1, x_2, \dots, x_n) : x_1 + 3x_2 = 4x_4 \}$ (YES)

(c) $\{ (x_1, x_2, \dots, x_n) : x_2 \text{ is irrational} \}$ (No, scalar multiplication does not hold)

(d) $\{ (x_1, x_2, \dots, x_n) : x_1 = x_4^2 \}$ (No, not closed under addition.)

(f) $\{ (x_1, x_2, \dots, x_n) : |x_1| \leq 1 \}$ (No, scalar multiplication as well as addition don't hold).

LINEAR COMBINATION

Let V be a vector space over IF (field).

A vector $v \in V$ is a linear combination of vectors u_1, u_2, \dots, u_m in V if there exist scalars $a_1, a_2, \dots, a_m \in IF$ such that

$$v = a_1 u_1 + a_2 u_2 + \dots + a_m u_m.$$

Alternatively, v is a linear combination of u_1, u_2, \dots, u_m if there is a solution to the vector eqⁿ

$$v = x_1 u_1 + x_2 u_2 + \dots + x_m u_m,$$

where x_1, x_2, \dots, x_m are unknown scalars.

Example:- (Linear combination in \mathbb{R}^n)

Write $v = (3, 7, -4) \in \mathbb{R}^3$ as a linear combination of vectors $u_1 = (1, 2, 3)$, $u_2 = (2, 3, 7)$, $u_3 = (3, 5, 6)$

i.e. we find the scalars x_1, x_2, x_3 s.t. $v = x_1 u_1 + x_2 u_2 + x_3 u_3$

$$\begin{bmatrix} 3 \\ 7 \\ -4 \end{bmatrix} = x_1 \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} + x_2 \begin{bmatrix} 2 \\ 3 \\ 7 \end{bmatrix} + x_3 \begin{bmatrix} 3 \\ 5 \\ 6 \end{bmatrix}$$

(For notational convenience, we have written the vector in \mathbb{R}^3 as columns, since it is easier to find the equivalent system of equations.)

$$x_1 + 2x_2 + 3x_3 = 3$$

$$2x_1 + 3x_2 + 5x_3 = 7$$

$$3x_1 + 7x_2 + 6x_3 = -4$$

Consider the Augmented matrix,

$$[A|b] = \left[\begin{array}{ccc|c} 1 & 2 & 3 & 3 \\ 2 & 3 & 5 & 7 \\ 3 & 7 & 6 & -4 \end{array} \right]$$

$$\begin{array}{l} R_2 \rightarrow R_2 - 2R_1 \\ R_3 \rightarrow R_3 - 3R_1 \end{array} \sim \left[\begin{array}{ccc|c} 1 & 2 & 3 & 3 \\ 0 & -1 & -1 & 1 \\ 0 & 1 & -3 & -13 \end{array} \right]$$

$$R_3 \rightarrow R_3 + R_2 \sim \left[\begin{array}{ccc|c} 1 & 2 & 3 & 3 \\ 0 & -1 & -1 & 1 \\ 0 & 0 & -4 & -12 \end{array} \right]$$

By back substitution, $-4z = -12 \Rightarrow z = 3$

$$-y - z = -12 \Rightarrow y = -4$$

$$x + 2y + 3z = 3 \Rightarrow x = 2$$

$$\left(\begin{array}{l} \text{Notation} \\ x_1 = x \\ x_2 = y \\ x_3 = z \end{array} \right)$$

Thus

$$\boxed{v = 2u_1 - 4u_2 + 3u_3}$$

Generally speaking:

Given a vector " \underline{v} " in $V = \mathbb{R}^n$ or \mathbb{C}^n as a linear combination of vectors u_1, u_2, \dots, u_m in V is equivalent to solving the system $AX = B$ of linear equations, where, v is the column B of constants and the u 's are the columns of the coefficient matrix A .

Such a system may have a unique solution, many solutions, or no solution.

In the last case - no solution - means that v can not be written as a linear combination of the u 's.

Example:- Express the polynomial $v = 3t^2 + 5t - 5$ as a linear combination of the polynomials

$$p_1 = t^2 + 2t + 1, \quad p_2 = 2t^2 + 5t + 4, \quad p_3 = t^2 + 3t + 6.$$

Solution:- $v = \alpha_1 p_1 + \alpha_2 p_2 + \alpha_3 p_3$

Method 1:- $3t^2 + 5t - 5 = \alpha_1(t^2 + 2t + 1) + \alpha_2(2t^2 + 5t + 4) + \alpha_3(t^2 + 3t + 6)$

$$\Rightarrow 3t^2 + 5t - 5 = (\alpha_1 + 2\alpha_2 + \alpha_3)t^2 + (2\alpha_1 + 5\alpha_2 + 3\alpha_3)t + (\alpha_1 + 4\alpha_2 + 6\alpha_3)$$

Comparing the like power of t , we obtain

$$\begin{aligned}\alpha_1 + 2\alpha_2 + \alpha_3 &= 3 \\ 2\alpha_1 + 5\alpha_2 + 3\alpha_3 &= 5 \\ \alpha_1 + 4\alpha_2 + 6\alpha_3 &= -5\end{aligned}$$

Solve the system of eqⁿ:-
$$\begin{bmatrix} 1 & 2 & 1 & 3 \\ 2 & 5 & 3 & 5 \\ 1 & 4 & 6 & -5 \end{bmatrix}$$

$$\begin{aligned}R_2 &\rightarrow R_2 - 2R_1 \\ R_3 &\rightarrow R_3 - R_1\end{aligned} \sim \begin{bmatrix} 1 & 2 & 1 & 3 \\ 0 & 1 & 1 & -1 \\ 0 & 2 & 5 & -8 \end{bmatrix}$$

$$R_3 \rightarrow R_3 - 2R_2 \sim \begin{bmatrix} 1 & 2 & 1 & 3 \\ 0 & 1 & 1 & -1 \\ 0 & 0 & 3 & -6 \end{bmatrix}$$

$$3\alpha_3 = -6 \Rightarrow \alpha_3 = -2$$

$$\alpha_2 + \alpha_3 = -1 \Rightarrow \alpha_2 = 1$$

$$\alpha_1 + 2\alpha_2 + \alpha_3 = 3 \Rightarrow \alpha_1 = -2$$

Thus, $v = 3p_1 + p_2 - 2p_3$

Method 2:-

$$v = \alpha_1 p_1 + \alpha_2 p_2 + \alpha_3 p_3$$

$$\text{i.e. } v = \alpha_1 p_1(t) + \alpha_2 p_2(t) + \alpha_3 p_3(t) \quad \forall t \in \mathbb{R}. \quad \text{--- (1)}$$

$$3t^2 + 5t - 5 = \alpha_1 (t^2 + 2t + 1) + \alpha_2 (2t^2 + 5t + 4) + \alpha_3 (t^3 + 3t + 6)$$

We can obtain three equations in the unknowns α_1, α_2 and α_3 by setting t equal to any three values.

$$\text{For example :- } t=0, \text{ in (1), we obtain } \alpha_1 + 4\alpha_2 + 6\alpha_3 = -5$$

$$4\alpha_1 + 11\alpha_2 + 10\alpha_3 = 3$$

$$t=1, \quad " \quad ,$$

$$\alpha_2 + 4\alpha_3 = -7.$$

$$t=-1, \quad "$$

Reducing this system to echelon form, solving by back substitution, we obtain

$$x = 3, y = 1, z = -2.$$

Definition:- Let V be a vector space over \mathbb{F} and let $S = \{u_1, u_2, \dots, u_n\}$ be a non-empty subset of V .

The linear span of S is defined as

$$L(S) = \left\{ \alpha_1 u_1 + \alpha_2 u_2 + \dots + \alpha_n u_n : \alpha_i \in \mathbb{F}, 1 \leq i \leq n \right\}.$$

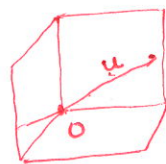
Remark:- 1) If $S = \{\phi\}$. Then $L(S) = \{0\}$.

(ii) $L(S)$ or $\text{span}(S)$ is a subspace of V that contains S .

(ii) If W is a subspace of V containing S , then $\text{span}(S) \subseteq W$.

i.e. $L(S)$ is the "smallest" subspace of V containing S .

Ex:- Let $u \neq 0 \in \mathbb{R}^3$. Then find $\text{span}(u)$.



$$L(u) = \{ \alpha u : \alpha \in \mathbb{R} \}.$$

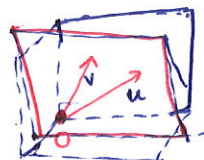
i.e. set consisting of all scalar multiple of u .

Geometrically, $\text{span}(u)$ is the line through the origin O and the end pts of u .

(2) Let u & v be vectors in \mathbb{R}^3 that are not multiple of each other.
 $S = \{u, v\}$

$$\text{Then } \text{span}(S) = \{ \alpha_1 u + \alpha_2 v : \alpha_1, \alpha_2 \in \mathbb{R} \}$$

= "plane through the origin O and the endpoints of u & v ."



Spanning Sets:

Let V be a vector space over K .

Vectors $u_1, u_2, \dots, u_m \in V$ are said to "span V " or to form a spanning set of V if every $v \in V$ is a linear combination of the vectors u_1, u_2, \dots, u_m .

i.e. \exists scalars a_1, a_2, \dots, a_m in K such that

$$v = a_1 u_1 + a_2 u_2 + \dots + a_m u_m.$$

Remark: 1) Suppose u_1, u_2, \dots, u_m span V . Then, for any vector w , the set w, u_1, u_2, \dots, u_m also span V .

2) Suppose u_1, u_2, \dots, u_m span V and suppose u_k is a linear combination of some of the other u 's. Then the u 's with u_k also span V .

3) Suppose u_1, u_2, \dots, u_m span V and suppose one of the u 's is the zero vector. Then the u 's without the zero vector also span V .

Example:- (1) $V = \mathbb{R}^3$.

(a) $e_1 = (1, 0, 0)$, $e_2 = (0, 1, 0)$, $e_3 = (0, 0, 1)$ span \mathbb{R}^3 .

or e_1, e_2, e_3 form a spanning set of \mathbb{R}^3 .

Solⁿ: let $(a, b, c) \in \mathbb{R}^3$ Then

$$(a, b, c) = a(1, 0, 0) + b(0, 1, 0) + c(0, 0, 1).$$

$$\text{i.e. } (a, b, c) = a e_1 + b e_2 + c e_3.$$

(b) $w_1 = (1, 1, 1)$, $w_2 = (1, 1, 0)$, $w_3 = (1, 0, 0)$ span \mathbb{R}^3 .

Solⁿ: $v \in \mathbb{R}^3$,

$$v = (a, b, c) = c w_1 + (b - c) w_2 + (a - b) w_3.$$

As,

$$\begin{bmatrix} a \\ b \\ c \end{bmatrix} = x \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} + y \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} + z \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$

$$z = c, \quad x + y = b \Rightarrow y = b - x = b - c$$

$$x + y + z = a \Rightarrow z = a - x - y = a - b.$$

(c) One can check that $v = (2, 7, 8)$ can^{not} be written as a linear combination of vectors

$$u_1 = (1, 2, 3), \quad u_2 = (1, 3, 5), \quad u_3 = (1, 5, 9)$$

i.e. u_1, u_2, u_3 do not span \mathbb{R}^3 .

Ex:- $V = P_n(t)$ consisting of all polynomials of degree $\leq n$.

(a) clearly every polynomial in $P_n(t) = a_0 + a_1 t + \dots + a_n t^n$ can be expressed as a linear combination of the $(n+1)$ polynomials $1, t, t^2, \dots, t^n$.

(b) Show that for any scalar c , the following $(n+1)$ powers of $t-c$,
 $1 = (t-c)^0, (t-c), (t-c)^2, \dots, (t-c)^n$.

also form a spanning set for $P_n(t)$.

(c) Consider the vector space $M = M_{2 \times 2}$ - consisting of all 2×2 matrices.

Then

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix} = a \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} + b \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} + c \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix} + d \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}.$$

i.e. any element of $M_{2 \times 2}$ can be written as a linear combination of

$$\begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}.$$