

①

$$A = \begin{bmatrix} 4 & 1 & -1 \\ 2 & 5 & -2 \\ 1 & 1 & 2 \end{bmatrix}.$$

Sol: Characteristic polynomial = $\det(A - \lambda I)$

$$\det(A - \lambda I) = \begin{vmatrix} 4-\lambda & 1 & -1 \\ 2 & 5-\lambda & -2 \\ 1 & 1 & 2-\lambda \end{vmatrix}$$

$$\text{Char. Poly.} = \lambda^3 - 11\lambda^2 + 39\lambda - 45$$

$$\text{Ch. equation} \rightarrow \lambda^3 - 11\lambda^2 + 39\lambda - 45 = 0$$

Eigenvalues — Roots of ch. equation.

$$\text{Now, } \lambda^3 - 11\lambda^2 + 39\lambda - 45 = 0$$

$$\Rightarrow (\lambda-3)(\lambda^2 - 8\lambda + 15) = 0$$

$$\Rightarrow (\lambda-3)(\lambda-5)(\lambda-3) = 0$$

$$\Rightarrow \lambda = 3, 3, 5.$$

Algebraic multiplicity of $\lambda=3 = 2$.

Algebraic multiplicity of $\lambda=5 = 1$.

E_λ = Eigen vector corresponding to $\lambda = 3 = \{x : (A - \lambda I)x = 0\}$

$$E_3 = \left\{ x = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} : (A - 3I)x = 0 \right\}$$

$$A - 3I = \begin{bmatrix} 1 & 1 & -1 \\ 2 & 2 & -2 \\ 1 & 1 & -1 \end{bmatrix}, \quad \text{R.EF of } (A - 3I) = \begin{bmatrix} 1 & 1 & -1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$(A - 3I)x \Rightarrow x + y - z = 0.$$

Here y, z are free variable. $y = t, z = s$

$$x = -y + z = -t + s$$

$$\therefore x = \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} -t+s \\ t \\ s \end{bmatrix} = t \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix} + s \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$$

$$G.M = \dim(E_3) = 2., \text{ As.}$$

$$\begin{aligned} E_3 &= \left\{ t \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix} + s \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} : t, s \in \mathbb{R} \right\} \\ &= \text{span} \left\{ \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} \right\}. \end{aligned}$$

G.M of $\lambda = 3 = 2 = A \cdot M$ of eigenvalue 3.

$$E_5 = \left\{ x = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} : (A - 5I)x = 0 \right\}$$

$$A - 5I = \begin{bmatrix} -1 & 1 & -1 \\ 2 & 0 & -2 \\ 1 & 1 & -3 \end{bmatrix}$$

R.EF of $(A - 5I) \div 2$

$$R_2 \rightarrow R_2 + 2R_1$$

$$R_3 \rightarrow R_3 + R_1$$

$$\begin{bmatrix} -1 & 1 & -1 \\ 0 & 2 & -4 \\ 0 & 2 & -4 \end{bmatrix}$$

$$R_3 \rightarrow R_3 - R_2$$

$$\begin{bmatrix} -1 & 1 & -1 \\ 0 & 2 & -4 \\ 0 & 0 & 0 \end{bmatrix}$$

Here z is free variable. $z = t$, $t \in \mathbb{R}$.

$$\text{From } (A - 5I)x = 0 \Rightarrow -x + y - z = 0 \\ y - 2z = 0 \Rightarrow y = 2z = 2t$$

$$x = z = t$$

$$x = \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} t \\ 2t \\ t \end{bmatrix} = t \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}$$

$$\text{Thus, } E_5 = \left\{ t \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}, t \in \mathbb{R} \right\} = \text{span} \left\{ \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix} \right\}$$

$$\dim E_5 = 1.$$

G.M of $E_5 = 1$ = A.M of eigenvalue 5.

Thus A is diagonalizable.

$$P = \begin{bmatrix} -1 & 1 & 1 \\ 1 & 0 & 2 \\ 0 & 1 & 1 \end{bmatrix}$$

$$\& D = P^T A P = \begin{bmatrix} 3 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 5 \end{bmatrix} .$$

$$\begin{aligned} f(A) &= P f(D) P^{-1} \\ &= P \begin{bmatrix} f(3) & 0 & 0 \\ 0 & f(3) & 0 \\ 0 & 0 & f(5) \end{bmatrix} P^{-1} . \end{aligned}$$

Example :-

(i)

$$A = \begin{bmatrix} 1 & 0 & 1 \\ -1 & 1 & 3 \\ -1 & 0 & 3 \end{bmatrix}$$

Solⁿ: First, we have $tI - A = \begin{bmatrix} t-1 & 0 & 1 \\ -1 & t-1 & 3 \\ -1 & 0 & t-3 \end{bmatrix}$

So,

$$\text{ch. poly } p(t) = \det(tI - A)$$

$$= (t-1) \begin{vmatrix} t-1 & 3 \\ 0 & t-3 \end{vmatrix} + (-1) \begin{vmatrix} 1 & t-1 \\ 1 & 0 \end{vmatrix}$$

$$= (t-1)^2(t-3) + (t-1)$$

$$= (t-1) [(t-1)(t-3) + 1]$$

$$= (t-1)(t-2)^2$$

Thus, the eigenvalues are 1, 2, 2.

* For $\lambda=1$, we want to find the null space of $(A-I)$.

i.e $A-I = \begin{bmatrix} 0 & 0 & -1 \\ 1 & 0 & -3 \\ 1 & 0 & -3 \end{bmatrix}$

Find x s.t $(A-I)x = 0$, $x = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$

Row echelon of $A-I = \begin{bmatrix} 1 & 0 & -3 \\ 0 & 0 & -1 \\ 0 & 0 & 0 \end{bmatrix}$

Free variable is x_2 . $(A-I)x = 0 \Rightarrow x_1 = 0, x_3 = 0, x_2 = t$

Thus, solⁿ is $\begin{bmatrix} 0 \\ t \\ 0 \end{bmatrix} = t \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$

(2)

Example :-

$$(i) \quad A = \begin{bmatrix} 1 & 0 & 1 \\ -1 & 1 & 3 \\ -1 & 0 & 3 \end{bmatrix}.$$

Solⁿ: First, we have $tI - A = \begin{bmatrix} t-1 & 0 & 1 \\ -1 & t-1 & 3 \\ -1 & 0 & t-3 \end{bmatrix}$

So,

$$\begin{aligned} \text{ch. poly } p(t) &= \det(tI - A) \\ &= (t-1) \begin{vmatrix} t-1 & 3 \\ 0 & t-3 \end{vmatrix} + (-1) \begin{vmatrix} 1 & t-1 \\ 1 & 0 \end{vmatrix} \\ &= (t-1)^2(t-3) + (t-1) \\ &= (t-1)[(t-1)(t-3)+1] \\ &= (t-1)(t-2)^2 \end{aligned}$$

Thus, the eigenvalues are 1, 2, 2.

For $\lambda=1$, we want to find the null space of $(A-I)$.

i.e $A-I = \begin{bmatrix} 0 & 0 & -1 \\ 1 & 0 & -3 \\ 1 & 0 & -3 \end{bmatrix}$.

Find x s.t $(A-I)x = 0$, $x = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$

Row echelon of $A-I = \begin{bmatrix} 1 & 0 & -3 \\ 0 & 0 & -1 \\ 0 & 0 & 0 \end{bmatrix}$

Free variable is x_2 . $(A-I)x = 0 \Rightarrow x_1 = 0, x_3 = 0, x_2 = t$

Thus, solⁿ is $\begin{bmatrix} 0 \\ t \\ 0 \end{bmatrix} = t \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$

Thus, eigenspace corresponding to eigenvalue 1

$$U = \left\{ \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} : \alpha \in \mathbb{R} \right\}$$

$$\dim E_1 = 1.$$

For $\lambda=2$, we want to find the eigenspace.

i.e. Find nullspace of $A - 2I$. $= \{x : (A - 2I)x = 0\}$,

$$x = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

$$A - 2I = \begin{bmatrix} 1 & 0 & -1 \\ 1 & 1 & -3 \\ 1 & 0 & -1 \end{bmatrix}$$

Row echelon form, $R_2 \rightarrow R_2 - R_1$
 $R_3 \rightarrow R_3 - R_1$

$$\sim \begin{bmatrix} 1 & 0 & -1 \\ 0 & 1 & -2 \\ 0 & 0 & 0 \end{bmatrix}$$

free variable is x_3 . Take $x_3 = t$. Then $(A - 2I)x = 0$

$$\Rightarrow x_2 - 2x_3 = 0 \Rightarrow x_2 = 2x_3 = 2t$$

$$x_1 - x_3 = 0 \Rightarrow x_1 = x_3 = t$$

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} t \\ 2t \\ t \end{bmatrix} = t \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}$$

Thus, 2-eigenspace is 1-dimensional & spanned by $\begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}$.

Algebraic Multiplicity — corresponding to "1" is 1.
"2" is 2.

Geometric Multiplicity corresponding to "1" is 1.
"2" is 1.

Since Algebraic Multiplicity \neq Geometric Multiplicity.

Therefore, A is not diagonalizable. So, we can not find P .

(ii) Calculate A^{-1} .

As we know by Cayley Hamilton Theorem, Every square matrix satisfy its characteristic eqn.

$$\therefore (A - I)(A - 2I)^2 = 0$$

$$\Rightarrow (A - I)(A^2 + 4I - 4A) = 0$$

$$\Rightarrow A^3 + 4A - 4A^2 - A^2 - 4I + 4A = 0$$

$$\Rightarrow A^3 - 5A^2 + 8A - 4I = 0$$

Multiplying by A^{-1} , we obtain

$$A^2 - 5A + 8I - 4A^{-1} = 0$$

$$\Rightarrow A^{-1} = \frac{1}{4} [A^2 - 5A + 8I]. \underline{\text{Ans}}$$

Example
② (ii)

$$A = \begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & -1 \\ 0 & 1 & 0 \end{bmatrix}$$

Solⁿ: $tI - A = \begin{bmatrix} t & 0 & 0 \\ -1 & t & 1 \\ 0 & -1 & t \end{bmatrix}$.

So, characteristic polynomial $p(t) = \det(tI - A)$
 $= t \begin{vmatrix} t & 1 \\ -1 & t \end{vmatrix} = t(t^2 + 1)$

So, ch. eq^w is $t(t^2 + 1) = 0$

Roots of ch. eq^w (eigenvalues) = $0, \pm i$.

Eigen vector corresponding to eigenvalue $\lambda = 0$.
ie we want to find null space of $(\lambda I - A) = -A$.

$$-A = \begin{bmatrix} 0 & 0 & 0 \\ -1 & 0 & 1 \\ 0 & -1 & 0 \end{bmatrix}$$

Row echelon form of $A \rightarrow R_1 \leftrightarrow R_2 \begin{bmatrix} -1 & 0 & 1 \\ 0 & 0 & 0 \\ 0 & -1 & 0 \end{bmatrix}$

$$R_3 \leftrightarrow R_2 \begin{bmatrix} -1 & 0 & 1 \\ 0 & -1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$\begin{array}{l} R_1 \rightarrow -R_1 \\ R_2 \rightarrow -R_2 \end{array} \quad \begin{bmatrix} 1 & 0 & -1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$x = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}, \quad x_3 = \text{free variable}$$

$$x_2 = 0$$

$$x_1 - x_3 = 0 \Rightarrow x_1 = x_3$$

$$x = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} x_1 \\ 0 \\ x_3 \end{bmatrix} = x_1 \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}.$$

So, the 0-eigenspace is 1-dimensional & spanned by $\begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$.

For $\lambda = i$, we want to find the nullspace of $(iI - A)$.

$$iI - A = \begin{bmatrix} i & 0 & 0 \\ -1 & i & 1 \\ 0 & -1 & i \end{bmatrix}$$

Row echelon form of $iI - A$, $R_2 \leftrightarrow R_1$

$$\begin{bmatrix} -1 & i & 1 \\ i & 0 & 0 \\ 0 & -1 & i \end{bmatrix}$$

$$R_1 \rightarrow -R_1 \quad \begin{bmatrix} 1 & -i & -1 \\ i & 0 & 0 \\ 0 & -1 & i \end{bmatrix}$$

$$R_2 \rightarrow R_2 - iR_1 \quad \begin{bmatrix} 1 & -i & -1 \\ 0 & -1 & i \\ 0 & -1 & i \end{bmatrix}$$

$$R_3 \rightarrow R_3 - R_1 \quad \begin{bmatrix} 1 & i & -1 \\ 0 & -1 & i \\ 0 & 0 & 0 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 & i & -1 \\ 0 & -1 & i \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

$$\text{Thus, } x_3 = 0, \quad -x_2 + ix_3 = 0 \Rightarrow x_2 = +i x_3$$

$$\begin{aligned} x_1 + ix_2 + x_3 &= 0 \\ x_1 - ix_2 + x_3 &= 0 \end{aligned}$$

Then

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ it \\ t \end{bmatrix} = t \begin{bmatrix} 0 \\ i \\ 1 \end{bmatrix}$$

Hence $E_i = \text{Eigenspace corresponding to } i = \left\{ t \begin{bmatrix} 0 \\ i \\ 1 \end{bmatrix} : t \in \mathbb{R} \right\}$

#.

$$\boxed{\dim E_i = 1}$$

For $\lambda = -i$, we want to find x s.t. $(A + iI)x = 0$.

$$A + iI = \begin{bmatrix} -i & 0 & 0 \\ -1 & -i & 1 \\ 0 & -1 & -i \end{bmatrix}$$

Row echelon form of $A + iI$ $= \begin{bmatrix} -1 & -i & 1 \\ -i & 0 & 0 \\ 0 & -1 & -i \end{bmatrix}$

$$R_2 \rightarrow iR_2 + R_1 \quad \begin{bmatrix} -1 & -i & 1 \\ 0 & -i & 1 \\ 0 & -1 & -i \end{bmatrix}$$

$$R_3 \rightarrow R_3 + iR_2 \quad \begin{bmatrix} -1 & -i & 1 \\ 0 & -i & 1 \\ 0 & 0 & 0 \end{bmatrix}$$

x_3 = free variable . $x_3 = t$

Then

$$\begin{bmatrix} -1 & -i & 1 \\ 0 & -i & 1 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\Rightarrow -x_1 - ix_2 + x_3 = 0, \quad -ix_2 + x_3 = 0$$

$$\Rightarrow x_1 = 0$$

Thus, eigenvector

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = t \begin{bmatrix} 0 \\ -i \\ 1 \end{bmatrix}.$$

$$\dim(E_{-i}) = 1.$$

Since $A \cdot M = G \cdot M = 1$, for every eigenvalue.

Hence, A is diagonalizable

$$(b) \text{ By Cayley Hamilton Thm, } A(A^2 + I) = 0 \quad (\because \text{ch. eq } t(t^2 + 1) = 0)$$

$$\Rightarrow A^3 + A = 0$$

Since 0 is an eigenvalue of A . Therefore $\det A = 0 \Rightarrow A$ is not invertible. & hence, we can not find the inverse.

$$P = \begin{bmatrix} 1 & 0 & 0 \\ 0 & i & -i \\ 1 & 1 & 1 \end{bmatrix} \quad . \quad \text{One can easily verify that}$$

$$P^{-1} A P = \begin{bmatrix} 0 & 0 & 0 \\ 0 & i & 0 \\ 0 & 0 & -i \end{bmatrix} = D.$$

$$\# f(A) = P f(D) P^{-1}.$$

$$= P \begin{bmatrix} f(\lambda_1) & 0 & 0 \\ 0 & f(\lambda_2) & 0 \\ 0 & 0 & f(\lambda_3) \end{bmatrix} P^{-1}$$

(iii)

$$A = \begin{pmatrix} 1 & -1 & 0 \\ 0 & 2 & 0 \\ 0 & 2 & 1 \end{pmatrix}$$

$\det(1I - A) = (1-1)^2 (1-2)$

So, eigenvalues are $\lambda=1, 1, 2$.

$$E_1 = \left\{ x : (A - I)x = 0 \right\}.$$

$$= \left\{ x = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} : \begin{pmatrix} 0 & -1 & 0 \\ 0 & 1 & 0 \\ 0 & 2 & 0 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \right\}$$

$$= \left\{ \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} : x_1 \text{ & } x_3 \text{ are free variable, } x_2 = 0 \right\}$$

$$= \begin{bmatrix} x_1 \\ 0 \\ x_3 \end{bmatrix}$$

$$= x_1 \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

$$= \text{span} \left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \right\}$$

$$\dim E_1 = 2.$$

$$E_2 = \left\{ x : (A - 2I)x = 0 \right\} = \left\{ x = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} : \begin{bmatrix} -1 & -1 & 0 \\ 0 & 0 & 0 \\ 0 & 2 & -1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \right\}$$

$$= \left\{ \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} : \begin{array}{l} x_1 = -x_2 \\ 2x_2 = x_3 \\ x_3 = \text{free variable} = t \end{array} \Rightarrow \begin{array}{l} x_1 = -t \\ x_2 = t \\ x_3 = t \end{array} \right\}$$

$$= \left\{ t \begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix} : t \in \mathbb{R} \right\}$$

dim $E_2 = 1$.

$$P = \begin{bmatrix} \lambda=1 & \lambda=1 & \lambda=2 \\ 1 & 0 & -y_2 \\ 0 & 0 & y_2 \\ 0 & 1 & 1 \end{bmatrix}, \quad P^{-1} = \begin{bmatrix} 1 & 1 & 0 \\ 0 & -2 & 1 \\ 0 & 1 & 0 \end{bmatrix}$$

$$P^{-1} A P = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \end{bmatrix} = D.$$

$A \cdot M$ corresponding to eigenvalue $\lambda = 2$ $\Rightarrow A \cdot M = G \cdot M$
 $G \cdot M$ $= 2$.

$A \cdot M$ corresponding to eigenvalue $\lambda = 1$ $\Rightarrow A \cdot M = G \cdot M$
 $G \cdot M$ " " $\lambda = 1$.

P is diagonalizable.

Calculate A^{-1} , $(\lambda-1)^2(\lambda-2) = 0 \Rightarrow (\lambda^2+1-2\lambda)(\lambda-2) = 0$
 $\Rightarrow \lambda^3 + \lambda - 2\lambda^2 - 2\lambda^2 - 2 + 4\lambda = 0$
 $\Rightarrow (\lambda-1)^2(\lambda-2) = 0 \Rightarrow \lambda^3 - 4\lambda^2 + 5\lambda - 2 = 0$
 $\Rightarrow \lambda^3 - 4\lambda^2 + 5\lambda - 2 = 0$
 $\Rightarrow A^{-1} = \frac{1}{2}[A^2 - 4A + 5I] \quad (\text{by multiplying } P^{-1})$,

$$A = \begin{pmatrix} 1 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix}.$$

Characteristic polynomial for $A = (x-1)^3$

eigenvalues of A are $\lambda = 1, 1, 1$

$A \cdot M$ corresponding to $\lambda = 1$ is 3.

Eigenspace corresponding to $\lambda = 1 = E_1 = \left\{ X = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} : (A - I)X = 0 \right\}$

$$= \left\{ X = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} : \begin{pmatrix} 0 & 1 & 1 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \right\}$$

$$= \left\{ \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} : \begin{array}{l} x_3 = 0 \\ x_2 = 0 \\ x_1 = t \text{ (free variable)} \end{array} \right\}$$

$$= \left\{ t \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} : t \in \mathbb{R} \right\}.$$

$$\dim E_1 = 1$$

$G \cdot M$ corresponding to $\lambda = 1 = 1$

$$A \cdot M \neq G \cdot M$$

$\Rightarrow A$ is not diagonalizable so we cannot find P .

By Cayley Hamilton thm, $(A - I)^3 = 0$

$$\Rightarrow A^3 - I - 3A^2 + 3A = 0$$

Multiplying by A^{-1} , we obtain,

$$A^2 - A^{-1} - 3A + 3I = 0$$

$$\Rightarrow A^{-1} = A^2 - 3A + 3I.$$

$f(t) = t^3 - 5t - 4$

$$f(A) = A^3 - 5A - 4I. \quad (\text{we know that})$$

$$A^3 - I - 3A^2 + 3A = 0$$

$$\boxed{A^3 = 3A^2 - 3A + I}$$

Thus $f(A) = 3A^2 - 8A - 3I.$

$$= 3 \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix} - 8 \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix} - 3 \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$= 3 \begin{bmatrix} 1 & 2 & 3 \\ 0 & 1 & 2 \\ 0 & 0 & 1 \end{bmatrix} - \begin{bmatrix} 8 & 8 & 8 \\ 0 & 8 & 8 \\ 0 & 0 & 8 \end{bmatrix} - \begin{bmatrix} 3 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 3 \end{bmatrix}$$

$$= \begin{bmatrix} 3 & 6 & 9 \\ 0 & 3 & 6 \\ 0 & 0 & 3 \end{bmatrix} - \begin{bmatrix} 11 & 8 & 8 \\ 0 & 11 & 8 \\ 0 & 0 & 11 \end{bmatrix}$$

$$= \begin{bmatrix} -8 & -2 & 1 \\ 0 & -8 & -2 \\ 0 & 0 & -8 \end{bmatrix}$$

3) All the eigenvalues of $n \times n$ Hermitian / symmetric matrix A are real.

Solution: Let λ be an eigenvalue of Hermitian matrix corresponding to eigenvector x .

$$\text{i.e. } Ax = \lambda x \quad \& \quad A = A^*$$

$$\text{Then } x^* A = x^* A^* = (Ax)^* = (\lambda x)^* = \bar{\lambda} x^*.$$

$$\text{Hence, } \lambda x^* x = x^*(\lambda x) = x^*(Ax) = (\bar{\lambda} x^*) x = \bar{\lambda} x^* x$$

$$\Rightarrow (\lambda - \bar{\lambda}) x^* x = 0.$$

But x is an eigenvector & hence $x \neq 0$ and so that the real no. $\|x\|^2 = x^* x$ is non zero as well.

$$\text{Thus, } \lambda = \bar{\lambda}$$

i.e. λ is real no.

In case of symmetric matrix. Just replace x^* with x^t .

OR * with t (transpose).

Proof follows similar as above.

Detail: $Ax = \lambda x \quad \& \quad A = A^t$

$$\begin{aligned} \bar{A}\bar{x} &= \bar{\lambda}\bar{x} \quad (\text{Taking conjugate}) \\ \Rightarrow \bar{A}\bar{x} &= \bar{\lambda}\bar{x} \\ \Rightarrow A\bar{x} &= \bar{\lambda}\bar{x} \quad (\because A \text{ is sym. with real entries}) \\ \text{Taking transpose both sides,} \\ \bar{x}^t A^t &= \bar{\lambda}\bar{x}^t \\ \text{Post multiplying by } x, \text{ & } A^t = A \\ \bar{x}^t A x &= \bar{\lambda}\bar{x}^t x \\ \Rightarrow \bar{x}^t \lambda x &= \bar{\lambda}\bar{x}^t x \quad (\because Ax = \lambda x) \\ \Rightarrow (\lambda - \bar{\lambda}) \bar{x}^t x &= 0 \Rightarrow \bar{\lambda} = \lambda \end{aligned}$$

- 4) The 3×3 matrix A has $(1, 0, 1)^t$ & $(1, 1, 0)^t$ as eigenvectors, both the eigenvalue 4, and its trace is 2.
Find the determinant of A and ch. poly. of A.

Sol: The matrix A is 3×3 matrix so it has 3 eigen values.

Eigenvector corresponding to eigenvalues 4, contain the vector $(1, 0, 1)^t$, $(1, 1, 0)^t$.

Therefore dim of eigenspace at least 2.

It means that eigenvalue 4 has multiplicity at least 2.

Let the other eigenvalue = λ .

$$\text{Then trace} = 2 \Rightarrow \text{sum of eigenvalues} = 2$$

$$\Rightarrow \lambda + 4 + 4 = 2$$

$$\Rightarrow \lambda = -6$$

Hence, determinant A = product of eigenvalues
 $= -6 \times 4 \times 4 = -96.$

$$\begin{aligned}\text{ch. poly. of } A &= (\lambda - 4)^2(\lambda + 6) \\ &= (\lambda^2 + 16 - 8\lambda)(\lambda + 6) \\ &= \lambda^3 + 16\lambda - 8\lambda^2 + 6\lambda^2 + 96 - 48\lambda \\ &= \lambda^3 - 2\lambda^2 - 32\lambda + 96\end{aligned}$$

- (5) The matrix A has ch. poly. $t(t+1)(t-2)$.
 What is the characteristic poly. of A^3 .

Solⁿ: The eigenvalues of A are 0, -1, 2.

\therefore The eigenvalues of A^3 are 0, -1, 8.

Thus, the ch. poly of A^3 is $(\lambda-0)(\lambda+1)(\lambda-8)$

$$\begin{aligned}
 &= (\lambda^2 + \lambda)(\lambda - 8) \\
 &= \lambda^3 + \lambda^2 - 8\lambda^2 - 8\lambda \\
 &= \lambda^3 - 7\lambda^2 - 8\lambda.
 \end{aligned}$$

- (6) (a) The eigenvalues of A & A^t are same.

Solⁿ: $\det(A - \lambda I) = \det((A - \lambda I)^t) \quad (\because \det A = \det A^t)$

$$\begin{aligned}
 &= \det(A^t - \lambda I)
 \end{aligned}$$

Since the ch. poly. of A & A^t are same implies same ch. eqn.

But eigenvectors/ch. roots may not be same.

Exa:- $A = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}$, $A^t = \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}$. eigenvalues of A & A^t are 0, 0.

But ch. vector of A = $x_1 \begin{bmatrix} 1 \\ 0 \end{bmatrix}$ & $A^t = x_2 \begin{bmatrix} 0 \\ 1 \end{bmatrix}$

(b). If $\lambda \neq 0$ is an eigenvalue of A then λ^{-1} is an eigenvalue of A^t . But eigenvectors are same.

Solⁿ: ch. eqn is $\det(A - \lambda I) = 0$

$$\Rightarrow \det(A - \lambda A^{-1}A) = 0$$

$$\Rightarrow \det(\lambda \lambda^{-1} A - \lambda A^{-1}A) = 0 \Rightarrow \lambda^n \det(\lambda^{-1}I - A^{-1}) \det A = 0$$

$$\Rightarrow \det(\lambda(\lambda^{-1}I - A^{-1})A) = 0 \Rightarrow \boxed{\det(\lambda^{-1}I - A^{-1}) = 0}$$

(C) If λ is an eigenvalue of A then λ^k is an eigenvalue of A^k for any natural no. k .

Sol: We have
 $Ax = \lambda x$.

$$\begin{aligned} \text{Now, } A^k x &= A^{k-1}(Ax) = A^{k-1}(\lambda x) = \lambda A^{k-1}x = \lambda A^{k-2}(Ax) \\ &= \lambda A^{k-2}(\lambda x) \\ &= \lambda^2 A^{k-2}x \\ &\quad \vdots \\ &= \lambda^k x. \end{aligned}$$

Thus, λ^k is an eigenvalue of A^k .
 But eigenvector of A & A^k are same.

(d) If A & B are $n \times n$ matrices with A non singular
 then BA^T & $A^T B$ have the same set of
 eigenvalues.

Solution:

$$\begin{aligned} &\det(\lambda I - BA^T) \\ &= \det(\lambda AA^T - AA^T B A^T) \\ &= \det(A(\lambda I - A^T B)A^T) \\ &= \det(A) \det(\lambda I - A^T B) \det A^T \\ &\text{since } A \text{ is invertible } \Rightarrow \det A \neq 0, \det A^T \neq 0 \end{aligned}$$

Thus $\det(\lambda I - BA^T) = 0 \iff \det(\lambda I - A^T B) = 0$.
 $\Rightarrow BA^T$ & $A^T B$ have same set of eigenvalues.

(e) Similar matrices have same eigenvalue.

Suppose A and B are similar matrix Then if
a matrix P s.t

$$P^{-1}AP = B$$

Sol: suppose λ is an eigenvalue corresponding to eigen-
vector x

$$\text{i.e } AX = \lambda X.$$

$$\begin{aligned} B(P^{-1}X) &= P^{-1}AP(P^{-1}X) \\ &= P^{-1}A(PP^{-1})X \\ &= P^{-1}AIX \\ &= P^{-1}AX \\ &= P^{-1}\lambda X \\ &= \lambda P^{-1}X \end{aligned}$$

$$\text{i.e } B(P^{-1}X) = \lambda P^{-1}X$$

$P^{-1}X$ is an eigenvector of B corresponding to eigenvalue.

\Rightarrow Thus, A & B have same eigenvalue.

Also if x is an eigenvector of A corresponding to λ

Then $P^{-1}x$ is an eigenvector of B corresponding to λ .

Relationship b/w Eigenvectors

(b) A & A^T have same eigenvector.

Let λ be the eigenvalue corresponding to eigenvector x .

$$\text{Then } Ax = \lambda x$$

Multiplying by A^T , we obtain

$$A^T x = \lambda A^T x$$

$$\Rightarrow \frac{1}{\lambda} x = A^T x$$

$$\text{i.e. } A^T x = \frac{1}{\lambda} x$$

$\Rightarrow x$ is an eigenvector of A corresponding to eigenvalue $\frac{1}{\lambda}$.

(c) A and A^T both have same eigenvectors although eigenvalues are different.

(d) Suppose x is an eigenvector of BA^T corresponding to eigenvalue λ .

$$\text{Then } BA^T x = \lambda x.$$

Claim: $A^T x$ is an eigenvector of $A^T B$ corresponding to eigenvalue λ .

$$\begin{aligned} (A^T B)(A^T x) &= A^T B A^T x \\ &= A^T (\lambda x) \\ &= \lambda A^T x \end{aligned}$$

$$\text{i.e. } A^T B(A^T x) = \lambda(A^T x)$$

7) Construct a non diagonal 2×2 matrix that is diagonalizable but not invertible.

Sol: Since the matrix is not invertible.

$\therefore 0$ is an eigenvalue.

Let the other eigenvalue is 1.

Thus, the ch. poly. $\lambda^2 - \lambda$.

If $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$. Then

$$|A - \lambda I| = \begin{vmatrix} a-\lambda & b \\ c & d-\lambda \end{vmatrix} = \lambda^2 - (a+d)\lambda + ad - bc$$

$$\Rightarrow ad - bc = 0$$

$$a + d = 1$$

Take $a = 1$, then $d = 0$

$\Rightarrow bc = 0 \Rightarrow$ either $b = 0$ or $c = 0$ -
or both $b = c = 0$.

Hence $A = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$ or $\begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}$

↓ with a double eigen value $\lambda = 0$.