


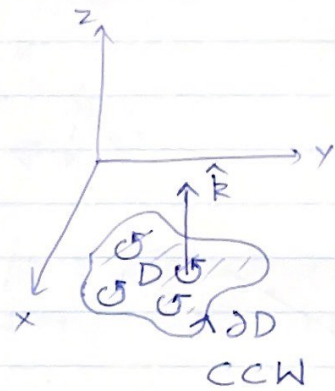
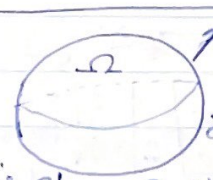


Oct 20/2023.

Summary:- "Integral of a derivative" Theorems
(Generalizations of Fundamental Thm. of Calculus)

FTC	$\int_a^b f'(x) dx = f(b) - f(a)$	
Fund. Thm of Line Integral 2D, 3D	$\int_C \nabla \phi \cdot d\vec{x} = \phi(\vec{b}) - \phi(\vec{a})$ ϕ - scalar potential for $\vec{F} = \nabla \phi$	
Stokes' Thm 3D	$\iint_{\Sigma} (\nabla \times \vec{F}) \cdot \hat{n} dS = \oint_{\partial \Sigma} \vec{F} \cdot d\vec{x}$ Circulation of \vec{F} around $\partial \Sigma$ Special case: Green's theorem	<div> <div>Σ ↓ open surface $\partial \Sigma$ ↓ closed boundary curve</div> <div></div> <div>\vec{F} is C' on $\Sigma \cup \partial \Sigma$ Oriented - Right hand Rule</div> </div>
2D	<p>When $\vec{F} = (F_1, F_2, 0)$, $F_1: \mathbb{R}^2 \rightarrow \mathbb{R}$ $F_2: \mathbb{R}^2 \rightarrow \mathbb{R}$</p> <p>$\nabla \times \vec{F} = (0, 0, \frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y})$</p> <p>$\hat{n}$ for any curve region D in xy-plane is \hat{k}</p> <p>\therefore Stokes' \Rightarrow Green</p> <p>$\iint_D (\frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y}) dA = \oint_{\partial D} \vec{F} \cdot d\vec{x}$ Circulation density (or) Vorticity at (x, y) Circulation of \vec{F} around ∂D</p>	 <p>CCW</p> <p>$\vec{F} = (F_1, F_2)$ is C' on $D \cup \partial D$ ∂D - smooth, simple curve, closed curve oriented CCW</p>
Divergence Thm 3D	$\iiint_{\Omega} \nabla \cdot \vec{F} dV = \iint_{\partial \Omega} \vec{F} \cdot \hat{n} dS$ Flux density at (x, y, z) Flux of \vec{F} outward through $\partial \Omega$	 \vec{F} is C' on $\Omega \cup \partial \Omega$

$$\underbrace{\nabla \cdot \vec{F}}_{\text{Scalar field}} = \left(\frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z} \right) \cdot (F_1, F_2, F_3) = \underbrace{\frac{\partial F_1}{\partial x} + \frac{\partial F_2}{\partial y} + \frac{\partial F_3}{\partial z}}_{\text{Scalar value at } (x, y, z)}$$

$$\underbrace{\nabla \times \vec{F}}_{\text{vector field}} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ F_1 & F_2 & F_3 \end{vmatrix} = \underbrace{\left(\frac{\partial F_3}{\partial y} - \frac{\partial F_2}{\partial z}, \frac{\partial F_1}{\partial z} - \frac{\partial F_3}{\partial x}, \frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right)}_{\text{Vector at } (x, y, z)}$$

Parallelism with Potentials for $\vec{F}: \mathbb{R}^3 \rightarrow \mathbb{R}^3$

$$\nabla \times \vec{F} = 0$$

$\Rightarrow \vec{F}$ is conservative (or) irrotational

(i.e) There exists a scalar potential $\phi: \mathbb{R}^3 \rightarrow \mathbb{R}$ for \vec{F}

$$(i.e) \vec{F} = \nabla \phi$$

• For C , a curve from \vec{a} to \vec{b}

$\int_C \vec{F} \cdot d\vec{x}$ is path independent

For any other curve C' from \vec{a} to \vec{b}

$$\begin{aligned} \int_C \vec{F} \cdot d\vec{x} &= \int_{C'} \vec{F} \cdot d\vec{x} \\ &= \phi(\vec{b}) - \phi(\vec{a}) \end{aligned}$$

(Curves must share same end-points)

$$\nabla \cdot \vec{F} = 0$$

$\Rightarrow \vec{F}$ is solenoidal (or) incompressible

there exists a vector potential $\vec{A}: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ for \vec{F}

$$(i.e) \vec{F} = \nabla \times \vec{A}$$

• For Σ , open surface with boundary $\partial \Sigma$ (oriented)

$\iint_{\Sigma} \vec{F} \cdot \hat{n} dS$ is surface independent

For any other open Σ' with same boundary $\partial \Sigma$ (with orientation same as above)

$$\begin{aligned} \iint_{\Sigma} \vec{F} \cdot \hat{n} dS &= \iint_{\Sigma'} \vec{F} \cdot \hat{n} dS \\ &= \oint_{\partial \Sigma} \vec{A} \cdot d\vec{x} \end{aligned}$$

A Special kind of field:

Suppose that \vec{F} is conservative as well as solenoidal. Then

$$\vec{F} = \nabla\phi \text{ for some } \phi \text{ (that is, } C^2) \\ \text{and } \nabla \cdot \vec{F} = 0 \text{ (i.e.) } \nabla \cdot (\nabla\phi) = 0. (**)$$

Now,

$$\nabla \cdot \nabla\phi = \left(\frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z} \right) \cdot \left(\frac{\partial\phi}{\partial x}, \frac{\partial\phi}{\partial y}, \frac{\partial\phi}{\partial z} \right) \\ = \frac{\partial^2\phi}{\partial x^2} + \frac{\partial^2\phi}{\partial y^2} + \frac{\partial^2\phi}{\partial z^2}$$

Sub. this (**) gives a PDE

$$\frac{\partial^2\phi}{\partial x^2} + \frac{\partial^2\phi}{\partial y^2} + \frac{\partial^2\phi}{\partial z^2} = 0 \quad (\text{Laplace Equation})$$

Conversely, if a scalar field ϕ obeys the Laplace Equation, then ϕ is the potential of a conservative vector field.

Notation:

$$\nabla^2 := \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} \text{ is the Laplace}$$

operator (or Laplacian)

More concisely, (in 2D and 3D), Laplace Equation can be written as $\nabla^2\phi = 0$

Stokes' Thm Divergence Thm, & Conservation Laws

One can use Div. Thm. to derive fundamental equations governing:

→ Fluid mechanics

(Continuity eqn. - See Mobius)

→ Electromagnetism

Two Math Results

1) If $F(t) = \int_{x=a}^{x=b} g(x, t) dx$ and g is C^1 , then

$$\begin{aligned} F'(t) &= \frac{d}{dt} F(t) = \frac{d}{dt} \int_{x=a}^{x=b} g(x, t) dx \\ &= \int_{x=a}^{x=b} \frac{\partial g}{\partial t}(x, t) dx \end{aligned}$$

Moving the derivative inside the integral, as long as the differentiation and integration variables are different.

2) If $\int_{x_1}^{x_2} f(x) dx = 0 \quad \forall x_1, x_2 \in [a, b]$, and f is continuous, then

$$f(x) = 0 \quad \forall x \in [a, b]$$

If an integral is zero regardless of the bounds of integration, the function itself must be zero.

The generalized form of 2) is known as the du Bois-Reymond Lemma.

Both 1) and 2) hold true for higher dimensions (i.e) they apply to double and triple integrals)

$$\iiint_{\Omega} f \, dv = 0 \quad \forall \Omega \Rightarrow f = 0$$

Often, you will see " Ω is an arbitrary region in \mathbb{R}^3 "

Deriving Gauss Law for electricity

Gauss law : Flux of \vec{E} through a closed surface = $\frac{(\text{Charge inside})}{\epsilon_0}$

Let Ω be an arbitrary region with closed boundary surface $\partial\Omega$

$$\iint_{\partial\Omega} \vec{E} \cdot \hat{n} \, ds = \frac{Q}{\epsilon_0} \rightarrow \text{permittivity}$$

Here, Q is the total charge inside $\partial\Omega$.

If $\rho(\vec{x}, t)$ denotes the charge density in Ω ,

then $Q = \iiint_{\Omega} \rho \, dv$

$$\therefore \iint_{\partial\Omega} \vec{E} \cdot \hat{n} \, ds = \frac{1}{\epsilon_0} \iiint_{\Omega} \rho \, dv$$

Apply Divergence Thm to LHS: (When \vec{E} is C^1 on $\Omega \cup \partial\Omega$)

$$\iint_{\partial\Omega} \vec{E} \cdot \hat{n} dS = \iiint_{\Omega} \nabla \cdot \vec{E} dV$$

$$\Rightarrow \iiint_{\Omega} \nabla \cdot \vec{E} dV = \frac{1}{\epsilon_0} \iiint_{\Omega} \rho dV$$

$$\Rightarrow \iiint_{\Omega} \left[\nabla \cdot \vec{E} - \frac{\rho}{\epsilon_0} \right] dV = 0$$

As Ω is arbitrary,

$$\nabla \cdot \vec{E} - \frac{\rho}{\epsilon_0} = 0$$

$$(i.e) \boxed{\nabla \cdot \vec{E} = \frac{\rho}{\epsilon_0}} \quad (ME 1)$$

Partial differential equation (PDE) for

$\vec{E} = (E_1, E_2, E_3)$ each E_i is function of (\vec{x}, t)
 $\vec{x} \in \mathbb{R}^3$

In what follows, Σ is an arbitrary open surface with closed boundary curve $\partial\Sigma$

Ω is an arbitrary region with closed boundary surface $\partial\Omega$

Assume \vec{E} and \vec{B} , magnetic field are C^1 on wherever we apply Div. Thm (or) Stokes' Thm

$$\text{Faraday's Law: } \oint_{\partial\Sigma} \vec{E} \cdot d\vec{x} = - \frac{d}{dt} \iint_{\Sigma} \vec{B} \cdot \hat{n} dS$$

↓ Stokes'

↓ Move the derivative inside

$$\iint_{\Sigma} (\nabla \times \vec{E}) \cdot \hat{n} dS = - \iint_{\Sigma} \frac{\partial \vec{B}}{\partial t} \cdot \hat{n} dS$$

$$\Rightarrow \iint_{\Sigma} \left(\nabla \times \vec{E} + \frac{\partial \vec{B}}{\partial t} \right) \cdot \hat{n} dS = 0$$

↓ du Bois-Reymond lemma
as Σ is arbitrary

$$(ME 2) \quad \nabla \times \vec{E} + \frac{\partial \vec{B}}{\partial t} = 0 \quad (\text{or}) \quad \nabla \times \vec{E} = - \frac{\partial \vec{B}}{\partial t}$$

III^{ly} in PS 5,

Gauss law for Magnetism

$$(ME 3) \quad \nabla \cdot \vec{B} = 0 \quad \text{from } \iint_{\partial\Omega} \vec{B} \cdot \hat{n} dS = 0 \quad \text{and}$$

$$(ME 4) \quad \nabla \times \vec{B} = \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t} + \mu_0 \vec{J} \quad \text{from } \oint_{\partial\Sigma} \vec{B} \cdot d\vec{x} = \mu_0 \epsilon_0 \frac{d}{dt} \iint_{\Sigma} \vec{E} \cdot \hat{n} dS + \mu_0 \iint_{\Sigma} \vec{J} \cdot \hat{n} dS$$

⏟
Ampere's Law

Here $\vec{J}(\vec{x}, t)$ is the electric current density at (\vec{x}, t) .

(ME 4) can be rewritten as

$$\frac{1}{\mu_0 \epsilon_0} \nabla \times \vec{B} = \frac{\partial \vec{E}}{\partial t} + \frac{\vec{J}}{\epsilon_0}$$

$$\text{Let } c = \frac{1}{\sqrt{\mu_0 \epsilon_0}}$$

$$(ME 4') \quad c^2 (\nabla \times \vec{B}) = \frac{\partial \vec{E}}{\partial t} + \frac{\vec{J}}{\epsilon_0}$$

Now take divergence on ~~the~~ both sides

$$c^2 \nabla \cdot (\nabla \times \vec{B}) = \nabla \cdot \frac{\partial \vec{E}}{\partial t} + \frac{\nabla \cdot \vec{J}}{\epsilon_0}$$

$$0 = \frac{\partial}{\partial t} \nabla \cdot \vec{E} + \frac{\nabla \cdot \vec{J}}{\epsilon_0}$$

$$0 = \frac{1}{\epsilon_0} \frac{\partial \rho}{\partial t} + \frac{\nabla \cdot \vec{J}}{\epsilon_0}$$

$$\Rightarrow \nabla \cdot \vec{J} = - \frac{\partial \rho}{\partial t}$$

In Global form, by Divergence Thm,

$$\iint_{\partial \Omega} \vec{J} \cdot \hat{n} dS = - \frac{d}{dt} \iiint_{\Omega} \rho dV = - \frac{dQ}{dt}$$

Flux of current from a closed surface $\partial \Omega$ is the decrease of the charge inside $\partial \Omega$
[Conservation of Electric charge] any flow of charge must come from some supply.

For simplicity, we look at the case with no charges ($\rho=0$ and no currents ($\vec{J}=0$)). Then the equations read:

$$\nabla \cdot \vec{E} = 0 \quad (1)$$

$$\nabla \times \vec{E} = - \frac{\partial \vec{B}}{\partial t} \quad (2)$$

$$\nabla \cdot \vec{B} = 0 \quad (3)$$

$$\nabla \times \vec{B} = \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t} \quad (4)$$

Take curl of (4),

$$\nabla \times (\nabla \times \vec{B}) = \nabla \times \left(\mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t} \right)$$

Curl of a curl identity

↓ Switch order of "∇×" and "∂/∂t"

$$\underbrace{\nabla(\nabla \cdot \vec{B}) - \nabla^2 \vec{B}}_{\substack{\parallel (3) \\ 0}} = \mu_0 \epsilon_0 \frac{\partial}{\partial t} (\nabla \times \vec{E})$$

↓ (2)

$$-\nabla^2 \vec{B} = \mu_0 \epsilon_0 \frac{\partial}{\partial t} \left(- \frac{\partial \vec{B}}{\partial t} \right)$$

$$\Rightarrow \frac{1}{c^2} \frac{\partial^2 \vec{B}}{\partial t^2} - \nabla^2 \vec{B} = 0 \quad \left(\text{as } c = \frac{1}{\sqrt{\mu_0 \epsilon_0}} \right)$$

$$\Rightarrow \boxed{\frac{\partial^2 \vec{B}}{\partial t^2} = c^2 \nabla^2 \vec{B}} \quad \text{a well-known second order PDE equation called "wave equation"}$$

More importantly, for waves travel with speed c , This c is nothing but the speed of light (in free space)

Static Phenomena: Suppose that there is no time dependence, i.e., any t derivatives are zero. The equations then read:

$$\left. \begin{aligned} \nabla \cdot \vec{E} &= \frac{\rho}{\epsilon_0} \quad (1) \\ \nabla \times \vec{E} &= 0 \quad (2) \end{aligned} \right\} \text{Electrostatics}$$

$$\left. \begin{aligned} \nabla \cdot \vec{B} &= 0 \quad (3) \\ \nabla \times \vec{B} &= \mu_0 \vec{J} \quad (4) \end{aligned} \right\} \text{Magnetostatics}$$

Notice that the electric and magnetic effects are decoupled.

① & ② Electrostatics

$\nabla \times \vec{E} = 0 \Rightarrow \vec{E}$ is conservative

$\exists \phi$ s.t. $\vec{E} = \nabla \phi$

$$(1) \Rightarrow \nabla \cdot (\nabla \phi) = \frac{\rho}{\epsilon_0}$$

$$\nabla^2 \phi = \frac{\rho}{\epsilon_0} \quad \left[\begin{array}{l} \text{Poisson} \\ \text{Equation} \end{array} \right]$$

↑
Laplacian operator

If $\rho = 0$, we get $\nabla^2 \phi = 0$
Laplace equation

By solving for ϕ , we can find \vec{E} by taking $\vec{E} = \nabla \phi$.

Magnetostatics - ③ & ④

$$\nabla \cdot \vec{B} = 0 \Rightarrow$$

$$\exists \vec{A} \text{ s.t. } \vec{B} = \nabla \times \vec{A}$$

$$(4) \Rightarrow \nabla \times (\nabla \times \vec{A}) = \mu_0 \vec{J} (*)$$

$$\nabla(\nabla \cdot \vec{A}) - \nabla^2 \vec{A} = \nabla \times (\nabla \times \vec{A})$$

(Curl of a curl identity)

\vec{A} is not unique. We can choose \vec{A} s.t.

$$\nabla \cdot \vec{A} = 0.$$

Then (*) becomes

$$\nabla^2 \vec{A} = -\mu_0 \vec{J} \quad \left(\begin{array}{l} \text{Vector} \\ \text{Poisson} \\ \text{Equation} \end{array} \right)$$

$$(\nabla^2 A_1, \nabla^2 A_2, \nabla^2 A_3)$$

$$= (-\mu_0 J_1, -\mu_0 J_2, -\mu_0 J_3)$$

3 Poisson equations

(or) Laplace if $\vec{J} = \vec{0}$

Once we know \vec{A} , compute $\vec{B} = \nabla \times \vec{A}$