AutoML: Dynamic Configuration & Learning

Population-based Training

Bernd Bischl Frank Hutter Lars Kotthoff <u>Marius Lindauer</u> Joaquin Vanschoren

On-the-fly Adaption

 Dynamic algorithm configuration assumes that we have access to a representative learning environment in an offline learning phase

On-the-fly Adaption

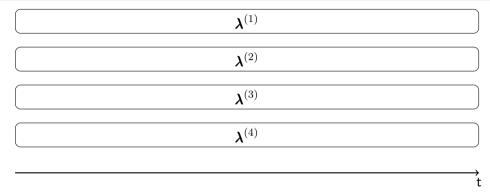
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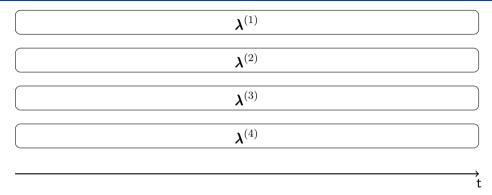
→ Try to figure out best hyperparameter settings on the fly

Massively parallelized Random Search



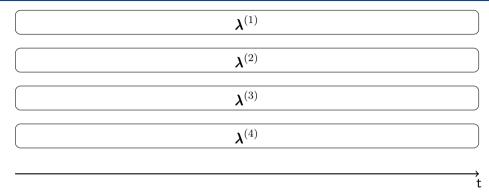
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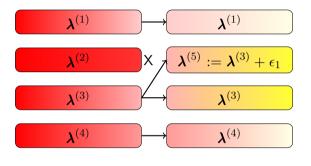
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- Pure exploration on a large population of configurations
- No dynamic adaptation

Population-based Training [Jaderberg et al. 2017]



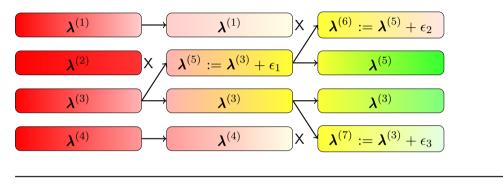
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- Since hyperparameter settings changes while training the models,
 PBT relates to dynamic algorithm configuration
- Since each population member (i.e., model) can be trained independently,
 PBT can be efficiently parallelized
 - → Drawback: requires substantial parallel compute resources

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- → Less parallel compute resources are required(?)
- → Scales better to higher dimensional spaces(?)

$\overline{\mathsf{PBT}} + \mathsf{BO}$: Outline

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- Several ideas on how to parallelize BO
 - ► Randomize the model training or optimization of the acquisition function
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 - ► Hallucinate performance of other hyperparameter settings in optimistically, pessimistically or in expectation of the current surrogate model

PBT + BO: Parallel Evaluation [Parker-Holder et al. 2020]

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- BO-Surrogate model predicts the cost improvement over time:

$$c_{\mathsf{PBT}}^{(t)}(\boldsymbol{\lambda}) = \frac{c^{(t)}(\boldsymbol{\lambda}) - c^{(t-1)}(\boldsymbol{\lambda})}{\Delta t}$$

where $c^{(t)}(\pmb{\lambda})$ is the cost for a given hyperparameter setting at time step t.

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 \bullet Remark: Also add $c^{(t-1)}$ as an input to the BO-surrogate model to ease the task of predicting the improvement