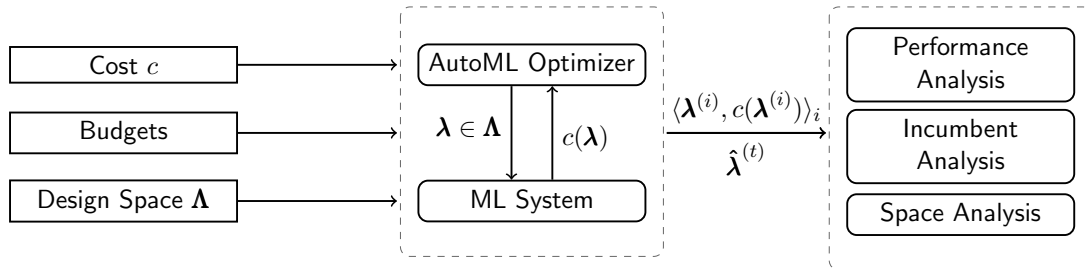


# AutoML: Interpretability

Studying the AutoML Optimization Process

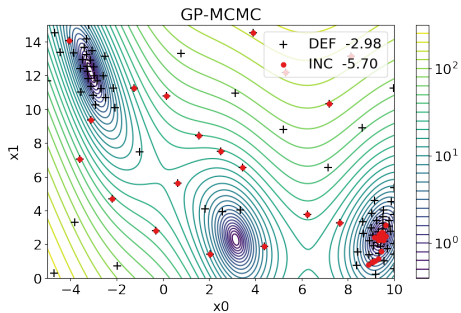
Bernd Bischl   Frank Hutter   Lars Kotthoff  
Marius Lindauer   Joaquin Vanschoren

# Idea



~> focus on how the AutoML optimizer samples from the design space  $\Lambda$

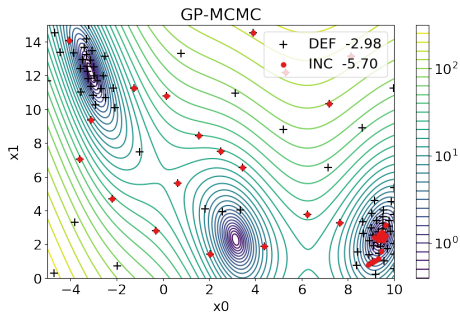
# Analyzing the Sampling Behavior



- Plot of a 1D or 2D function

Source: [Lindauer et al. 2019]

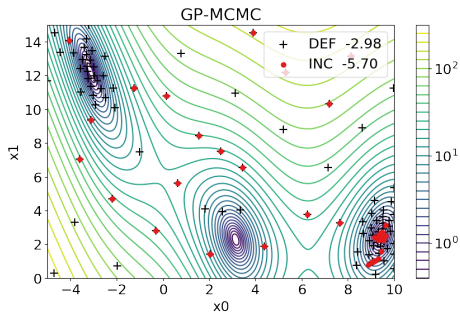
# Analyzing the Sampling Behavior



Source: [Lindauer et al. 2019]

- Plot of a 1D or 2D function
- Background shows the ground truth (real function values)

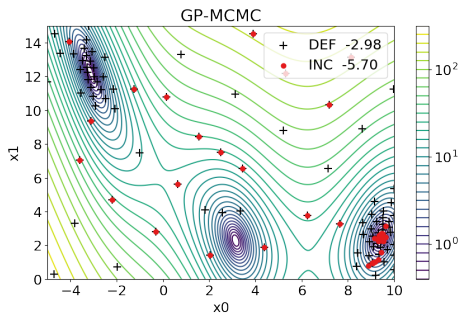
# Analyzing the Sampling Behavior



Source: [Lindauer et al. 2019]

- Plot of a 1D or 2D function
- Background shows the ground truth (real function values)
- Dots are sampled points in the search space

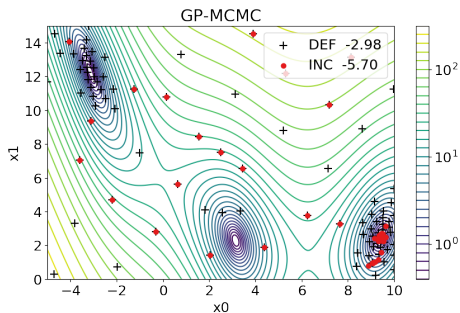
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Source: [Lindauer et al. 2019]

- Plot of a 1D or 2D function
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# Analyzing the Sampling Behavior

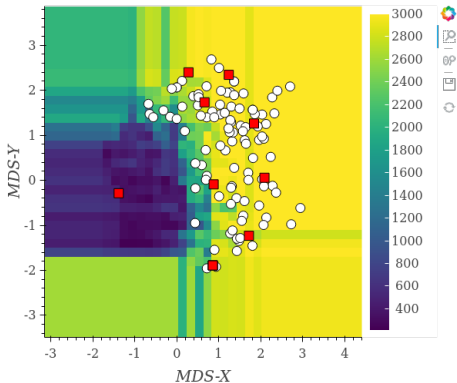


Source: [Lindauer et al. 2019]

- Plot of a 1D or 2D function
- Background shows the ground truth (real function values)
- Dots are sampled points in the search space
- Typical approach in Bayesian Optimization community

~> Impossible for higher dimensional problems?

# Analyzing the Sampling Behavior in $N$ -D

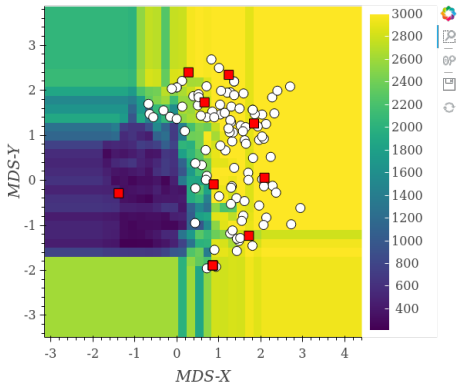


- Same idea as before  
but we have to project  $N$ -D into 2-D

Source: [Lindauer et al. 2019]



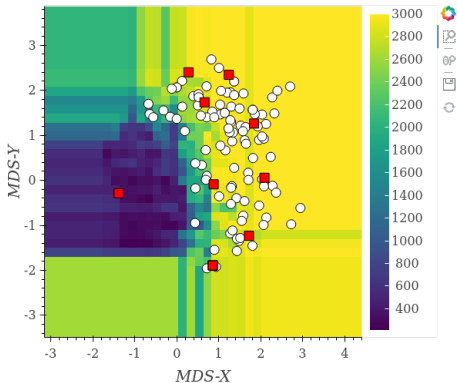
# Analyzing the Sampling Behavior in $N$ -D



Source: [Lindauer et al. 2019]

- Same idea as before  
but we have to project  $N$ -D into 2-D
  - 1 Use an MDS to project down to 2-D

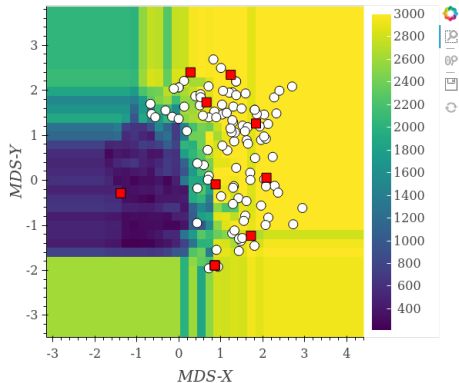
# Analyzing the Sampling Behavior in $N$ -D



Source: [Lindauer et al. 2019]

- Same idea as before  
but we have to project  $N$ -D into 2-D
  - 1 Use an MDS to project down to 2-D
  - 2 Each dot is single hyperparameter configuration

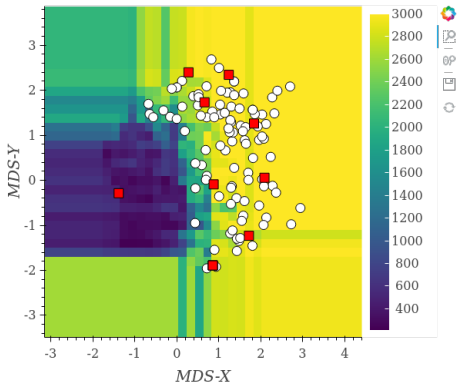
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Source: [Lindauer et al. 2019]

- Same idea as before  
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  - 1 Use an MDS to project down to 2-D
  - 2 Each dot is single hyperparameter configuration
  - 3 Red squares are intermediate incumbents

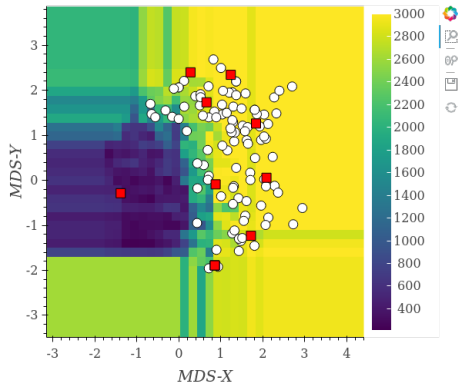
# Analyzing the Sampling Behavior in $N$ -D



Source: [Lindauer et al. 2019]

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  - 2 Each dot is single hyperparameter configuration
  - 3 Red squares are intermediate incumbents
  - 4 The background is colored wrt a performance-estimate (e.g., reusing model fitted during BO)

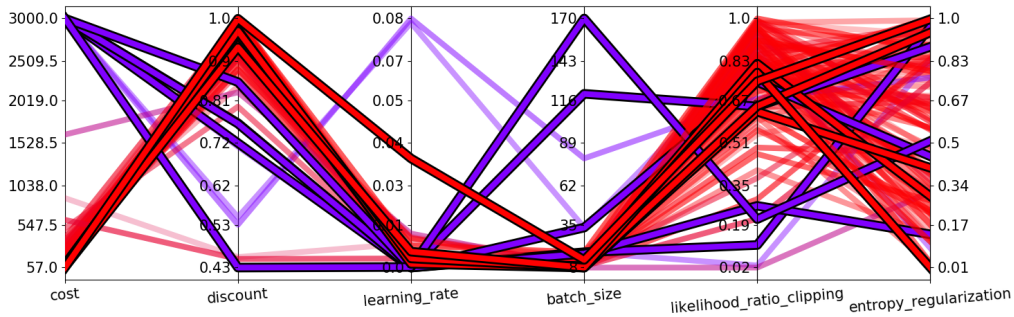
# Analyzing the Sampling Behavior in $N$ -D



Source: [Lindauer et al. 2019]

- Same idea as before but we have to project  $N$ -D into 2-D
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  - 2 Each dot is single hyperparameter configuration
  - 3 Red squares are intermediate incumbents
  - 4 The background is colored wrt a performance-estimate (e.g., reusing model fitted during BO)
  - 5 Extension: Animation by showing how points get added over time

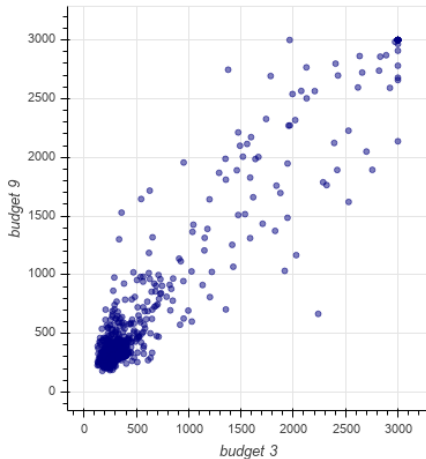
# Parallel Coordinate Plot [Golovin et al 2017]



Source: [Lindauer et al. 2019]

- Each coordinate is one hyperparameter;
- Except the most left one: cost or loss

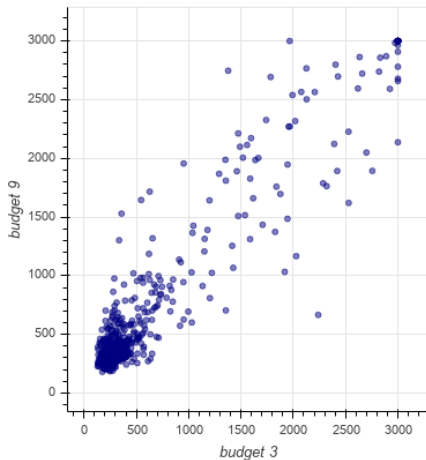
# Multi-Fidelity Checks



- Challenge of multi-fidelity approaches:
  - ▶ How to choose the fidelities (a.k.a. budgets)

Source: [Lindauer et al. 2019]

# Multi-Fidelity Checks

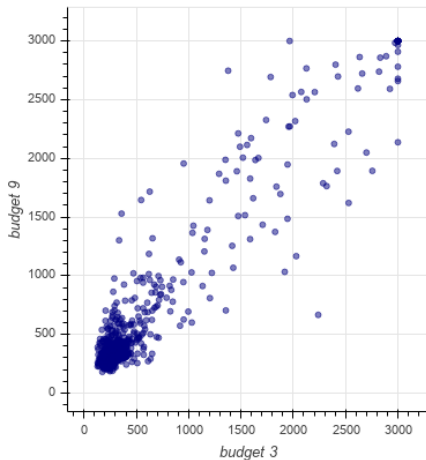


- Challenge of multi-fidelity approaches:
  - ▶ How to choose the fidelities (a.k.a. budgets)
- Important Property:
  - ▶ Decisions on small budgets should be reasonable for higher budgets

Source: [Lindauer et al. 2019]



# Multi-Fidelity Checks



Source: [Lindauer et al. 2019]

- Challenge of multi-fidelity approaches:
  - ▶ How to choose the fidelities (a.k.a. budgets)
- Important Property:
  - ▶ Decisions on small budgets should be reasonable for higher budgets
- Analysis:
  - 1 Scatter plot of performance on Budget X vs. Budget Y
  - 2 Each dot is sampled hyperparameter configuration
  - 3 Compute rank correlation (here: 0.69)