AutoML: Neural Architecture Search (NAS) Blackbox Optimization Methods

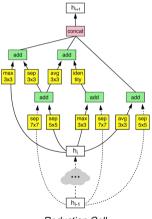
Bernd Bischl <u>Frank Hutter</u> Lars Kotthoff Marius Lindauer Joaquin Vanschoren

NAS as Hyperparameter Optimization

• NAS can be formulated as a HPO problem

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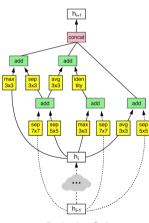
- NAS can be formulated as a HPO problem
- E.g., cell search space by [Zoph et al. 2018] has 5 categorical choices per block
 - 2 categorical choices of hidden states
 - * For block N, the domain of these categorical variables is $\{h_i, h_{i-1}, \text{output of block } 1, ..., \text{output of block } N-1\}$
 - 2 categorical variables choosing between operations
 - ▶ 1 categorical variable choosing the combination method
 - ► Total number of hyperparameters for the cell: 5B (with B=5 by default)



Reduction Cell

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 - ▶ Total number of hyperparameters for the cell: 5B (with B=5 by default)
- In general: one may require conditional hyperparameters
 - ► E.g., chain-structured search space
 - ★ Top-level hyperparameter: number of layers L
 - ★ Hyperparameters of layer k conditional on $L \ge k$



Reduction Cell

Early Work on Neuroevolution (already since the 1990s)

[Kitano. 1990; Angeline et al. 1994; Stanley and Miikkulainen. 2002; Bayer et al. 2009; Floreano et al. 2008]

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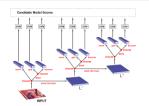
- Evolves architectures & often also their weights
- Typical approach:
 - ▶ Initialize a population of N random architectures
 - Sample N individuals from that population (with replacement) according to their fitness
 - lacktriangle Apply mutations to those N individuals to produce the next generation's population
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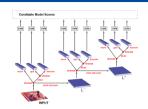
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- Mutations include adding, changing or removing a layer

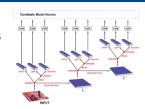
- With TPE [Bergstra et al. 2011]:
 - ▶ Joint optimization of a vision architecture with 238 hyperparameters [Bergstra et al. 2013]
 - ▶ State-of-the-art performance on 3 disparate problems:
 - ★ Face matching, face identification, and object recognition

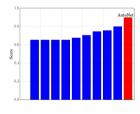


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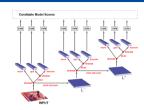


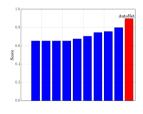
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 - ▶ In 2015, Auto-Net already had several successes in ML competitions
 - ★ E.g., human action recognition: 54491 data points, 5000 features, 18 classes
 - * First automated deep learning (Auto-DL) method to win a machine learning competition dataset against human experts



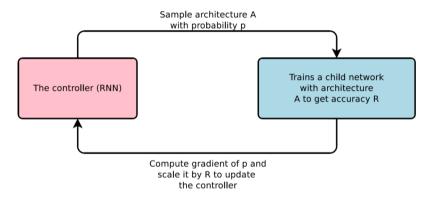


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- With Gaussian processes:
 - ► Arc kernel [Swersky et al. 2013]



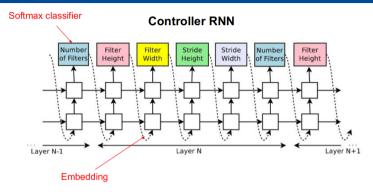


Reinforcement Learning [Zoph and Le. 2016]



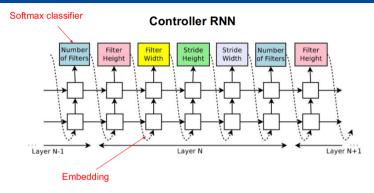
- Use RNN ("Controller") to generate a NN architecture piece-by-piece
- Train this NN ("Child Network") and evaluate it on a validation set
- Use Reinforcement Learning (RL) to update the parameters of the Controller RNN to optimize the performance of the child models

Learning CNNs with RL [Zoph and Le. 2016]



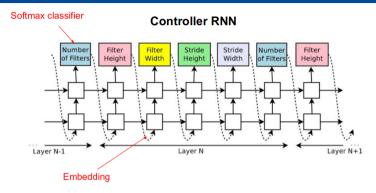
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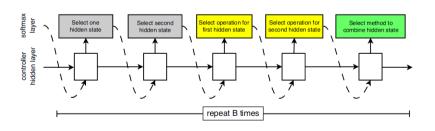
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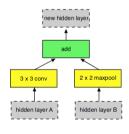


- For a fixed number of layers, select:
 - Filter width/height, stride width/height, number of filters
- Large computational demands (800 GPUs for 2 weeks, 12.800 architectures evaluated)
- State-of-the-art results for CIFAR-10 & Penn Treebank architecture
 - → Brought NAS into the limelight

Learning CNN cells with RL [Zoph et al. 2018]

- 2 types of cells: normal and reduction cells
- ullet For each type of cell: B blocks, each with 5 choices
 - Choose two previous feature maps (from this cell)
 - For each of these, choose an operation (3×3 conv, max-pool, etc.)
 - Choose a merge operation to combine the two results (concat or add)





Learning CNN cells with evolution [Real et al. 2018]

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 - Choose two previous feature maps (from this cell)
 - For each of these, choose an operation (3×3 conv, max-pool, etc.)
 - Choose a merge operation to combine the two results (concat or add)
- Evolution simply tackles this as a HPO problem with $2\times5\times B$ variables:



Select second hidden state

Select operation for first hidden state

Select operation for second hidden state

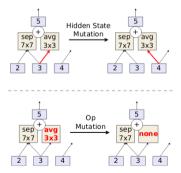
Select method to combine hidden state

Regularized/Aging Evolution [Real et al. 2018]

- Quite standard evolutionary algorithm
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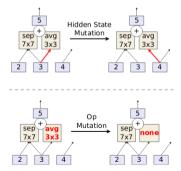
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- Standard SGD for training weights (optimizing the same blackbox as RL)
- Same fixed-length (HPO) search space as used for RL [Zoph et al. 2018]



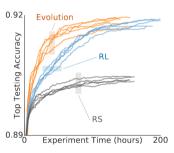
Different types of mutations in cell search space

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Different types of mutations in cell search space



 $\begin{array}{c} {\sf State}\text{-of-the-art performance in} \\ {\sf apples-to-apples comparison} \\ {\sf \rightarrow AmoebaNet} \end{array}$

- Encode the architecture space by categorical hyperparameters (like regularized evolution)
- Strong performance with tree-based models
 - ► TPE [Bergstra et al. 2013]
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 - BANANAS [White et al. 2019]

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 - BANANAS [White et al. 2019]
- BO is very competitive, has been shown to outperform RL [Ying et al. 2019]

Current State of the Art: Differential Evolution

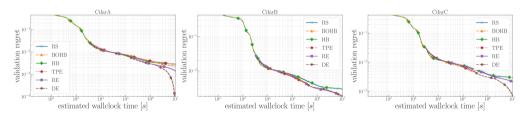
• Comprehensive experiments on a wide range of 12 different NAS benchmarks [Awad et al. 2020]

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Results:

- Regularized evolution is very robust, typically amongst best of the methods discussed so far
- ▶ Evolution variant of differential evolution is yet better; most efficient and robust method



Questions to Answer for Yourself / Discuss with Friends

Repetition:

What are some pros and cons of using black-box optimizers for NAS?

Repetition:

How can NAS be modelled as a HPO problem?

• Discussion:

Given enough resources, will blackbox NAS approaches always improve performance?

Discussion:

Why does discarding the oldest individual (rather than the worst) help in regularized/aging evolution?

• Transfer:

How would you write NAS with the hierarchical search space as a HPO problem?