AutoML: Introduction

Overview of AutoML Problems

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Different metrics to measure the success of ML and AutoML:

Accuracy on a validation dataset

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- \leadsto AutoML optimizes an arbitrary cost function, denoted as c.
- \sim $c(\cdot)$ can also return several cost metrics

Hyperparameters of an SVM



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sklearn.svm.SVC Examples using sklearn.svm.SVC

sklearn.svm.SVC

class sklearn.svm. SVC (C=1.0, kernel='rbf', degree=3, gamma='auto_deprecated', coef0=0.0, shrinking=True, probability=False, fol=0.001, cache_size=200, class_weight=None, verbose=False, max_iter=-1, decision_function_shape='ovir', random_state=None) [source]

C-Support Vector Classification.

The implementation is based on libsym. The fit time complexity is more than quadratic with the number of samples which makes it hard to scale to dataset with more than a couple of 10000 samples.

The multiclass support is handled according to a one-vs-one scheme.

For details on the precise mathematical formulation of the provided kernel functions and how gamma, coef0 and degree affect each other, see the corresponding section in the narrative documentation: Kernel functions.

Read more in the User Guide.

Parameters: C: float, optional (default=1.0)

Penalty parameter C of the error term.

kernel: string, optional (default='rbf')

Specifies the kernel type to be used in the algorithm. It must be one of 'linear', 'poly', 'rbf', 'sigmoid', 'precomputed' or a callable. If none is given, 'rbf' will be used. If a callable is given it is used to pre-compute the kernel matrix from data matrices; that matrix should be an array of shape (n_samples, n_samples).

degree: int, optional (default=3)

Degree of the polynomial kernel function ('poly'), Ignored by all other kernels.

gamma: float, optional (default='auto')

Kernel coefficient for 'rbf', 'poly' and 'sigmoid'.

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The hyper-parameter optimization (HPO) problem is to find a hyper-parameter configuration that minimizes this cost:

$$\lambda^* \in \underset{\lambda \in \Lambda}{\operatorname{arg \, min}} c(\mathcal{A}_{\lambda}, \mathcal{D}_{train}, \mathcal{D}_{valid})$$

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- Sometimes, we want to optimize for different metrics, instead of one
 - → multi-objective optimization and Pareto fronts

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 - decision tree
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- studied 179 classifiers on 121 datasets [Fernández-Delgado et al. 2015]
- In practice, we actually want to jointly choose the best ML-algorithm and its hyperparameters

CASH: Combined Algorithm Selection and Hyperparameter Optimization

Definition

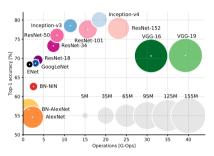
Let

- ullet ${f A}=\{{\cal A}_1,{\cal A}_2,\ldots,{\cal A}_k\}$ be a set of algorithms (a.k.a. portfolio)
- ullet $oldsymbol{\Lambda}$ be a set of hyperparameters of each machine learning algorithm \mathcal{A}_i
- ullet \mathcal{D}_{opt} be a dataset which is split into \mathcal{D}_{train} and \mathcal{D}_{valid}
- $c(\mathcal{A}_{\lambda}, \mathcal{D}_{train}, \mathcal{D}_{valid})$ denote the cost of \mathcal{A}_{λ} trained on \mathcal{D}_{train} and evaluated on \mathcal{D}_{valid} .

we want to find the best combination of algorithm $\mathcal{A} \in \mathbf{A}$ and its hyperparameter configuration $\lambda \in \Lambda$ minimizing:

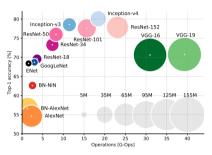
$$(\mathcal{A}^*, \boldsymbol{\lambda}^*) \in \underset{\mathcal{A} \in \mathbf{A}, \boldsymbol{\lambda} \in \boldsymbol{\Lambda}}{\operatorname{arg \, min}} c(\mathcal{A}_{\boldsymbol{\lambda}}, \mathcal{D}_{train}, \mathcal{D}_{valid})$$

- Many architecture were proposed
- Differences in
 - Depth
 - Resolution
 - Width
 - Operators
 - Connections
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on Imagenet [Canzian et al. 2017]

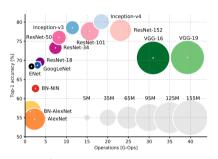
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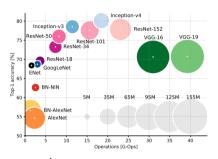


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- For other datasets, you might need different architectures to achieve top-performance
 - ► For similar datasets, you might use scaled versions of known architectures (e.g., CIFAR10 and Imagenet)

Neural Architecture Search (NAS)

Definition

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- ullet λ be an architecture for a deep neural network N with domain Λ ,
- ullet \mathcal{D}_{opt} be a dataset which is split into \mathcal{D}_{train} and \mathcal{D}_{valid}
- $c(N_{\lambda}, \mathcal{D}_{train}, \mathcal{D}_{valid})$ denote the cost of N_{λ} trained on \mathcal{D}_{train} and evaluated on \mathcal{D}_{valid} .

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- In practice, you want jointly optimize HPO and NAS [Zela et al. 2018]

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the per-instance algorithm selection problem is to obtain a mapping $s:\mathcal{D}\mapsto\mathcal{A}$ such that

$$\underset{s}{\operatorname{arg\,min}} \int_{\mathbf{D}} c(s(\mathcal{D}), \mathcal{D}) p(\mathcal{D}) \, d\mathcal{D}$$

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- $c: \Pi \times D \to \mathbb{R}$ be a cost metric assessing the cost of a conf. policy $\pi \in \Pi$ on $\mathcal{D} \in \mathbf{D}$ the dynamic algorithm configuration problem (DAC) is to obtain a configuration policy $\pi^*: s_t \times \mathcal{D} \mapsto \lambda$ by optimizing its cost across a distribution of datasets:

$$\pi^* \in \operatorname*{arg\,min}_{\pi \in \Pi} \int_{\mathbf{D}} p(\mathcal{D}) c(\pi, \mathcal{D}) \, \mathrm{d}\mathcal{D}$$

Summary

HPO Search for the best hyperparameter configuration of a ML algorithm

CASH Search for the best combination of algorithm and hyperparameter configuration

NAS Search for the architecture of neural network

Selection Predict the best algorithm (and its hyperparameter configuration)

DAC Predict the best hyperparameter configuration for an algorithm state at a given time point