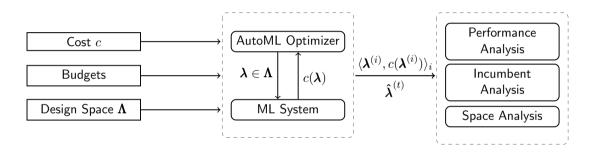
#### AutoML: Interpretability

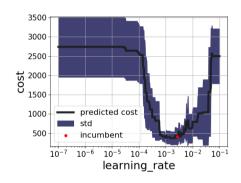
Incumbent Analysis and Local Hyperparameter Importance

Bernd Bischl Frank Hutter Lars Kotthoff <u>Marius Lindauer</u> Joaquin Vanschoren



→ focus on why is the eventually returned configuration a good choice

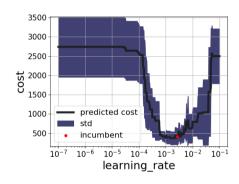
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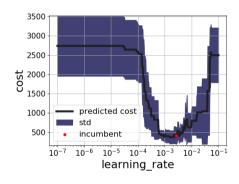
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- Typical question of users:
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  - Key Ideas:
    - Re-use probabilistic models as trained in BO
    - Plot performance change around  $\hat{\pmb{\lambda}}^{(t)}$  along each dimension

# Quantifying Local Importance [Biedenkapp et al. 2018]

$$VAR_{\lambda}(i) = \sum_{v \in \Lambda} (\mathbb{E}_{v \sim \Lambda_i}[L(\lambda)] - L(\lambda[\lambda_i := v]))^2$$
(1)

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While fixing all other hyperparameters to the incumbent value, the hyperparameter with the highest variance is the most important one

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- Cheap approach: Assess  $\lambda^{(end)}$  with each hyperparameter value from  $\lambda^{(start)}$
- ullet Expensive approach: Try all mixtures of  $oldsymbol{\lambda}^{( ext{end})}$  and  $oldsymbol{\lambda}^{( ext{start})}$ 
  - Only feasible for small spaces and fairly cheap ML systems
- ullet Trade-off: Find a way from  $oldsymbol{\lambda}^{(start)}$  to  $oldsymbol{\lambda}^{(end)}$  in a greedy fashion [Fawcett and Hoos. 2016]

Given:

$$m{\lambda}^{( extsf{start})} = [1, 1, 0, 100] \qquad L_{ extsf{start}} = 20\% \ m{\lambda}^{( ext{end})} = [0.98, 2.42, 1, 42] \quad L_{ ext{end}} = 4\%$$

Given:

$$m{\lambda}^{({\sf start})} = [1, 1, 0, 100] \qquad L_{{\sf start}} = 20\% \ m{\lambda}^{({\sf end})} = [0.98, 2.42, 1, 42] \qquad L_{{\sf end}} = 4\%$$

$$\lambda^{(1)} = [0.98, 1, 0, 100] \quad L_1 = 19\%$$

Given:

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$$\lambda^{(1)} = [0.98, 1, 0, 100] \quad L_1 = 19\%$$
  
 $\lambda^{(2)} = [1, 2.42, 0, 100] \quad L_2 = 20\%$ 

Given:

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 $\lambda^{(3)} = [1, 1, 1, 100] \quad L_3 = 7\%$ 

Given:

$$m{\lambda}^{( extsf{start})} = [1, 1, 0, 100] \qquad L_{ extsf{start}} = 20\% \ m{\lambda}^{( ext{end})} = [0.98, 2.42, 1, 42] \quad L_{ ext{end}} = 4\%$$

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 $\lambda^{(4)} = [1, 1, 0, 42] \quad L_4 = 16\%$ 

Given:

$$m{\lambda}^{({
m start})} = [1, 1, 0, 100] \qquad L_{{
m start}} = 20\% \ m{\lambda}^{({
m end})} = [0.98, 2.42, 1, 42] \qquad L_{{
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1st Iteration:

$$\lambda^{(1)} = [0.98, 1, 0, 100] \quad L_1 = 19\%$$
 $\lambda^{(2)} = [1, 2.42, 0, 100] \quad L_2 = 20\%$ 
 $\lambda^{(3)} = [1, 1, 1, 100] \quad L_3 = 7\%$ 
 $\lambda^{(4)} = [1, 1, 0, 42] \quad L_4 = 16\%$ 

 $\rightsquigarrow$  1st step:  $\lambda_2$  – flipping hyperparameter 3

Given:

$$m{\lambda}^{( ext{start})} = [1, 1, 0, 100] \qquad L_{ ext{start}} = 20\% \ m{\lambda}^{(s1)} = [1, 1, 1, 100] \qquad L = 7\% \ m{\lambda}^{( ext{end})} = [0.98, 2.42, 1, 42] \qquad L_{ ext{end}} = 4\%$$

2nd Iteration:

$$\boldsymbol{\lambda}^{(1)} = [0.98, 1, 1, 100] \quad L_1 = 6\%$$

Given:

$$m{\lambda}^{( ext{start})} = [1, 1, 0, 100] \qquad L_{ ext{start}} = 20\% \ m{\lambda}^{(s1)} = [1, 1, 1, 100] \qquad L = 7\% \ m{\lambda}^{( ext{end})} = [0.98, 2.42, 1, 42] \qquad L_{ ext{end}} = 4\%$$

2nd Iteration:

$$\lambda^{(1)} = [0.98, 1, 1, 100]$$
  $L_1 = 6\%$   
 $\lambda^{(2)} = [1, 2.42, 1, 100]$   $L_2 = 7\%$ 

Given:

$$\begin{array}{lll} \pmb{\lambda}^{(\mathsf{start})} &= [1, 1, 0, 100] & L_{\mathsf{start}} = 20\% \\ \pmb{\lambda}^{(s1)} &= [1, 1, 1, 100] & L = 7\% \\ \pmb{\lambda}^{(\mathsf{end})} &= [0.98, 2.42, 1, 42] & L_{\mathsf{end}} = 4\% \\ \end{array}$$

2nd Iteration:

$$\lambda^{(1)} = [0.98, 1, 1, 100]$$
  $L_1 = 6\%$   
 $\lambda^{(2)} = [1, 2.42, 1, 100]$   $L_2 = 7\%$   
 $\lambda^{(3)} = [1, 1, 1, 42]$   $L_3 = 5\%$ 

 $\rightsquigarrow$  2nd step:  $\lambda_3$  – flipping hyperparameter 4

Given:

$$\begin{array}{lll} \pmb{\lambda}^{(\mathsf{start})} &= [1, 1, 0, 100] & L_{\mathsf{start}} = 20\% \\ \pmb{\lambda}^{(s1)} &= [1, 1, 1, 100] & L = 7\% \\ \pmb{\lambda}^{(s2)} &= [1, 1, 1, 42] & L = 5\% \\ \pmb{\lambda}^{(\mathsf{end})} &= [0.98, 2.42, 1, 42] & L_{\mathsf{end}} = 4\% \\ \end{array}$$

3rd Iteration:

$$\lambda^{(1)} = [0.98, 1, 1, 100]$$
  $L_1 = 4\%$   
 $\lambda^{(2)} = [1, 2.42, 1, 100]$   $L_2 = 5\%$ 

 $\rightsquigarrow$  2nd step:  $\lambda_3$  – flipping hyperparameter 1

#### Ablation Path:

$$\begin{split} \pmb{\lambda}^{(\mathsf{start})} &= [1, 1, 0, 100] & L_{\mathsf{start}} = 20\% \\ \pmb{\lambda}^{(s1)} &= [1, 1, 1, 100] & L = 7\% \\ \pmb{\lambda}^{(s1)} &= [1, 1, 1, 42] & L = 5\% \\ \pmb{\lambda}^{(s3)} &= [0.98, 1, 1, 42] & L = 4\% \\ \pmb{\lambda}^{(s4)} &= [0.98, 2.42, 1, 42] & L = 4\% \\ \pmb{\lambda}^{(\mathsf{end})} &= [0.98, 2.42, 1, 42] & L_{\mathsf{end}} = 4\% \end{split}$$

#### **Algorithm 1** Greedy Ablation

**Input**: Algorithm  $\mathcal{A}$  with configuration space  $\Lambda$ , start configuration  $\lambda^{(\text{start})}$ . end configuration  $\lambda^{(end)}$  cost metric c

$$\lambda \leftarrow \lambda^{(\text{start})};$$
 $P \leftarrow [];$ 

#### Algorithm 2 Greedy Ablation

**Input**: Algorithm  $\mathcal A$  with configuration space  $\mathbf \Lambda$ , start configuration  $\mathbf \lambda^{(\mathsf{start})}$ , end configuration  $\mathbf \lambda^{(\mathsf{end})}$ , cost metric c

```
oldsymbol{\lambda} \leftarrow oldsymbol{\lambda}^{(\mathsf{start})}; \ P \leftarrow [] \ ; \ \mathbf{foreach} \ t \in \{1 \dots |oldsymbol{\Lambda}|\} \ \mathbf{do}
```

#### **Algorithm 3** Greedy Ablation

**Input**: Algorithm  $\mathcal A$  with configuration space  $\mathbf \Lambda$ , start configuration  $\mathbf \lambda^{(\mathsf{start})}$ , end configuration  $\mathbf \lambda^{(\mathsf{end})}$ , cost metric c

```
\begin{split} \boldsymbol{\lambda} &\leftarrow \boldsymbol{\lambda}^{(\mathsf{start})}; \\ P &\leftarrow [] \ ; \\ \textbf{foreach} \ t \in \{1 \dots |\boldsymbol{\Lambda}|\} \ \textbf{do} \\ & \begin{vmatrix} \boldsymbol{\lambda}_{\delta}' \leftarrow \mathsf{apply} \ \delta \ \mathsf{to} \ \boldsymbol{\lambda}; \\ \mathsf{evaluate} \ c(\boldsymbol{\lambda}_{\delta}'); \end{vmatrix} \end{split}
```

#### **Algorithm 4** Greedy Ablation

```
Input: Algorithm \mathcal A with configuration space \pmb \Lambda, start configuration \pmb \lambda^{(\mathsf{start})} end configuration \pmb \lambda^{(\mathsf{end})}, cost metric c
```

```
\lambda \leftarrow \lambda^{(\text{start})}:
   P \leftarrow []:
   foreach t \in \{1 \dots |\Lambda|\} do
        foreach \delta \in \Delta(\lambda, \lambda^{(end)}) do
                \lambda'_{\delta} \leftarrow \text{apply } \delta \text{ to } \lambda;
                 evaluate c(\lambda'_{\delta});
         Determine most important change \delta^* \in \arg\min_{\delta \in \Delta(\boldsymbol{\lambda}, \boldsymbol{\lambda}^{(\text{end})})} c(\boldsymbol{\lambda}_{\delta});
           \lambda \leftarrow \text{apply } \delta^* \text{ to } \lambda:
            P.append(\delta^*):
```

#### **Algorithm 5** Greedy Ablation

```
Input: Algorithm {\mathcal A} with configuration space {\mathbf \Lambda}, start configuration {\mathbf \lambda}^{(\mathsf{start})}
              end configuration \lambda^{(end)}, cost metric c
```

```
\lambda \leftarrow \lambda^{(\text{start})}:
   P \leftarrow []:
   foreach t \in \{1 \dots |\Lambda|\} do
         foreach \delta \in \Delta(\lambda, \lambda^{(end)}) do
                \lambda'_{\delta} \leftarrow \text{apply } \delta \text{ to } \lambda;
             evaluate c(\lambda'_{\delta});
         Determine most important change \delta^* \in \arg\min_{\delta \in \Delta(\boldsymbol{\lambda}, \boldsymbol{\lambda}^{(\text{end})})} c(\boldsymbol{\lambda}_{\delta});
           \lambda \leftarrow \text{apply } \delta^* \text{ to } \lambda:
            P.append(\delta^*):
```

return Ablation path P

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  [Biedenkapp et al. 2017]
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    - Often only a few of the hyperparameters have an big impact
    - You have plateaus in your ablation path because of interaction effects