

AutoML: Dynamic Configuration & Learning

Population-based Training

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 - What if we don't access to such an env or don't have to time for offline learning?
- ~> Try to figure out best hyperparameter settings on the fly

Massively parallelized Random Search

$\lambda^{(1)}$

$\lambda^{(2)}$

$\lambda^{(3)}$

$\lambda^{(4)}$

t

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Population-based Training [Jaderberg et al. 2017]

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$\lambda^{(2)}$

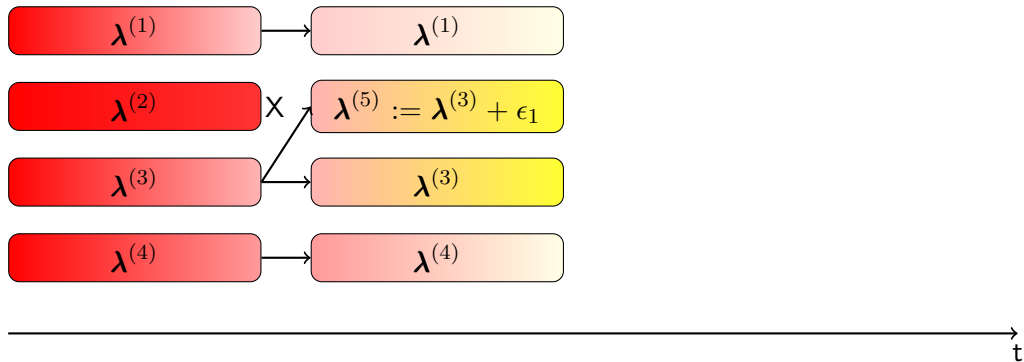
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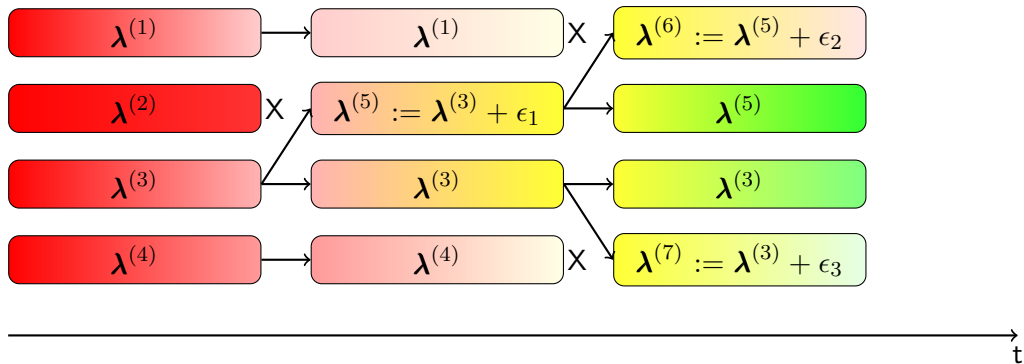
- The color indicates the performance over time

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- 1 Sample initial population
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- PBT returns an already trained model (e.g., DNN or RL policy)
- PBT uses evolutionary computing to determine well-performing hyperparameter settings
- Since hyperparameter settings changes while training the models, PBT relates to dynamic algorithm configuration
- Since each population member (i.e., model) can be trained independently, PBT can be efficiently parallelized
 - ↪ Drawback: requires substantial parallel compute resources

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- Idea: Can we use BO to guide PBT?
- ~> Less parallel compute resources are required(?)
- ~> Scales better to higher dimensional spaces(?)

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 - ▶ Each population member is a combination of hyperparameter setting λ and (partially trained) model
- ❷ Train population for a bit
- ❸ Tournament selection to drop poorly performing population members
- ❹ Use [Bayesian optimization](#) to select new hyperparameter settings
 - ▶ Change the hyperparameter settings, but inherits the partially trained model (+ perturbation)
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- Several ideas on how to parallelize BO
 - ▶ Randomize the model training or optimization of the acquisition function
 - ▶ Thompson sampling to use only a single explanation of the data (in proportion to its likelihood)
 - ▶ Hallucinate performance of other hyperparameter settings in optimistically, pessimistically or in expectation of the current surrogate model

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- BO-Surrogate model predicts the cost improvement over time:

$$c_{\text{PBT}}^{(t)}(\lambda) = \frac{c^{(t)}(\lambda) - c^{(t-1)}(\lambda)}{\Delta t}$$

where $c^{(t)}(\lambda)$ is the cost for a given hyperparameter setting at time step t .

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- Remark: Also add $c^{(t-1)}$ as an input to the BO-surrogate model to ease the task of predicting the improvement