

# Chapter 5: Tree

## Part II

---

Department of Computer Science and Engineering  
Kathmandu University

# Contents

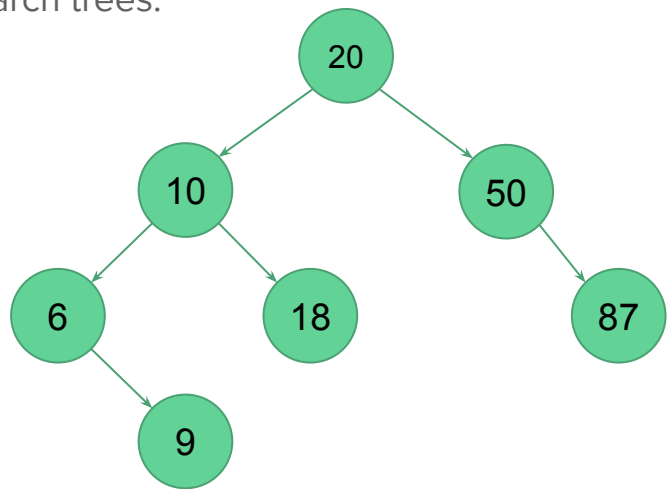
- Concept and definition
  - Basic terminologies
  - Tree representation
  - Binary tree
    - Definition
    - Types
    - Representation
    - Traversal
  - Applications of Binary Trees
    - Binary Search Tree
    - Heap
    - Huffman coding
-

# Binary search tree

---

# Binary Search Tree

- A binary search tree (BST) is a binary tree that is either empty or (in which each node contains a key that) satisfies the following properties.
  - The keys (if any) in left sub-tree are smaller than the key in the root.
  - The keys (if any) in the right subtree are larger than the key in the root.
  - The left and right subtrees are also binary search trees.



# Binary Search Tree

- A BST has a better performance than any of the data structures studied so far when the functions to be performed are search, insert and delete.
- BSTs are used in many search applications where data is constantly entering/leaving, such as the map (or dictionary) and set objects in many languages' libraries.

# Binary Search Tree Operations

1. Searching a BST
  - a. Find the smallest node
  - b. Find the largest node
  - c. Find a requested node
2. Insertion
3. Deletion

# Finding the smallest node

The main idea is to follow the left branches until we get to a leaf. The smallest node is the far-left node in the tree.

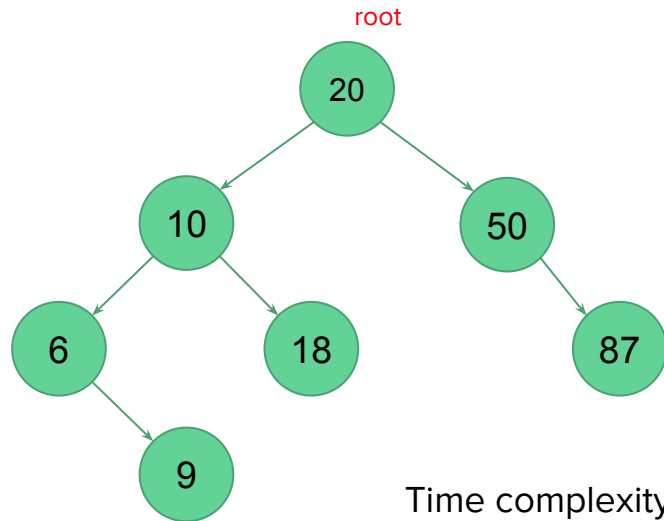
**Algorithm:** Find the smallest node in a BST

**Input:** A BST, T(root)

**Output:** The smallest node in T

**Steps:**

1. If left subtree is empty  
    return root
2. End if
3. smallest = find smallest node in the left subtree
4. return smallest



# Finding the smallest node

The main idea is to follow the left branches until we get to a leaf. The smallest node is the far-left node in the tree.

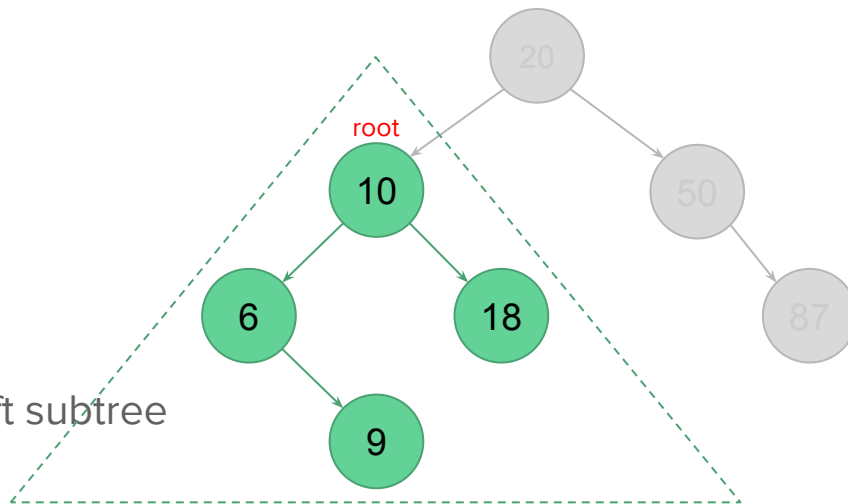
**Algorithm:** Find the smallest node in a BST

**Input:** A BST, T(root)

**Output:** The smallest node in T

**Steps:**

1. If left subtree is empty  
    return root
2. End if
3. smallest = find smallest node in the left subtree
4. return smallest



Time complexity = ?



# Finding the smallest node

The main idea is to follow the left branches until we get to a leaf. The smallest node is the far-left node in the tree.

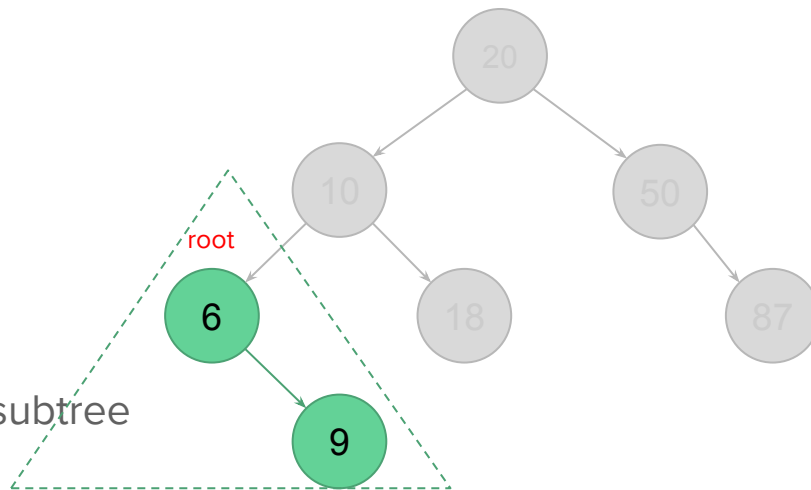
**Algorithm:** Find the smallest node in a BST

**Input:** A BST, T(root)

**Output:** The smallest node in T

**Steps:**

1. If left subtree is empty  
    return root
2. End if
3. smallest = find smallest node in the left subtree
4. return smallest



Time complexity = ?

# Finding the largest node

The largest node is the far-right node in the tree. Follow the right branches until we get to a leaf.

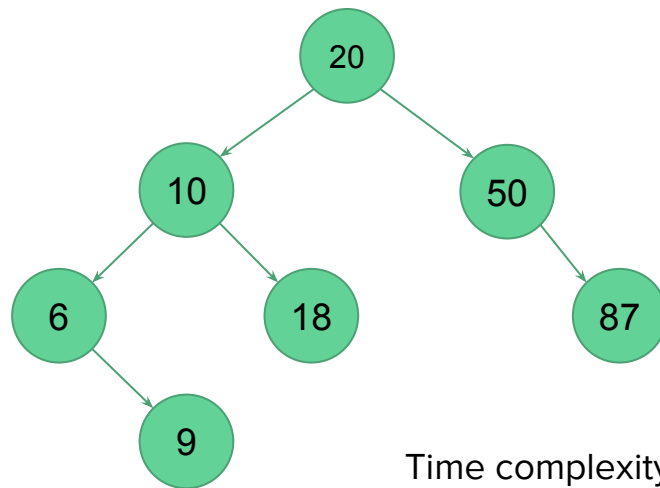
**Algorithm:** Find the largest node in a BST

**Input:** A BST, T(root)

**Output:** The largest node in T

**Steps:**

1. If right subtree is empty  
    return root
2. End if
3. largest = find smallest node in the right subtree
4. return largest



Time complexity = ?

# Finding a requested node (recursive)

**Algorithm:** searchBST (root, targetKey)

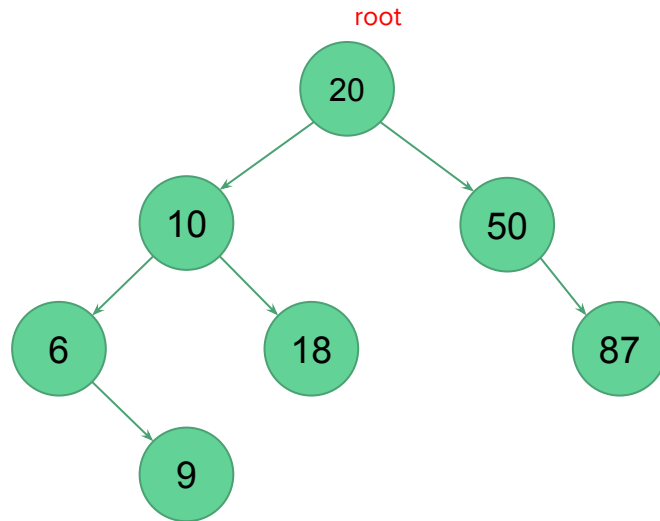
**Description:** Search a BST,  $T(\text{root})$  for the requested key targetKey

**Input:**  $T(\text{root})$ , targetKey

**Output:** The requested key

**Steps:**

1. If T is empty  
    return null
2. endif
3. If targetKey < root->key  
    return searchBST(left subtree, targetKey)
4. else if targetKey > root->key  
    return searchBST(right subtree, targetKey)
5. else  
    return root
6. endif



# Finding a requested node (recursive)

**Algorithm:** searchBST (root, targetKey)

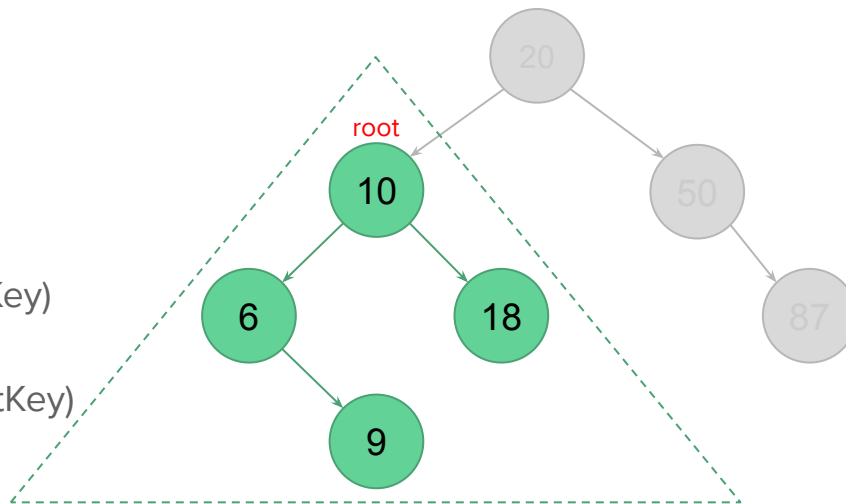
**Description:** Search a BST,  $T(\text{root})$  for the requested key targetKey

**Input:**  $T(\text{root})$ , targetKey

**Output:** The requested key

**Steps:**

1. If T is empty  
    return null
2. endif
3. If targetKey < root->key  
    return searchBST(left subtree, targetKey)
4. else if targetKey > root->key  
    return searchBST(right subtree, targetKey)
5. else  
    return root
6. endif



# Finding a requested node (iterative)

**Algorithm:** searchBST (root, targetKey)

**Description:** Search a BST,  $T(\text{root})$  for the requested key targetKey

**Input:**  $T(\text{root})$ , targetKey

**Output:** The requested key

**Steps:**

1. temp = root
2. while (temp != null)
  - a. If temp->key == targetKey
    - i. return temp
  - b. else if temp->key > targetKey
    - i. temp = temp->leftChild
  - c. else
    - i. temp = temp->rightChild
3. End while
4. return null

Time complexity = ?

# Inserting a node into a BST

All BST insertions take place at a leaf or a leaf-like node (i.e. a node that has only one null subtree).

Example:

Insert the following sequence of keys in an empty BST:

34, 56, 23, 44, 19, 77, 60, 33, 20

# Inserting a node into a BST

All BST insertions take place at a leaf or a leaf-like node (i.e. a node that has only one null subtree).

Example:

Insert the following sequence of keys in an empty BST:

34, 56, 23, 44, 19, 77, 60, 33, 20

34

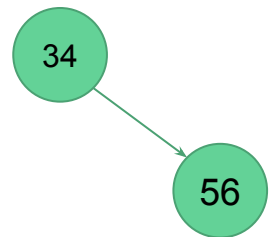
# Inserting a node into a BST

All BST insertions take place at a leaf or a leaf-like node (i.e. a node that has only one null subtree).

Example:

Insert the following sequence of keys in an empty BST:

34, 56, 23, 44, 19, 77, 60, 33, 20





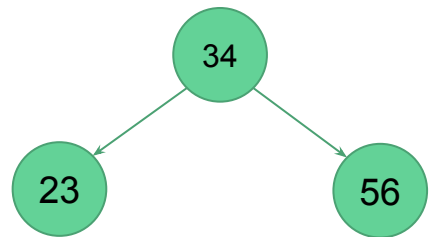
# Inserting a node into a BST

All BST insertions take place at a leaf or a leaf-like node (i.e. a node that has only one null subtree).

Example:

Insert the following sequence of keys in an empty BST:

34, 56, 23, 44, 19, 77, 60, 33, 20



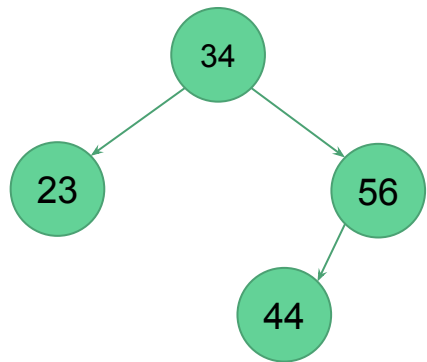
# Inserting a node into a BST

All BST insertions take place at a leaf or a leaf-like node (i.e. a node that has only one null subtree).

Example:

Insert the following sequence of keys in an empty BST:

34, 56, 23, 44, 19, 77, 60, 33, 20



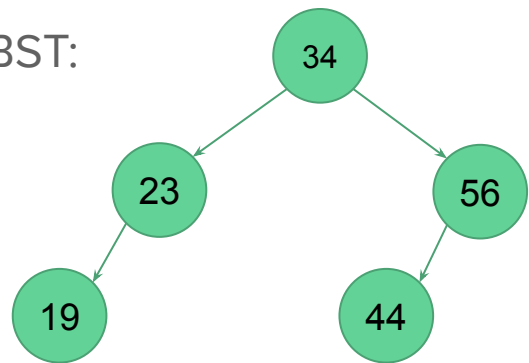
# Inserting a node into a BST

All BST insertions take place at a leaf or a leaf-like node (i.e. a node that has only one null subtree).

Example:

Insert the following sequence of keys in an empty BST:

34, 56, 23, 44, 19, 77, 60, 33, 20



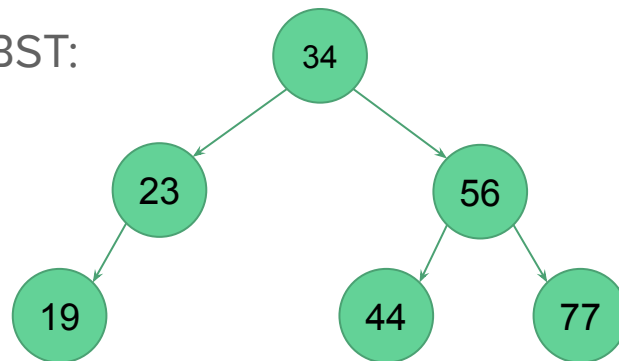
# Inserting a node into a BST

All BST insertions take place at a leaf or a leaf-like node (i.e. a node that has only one null subtree).

Example:

Insert the following sequence of keys in an empty BST:

34, 56, 23, 44, 19, 77, 60, 33, 20



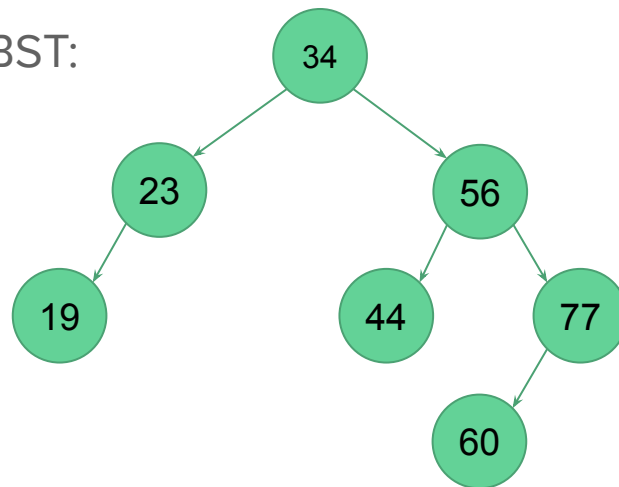
# Inserting a node into a BST

All BST insertions take place at a leaf or a leaf-like node (i.e. a node that has only one null subtree).

Example:

Insert the following sequence of keys in an empty BST:

34, 56, 23, 44, 19, 77, 60, 33, 20



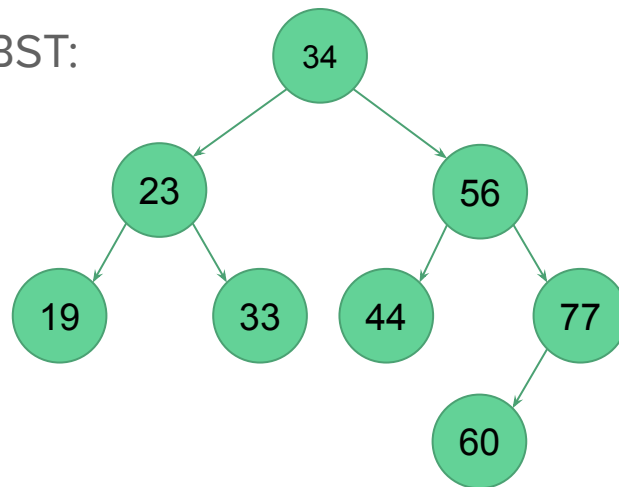
# Inserting a node into a BST

All BST insertions take place at a leaf or a leaf-like node (i.e. a node that has only one null subtree).

Example:

Insert the following sequence of keys in an empty BST:

34, 56, 23, 44, 19, 77, 60, 33, 20



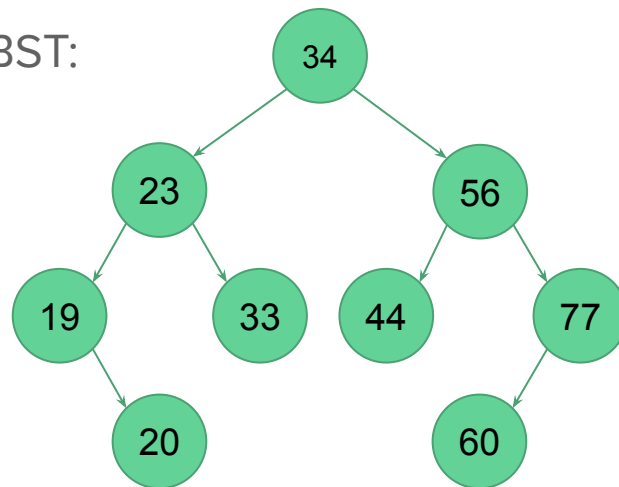
# Inserting a node into a BST

All BST insertions take place at a leaf or a leaf-like node (i.e. a node that has only one null subtree).

Example:

Insert the following sequence of keys in an empty BST:

34, 56, 23, 44, 19, 77, 60, 33, 20



# Inserting a node into a BST

**Algorithm:** addBST(root, newNode)

**Description:** Add a node into a BST

**Input:** A BST T(root), newNode

**Output:** Address of potential new tree root

**Steps:**

1. If T is empty (i.e. root is null)
  - 1.1. set root to newNode
  - 1.2. return newNode
2. endif
3. If newNode->key < root->key
  - 3.1. return addBST (left subtree, newNode)
4. else
  - 4.1. return addBST (right subtree, newNode )
5. endif

Time complexity = ?



# Deleting a node from a BST

3 cases:

**Case 1:** The node to be deleted has no child

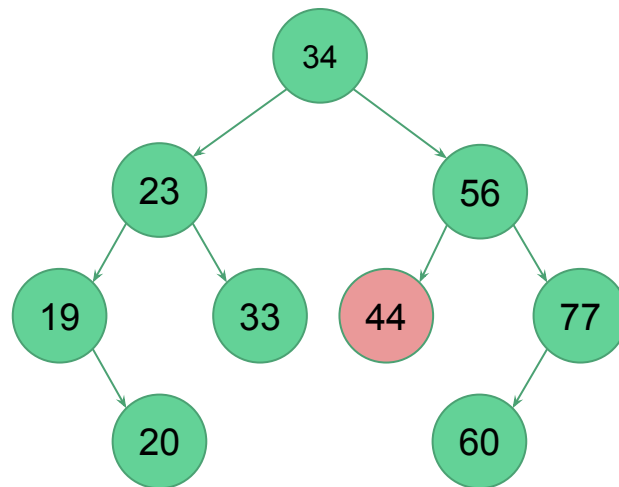
**Case 2:** The node to be deleted has only one child

**Case 3:** The node to be deleted has two subtrees

# Deleting a node from a BST

## Case 1: The node to be deleted has no child

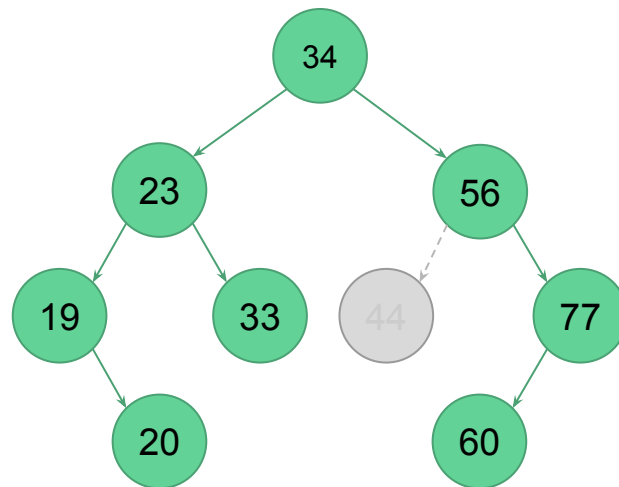
- Just delete the node



# Deleting a node from a BST

## Case 1: The node to be deleted has no child

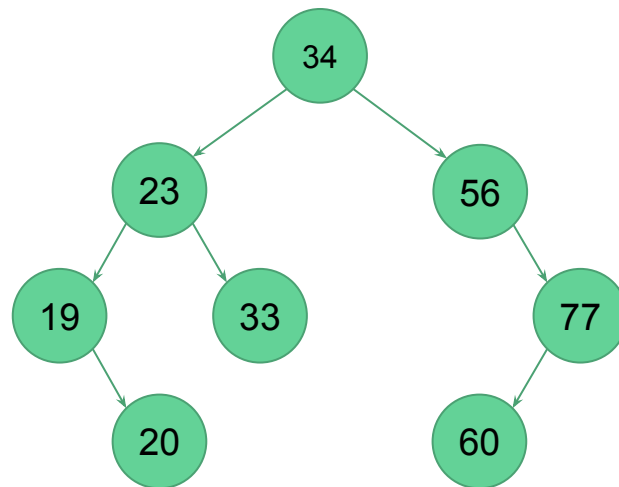
- Just delete the node



# Deleting a node from a BST

## Case 1: The node to be deleted has no child

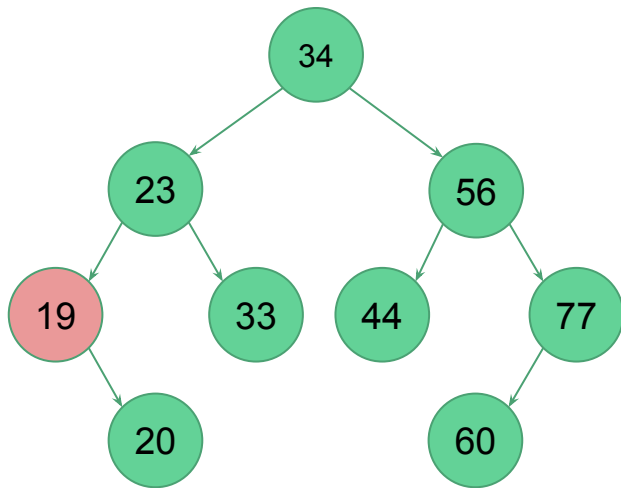
- Just delete the node



# Deleting a node from a BST

## Case 2: The node to be deleted has only one child

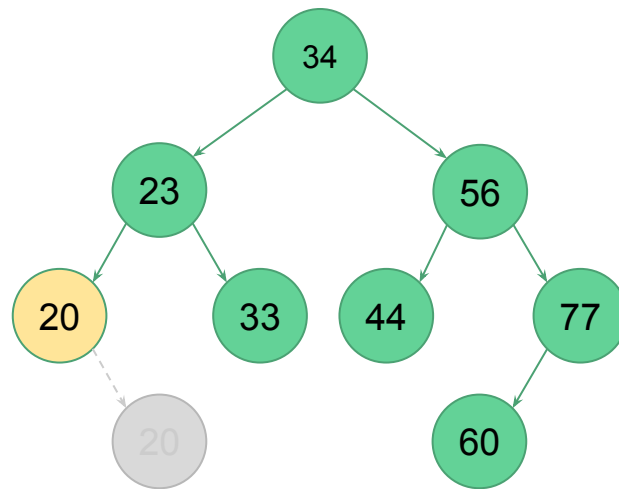
- If the node to be deleted has only a right subtree, then delete the node and attach the right subtree to the deleted node's parent
- If the node to be deleted has only a left subtree, delete the node and attach the left subtree to the deleted node's parent



# Deleting a node from a BST

## Case 2: The node to be deleted has only one child

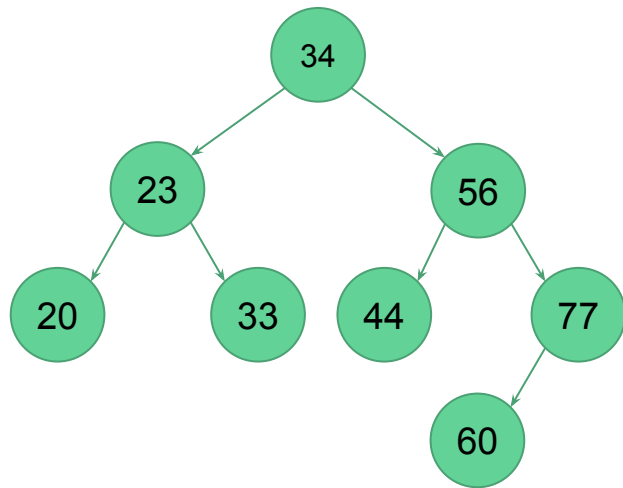
- If the node to be deleted has only a right subtree, then delete the node and attach the right subtree to the deleted node's parent
- If the node to be deleted has only a left subtree, delete the node and attach the left subtree to the deleted node's parent



# Deleting a node from a BST

## Case 2: The node to be deleted has only one child

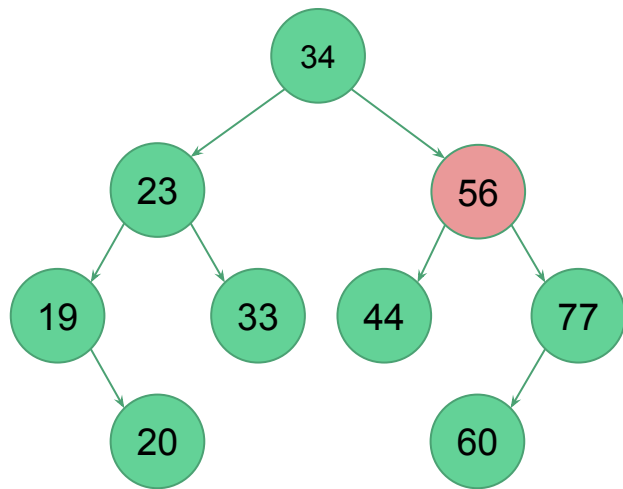
- If the node to be deleted has only a right subtree, then delete the node and attach the right subtree to the deleted node's parent
- If the node to be deleted has only a left subtree, delete the node and attach the left subtree to the deleted node's parent



# Deleting a node from a BST

## Case 3: The node to be deleted has two subtrees

- Find the largest node in the deleted node's left subtree and move its data to replace the deleted node's data, **or**
- Find the smallest node in the deleted node's right subtree and move its data to replace the deleted node's data

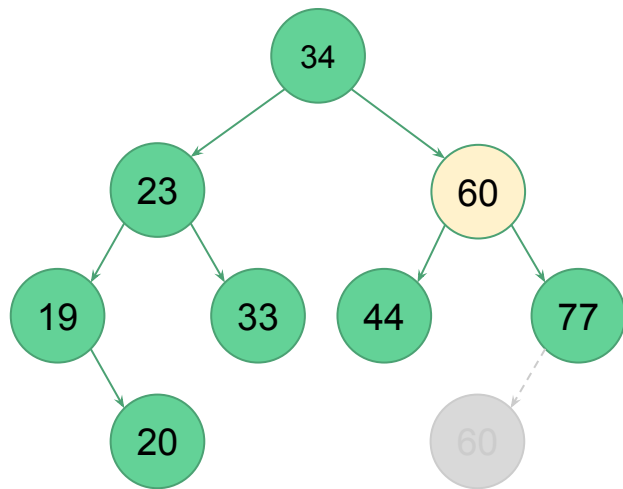




# Deleting a node from a BST

## Case 3: The node to be deleted has two subtrees

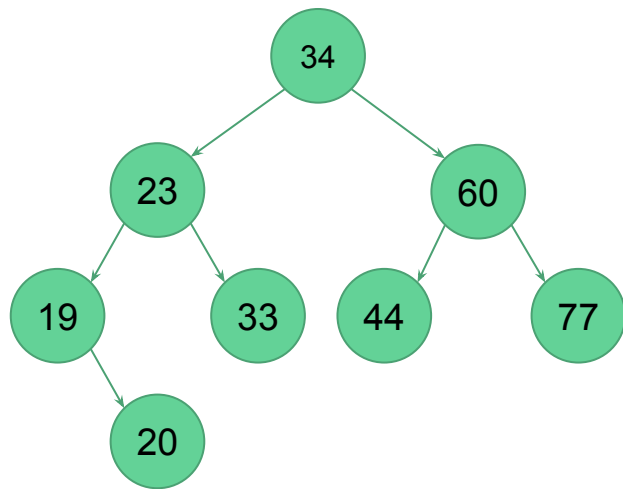
- Find the largest node in the deleted node's left subtree and move its data to replace the deleted node's data, **or**
- Find the smallest node in the deleted node's right subtree and move its data to replace the deleted node's data



# Deleting a node from a BST

## Case 3: The node to be deleted has two subtrees

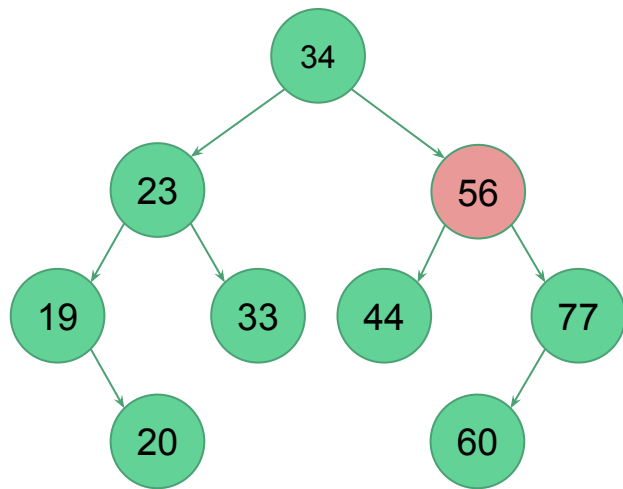
- Find the largest node in the deleted node's left subtree and move its data to replace the deleted node's data, **or**
- Find the smallest node in the deleted node's right subtree and move its data to replace the deleted node's data



# Deleting a node from a BST

## Case 3: The node to be deleted has two subtrees

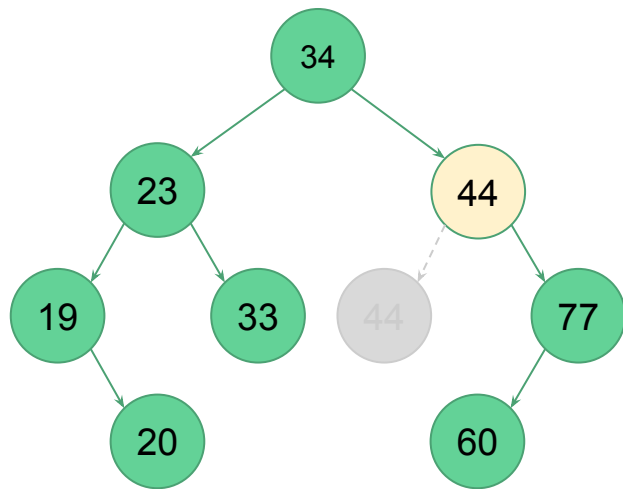
- Find the largest node in the deleted node's left subtree and move its data to replace the deleted node's data, **or**
- Find the smallest node in the deleted node's right subtree and move its data to replace the deleted node's data



# Deleting a node from a BST

## Case 3: The node to be deleted has two subtrees

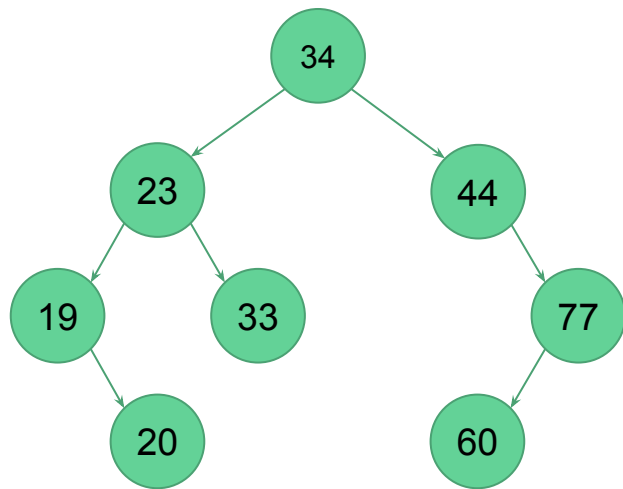
- Find the largest node in the deleted node's left subtree and move its data to replace the deleted node's data, **or**
- Find the smallest node in the deleted node's right subtree and move its data to replace the deleted node's data



# Deleting a node from a BST

## Case 3: The node to be deleted has two subtrees

- Find the largest node in the deleted node's left subtree and move its data to replace the deleted node's data, **or**
- Find the smallest node in the deleted node's right subtree and move its data to replace the deleted node's data



# Deleting a node from a BST

**Desc:** Delete a node from BST

**Input:** A BST, T(root), a key to delete, dltKey

**Output:** true if the node is deleted false if not

**Steps:**

1. if the tree is empty, then return false
2. if dltkey < root->key
  - 2.1. return deleteBST (left subtree, dltkey)
3. else if dltkey > root->key
  - 3.1. return delete BST (right subtree, dltKey)
4. else
  - 4.1. If no left subtree
    - 4.1.1. make right subtree the root
    - 4.1.2. return true
  - 4.2. else if no right subtree
    - 4.2.1. make left subtree the root
    - 4.2.2. return true

- 1.3. else
  - 1.3.1. nodeToDelete = root
  - 1.3.2. largest = largest node in left subtree
  - 1.3.3. move data in largest to nodeToDelete
  - 1.3.4. return deleteBST (left subtree of nodeToDelete, key of largest)
- 1.4. endif
5. endif

Time complexity = ?

# Complexity of BST operations

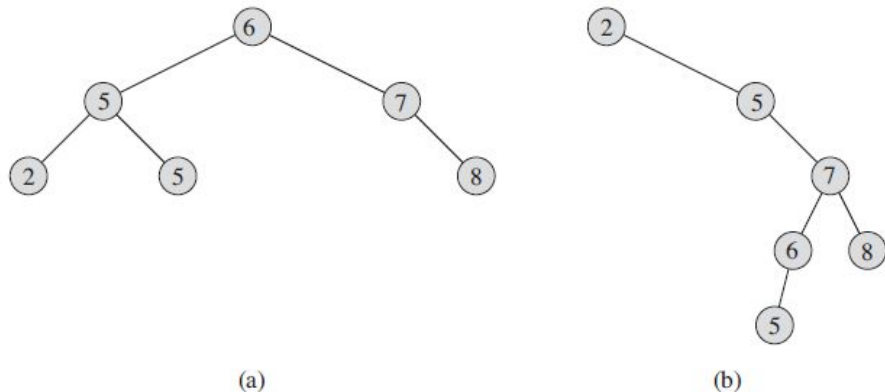
Searching, insertion, and deletion in a binary search tree of height  $h$  run in  $O(h)$  time.

These operations are fast if the height of the search tree is small

If its height is large, they may run no faster than with a linked list.

In the worst case (max. height),  
 $h = n - 1$

In the best case (min. height),  
 $h = \lfloor \log_2 n \rfloor$



**Figure 12.1** Binary search trees. For any node  $x$ , the keys in the left subtree of  $x$  are at most  $x.key$ , and the keys in the right subtree of  $x$  are at least  $x.key$ . Different binary search trees can represent the same set of values. The worst-case running time for most search-tree operations is proportional to the height of the tree. (a) A binary search tree on 6 nodes with height 2. (b) A less efficient binary search tree with height 4 that contains the same keys.

# AVL Search Tree

- An AVL tree is a balanced binary search tree, i.e. a binary tree that is either empty or consists of two AVL subtrees whose heights differ by no more than 1.
- It is named after its two Soviet inventors, Georgy **A**delson-**V**elsky and Evgenii Landis.
- Whenever we insert a node into a tree or delete a node from a tree, the resulting tree may be unbalanced.
- When we detect that a tree is unbalanced we rebalance it.
- AVL trees are balanced by rotating node either to the left or to the right.



# Heaps

---

# Heaps

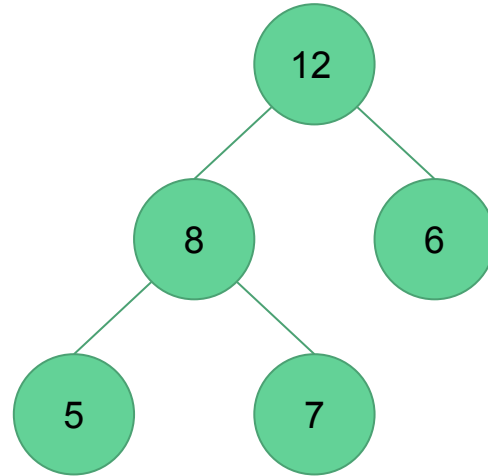
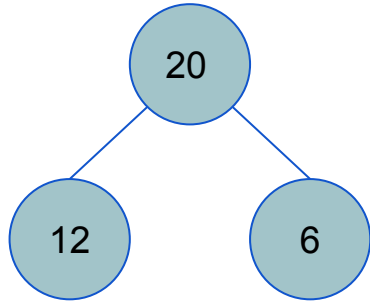
A heap is a binary tree with the following properties:

1. The tree is **complete or almost complete**
2. The key value of each node is **greater than or equal** to the key value in each of its descendants (in a **max-heap**)

*In a **min-heap**, the key value of each node is **smaller or equal** to the key value in each of its descendants*

# Heaps

## Examples



# Operations

- Find-max (or find-min)
- Insertion
- Deletion
- Increase-key or decrease-key

For these operations, we need two basic algorithms:

1. Reheap up
2. Reheap down

# Insertion into a heap

Like BST, insertion into a heap **takes place at a leaf** (or a leaf-like node)

Because the heap is a complete or nearly complete binary tree, the node must be placed in **the last leaf level at the first empty position**.

This might cause a situation where the new node's key is larger than that of its parent, i.e. **the heap structure is broken**.

The **reheap up** operation reorders a “broken” heap by **floating the last element up the tree** until it is in its correct location in the heap.

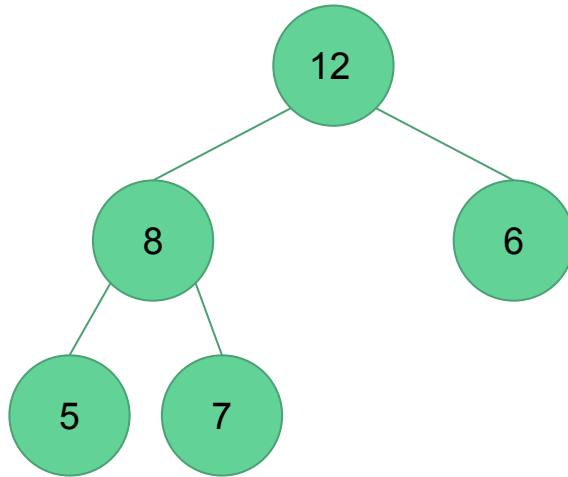
# Reheap up

The new node is floated up the tree by **exchanging the child and parent keys and data**

By repeatedly exchanging child/parent keys and data, the data will eventually rise to the correct place in the heap.

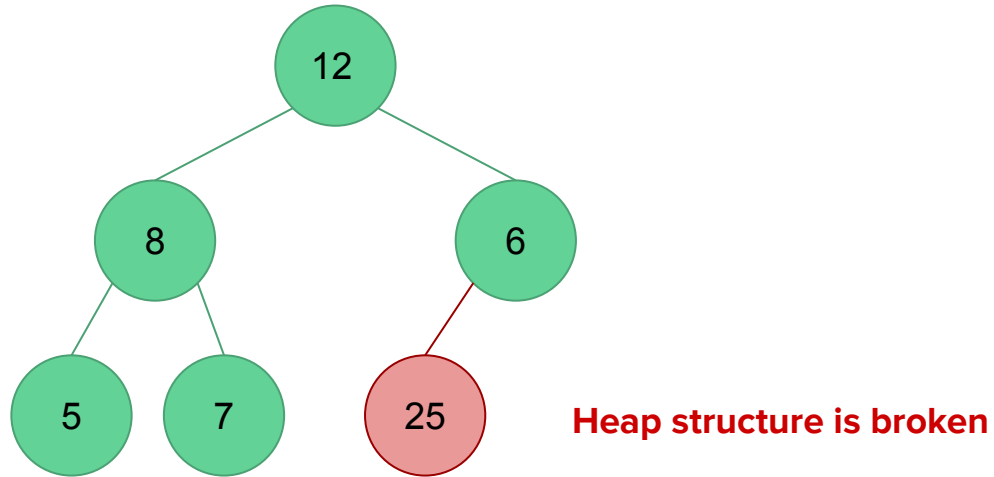
# Reheap up

Example: Insert 25 into this heap



# Reheap up

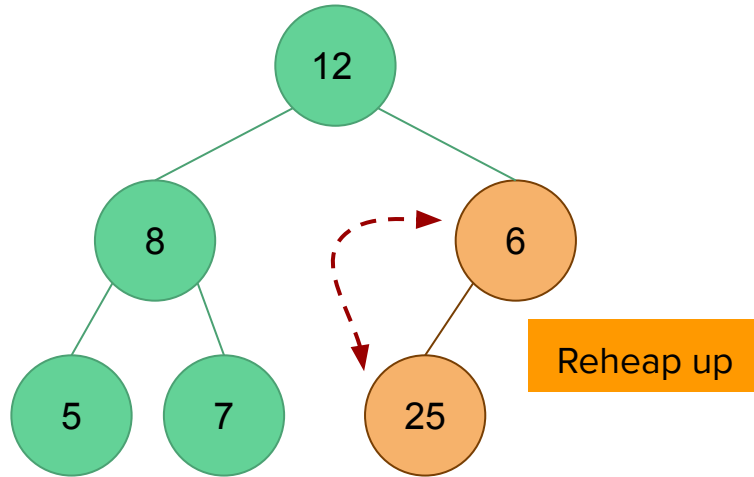
Example: Insert 25 into this heap





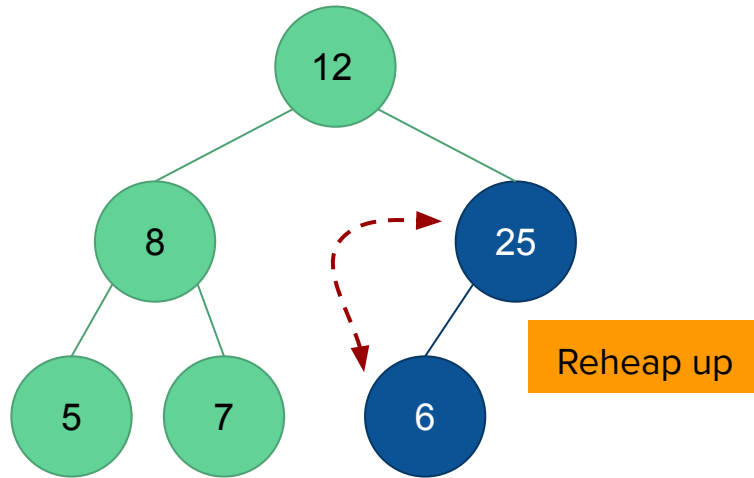
# Reheap up

Example: Insert 25 into this heap



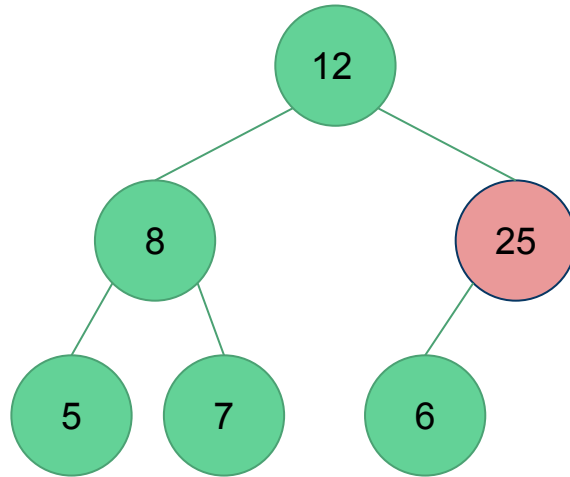
# Reheap up

Example: Insert 25 into this heap



# Reheap up

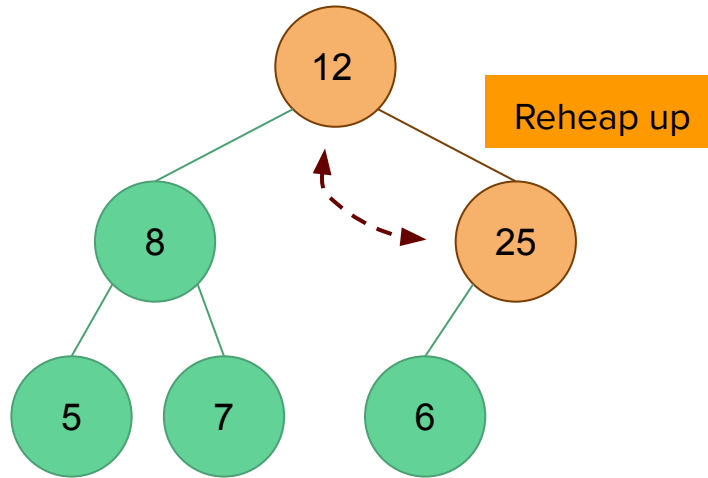
Example: Insert 25 into this heap



**Heap structure is broken**

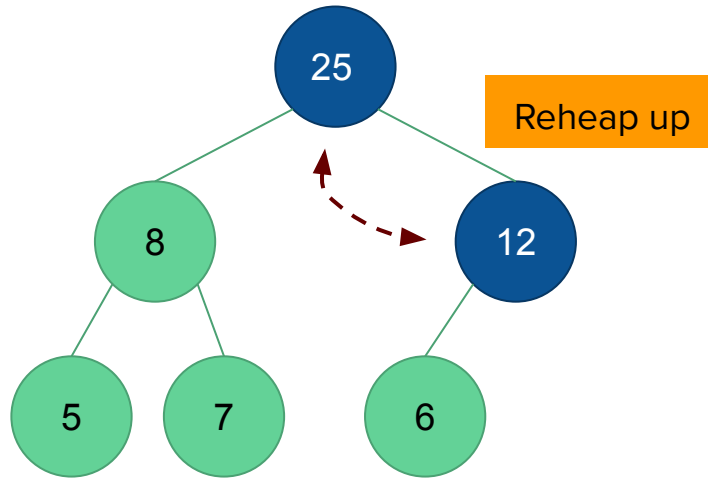
# Reheap up

Example: Insert 25 into this heap



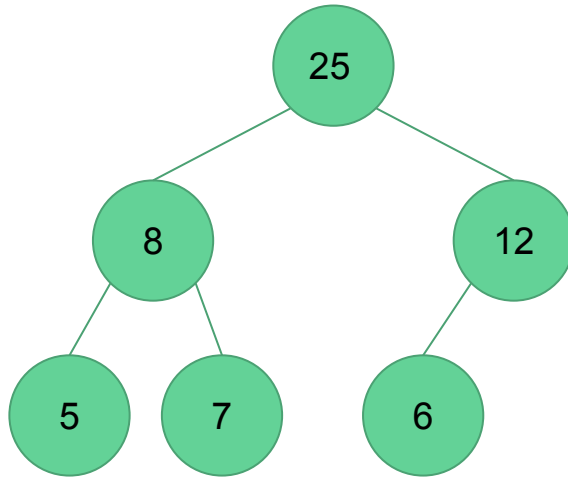
# Reheap up

Example: Insert 25 into this heap



# Reheap up

Example: Insert 25 into this heap



# Deletion in a heap

The standard deletion operation on heaps is to **delete the root node of the heap**.

Deleting the root of the heap leaves us with two disjoint trees.

To correct the situation, we **move the data in the last tree node to the root**.

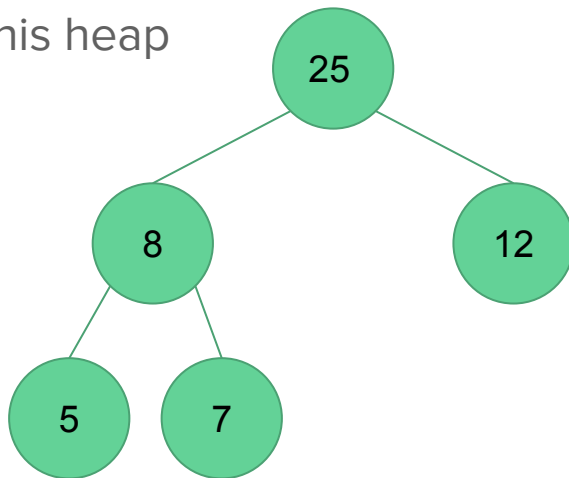
This destroys the tree's heap properties.

**Reheap down** operation reorders a “broken” heap by **pushing the root down the tree** until it is in its correct position in the heap.

# Reheap down

Starting from the root, select the larger of the two children and exchange with the parent.

**Example:** Delete the root from this heap

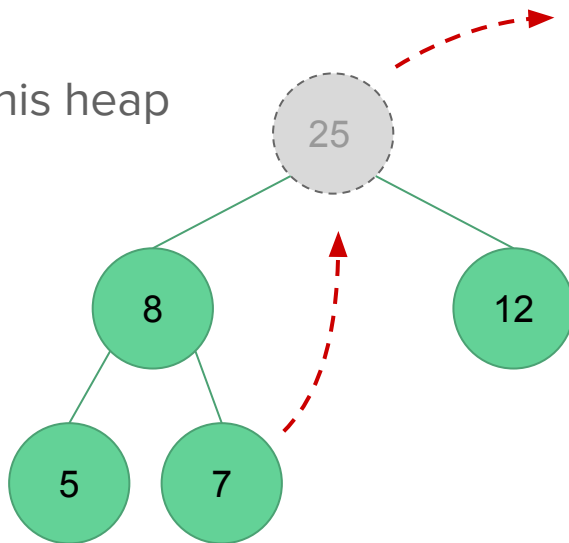




# Reheap down

Starting from the root, select the larger of the two children and exchange with the parent.

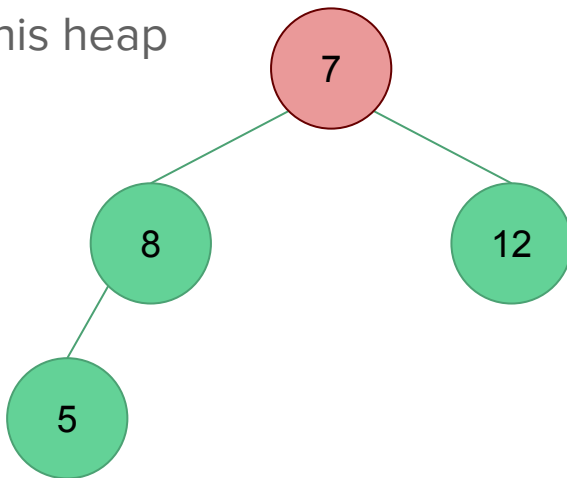
**Example:** Delete the root from this heap



# Reheap down

Starting from the root, select the larger of the two children and exchange with the parent.

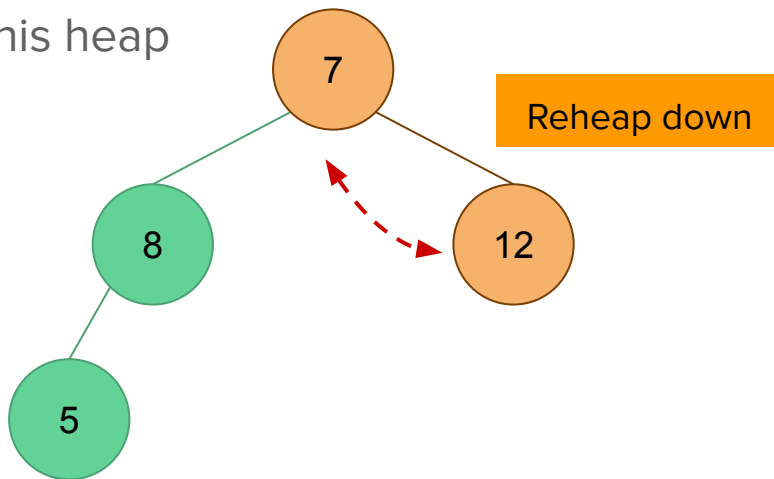
**Example:** Delete the root from this heap



# Reheap down

Starting from the root, select the larger of the two children and exchange with the parent.

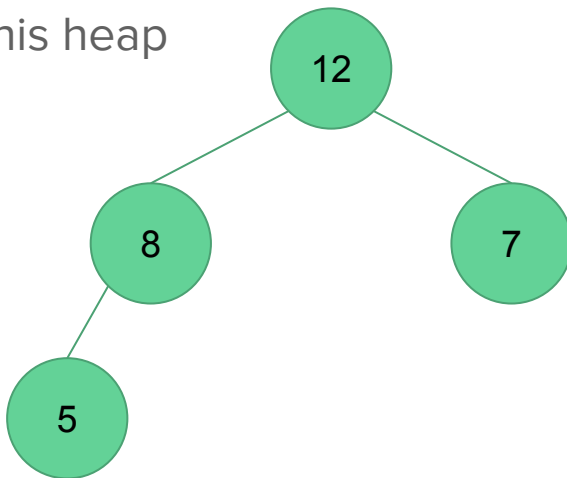
**Example:** Delete the root from this heap



# Reheap down

Starting from the root, select the larger of the two children and exchange with the parent.

**Example:** Delete the root from this heap



# Priority queue

Heaps can be used to implement **priority queues**.

A **priority queue** is a collection of elements such that each element has an associated priority and **the element to be deleted is the one with the highest (or lowest) priority**.

# Operations in a min (ascending) priority queue

Using a min-heap, we can implement an ascending priority queue with the following operations

1. Return an element with minimum priority
  - The minimum element can be found in  $O(1)$  time
2. Insert an element with an arbitrary priority
  - This can be done in  $O(\log n)$  time
3. Delete an element with minimum priority
  - This can be done in  $O(\log n)$  time

# Huffman coding

---

# Huffman coding

**Coding:** Assigning binary codewords to (blocks of) source symbols

**Huffman coding** is a lossless data compression algorithm.

**Idea:**

- Assign variable-length codes to input characters, based on the frequencies of corresponding characters.
- The most frequent character gets the smallest code and the least frequent character gets the largest code.



# Huffman coding

There are mainly two major parts in Huffman Coding

1. **Build a Huffman Tree** from input characters.
2. Traverse the Huffman Tree and **assign codes to characters**.

# Building a Huffman tree

1. Organize the entire character set into a row, **ordered according to frequency** from highest to lowest (or vice versa). **Each character is now a node at the leaf level of a tree**
2. **Find two nodes with the smallest combined frequency weights and join them to form a third node**, resulting in a simple two-level tree. The weight of the new node is the combined weights of the original two nodes.
3. **Repeat step 2** until all of the nodes, on every level, are combined into a single tree.

# Huffman coding example

Input character string: "**datastructures**"

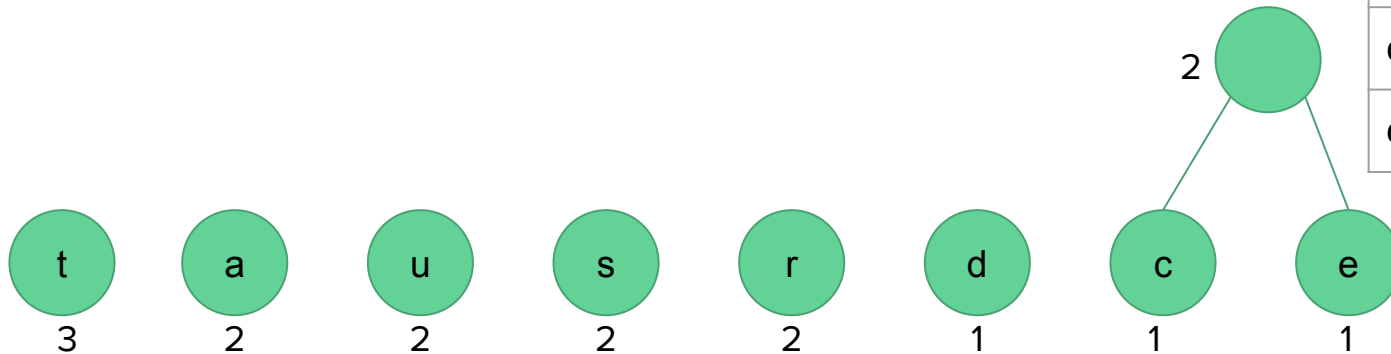
We first build the frequency table

character	frequency
t	3
a	2
u	2
s	2
r	2
d	1
c	1
e	1

# Huffman coding example

Build a Huffman tree:

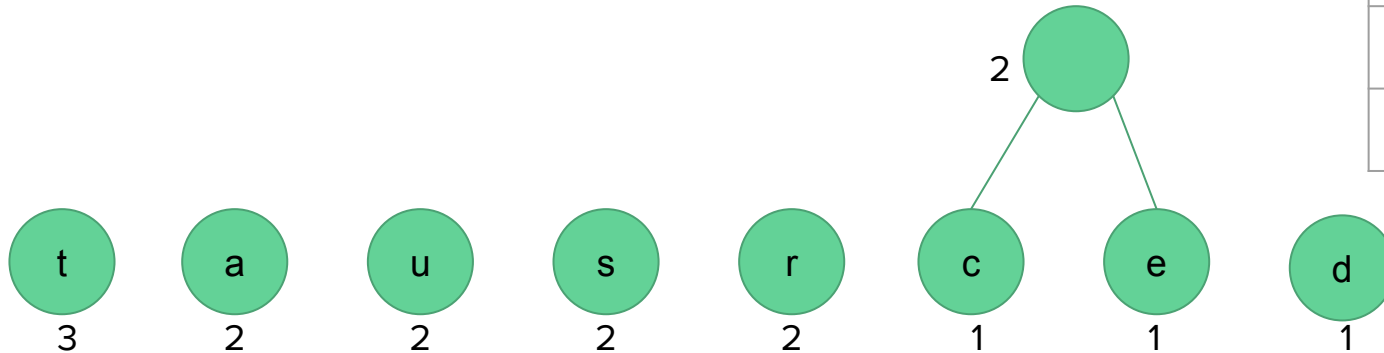
character	frequency
t	3
a	2
u	2
s	2
r	2
d	1
c	1
e	1



# Huffman coding example

Build a Huffman tree:

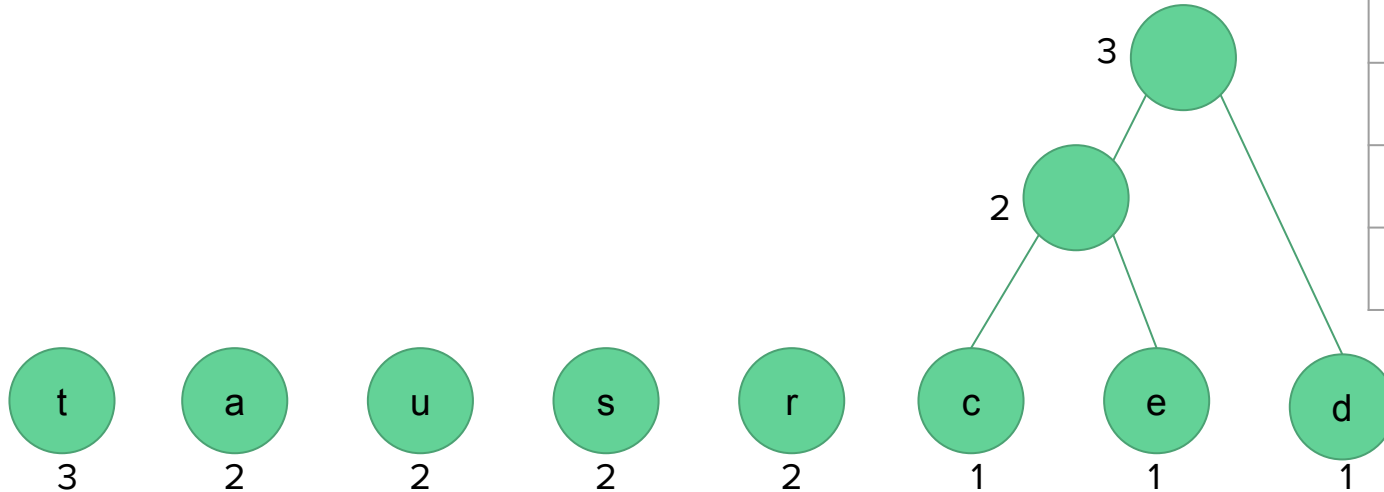
character	frequency
t	3
a	2
u	2
s	2
r	2
d	1
c	1
e	1



# Huffman coding example

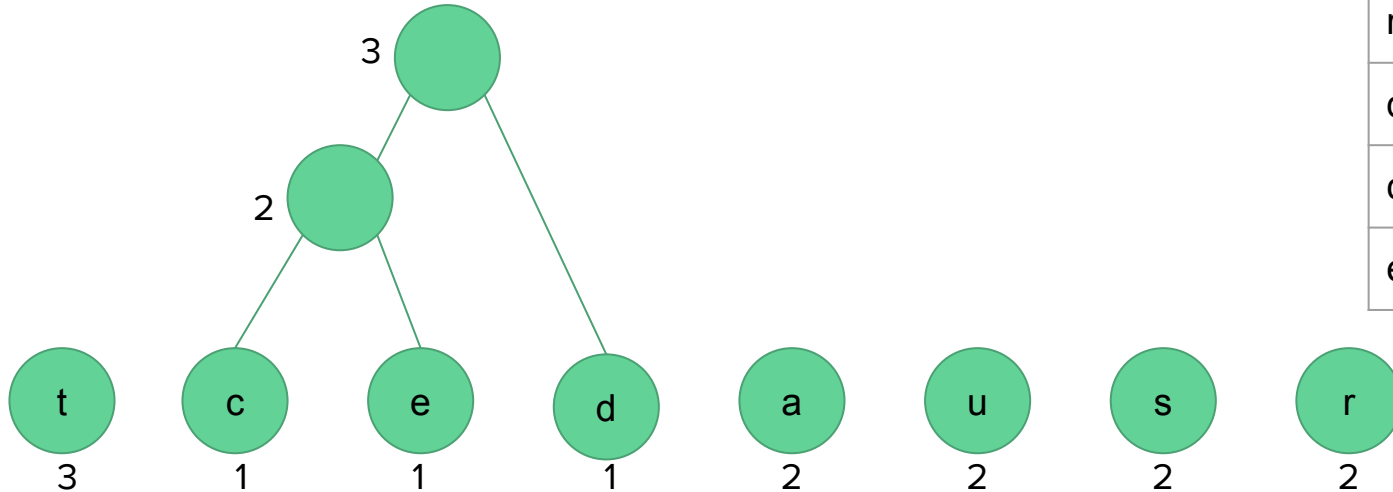
Build a Huffman tree:

character	frequency
t	3
a	2
u	2
s	2
r	2
d	1
c	1
e	1



# Huffman coding example

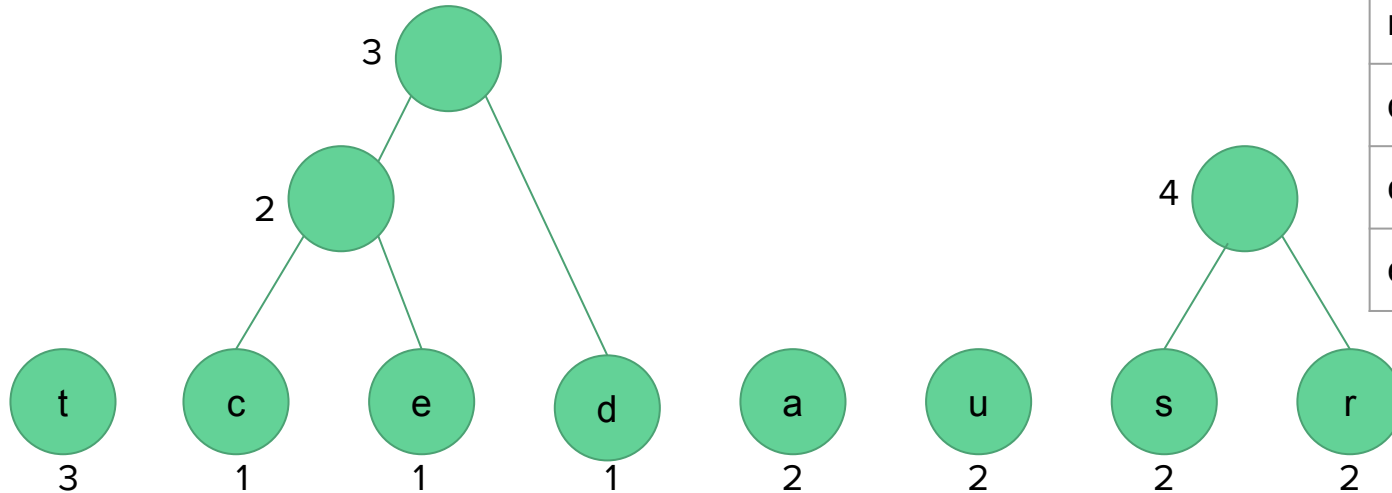
Build a Huffman tree:



character	frequency
t	3
a	2
u	2
s	2
r	2
d	1
c	1
e	1

# Huffman coding example

Build a Huffman tree:

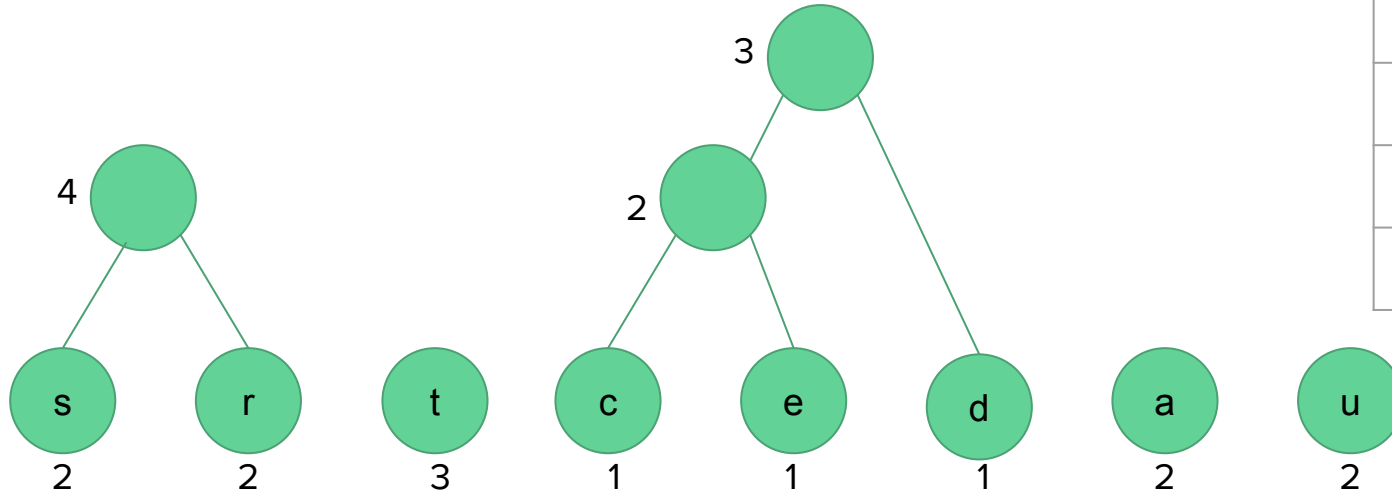


character	frequency
t	3
a	2
u	2
s	2
r	2
d	1
c	1
e	1



# Huffman coding example

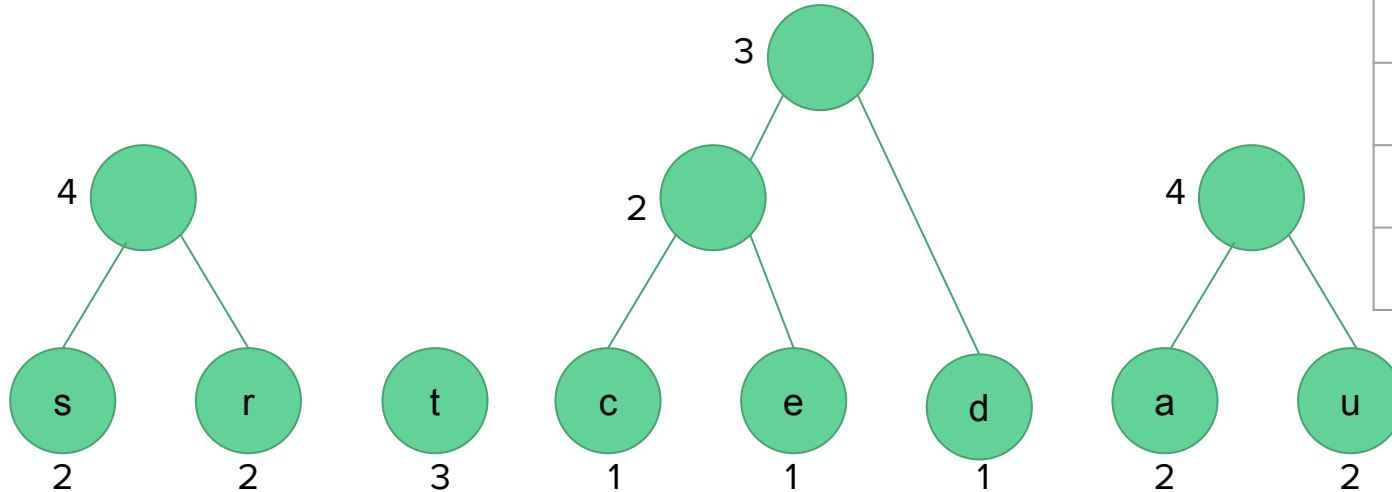
Build a Huffman tree:



character	frequency
t	3
a	2
u	2
s	2
r	2
d	1
c	1
e	1

# Huffman coding example

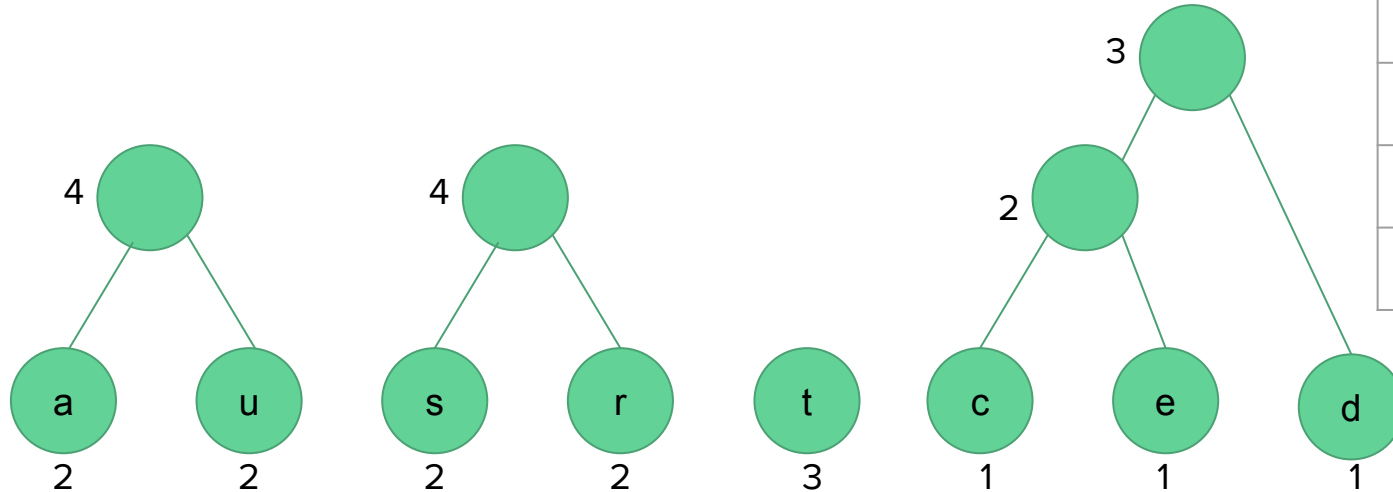
Build a Huffman tree:



character	frequency
t	3
a	2
u	2
s	2
r	2
d	1
c	1
e	1

# Huffman coding example

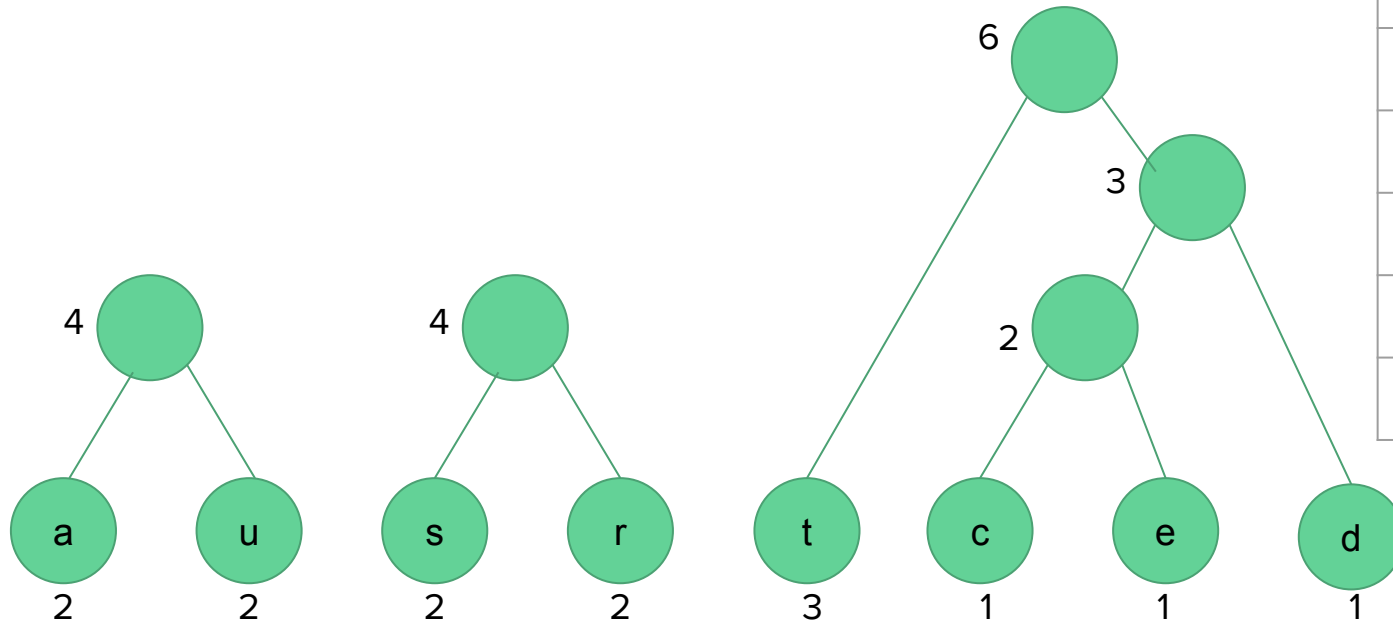
Build a Huffman tree:



character	frequency
t	3
a	2
u	2
s	2
r	2
d	1
c	1
e	1

# Huffman coding example

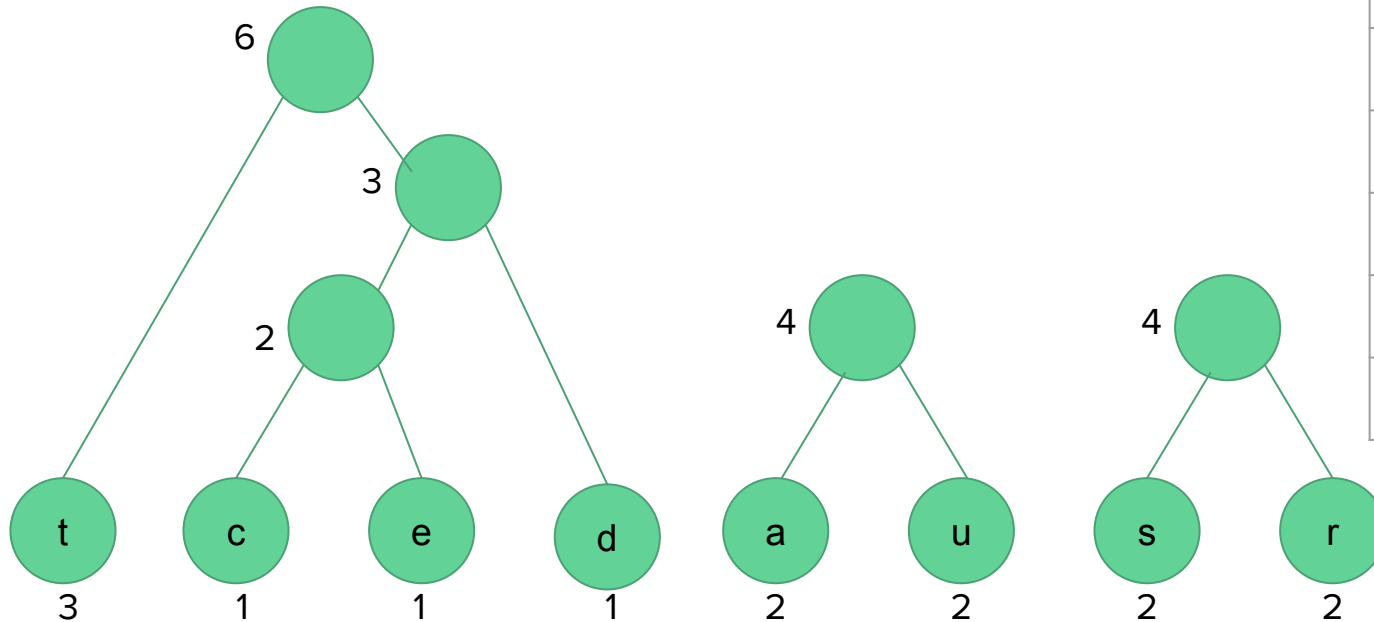
Build a Huffman tree:



character	frequency
t	3
a	2
u	2
s	2
r	2
d	1
c	1
e	1

# Huffman coding example

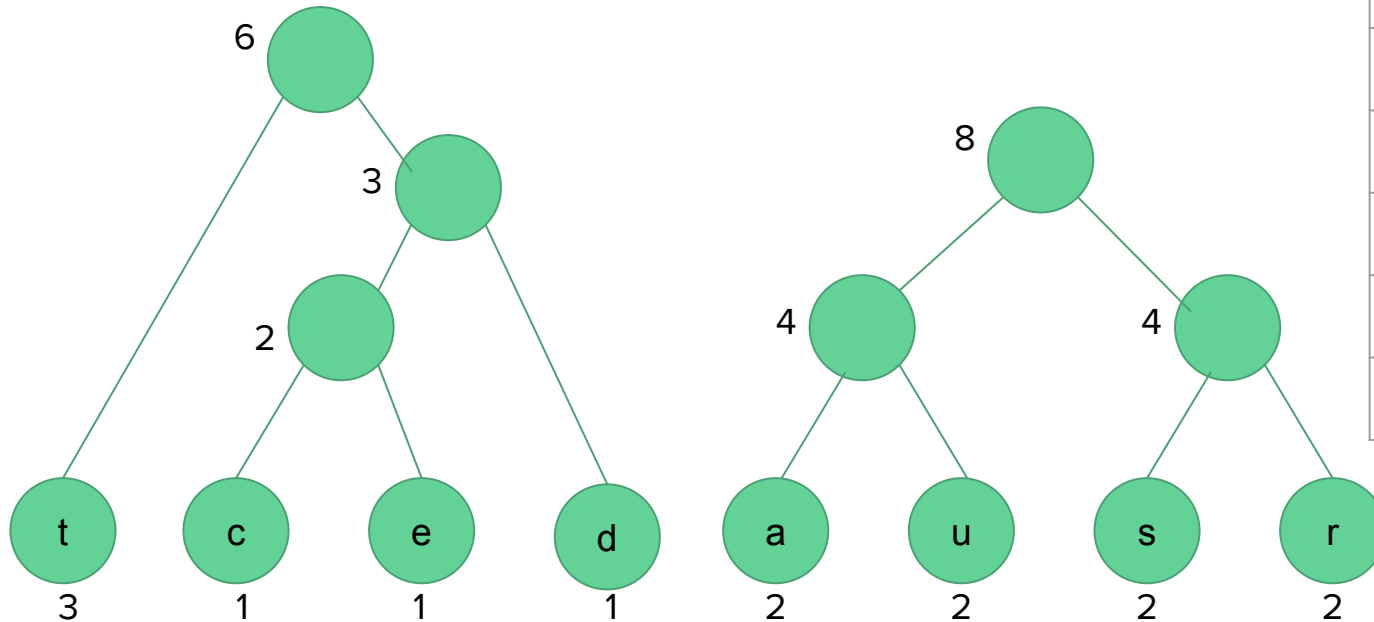
Build a Huffman tree:



character	frequency
t	3
a	2
u	2
s	2
r	2
d	1
c	1
e	1

# Huffman coding example

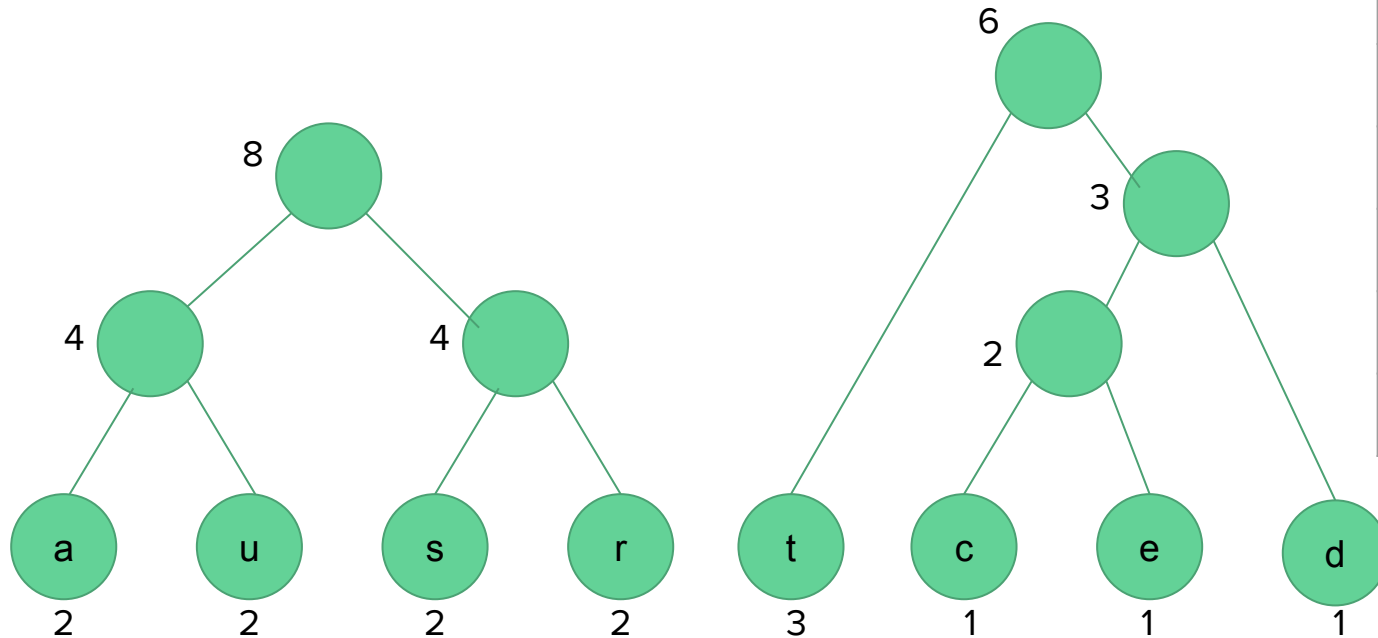
Build a Huffman tree:



character	frequency
t	3
a	2
u	2
s	2
r	2
d	1
c	1
e	1

# Huffman coding example

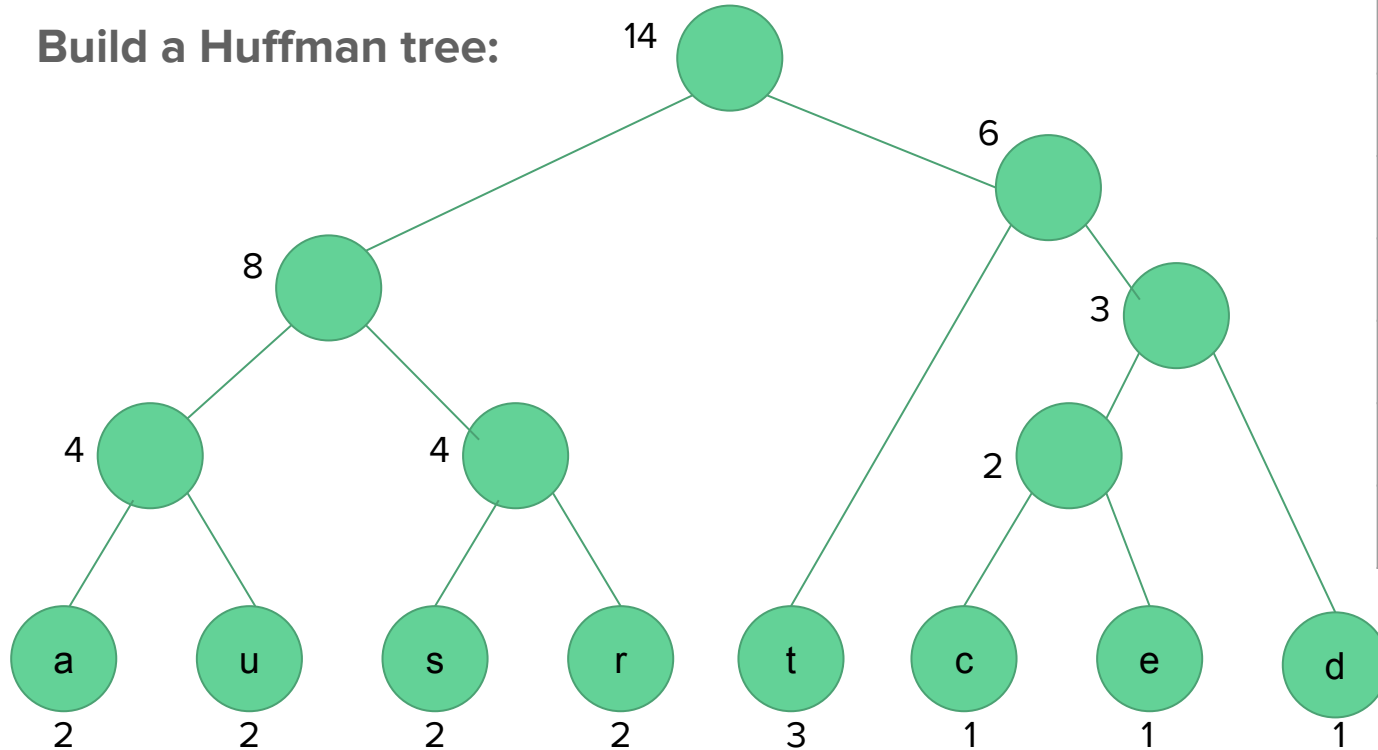
Build a Huffman tree:



character	frequency
t	3
a	2
u	2
s	2
r	2
d	1
c	1
e	1

# Huffman coding example

Build a Huffman tree:



character	frequency
t	3
a	2
u	2
s	2
r	2
d	1
c	1
e	1



# Huffman coding example

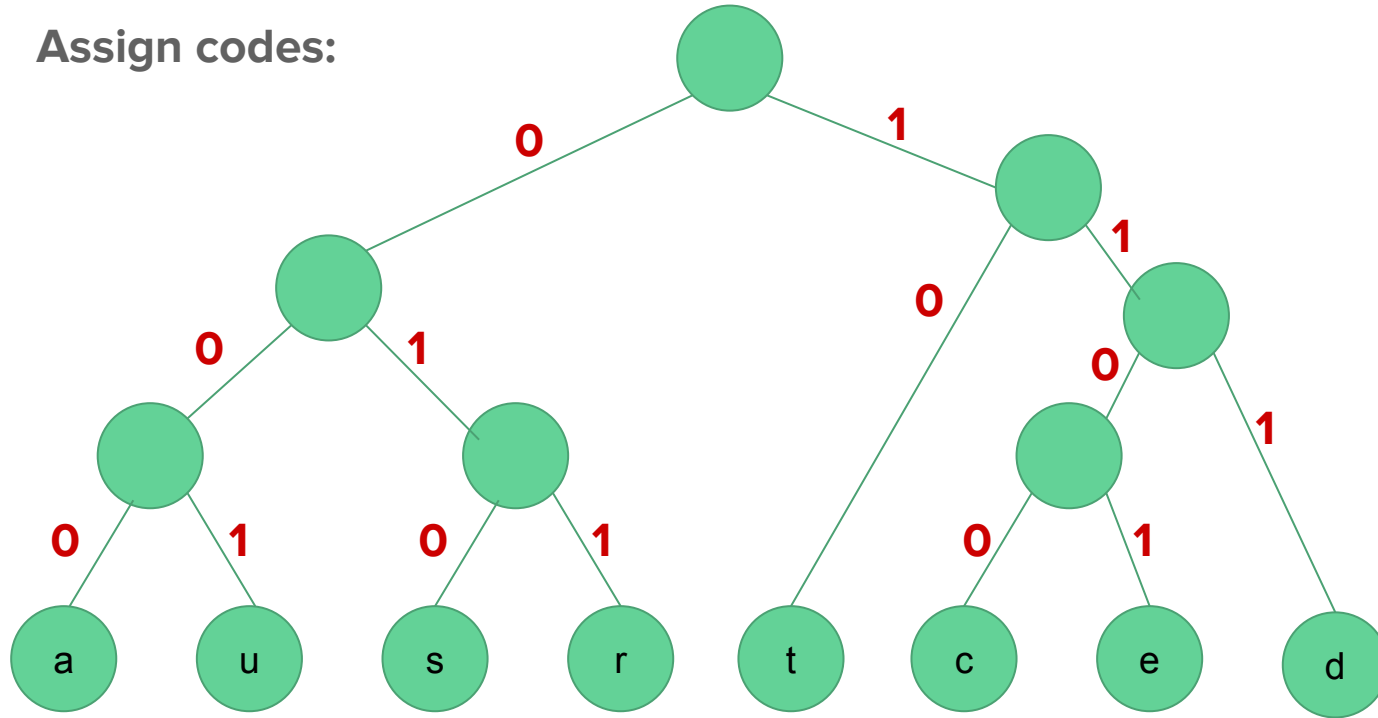
Now we **assign codes** to the tree by **placing a 0 on every left branch and a 1 on every right branch**

A traversal of the tree from root to leaf give the Huffman code for that particular leaf character

These codes are then used to encode the string

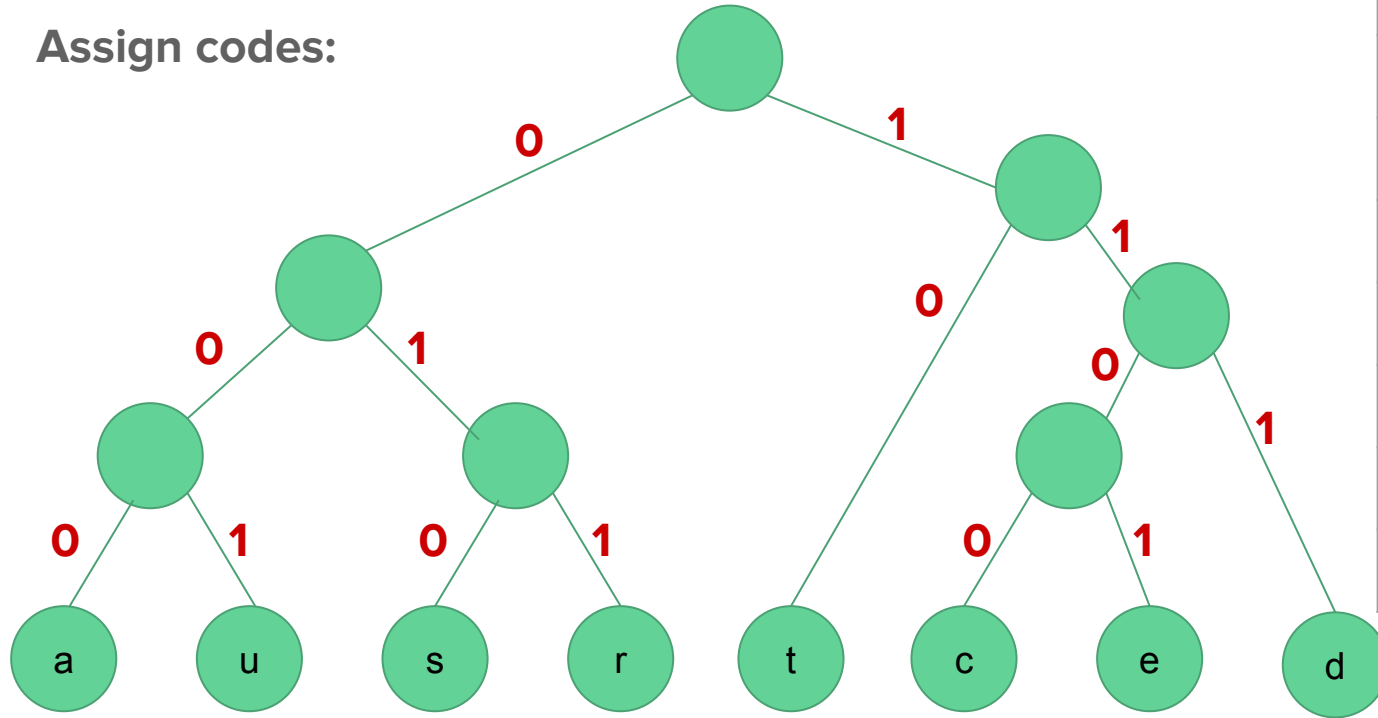
# Huffman coding example

Assign codes:



# Huffman coding example

Assign codes:



character	Huffman code
t	10
a	000
u	001
s	010
r	011
d	111
c	1100
e	1101

# Huffman coding example

Thus “datastructures” turns into

11100010000010100110011100100010111101010

If 8-bit ASCII code had been used instead of Huffman coding, “datastructures” would have been

0110010001100001011101000110000101110011

0111010001110010011101010110001101110100

01110101011100100110010101110011

character	Huffman code	ASCII code
t	10	01110100
a	000	01100001
u	001	01110101
s	010	01110011
r	011	01110010
d	111	01100100
c	1100	01100011
e	1101	01100101

# Huffman coding

## **Uncompression:**

Read the file bit by bit

1. Start at the root of the tree
2. If a 0 is read, head left
3. If a 1 is read, head right
4. When a leaf is reached, decode that character and start over again at the root of the tree

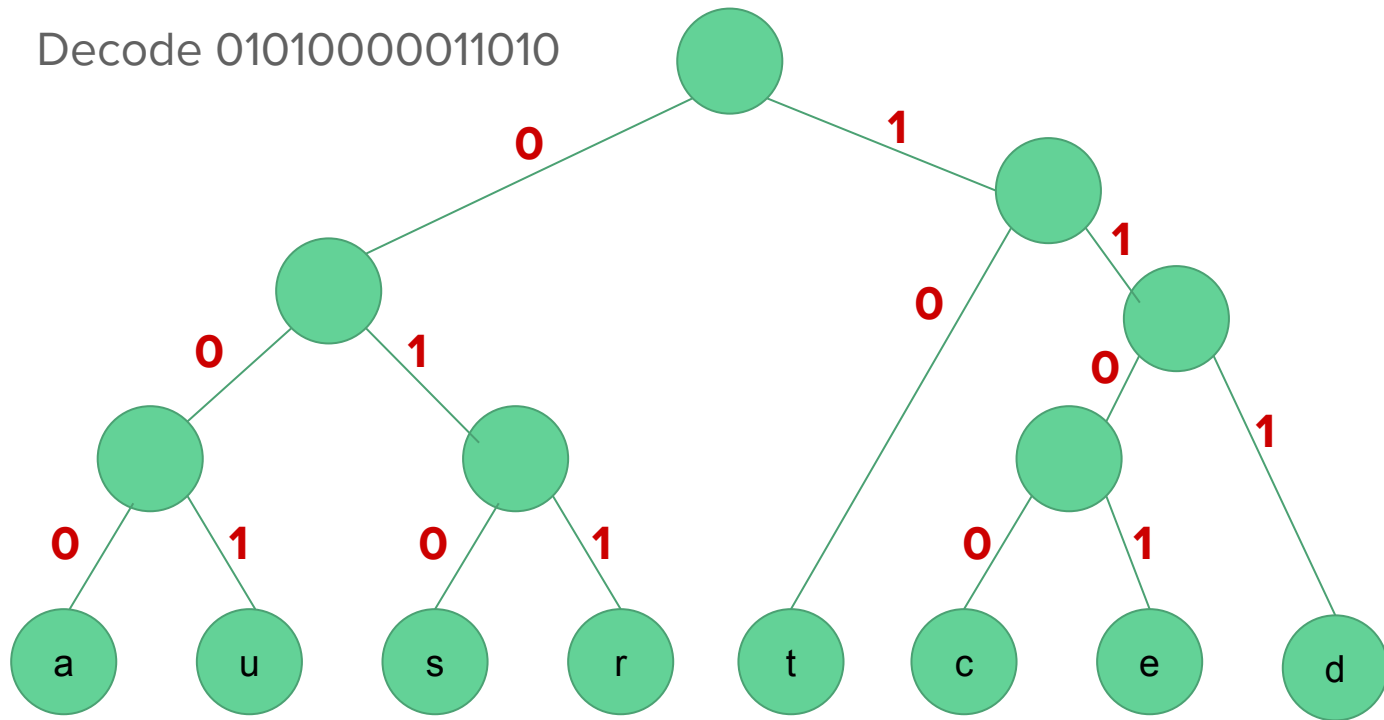
# Huffman coding

## **Uncompression example:**

Decode 01010000011010 using the previous Huffman tree

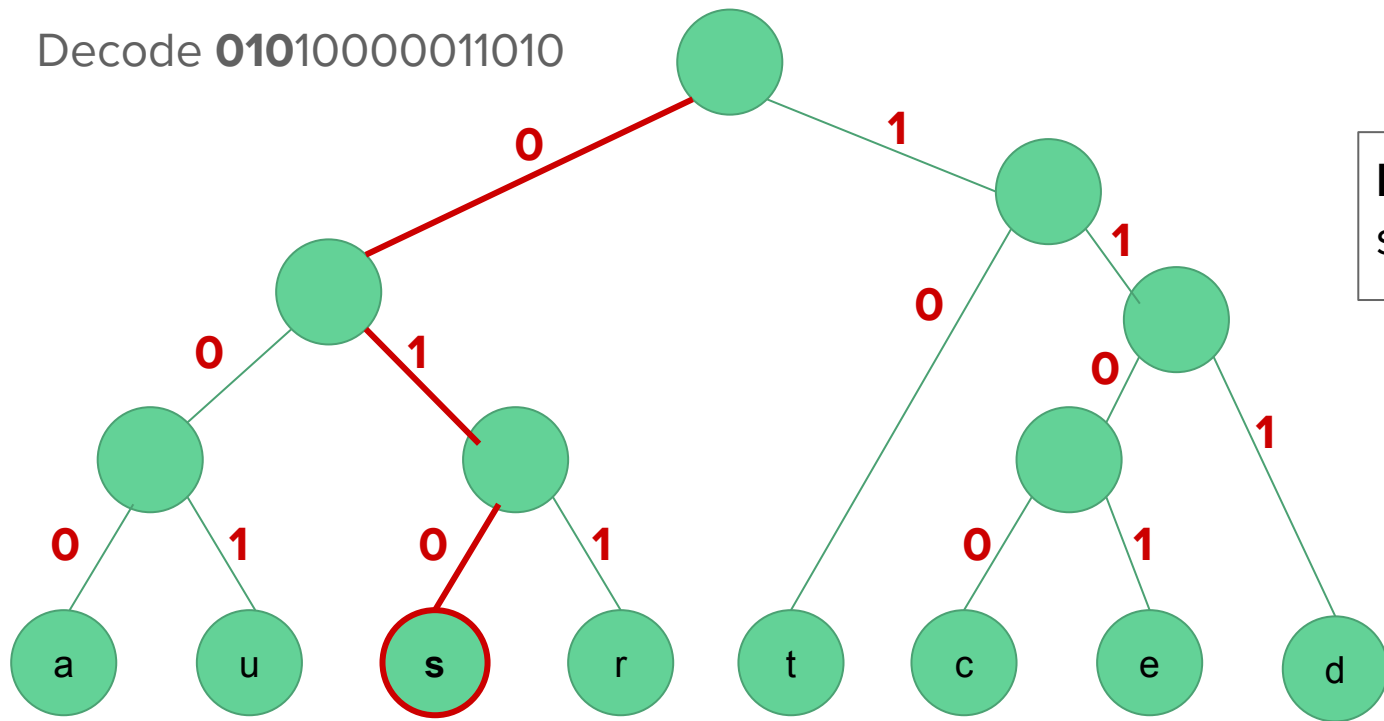
# Uncompression example

Decode 01010000011010



# Uncompression example

Decode **01010000011010**



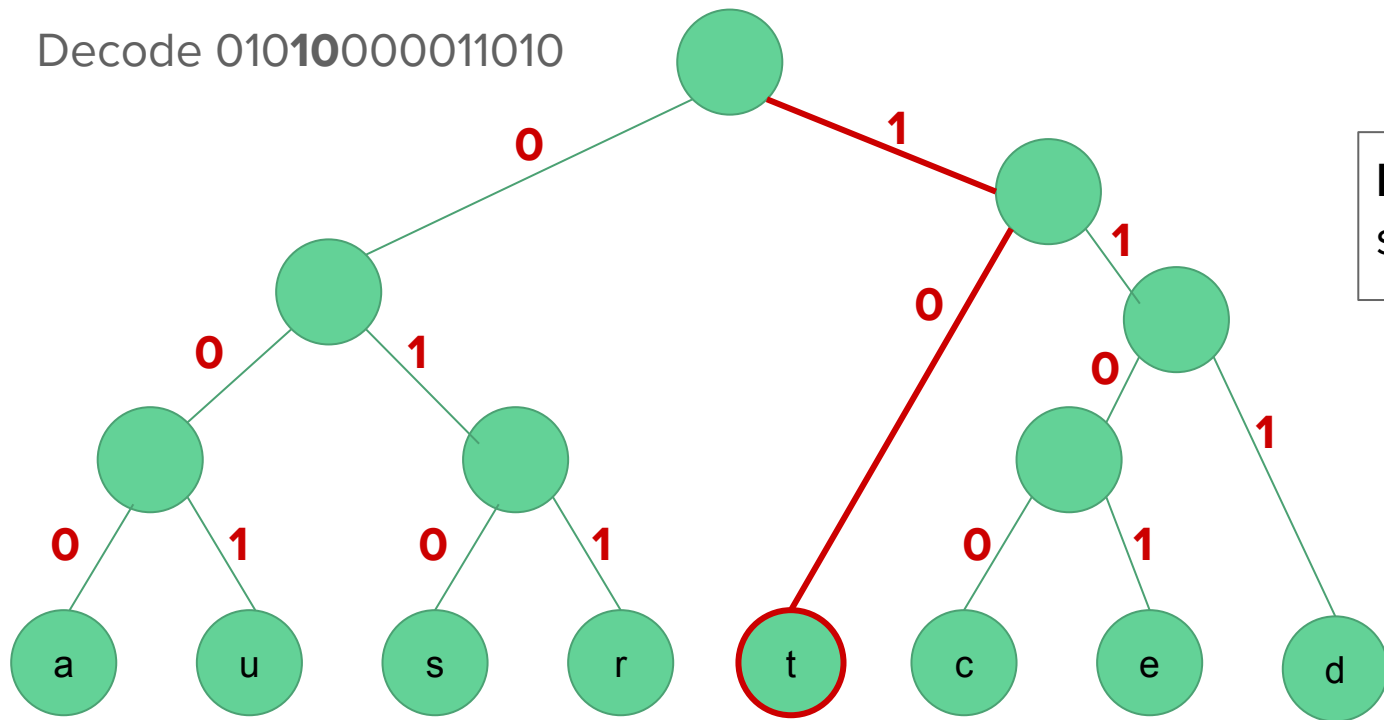
**Decoded string:**

s



# Uncompression example

Decode 010**1**0000011010

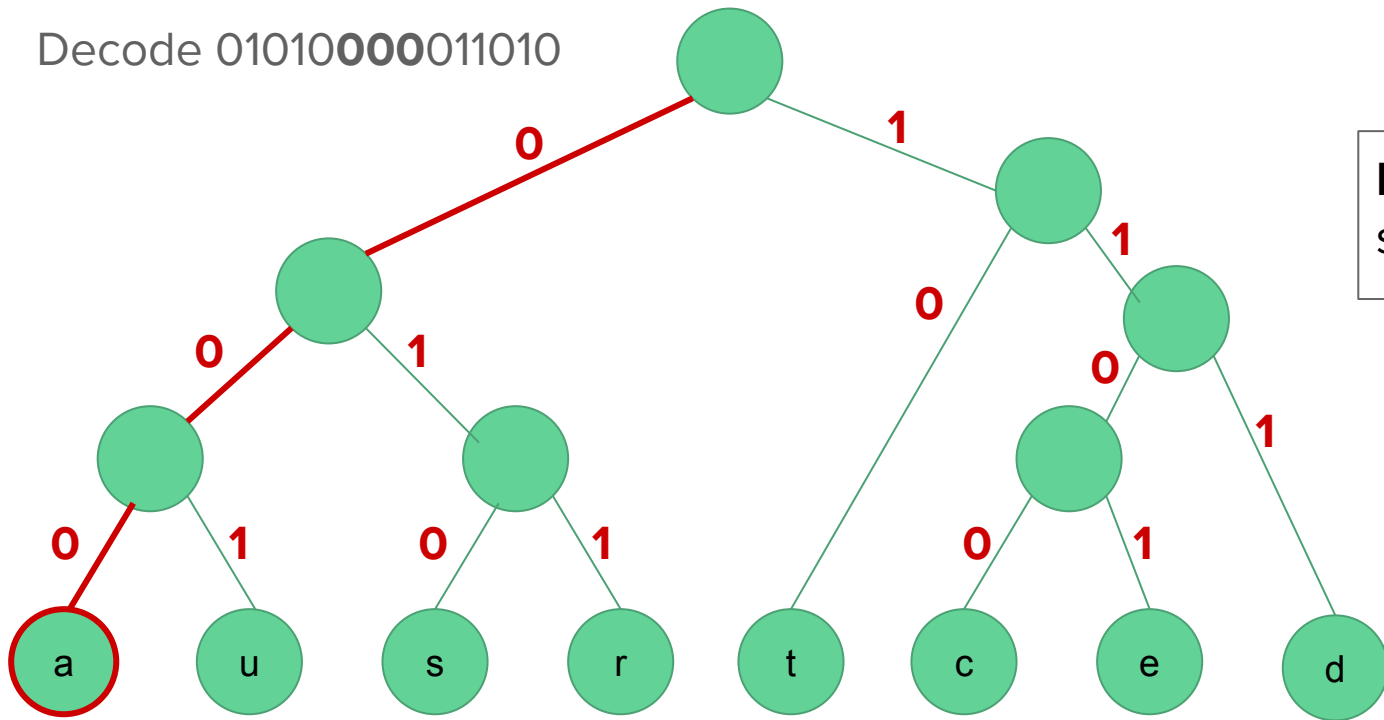


**Decoded string:**

st

# Uncompression example

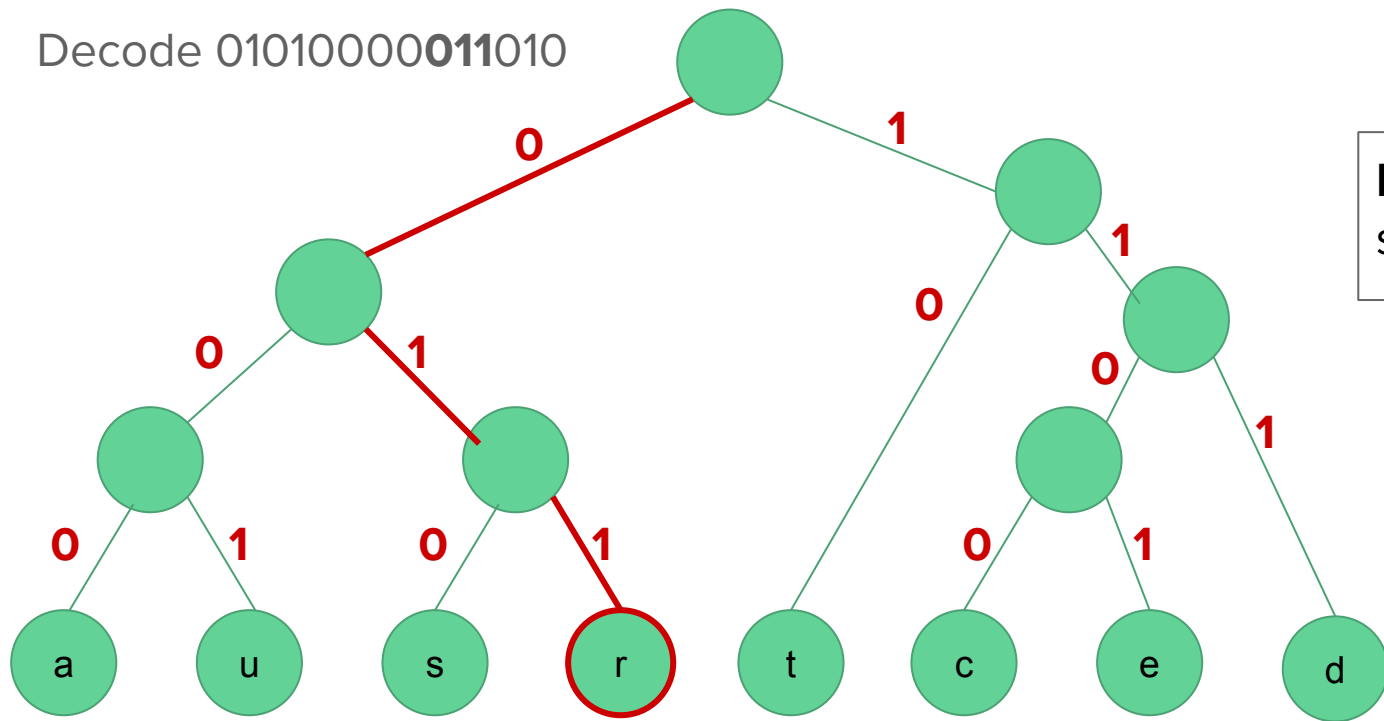
Decode 01010**000**011010



**Decoded string:**  
sta

# Uncompression example

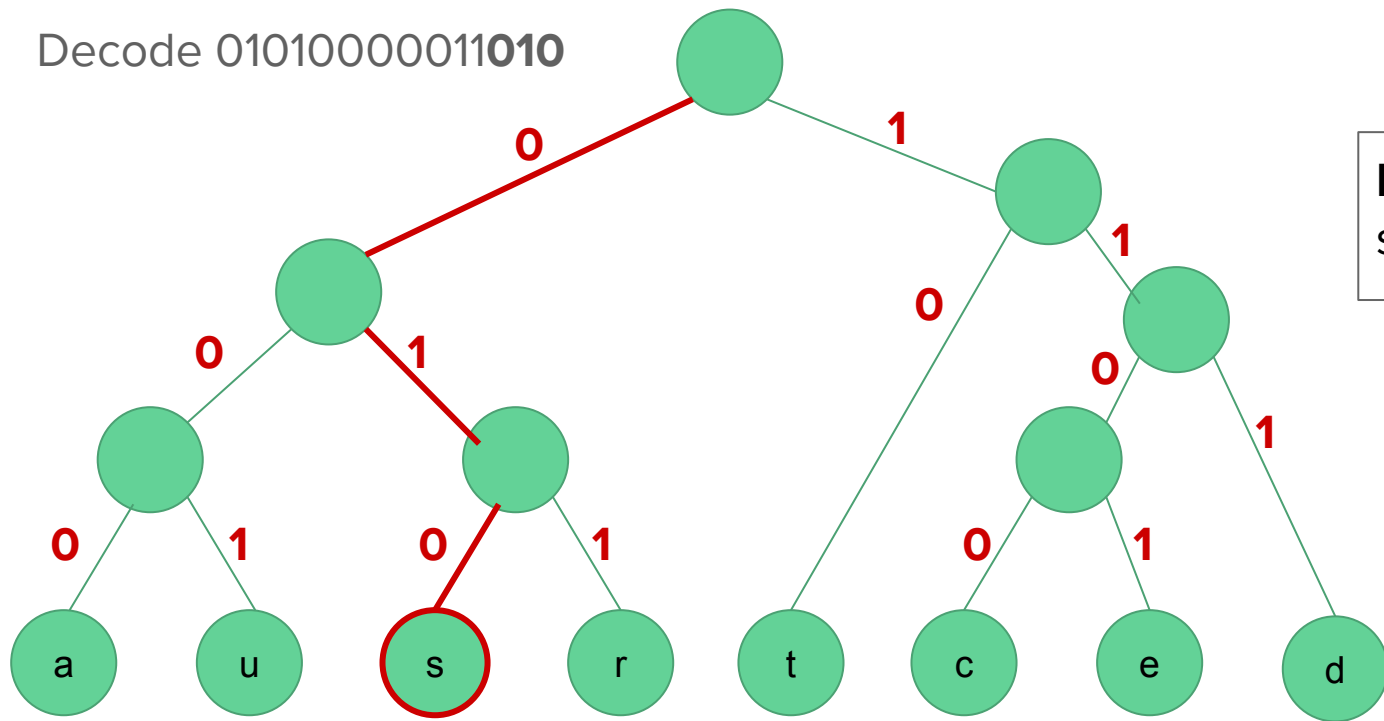
Decode 01010000**01**1010



**Decoded string:**  
star

# Uncompression example

Decode 01010000011**010**



**Decoded string:**  
stars