Markov Chains

It is a stochastic Model that depicts a sequence of possible events where predictions or probabilities of next state are based only on the previous state

stochastic means having a random probability distribution that may be analyzed startically but may not be predicted precisely.

The Markov Property is followed which means that probability of state h depends only on n-1 state but not n-2, n-3 ... or any other previous states (Memoryless Property)

They are similar to Finite state Machines but have probabilities associated with them.

Markov Chains are used in weather prediction genetics, finance, NLP, search engines and queue analysis

It is a very basic model used in data science, a precursor to MMM

A state
$$S_{t}$$
 is Markov iff

$$P\left[S_{t+1} \middle| S_{t}\right] = P\left[S_{t+1} \middle| S_{1}, \dots S_{t}\right]$$
The future is independent of the past given the present "

A Markov model assumes that ->
Once current state is known the history is thrown away, because the current state contains all previous information

example we have climate of days. Today is a hot day. What will it be tomorrow? If today is not,
The probability that it will be mild is 0.5 hot again is 0.3 and cold is 0.2 We have to assume that tomorrows temperature is dependant only on todays temperature and not yesterdays temperature 0.3 0.2 } Transition Probabilities Not, Cold, Mild → states. eg $P(\chi_{h+1} = Cold \mid \chi_h = Not) = 0.2$ Similarly for every state we have transitions The sum of all transition probabilities from one state must be I is. 0.3+0.2+0.5=1 all outgoing arrows must sum to 1

The incomming arrows need not be 1

what is the probability that day after tomorrow is not of today is Mild?

$$P(X_{n+2} = Not | X_n = Mild)$$

P(Xh+2=Not | Xh+1=Not, Xh=Mild) P(Xh+1=Not | Xh=Mild)
P(X | M + 1 | X - Mild) P(Xh+1=Not | Xh-Mild)

+ $P(X_{n+2} = Not) X_{n+1} = Mild_{r}X_{n} = Mild_{r}) P(X_{n+1} = Mild_{r}) X_{n} = Mild_{r}$ + $P(X_{n+2} = Not) X_{n+1} = Mild_{r}) P(X_{n+1} = Mild_{r}) P(X_{n+1} = Mild_{r})$

By local Markor Property

$$P(X_{h+2} = \bigcirc | X_{h+1} = \bigcirc, X_h = Muld) =$$
 $P(X_{h+2} = \bigcirc | X_{h+1} = \bigcirc)$ as Todays s' Mild elimate doesn't affect day after tom-

0.2 × 0.5 + 0.2 × 0.5 + 0.3 × 0.1

Adjacency Matrix

The transition is represented as an adjacency Matrix for solving

Mot Mild Cold

Not 0.2 0.3 0.5

Mild 0.5 0.2 0.3

Cold 0-1 0.6 0.3

A - \[0.2 0-3 0.5 \]

This is used to translate the probability calculations into expirient matrix multiplications

Calculations into efficient matrix multiple

Day (Day 2

Not Not → 0-2

Not Mild → 0.3

This is also called as state transition matrix

This is also called as slate transition may $P_{SS}' = P \left[S_{t+1} = S \mid S_t = S \right]$ Next state current state

Random Walk

fandom walk means moving along the transition of states in a random manner respecting the probabilities of transition eg a random walk might be Not - Mild - Not - Mild - Cold - Mild - Not This can be used for generation of a sequence in line with the transition probabilities Nelpful to model particle diffusion, stock prices lled to compose music, generate text

Calculation of Probabilities using Matrix Consider prior probability T Today is Mild :- TT = [0 | 0] When we Multiply To by A we get the probability that what tomorrow will be $\pi A = [0.5 \ 0.2 \ 0.3] = \pi_1$ ·· Tomorron it will be Hot with propositify 0.5, Mill with 0.2, Cold with 0.3 What is the probability that Day after tomorrow is Not given today is Mild? Multiply the New Vector TT, by A $\pi_{1} A = \begin{bmatrix} 0.23 & 0.37 & 0.4 \end{bmatrix} = \pi_{2}$ Probability that it is hot is 0.23 cold is 0.4.
The elements of TI must add up to 1 We can use TIz to calculate the probabilities for further days In the end The will converge, to a value and remain the same which is the stationary state.

Stationary Distribution

If we perform random walk for a long time, the probabilities of a day climate start converging

eg P(Day=Not) or P(Day= Cold)
car be calculated over as sandom walks wont
change.

This is because the MC reaches a state where the probability of next state occurring will be same for all future states

These are called stationary distributions or equilibrium state or steady state The stationary distribution doesn't change with time. Over time the influence of the initial state diminishes and probabilities become spread out over time, balancing the transition between states.

This means that regardless of the initial state the system eventually settles into a stable distribution.

These can be calculated by linear algebra without having to perform so vardom walks We want to find a value that converges over time. that is when we calculate the Probabilities that day will be cold -

Th A - That

if there exists a stationary state then $T_{k+1} = T_k$

∴ πA = π

Solving using eigen vectors

A V = AV elements of T1 must add up to 1 $\Sigma \pi_i = 1$ Σ VATT

λ→ 1

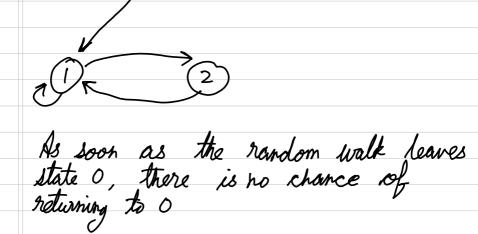
Solving 1 & & 7 can be obtained

There can be more than one values of Il that is more than one stationary state

Markon chains are used in transition between

Markov chain is used to determine the equilibrium condition whose probabilities sepresent ranking of webpages.

Reducible Markov chains



Hence the Probability of revisiting state 0 on a random walk starting with 0 is less than

O is the transient state. We don't know if we are comming back

1 & 2 are called recurrent states. The probability of random walk revisiting it is I This type of Markov chains are called reducible.

If every state is rechable from any state then it becomes irreducible Markon chain

We have calculated Tr for a single starting state Similarly, une car calculate all possibilities $\begin{array}{rcl}
A \times A &=& 0.24 \\
& 0.23 \\
& 0.35
\end{array}$ 0.42 0.34 0.4 0.37 0.32 0.35 0.33 Sum of all rows must be ! Not Mild Cold Mot 0.24

Mild 0.23

Cold 0.35 0.42 0.34 0.4 0.34 0.32 0.33 Day O Day 2 Mot Not →

Mill, Not →

Cold, Cold → 0.24 0-23 0.32 for 3 day Prior probabilities, become A while transition probabilities remain A. This way for 3rd day all the combinations can be calculated using A In other words, A can be expressed, as the probability of reaching a state from a given state after 2 steps ie Probability of reaching flot from starting with not day is 2 days is 0-24 This can be done by any of the paths Not - cold - Not Not - Not - not Not - Mild-Not The total probability is the sum of all the 3 paths is. = P(Not - cold) x P(cold - not) + P(Not-Not) × P(Not-Not) - P (Not. Mild) x P (Mild-Not) also represented as Pou(1) * Poz(1) + Poi(1) + P1z(1) + Por (1) + P22/1) -(1) for A we thus have the probability of reaching state; to; in exactly h $P_{ij}(n) = A_{ij}$ Thus by repeated Matrix Multiplication, we can find the n step transition probability. So we can generalize (1) As $P_{ij}(h) = \sum_{k} P_{ik}(x) \times P_{kj}(h-x)$ This is called as the chapman-kolmogow k- intermediate state gives in 8 steps lim A = stable state n → ω

Advantages -> Simplicity Efficiency Interpretability scalability to large datasets Disadvantages -> Memoryless Can't handle complex patterns trained accurately Homogenity Assumption > the transition table is same over time Markor chains can be trained through count based estimation (Counting no of times the transition occurs of updating values) or through prior knowledge

1) A coin is tossed repeatedly what are the expected, number of throws before two consecutive heads? -> 5 O.5 | New O.5 | 2 Macdo A: Current toss was head & last one we not head

B: Current toss was tails

C: Current toss was head & last one was head

S: starting state Rardom walk -> BABBABBAA, AA, BAA, ...
BABAA, ABBAA, etc Expected no of throws from state A O.SX FB $F_A = 1 +$ + 0.5% Ec Current Going to Ep of toss Expected no of throws from state of EB = 1 + 0.5 x EA + 0.5 x EB

Current
Going to
FA

Comming
back to E bank to EB $E_c = o$ (end) : We get FA = 1 + 0.5 FB (1)
FB = 1 + 0.5 FB + 0.5 FD (2) from O & O Bubs EA EB= 1+ 0.5 (1+0.3 FB) +0.3 FB : $F_{B} = 1 + 0.5 + 0.75 F_{B}$: $F_{B} = \frac{1.5}{0.25} = 6$:.. EA = 4 from starting state 5 Es = 1 + 0.5 En + 0.5 EB = 1+ 0.5x3+ 0.5x6 - 6 Answer - 6