```
import cvxpy as cp
import numpy as np
from itertools import product
```

#### Data of the Problem

```
shipping_cost = np.array([[1,3,2],[3,2,2]]).reshape(2,3)
production_cost = np.array([11,10]).reshape(2,1)
given_demand = np.array([[100,150,120],[120,180,150],[150,200,180]]).reshape(3,3)
selling_price = np.array([[16,16]]).reshape(2,1)
produce = np.array([100,200]).reshape(2,1)
produce_limit = np.array([300,300]).reshape(2,1)
senario = 27
senario_prob = (1/senario)*(np.ones((senario,1)))
```

### Senario generation of the demand

```
senario = given_demand.T
senario_comb = []
index = np.arange(0,3)
index_permute = product(index,repeat=3)
for i in index_permute:
    temp_array =[]
    for j in range(0,3):
        temp_array.append(float(senario[j,:][i[j]]))
    senario_comb.append(temp_array)
all_demand = np.array(senario_comb).reshape(27,3)
```

#### Question 1.3 Solve large scale problem combining all senarios into one problem

#### Large scale problem solution

```
produce = cp.Variable(shape=(2,1))
sell = cp.Variable(shape=(54,3))
salvage = cp.Variable(shape=(54,1))
produce_limit = np.array([300,300]).reshape(2,1)
ls_constraints_senario = []
for index,demand in enumerate(all_demand):
   i = index*2
   ls_constraints_senario.append(cp.sum(sell[i:i+2,:],axis=1,keepdims=True) +salvage[i:i+2,:] <= produce)</pre>
   ls\_constraints\_senario.append(cp.sum(sell[i:i+2,:],axis=0,keepdims=True) \ <= \ demand.reshape(1,-1))
ls_constraints = [produce>=0,produce<=produce_limit,sell>= np.zeros_like(sell),salvage>= np.zeros_like(salvage)]
ls_constraints.extend(ls_constraints_senario)
ls_objective = cp.Minimize((production_cost.T@produce)-(16/27)*cp.sum(sell,keepdims=True) + (1/27)*cp.trace(((((np.repeat([shipping_cost],27
ls_problem = cp.Problem(ls_objective, ls_constraints)
ls_problem.solve()
    -1609.999997418313
print("----Large Scale formulation results----")
print("Optimal Production plan ", produce.value)
print("Optimal Value of the Problem", ls_problem.value)
    ----Large Scale formulation results----
     Optimal Production plan [[120.00000002]
      [299.99999999]]
     Optimal Value of the Problem -1609.9999997418313
```

# Expected value of demand

```
expected_demand = np.mean(all_demand,axis=0)
produce = cp.Variable(shape=(2,1))
sell = cp.Variable(shape=(2,3))
salvage = cp.Variable(shape=(2,1))
produce_limit = np.array([300,300]).reshape(2,1)
ed_constraints_senario = []
ed_constraints_senario.append(cp.sum(sell,axis=1,keepdims=True) +salvage <= produce)</pre>
ed_constraints_senario.append(cp.sum(sell,axis=0,keepdims=True) <= expected_demand.reshape(1,-1))
ed_constraints = [produce>=0,produce<=produce_limit,sell>= np.zeros_like(sell),salvage>= np.zeros_like(salvage)]
ed_constraints.extend(ed_constraints_senario)
ed_objective = cp.Minimize((production_cost.T@produce)-(16)*cp.sum(sell,keepdims=True) + (1)*cp.trace(((((np.repeat([shipping_cost],1,axis=@
ed_problem = cp.Problem(ed_objective, ed_constraints)
ed_problem.solve()
<del>→</del> -1773.3333279947847
print("---- Results using deterministic expected demand----")
print("\nOptimal Production plan using",produce.value)
print("\nOptimal Value of the Problem",ed_problem.value)
---- Results using deterministic expected demand----
     Optimal Production plan using [[150.0000002]
      [299.99999937]]
     Optimal Value of the Problem -1773.3333279947847
```

#### Q-1.4

# Solving problem treating each demand individually

```
produce_over_scenario = []
objective_over_scenario = []
for demand in all_demand:
   produce = cp.Variable(shape=(2,1))
   sell = cp.Variable(shape=(2,3))
   salvage = cp.Variable(shape=(2,1))
   produce_limit = np.array([300,300]).reshape(2,1)
   constraints senario = []
   constraints_senario.append(cp.sum(sell,axis=1,keepdims=True) +salvage <= produce)</pre>
   constraints\_senario.append(cp.sum(sell,axis=0,keepdims=True) <= demand.reshape(1,-1))
   constraints = [produce>=0,produce<=produce_limit,sell>= np.zeros_like(sell),salvage>= np.zeros_like(salvage)]
   constraints.extend(constraints_senario)
   problem = cp.Problem(objective, constraints)
   problem.solve()
   produce_over_scenario.append(produce.value)
   objective_over_scenario.append(problem.value)
print("Production plan considering each demand as determinstic:\n")
for index,demand in enumerate(all_demand):
   print("\n----Senario 1----")
   print("\n Demand : ",demand)
   print("Optimal production",produce_over_scenario[index])
```

print("Optimal objective value",objective\_over\_scenario[index])

```
[269.99999984]]
Optimal objective value -1679.9999955343733
----Senario 1----
Demand: [150. 150. 150.]
Optimal production [[150.00000009]
 [299.99999988]]
Optimal objective value -1799.99999274376
----Senario 1----
Demand: [150. 150. 180.]
Optimal production [[179.99999999]
[299.99999952]]
Optimal objective value -1889.999994982722
----Senario 1----
Demand : [150. 180. 120.]
Optimal production [[150.00000012]
 [299.9999987]]
Optimal objective value -1799.99999237106
----Senario 1----
Demand: [150. 180. 150.]
Optimal production [[179.99999999]
 [299.99999959]]
Optimal objective value -1889.9999953212587
----Senario 1-----
Demand : [150. 180. 180.]
Optimal production [[210.00000018]
[299.99999963]]
Optimal objective value -1979.9999971065438
----Senario 1----
Demand : [150. 200. 120.]
Optimal production [[170.00000024]
 [299.99999969]]
Optimal objective value -1859.9999973345073
----Senario 1----
Demand: [150. 200. 150.]
Optimal production [[200.00000007]
[299.99999967]]
Optimal objective value -1949.999996957781
----Senario 1----
Demand : [150. 200. 180.]
Optimal production [[230.00000017]
 [299.9999995]]
Optimal objective value -2039.9999956183058
```

# Calculating value of perfect information

```
produce_over_scenario = np.array(produce_over_scenario).reshape(27,2)
objective_over_scenario = np.array(objective_over_scenario).reshape(27,1)
value_of_perfect_info = ls_problem.value - np.mean(objective_over_scenario)
print("Value of value of perfect information ",value_of_perfect_info)

    Value of value of perfect information 159.9999967386409
```

#### Q 1.5

Solve the scenario formulation with nonanticipativity constraints.

```
produce = cp.Variable(shape=(2,27))
sell = cp.Variable(shape=(54,3))
salvage = cp.Variable(shape=(54,1))
produce_limit = (np.array([300,300]).reshape(2,1))
produce_limit_ext = np.repeat([produce_limit],27,axis=0).reshape(2,27)
na_constraints = []
# Nonanticipativity constraints
for index,demand in enumerate(all_demand):
      na\_constraints.append(cp.reshape(produce[:,index],shape=(2,1)) == (1/27)*cp.sum(produce,axis=1,keepdims=True))
for index,demand in enumerate(all_demand):
      i = index*2
      na_constraints.append(cp.sum(sell[i:i+2,:],axis=1,keepdims=True) +salvage[i:i+2,:] <= cp.reshape(produce[:,index],shape=(2,1)))</pre>
      na\_constraints.append(cp.sum(sell[i:i+2,:],axis=0,keepdims=True) <= demand.reshape(1,-1))
constraints = [produce>=0,produce<=produce_limit,sell>= np.zeros_like(sell),salvage>= np.zeros_like(salvage)]
na_constraints.extend(constraints)
na\_objective = cp.Minimize((1/27)*cp.sum(production\_cost.T@produce) - (16/27)*cp.sum(sell,keepdims=True) + (1/27)*cp.trace(((((np.repeat([shiptimal form) of the context of the cost.T@produce) - (16/27)*cp.sum(sell,keepdims=True) + (1/27)*cp.trace(((((np.repeat([shiptimal form) of the cost.T@produce) - (16/27)*cp.sum(sell,keepdims=True) + (1/27)*cp.trace((((((np.repeat([shiptimal form) of the cost.T@produce) - (16/27)*cp.sum(sell,keepdims=True) + (1/27)*cp.trace(((((((np.repeat([shiptimal form) of the cost.T@produce) - (16/27)*cp.sum(sell,keepdims=True) + (1/27)*cp.trace((((((np.repeat([shiptimal form) of the cost.T@produce) - (16/27)*cp.sum(sell,keepdims=True) + (1/27)*cp.trace(((((((np.repeat([shiptimal form) of the cost.T@produce) - (16/27)*cp.sum(sell,keepdims=True) + (1/27)*cp.trace(((((((np.repeat([shiptimal form) of the cost.T@produce) - (16/27)*cp.sum(sell,keepdims=True) + (1/27)*cp.sum(sell,keepdims=True) +
na_problem = cp.Problem(na_objective, na_constraints)
na_problem.solve()
        -1609.999999266336
print("---- Results using nonanticipativity ----")
print("\nOptimal Production plan using",produce.value)
print("\nOptimal Value of the Problem",na_problem.value)
 ---- Results using nonanticipativity ----
        Optimal Production plan using [[120.00000001 120.00000001 120.00000001 120.00000001 120.00000001
            120.00000001 120.00000001 120.00000001 120.00000001 120.00000001
            120.00000001 120.00000001 120.00000001 120.00000001 120.00000001
            120.00000001 120.00000001 120.00000001 120.00000001 120.00000001
            120.00000001 120.00000001 120.00000001 120.00000001 120.00000001
            120.00000001 120.00000001]
           299.9999999 299.99999999]]
        Optimal Value of the Problem -1609.999999266336
for i in range(0,27):
      print(f"\nSecinario-{i}-----")
       print("Dual values for non anticipativiaty constraints")
      print(na_problem.constraints[i].dual_value)
 ₹
```

```
Secinario-20-----
Dual values for non anticipativiaty constraints
[[0.14818783]
[0.13000983]]
Secinario-21-----
Dual values for non anticipativiaty constraints
[[0.14818783]
[0.10750179]]
Secinario-22-----
Dual values for non anticipativiaty constraints
[[0.14818783]
 [0.13000983]]
Secinario-23-----
Dual values for non anticipativiaty constraints
[[0.14818783]
 [0.13000983]]
Secinario-24-----
Dual values for non anticipativiaty constraints
[[0.14818783]
 [0.13000984]]
Secinario-25-----
Dual values for non anticipativiaty constraints
[[0.14818783]
[0.13000984]]
Secinario-26-----
Dual values for non anticipativiaty constraints
[[0.14818783]
 [0.13000984]]
```

#### Q-1.6

# Solve the problem by the cutting plane method in the basic version (Benders decomposition)

```
def solve_second_stage_problem(produce,demand,shipping_cost):
   sell = cp.Variable(shape=(2,3))
   salvage = cp.Variable(shape=(2,1))
   objective = cp.Minimize(-16*cp.sum(sell,keepdims=True) + cp.trace((((shipping_cost@(sell.T))))))
   constraints = [cp.sum(sell,axis=1,keepdims=True) +salvage <= produce,cp.sum(sell,axis=0,keepdims=True) <= demand.reshape(1,-1), sell>= r
   problem = cp.Problem(objective, constraints)
   problem.solve()
   return problem
def solve_master_problem(produce,produce_limit,g_ks,alpha_ks):
   production_cost = np.array([11,10]).reshape(2,1)
   produce = cp.Variable(shape=(2,1),name="produce")
   v = cp.Variable(shape=(1,1),name="value")
   constraints = []
   for i in range(0,len(g_ks)):
        constraints.append(np.array(g\_ks[i]).T@produce+np.array(alpha\_ks[i]) <= v)
   constraints.extend([produce>=0,v>=-100000,produce<=produce_limit])</pre>
   objective = cp.Minimize(production_cost.T@produce + v)
   problem = cp.Problem(objective, constraints)
   problem.solve()
   return problem
```

```
produce = np.array([100,200]).reshape(2,1) # Initial Guess
g_ks = []
alpha_ks = []
objctive_values = [np.nan]
epsilon = 10**(-4)
iter = 0
while True:
   # Solve Second stage problem for each demand and store its duals and objective values
   duals = []
   objs= []
   for demand in all_demand:
       second_stage_sol = solve_second_stage_problem(produce,demand,shipping_cost)
       temp_dual = second_stage_sol.constraints[0].dual_value  # Take the duals of 1st contraint
       temp_obj = second_stage_sol.value
                                                             # Take the objective value of second stage problem
       # Store duals and objective values for each senario
       duals.append(temp_dual)
       objs.append(temp_obj)
   # Reshaping the values
   duals = np.array(duals).reshape(-1,2)
   objs = np.array(objs).reshape(-1,1)
   g_ks_temp = (-senario_prob.T@duals).T
   alpha_ks_temp = senario_prob.T@objs - g_ks_temp.T@produce
   g_ks.append(g_ks_temp)
   alpha_ks.append(alpha_ks_temp)
   first_stage_sol = solve_master_problem(produce,produce_limit,g_ks,alpha_ks)
   obj_value = first_stage_sol.value
   new_produce = first_stage_sol.var_dict["produce"].value
   new_limit = first_stage_sol.var_dict["value"].value
   if np.abs(obj value - objctive values[-1])<= epsilon:</pre>
       print("Terminating condition satisfied !")
       break
   else:
       pass
   objctive_values.append(obj_value)
   produce,limit = new_produce,new_limit # swap the values
    iter = iter+1
   print(f"\n-----")
   print(f"\nproduction is {produce}")
   print(f"\nobjctive value is {first_stage_sol.value}\n")
∓
     -----Iteration no. 1-----
     production is [[300.00000004]
      [299.99999992]]
     objctive value is -2351.895943550797
     -----Iteration no. 2-----
     production is [[149.00805118]
     [299.9999992]]
     objctive value is -1784.2447749212179
     -----Iteration no. 3-----
     production is [[112.70470909]
     [300.00000003]]
     objctive value is -1647.7631011106232
```

```
-----Iteration no. 4-----
    production is [[125.23365091]
     [299.99999495]]
    objctive value is -1618.5289057328064
    -----Iteration no. 5-----
    production is [[119.99999869]
     [299.99999991]]
    objctive value is -1609.9999959895367
    Terminating condition satisfied !
print("---- Results using Bender Decompostion ----")
print(f"\nproduction is {produce}")
print(f"\nobjctive value is {first_stage_sol.value}\n")
---- Results using Bender Decompostion ----
    production is [[119.9999869]
     [299.99999991]]
    objctive value is -1609.9999957406962
```

# Q-1.7 (Solve the problem by the multicut method)

```
def solve_master_problem_ml(produce,g_ks,alpha_ks,senario_prob,production_cost,produce_limit):
    produce = cp.Variable(shape=(2,1),name="produce")
    v = cp.Variable(shape=(len(senario_prob),1),name="value")
    constraints = []
    for i in range(0,len(g_ks)):
        for j in range(0,len(g_ks[i])):
            constraints.append (np.array ([g\_ks[i][j]]) @ produce + np.array ([alpha\_ks[i][j]]) <= v[j]) \\
    constraints.extend([produce>=0,v>=-100000,produce<=produce_limit])</pre>
    objective = cp.Minimize(production_cost.T@produce + senario_prob.T@v)
    problem = cp.Problem(objective, constraints)
    problem.solve()
    return problem
g_ks = []
alpha_ks = []
senario = 27
objctive_values = [np.nan]
epsilon = 10**(-4)
iter = 0
while True:
    # Solve Second stage problem for each demand and store its duals and objective values
    duals = []
    objs= []
    for demand in all demand:
        second_stage_sol = solve_second_stage_problem(produce,demand,shipping_cost)
        temp_dual = second_stage_sol.constraints[0].dual_value  # Take the duals of 1st contraint
        temp_obj = second_stage_sol.value
                                                                  # Take the objective value of second stage problem
        # Store duals and objective values for each senario
        duals.append(temp_dual)
```

```
objs.append(temp_obj)
    # Reshaping the values
   duals = np.array(duals).reshape(-1,2)
   objs = np.array(objs).reshape(-1,1)
   gks_batch = []
   alpha_ks_batch = []
   for i in range(0, senario):
       gks_batch.append(-duals[i])
       alpha_ks_batch.append(objs[i]+duals[i].T@produce)
   g_ks.append(gks_batch)
   alpha_ks.append(alpha_ks_batch)
   first_stage_sol = solve_master_problem_ml(produce,g_ks,alpha_ks,senario_prob,production_cost,produce_limit)
   obj_value = first_stage_sol.value
   new_produce = first_stage_sol.var_dict["produce"].value
   new_limit = first_stage_sol.var_dict["value"].value
   if np.abs(obj_value - objctive_values[-1])<= epsilon:</pre>
       print("Terminating condition satisfied !")
       break
   else:
       pass
   objctive_values.append(obj_value)
   produce,limit = new_produce,new_limit # swap the values
   iter = iter+1
   print(f"\n-----")
   print(f"\nproduction is {produce}")
   print(f"\nobjctive value is {first_stage_sol.value}\n")
₹
     -----Iteration no. 1-----
    production is [[299.9999989]
     [299.9999999]]
    objctive value is -1727.7034315843757
    -----Iteration no. 2-----
    production is [[120.00000283]
     [299.99999952]]
    objctive value is -1609.9999916085671
    Terminating condition satisfied !
print("---- Results using Multicut Method----")
print(f"\nproduction is {produce}")
print(f"\nobjctive value is {first_stage_sol.value}\n")
---- Results using Multicut Method----
    production is [[120.00000283]
     [299.99999952]]
    objctive value is -1609.999988313576
```