

$L_p(\Omega, \mathcal{F}, P)$  is a complete space  $\rightarrow$  Every Cauchy sequence has a limit.

Linear + Normed + Complete  $\rightarrow$  Banach Space  
 (vector space)  
 "Theory of Linear Operators" (Baraen text)

We discuss risk measures of random variables  
 that are elements of  $L_p(\Omega, \mathcal{F}, P)$ .

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3 important spaces :  
 • finite dimensional  
 • Banach spaces  
 • space of continuous functions

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$\rho: \mathbb{Z} \rightarrow \mathbb{R}$  (assigns real number to random variable of random losses)

Axioms: (R1) Convexity:  $\forall z, v \in \mathbb{Z}, \forall t \in [0,1]$

$$\text{then } \rho(tz + (1-t)v) \leq t\rho(z) + (1-t)\rho(v)$$

(R2) Monotonicity: if  $z, v \in \mathbb{Z}, z \leq v$  ( $z(w) \leq v(w)$ )  
 Then  $\rho(z) \leq \rho(v)$  with probability 1

(R3) Translation Equivalence:  $c \in \mathbb{R}, z \in \mathbb{Z}$  then

$$\rho(z + c\mathbf{1}) = \rho(z) + c \quad \begin{matrix} \mathbf{1} \in \mathbb{Z} \\ \text{RV that is always equal to 1} \end{matrix}$$

(R4) Positive Homogeneity: if  $\gamma > 0$  and  $z \in \mathbb{Z}$  then

$$\rho(\gamma z) = \gamma \rho(z)$$

Risk measure  $\rho$  is coherent if it satisfies (R1) - (R4)

- In finite dimension, convex functions are continuous
- In infinite dimension, convex functions are not necessarily continuous.
- In  $\mathbb{L}^p$ , functions satisfying (R1), (R2) are continuous.  
Proof omitted

### Risk measure Examples:

- ①  $\rho(z) = E[z]$  (Everything comes from Expectation being a linear operator)
- convexity  $E[tz + (1-t)v] = tE[z] + (1-t)E[v]$  (relaxation)
- monotonicity  $z \leq v \Rightarrow E[z] \leq E[v]$
- translation equivalence  $E[z + c\mathbb{1}] = E[z] + c$
- positive homogeneity  $E[\gamma z] = \gamma E[z] + \gamma$  (relaxation)
- ② mean-semideviation  $\underline{z} = \underline{z}_p(\Omega, \mathcal{F}, P)$ ,  $p \in [1, \infty]$ ,  $p: \mathbb{Z} \rightarrow \mathbb{R}$
- $$\rho(z) = E[z] + \alpha \| (z - E[z])_+ \|_p, \alpha \in [0, 1]$$

Suppose  $\alpha = 1$ , then  $\rho(z) = E[z] + \| (z - E[z])_+ \|_p$

$$= E[z] + \underbrace{\left( E[(z - E[z])_+]^p \right)}_{\max(0, z - E[z])}^{1/p}$$

$\Rightarrow$  Semideviation: we only consider deviations from mean that are bad.

Clearly,  $\rho(z) \geq E[z]$

first we show  $\|\cdot\|_p$  is a valid norm:

$$(1) \|v+z\| \leq \|v\| + \|z\|$$

$$(2) \|\gamma z\| = |\gamma| \|z\| \quad \forall \gamma \in \mathbb{R}$$

Entropic Risk measure (popular in dynamical systems/economics)

not coherent since it does not satisfy positive homogeneity

Let

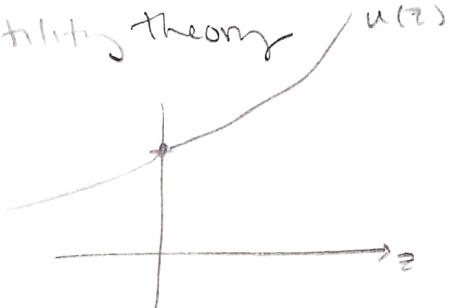
$$z \in \mathbb{Z} \Leftrightarrow E[e^{\kappa|z|}] < +\infty \quad \text{if } \kappa > 0$$

$$\rho(z) = \frac{1}{\kappa} \ln(E[e^{\kappa z}])$$

connection to Von Neumann Utility theory

$$z \rightarrow u(z) = e^{\kappa z}$$

$$E[u(z)] = E[e^{\kappa z}]$$



$$\rho(z) = u^{-1}(E[u(z)])$$

$$= \frac{1}{\kappa} \ln(E[e^{\kappa z}])$$

then

$$e^{\kappa\rho} = E[e^{\kappa z}]$$

Convexity of  $\rho(z)$

$$\begin{aligned}\rho(\alpha z + (1-\alpha)v) &= \frac{1}{\kappa} \ln(E[\exp(\alpha \kappa z + (1-\alpha)\kappa v)]) \\ &= \frac{1}{\kappa} \ln(E[(e^{\kappa z})^\alpha (e^{\kappa v})^{1-\alpha}])\end{aligned}$$

By Hölder's Inequality

$$E[(e^{\kappa z})^\alpha (e^{\kappa v})^{1-\alpha}] \leq (E[e^{\kappa z}])^\alpha (E[e^{\kappa v}])^{1-\alpha}$$

## 1) Optimized Certainty Equivalent

$\alpha: \mathbb{R} \rightarrow \mathbb{R}$  non decreasing, convex w.r.t.  $z$  (a.s.)  
 $\text{fun}(t) = ct^{\rho} \forall t \in \mathbb{R}, c > 0, \rho \geq 1$

$$\rho(z) = \inf_{t \in \mathbb{R}} \{ z + E[u(z-t)] \}$$

$\rho$  is convex measure of risk and coherent if  $u$  is positive homogeneous.

## 2) Value at Risk

at level  $\alpha \in (0,1), z \in \mathbb{Z}$

Var is the  $(1-\alpha)$  quantile of distribution of  $z$

$$\text{VaR}_{\alpha}(z) = \inf \{ \eta : F_z(\eta) \geq 1-\alpha \} = F_z^{-1}(1-\alpha)$$

VaR is monotonic, has translation property, and positive homogeneous but it is not convex.

Example:  $Z \sim \text{Bern}(p)$

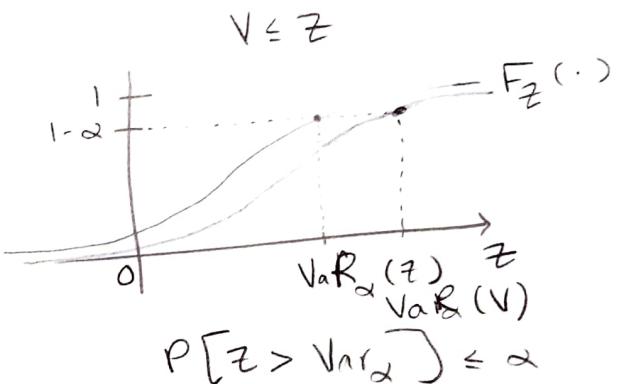
$V \perp\!\!\!\perp Z$  with same dist.

For  $p < \alpha < 1$  we have  $\text{VaR}_{\alpha}(z) = \text{VaR}_{\alpha}(V) = 0$

For  $p < \alpha < 1 - (1-p)^2$ ,  $\text{VaR}_{\alpha}(\lambda z + (1-\lambda)V) > 0 = \lambda \text{VaR}_{\alpha}(z) + (1-\lambda)\text{VaR}_{\alpha}(V)$

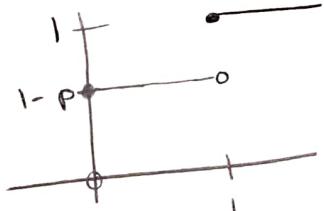
$$\text{VaR}_{\alpha}(z) = \begin{cases} 1 & \text{if } \alpha < p \\ 0 & \text{if } \alpha \geq p \end{cases}$$

$\lambda \in (0,1)$   
 contradicting convexity

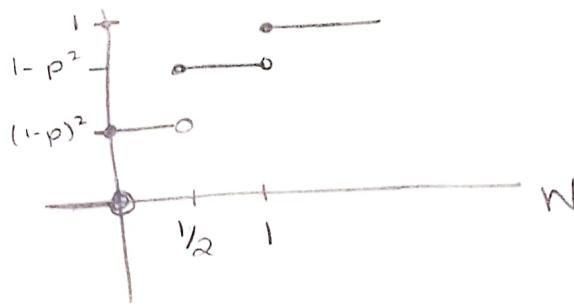


$$P(Z=0) = 1-p$$

$$P(Z=1) = p$$

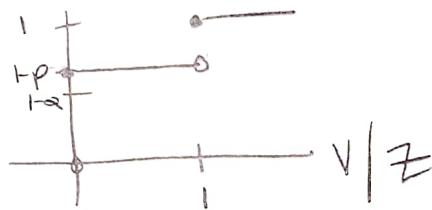


$$W = \frac{1}{2} Z + \frac{1}{2} V$$



We may choose  $\alpha$ :

$$p < \alpha < 1 - (1-p)^2$$



$$\text{VaR}_\alpha(V) = \text{VaR}_\alpha(Z) = 0$$

$$\text{VaR}_\alpha(W) = \frac{1}{2}$$

$\Rightarrow$  does not encourage diversification  
since risk is not reduced  
by combining uncorrelated risks.

VaR prefers large losses with small probability (prefers  $Z$  or  $V$  over  $W$ )

3) Average Value at Risk  $z_\alpha$  at level  $\alpha \in (0, 1]$  is

$$\text{AVaR}_\alpha^+(Z) = \frac{1}{\alpha} \int_{\text{VaR}_\alpha(Z)}^{\infty} \text{VaR}_\beta(Z) d\beta$$

if the  $(1-\alpha)$ -quantile of  $Z$  is unique, then

$$P[Z \geq \text{VaR}_\alpha(Z)] = \alpha \quad \text{and we change variables to obtain}$$

$$\text{AVaR}_\alpha(Z) = \frac{1}{\alpha} \int_{\text{VaR}_\alpha(Z)}^1 z dF_Z(z) = E[Z | Z \geq \text{VaR}_\alpha(Z)]$$

So it is also called the Conditional Value at Risk  
with assumption that  $(1-\alpha)$ -quantile is unique

$\mathbb{G}$ -profits

$$\text{AVaR}_{\alpha}^{\pm}(G) \doteq \text{AVaR}_{\alpha}^{+}(-G)$$

$$= \inf_{\eta} \left\{ \eta + \frac{1}{2} E[(-G - \eta)_+]^2 \right\}$$

$$t = -\eta$$

$$= \inf_t \left\{ t + \frac{1}{2} E[(t - G)_+]^2 \right\}$$

minimize

Risk measure for Discrete RV (Homework) Next

$$\rho: \mathbb{R}^K : P(Z = z_i) = p_i \quad \text{for } i=1, \dots, K$$

$$\rho(z) = E[Z] + \delta E[(z - E[Z])_+] \quad (\text{first order semideviation})$$

$$\text{Let } \mu = E[Z] = \frac{1}{K} \sum_{j=1}^K p_j z_j \quad \text{then}$$

$$\rho(z) = \mu + \delta \sum_{j=1}^K \underbrace{p_j (z_j - \mu)_+}_{v_j \leftarrow \max(0, z_j - \mu)}$$

To minimize  $\rho(z)$  we can write:

$$\min_{\mu} \mu + \delta \sum_{j=1}^K p_j v_j$$

$$\text{s.t. } v_j \geq z_j - \mu \quad j=1, \dots, K$$

$$v_j \geq 0 \quad j=1, \dots, K$$

$$2 \text{ stage problem: } \min c^T x + \rho(Q(x))$$

$$\text{s.t. } x \in X$$

$w_j = \underline{Q}_j(x) - \text{Lower bound for } Q_j(x) \quad (\text{multicut method})$

$$Q_j(x) \geq w_j \rightarrow \text{calculate } \rho(w)$$

For Bern Example

$$\text{AVaR}_\alpha(z) = \begin{cases} \frac{1}{2} & 1 \cdot d\beta = 1 \quad \alpha < p \\ \frac{1}{2} & 1 \cdot d\beta = \frac{p}{\alpha} \quad \alpha \geq p \end{cases}$$

$$U(z) = (z - n)_+$$

Extremal Representation: for  $\alpha \in [0, 1]$  we have

$$\text{AVaR}_\alpha(z) = \inf_{n \in \mathbb{R}} \left\{ n + \frac{1}{2} E[(z - n)_+] \right\}$$

proof: we have

$$F^{(-2)}(z, 1) = \text{AVaR}_1(z) = \int_0^1 F_z^{-1}(\beta) d\beta = E[z]$$

$$\text{AVaR}_\alpha(z) = \frac{1}{2} \int_0^\alpha \text{VaR}_\gamma(z) d\gamma$$

$$= \frac{1}{2} \int_0^\alpha F_z^{-1}(1-\gamma) d\gamma \quad \beta = 1-\gamma$$

$$= \frac{1}{2} \int_1^{1-\alpha} F_z^{-1}(\beta) d\beta$$

$$= \frac{1}{2} \int_{1-\alpha}^1 F_z^{-1}(\beta) d\beta = \frac{1}{2} (E[z] - F_z^{(-2)}(1-\alpha))$$

Substituting  $F_z^{(-2)}(\alpha) = \sup_{n \in \mathbb{R}} \{ \alpha n - E[(n-z)_+] \}$  we obtain  
 (does not require unique  $(1-\alpha)$ -quantile) (conjugate duality of  $F_z^{(z)}$  and  $F_z^{(-2)}$ )

$$\text{AVaR}_\alpha(z) = \frac{1}{2} E[z] - \frac{1}{2} \sup_{n \in \mathbb{R}} \{ (1-\alpha)n - E[(n-z)_+] \}$$

$$= \frac{1}{2} \inf_{n \in \mathbb{R}} \{ -(1-\alpha)n + E[z] - E[(n-z)_+] \}$$

observe  $z + (n-z)_+ = n + (z-n)_+$ , we get

$$\text{AVaR}_\alpha(z) = \inf_{n \in \mathbb{R}} \left\{ n + \frac{1}{2} E[(z-n)_+] \right\}$$

$$\begin{aligned}
 \text{AVaR}_\alpha^+(z) &= \min_{\eta} \left\{ \eta + \frac{1}{\alpha} E[(z - \eta)_+] \right\} \\
 &= \min_{\eta} \left\{ \eta + \frac{1}{\alpha} \sum_{k=1}^K p_k (z_k - \eta)_+ \right\} \\
 &= \min_{\eta, v} \left\{ \eta + \frac{1}{\alpha} \sum_{k=1}^K p_k v_k \right\} \\
 &\quad \text{s.t. } v_k \geq z_k - \eta \quad k = 1, \dots, K \\
 &\quad v_k \geq 0
 \end{aligned}$$

AVaR is bad risk measure for Garden state example b/c it's too conservative. we may use

$$\min (1-\lambda)E[z] + \lambda \text{AVaR}_\alpha^+(z)$$

Convexity of  $\text{AVaR}_\alpha^+(\cdot)$

$$\text{AVaR}_\alpha(z) = \min_{\eta} \left\{ \eta + \frac{1}{\alpha} E[(z - \eta)_+] \right\} \quad \hat{\eta}_z - \text{optimal}$$

$$\text{AVaR}_\alpha(v) = \min_{\eta} \left\{ \eta + \frac{1}{\alpha} E[(v - \eta)_+] \right\} \quad \hat{\eta}_v - \text{optimal}$$

$$\text{AVaR}_\alpha(\lambda z + (1-\lambda)v) = \min_{\eta} \left\{ \eta + \frac{1}{\alpha} E[(\lambda z + (1-\lambda)v - \eta)_+] \right\} \quad \text{choose } \eta = \lambda \hat{\eta}_z + (1-\lambda) \hat{\eta}_v$$

$$\leq \lambda \hat{\eta}_z + (1-\lambda) \hat{\eta}_v + \frac{1}{\alpha} E[(\lambda z + (1-\lambda)v - (\lambda \hat{\eta}_z + (1-\lambda) \hat{\eta}_v))_+]$$

$$= \lambda \hat{\eta}_z + (1-\lambda) \hat{\eta}_v + \frac{1}{\alpha} E[(\lambda(z - \hat{\eta}_z) + (1-\lambda)(v - \hat{\eta}_v))_+] \quad \boxed{(\cdot)_+ \text{ is convex}}$$

$$\leq \lambda (\hat{\eta}_z + \frac{1}{\alpha} E[(z - \hat{\eta}_z)_+]) + (1-\lambda) (\hat{\eta}_v + \frac{1}{\alpha} E[(v - \hat{\eta}_v)_+])$$

$$= \lambda \text{AVaR}_\alpha^+(z) + (1-\lambda) \text{AVaR}_\alpha^+(v)$$

$$\min_x \mathbf{c}^T \mathbf{x} + \rho(\mathbf{w}) = \min_{\mathbf{x}, \mathbf{v}} \mathbf{c}^T \mathbf{x} + \mu + \delta \sum_{j=1}^K p_j v_j$$

$$v_j \geq w_j - \mu \quad (*)$$

$$v_j \geq 0$$

$$\mu = \sum_{j=1}^K p_j w_j$$

$w_j$  - cost of scenario  $j \rightarrow$  defined by cuts

$v_j$  - upper bound that follows from representation of risk measure

$$\min \mathbf{c}^T \mathbf{x} + E[Q(\mathbf{x})]$$

$Q(\mathbf{x})$  has realizations  $Q_j(\mathbf{x}) \quad j=1, \dots, K$  with prob.  $p_j$

multicut Algo:

master problem  $\min \mathbf{c}^T \mathbf{x} + \boxed{\sum_k p_k w_k} \rightarrow$  is lower bound for  $E[Q(\mathbf{x})]$   
 $w_k \geq$  cuts for scenario  $k=1, \dots, K$

$$\mathbf{x} \in X$$

Now we want to solve  $\min \mathbf{c}^T \mathbf{x} + \rho(Q(\mathbf{x}))$

$\rho(w)$  is a lower bound of  $\rho(Q(\mathbf{x}))$

$\rho(w)$  has a LP representation that can be absorbed into the master problem see constraints in  $(*)$ .

~~Typically min of 2 convex functions is not convex~~

But since  $\eta + \frac{1}{2} E[(z-\eta)_+]$  is jointly convex

in  $(\eta, z)$  we have  $\min_{\eta} \left\{ \eta + \frac{1}{2} E[(z-\eta)_+] \right\}$

is convex.

Additional Thm:  $f(x, y)$  jointly convex in  $(x, y)$

then  $F(x) = \min_y \{f(x, y)\}$  is convex (in  $x$ )

\* Can prove for extra credit.

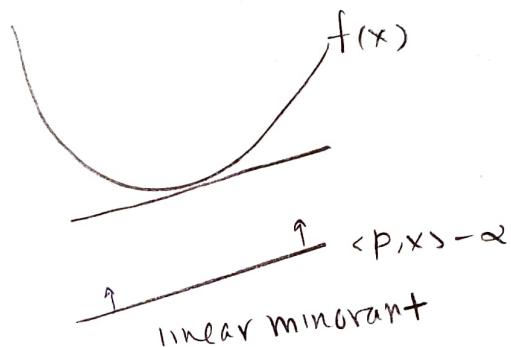
Other properties for AVaR follows directly from

$$\text{AVaR}_{\alpha}(z) = \int_0^1 \text{VaR}_\beta(z) d\beta$$

so AVaR is coherent risk measure.

### Conjugate Duality for Risk Measures

Recall convex conjugate functions



$$f(x) \geq \langle p, x \rangle - \alpha \quad \forall x$$

$$\alpha \geq \langle p, x \rangle - f(x) \quad \forall x$$

$$\alpha^* = \sup_x \{ \langle p, x \rangle - f(x) \}$$

(smallest possible  $\alpha$  is largest RHS)

$$f^*(p) = \sup_x \{ \langle p, x \rangle - f(x) \}$$

$$f(x) = \sup_p \{ \langle p, x \rangle - f^*(p) \} = f^{**}(x)$$

(Werner Fenchel Type Lectures on this topic available at Princeton)

$\rho(z)$  measure of risk that is convex and finite

$$\rho(f) < +\infty \quad \forall f \in \mathcal{Z} = \mathcal{L}_p(\Omega, \mathcal{F}, P)$$

$$1 \leq p < \infty$$

$$\rho^*(y) = \sup_{z \in \mathcal{Z}} \left\{ \underbrace{\langle y, z \rangle}_{\text{---}} - \rho(z) \right\}$$

• linear continuous functional on  $\mathcal{Z}$   
which must have form:

$$\langle y, z \rangle = \int_{\Omega} z(\omega) y(\omega) P(d\omega) \quad (*)$$

In finite dimension

$$\langle c, x \rangle = c_1 x_1 + c_2 x_2 + \dots + c_n x_n$$

$$\langle c, x \rangle_p = p_1 c_1 x_1 + p_2 c_2 x_2 + \dots + p_n c_n x_n = \sum_{i=1}^n p_i c_i x_i$$

$$\text{where } \sum_{i=1}^n p_i = 1, p_j \geq 0$$

$\langle \cdot, \cdot \rangle_p$  prevents very large dimension to blow up  $\rightarrow \infty$   
as  $\langle \cdot, \cdot \rangle$  does.

Let  $n \rightarrow \infty$  then  $\langle c, x \rangle < \infty$  if  $\sum_{i=1}^{\infty} c_i^2 < +\infty$   
 $\sum_{i=1}^{\infty} x_i^2 < +\infty$

then we recover the form  $(*)$

Let  $\mathcal{Z} = \mathcal{L}_2(\Omega, \mathcal{F}, P)$  then  $\forall z, y \in \mathcal{Z}$ :

$$\int_{\Omega} z^2(\omega) P(d\omega) < +\infty, \quad \int_{\Omega} y^2(\omega) P(d\omega) < +\infty$$

So

$$\int_{\Omega} z(\omega) y(\omega) P(d\omega) \leq \frac{1}{2} \int_{\Omega} (z^2(\omega) + y^2(\omega)) P(d\omega) < +\infty$$

major question in functional analysis was the representation of all linear functionals which is

$$\langle z, \zeta \rangle = \int_{\Omega} z(\omega) \zeta(\omega) P(d\omega)$$

$$z^* = p^*(\zeta) = \sup_{z \in Z} \{ \langle z, \zeta \rangle - p(z) \}$$

Biconjugate function of  $p$

$$p^{**}(z) = \sup_{\zeta \in Z} \{ \langle z, \zeta \rangle - p^*(\zeta) \}, z \in Z$$

$$\langle \gamma, z \rangle - \alpha$$

Fenchel Moreau Thm: if  $p$  is proper, convex and lower semicontinuous then  $p^{**} = p$

Moreau - extend Fenchel theory to infinite dimensional spaces.

$Z^*$  is the space where all linear continuous functionals exist. (Dual space)

Dual Representation of Coherent measures of Risk (Thm)

if  $p: Z \rightarrow \bar{\mathbb{R}}$  is convex, proper, LSC, then  $p(z) = p^{**}(z)$

(i) monotonicity condition is satisfied  $\Leftrightarrow$  every  $\zeta \in A$  is nonnegative (where  $A = \text{dom } p^*$ )

(ii) translation condition satisfied  $\Leftrightarrow$

$$\int_{\Omega} \zeta(\omega) P(d\omega) = 1, \forall \zeta \in A$$

(iii) positive homogeneity satisfied  $\Leftrightarrow p(\cdot)$  can be represented in the form  $p(z) = \sup_{\zeta \in A} \{ \langle z, \zeta \rangle \} \quad \forall z \in Z$

For (ii), ( $\Rightarrow$ )

$$\begin{aligned}\rho^*(\xi) &= \sup_z \left\{ \langle \xi, z \rangle - \rho(z) \right\} \\ &= \sup_{z,c} \left\{ \langle \xi, z+c \rangle - \rho(z+c) \right\} \\ &= \sup_{z,c} \left\{ \langle \xi, z \rangle + \langle \xi, c\mathbb{1} \rangle - \rho(z) - c \right\} \\ &= \sup_z \left\{ \langle \xi, z \rangle - \rho(z) \right\} + \sup_c \left\{ \langle \xi, c\mathbb{1} \rangle - c \right\} \\ &= \rho^*(\xi) + \sup_c \left\{ \langle \xi, c\mathbb{1} \rangle - c \right\}\end{aligned}$$

So  $\sup_c \left\{ \langle \xi, c\mathbb{1} \rangle - c \right\} = 0$  only possible if  
 $\langle \xi, \mathbb{1} \rangle = 1$ .  $\square$

By (i), (ii)  $\xi$  is a probability density!

Recall convex conjugate functions

- $\rho(z)$  convex

- $\rho^*(y) = \sup_{z \in \mathbb{Z}} \{ \langle y, z \rangle - \rho(z) \}$



- $\rho(z) = \sup_{y \in A} \{ \langle y, z \rangle - \rho^*(y) \}$

where  $A = \text{dom } \rho^*$

for (i), ( $\Rightarrow$ ) Suppose  $\rho$  satisfies monotonicity condition,

but  $\exists y \in A : P[y < 0] > 0$ . Then  $\langle \mathbf{1}_{\{y < 0\}}, \cdot \rangle < 0$

for any  $z_0$  such that  $\rho(z_0) < +\infty$  consider the ray

$z_t = z_0 - t \mathbf{1}_{\{y < 0\}}$ . By construction,  $z_0 \geq z_t \forall t \geq 0$

and by monotonicity condition  $\rho(z_0) \geq \rho(z_t) \forall t \geq 0$ .

$$\rho^*(y) \geq \sup_{t \geq 0} \{ \langle z_t, y \rangle - \rho(z_t) \}$$

$$\geq \sup_{t \geq 0} \{ \langle z_0, y \rangle - t \langle \mathbf{1}_{\{y < 0\}}, y \rangle - \rho(z_0) \}$$

$$= +\infty$$

which contradicts assumption  $y \notin A$ . Therefore  $P[y < 0] = 0$   
 $\forall y \in A$ .

( $\Leftarrow$ ) Suppose every element of  $A$  is non-negative. Let  $z \leq v$ , then

$$\langle z, y \rangle \leq \langle v, y \rangle \quad \forall y \in A. \text{ By definition of } \rho(\cdot), \text{ in}$$

$$\rho(z) \leq \rho(v)$$

(iii) ( $\Rightarrow$ ) Let  $\rho$  be positively homogeneous. Let  $\gamma > 0$ .

$$\begin{aligned}\rho^*(\zeta) &= \sup_{z \in Z} \{ \langle z, \zeta \rangle - \rho(z) \} \\ &= \sup_{z \in Z} \{ \langle \gamma z, \zeta \rangle - \rho(\gamma z) \} \\ &= \sup_{z \in Z} \{ \gamma \langle z, \zeta \rangle - \gamma \rho(z) \} \\ &= \gamma \sup_{z \in Z} \{ \langle z, \zeta \rangle - \rho(z) \} \\ &= \gamma \rho^*(\zeta) = 0\end{aligned}$$

Plugging into dual representation

$$\begin{aligned}\rho(z) &= \sup_{\zeta \in \mathbb{X}} \{ \langle z, \zeta \rangle - \rho^*(\zeta) \} \\ &= \sup_{\zeta \in \mathbb{X}} \{ \langle z, \zeta \rangle \}\end{aligned}$$

( $\Leftarrow$ ) if  $\rho(z) = \sup_{\zeta \in \mathbb{X}} \{ \langle z, \zeta \rangle \}$  then its positively homogen.

$$\sum_{k=1}^K \mu_k = \sum_{k=1}^K \lambda_k + (\sum_{k=1}^K p_k) \lambda_0 = 1 \quad \text{by constraints}$$

$$\begin{aligned} \mu_k &= \lambda_k + p_k (1 - \sum_{k=1}^K \lambda_k) \geq \lambda_k + p_k (1 - \lambda_k \sum_{k=1}^K p_k) \\ &\quad \underbrace{\lambda_k}_{\sum_{k=1}^K \lambda_k} \quad \underbrace{\sum_{k=1}^K p_k}_{1} \\ &= \lambda_k + p_k (1 - \lambda_k) \geq 0 \end{aligned}$$

so  $\mu_k$  are probabilities. Then

$$p(z) = \max_{\frac{d\mu}{dp} \in \mathcal{A}} E^{\mu}[z] \quad (\text{Dual representation})$$

Let  $p: \mathbb{Z} \rightarrow \bar{\mathbb{R}}$  be LSC, proper, coherent risk measure. Then

- (i)  $\partial p(z)$  is a nonempty, bounded, weakly compact subset of  $\mathbb{Z}^*$  given by

$$\partial p(z) = \operatorname{argmax}_{\varphi \in \partial p(0)} \{ \langle \varphi, z \rangle \}$$

- (ii)  $p$  is Hadamard directionally differentiable at  $z$  and

$$p'(H, z) = \sup_{\{\varphi \in \partial p(z)\}} \{ \langle \varphi, H \rangle \} \quad H \in \mathbb{Z}.$$

## Dual Representation Examples

$P = \mathbb{I}$ ,  $\Omega = \{w_1, \dots, w_K\}$  with probabilities  $p_1, \dots, p_K$ .

$z_k = z(w_k)$  for  $k = 1, \dots, K$

mean semideviation

$$\rho(z) = E[z] + \alpha E[(z - E[z])_+]$$

$$= \mu + \alpha \sum_{k=1}^K p_k (z_k - \mu)_+$$

$$v_k$$

$$\mu = \sum_{k=1}^K p_k z_k$$

$$v_k = z_k - \mu$$

$$v_k \geq 0.$$

$$\rho(z) = \min \mu + \alpha \sum_{k=1}^K p_k v_k$$

$$\text{s.t. } \mu = \sum_{k=1}^K p_k z_k \quad \leftarrow (\lambda_0)$$

$$\mu + v_k \geq z_k \quad k = 1, \dots, K \quad \leftarrow (\lambda_k \geq 0)$$

$$v_k \geq 0 \quad k = 1, \dots, K$$

## Dual Problem

$$\max \lambda_0 \sum_{k=1}^K p_k z_k + \sum_{k=1}^K \lambda_k z_k$$

$$\text{s.t. } \lambda_0 + \sum_{k=1}^K \lambda_k = 1$$

$$\lambda_k \leq \alpha p_k \quad k = 1, \dots, K$$

$$\lambda_k \geq 0 \quad k = 1, \dots, K$$

$$\max \sum_{k=1}^K \lambda_k z_k \quad \text{s.t. some constraints} \quad \text{where } \mu_k = \lambda_k + p_k \lambda_0$$

For a mapping  $F: \mathbb{R}^n \rightarrow \bar{\mathbb{Z}}$ , denote  $[F(x)](\omega) = f_\omega(x)$

and consider the composite function  $\phi(\cdot) = p(F(\cdot))$

Lemma Let  $F: \mathbb{R}^n \rightarrow \bar{\mathbb{Z}}$  be a convex mapping, that is,

$$F(\lambda x + (1-\lambda)y) \leq \lambda F(x) + (1-\lambda)F(y) \text{ a.s. } \forall \lambda \in [0,1],$$

then  $F$  is continuous, directionally differentiable with directional derivative at  $\bar{x} \in \mathbb{R}^n$

$$[F'(\bar{x}, h)](\omega) = f'_\omega(\bar{x}, h), \quad \omega \in \Omega, h \in \mathbb{R}^n$$

"derivative of random function is derivative"

Furthermore,  $\phi(\cdot) = p(F(\cdot))$  is convex.

### Extension of Strassen's Thm

Suppose  $F: \mathbb{R}^n \rightarrow \bar{\mathbb{Z}}$  is convex and  $p$  is finite valued, coherent

Then  $\phi = p \circ F$  is directionally differentiable and subdifferentiable

at any  $\bar{x}$ , it has finite valued directional derivative

$\forall h \in \mathbb{R}^n$  and (Let  $\bar{z} = F(\bar{x})$ )

$$\rho'(\bar{z}, F'(\bar{x}, h)) = \sup_{\{g \in \partial p(\bar{z})\}} \left\{ \int_{\Omega} f'_\omega(\bar{x}, h) g(\omega) P(d\omega) \right\}$$

$$\partial \phi(\bar{x}) = \bigcup_{\{g \in \partial p(\bar{z})\}} \left\{ \int_{\Omega} \partial f_\omega(\bar{x}) g(\omega) P(d\omega) \right\}$$

## Law Invariant Risk Measures

Defn:  $\rho: \mathbb{Z} \rightarrow \bar{\mathbb{R}}$  is law-invariant w.r.t. the reference probability measure  $P$ , if  $\forall z, v \in \mathbb{Z}$  if

$$\{z \stackrel{D}{\sim} v\} \Rightarrow \{\rho(z) = \rho(v)\}$$

This class contains all interesting risk measures (any measure calculated w/ moments)

Consider  $\Omega = \{w_1, \dots, w_n\}$  with  $P(w_i) = \frac{1}{n}$  for  $i=1, \dots, n$ . For a RV on  $\Omega$  we can obtain the quantile function  $F_z^{-1}$  by finding permutation  $T_z: \Omega \rightarrow \Omega$ :

$$z(T_z(w_1)) \leq z(T_z(w_2)) \leq \dots \leq z(T_z(w_n))$$

and we set  $F_z^{-1}(p) = z(T_z(w_i))$  whenever  $\frac{i-1}{n} < p \leq \frac{i}{n}$

for  $i=1, \dots, n$ . Since 2 RVs,  $z$  and  $v$ , have same distribution if their quantile functions coincide, 2 permutations can be found,  $T_z$  and  $T_v$ , such that

$$z(T_z(w_i)) = v(T_v(w_i))$$

thus for  $T = T_v T_z^{-1}$  we get

$$z(w_i) = v(T(w_i)) \quad i=1, \dots, n$$

## Kusuoka Representation

Let  $\Omega = \{\omega_1, \dots, \omega_n\}$  with  $P[\omega_i] = 1/n$ . A convex risk measure  $\rho: \mathbb{R} \rightarrow \mathbb{R}$  is law-invariant if and only if a set  $\Delta$  of probability vectors in  $\mathbb{R}^n$  exists such that

$$\rho(z) = \sup_{x \in \Delta} \left\{ \sum_{i=1}^n x_i \text{AN.R}_{i,n}(z) \right\} + z \in \mathbb{Z}$$

Proof: By dual representation

$$\rho(z) = \max_{\xi \in \mathcal{X}} \left\{ \frac{1}{n} \sum_{i=1}^n z_i \xi_i \right\}, \quad z \in \mathbb{Z}$$

where  $z_i = z(\omega_i)$   
 $\xi_i = \xi(\omega_i)$

Denote  $z_{[1]} \leq z_{[2]} \leq \dots \leq z_{[n]}$  ordered realizations of  $z$

By Law Invariance of  $\rho$  we have

$$\rho(z) = \max_{\xi \in \mathcal{X}} \left\{ \frac{1}{n} \sum_{i=1}^n z_{[i]} \xi_i \right\}, \quad z \in \mathbb{Z}$$

Let  $\xi \in \mathcal{X}$ .  $\rho^*(\xi) = \max_{z \in \mathbb{Z}} \left\{ \frac{1}{n} \sum_{i=1}^n \xi_i z_i - \rho(z) \right\}$

$$= \max_{z \in \mathbb{Z}} \left\{ \frac{1}{n} \sum_{i=1}^n \xi_i z_{[T(i)]} - \rho(z) \right\} \quad \begin{matrix} \text{by Law Invariance} \\ (\rho(z \circ T) = \rho(z)) \end{matrix}$$

$$= \max_{z \in \mathbb{Z}} \left\{ \frac{1}{n} \sum_{j=1}^n \xi_{T^{-1}(j)} z_j - \rho(z) \right\}$$

$$= \rho^*(\xi \circ T^{-1})$$

So  $\mathcal{X}$  is closed under permutation. Then

By Littlewood-Hardy-Polya inequality we have

$$\sum_{i=1}^n z_{[i]} \xi_i = \sum_{i=1}^n z_{[i]} \xi_{[i]}$$

$$\text{Then } \rho(z) = \max_{\{\zeta\in\mathcal{A}\}} \left\{ \frac{1}{n} \sum_{i=1}^n z_{[i]} \zeta_{[i]} \right\}, \quad z \in \mathbb{Z}$$

Denote  $\zeta_{[0]} = 0$ . we may rewrite the sum (integration by parts)

$$\begin{aligned} \frac{1}{n} \sum_{i=1}^n z_{[i]} \zeta_{[i]} &= \frac{1}{n} \sum_{i=1}^n (\zeta_{[i]} - \zeta_{[i-1]}) \sum_{j=i}^n z_{[j]} \\ &= \sum_{i=1}^n \frac{n-i+1}{n} (\zeta_{[i]} - \zeta_{[i-1]}) \frac{1}{n-i+1} \sum_{j=i}^n z_{[j]} \end{aligned}$$

$$\text{Define } \lambda_i = \frac{n-i+1}{n} (\zeta_{[i]} - \zeta_{[i-1]}), \quad i=1, \dots, n$$

$$\rho(z) = \max_{\{\zeta\in\mathcal{A}\}} \left\{ \underbrace{\sum_{i=1}^n \lambda_i \frac{1}{n-i+1} \sum_{j=i}^n z_{[j]}}_{\text{AVaR}_{\alpha_i}(z)} \right\}$$

We see  $\lambda_i \geq 0$  and

$$\sum_{i=1}^n \lambda_i = \sum_{i=1}^n \frac{n-i+1}{n} (\zeta_{[i]} - \zeta_{[i-1]}) = \sum_{i=1}^n \frac{1}{n} \zeta_{[i]} = 1$$

Thm: Let  $\mathcal{Z} = \mathcal{L}_p(\Omega, \mathcal{F}, P)$ ,  $p \in [1, \infty)$  where  $\Omega$  is standard and atomless. Then a proper LSC convex risk measure  $\rho: \mathcal{Z} \rightarrow \bar{\mathbb{R}}$  is law invariant if and only if a set  $\Delta$  of probability measures on the interval  $(0, 1]$  exists such that

$$\rho(z) = \sup_{\lambda \in \Delta} \left\{ \int \text{AVaR}_{\alpha}(z) \lambda(d\alpha) \right\} \quad \forall z \in \mathcal{Z}$$

Consistency with increasing convex order  
 $\eta + \frac{1}{\alpha} E[(z_1 - \eta)_+] \leq \eta + \frac{1}{\alpha} E[(z_2 - \eta)_+] \forall \eta, \alpha \in (0, 1]$

$$\Rightarrow \min_{\eta} \left\{ \eta + \frac{1}{\alpha} E[(z_1 - \eta)_+] \right\} \leq \min_{\eta} \left\{ \eta + \frac{1}{\alpha} E[(z_2 - \eta)_+] \right\}$$

$$\Rightarrow \text{AVaR}_{\alpha}(z_1) \leq \text{AVaR}_{\alpha}(z_2) + \alpha$$

$$\Rightarrow \int_0^1 \text{AVaR}_{\alpha}(z_1) \lambda(d\alpha) \leq \int_0^1 \text{AVaR}_{\alpha}(z_2) \lambda(d\alpha)$$

$$\Rightarrow \sup_{\lambda \in \Delta} \left\{ \int_0^1 \text{AVaR}_{\alpha}(z_1) \lambda(d\alpha) \right\} \leq \sup_{\lambda \in \Delta} \left\{ \int_0^1 \text{AVaR}_{\alpha}(z_2) \lambda(d\alpha) \right\}$$

$$\Rightarrow p(z_1) \leq p(z_2)$$

12/4/24 Conditional Risk Mappings | Dynamical Models

Sample space  $\Omega$  with sigma algebras  $\mathcal{F}_1 \subset \mathcal{F}_2$  and a probability measure  $P$  on  $(\Omega, \mathcal{F}_2)$ . Consider spaces

$$\mathbb{Z}_2 = \mathcal{L}_P(\Omega, \mathcal{F}_1, P), \quad \mathbb{Z}_1 = \mathcal{L}_P(\Omega, \mathcal{F}_2, P)$$

Observation  $t=1$

$$\mathcal{F}_1 \subset \mathcal{F}_2$$

$\sqsubseteq$

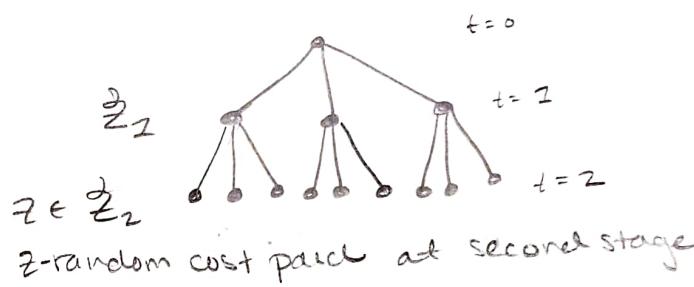
events that can be distinguished at stage  $t=1$   
(context)

•  $p(z)$  may be  $\mathcal{F}_2$  measurable

$$p: \mathbb{Z}_2 \rightarrow \mathbb{Z}_1$$

$p$  is a coherent conditional risk

mapping if it satisfies the following



R1) Convexity:  $p(\alpha z + (1-\alpha)v) \leq \alpha p(z) + (1-\alpha)p(v)$

$$\forall z, v \in \mathbb{Z}_2, \forall \alpha \in [0, 1]$$

R2) Monotonicity: if  $v, z \in \mathbb{Z}_2$  and  $z \leq v$ , then  $p(z) \leq p(v)$

R3) Translation

Equivariance: if  $y \in \mathbb{Z}_1$  and  $z \in \mathbb{Z}_2$ , then  $p(z+y) = p(z) + y$

R4) Positive Homogeneity: if  $\gamma \geq 0$  and  $z \in \mathbb{Z}_2$  then

$$p(\gamma z) = \gamma p(z)$$

where " $\leq$ " are understood in the  $P$ -almost sure sense, (pointwise)

A mapping  $p: \mathbb{Z}_2 \rightarrow \mathbb{Z}_1$  satisfying (R1) - (R3) is a convex conditional risk mapping.

## I) Conditional Expectation

The mapping  $E[\cdot | \mathcal{F}_2] : \mathbb{Z}_2 \rightarrow \mathbb{Z}_2$  is a conditional risk mapping

For any  $p \geq 1$  and  $z \in L_p(\Omega, \mathcal{F}_2, P)$  Jensen's inequality

implies  $E[|z|^p | \mathcal{F}_2] \geq |E[z | \mathcal{F}_2]|^p$  hence

$$\int_{\Omega} |E[z | \mathcal{F}_2]|^p dP = \int_{\Omega} E[|z|^p | \mathcal{F}_2] dP = E[|z|^p] < +\infty$$

Thus  $E[\cdot | \mathcal{F}_2]$  maps  $\mathbb{Z}_2$  to  $\mathbb{Z}_2$ . Conditional Expectation is a linear operator so (R1), (R4) follow. (R2), (R3) also follow for conditional expectation.

## 2) Conditional AVaR

For  $\alpha \in (0, 1]$  define  $AVaR_{\alpha}(\cdot | \mathcal{F}_2) : \mathbb{Z}_2 \rightarrow \mathbb{Z}_2$  as

$$[AVaR_{\alpha}(z | \mathcal{F}_2)](w) = \inf_{y \in \mathbb{Z}_2} \left\{ y(w) + \frac{1}{\alpha} E[(z - y)_+ | \mathcal{F}_2](w) \right\}, \quad w \in \Omega.$$

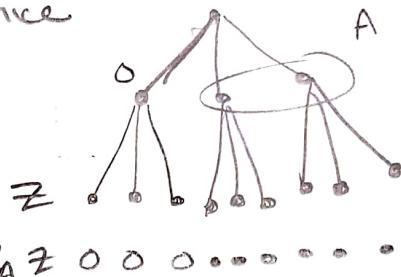
## Local Properties of Conditional Risk Mappings.

Suppose  $\rho: \mathbb{Z}_2 \rightarrow \mathbb{Z}_2$  satisfies (R1) - (R4) then

$$\rho(1\mathbb{I}_A z) = \mathbb{I}_A \rho(z) \quad \forall A \in \mathcal{F}_1, z \in \mathbb{Z}_2$$

Proof: Consider  $\rho: \mathbb{Z}_2 \rightarrow \mathbb{Z}_2$  and nonnegative function  $\xi \in \mathbb{Z}_2^*$  such that

$$\int_{\Omega} \xi(w) dP(w) = 1, \text{ we associate } \mathbb{Z}$$



$$\rho_{\xi}(z) \doteq \int_{\Omega} \xi(w) \rho(z(w)) dP(w), \quad z \in \mathbb{Z}_2$$

Conditions (R1) - (R4) for  $\rho$  imply the corresponding condition (R1) - (R4) for  $\rho_{\xi}$ , hence  $\rho_{\xi}$  is a coherent risk measure defined on  $\mathbb{Z}_2 = \mathcal{L}_{\rho}(\Omega, \mathcal{F}_2, P)$ . For  $B \in \mathcal{F}_1$  we get by (R3)

$$\begin{aligned} \rho_{\xi}(z + \alpha \mathbb{I}_B) &= \int_{\Omega} \xi(w) [\rho(z) + \alpha \mathbb{I}_B](w) dP(w) \\ &= \rho_{\xi}(z) + \alpha \int_B \xi(w) dP(w) \quad \forall \alpha \in \mathbb{R} \end{aligned}$$

Since  $\rho_{\xi}$  is coherent it has a dual representation (see latest book for proof, using conditional expectations)

## Dynamic Measures of Risk

$(z_1, z_2, \dots, z_T)$  sequence of random costs where  $z_t$  is observed at time  $t$ . Probability space  $(\Omega, \mathcal{F}, P)$  with filtration  $\mathcal{F}_1 \subset \mathcal{F}_2 \subset \dots \subset \mathcal{F}_T \subset \mathcal{F}$  and assume  $\mathcal{F}_1 = \{\emptyset, \Omega\}$   
 $\mathbb{Z}_t = \mathcal{L}_P(\Omega, \mathcal{F}_t, P), P \in [1, \infty), \mathbb{Z}_{t,T} = \mathbb{Z}_t \times \mathbb{Z}_{t+1} \times \dots \times \mathbb{Z}_T$ .

Defn A dynamic risk measure is a sequence of mappings  
 $p_{t,T} : \mathbb{Z}_{t,T} \rightarrow \mathbb{Z}_t, t=1, \dots, T$  satisfying for all  $t$  and all  $(z_t, \dots, z_T)$  and  $(w_t, \dots, w_T)$  in  $\mathbb{Z}_{t,T}$  the monotonicity property:

If  $(z_t, \dots, z_T) \leq (w_t, \dots, w_T)$  then

$$p_{t,T}(z_t, \dots, z_T) \leq p_{t,T}(w_t, \dots, w_T)$$

The value of the "tail risk measure"  $p_{t,T}(z_t, \dots, z_T)$  can be interpreted as a fair one time  $\mathcal{F}_t$ -measurable charge we would pay at time  $t$  instead of sequence of random costs:  $z_t, \dots, z_T$

Defn: A dynamic risk measure  $\{p_{t,T}\}_{t=1}^T$  is called time consistent if  $\forall 1 \leq t \leq \theta \leq T$  all sequences  $z, w \in \mathbb{Z}_{t,T}$  the conditions  $z_k = w_k, k = t, \dots, \theta-1$  and  $p_{\theta,T}(z_\theta, \dots, z_T) \leq p_{\theta,T}(w_\theta, \dots, w_T)$  imply that  $p_{t,T}(z_t, \dots, z_T) \leq p_{t,T}(w_t, \dots, w_T)$

• Needs to be assumed, does not follow from the definition of dynamic risk measures.

For a dynamic risk measure  $\{P_{t,T}\}_{t=1}^T$  we can define broader family of conditional risk measures by setting

$$P_{\tau,\theta}(z_\tau, \dots, z_\theta) = P_{\tau,T}(z_\tau, \dots, z_\theta, 0, \dots, 0) \quad 1 \leq \tau < \theta \leq T$$

Thm Suppose a dynamic risk measure  $\{P_{t,T}\}_{t=1}^T$  satisfies for all  $t=1, \dots, T$  and  $z_t \in \mathbb{Z}_t$  the condition:

$$P_{t,T}(z_t, 0, \dots, 0) = z_t$$

Then it is time constant if and only if for all  $1 \leq \tau < \theta \leq T$  and  $z \in \mathbb{Z}_{\tau,T}$  we have:

$$P_{\tau,T}(z_\tau, \dots, z_\theta, \dots, z_T) = P_{\tau,\theta}(z_\tau, \dots, z_{\theta-1}, P_{\theta,T}(z_\theta, \dots, z_T))$$

Proof. Consider  $z = (z_\tau, \dots, z_{\theta-1}, z_\theta, z_{\theta+1}, \dots, z_T)$

$$N = (z_\tau, \dots, z_{\theta-1}, P_{\theta,T}(z_\theta, \dots, z_T), 0, \dots, 0)$$

$$P_{\mathcal{F}_T}(z_{-1}, z_{t+1}, \dots, z_T) = E[z_t + \dots + z_T | \mathcal{F}_t] = E_t[z_t + \dots + z_T]$$

Tower property of expectation:  $E_t[z_t + z_{t+1} + \dots + z_{T-1} + z_T]$

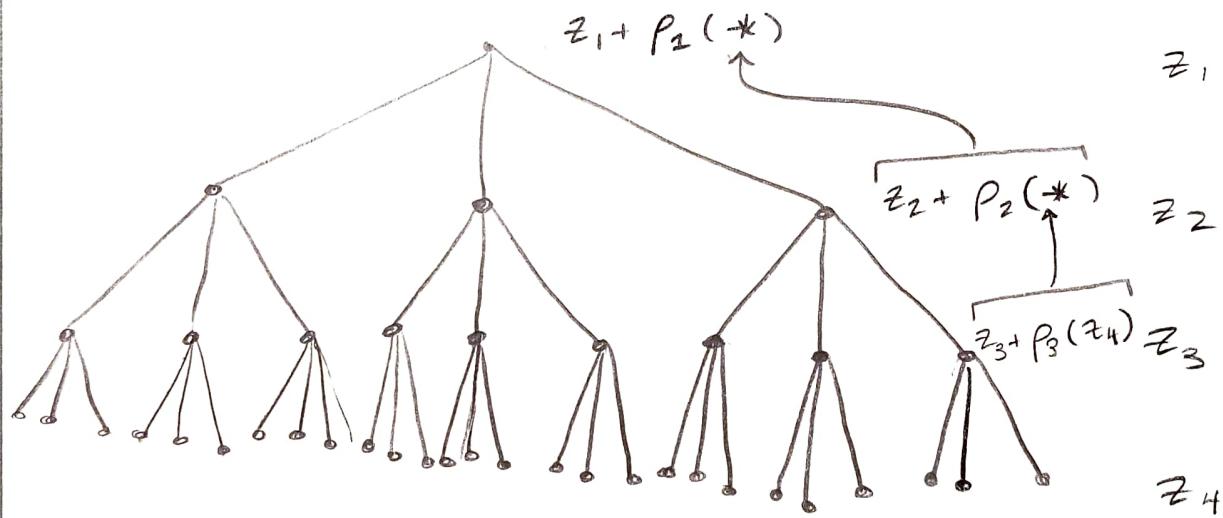
$$= E_t E_{t+1} \dots E_{T-1} [z_t + \dots + z_{T-1} + z_T]$$

$$= E_t E_{t+1} \dots E_{T-2} [z_t + \dots + z_{T-1} + E_{T-1}[z_T]]$$

Continuing in this way:

=

time consistent dynamic risk measure also has this property and is completely defined by one step dynamic risk measures  $P_t$ ,  $t = 1, \dots, T-1$



"Composition of partially aggregated risk"

$$D_1 \rightarrow x_1 \rightarrow D_2 \rightarrow x_2 \rightarrow \dots \rightarrow D_t \rightarrow x_t \rightarrow \dots \rightarrow D_T \rightarrow x_T$$

$$\text{Cost } f_1(x_1) + f_2(x_2) + \dots + f_T(x_T)$$

$$x_t \in \mathcal{X}_t(x_{t-1}, D_{[t]})$$

$z_1 = f_1(x_1), z_2 = f_2(x_2), \dots, z_T = f_T(x_T)$  are random variables

since decision depend on random data process  $D_t$ .

# Stochastic Subgradient Methods

12/11/2024

$\min_{x \in X} f(x)$  where  $f: \mathbb{R}^n \rightarrow \mathbb{R}$  convex,  $X \subset \mathbb{R}^n$  convex and closed.  
 Subgradients of  $f(\cdot)$  are not available and we use  
 their statistical estimates.

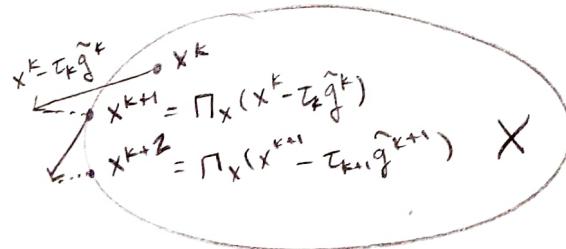
Example (EV-optimization)

$f(x) = E[F(x, z)]$  where  $z$  is an  $m$ -dimensional random vector,  $F: \mathbb{R}^n \times \mathbb{R}^m \rightarrow \mathbb{R}$ . If  $F(\cdot, z)$  is convex &  $z \in \mathbb{R}^m$  and the expected value  $E[F(x, z)]$  is finite for all  $x$ , then by Strassen's Thm  $\partial f(x) = E[\partial F(x, z)]$

Here  $g \in \partial f(x)$  if and only if a measurable selector  $G(x, z) \in \partial F(x, z)$  exists such that  $g = E[G(x, z)]$ . At a point  $x$ , we can sample a realization  $\hat{z}$  of  $z$  and obtain a stochastic subgradient  $\hat{g}(x) = G(x, \hat{z}) \in \partial F(x, \hat{z})$ . The conditional expectation of  $\hat{g}(x)$  given  $x$  is a subgradient of  $f(\cdot)$  at  $x$ .

method:  $x^{k+1} = \Pi_X (x^k - \tau_k \hat{g}^k)$ ,  $k=1, 2, \dots$

where  $\Pi_X$  is the orthogonal projection on the set  $X$



directions  $\hat{g}^k \in \mathbb{R}^n$  and stepsizes  $\tau_k > 0$  are random thus iterates  $\{x^k\}$  are random.

Assumptions  $\mathcal{F}_k$  -  $\sigma$ -algebra generated by  $\{\hat{x}^1, \hat{g}^1, \hat{x}^2, \dots, \hat{g}^{k-1}, \hat{x}^k\}$

(A1) stepsites  $T_k$  are  $\mathcal{F}_k$ -measurable such that

$$(i) T_k > 0 \quad k=1, 2, \dots$$

$$(ii) \sum_{i=1}^{\infty} T_k = +\infty \quad a.s.$$

$$(iii) E\left[\sum_{i=1}^{\infty} T_k^2\right] < +\infty$$

trend will dominate the error (variance)

(A2) The random vectors  $\hat{g}^k$  satisfy for  $k=1, 2, \dots$  the conditions:

$$(i) \hat{g}^k = g^k + e^k \text{ with } g^k \in \partial f(x^k)$$

$$(ii) E[e^k | \mathcal{F}_k] = 0$$

$$(iii) E[\|e^k\|^2 | \mathcal{F}_k] \leq \sigma^2, \text{ where } \sigma^2 \text{ is a constant}$$

(A3) The set  $X$  is compact.

Under (A3), a constant  $C$  exists, such that  $\|g\| \leq C$  for all  $g \in \partial f(x)$  where  $x \in X$ .

Recall Martingale Convergence Theorem —

Suppose  $(\Omega, \mathcal{F}, P)$  is a probability space and the sequence  $\{\mathcal{F}_n\}$  of  $\sigma$ -fields satisfies  $\mathcal{F}_1 \subset \mathcal{F}_2 \subset \dots \subset \mathcal{F}_n \subset \dots \subset \mathcal{F}$ . A sequence of real RVs  $\{X_n\}$  in  $L_1(\Omega, \mathcal{F}, P)$  is a martingale if

$$E[X_{n+1} | \mathcal{F}_n] = X_n, \quad n=1, 2, \dots$$

super martingale  $E[X_{n+1} | \mathcal{F}_n] \leq X_n$

sub martingale  $E[X_{n+1} | \mathcal{F}_n] \geq X_n$

Thm (Doob): if  $\{X_n\}$  is a submartingale with  $\sup_n E[X_n^+] < +\infty$ , or a supermartingale with  $\sup_n E[X_n^-] < +\infty$ , then the sequence  $\{X_n\}$  is convergent with probability 1 to some random limit  $X^\infty$

Example:  $\exists$  scalar R.V.

$$\min_x \frac{1}{2} E[(x - z)^2]$$

$$F(x, z) = \frac{1}{2} (x - z)^2$$

$$\partial_x F = \{x - z\} \Rightarrow \hat{g}(x) = x - z$$

$$x^{k+1} = x^k - \tau_k \hat{g}^k = x^k - \tau_k (x^k - z^k) = (1 - \tau_k)x^k + \tau_k z^k$$

$$\text{Choose } \tau_k = \frac{1}{k}$$

$$x^{k+1} = \left(1 - \frac{1}{k}\right)x^k + \frac{1}{k} z^k \quad x^0 = 0$$

$$= \frac{k-1}{k} x^k + \frac{1}{k} z^k$$

$$\text{We see } x^k = \frac{1}{k-1} \sum_{i=1}^{k-1} z^i \quad (\text{online average})$$

clearly  $x^k \rightarrow E[z]$  which is the optimal solution

Convergence Thm: Assume (A1)-(A3). Then the sequence  $\{x^k\}$  generated by the method converges to an optimal solution with probability 1.

Proof: since  $f$  is convex, we consider optimality metric of distance to optimal solution,  $x^*$

$$\|x^{k+1} - x^*\|^2 = \|\nabla_x (x^k - \tau_k \hat{g}^k) - x^*\|^2$$

Follow in notes. (Yuri Ermakov)

### Finite Iteration performance

Suppose we use deterministic step sizes  $\tau_k > 0$ ,  $k=1, 2, \dots$ , we have

$$E[\|x^{k+1} - x^*\|^2 | \mathcal{F}_k] \leq \|x^k - x^*\|^2 - 2\tau_k (f(x^k) - f(x^*)) + \hat{\sigma}^2 \tau_k^2$$

Taking full expectation

$$\tau_k E[f(x^k) - f(x^*)] \leq \frac{1}{2} \left[ E[\|x^k - x^*\|^2] - E[\|x^{k+1} - x^*\|^2] + \hat{\sigma}^2 \tau_k^2 \right]$$

The sum of these inequalities for  $k = 0, 1, \dots, N$  yields

$$E\left[\sum_{k=1}^N \tau_k [f(x^k) - f(x^*)]\right] \leq \frac{1}{2} \|x^1 - x^*\|^2 + \frac{\hat{\sigma}^2}{2} \sum_{k=1}^N \tau_k$$

$$\sum_{j=1}^N \tau_j$$

$$\sum_{j=1}^N \tau_j$$

Let  $\alpha_k = \frac{\tau_k}{\sum_{j=1}^N \tau_j} > 0$ . We see  $\sum_{k=1}^N \alpha_k = 1$  so we may interpret

them as probabilities. Then

$$E\left[\sum_{k=1}^N \alpha_k (f(x^k) - f(x^*))\right] \leq \text{RHS}$$

$$E\left[\sum_{k=1}^N \alpha_k f(x^k)\right] - f(x^*) \leq \text{RHS}$$

Since  $f$  is convex we have

$$f(\bar{x}^N) \leq \sum_{k=1}^N \alpha_k f(x^k), \text{ where } \bar{x}^N = \sum_{k=1}^N \alpha_k x^k$$

$$\text{so } E[f(\bar{x}^N)] - f(x^*) \leq \frac{1}{2} \frac{\|x^1 - x^*\|^2 + \hat{\sigma}^2 \sum_{k=1}^N \tau_k^2}{\sum_{k=1}^N \tau_k}$$

We choose  $\tau_k = \frac{\alpha}{N}$  and get

$$E[f(\bar{x}^N)] - f(x^*) \leq \frac{1}{2} \frac{\|x^1 - x^*\|^2 + \hat{\sigma}^2 \alpha^2}{\alpha \sqrt{N}}$$

So we may choose  $N$  and  $\alpha$  obtain a sufficient quality guarantee

For final homework: implement this method on absolute value regression. We may also use  $\tau_k = \frac{\alpha}{\sqrt{k}}$  so we do not need to

choose number of steps  $N$ . Do analysis here with this  $\tau_k$  and get quality estimate.

Hint: get upper bound of  $\sum_{k=1}^N \tau_k^2 \Rightarrow$  summing rectangles  $\Rightarrow$  under estimate integral of some

lower bound of  $\sum_{k=1}^N \tau_k$

## Smooth Unconstrained Problems

$f(\cdot)$  is continuously differentiable and its gradient  $\nabla f(\cdot)$  is Lipschitz continuous with constant  $L$ .  $X = \mathbb{R}^n$

$$x^{k+1} = x^k - T_k \hat{g}^k, \quad k=1, 2, \dots$$

where  $\hat{g}^k = \nabla f(x^k) + e^k$

Define  $X^* = \{x \in \mathbb{R}^n : \nabla f(x) = 0\}$

Thm: Assume (A1)-(A3) and let  $f^* = \min f(x)$  be finite. Then with probability 1, the sequence  $\{f(x^k)\}$  is convergent and every accumulation point  $\hat{x}$  of the sequence  $\{x^k\}$  satisfies  $\nabla f(\hat{x}) = 0$ .

## Averaging of Directions

Here we generate 2 sequences: the main iterated  $\{x^k\}$  and the path averaged stochastic subgradients  $\{z^k\}$ . Given  $x^k, z^k$  we solve

$$\min_{y \in X} \left\{ \langle z^k, y - x^k \rangle + \frac{1}{2} \|y - x^k\|^2 \right\} \quad (19)$$

denote  $y^k$  as the solution. We make a step in primal terms

$$x^{k+1} = x^k + \tau_k (y^k - x^k)$$

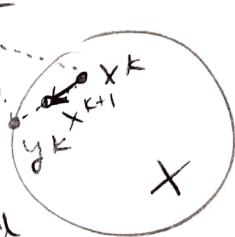
We observe a stochastic subgradient  $\hat{g}^{k+1}$  at  $x^{k+1}$  and update the average subgradients by

$$z^{k+1} = (1 - \alpha \tau_k) z^k + \alpha \tau_k \hat{g}^{k+1}$$

The subproblem (19) is equivalent to  $y^k = \Pi_X(x^k - z^k)$

- In unconstrained case ( $X = \mathbb{R}^n$ ) we have  $x^k - z^k$

$y^k = x^k - z^k$  so  $x^{k+1} = x^k - \tau_k z^k$  which is analogous to <sup>stochastic</sup> subgradient method, but with the "filtered" stochastic subgradient  $z^k$  used instead of last observed  $\hat{g}^k$ .



Home work:  $\min_x E \left[ |x_0 + x_1 A_1 + x_2 A_2 + A_3| \right]$   $A_1, A_2, A_3$  - random

$$\partial F(x, A) = \begin{cases} 1 + A_1 + A_2 & \text{if } x_0 + x_1 A_1 + x_2 A_2 + A_3 > 0 \\ -1 - A_1 - A_2 & \text{if } x_0 + x_1 A_1 + x_2 A_2 + A_3 < 0 \end{cases}$$

$$x_0^{N+1} = x_0^1 + \sum_{k=1}^N (\pm \tau_k), \quad \sum_{k=1}^{\infty} (\pm \frac{1}{k}) < +\infty \quad \text{if } \pm \text{ equally likely.}$$

