

CS-E4740 Federated Learning

A FL Design Principle

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What are main components of ML and how are they combined?

Previous Lecture:
Networked Data and Models

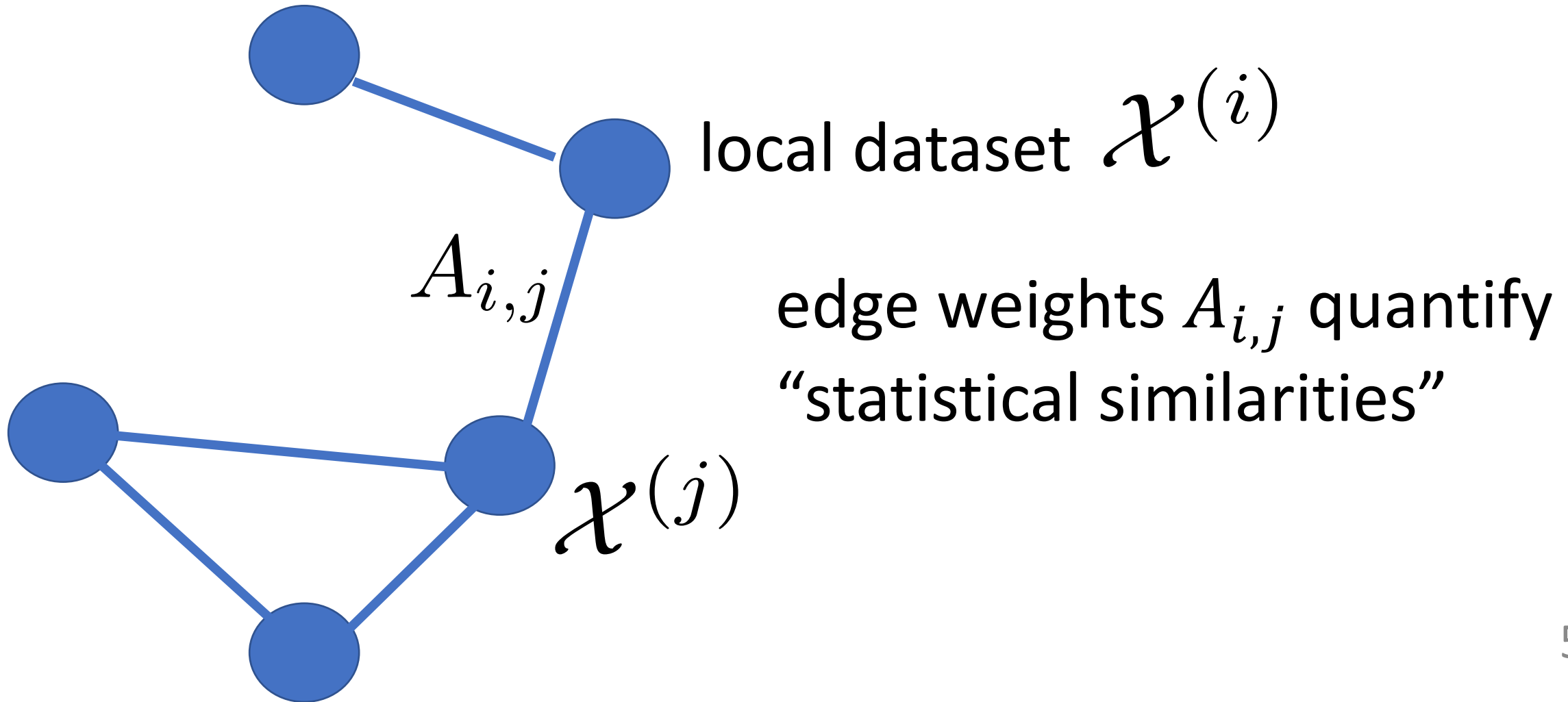
Today:
Loss and Optimization

Weather Stations.

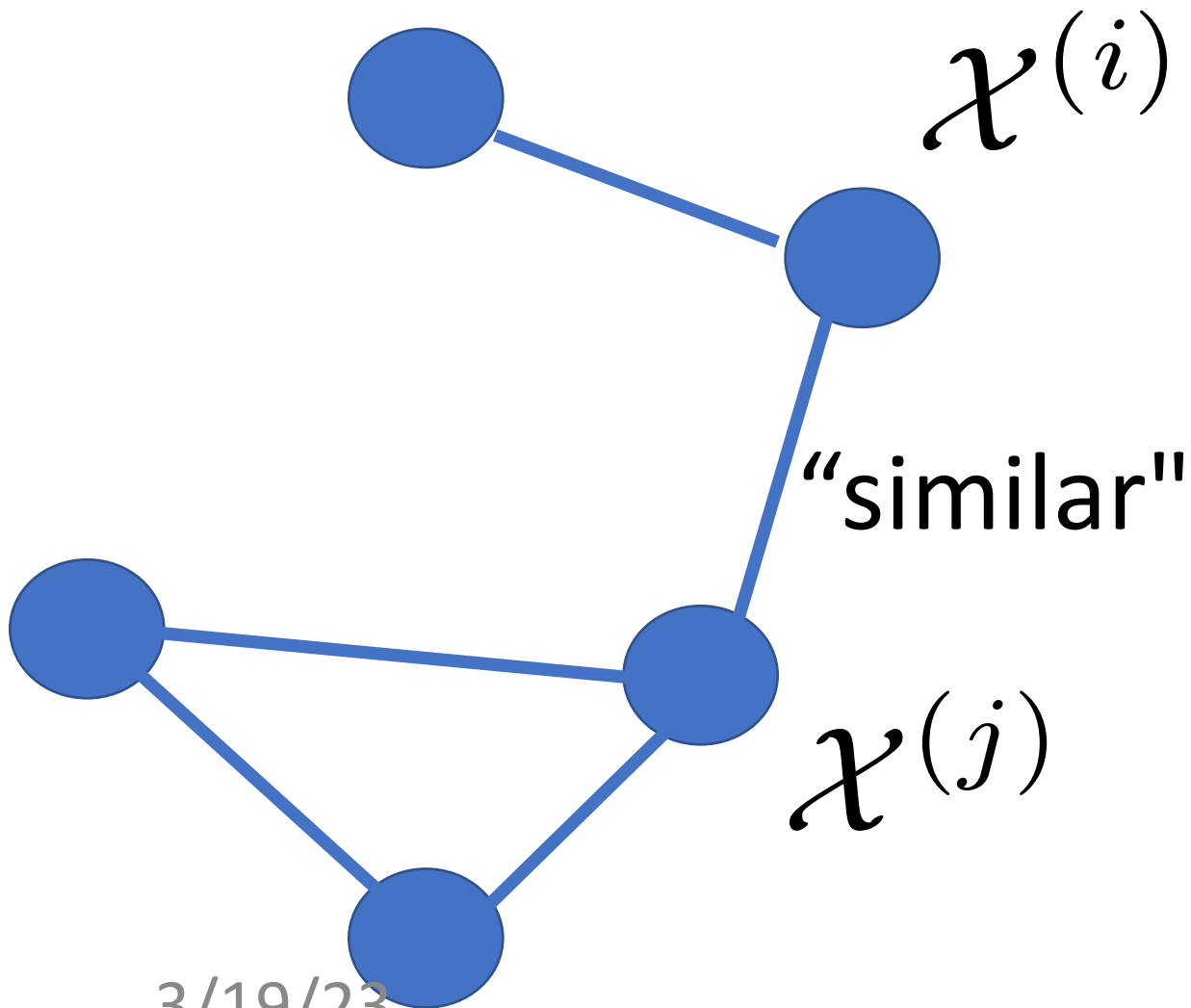


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INSTITUTE

The Empirical Graph



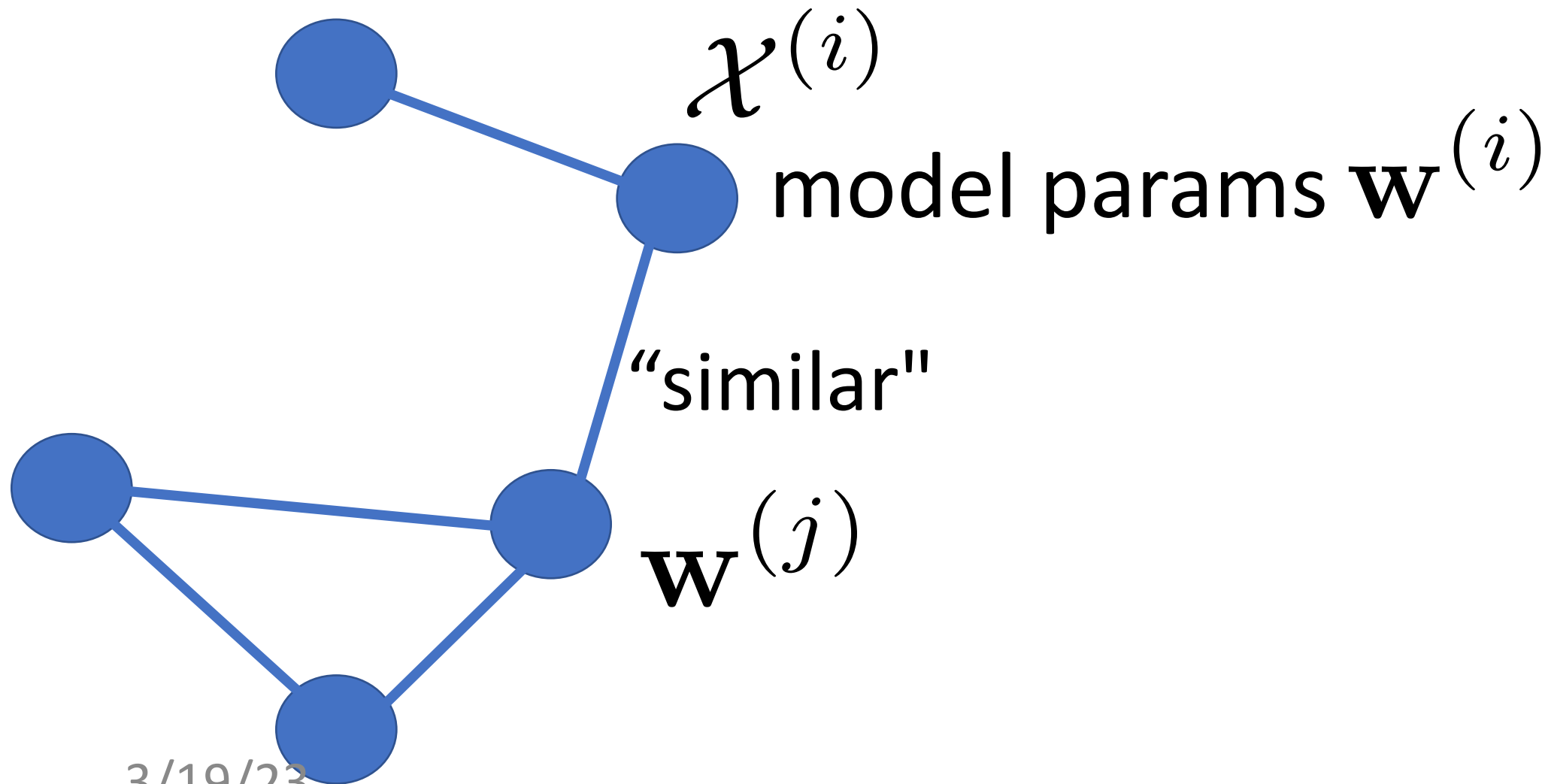
Networked Models.



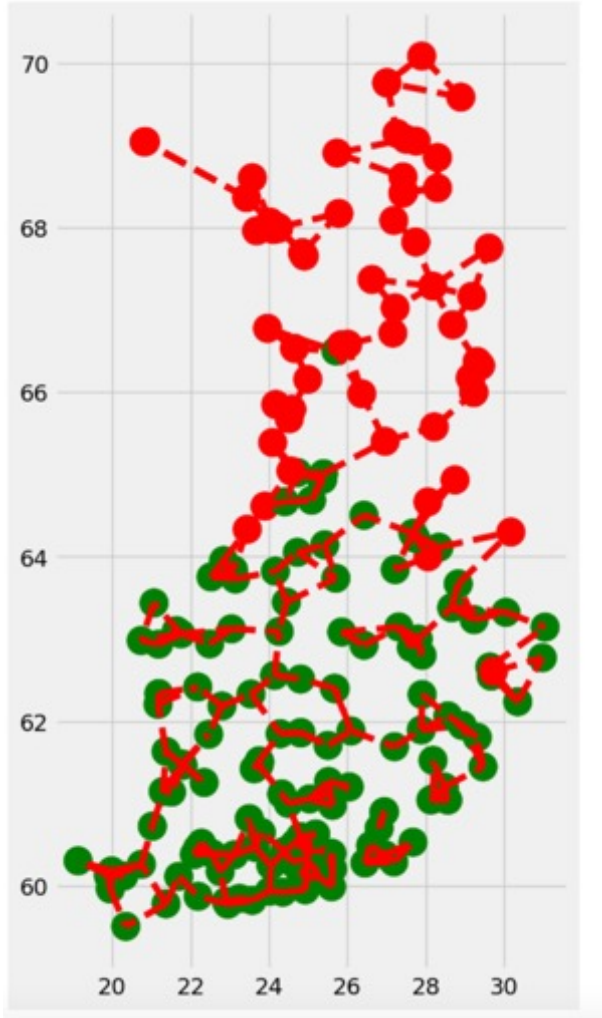
local model for each node

couple models at
connected nodes

Networked Parametric Models.



Clustering Assumption



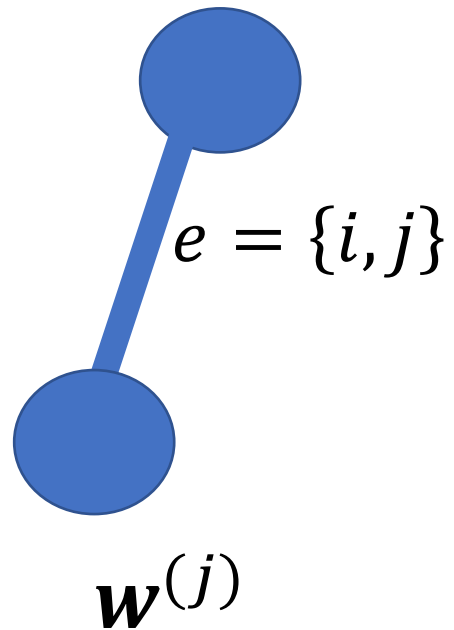
the local datasets form clusters

datasets in same can be
approximated as realizations of i.i.d.
RVs with prob. dist $p(x,y;c)$

high edge density inside clusters

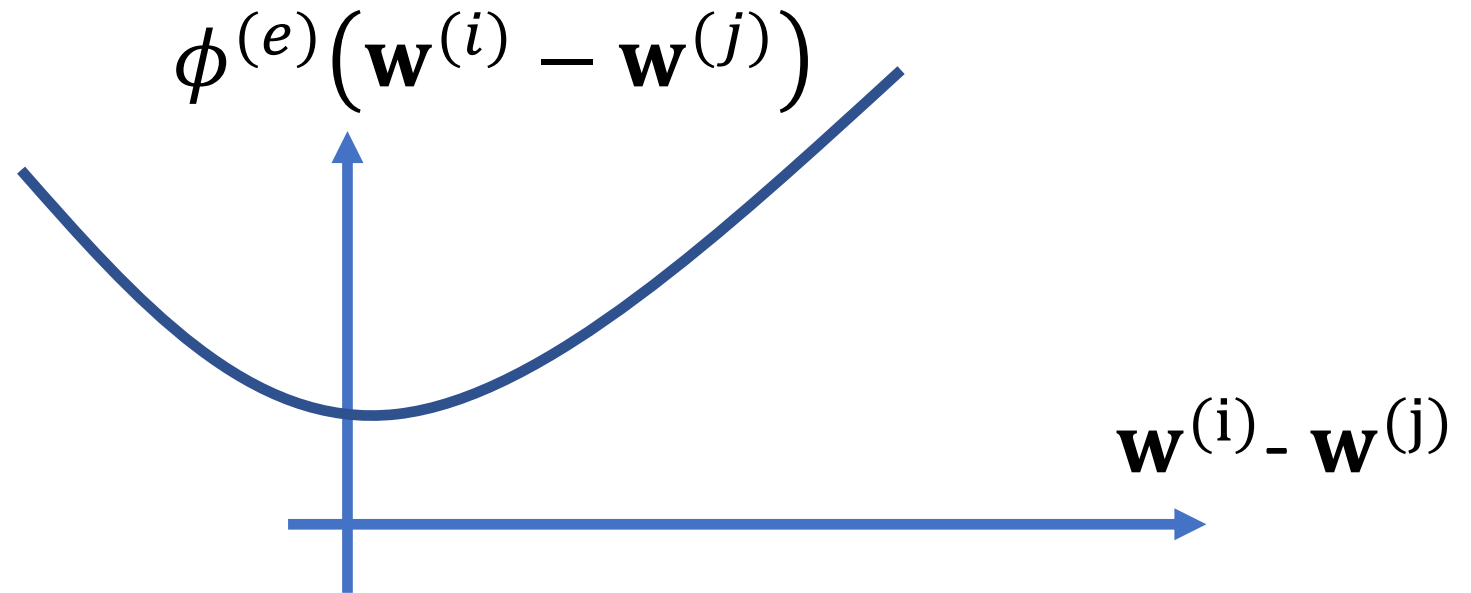
Measure Clustering via Variation

local model params $\mathbf{w}^{(i)}$

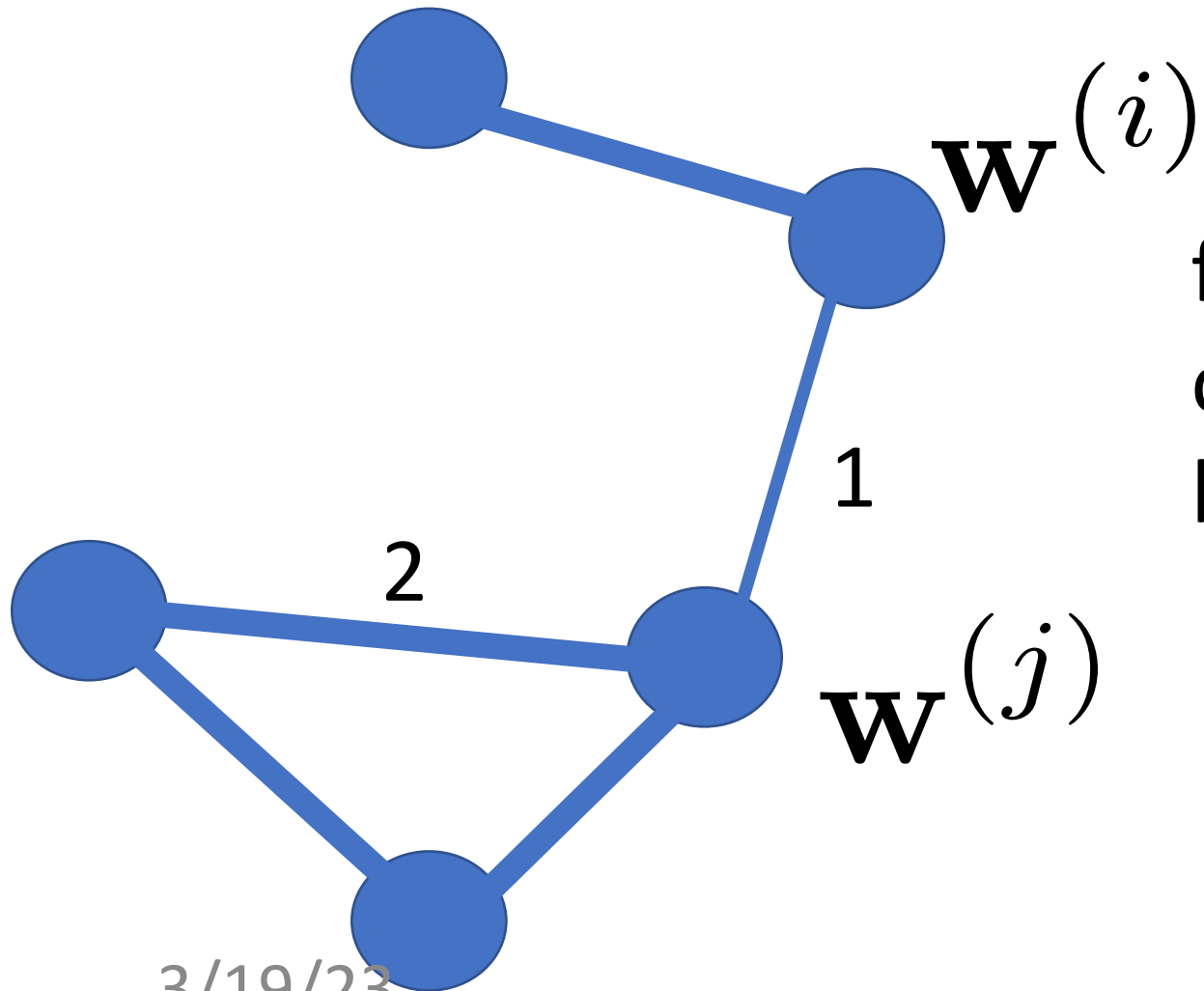


require similar params at ends of edge e

penalty function measures “variation”



Generalized Total Variation (GTV)



force model params at well
connected nodes to be similar
by requiring small GTV

$$\sum_{\{i,j\}} A_{i,j} \phi(\mathbf{w}^{(i)} - \mathbf{w}^{(j)})$$

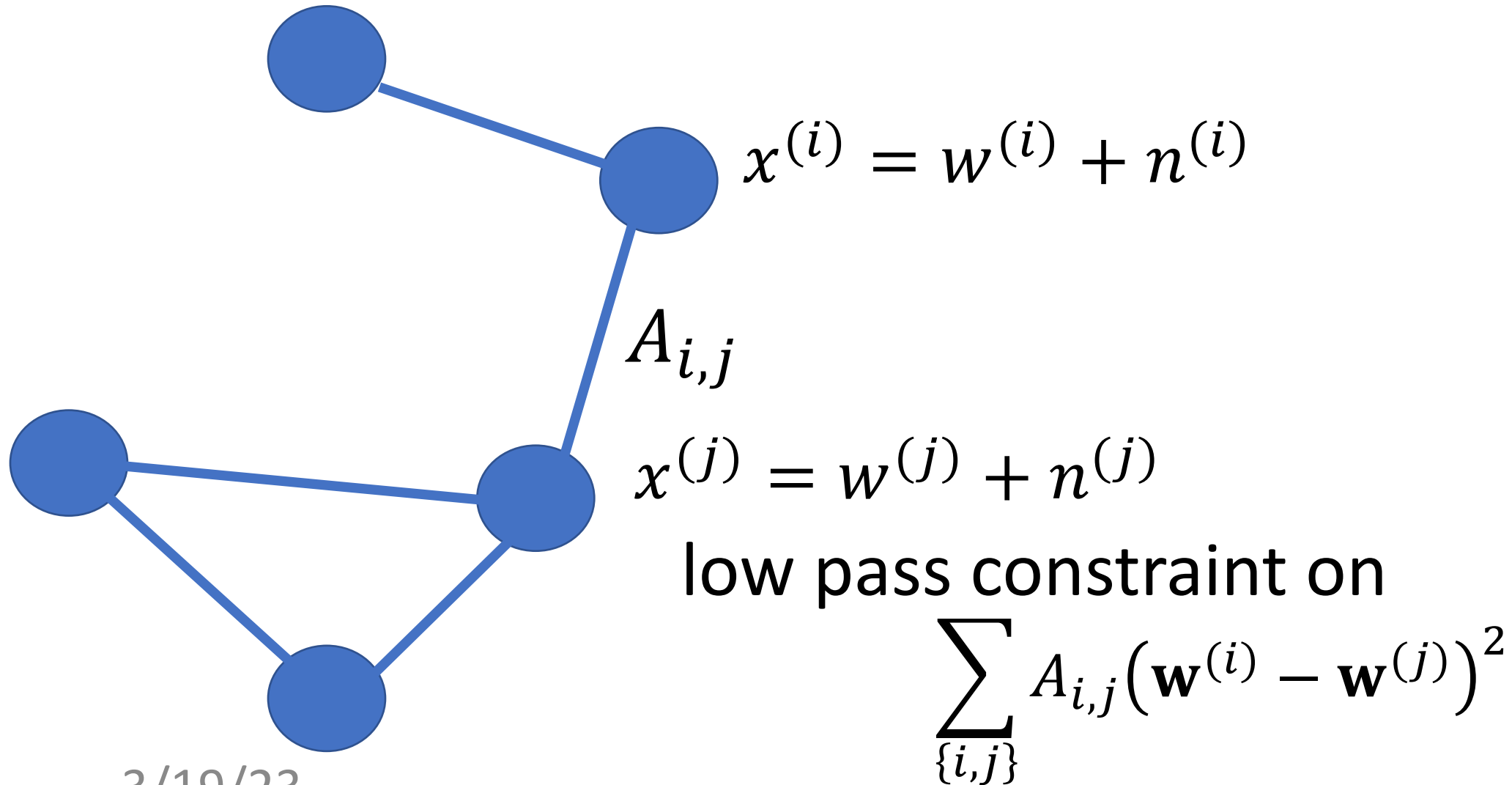
Two Special Cases of GTV.

total variation $\phi(\mathbf{u}) = \|\mathbf{u}\|_2$

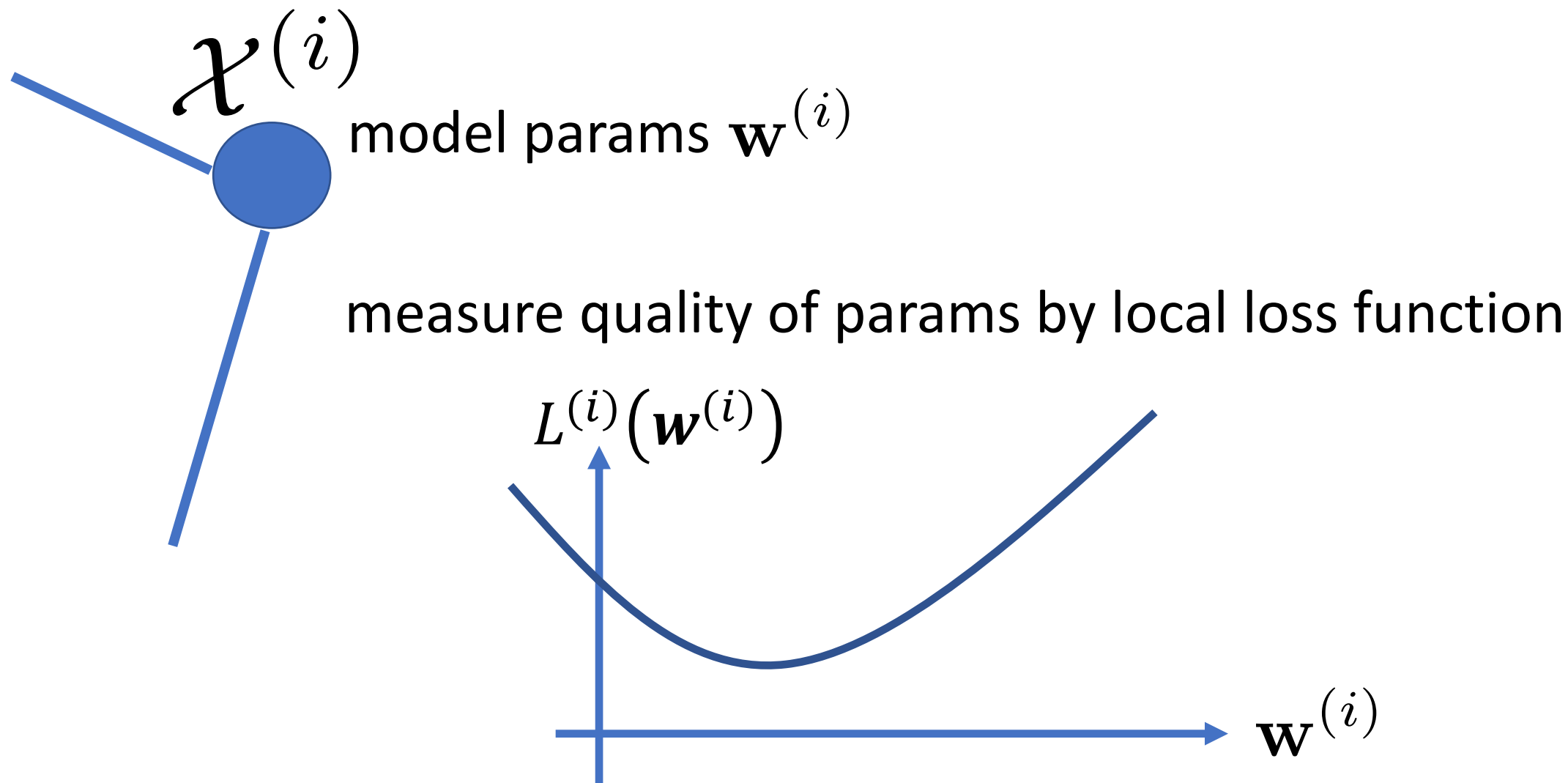
graph Laplacian quadratic form is GTV with

$$\phi(\mathbf{u}) = \|\mathbf{u}\|_2^2$$

Smooth Graph Signals.

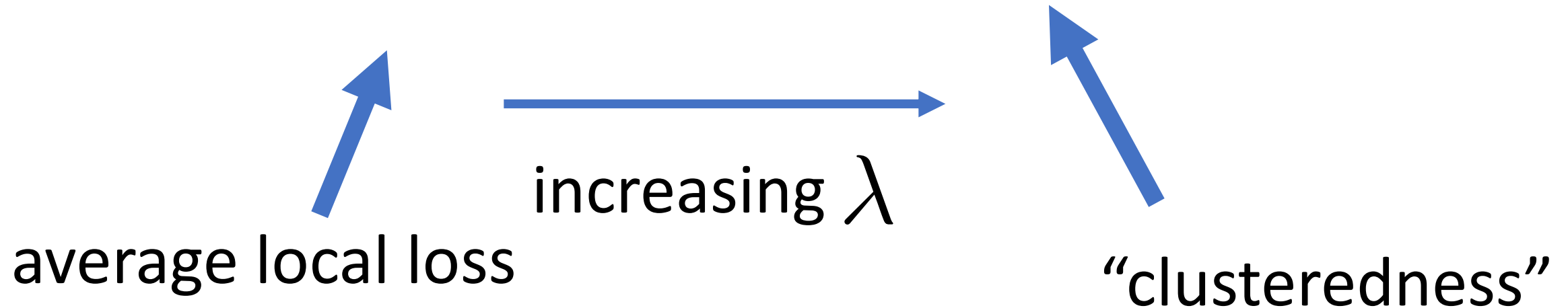


Local Loss Function.



GTV Minimization

$$\min_{\mathbf{w}} \sum_i L^{(i)}(\mathbf{w}^{(i)}) + \lambda \sum_{\{i,j\}} A_{i,j} \phi(\mathbf{w}^{(i)} - \mathbf{w}^{(j)})$$



Network Lasso

$$\min_{\mathbf{w}} \sum_i L^{(i)}(w^{(i)}) + \lambda \sum_{\{i,j\}} A_{i,j} \|w^{(i)} - w^{(j)}\|$$

Network Lasso: Clustering and Optimization in Large Graphs

by D Hallac · 2015 · Cited by 206 — **Network Lasso: Clustering and Optimization in Large Graphs** ... Keywords: Convex **Optimization**, ADMM, **Network Lasso**. Go to: ... 2013 [**Google Scholar**]. 2.

[Abstract](#) · [INTRODUCTION](#) · [CONVEX PROBLEM...](#) · [EXPERIMENTS](#)

Special Case: “MOCHA”

$$\min_w \sum_i L^{(i)}(w^{(i)}) + \lambda \sum_{\{i,j\}} A_{i,j} \|w^{(i)} - w^{(j)}\|^2$$

<https://papers.nips.cc> › paper › 7029-federated-m... ▼ PDF

Federated Multi-Task Learning - NIPS Proceedings

by V Smith · 2017 · Cited by 501 — 3.2 MOCHA: A Framework for **Federated Multi-Task Learning**. In the **federated** setting, the aim is to train statistical models directly on the edge, and thus we solve (1) while assuming that the data $\{X_1, \dots, X_m\}$ is distributed across m nodes or devices.

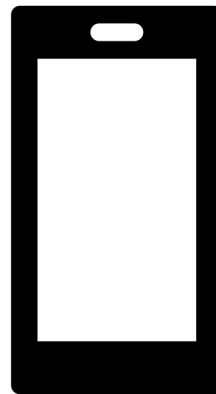
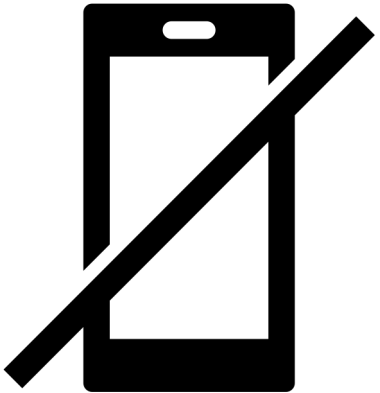
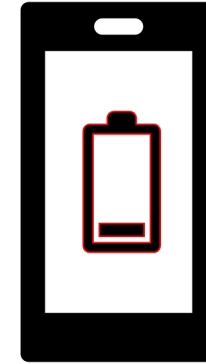
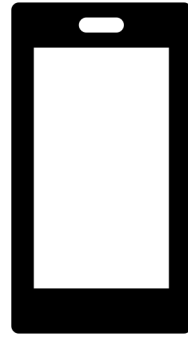
Two Key Questions of ML

$$\min_{\mathbf{w}} \sum_i L^{(i)}(\mathbf{w}^{(i)}) + \lambda \sum_{\{i,j\}} A_{i,j} \phi(\mathbf{w}^{(i)} - \mathbf{w}^{(j)})$$

- computational aspects: how can we efficiently compute solutions (approximately)
- statistical aspects: are the solutions any good?

Computational Aspects

A FL Setting



Requirements

- run in ad-hoc nets of low-cost devices
- robustness against node/link failures
- robustness against “stragglers”

Another FL Setting...

<https://www.google.com/about/datacenters/>



https://en.wikipedia.org/wiki/Optical_fiber

GTV Min. for Local Lin.Reg.

$$\min_{\mathbf{w}} \sum_i \|\mathbf{X}^{(i)} \mathbf{w}^{(i)} - \mathbf{y}^{(i)}\|^2 + \lambda \sum_{\{i,j\}} A_{i,j} \|\mathbf{w}^{(i)} - \mathbf{w}^{(j)}\|^2$$

using stacked parameters $\mathbf{w} = (\mathbf{w}^{(1)}, \dots, \mathbf{w}^{(n)})^T$,

$$\min_{\mathbf{w}} \mathbf{w}^T \mathbf{Q} \mathbf{w} + \mathbf{w}^T \mathbf{q}$$

with psd matrix \mathbf{Q} and vector \mathbf{q} that depend on local datasets, GTVMin parameter λ and empirical graph

GTV Min. for Local Lin.Reg.

$$\min_{\mathbf{w}} \mathbf{w}^T \mathbf{Q} \mathbf{w} + \mathbf{w}^T \mathbf{q}$$

can be solved using gradient methods

$$\mathbf{w}^{(k+1)} = \mathbf{w}^{(k)} - \alpha_k (2\mathbf{Q}\mathbf{w}^{(k)} + \mathbf{q})$$

Statistical Aspects

GTV Min. for Local Lin.Reg.

$$\min_{\mathbf{w}} \sum_i \|\mathbf{X}^{(i)} \mathbf{w}^{(i)} - \mathbf{y}^{(i)}\|^2 + \lambda \sum_{\{i,j\}} A_{i,j} \|\mathbf{w}^{(i)} - \mathbf{w}^{(j)}\|^2$$

using stacked parameters $\mathbf{w} = (\mathbf{w}^{(1)}, \dots, \mathbf{w}^{(n)})^T$,

$$\sum_{\{i,j\}} A_{i,j} \|\mathbf{w}^{(i)} - \mathbf{w}^{(j)}\|^2 = \mathbf{w}^T (\mathbf{L} \otimes \mathbf{I}) \mathbf{w}$$

with the graph Laplacian \mathbf{L}

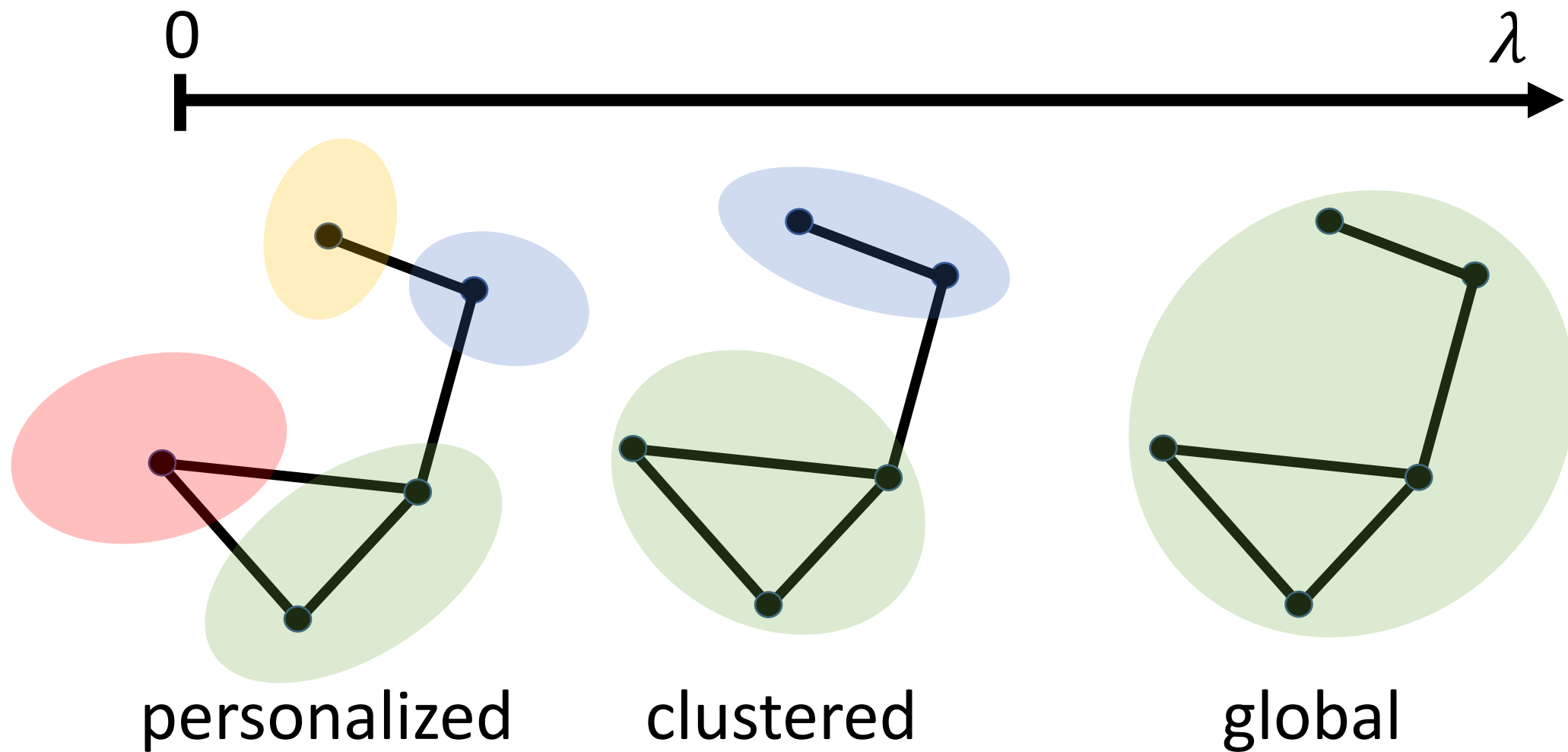
Spectral Clustering

for large λ , GTVMin is to minimize

$$\sum_{\{i,j\}} A_{i,j} \|\mathbf{w}^{(i)} - \mathbf{w}^{(j)}\|^2 = \mathbf{w}^T (\mathbf{L} \otimes \mathbf{I}) \mathbf{w}$$

\Rightarrow local model parameters should be composed of eigvecs. of \mathbf{L} corresponding to smallest eig.vals

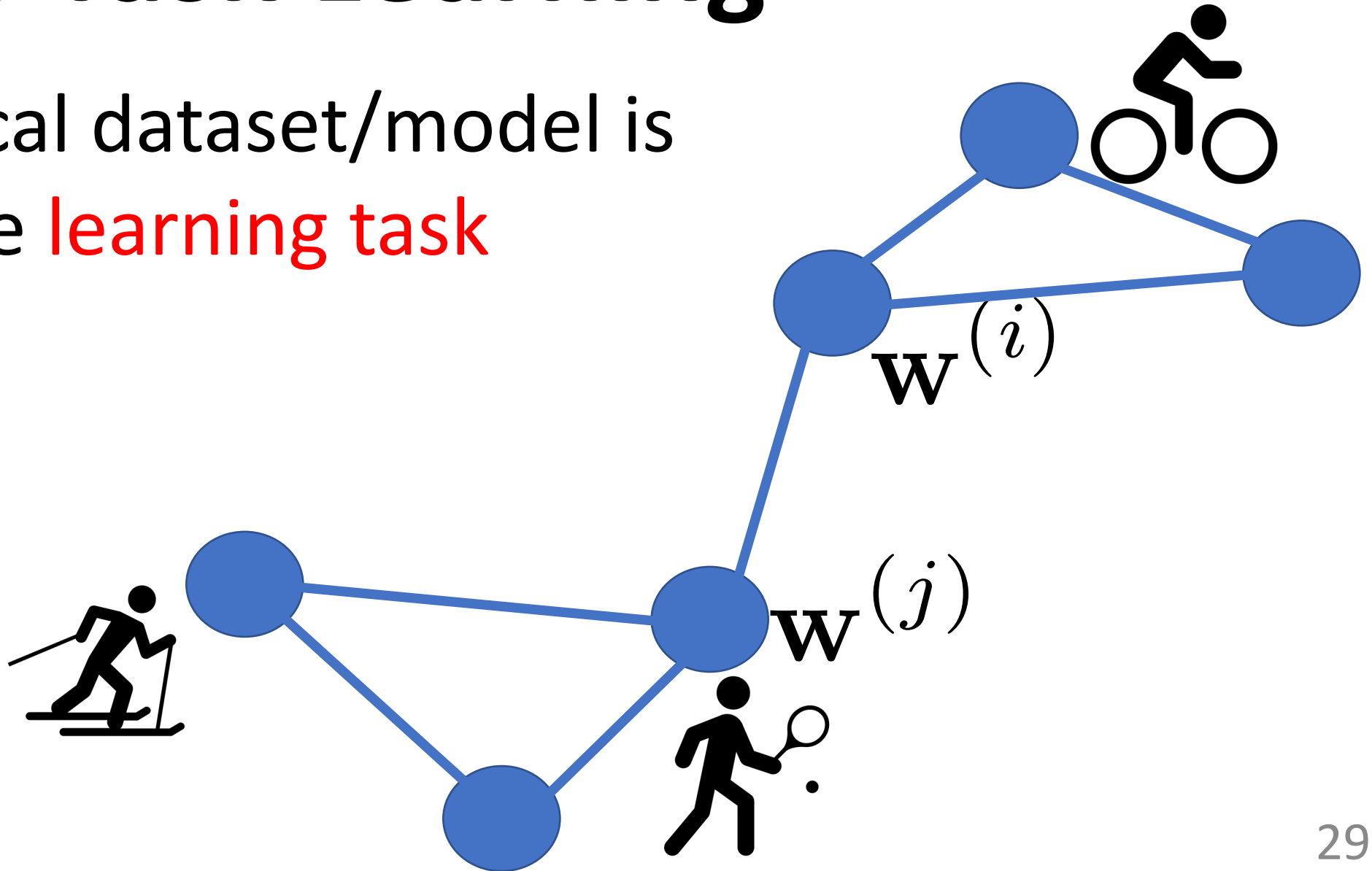
Clustering of GTVMin Solutions



Interpretations

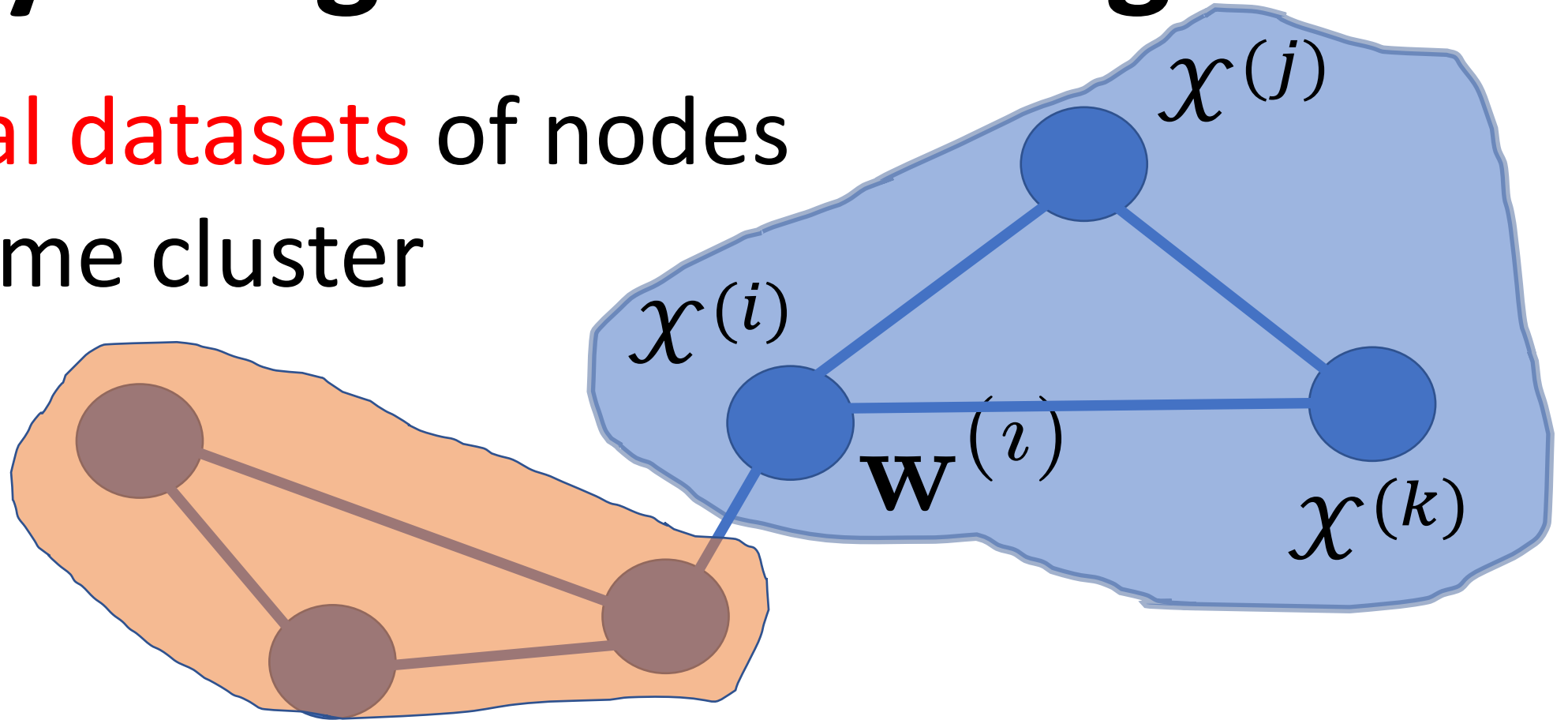
Multi-Task Learning

each local dataset/model is
separate **learning task**



Locally Weighted Learning

pool local datasets of nodes
in the same cluster



William S. Cleveland, Susan J. Devlin, Eric Grosse,
“Regression by local fitting: Methods, properties, and computational algorithms,”
Journal of Econometrics, Volume 37, Issue 1, 1988.

Generalized Convex Clustering

$$\min_{\mathbf{w}} \sum_i \|w^{(i)} - a^{(i)}\|^2 + \lambda \sum_{\{i,j\}} A_{i,j} \|w^{(i)} - w^{(j)}\|_p$$

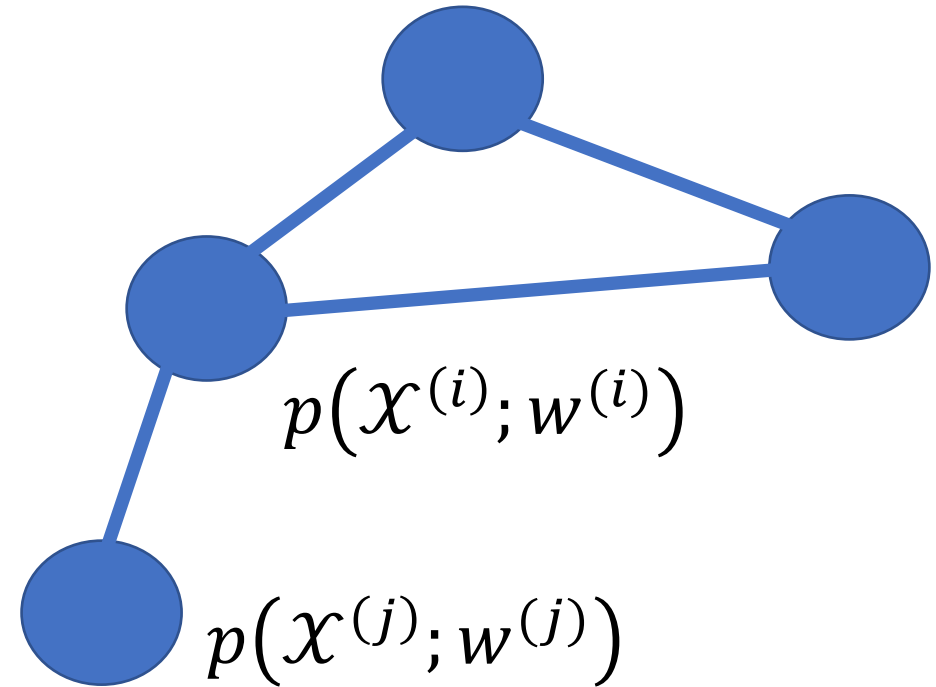
D. Sun, K.-C. Toh, Y. Yuan;

Convex Clustering: Model, Theoretical Guarantee and Efficient Algorithm, JMLR, 22(9):1–32, 2021

(Probabilistic) Graphical Model

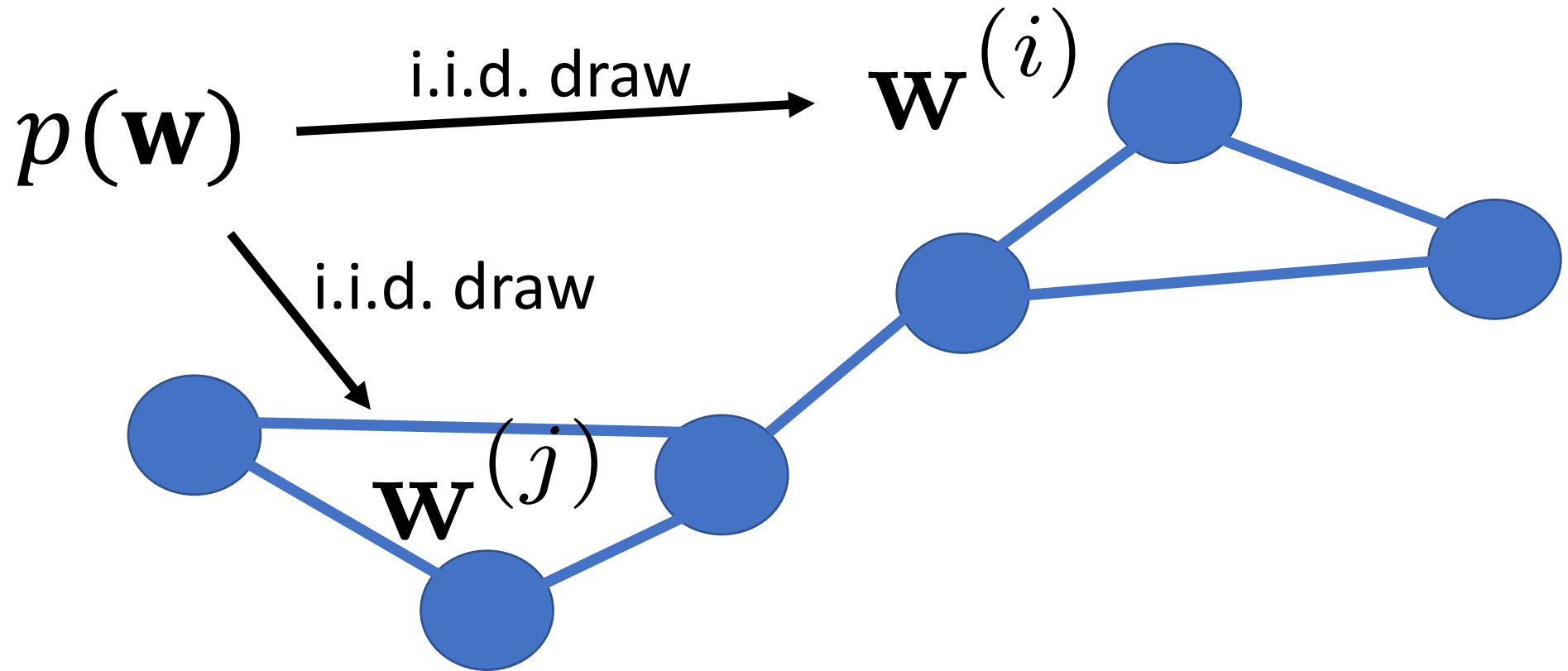
separate prob. space for each local dataset

traditionally, PGMs use a common prob. space for all local datasets



AJ, "Networked Exponential Families for Big Data Over Networks,"
in *IEEE Access*, vol. 8, pp. 202897-202909, 2020, doi:
10.1109/ACCESS.2020.3033817.

Approx. Hierarch. Bayes' Model

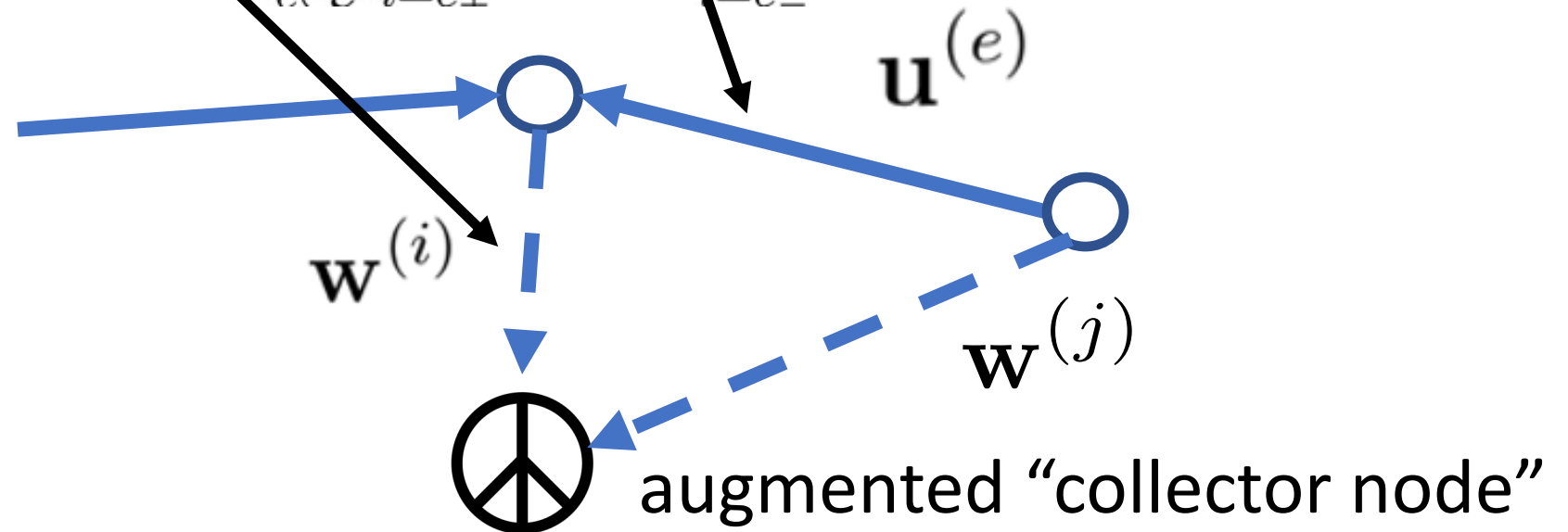


Lyu, B., Hanzely, F., and Kolar, M., "Personalized Federated Learning with Multiple Known Clusters", *arXiv e-prints*, 2022.
doi:10.48550/arXiv.2204.13619.

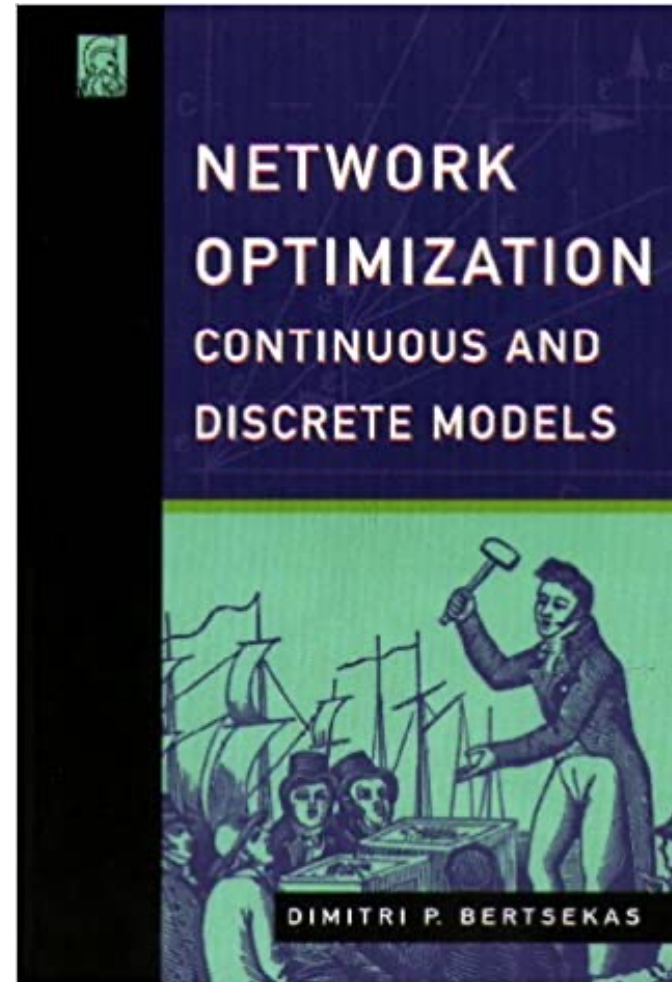
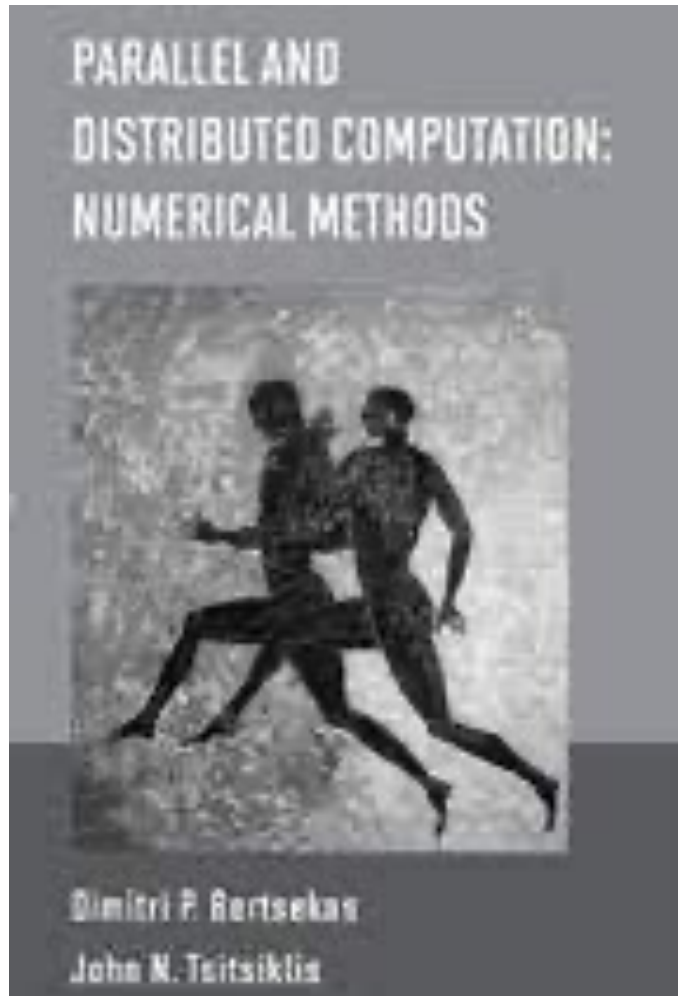
Non-Linear Min-Cost-Flow

$$\max_{\mathbf{u} \in \mathcal{U}} - \sum_{i \in \mathcal{V}} L_i^* (\mathbf{w}^{(i)}) - \lambda \sum_{e \in \mathcal{E}} A_e \phi^* (\mathbf{u}^{(e)} / (\lambda A_e))$$

subject to $-\mathbf{w}^{(i)} = \sum_{e \in \mathcal{E}} \sum_{i=e_+} \mathbf{u}^{(e)} - \sum_{i=e_-} \mathbf{u}^{(e)}$ for all nodes $i \in \mathcal{V}$.



Non-Linear Min-Cost-Flow



Electrical Network.

("AI is new Electricity!")

Kirchhoff's Current Law



$$\sum_{e \in \mathcal{E}} \sum_{i=e_+} \hat{\mathbf{u}}^{(e)} - \sum_{i=e_-} \hat{\mathbf{u}}^{(e)} = -\nabla L_i(\hat{\mathbf{w}}^{(i)}) \text{ for all nodes } i \in \mathcal{V}$$

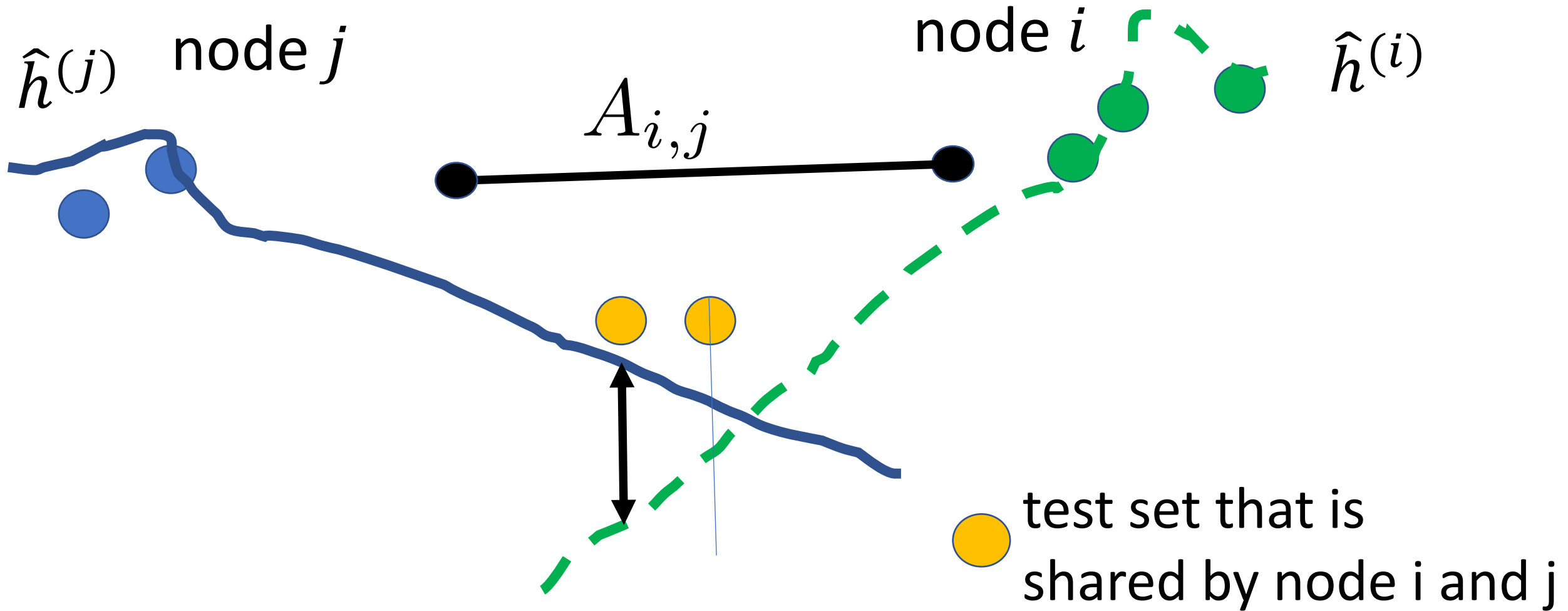
$$\hat{\mathbf{w}}^{(e_+)} - \hat{\mathbf{w}}^{(e_-)} \in (\lambda A_e) \partial \phi^*(\hat{\mathbf{u}}^{(e)} / (\lambda A_e)) \text{ for every edge } e \in \mathcal{E}.$$



Generalized Ohm Law

GTVMin for Non-Param. Models

Variation of Non-Param. Models



Wrap Up.

- couple local model training via regularization
- regularizer obtained via GTV (over empirical graph)
- FL algorithms = optimization methods for GTV min
- GTVmin pools local datasets into clusters
- cluster structure depends on emp.graph **and** local data!

Thank you for
your attention!