

11.11.2024. D.S

This is a type of a system s/w.
It create interface between user and h/w.

OS-designed Approach.

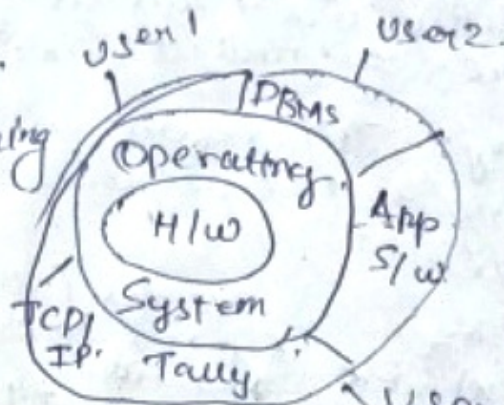
layer based.

kernel based.

layer based.

Bottom layer: H/w.

machine level programming
is used for direct H/w
access. It is hard and
it is dependent on
h/w.



It acts as: resource manager
and resource allocator.

2 types of resources:

- (i) H/w resource (memory, processor, I/O device)
- (ii) S/w resource.

system is divided into 3 module,

- ① memory
- ② processor
- ③ I/O module,

S/O resources are file and application I/O.
OS just work like foreman.

OS Design Goals

- (i) Primary Goal: User Convenient. / user friendly.
- (ii) Secondary Goal: Efficiency: Throughput must be maximum (max. no. of jobs finished per unit time)
- (iii) Turnaround time / latency (latency must be low)

$$TAT = CT - AT$$

BT = Burst Time

Q. Assume we have 4 process P_1, P_2, P_3, P_4 .

Process No. (Pno)	AT	BT (ms)
P_1	0	4
P_2	1	3
P_3	2	5
P_4	3	6

Process is two types: CPU Bound Process, I/O Bound process.
CPU Bound wants more time of CPU.

Process Vs Program.

Program (set of Inst).

Program: ~~code~~

Program: passive

Program under execution: process.

Process: Operating body

Process: Active and Dynamic

Process of Running (states of process)
New \rightarrow Ready \rightarrow Running \rightarrow Wait / Block \rightarrow Terminate

Process will each time change its state.

Program will not need resources. Process will need Process.

CPU Bound will be more in Run state.

I/O Bound will be more in the wait Block

new state is born / creation of process.

Then process will go to the ready state.

Ready state is in memory.

New \rightarrow Ready: long Term Scheduler.

'Ready \rightarrow Running: short Term scheduler

In Ready state; new process wait to run on CPU

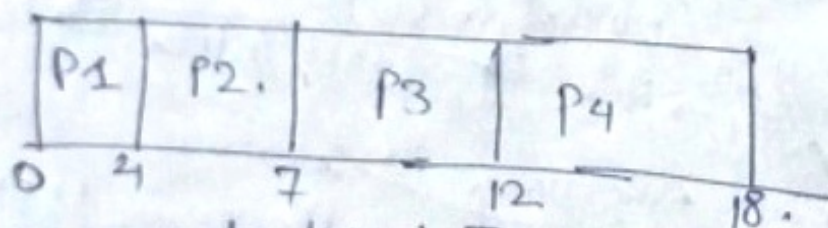
Short Term scheduler run on the algorithm.

FCFS / Criteria: AT, Non Primitive.

Pno	AT	BT	CT	CT-AT TAT	$WT = TAT - BT$ $\frac{WT}{WT}$
P ₁	0	4	4	4	0
P ₂	1	3	7	6	3
P ₃	2	5	12	10	5
P ₄	3	6	18	15	9

*Non Primitive: One process from ready to run will not go again to ready Que.

Ready
P₄ ~~P₂~~ ~~P₁~~



WT must be less; Throughput is High,
Avg TAT and RT (in-preemptive)

RT \approx First service AT
Time

Throughput: no. of jobs (processes)
completed per unit of time
is called Throughput

next class: Types of OS

Types of OS

- ① Batch OS.
- ② multi-programming OS.
- ③ multi-tasking OS. (Timesharing OS).
- ④ real-time OS. (RTOS).
- ⑤ multi-processor OS.
- ⑥ Network OS.
- ⑦ Distributed OS.

Batch-OS

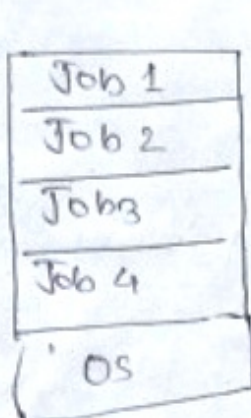
similar type of jobs, batch was made.

language: JCL: job control language.

used during: 1st Before 1st Gen.

It is pure non-preemptive.

(no new job start until current job is finished)



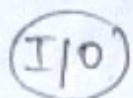
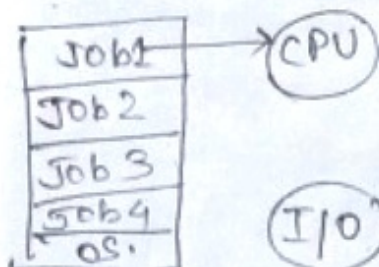
Process

CPU Bound
(B.T = Burst Time)

I/O Bound

(I.O.B.T: Input Output Burst time).

* Disadvantage was: most of time CPU was idle.



Better sol.

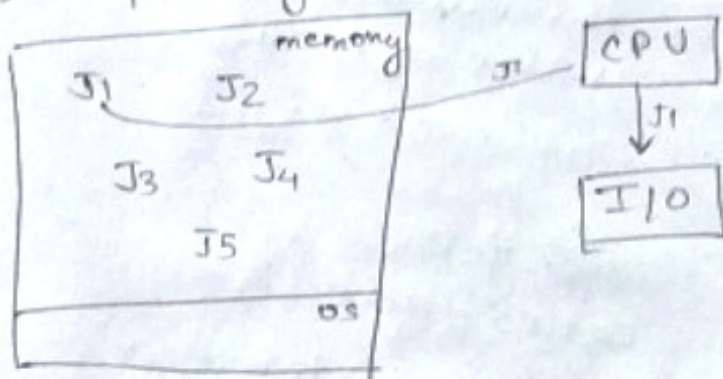
for maximum utilisation of CPU.
CPU busy throughput is high.

batch: jobs of similar nature.

Suppose Job 1 was selected for CPU execution. That time Job 1 want I/O operation. Job 1 goes to I/O device; CPU becomes Idle.

* user cannot directly interact with system.
The system has an operator. in 1st Gen / 2nd Gen computer. To operator, we gave task, the operator made batches and execution was batch by batch.

- * user cannot set priority: It is pure non preemptive. Job 4 has priority high than Job 1. Until and unless Job 1 is not finished, Job 4 not start.
 - * user cannot directly interact with the machine.
 - * user cannot set priority.
 - * Decreased throughput of the system.
 - Throughput: no. of jobs completed per unit time.
 - Throughput will decrease in batch system due to CPU is idle.
 - * if the job is completed completely then only another job will be scheduled onto the CPU.
 - * FCFS: (first come first serve) scheduling algorithm is used in batch operating system.
 - * IBM developed an OS - OS/2 is an example of batch operating system (outdated).
- 2nd Operating system was multi-programming OS:



J_1 was scheduled to CPU (from ready to run)
 $\{J_1, J_2, \dots, J_5\}$ are in ready state in memory.

J_1 required I/O devices; so J_1 goes to I/O device
 Then automatically acc. to algorithm other jobs $\{J_2, \dots, J_5\}$ are scheduled to the CPU.
 while J_1 is doing I/O operation.

By this maximum utilisation of CPU.
 Another job will be brought from ready to run.

Q) If the job is leaving the CPU to perform I/O operation then another job which is ready for execution will be scheduled on the CPU.

CPU - Scheduling Algorithms.

In different or different Algorithms are used. Max. utilisation of CPU is done in multiprogramming. For Input/output: Job is in wait/block, then is send to ready queue.

Increased throughput of the system.

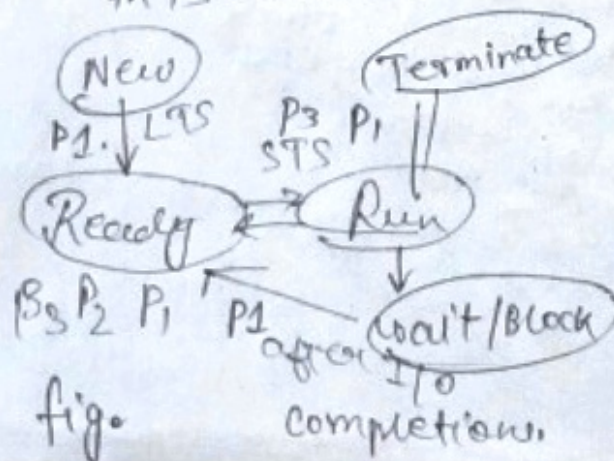
eg.

Windows, Unix, Linux are multiprogramming OS.

Major drawback (Batch OS): CPU was Idle, Throughput Low.

Process has different states:

- ① **new state:** process creation happens. (program: set of instructions) under execution is process. In new state, there is creation of process OR process was already created.
- ② **ready state:** process will wait to run on the CPU.
- ③ **run state:** process will go to CPU. OS has a program called scheduler. Scheduler is of 3 types:
 LTS - long term scheduler (new to ready)
 STS - short term scheduler (ready to run)
 MTS - mid term scheduler



④ **wait/block:** process come from run state to this block due to I/O requirement. Then send to ready state after I/O completion.

- ④ Short-term scheduler will use algorithms to schedule the processes to running state.
- ⑤ Terminate state: After Run state when process gets killed/terminated.
eg download 100% complete (Then download process is Terminated).
Normal Termination: successful execution of program
close/Terminate: 80% downloaded; cancelled.

fig. is described.

P1 go to CPU to run.
P1 need I/O operation; go to wait/block state.
P3 has more priority, P3 sent to CPU to run.
and P1 sent back to Ready state.