Binary Search Trees (BST)

Binary Tree Property:

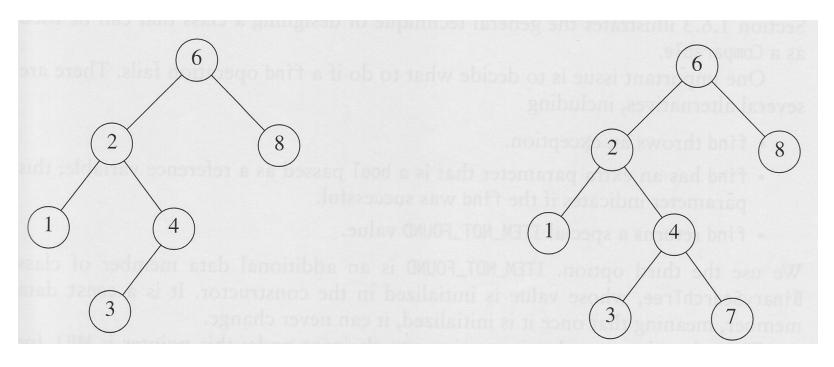
No node can have more than two children.

Binary Search Tree Property:

For every node X in the tree:

- (i) the values of all the items in its *left* subtree are *smaller* than the item in X, and
- (ii) the values of all items in its *right* subtree are *larger* than the item in X.
- All elements in the tree can be ordered in some consistent manner.

Examples



BST

Binary Tree

BinarySearchTree Class

```
template <typename Comparable>
class BinarySearchTree
   public:
             BinarySearchTree();
             BinarySearchTree( const BinarySearchTree & rhs );
             ~BinarySearchTree();
             const Comparable & findMin() const;
             const Comparable & findMax( ) const;
             bool contains( const Comparable & x ) const;
             bool isEmpty() const;
             void printTree( ) const;
             void makeEmpty( );
             void insert( const Comparable & x );
             void remove( const Comparable & x );
             const BinarySearchTree & operator=( const BinarySearchTree & rhs );
```

BinarySearchTree Class

BinarySearchTree Class

```
private:
  BinaryNode *root;
  void insert( const Comparable & x, BinaryNode * & t );
  void remove( const Comparable & x, BinaryNode * & t );
           //pointer variable passed using call by reference
  BinaryNode * findMin( BinaryNode *t ) const;
  BinaryNode * findMax( BinaryNode *t ) const;
  bool contains( const Comparable & x, BinaryNode *t ) const;
  void makeEmpty( BinaryNode * & t );
  void printTree( BinaryNode *t ) const;
  BinaryNode * clone( BinaryNode *t ) const;
```

};

contains Method (public)

```
// Returns true if x is found in the tree.
bool contains( const Comparable & x ) const
{
   return ( contains( x, root ) );
}
```

contains Method (internal)

```
/**
* Internal method to find an item in a subtree.
* x is item to search for.
* t is the node that roots the tree.
*/
bool contains (const Comparable & x, BinaryNode *t) const
{
   if(t == NULL)
            return NULL:
   else if( x < t->element )
            return contains(x, t->left);
   else if( t->element < x )
            return contains( x, t->right ); in average T(N) = O(\log N)
   else
            return true: // Match
```

findMin Method (internal)

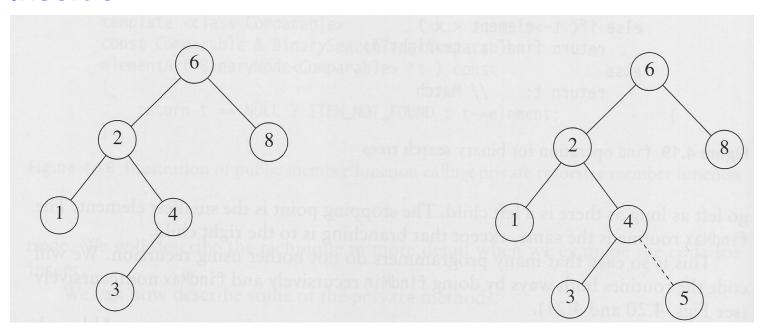
```
/**
* Internal method to find the smallest item in a subtree t.
* Return node containing the smallest item.
*/
BinaryNode * findMin( BinaryNode *t ) const
  if(t == NULL)
         return NULL;
  if(t->left==NULL)
         return t;
  return findMin( t->left );
                                       T(N) = ?
}
```

findMax Method (internal)

It is safe to change t because we are working with a copy of the pointer

Insert Operation

Insert 5

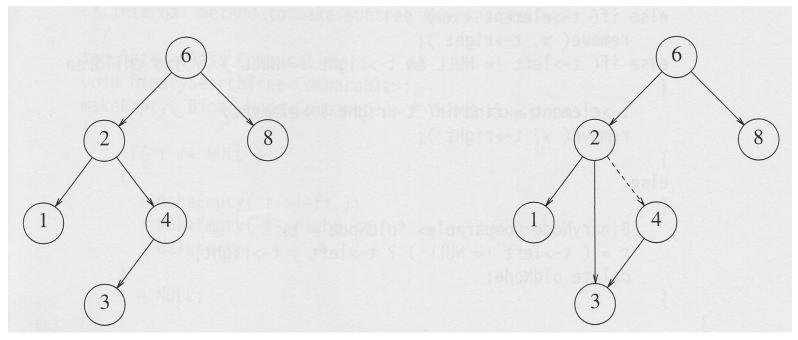


insert Method

```
/**
* Internal method to insert into a subtree.
* x is the item to insert.
* t is the node that roots the tree.
* Set the new root.
*/
void insert( const Comparable & x, BinaryNode * & t ) const
   if(t == NULL)
            t = new BinaryNode(x, NULL, NULL);
   else if( x < t->element )
            insert(x, t->left);
   else if( t->element < x )
            insert( x, t->right );
   else; // Duplicate; do nothing
                                                           T(N) = ?
}
```

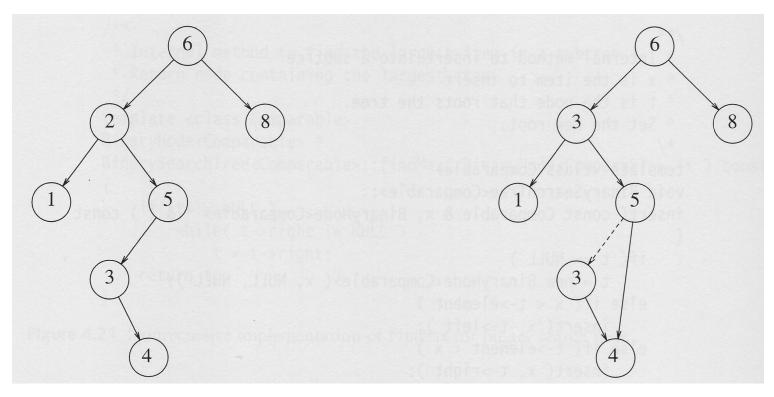
remove Operation

Delete a node with one child => remove 4



remove Operation

Delete a node with two children => remove 2



remove Method

```
/**
* Internal method to remove from a subtree.
* x is the item to remove; t is the node that roots the tree. Set the new root.
*/
void remove( const Comparable & x, BinaryNode * & t ) const
   if(t == NULL)
             return; // Item not found; do nothing
   if( x < t->element )
             remove(x, t->left);
   else if( t->element < x )
             remove(x, t->right);
   else if( t->left != NULL && t->right != NULL ) // Two children
   {
             t->element = findMin( t->right )->element;
             remove( t->element, t->right );
   else
   {
             BinaryNode *oldNode = t;
             t = (t->left != NULL)? t->left : t->right;
             delete oldNode;
                                                       T(N) = ?
```

Destructor and makeEmpty

```
/**
* Destructor for the tree.
*/
~BinarySearchTree()
   makeEmpty();
/**
* Internal method to make subtree empty.
*/
void makeEmpty( BinaryNode * & t ) const
  if( t != NULL )
            makeEmpty( t->left );
            makeEmpty( t->right );
            delete t;
  t = NULL;
                                                        T(N) = ?
```

operator= and clone

```
/** * Deep copy. */
const BinarySearchTree & operator=( const BinarySearchTree & rhs )
   if( this != &rhs )
            makeEmpty();
            root = clone( rhs.root );
   return *this;
/** * Internal method to clone subtree. */
BinaryNode * clone( BinaryNode * t ) const
   if(t == NULL)
            return NULL;
   return new BinaryNode( t->element,
                      clone( t->left ), clone( t->right ) );
}
```

Average Case Analysis

- T(N) = O(d) for all operations except MakeEmpty and operator=, where d = depth of the node containing the accessed item.
- Average analysis:

Q: What is the average depth over all nodes in a tree?

- Assumption:
 - all insertion sequences are equally likely.
- Internal path length: D(N) = sum of the depths of all nodes in the tree
- Average depth = D(N)/N
- D(N) = ?

Average Case Analysis

- D(N) = internal path length of a tree T of N nodes
 D(1) = 0, D(0) = 0
- T consists of:
 - An i-node left subtree => D(i) + i
 - An (N-i-1)-node right subtree => D(N-i-1) + (N-i-1)
- D(N) = D(i) + D(N-i-1) + N-1
- All subtree sizes are equally likely

$$D(N) = \frac{2}{N} \left[\sum_{j=0}^{N-1} D(j) \right] + N - 1$$

Average Case Analysis

- ND(N) (N-1)D(N-1) = 2D(N-1) + 2(N-1)
- ND(N) = (N+1)D(N-1) + 2(N-1)
- D(N)/(N+1) = D(N-1)/N + 2(N-1)/(N(N+1))
- $D(N)/(N+1) = D(1)/2 + 2(\sum_{i=1}^{N} (i-1)/(i(i+1)))$
- $D(N)/(N+1) = 2 \sum_{2}^{N} (2/(i+1) 1/i)$
- $D(N)/(N+1) = 2(1/(N+1) \frac{1}{2} + \sum_{2}^{N} (1/(i+1))$
- $D(N) = O(N \log N)$
- => Average depth of a node = O(log N)