

sensorTask



```
graph LR; A[sensorTask] --> B[sendCAN_BMU_BrakePressure];
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is white with a black border and contains the text 'sensorTask'. The right box is gray with a black border and contains the text 'sendCAN\_BMU\_BrakePressure'. A dark blue arrow points from the right side of the first box to the left side of the second box.

sendCAN\_BMU\_BrakePressure