

Privacy-ensuring fall detection using mmWave technology

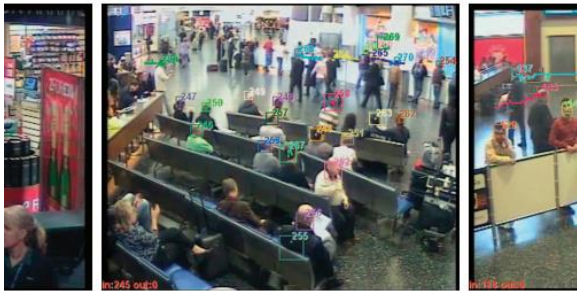
Abanob Tawfik

z5075490

Recap

- One of the biggest causes of fatal and non-fatal injuries amongst people
- According to the World Health Organisation
 - Falls are the second leading cause of accidental or unintentional injury deaths worldwide
 - Each year approximately 646,000 people die from falls globally
 - Adults over the age over 65 tend to suffer the greatest number of fatal falls
 - 37.3 million falls occur each year that require medical attention

Problems in Fall Detection



- Phone and sensor based fall detection methods can be problematic
- Camera-based monitoring requires data for training which is often unacquirable as:
 - Falls are unlikely events
 - It is unethical to ask elderly people to fall
 - Training data from healthier younger people cannot simulate a real natural fall
- There is still no standard for fall detection that performs consistently well
- Camera-based monitoring raises privacy concerns

Aim For Thesis B

[illegible]

Progress During Thesis B

- Progress for thesis B began early
- First task was to setup a codebase in katana
- After code base was set up in katana issues had arisen
 - Data storage (OneDrive)

Progress During Thesis B

- After successfully setting up katana I created a manual guide for others to use
 - Set up katana
 - Integrate one drive
- I had also gotten a shared drive to store all the data for the team to use
- Began coding the complex model

Data Preprocessing

- Data pre-processing had been problematic since mmWave data was stored as a csv dump in raw point cloud form
- Data had no structure, making the model unable to distinguish between activities
- Developed a data cleaning script to link training data to activities and provide structure to the data

Start_Time	Location_Class	Activity_Class
00:00.98334	Room	StartSignal
00:05.15000	Room	Walking
00:11.11300	Room	Stand
00:13.61362	Room	Walking
00:20.49994	Room	Stand
00:23.66667	Room	Walking
00:30.07923	Room	Stand
00:33.69551	Room	Walking
00:39.45000	Room	Stand
00:45.41667	Room	Walking
00:51.16137	Room	Stand
00:56.78334	Room	Walking
01:08.15000	Room	Stand
01:12.28198	Room	Walking
01:14.85954	Room	FinishSignal
01:17.78335	Room	EndTime

▼ Radar
▼ over-05-00-00_2020-08-19
■ points_cloud.csv
■ target_list.csv
■ track_ids.csv

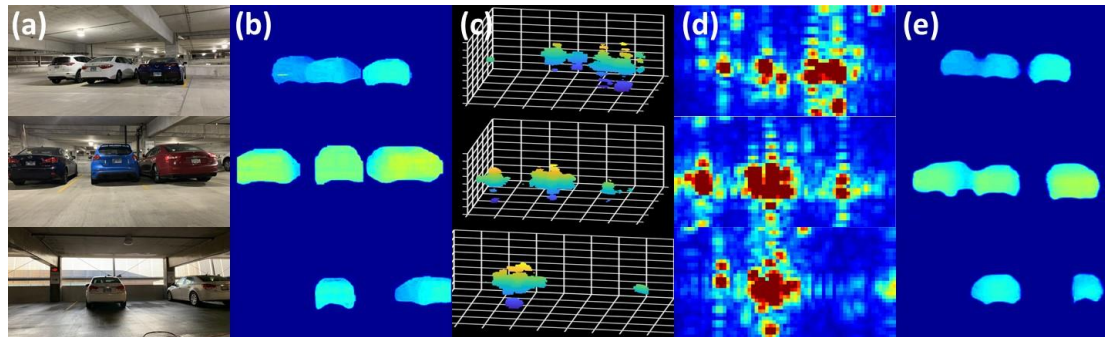
▼ Data_Input
> Background
> EndTime
> Falling
> FinishSignal
> LayBed
> LayFloor
> Sit
> SitBed
> Stand
> StartSignal
> Transition
> Transitions
> Walking

Data Preprocessing

- Data is initially a point cloud of mmWave data, where one frame contains a random amount of points
- Data needs to be grouped into frames
- Activities are then defined by their sequence of frames
- Samples can be categorised into normal and abnormal data

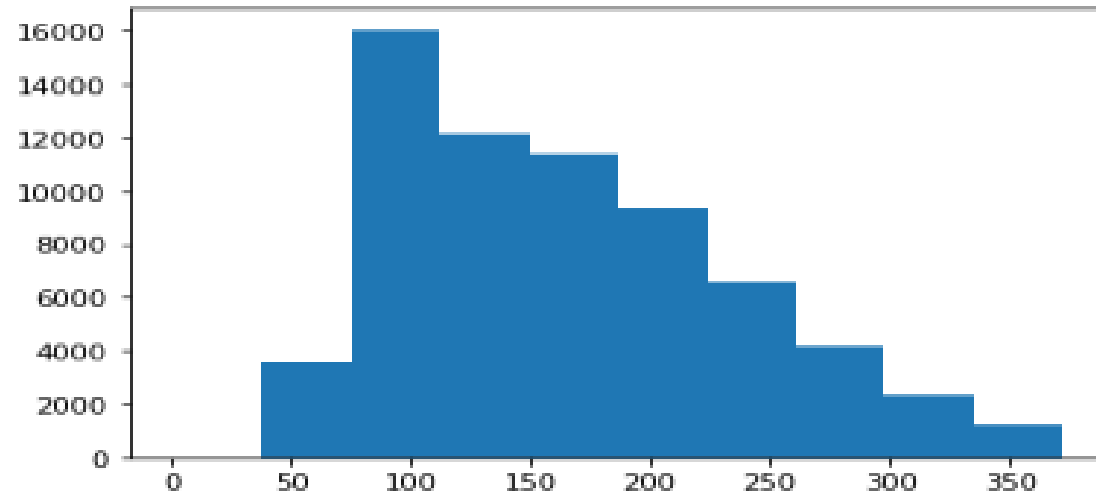
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Issue Arises



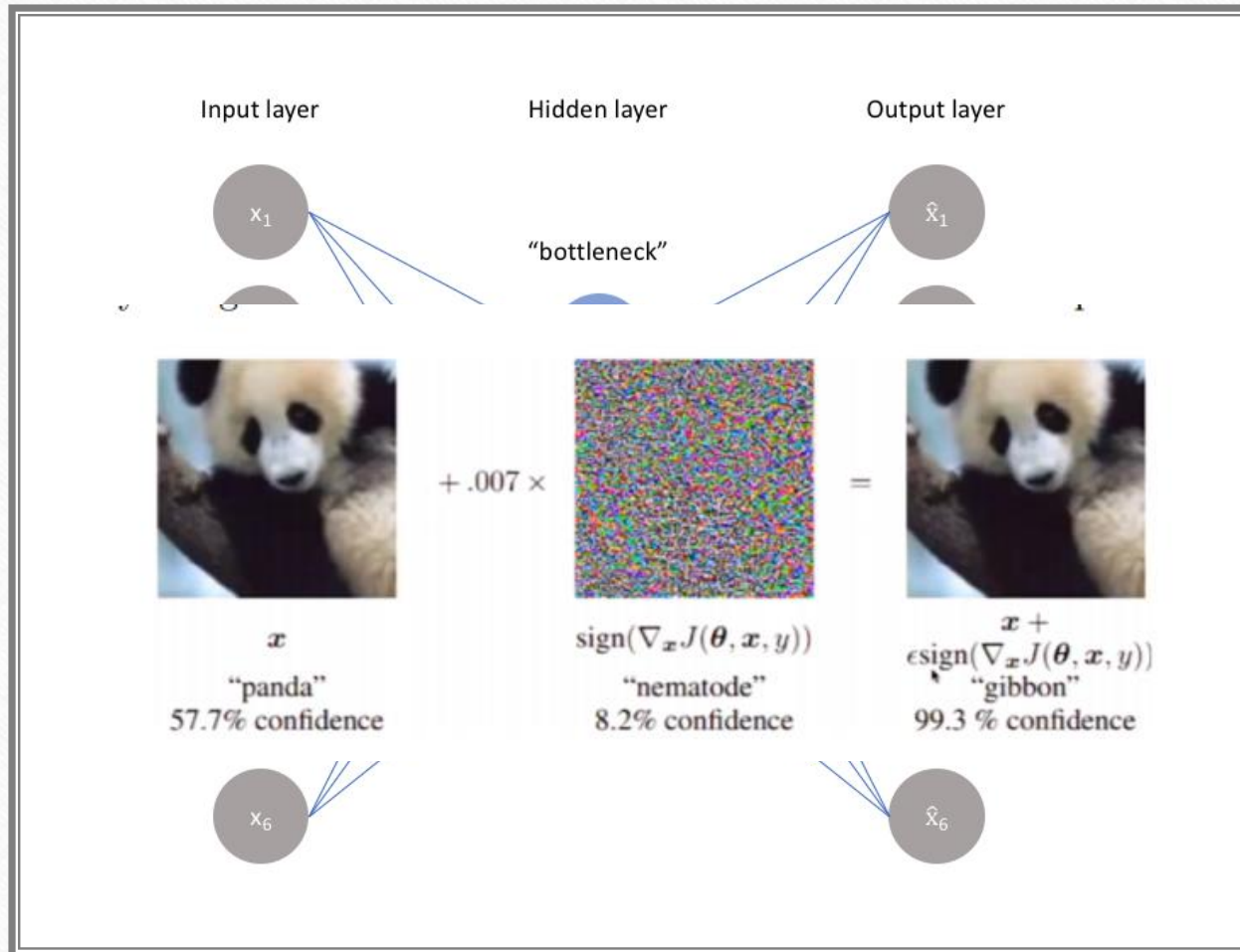
- Due to the real-time requirement of the project at hand, data input became problematic
- Point cloud frames have a random number of points due to nature of point cloud data
- Machine learning models work with fixed input size

Solution

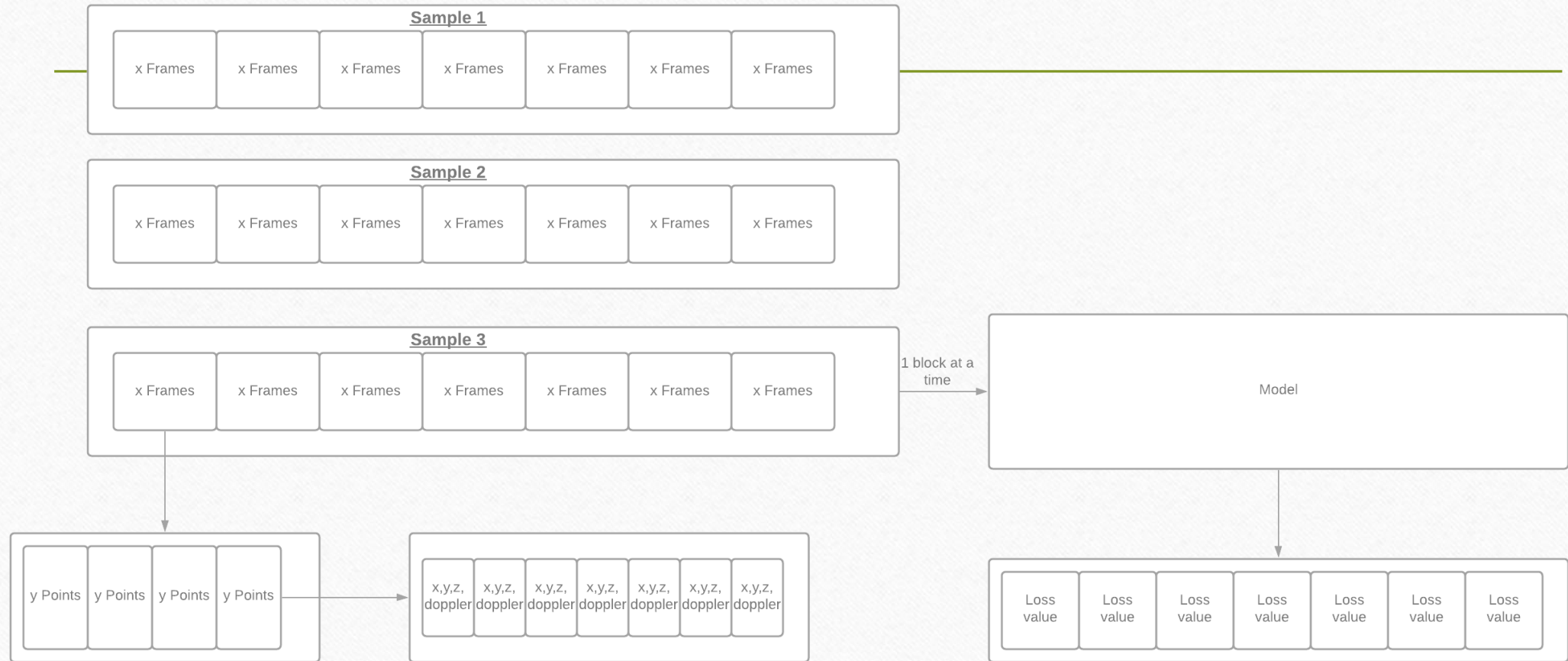


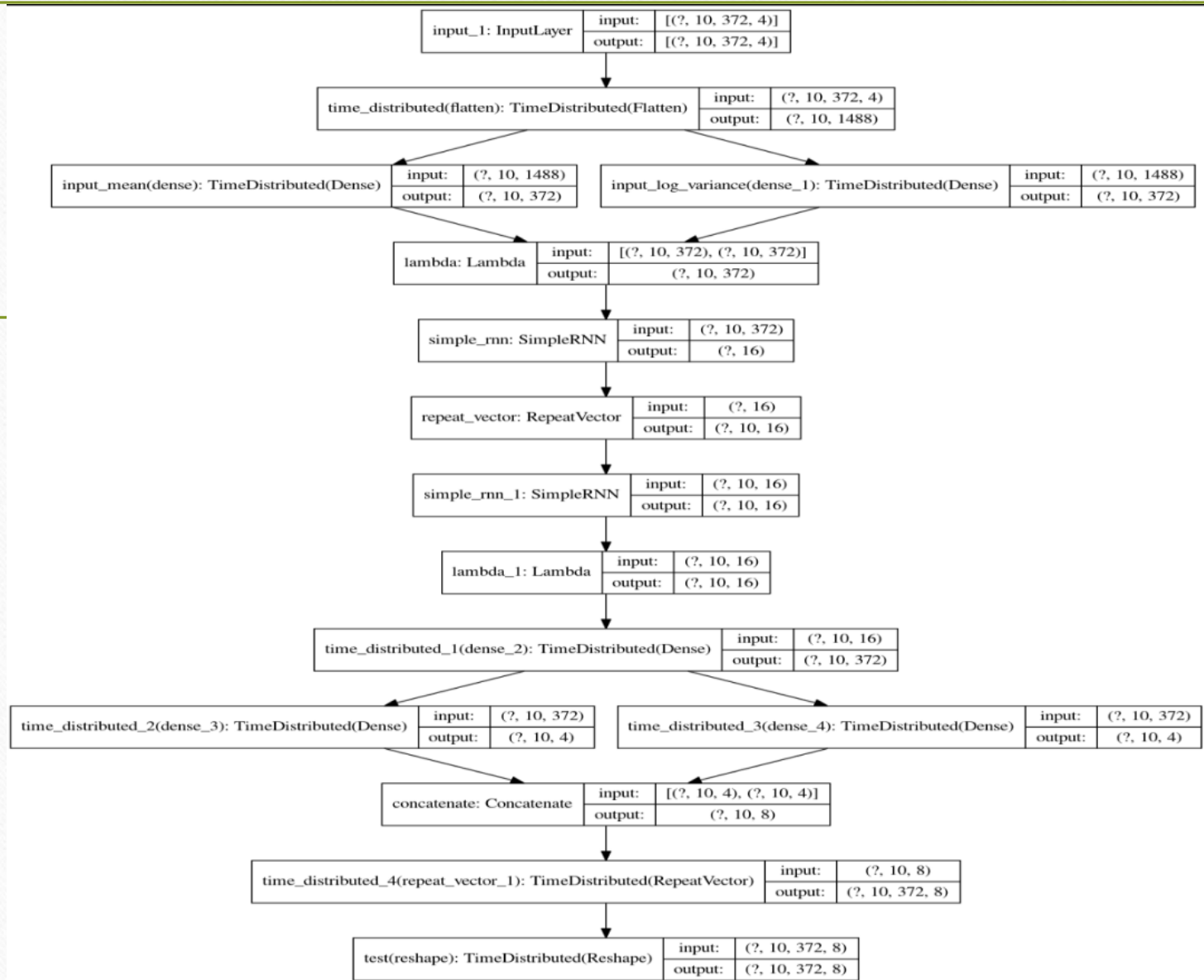
- Frame statistics were gathered
 - Training set
 - Testing set
- Using this result, all input was oversampled to match the maximum possible frame size

Autoencoders



My Model Design – Input Output





Thresholding

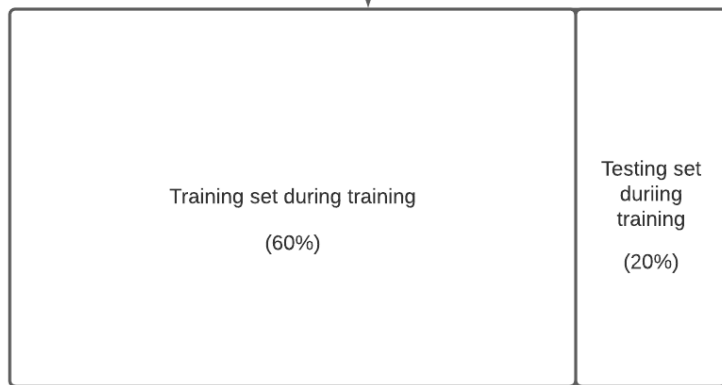
Threshold = 0.01

0.000431	0.00201	0.00301	0.0001	0.02	0.0031	0.00012	0.0091	0.00321	0.0021	0.0001	0.0051	0.0041
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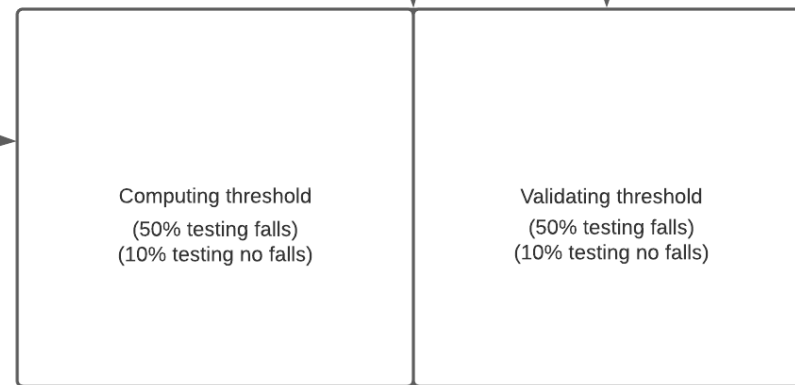
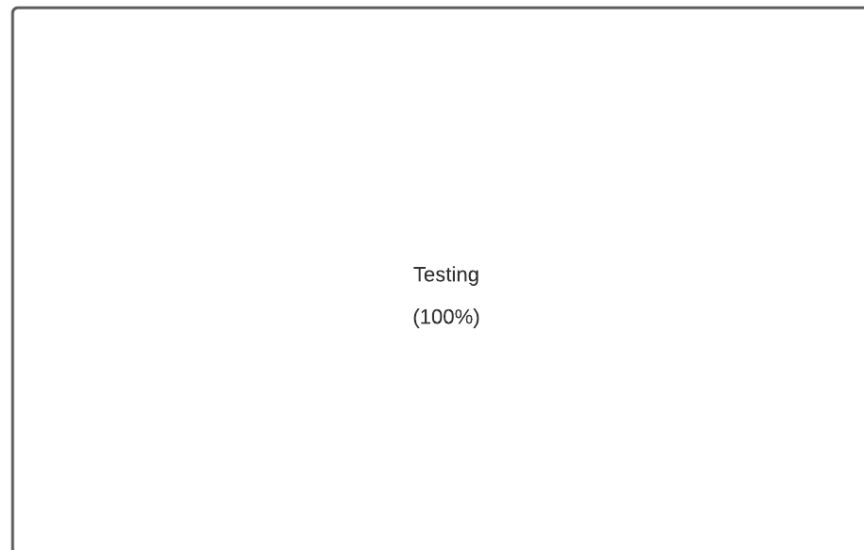
Fall detected since a
set of x frames was
over threshold

- To determine if a fall occurred, we check if a loss value is above a threshold
- Finding an optimal threshold to both minimise false positives and maximise true positives is a hard task
- Youden index can be used to determine this threshold
- Threshold must be validated itself
 - Test set split into two

Non-Fall Samples



Fall Samples



Results of Model From Thesis B

- The current model has yet to implement the youden's index to find an optimal threshold
- This term was more focused on pre-processing and model design
 - Training hasn't been completed yet to a satisfactory level
- Due to the losses in the data, it made it impossible to find a threshold
 - Using 10 frames to determine a loss is not enough
- Despite no great results this term so far, I've set the ball rolling for Thesis C

Outcome of Thesis B

- The model planned for development was completed in its initial form
- All data preprocessing issues overcome
- Data is now processed automatically with many customizable options
 - Still adding more
- The model generated is flexible with many hyper-parameters
- Model can be easily ported into a real time solution

Checklist

To Do	Doing	Done
Port the system into realtime	Create hyper-parameters for the model based on frame size	Data cleaning, add structure to data
Move data into katana shared directory	Develop Youden Index code for finding a threshold	Data preprocessing, organise data into frames
Develop data pre-processing for occupancy grid	+ Add a card	Frame preprocessing to determine maximum frame size
Develop a CNN feature extraction model, to pass into the current model (occupancy grid data vs raw data)		Create model
+ Add a card		Generate results from the model
		Organise the training and testing data for both training and validation
		Analyse results and determine ways to improve model and or threshold
		+ Add a card

Revised Gantt Chart For Thesis B

[illegible]

Old Gantt Chart For Thesis C

[illegible]

Revised Gantt Chart For Thesis C

[illegible]

References

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