# EIE4003 Final Project Presentation

Massive MIMO Performance With Imperfect Channel Reciprocity and Channel Estimation Error

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 <u>Massive MIMO Performance</u> With <u>Imperfect Channel Reciprocity</u> and <u>Channel Estimation Error</u>

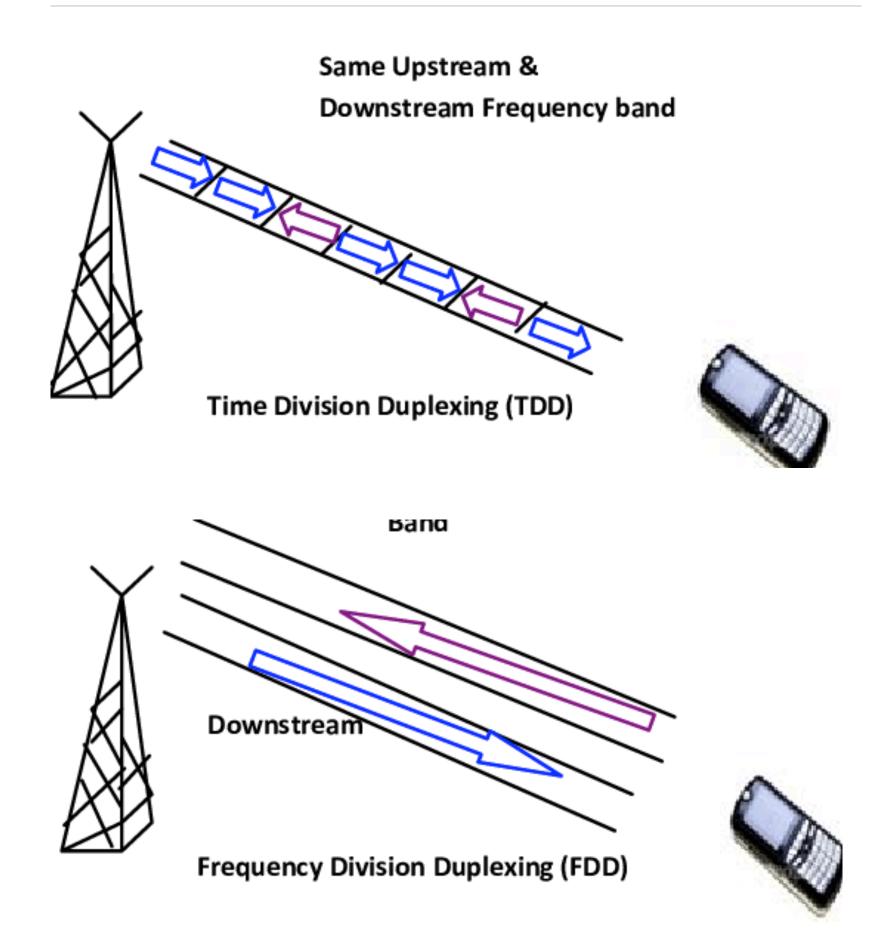
### Core concepts:

- 1. TDD and Channel Reciprocity
- 2. Channel Estimation
- 3. Massive MIMO

### 1. TDD and Channel Reciprocity

TDD - Time Division Duplexing

FDD - Frequency Division Duplexing



### 1. TDD and Channel Reciprocity

- Channel Reciprocity  $H_r = H_t^T$ :
  - TDD: time difference < channel coherence time  $\checkmark$  smaller pilot overhead
  - FDD: freq. difference < channel coherence bandwidth
- Imperfect Channel Reciprocity —> RF chain mismatch

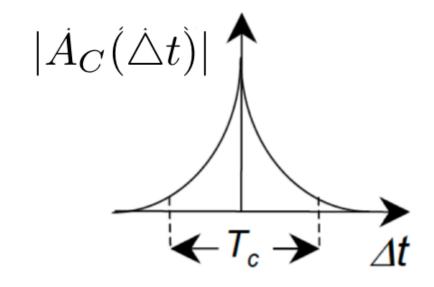


Fig.1 Channel Coherence Time

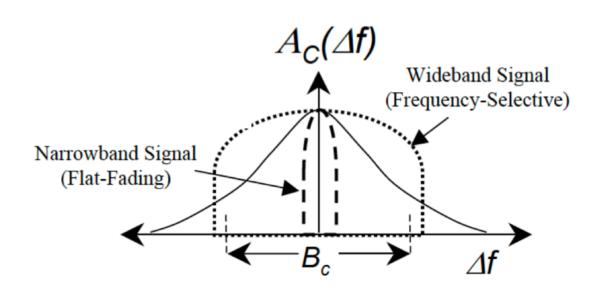


Fig.2 Channel Coherence Bandwidth

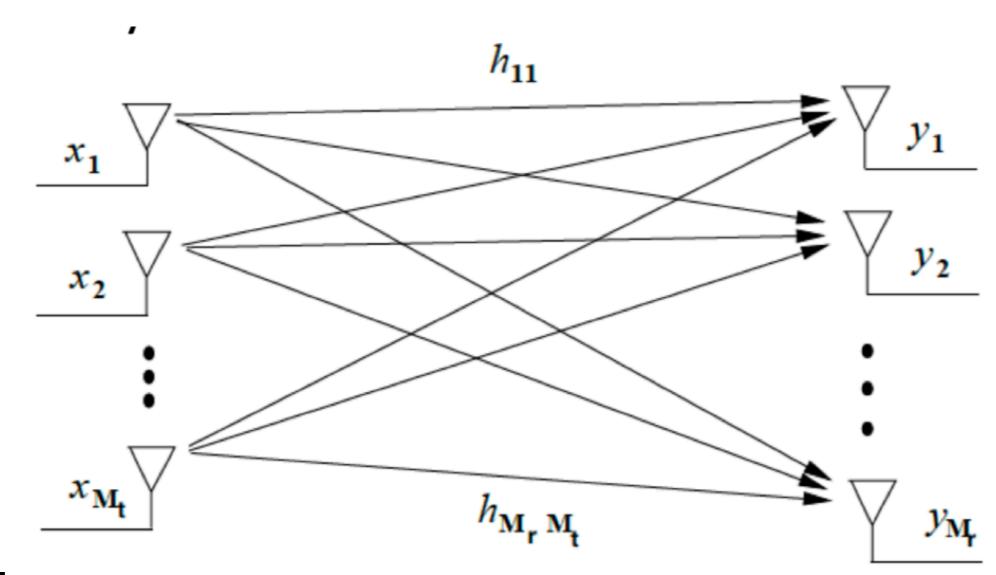
#### 2. Channel Estimation

- Utilize Channel Reciprocity  $H_u = H_d^T$
- But with Estimation Error

Base Station  $H_d$  User Equipment  $H_u = H_d^T$ 

#### 3. Massive MIMO

- Natural extend of MIMO
- $M \to \infty, N \to \infty$
- Millimeter Wave (mmWave)
- Ultra-dense Network
- Channel Hardening -> linear precoding



### Core concepts:

- 1. TDD and Channel Reciprocity ——— Imperfect Channel Reciprocity
- 2. Channel Estimation ——— Channel Estimation Error
- 3. Massive MIMO --- Asymptotic SINR Analysis

# 2. Theory Section

- A. System Model
- B. SINR for MRT and ZF
- C. Asymptotic SINR Analysis

- Imperfect Channel Reciprocity
- Channel Estimation Error

#### Basic Setting:

- 1 BS with M antennas
- K user with single antenna
- M >> k
- Antenna coupling negligible
- Within channel coherence time

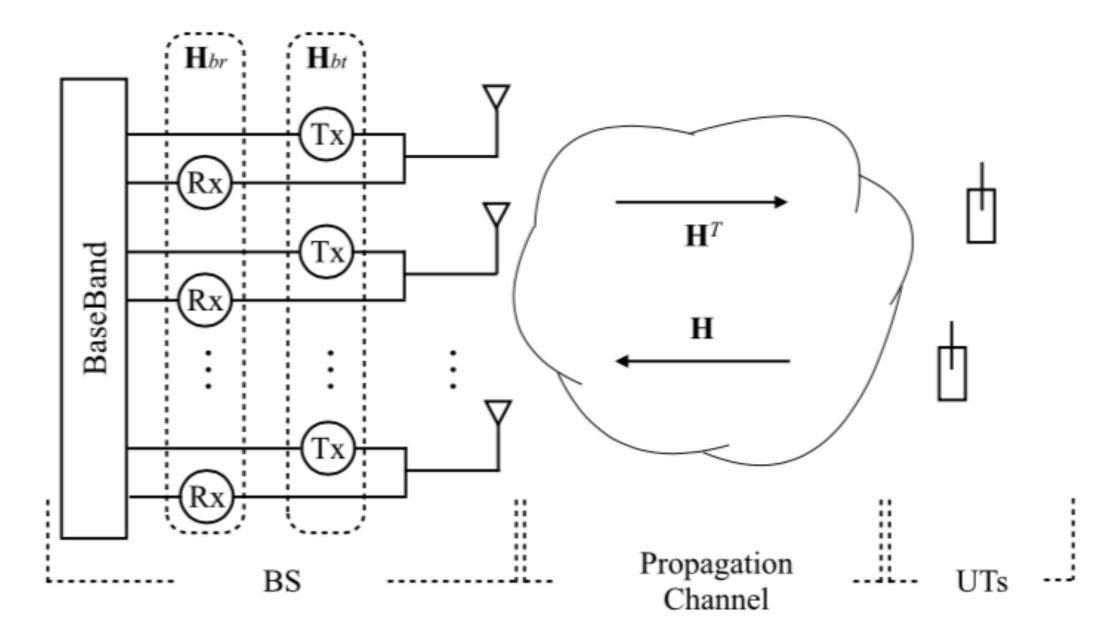


Fig. 1. A massive MU-MIMO TDD system.

#### • 1. Imperfect Channel Reciprocity (e.g. in RX)

- Effective response of RF:  $H_{br} = diag(h_{br,1}, \dots, h_{br,i}, \dots, h_{br,M})$ ,  $\mathbf{H} \in \mathbb{C}^{M \times K}$
- Amplitude/Phase:  $h_{br,i} = A_{br,i} \exp \left( j \varphi_{br,i} \right)$
- Independent Variable: (truncated gaussian distribution)

$$A_{bt,i} \sim \mathcal{N}_{\Gamma}(\alpha_{bt,0}, \sigma_{bt}^{2}), A_{bt,i} \in [a_{t}, b_{t}],$$

$$\varphi_{bt,i} \sim \mathcal{N}_{\Gamma}(\theta_{bt,0}, \sigma_{\varphi_{t}}^{2}), \varphi_{bt,i} \in [\theta_{t,1}, \theta_{t,2}],$$

$$A_{br,i} \sim \mathcal{N}_{\Gamma}(\alpha_{br,0}, \sigma_{br}^{2}), A_{br,i} \in [a_{r}, b_{r}],$$

$$\varphi_{br,i} \sim \mathcal{N}_{\Gamma}(\theta_{br,0}, \sigma_{\varphi_{r}}^{2}), \varphi_{br,i} \in [\theta_{r,1}, \theta_{r,2}],$$

• 1. Imperfect Channel Reciprocity (e.g. in RX)

• RF Mismatch: 
$$\mathbf{E} \triangleq \mathbf{H}_{bt}\mathbf{H}_{br}^{-1} = \operatorname{diag}\left(\frac{h_{bt,1}}{h_{br,1}}, \cdots, \frac{h_{bt,i}}{h_{br,i}}, \cdots, \frac{h_{bt,M}}{h_{br,M}}\right)$$

• RF Mismatch is a multiplicative error, which will be shown later.

#### 2. Channel Estimation Error

- Additive Random Error:
  - $\hat{\mathbf{H}}_{u} = \sqrt{1 \tau^2} \mathbf{H}_{br} \mathbf{H} + \tau \mathbf{V}$
- Estimation Variance Parameter  $\tau \in [0,1]$ :
  - $\tau = 0$ , perfect estimation
  - $\tau = 1$ , only estimation error, uncorrelated with real channel response

 $\hat{\mathbf{H}}_u$ : estimation of uplink channel  $\mathbf{H}_u$ : actual uplink channel response  $\mathbf{H}$ : propagation channel

 ${f V}$ : channel estimation error

#### Entire Channel Model:

• Estimated downlink by Channel Reciprocity:  $\hat{\mathbf{H}}_d = \hat{\mathbf{H}}_u^T = \sqrt{1 - \tau^2} \mathbf{H}^T \mathbf{H}_{br} + \tau \mathbf{V}^T$ 

• Actual downlink channel response:  $\mathbf{H}_d = \mathbf{H}^T \mathbf{H}_{bt}$ 

Comparison: 
$$\mathbf{H}_d = \frac{1}{\sqrt{1 - \tau^2}} \left( \hat{\mathbf{H}}_d \right)$$

 $\mathbf{H}_{d} = \frac{1}{\sqrt{1 - \tau^{2}}} \left( \hat{\mathbf{H}}_{d} - \tau \mathbf{V}^{T} \right) \cdot \mathbf{H}_{br}^{-1} \mathbf{H}_{bt}$ reciprocity errors

### Receive Signal:

$$\mathbf{y} = \sqrt{\rho_d} \lambda \mathbf{H}_d \mathbf{W} \mathbf{s} + \mathbf{n} = \sqrt{\rho_d} \lambda \mathbf{H}^T \mathbf{H}_{bt} \mathbf{W} \mathbf{s} + \mathbf{n}$$

# 2B. Theory - SINR for MRT and ZF

- MRT (maximum ratio transmission):
  - a match filter approach to maximize SNR:

$$\mathbf{W}_{\text{mrt}} = \hat{\mathbf{H}}_d^H = \sqrt{1 - \tau^2} \mathbf{H}_{br}^* \mathbf{H}^* + \tau \mathbf{V}^*$$

- **ZF** (zero-forcing):
  - Cancel the interference:

$$\mathbf{W}_{\mathrm{zf}} = \hat{\mathbf{H}}_{d}^{H} \left( \hat{\mathbf{H}}_{d} \hat{\mathbf{H}}_{d}^{H} \right)^{-1}$$

### 2B. Theory - SINR for MRT and ZF

• SINR (Signal to Interference and Noise Ratio):

$$y_k = \underbrace{\sqrt{\rho_d} \lambda \mathbf{h}_k^T \mathbf{H}_{bt} \mathbf{w}_k s_k}_{\text{Desired Signal}} + \underbrace{\sqrt{\rho_d} \lambda \sum_{i=1, i \neq k}^{K} \mathbf{h}_k^T \mathbf{H}_{bt} \mathbf{w}_i s_i}_{\text{Inter-user Interference}} + \underbrace{n_k}_{\text{Noise}}$$

And it can be approximated by:

$$SINR_{k} = \mathbb{E}\left\{\frac{P_{s}}{P_{I} + \sigma_{k}^{2}}\right\} \approx \mathbb{E}\left\{P_{s}\right\} \mathbb{E}\left\{\frac{1}{P_{I} + \sigma_{k}^{2}}\right\}$$

### 2C. Theory - Asymptotic SINR Analysis

Asymptotic SINR: (Channel Reciprocity Error Only)

$$\lim_{\substack{M \to \infty \\ K \gg 1}} SINR_{k,mrt} = \boxed{\frac{M}{K}} A_I \qquad \qquad \lim_{\substack{M \to \infty \\ M \gg K \gg 1,}} SINR_{k,zf} = \boxed{\frac{M}{K}} \left(\frac{1}{A_I^{-1} - 1}\right)$$

- Upper Bound due to inter-user interference (ISI): MRT = ZF
- Ceiling Effect due to the reciprocity error  $(A_I)$

## 2C. Theory - Asymptotic SINR Analysis

Asymptotic SINR: (Compound Effect of two Errors)

$$\lim_{M \to \infty, \atop K \gg 1} \operatorname{SINR}_{k, \operatorname{mrt}} = \boxed{\frac{M}{K}} \left( \frac{\rho_d \tilde{B}_I}{\rho_d + A_t^{-1}} \right) \qquad \lim_{M \to \infty, \atop K \gg 1} \operatorname{SINR}_{k, \operatorname{zf}} = \boxed{\frac{M - K}{K}} \left( \frac{\rho_d \tilde{B}_I}{\rho_d \left( 1 - \tilde{B}_I \right) + A_t^{-1}} \right)$$

- Upper Bound due to inter-user interference (ISI): MRT > ZF
- Ceiling Effect due to the compound error:  $\tilde{B}_I pprox \left(1 au^2\right) A_I$ 
  - Note that also affected by <u>transmit power</u>

# 3. Simulation Result

- A. Channel Reciprocity Error
- B. Compound Effect
- C. MRT ZF Comparison

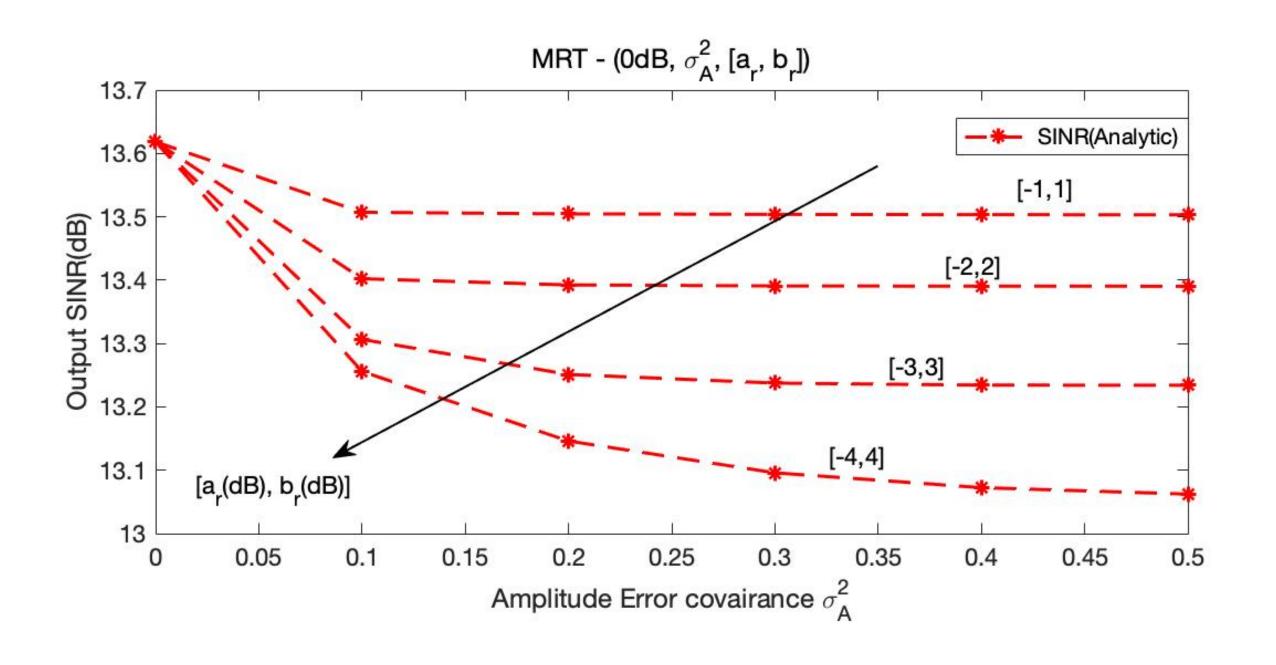
#### Cases:

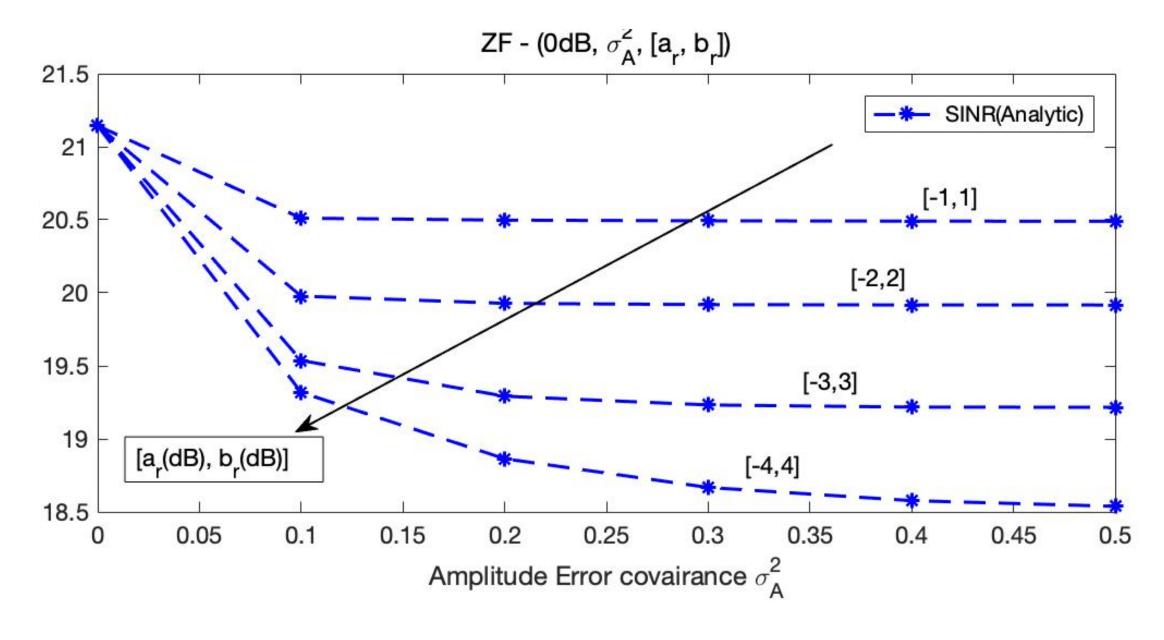
- 1. Fix phase, amplitude error only
- 2. Fix amplitude, phase error only
- 3. Both phase and amplitude error

#### Scenarios in each case:

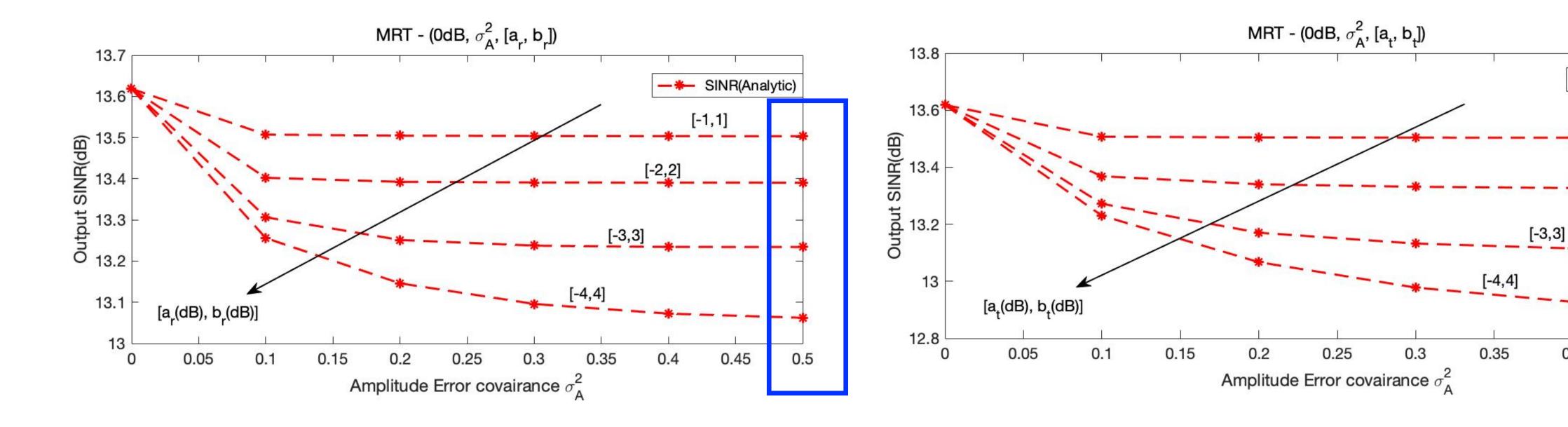
- 1. Change truncated range and variance
- 2. Compare TX and RX
- 3. Compare MRT and ZF

- Cases 1: Fix phase, amplitude error only
  - 1. SINR degrades with the increase of variance and truncate range.





- Cases 1: Fix phase, amplitude error only
  - 2. TX and RX brings slightly different impact to SINR



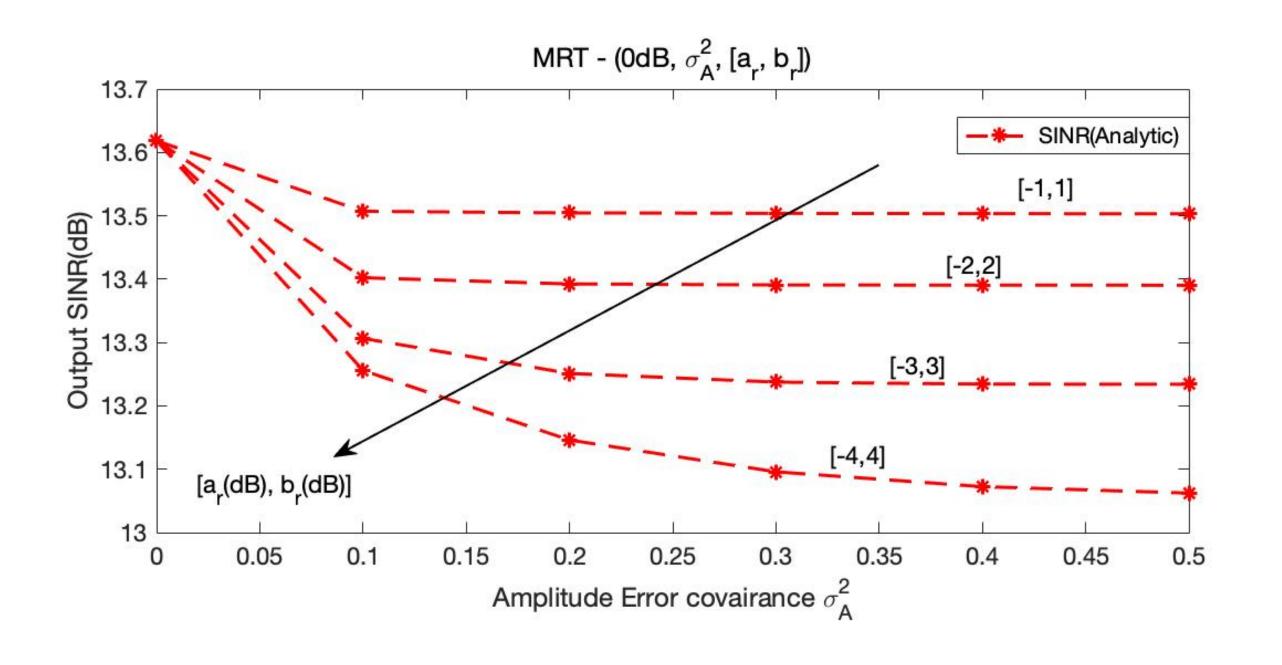
SINR(Analytic)

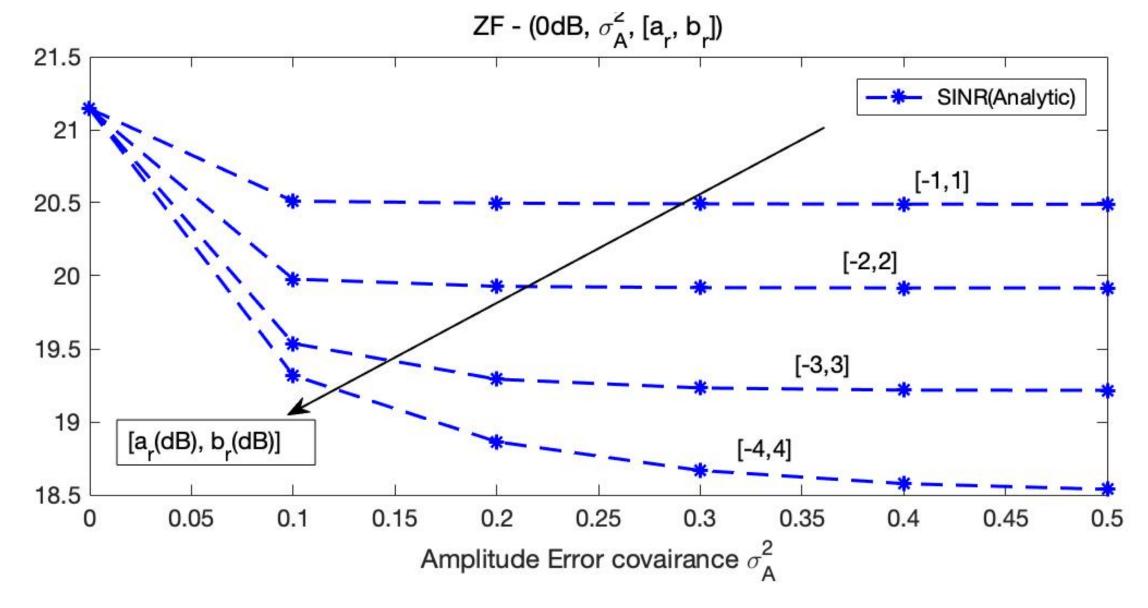
0.45

[-1,1]

[-2,2]

- Cases 1: Fix phase, amplitude error only
  - 3. ZF is more sensitive to error than MRT





Cases 2: Fix amplitude, phase error only

- 1. Similar to case 1
- 2. Phase has more impact than amplitude
- 3. Error mean has less impact than truncate range on SINR

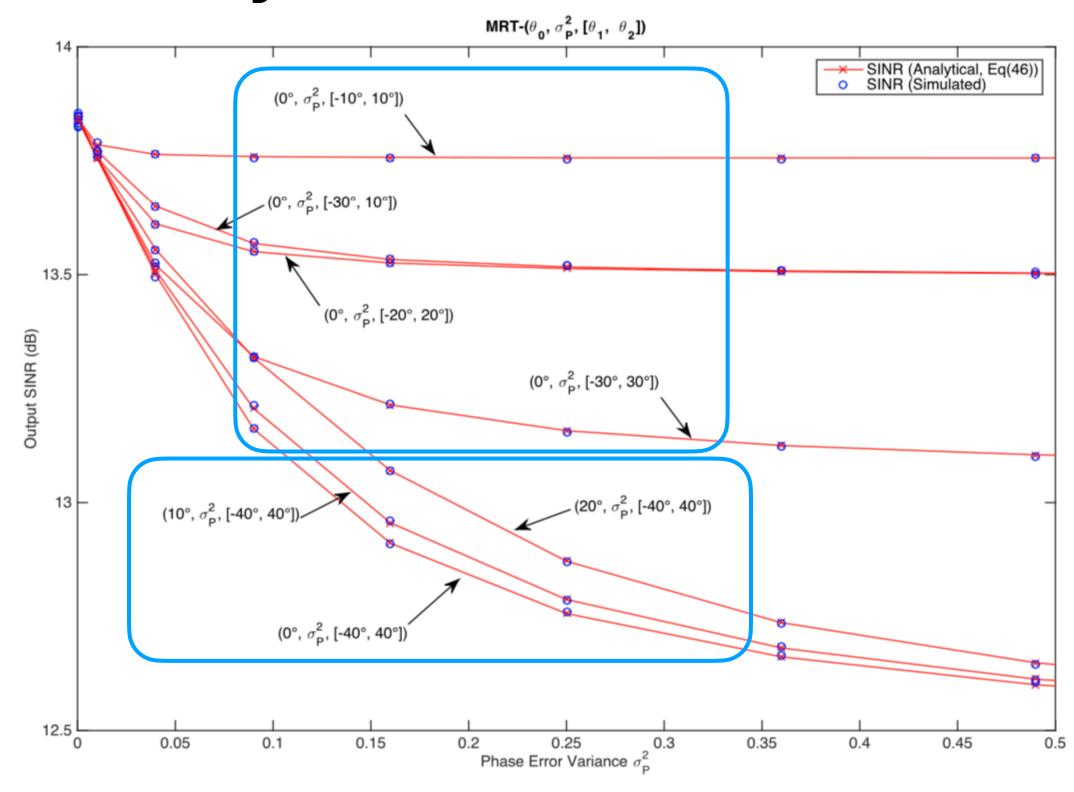
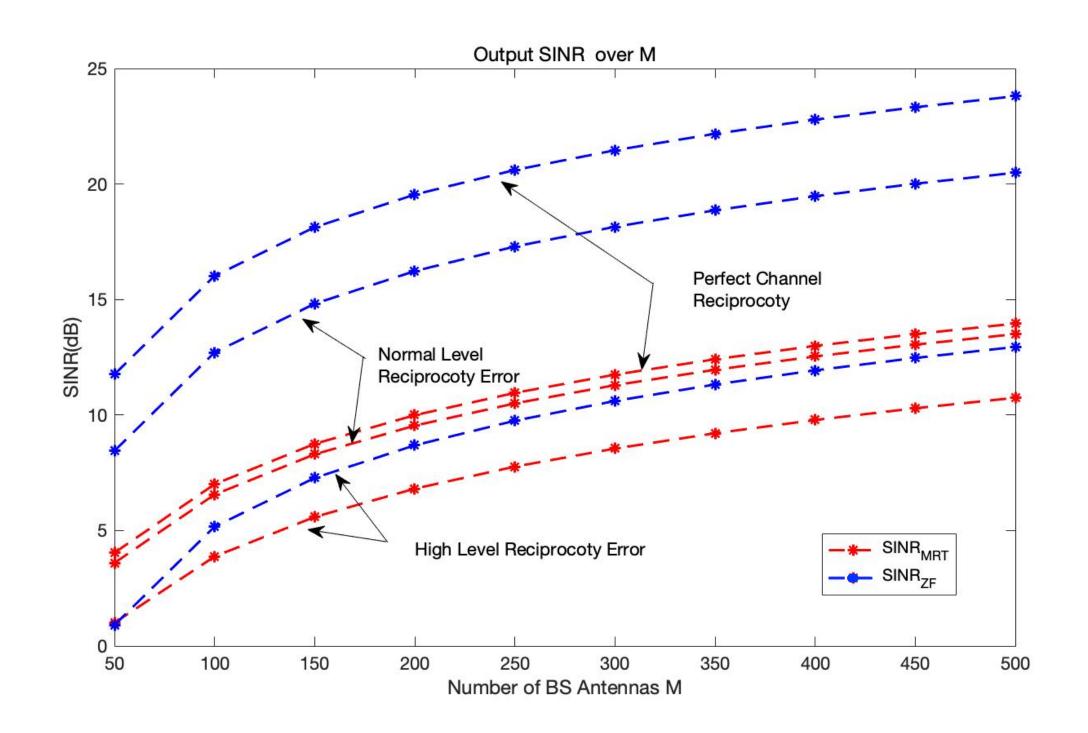
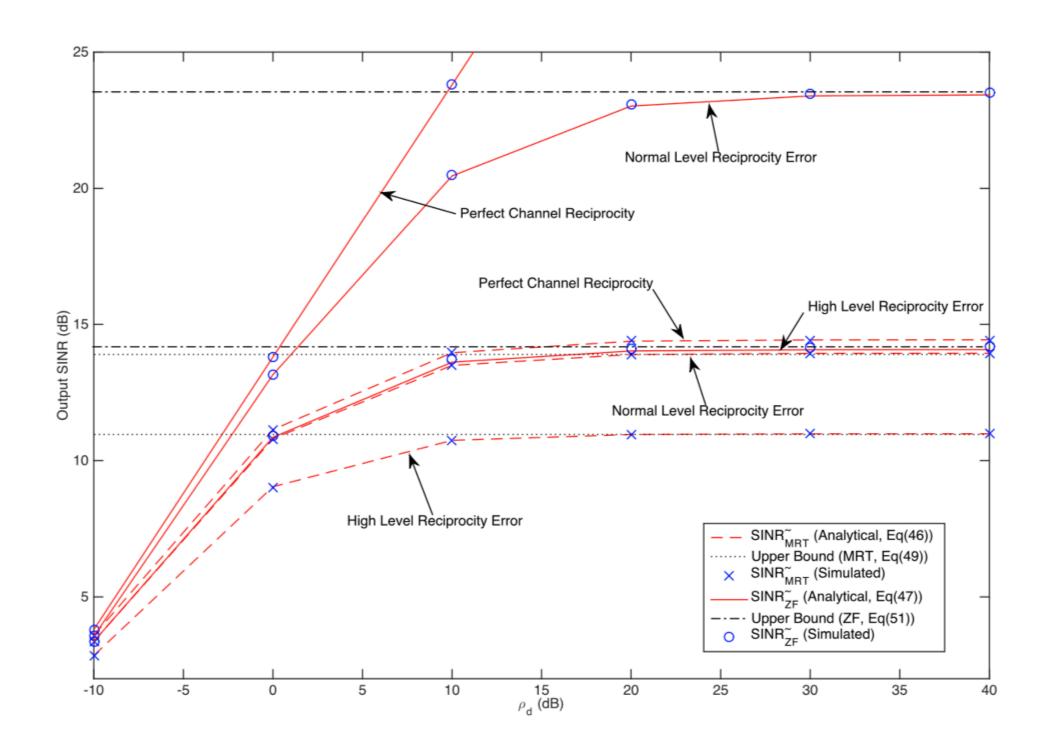


Fig. 4. Output SINR with MRT precoding in the presence of fixed amplitude errors and different combinations of phase errors.

#### Cases 3: both phase/amp error

- 1. SINR increases with the number of antennas in BS
- 2. Ceiling Effect (previous introduced):  $\lim_{\substack{M \to \infty \\ \nu \le 1}} SINR_{k,mrt} = \frac{M}{K} A_I$
- 3. ZF outperforms MRT

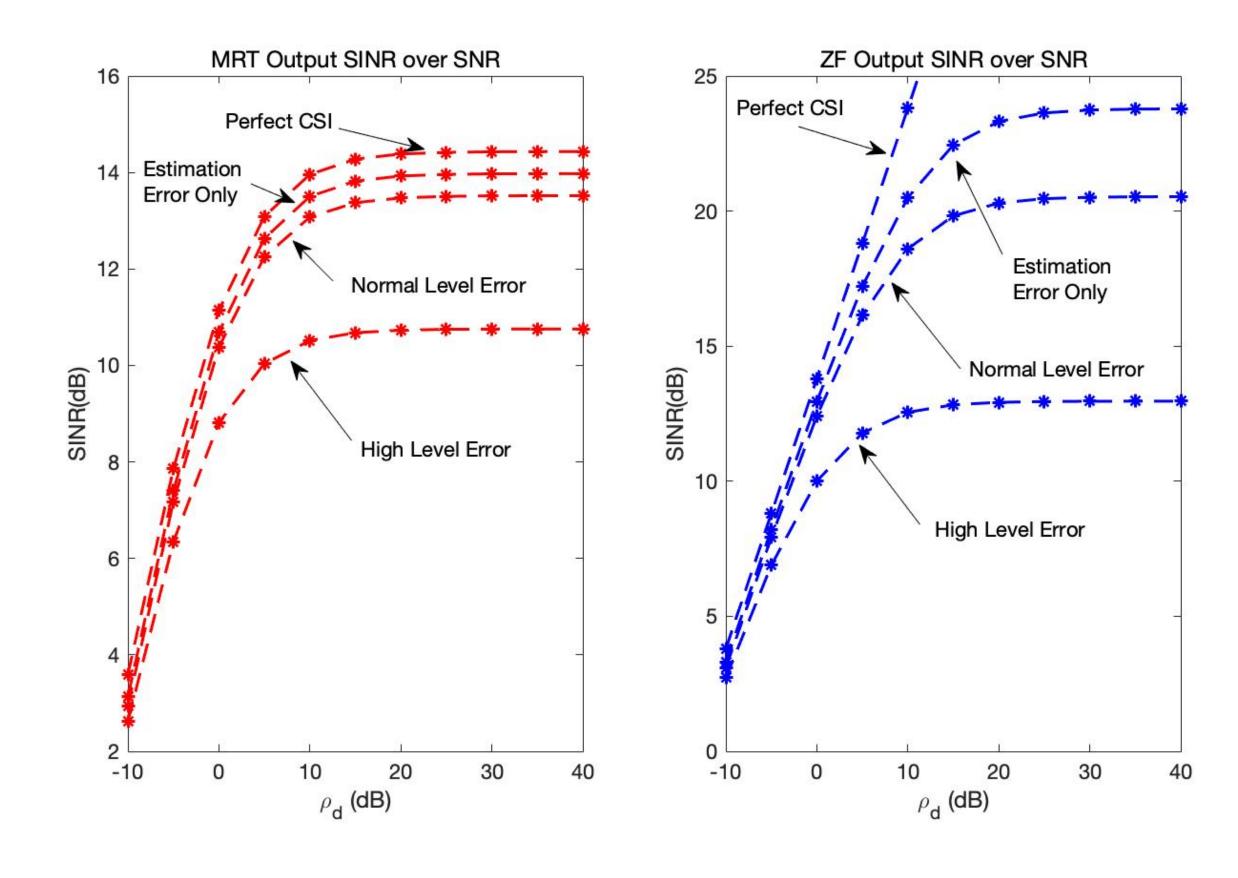




### 3B. Result - Compound Effect

Compound Effect: channel reciprocity error + estimation error

- 1. Degradation dur to error
- 2. Again, ZF outperforms MRT



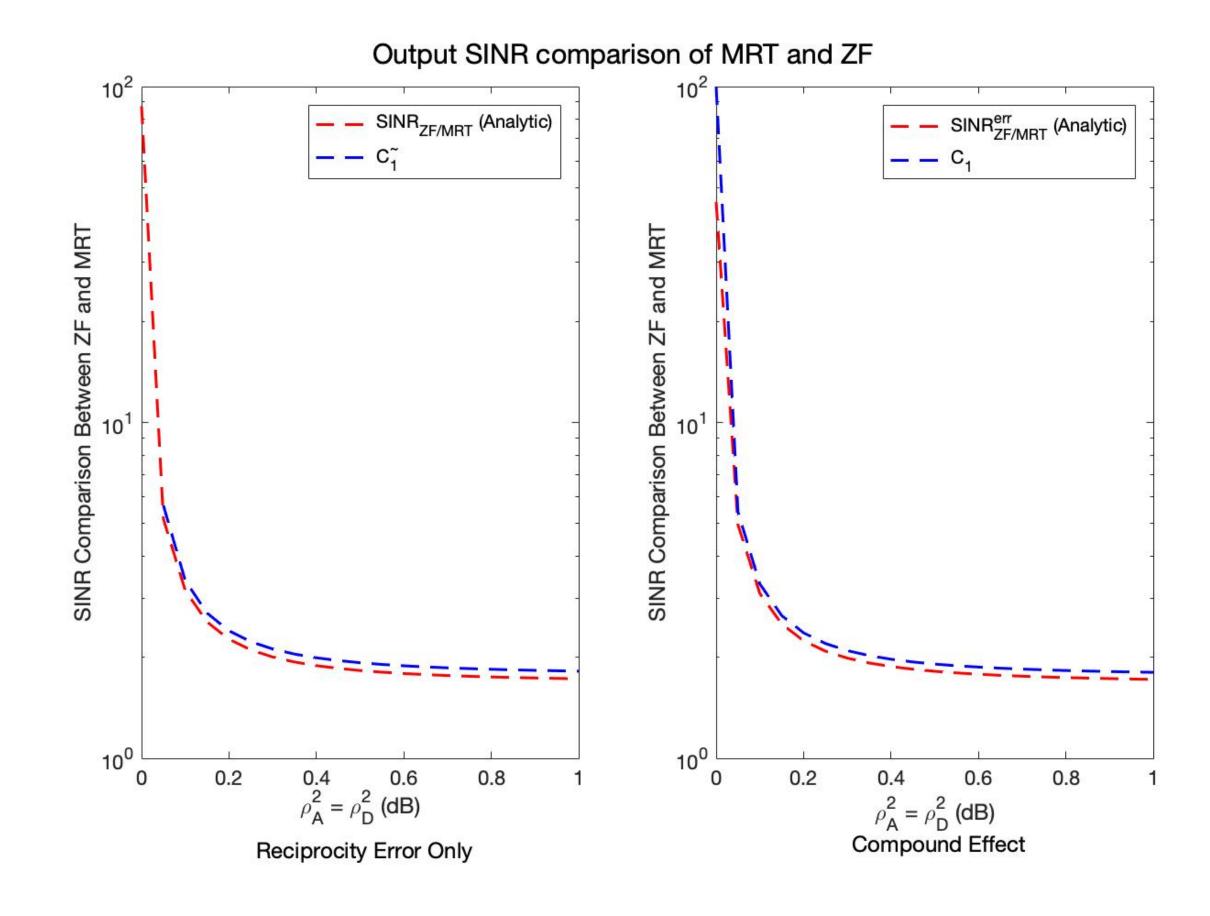
### 3C. Result - MRT ZF Comparison

#### MRT ZF Comparison:

ZF generally outperforms
MRT in both cases

$$\int_{C_{I}} \tilde{C}_{I} \triangleq \lim_{\substack{\rho_{d}(1-A_{I})\gg 1\\ M\to\infty, M\gg K\gg 1}} \frac{\operatorname{SINR}_{k,\operatorname{Zf}}}{\operatorname{SINR}_{k,\operatorname{mrt}}} = \frac{1}{1-A_{I}} > 1$$

$$C_{I} \triangleq \lim_{\substack{M\to\infty,\\ M\gg K\gg 1}} \frac{\operatorname{SINR}_{k,\operatorname{zf}}}{\operatorname{SINR}_{k,\operatorname{mrt}}} = \frac{1}{1-\tilde{B}_{I}} \geq 1$$



# 4. Conclusion/Discussion

### 4. Conclusion

- In conclusion, we model the system with
  - Imperfect Channel Reciprocity -> ceiling effect
  - Channel Estimation Error
- And analyze the output SINR in
  - Normal MIMO
  - Massive MIMO (asymptotic)
- Finally indicate **factors** that may affect output SINR, and **compare** different precoding scheme for choosing precoding scheme
  - -> ZF outperforms MRT, but MRT is more robust to error

### 4. Discussion

#### Further research:

- Consider other linear precoding scheme such as MMSE, or non-linear precoding scheme such as dirty paper coding
- Consider computational complexity and energy efficiency
- Possibly extend to FDD
- $M \approx k$  in ultra dense network?

### 5. Reference List

- D. Mi, M. Dianati, L. Zhang, S. Muhaidat and R. Tafazolli, "Massive MIMO Performance With Imperfect Channel Reciprocity and Channel Estimation Error," in IEEE Transactions on Communications, vol. 65, no. 9, pp. 3734-3749, Sept. 2017, doi: 10.1109/TCOMM.2017.2676088.
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