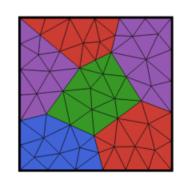




Introduction and overview of Ferrite.jl

Fredrik Ekre Ferrite.jl User & Developer meetup, 2022-09-26



Outline

- What is Julia and Ferrite.jl
- Structure of a FEM program
- What Ferrite.jl provides
- What Ferrite.jl *not* provides
- Other packages and composability
- What needs more work

Who am I?

- Gothenburg, Sweden
- Education at Chalmers University of Technology
 - BSc Civil engineering (2014)
 - MSc Applied Mechanics (2016)
 - PhD Solid and Structural Mechanics (2021). Project: Numerical model reduction and error estimation for multiscale modeling
- Postdoc at IAM since Sept. 2021
- Started with Julia 2015 (v0.4.1)
- Co-developed Ferrite.jl since the start of my PhD



What is Julia?

- High-level dynamic programming language
- General purpose (initially targeting numerical computing)
- Free (as in beer and freedom) and open source
- Ambition to solve the "two-language problem"
- First public in 2012
- Release 1.0 in 2018

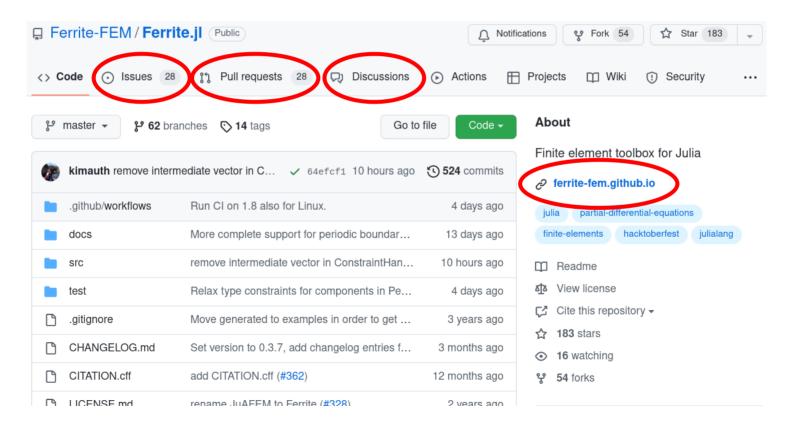


What is Ferrite.jl?

- Finite element toolbox written in Julia
- Not a complete FEA software, but provide many important puzzle pieces
- Initiated by Kristoffer Carlsson in 2016
- No particular road map: we have implemented what we need for our particular research problems

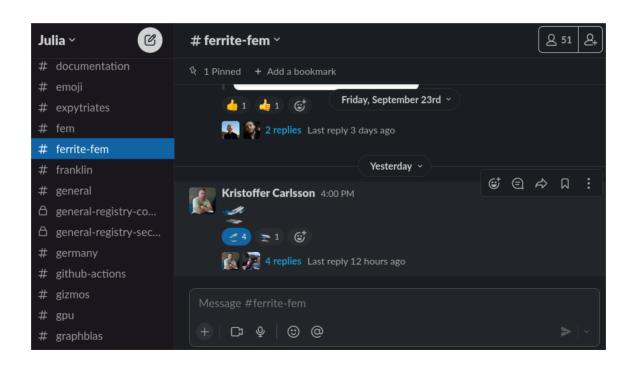
Where to find Ferrite.jl?

GitHub: issues, pull requests, discussions, documentation



Where to find Ferrite.jl?

#ferrite-fem channel on Julia slack workspace



FEM puzzle pieces

Pre-processing

- · Geometry
- Meshing

Assembly

- Tensor operations
- · Shape functions
- Material modeling
- · Numerical integration
- · Boundary conditions

Linear solver for Ax = b (sparse system of equations)

- Direct solver
- Iterative solver

Pre-processing

- Evaluation of secondary quantities
- Visualization

FEM puzzle pieces: Pre-processing

Meshing and geometry modeling

- Not directly provided by Ferrite.jl
- Leverage existing software by parsing output from other software into Ferrite.jl grid format (Gmsh, Abaqus, ...)
 - Works great for "static" meshes
 - For mesh adaptivity a library interface would be better
- Preliminary work for mesh adaptivity by Dennis/Maximilian and co-workers

FEM puzzle pieces: Assembly

- Assembly functionality is the core of Ferrite.jl
- Distribution and book keeping of degrees-of-freedom
- Finite element "kernel" functionality
 - Evaluation of shape functions
 - Evaluation of functions in FE-space (linear, quadratic, ...)
 - Numerical integration, quadrature rules
- (Material modeling: Tensors.jl)
- Routines for assemble element contributions to global system
- Utilities for Dirichlet, Neumann, periodic (Dirichlet) boundary conditions

Dof management: the Dof Handler

Example: two-field problems with linear approximation for a pressure field and quadratic approximation for a displacement field

```
grid = setup_grid(...)
                                       # Generate grid
dh = DofHandler(grid)
                                       # Create DofHandler
push!(dh, :p, Lagrange{3,RefCube,1}()) # Linear pressure field
push!(dh, :u, Lagrange{3,RefCube,2}()) # Quadratic displacement field
close!(dh)
                                       # Finalize
# Query information
ndofs_per_cell(dh)
                                       # Number of dofs per element
celldofs(dh, i)
                                        # Dofs for element i
```

FE kernel: FEValues

Numerical integration and shape function evaluation handled by CellScalarValues (or CellVectorValues)

```
interpolation = Lagrange{3, RefCube, 1}() # Linear interpolation
quad_rule = QuadratureRule{dim, RefCube}(2) # Second order quadrature
cellvalues = CellScalarValues(quad_rule, interpolation)
# Value of shape function i in quadrature point qp
shape_value(cellvalues, qp, i)
# Gradient of shape function i in quadrature point qp
shape_gradient(cellvalues, qp, i)
# Value of FE approximated function with element vector ue
function_value(cellvalues, qp, ue)
```

FE kernel: FEValues

Example: Integration of element matrix and RHS for heat equation

```
for q_point in 1:getnquadpoints(cellvalues)
    d\Omega = getdetJdV(cellvalues, q_point)
    for i in 1:n_basefuncs
        φi = shape_value(cellvalues, q_point, i)
        ∇φi = shape_gradient(cellvalues, q_point, i)
        fe[i] += \phi i * d\Omega
        for j in 1:n_basefuncs
            ∇φj = shape_gradient(cellvalues, q_point, j)
            Ke[i, j] += (∇φi • ∇φj) * dΩ
        end
    end
end
```

Global assembly

Efficient global sparse matrix assembly:

```
# Global tangent matrix and RHS
K = create_sparsity_pattern(dh)
f = zeros(ndofs(dh))
# Assembler for efficient sparse matrix assembly
assembler = start_assemble(K, f)
# Assemble all the elements
for i in 1:nelements
    Ke, fe = element_routine(...)
    assemble!(assembler, celldofs(dh, i), Ke, fe)
end
```

Boundary conditions: the ConstraintHandler

Dirichlet boundary conditions:

```
# Constructor
ch = ConstraintHandler(dh)
dbc = Dirichlet(
                                               # Field name
          :u,
         getfaceset(grid, "DBC"),
                                               # Boundary domain
         (x, t) \rightarrow [\sin(t), \cos(t)],
[1, 3]
                                               # Prescribed value
                                               # Prescribed components
add!(ch, dbc)
                                               # Add to ConstraintHandler
close!(ch)
                                               # Finalize
```

Boundary conditions: the ConstraintHandler

Periodic boundary conditions:

```
ch = ConstraintHandler(dh)
                                            # Constructor
# Compute mapping between mirror and image faces
face_pairs = collect_periodic_faces("mirror", "image")
dbc = PeriodicDirichlet(
                                            # Field name
         :u,
         face_pairs,
                                            # Face mapping
         [2, 3]
                                            # Constrained components
add!(ch, dbc)
                                            # Add to ConstraintHandler
close!(ch)
                                            # Finalize
```

Boundary conditions: Neumann

FaceScalarValues (and FaceVectorValues) analoguous to CellScalarValues for boundary integration

(Currently somewhat "boiler-platey" and would be nice to improve!)

FEM puzzle pieces: Linear system

The default global tangent matrix is a standard Julia SparseMatrixCSC: use your favorite solver!
Single-core:

- Direct solvers for sparse system shipped with Julia (CHOLMOD/UMFPACK)
- Iterative solvers from other Julia packages such as LinearSolve.jl Multi-core (MPI):
 - HYPRE.jl for distributed solvers using compatible with PartitionedArrays.jl
 - (Preliminary work by Dennis for assembly with PartitionedArrays.jl)
- ... which he promised me yesterday to finish during the Hackathon today!

FEM puzzle pieces: Post-processing

Ferrite.jl provide utilities for

- Evaluation of secondary quantities
- Evaluation of primary/secondary fields in arbitrary points of the domain
- Export to VTK file format for "color mechanics"

FerriteViz.jl: Makie.jl based plotting of "Ferrite.jl" data.

HPC with Ferrite.jl?

- Julia (the language) have well developed functionality for both multithreading (single computer) and multi-core (many computers)
 - Multi-threaded assembly: works nicely, see examples
 - Multi-core assembly: work in progress
- Easier to interface with existing HPC libraries

Composability and interaction with other packages

- Ferrite.jl only provide some of the puzzle pieces
- Mostly standard data structures: easy to compose with other packages. Some examples:
 - Tensors.jl: Fast tensor operations, automatic differentiation
 - ForwardDiff.jl: Automatic differentiation for element routine
 - BlockArrays.jl: Block matrix functionality for e.g. multifield problems
 - MaterialModels.jl: Library for standard material models
 - LinearSolve.jl: collection of linear solvers for (sparse) matrices
 - DifferentialEquations.jl: State of the art library for time-integration
 - NLsolve.jl: Algorithms for non-linear systems
 - •

What needs more work?

- Utilities for HPC and multi-core assembly
- Mesh adaptivity
- Less boiler plate code
- Documentation!

Thanks for listening!