DATA11002 Introduction to Machine Learning

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11 November 2020



How to adjust model complexity in (linear) regression?

- feature selection (applicable to all supevised learning models!)
- regularization (shrinkage)
 - ridge regression
 - lasso

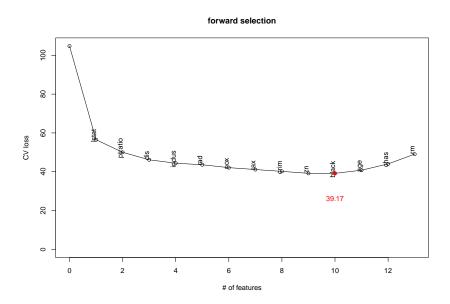
Feature selection

- One way to regulate model flexibility is to choose features (less features = less flexible model)
- Naive algorithm: Given number of features k, find a subset of features of size k, train a regressor for these features, compute (cross-)validation loss, choose the smallest loss.
- ▶ Problem: there are too many subsets, running time $O(p^k)$.
 - subset-selection problem is NP-hard, i.e., fast exact algorithm not likely to exist for large problems.
- **forward selection**: greedy heuristic, running time O(pk).
 - choose feature that gives the smallest (cross-)validation loss
 - add a feature which (added to previously chosen features) gives smallest (cross-)validation loss
 - iterate until you have k features
- backward selection: start from all features, drop them one by one.

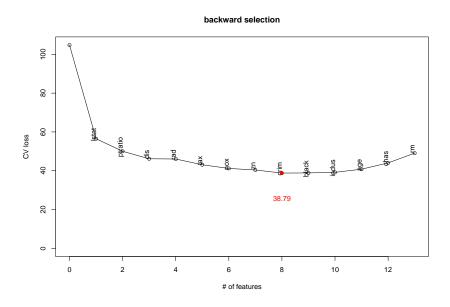
Forward selection

```
fsel <- function(loss,s,v=c(),r=c(),stopat=0) {</pre>
  if(length(v)==0) v \leftarrow loss(r)
  while(length(s)>stopat) {
    a <- sapply(s,function(si) loss(c(r,si)))
    i <- which.min(a)</pre>
    v \leftarrow c(v,a[i])
    r \leftarrow c(r,s[i])
    s \leftarrow s[-i]
  V
```

Forward selection



Backward selection



Regularization: Ridge regression and Lasso

- Feature subset selection is one way to control the complexity of the model
- ▶ We can also "softly" punish more complex models
- Observation: badly overfitting linear models often have large regression coefficients!
- ► Idea: we can constrain allowed models "softly" by punishing large regression coefficients.
 - increase bias
 - decrease variance

Bayesian regularization

The joint probability distribution can be defined, e.g., as

$$p(X, Y, \beta) = p(Y \mid X, \beta)p(X)p(\beta),$$

where the likelihood is, e.g., $p(Y \mid X, \beta) \propto \exp\left(-(Y - X\beta)^T (Y - X\beta)/(2\sigma^2)\right)$ and prior of β , e.g., $p(\beta) \propto \exp\left(-\beta^T \beta/(2\sigma_P^2)\right)$.

maximum-likelihood (ML) solution ("normal" OLS regression):

$$\hat{\beta}_{ML} = \operatorname{arg\,max}_{\beta} p(Y, X \mid \beta) = \operatorname{arg\,min}_{\beta} \sum_{i=1}^{n} (\beta^{T} x_{i} - y_{i})^{2}.$$

maximum-a-posteriori (MAP) solution (Ridge regression with $\lambda_{ridge} = \sigma^2/\sigma_P^2$!):

$$\hat{\beta}_{MAP} = \arg \max_{\beta} p(\beta \mid X, Y) = \arg \max_{\beta} p(Y \mid X, \beta) p(\beta) / p(Y)$$

$$= \arg \min_{\beta} \left(\sum_{i=1}^{n} (\beta^{T} x_{i} - y_{i})^{2} + \sigma^{2} / \sigma_{P}^{2} \sum_{j=0}^{p} \beta_{j}^{2} \right).$$

Bayesian regularization (addendum)

Here the data set is composed of the vector of dependent variables $Y \in \mathbb{R}^n$ and the design matrix $X \in \mathbb{R}^{n \times p}$. $\beta \in \mathbb{R}^p$ is the parameter vector.

We can then write

$$P(Y \mid X, \beta) = \prod_{i=1}^{n} p(y_i \mid x_i, \beta)$$

.

Notice that $\arg\max\exp\left(-A\right)=\arg\min A$. We often write likelihoods as sums of logarithms that we minimize instead of products of exponents which we maximize.

The terms P(X) or p(Y) do not depend on the parameter β and have therefore no effect on optimisation.

Regularization: Ridge regression and Lasso

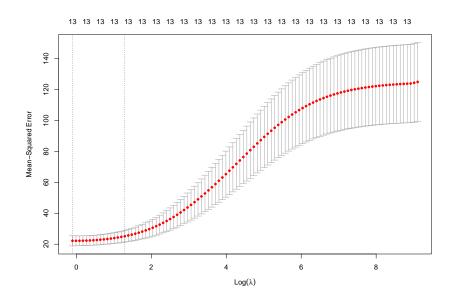
Define new loss by

$$L(\beta) = \sum_{i=1}^{n} \epsilon_i^2 + \lambda_{\textit{ridge}} \sum_{j=1}^{p} \beta_j^2 + \lambda_{\textit{lasso}} \sum_{j=1}^{p} |\beta_j|,$$

where $\epsilon_i = y_i - \beta^T x_i$ and solve $\hat{\beta} = \arg \min_{\beta} L(\beta)$.

- ▶ If $\lambda_{ridge} = \lambda_{lasso} = 0$ we have *OLS regression*
- ▶ If $\lambda_{ridge} > 0$ we have ridge regression
- ▶ If $\lambda_{lasso} > 0$ we have *lasso regression*
- Surprisingly, it seems to work
- ▶ Lasso leads to sparse solutions (= some coefficients in β are zero)
- Recall: ridge (lasso) is actually MAP estimate of some Bayesian model!
- ▶ Choose best λ_{ridge} or λ_{lasso} by cross-validation!

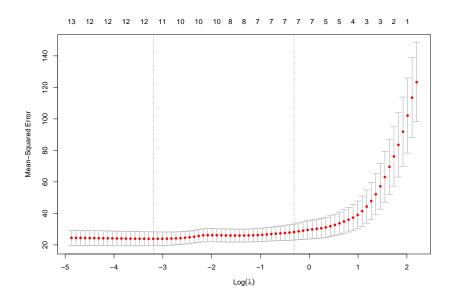
Regularization: Ridge (glmnet)



Regularization: Ridge (glmnet)

```
## 14 x 1 sparse Matrix of class "dgCMatrix"
##
## (Intercept) 7.451512136
            -0.461250890
## crim
               0.002860180
## zn
               -0.016421043
## indus
## chas
               5.357356114
              -15.957140792
## nox
                7.527665958
## rm
## age
               -0.033488479
               -1.039928854
## dis
## rad
               0.160113192
## tax
               -0.002841258
## ptratio
               -1.185632554
## black
               0.018171379
               -0.132305860
## 1stat
```

Regularization: Lasso (glmnet)



Regularization: Lasso (glmnet)

```
## 14 x 1 sparse Matrix of class "dgCMatrix"
##
## (Intercept) 2.28894650
## crim
             -0.67124849
## zn
                0.01341071
## indus
## chas
                4.34920970
              -25.58487796
## nox
## rm
                8.76517284
## age
               -0.03289982
## dis
               -1.24603284
## rad
               0.25758428
## tax
## ptratio
               -1.26244126
## black
               0.02290108
               -0.03657072
## 1stat
```

No regularization: OLS

```
##
## Call:
## lm(formula = medv ~ ., data = Boston50)
##
## Residuals:
##
     Min
             10 Median
                                  Max
## -6.0023 -1.9201 -0.0997 2.1878 8.9836
##
## Coefficients:
##
              Estimate Std. Error t value Pr(>|t|)
## (Intercept) 6.554729 19.778882 0.331 0.742264
             ## crim
## zn
             0.002362 0.041679 0.057 0.955116
## indus
             0.062568 0.173504 0.361 0.720495
## chas
            4.375175 4.748208 0.921 0.362956
## nov
         -30.024571 18.752893 -1.601 0.118103
## rm
            8.640479 1.434729 6.022 6.49e-07 ***
             -0.032085 0.037129 -0.864 0.393223
## age
## dis
             -1.332462 0.649861 -2.050 0.047663 *
## rad
             0.389590 0.257750 1.512 0.139389
             ## tax
## ptratio
             -1.309372 0.321526 -4.072 0.000244 ***
## black
             0.023658 0.009588 2.467 0.018500 *
## 1stat
             -0.065550 0.147265 -0.445 0.658903
## ---
## Signif. codes: 0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
##
## Residual standard error: 3.992 on 36 degrees of freedom
## Multiple R-squared: 0.9051, Adjusted R-squared: 0.8708
## F-statistic: 26.41 on 13 and 36 DF, p-value: 1.591e-14
```



Classifiers

Classification is the same as the regression, with the following differences:

► The response variable is categorical (class). In this course, we mainly discuss binary classification.

Statistical learning model (recap)

- ▶ Recall that X are the input variables (features, predictors, etc.), and Y denotes the output variable (dependent variable etc.).
- ▶ In classification, we assume Y to be a set of class labels, e.g., 0 or 1, or +1 or -1.
- Assume that there is a fixed but *unknown* probability distribution F over $X \times Y$ such that pairs are (x_i, y_i) are i.i.d. samples from it.
- ▶ We wish to minimise the *generalisation error* (also called *risk*) of \hat{f} , which is the expected loss $E_{(x,y)\sim F}\left[L(\hat{f}(x),y)]\right]$ where $E_{(x,y)\sim F}[\Box]$ denotes expectation of \Box when a single data point (x,y) is drawn i.i.d from F.

Some definitions/notation

- ▶ $P(X = x_i, Y = y_i)$ denotes the probability of pair (x_i, y_i) . (Sometimes we write $P(x_i, y_i)$ for short.)
- ▶ $P(Y = y_i \mid X = x_i)$ denotes the **conditional probability** of observing y_i given x_i . (We can also write $P(Y = y_i \mid x_i)$ or $P(y_i \mid x_i)$ for short.)
- ▶ If we knew P (which we in practice never do!), we could implement an "optimal" classifier by assigning x_i to the class y_i that maximises $P(y_i \mid x_i)$.
- In the following, we are particularly interested in *models* for $P(Y = y_i \mid x_i)$. These models are almost always "wrong", but perhaps they give good predictions anyway!

- Logistic regression models are linear models for probabilistic binary classification (so, not really regression where response is continuous)
- ▶ Given input (vector) x, the output is a probability that Y = 1. Let's denote it by $\hat{p}(Y = 1 \mid x)$.
- However, instead of using a linear model directly as in

$$\hat{p}(Y=1\mid x)=\beta^T x$$

we let

$$\log \frac{\hat{p}(Y=1 \mid x)}{\hat{p}(Y=0 \mid x)} = \beta^T x$$

▶ This amounts to the same as

$$\hat{p}(Y = 1 \mid x) = \frac{\exp(\beta^T x)}{1 + \exp(\beta^T x)} = \frac{1}{\exp(-\beta^T x) + 1}$$

- ▶ For convenience, we use here class labels 0 and 1
- ▶ Given probabilistic prediction $\hat{p}(y \mid x)$, and assuming instance x_i has already been observed, the **conditional likelihood** for a sample point (x_i, y_i) is

$$\hat{p}(Y = y_i \mid x_i) = \begin{cases} \hat{p}(Y = 1 \mid x_i) &, y_i = 1 \\ 1 - \hat{p}(Y = 1 \mid x_i) &, y_i = 0 \end{cases}$$

which we write as

$$\hat{p}(Y = y_i \mid x_i) = \hat{p}(Y = 1 \mid x_i)^{y_i} (1 - \hat{p}(Y = 1 \mid x_i))^{1 - y_i}$$

Conditional likelihood of sequence of independent samples (x_i, y_i) , i = 1, ..., n is then

$$\prod_{i=1}^{n} \hat{p}(Y=1 \mid x_i)^{y_i} (1 - \hat{p}(Y=1 \mid x_i))^{1-y_i}$$

- we say 'conditional' to emphasise that we take x_i as given and only model probability of labels y_i
- To maximise conditional likelihood, we can equivalently maximise conditional log-likelihood

$$LCL(\beta) = \sum_{i=1}^{n} (y_i \ln \hat{p}(Y = 1 \mid x_i) + (1 - y_i) \ln(1 - \hat{p}(Y = 1 \mid x_i)))$$

This is the same as log-loss (except that the sign is flipped, i.e., without the minus)!

- Maximizing the likelihood (or minimizing log-loss) isn't as straightforward as in the case of linear regression
- Nevertheless, the problem is convex which means that gradient-based techniques exist to find the optimum
- Standard techniques in R, Python, Matlab, . . .
- ▶ Often used with regularisation, as in linear regression
 - ► ridge: $arg min(-LCL(\beta) + \lambda \beta^T \beta)$
 - lasso: $arg min(-LCL(\beta) + \lambda |\beta|_1)$
- In particular, if data is linearly separable, non-regularised solution tends to infinity

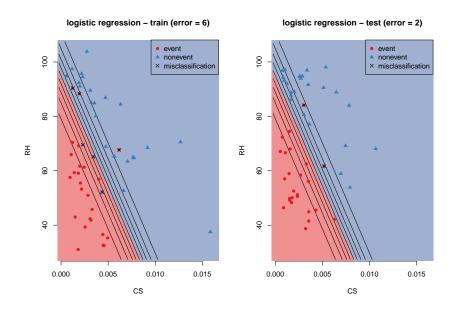
- ▶ Define $t = \text{logit}(p) = \log(p/(1-p))$
- Define

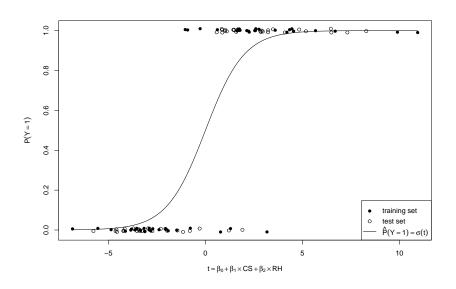
$$p = \operatorname{logit}^{-1}(t) = \operatorname{logistic}(\underline{t}) = \sigma(t) = 1/(1 + \exp(-t))$$

- ► $P(Y = 1 \mid X = x) = \sigma(\beta^T x),$ $P(Y = 0 \mid X = x) = 1 - \sigma(\beta^T x)$
- Log-likelihood of the training data $L = \prod_{i=1}^{n} P(Y = y_i \mid X = x_i)$
- ▶ ML solution: find β that minimizes

$$-\log L = -\sum_{i=1}^{n} \left(y_i \log \left(\sigma(\beta^T x_i) \right) + (1 - y_i) \log \left(1 - \sigma(\beta^T x_i) \right) \right).$$

```
npf.lr <- glm(class2 ~ .,npf$dtr,family=binomial)
summary(npf.lr)
##
## Call:
## glm(formula = class2 ~ ., family = binomial, data = npf$dtr)
##
## Deviance Residuals:
       Min 1Q Median
                                   3Q
                                           Max
## -2.53450 -0.29380 -0.01999 0.38804 1.63960
##
## Coefficients:
##
               Estimate Std. Error z value Pr(>|z|)
## (Intercept) -13.23554 3.49850 -3.783 0.000155 ***
## CS
           1130.15609 400.33798 2.823 0.004758 **
                ## RH
## ---
## Signif. codes: 0 '***' 0.001 '**' 0.05 '.' 0.1 ' ' 1
##
## (Dispersion parameter for binomial family taken to be 1)
##
      Null deviance: 69.315 on 49 degrees of freedom
## Residual deviance: 25.529 on 47 degrees of freedom
## ATC: 31.529
##
## Number of Fisher Scoring iterations: 6
```





Generative vs. discriminative learning

- Logistic regression was an example of a **discriminative** and **probabilistic** classifier that directly models the class distribution $P(y \mid x)$
- Another probabilistic way to approach the problem is to use **generative** learning that builds amodel for the whole joint distribution P(x, y) often using the decomposition $P(x, y) = P(y)P(x \mid y)$
- Both approaches have their pros and cons:
 - Discriminative learning: only solve the task that you need to solve; may provide better accuracy since focuses on the specific learning task; optimization tends to be harder
 - Generative learning: often more natural to build models for $P(x \mid y)$ than for $P(y \mid x)$; handles missing data more naturally; optimization often easier

Generative vs. discriminative learning

- Estimating the *class prior* P(y) is usually simple
- lacktriangleright For example, in binary classification this time with $Y \in \{0,1\}$
 - we can usually just count the number of positive examples $\it n_1$ and negative examples $\it n_0$ and set

$$P(Y = 1) = n_1/(n_1 + n_0),$$

and

$$P(Y=0) = n_0/(n_1 + n_0),$$

- Since P(x, y) = P(x | y)P(y), what remains is estimating P(x | y). In binary classification, we could now e.g.
 - use the positive examples to build a model for $P(x \mid Y = 1)$
 - use the negative examples to build a model for $P(x \mid Y = -1)$
- ightharpoonup To classify a new data point x, we use the Bayes formula

$$P(y \mid x) = \frac{P(x \mid y)P(y)}{P(x)} = \frac{P(x \mid y)P(y)}{\sum_{y'} P(x \mid y')P(y')}$$

Generative vs. discriminative learning covered

- Examples of discriminative classifiers:
 - logistic regression
 - ► k-NN
 - decision trees
- Examples of generative classifiers:
 - naive Bayes (NB)
 - linear discriminant analysis (LDA)
 - quadratic discriminant analysis (QDA)