

First project



Mastering Embedded System Online Diploma

High-Pressure-Detector



Name: Abdullah Mohamed Ibrahim hassan

My Profile: abdallahmohamed4197@gmail.com (learn-in-depth.com)

My GitHub: [AbdallahMohamedd](https://github.com/AbdallahMohamedd) (Abdallah mohamed) (github.com)

LinkedIn: [Abdallah Mohamed | LinkedIn](#)

Facebook: [Facebook](#)

Case study:

After meeting with the customer, we have outlined the core concept of the project, which includes the following key requirements:

- The system must be capable of measuring pressure within a crew cabin.
- An alarm should be triggered when the pressure exceeds 20 bar.
- The alarm should remain active for a duration of 60 seconds.
- Optionally, the system should have the capability to store measured pressure values in a flash memory, each accompanied by a timestamp.

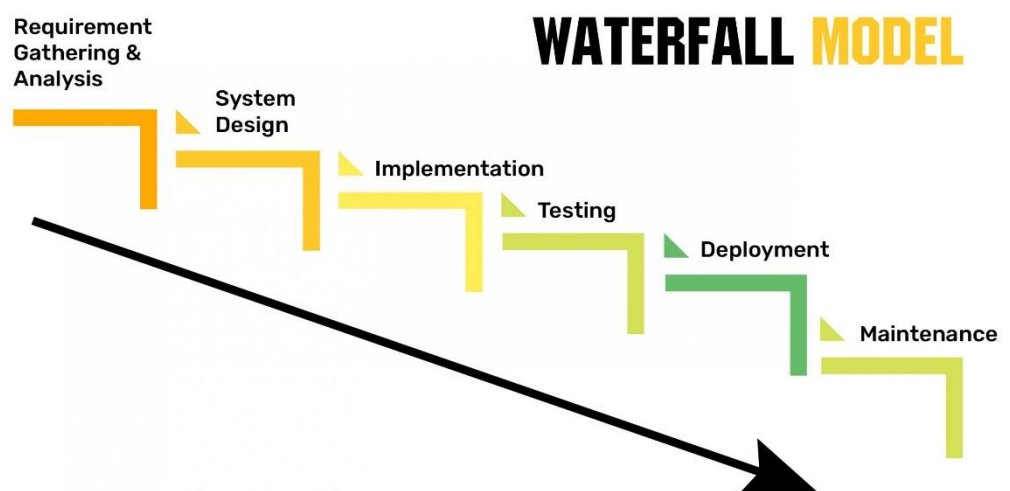
Several assumptions have been considered during project planning:

- The sensor is assumed to have no risk of failure.
- The alarm system is also assumed to have no risk of failure.
- The microcontroller unit (MCU) is expected to always have a power source.
- Maintenance and upkeep of the MCU are not within the scope of this project.

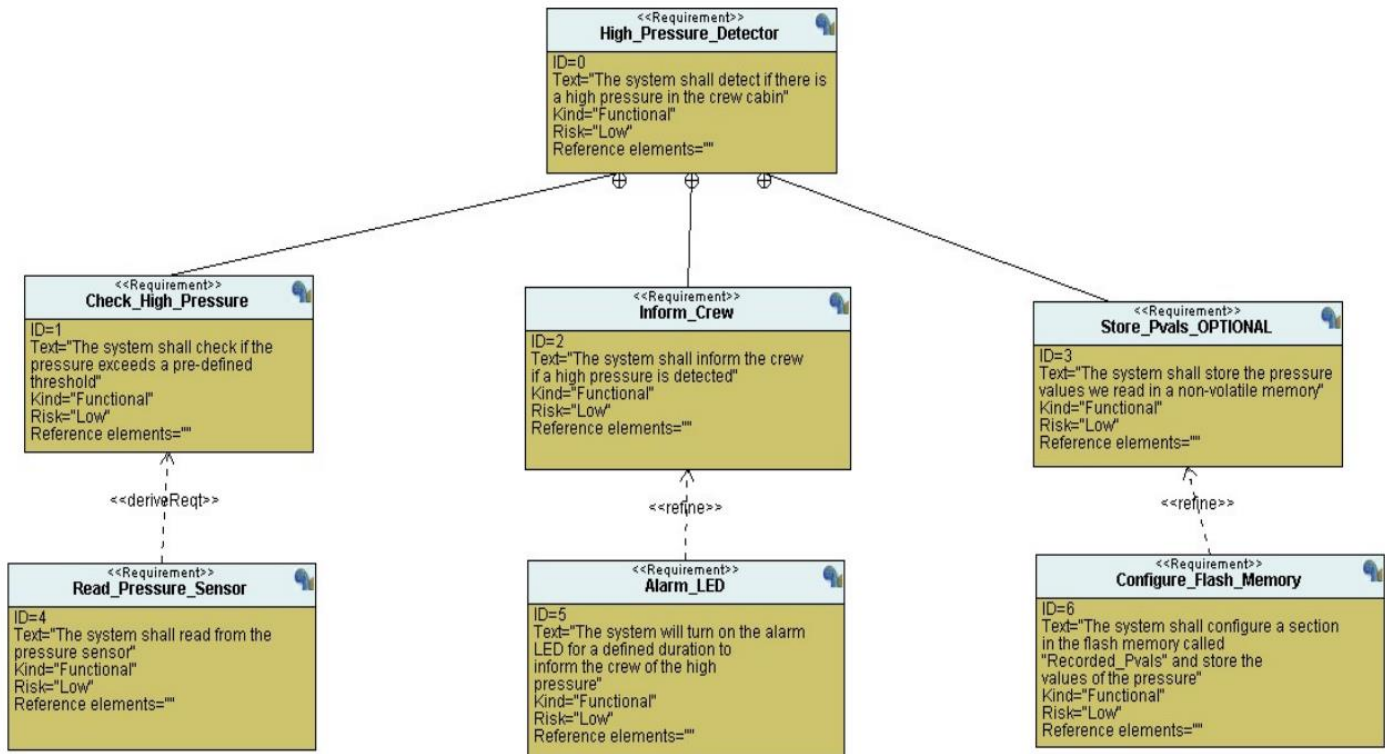
Regarding versioning, it's worth noting that the feature for saving captured pressure values will **NOT** be included in the initial software release.

Method:

The system was designed using the Waterfall model, following the UML standards.



Requirements:

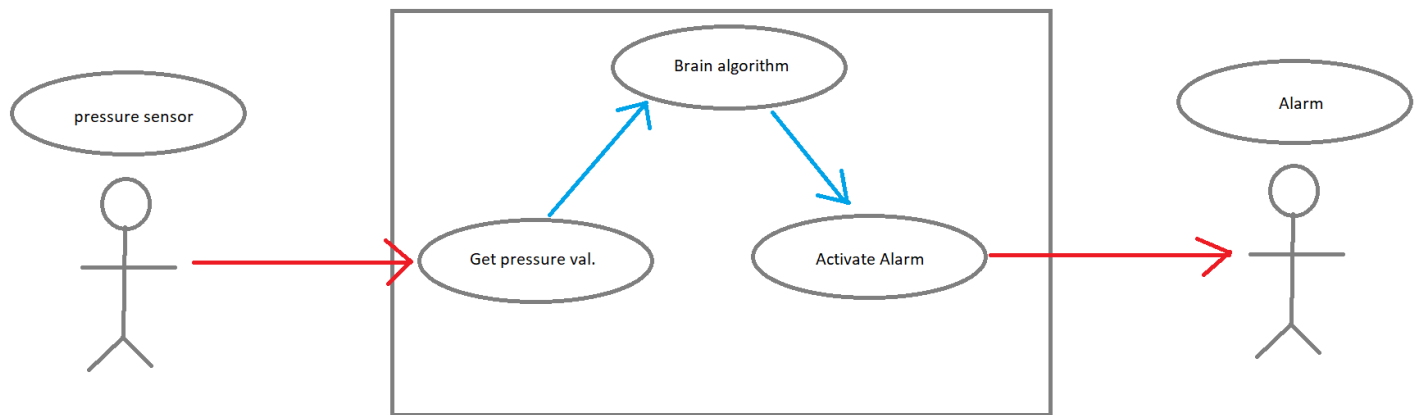


space exploration:

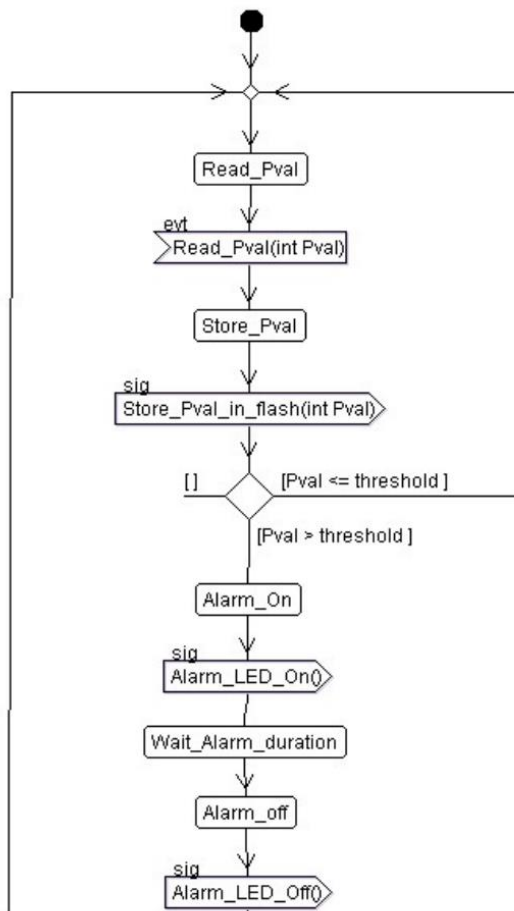
A single SOC Stm32 microcontroller with a **cortex-M3** processor will be used to implement this project.

System analysis:

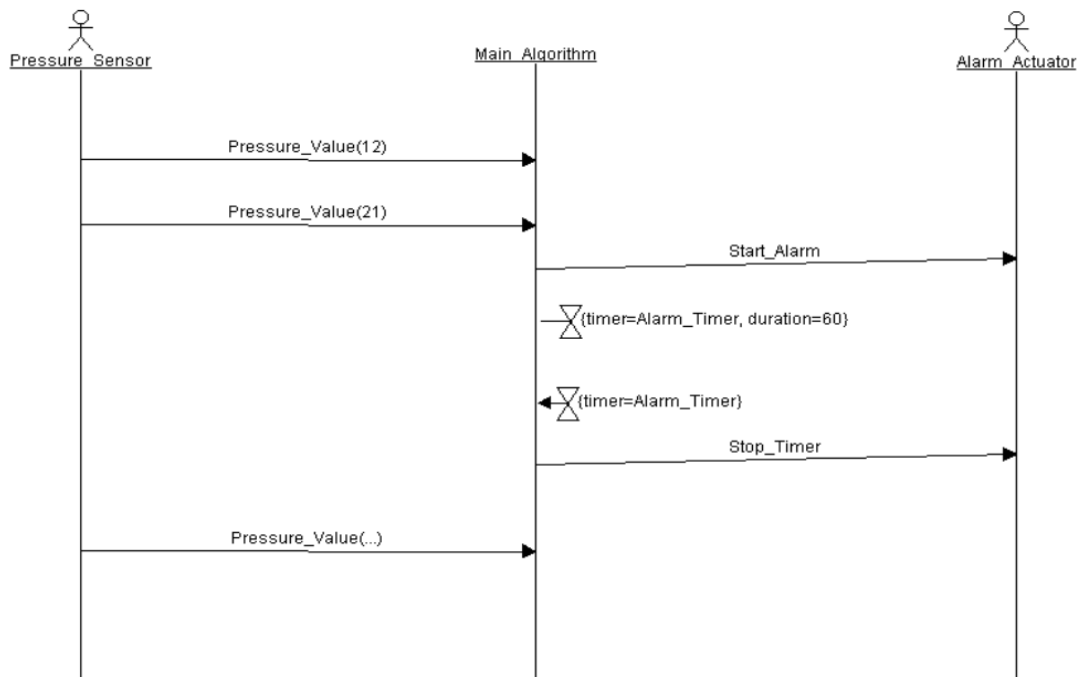
a. Use Case Diagram



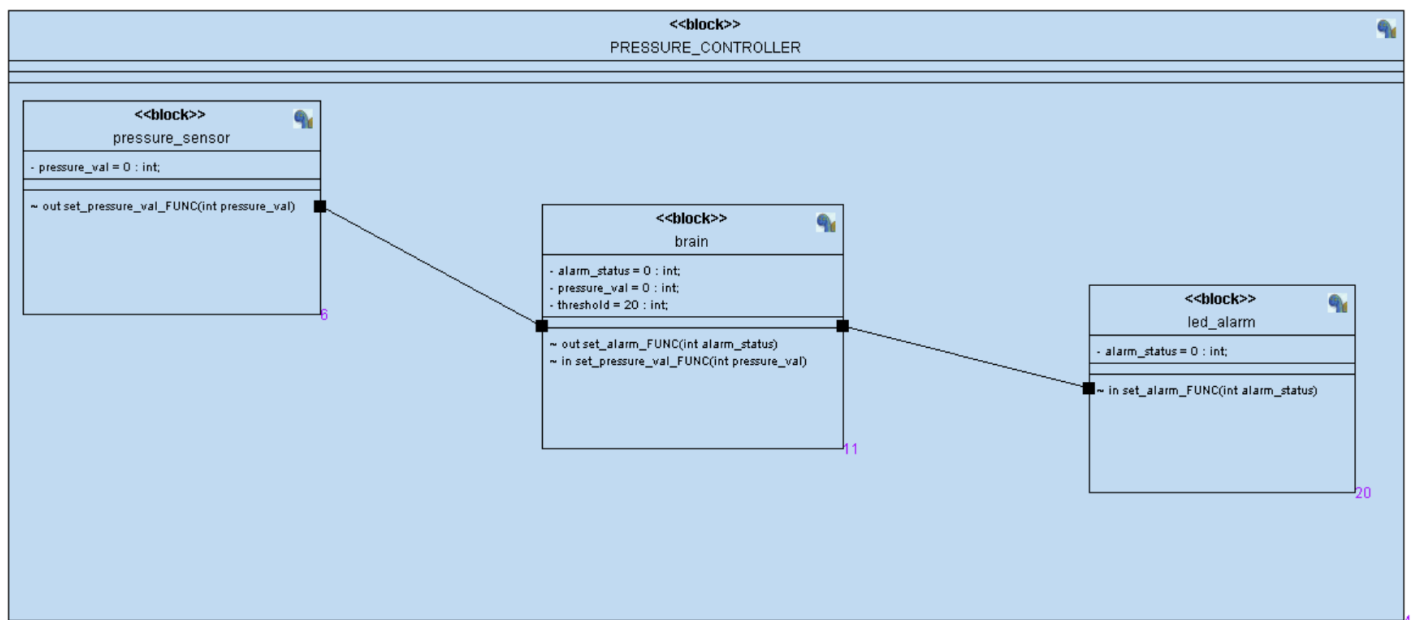
b. Activity diagram



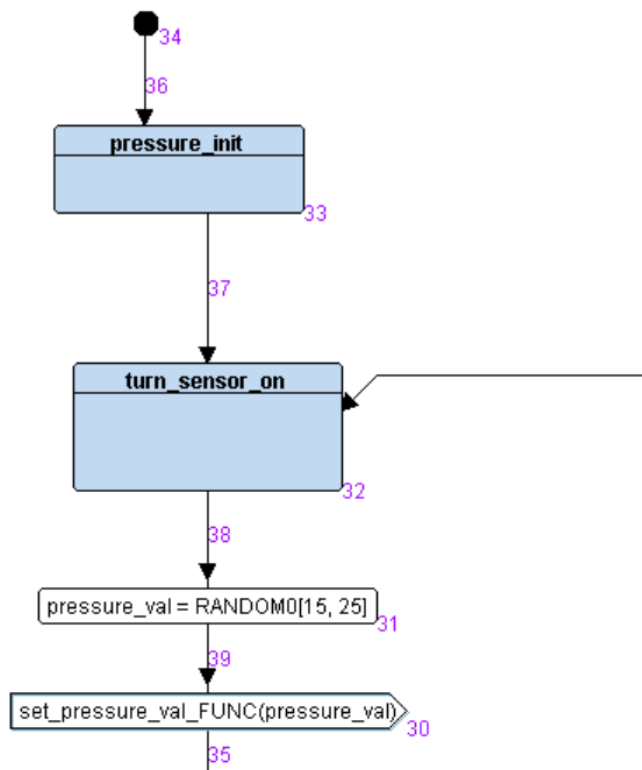
C. sequence diagram



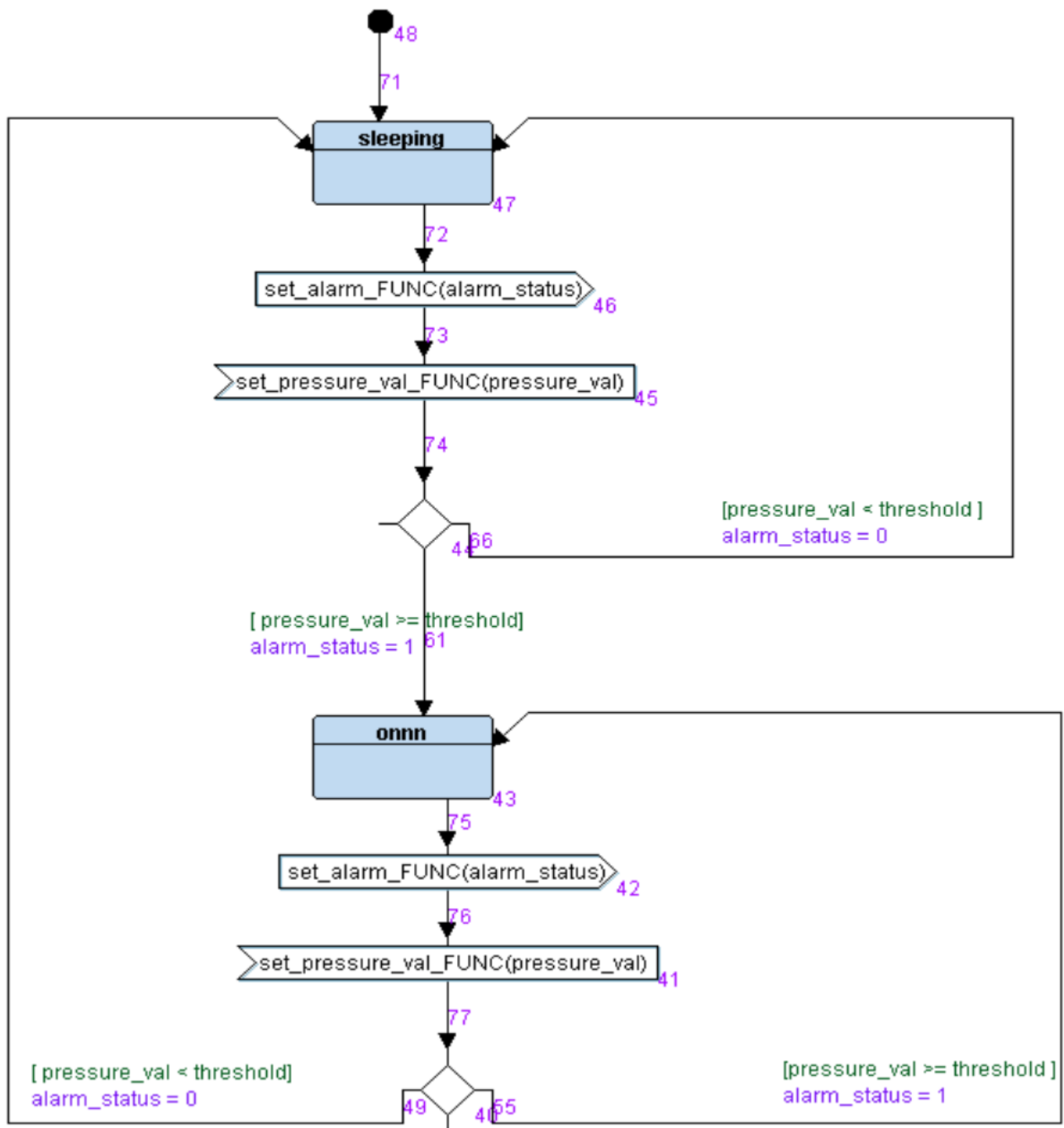
block diagram:



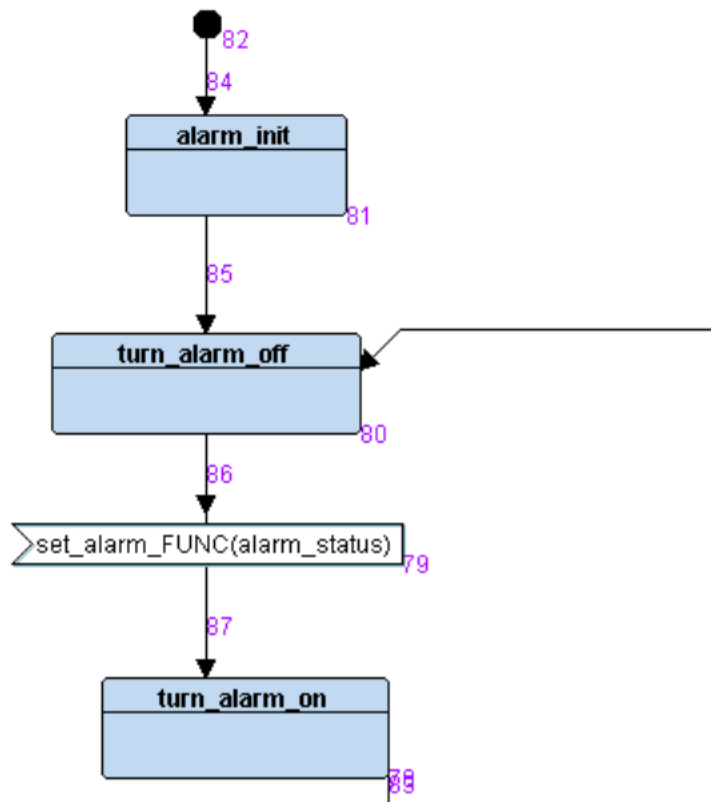
Pressure sensor driver



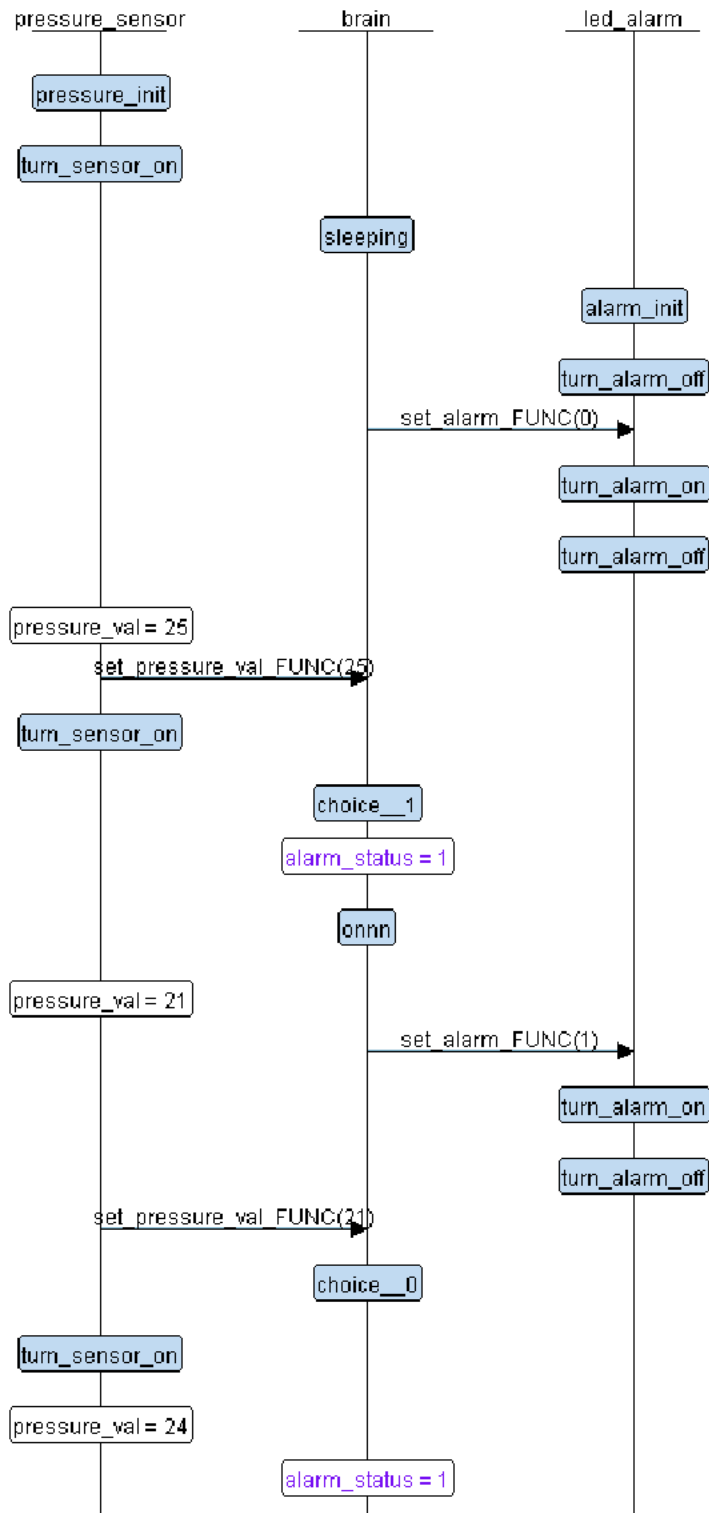
Brain

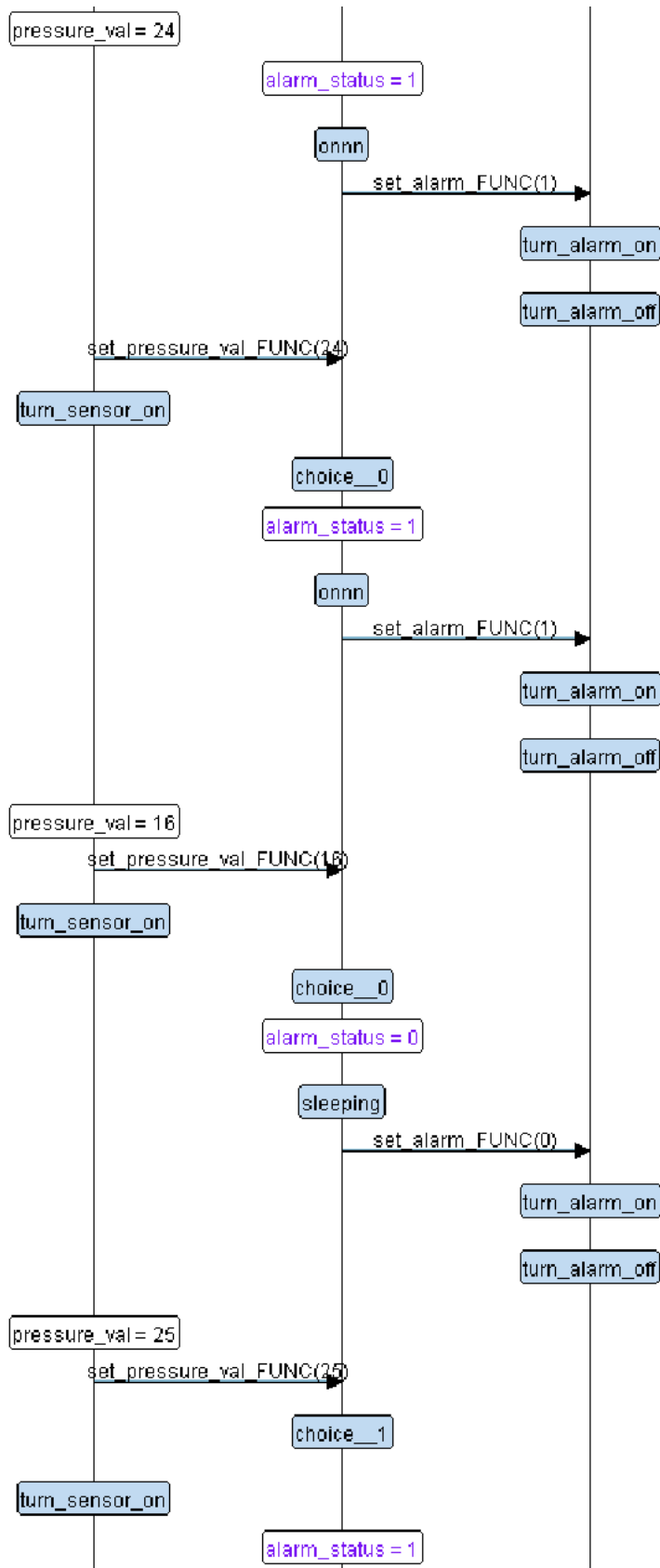


Led alarm.



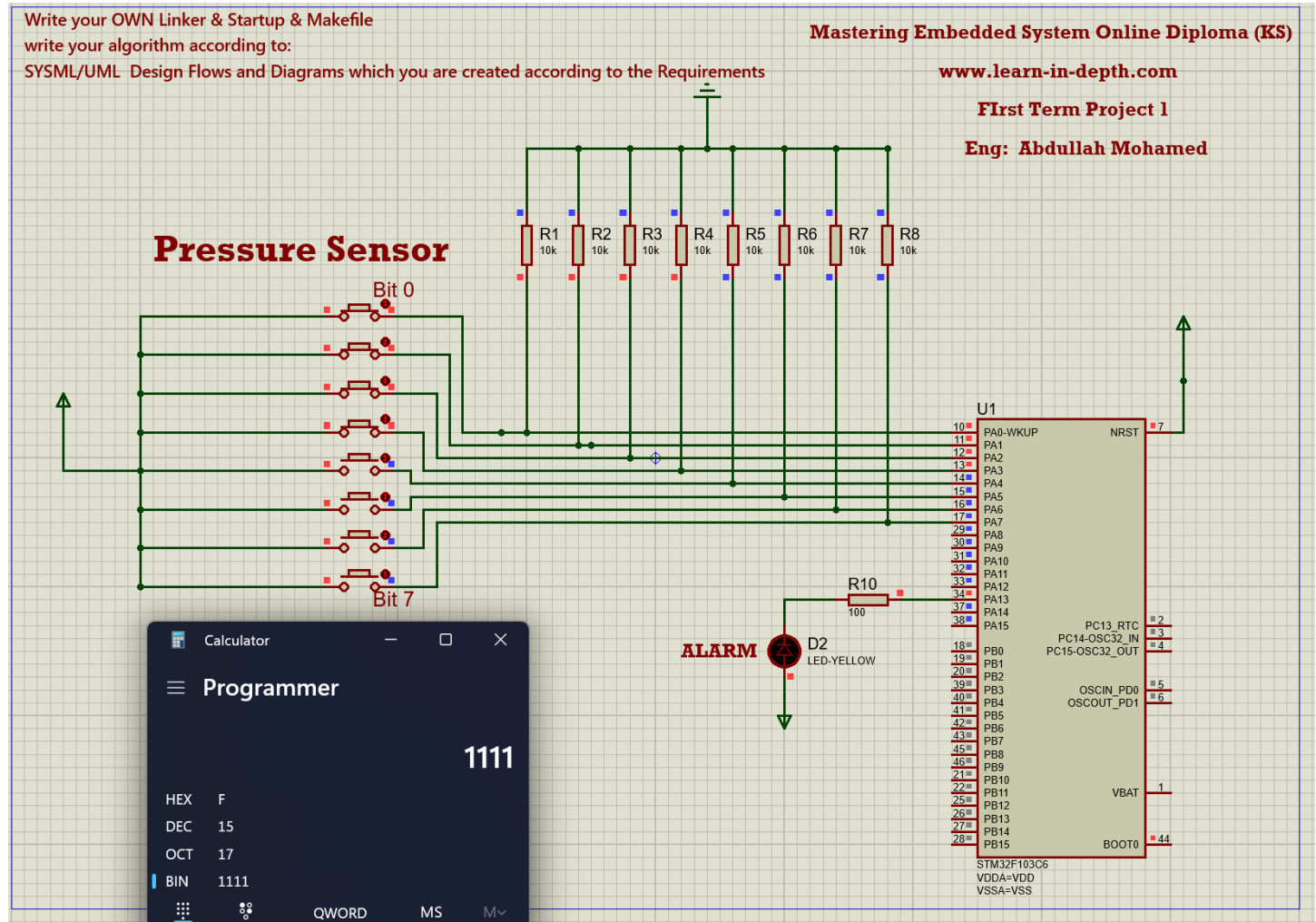
Logic verification





Case 2:

Reading 15 bar.... is smaller than “threshold (20 bar)”



Symbols:

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```
$ arm-none-eabi-nm.exe pressure_sensor.o
                 U getPressureVal
00000000 T pressure_init_FUNC
00000001 C preusser_current_state
00000004 C PS_p_to_func
00000000 B PS_pressure_val
                 U set_pressure_connection_FUNC
0000001c T turn_sensor_on_FUNC
```

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```
$ arm-none-eabi-nm.exe led_alarm.o
00000001 C alarm_current_state
00000040 T alarm_init_FUNC
00000004 C alarm_p_to_func
                 U Delay
00000000 B led_alarm
                 U Set_Alarm_actuator
00000000 T Set_Alarm_connection_FUNC
0000005c T turn_alarm_off_FUNC
00000078 T turn_alarm_on_FUNC
```

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```
$ arm-none-eabi-nm.exe brain.o
00000004 B brain_alarm_status
00000001 C brain_current_state
00000004 C brain_p_to_func
00000000 B brain_pressure_val
00000000 D brain_threshold
00000078 T onnn_FUNC
                 U Set_Alarm_connection_FUNC
00000000 T set_pressure_connection_FUNC
0000005c T sleeping_FUNC
```

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\$ arm-none-eabi-nm.exe driver.o

```
00000000 T Delay
00000024 T getPressureVal
0000008c T GPIO_INITIALIZATION
0000003c T Set_Alarm_actuator
```

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\$ arm-none-eabi-nm.exe main.o

```
00000001 C alarm_current_state
          U alarm_init_FUNC
          U alarm_p_to_func
00000001 C brain_current_state
          U brain_p_to_func
          U GPIO_INITIALIZATION
00000020 T main
          U pressure_init_FUNC
00000001 C preusser_current_state
          U PS_p_to_func
00000000 T setup
          U sleeping_FUNC
```

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\$ arm-none-eabi-nm.exe startup.o

```
          U _E_BSS
          U _E_DATA
          U _E_TEXT
          U _S_BSS
          U _S_DATA
00000000 W Bus_fault
00000000 T Default_Handler
00000000 W H_fault_Handler
          U main
00000000 W MM_fault_Handler
00000000 W NMI_Handler
0000000c T Rest_Handler
          U stack_top
00000000 W Usage_fault_Handler
00000000 D vectors
```