## Görüntü İşlemede Mimari Detaylar

Batuhan Düzgün

#### Roadmap

- 1- Image Processing Introduction
- 2- History of Photography
- 3- Applications of Digital Image Processing
- 4- Industrial Applications
- 5- Image Processing Methods
- 6- Tesseract OCR Engine & OpenCV
- 7- Example Project: "sahibinden.com" Staff Identity Card OCR Project
- 8- Resources and Questions

Image Processing Introduction

#### **Image Processing**

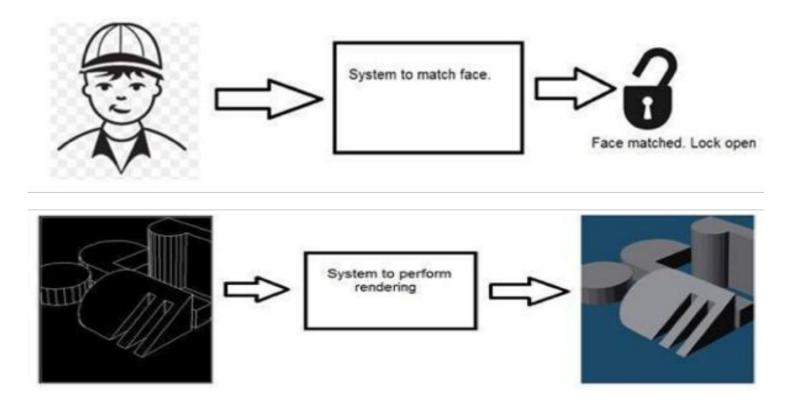
1- Analog Image Processing

2- Digital Image Processing

#### Overlapping Fields

- 1- Computer Vision
- 2- Computer Graphics
- 3- Signal Processing
- 4- Artificial Intelligence

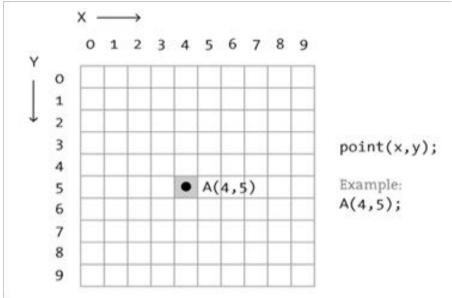
#### Overlapping Fields



#### What is an Image?

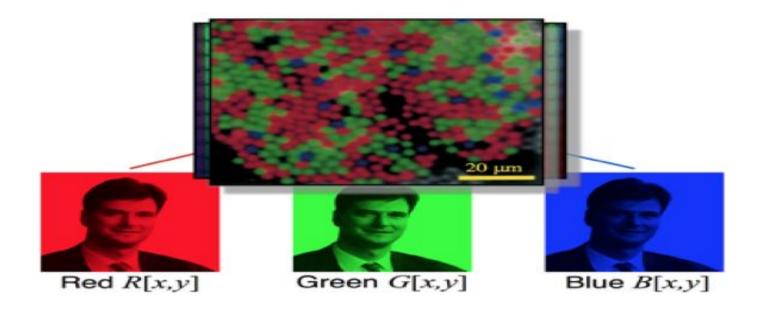
Mathematical function f(x,y) where x and y are the two coordinates horizontally and vertically.





#### Pixel?

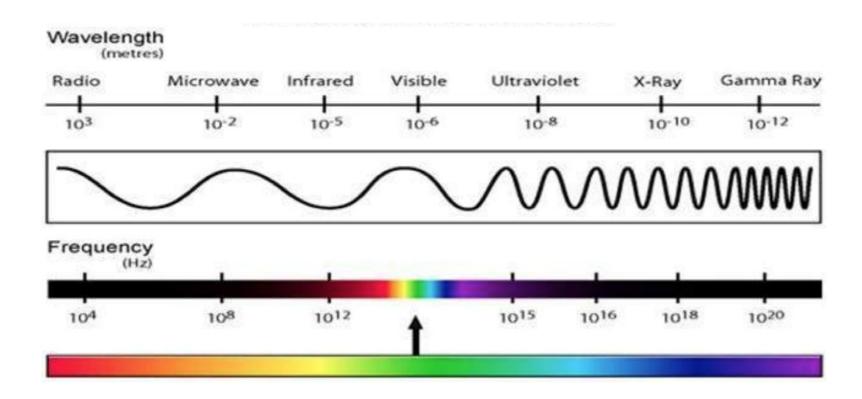
- Pixel is the smallest element of an image.
- In an 8-bit gray scale image, the value of the pixel between 0 and 255.



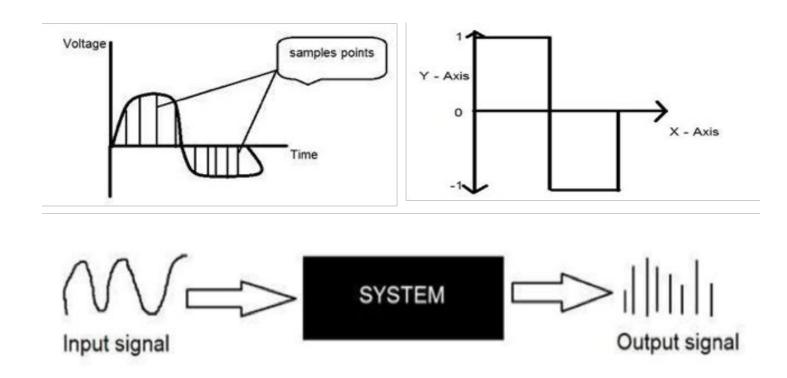
#### Pixel?

- Red Green Blue (RGB)
- Decimal Format: (0,255,0)
- Hex Format: #FFFFF

#### Electro Magnetic Spectrum



#### Signal Processing (Analog to Digital)



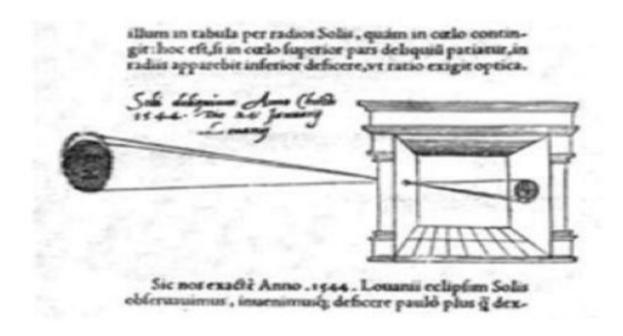
## History of Photography

#### Camera Obscura

- The principles of the camera were first introduced by a Chinese philosopher
   MOZI.
- Ibn al-Haitham built the first camera obscura.

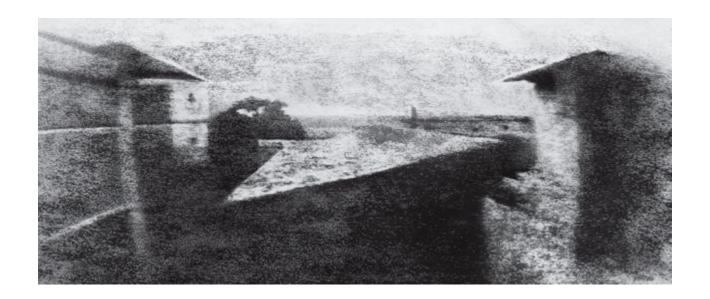
#### Da Vinci

Many principles of camera obscura has been defined in Codex Atlanticus.



#### First Photograph

 The first photograph was taken in 1814 by a French inventor Joseph Nicephore Niepce. (Le Gras, France)



#### Analog and Digital Cameras

Leica and Argus

Leica and argus are the two analog cameras developed in 1925 and in 1939 respectively.

Digital Cameras

Mavica was launched by Sony in 1981

## Applications of Digital Image

Processing

#### Application Fields

- Medical field
- Machine/Robot vision
- Color processing
- Pattern recognition
- Video processing

## Industrial Image Processing and OCR Applications

#### **Application Fields**



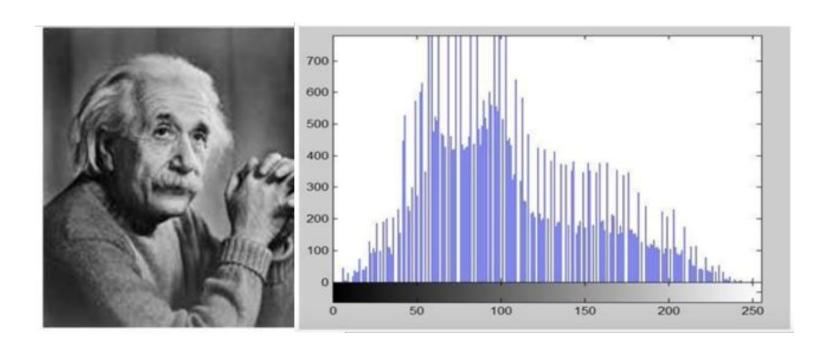




# Image Processing Methods

#### Histogram of an image

Histograms shows frequency. The frequency of pixels intensity values.



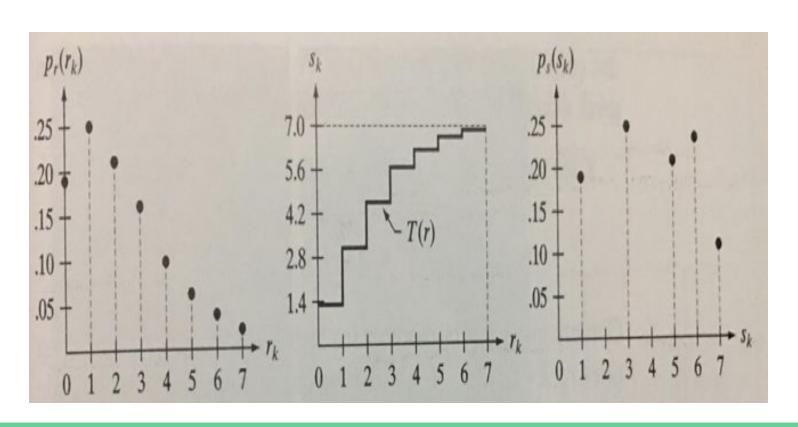
Histogram equalization is used to enhance contrast.

Steps:

- 1- Find histogram of an image
- 2- Calculate Cumulative Distributive Function
- 3- Map new values in the histogram
- Let's assume that we have 3-bit image. It will have (0-7) values.

M=64 and N=64 ==> MxN=4096

rk	$n_k$	$p_r(r_k) = n_k/MN$
$r_0 = 0$	790	0.19
$r_1 = 1$	1023	0.25
$r_2 = 2$	850	0.21
$r_3 = 3$	656	0.16
$r_4 = 4$	329	0.08
$r_5 = 5$	245	0.06
$r_6 = 6$	122	0.03
$r_7 = 7$	81	0.02



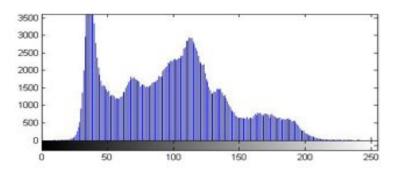
$s_0 = 1.33 \rightarrow 1$	$s_4 = 6.23 \rightarrow 6$
$s_1 = 3.08 \rightarrow 3$	$s_5 = 6.65 \rightarrow 7$
$s_2 = 4.55 \rightarrow 5$	$s_6 = 6.86 \rightarrow 7$
$s_3 = 5.67 \rightarrow 6$	$s_7 = 7.00 \rightarrow 7$

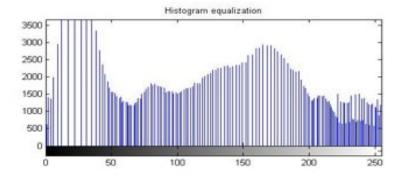
Original Image



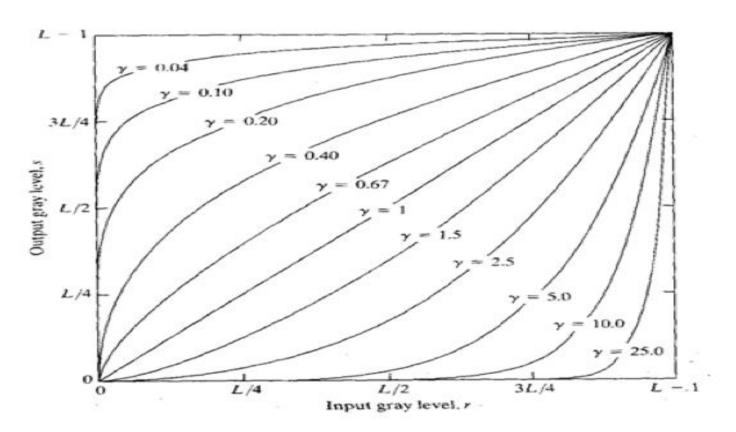
Enhanced Image



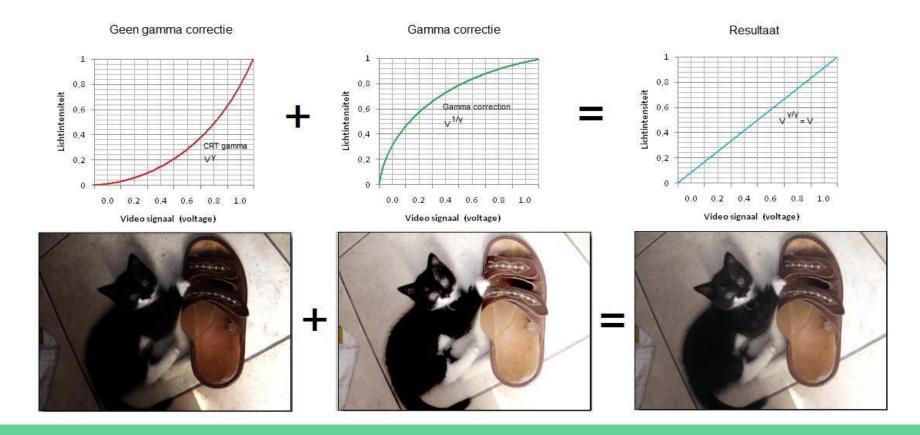




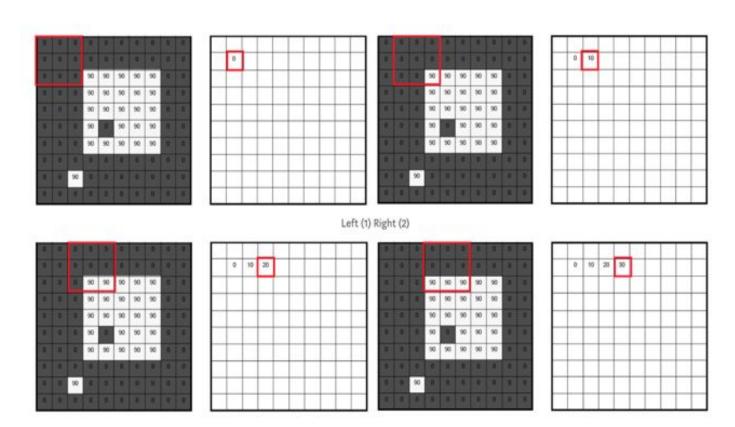
#### **Gamma Correction**



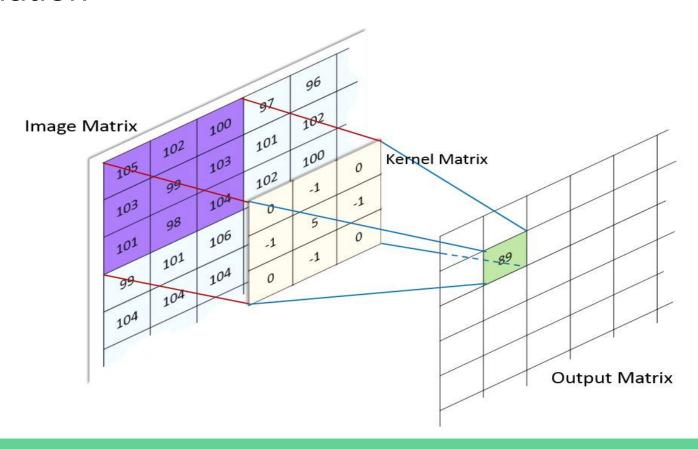
#### **Gamma Correction**



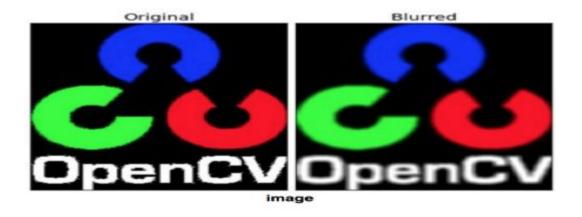
#### Convolution



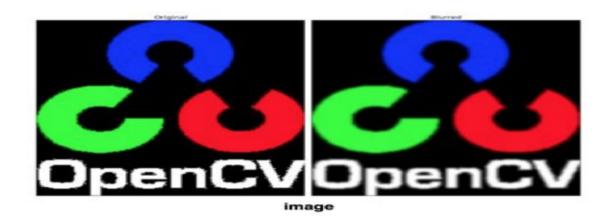
#### Convolution



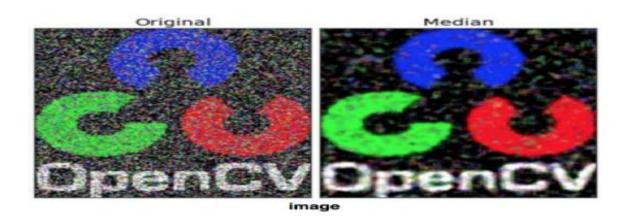
 Averaging: It simply takes the "average of all the pixels" under kernel area and replace the central element.



Gaussian Blurring: It blurs an image by a Gaussian function to "reduce image noise and reduce detail".



 Median Blurring: It takes "median of all the pixels" under kernel area and central element is replaced with this median value. This is highly effective against "salt-and-pepper noise" in the images.



Bilateral Filtering: It is highly effective in noise removal while "keeping edges sharp".



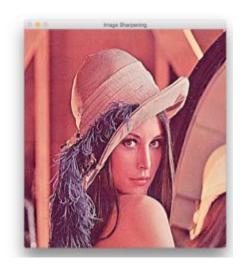
image

#### Sharpening Images

We use OpenCV's filter2D function.

Sharpening Kernel





 Morphological transformations are some simple operations based on the image shape.

- Structuring Element:
  - 1. Rectangular Kernel
  - 2. Elliptical Kernel
  - 3. Circular Kernel

```
[1, 1, 1, 1, 1] [0, 0, 1, 0, 0]

[1, 1, 1, 1, 1] [1, 1, 1, 1, 1]

[1, 1, 1, 1, 1] [1, 1, 1, 1, 1]

[1, 1, 1, 1, 1] [1, 1, 1, 1, 1]

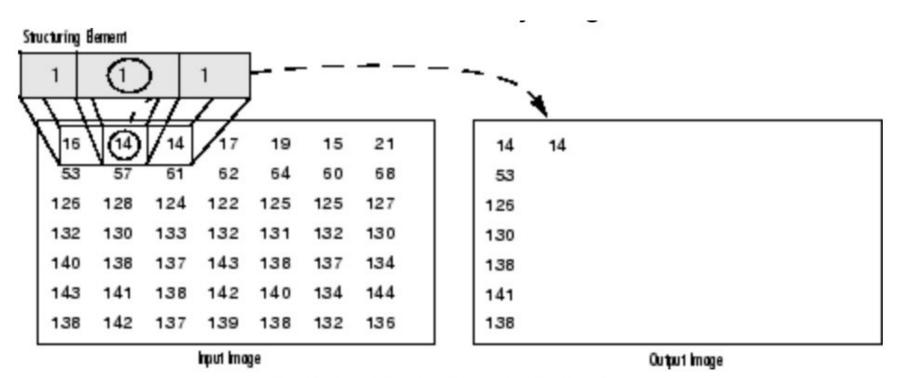
[1, 1, 1, 1, 1] [0, 0, 1, 0, 0]
```

```
[0, 0, 1, 0, 0]
[0, 0, 1, 0, 0]
[1, 1, 1, 1, 1]
[0, 0, 1, 0, 0]
[0, 0, 1, 0, 0]
```

• **Erosion**: It erodes away the boundaries of foreground object.



image

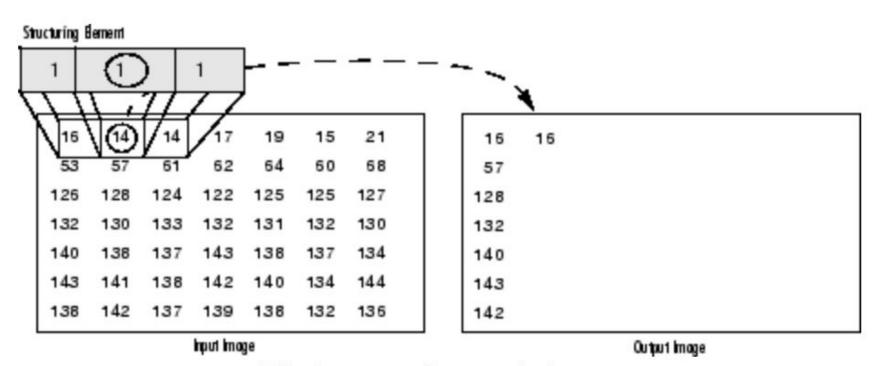


**Erosion on a Grayscale Image** 

**Dilation**: It increases the white region in the image or size of foreground object increases.



image



Dilation on a Grayscale Image

Opening: Erosion followed by Dilation



image

Closing: Dilation followed by Erosion



image

Original



Horizontal Opening



Vertical Opening



# Perspective Transformations

- Perspective transformation deals with the conversion of 3D world into 2D image.
- We need 4 points on the input image and corresponding points on the output image.

# Perspective Transformations





• From a grayscale image, thresholding can be used to **create binary images**.

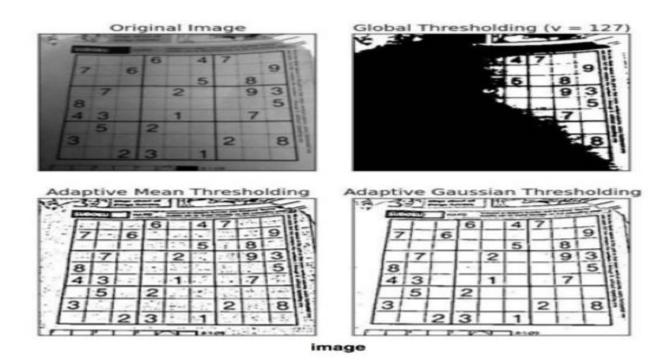
Simple Thresholding : give a "constant threshold" value

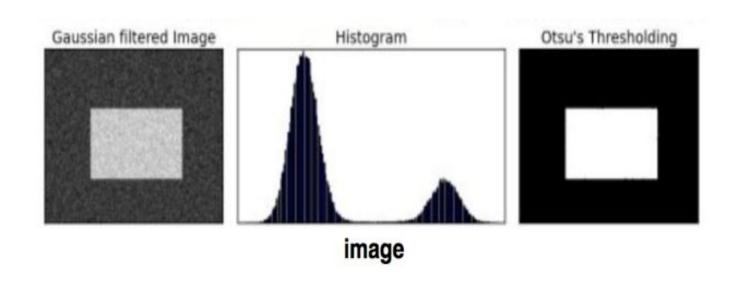
Adaptive Thresholding: calculate "threshold for a small regions" of the image

Otsu's Binarization : calculates "threshold value from image histogram" for a bimodal image









What are edges?

We can also say that **sudden changes of discontinuities** in an image are called as edges.

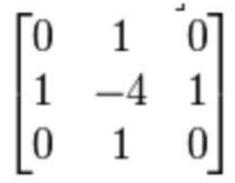
- Canny Edge Detection
- Sobel Edge Detection
- Laplacian Edge Detection

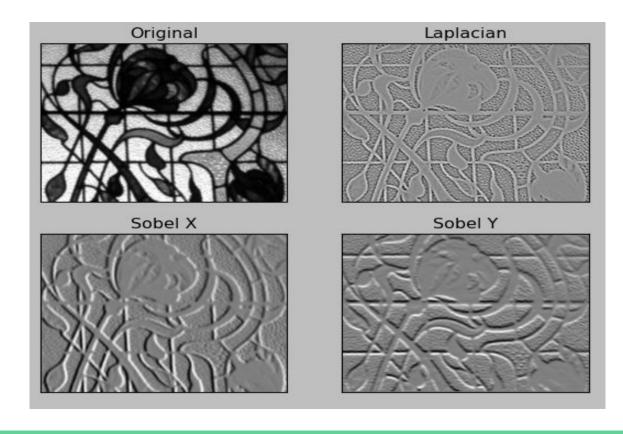
 Sobel Edge Detection: First derivatives of the image separately for the X and Y axes.

$$\mathbf{G}_x = egin{bmatrix} -1 & 0 & +1 \ -2 & 0 & +2 \ -1 & 0 & +1 \end{bmatrix} * \mathbf{A} \quad ext{and} \quad \mathbf{G}_y = egin{bmatrix} -1 & -2 & -1 \ 0 & 0 & 0 \ +1 & +2 & +1 \end{bmatrix} * \mathbf{A}$$

$$\mathbf{G}=\sqrt{{\mathbf{G}_x}^2+{\mathbf{G}_y}^2}$$

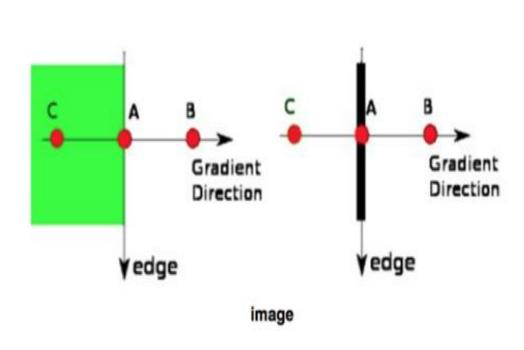
• Laplacian Edge Detection: Laplacian edge detector uses only one kernel.

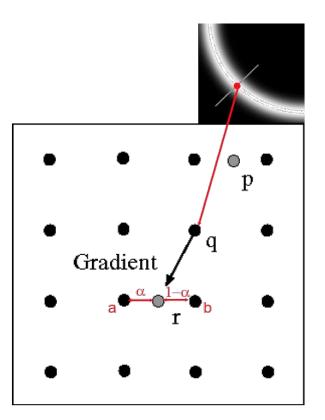




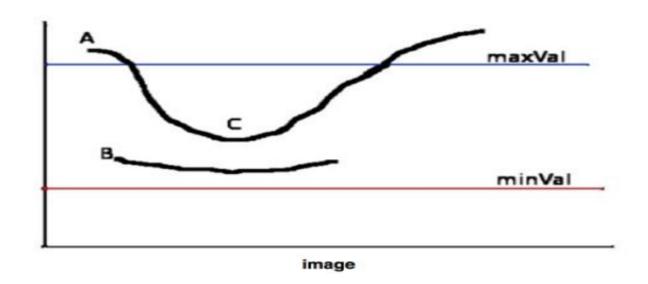
Canny Edge Detection

- 1. **Noise Reduction:** 5x5 Gaussian Filter for smoothing.
- 2. Finding Intensity Gradient of the Image: Using Sobel kernels.
- 3. **Non-maximum Suppression:** remove any unwanted pixels.





Hysteresis Thresholding: two threshold values, minVal and maxVal.



# Tesseract OCR Engine & OpenCV

# Optical Character Recognition (OCR)?

- It includes the mechanical and electrical conversion of scanned images of handwritten, typewritten text into machine text.
- Turning image files into fully searchable documents.

# Tesseract OCR Engine?

• Tesseract is an **open source** text recognizer (OCR) Engine, available under the Apache 2.0 license.

Install on Mac OS: brew install tesseract

Source Code : <a href="https://github.com/tesseract-ocr/">https://github.com/tesseract-ocr/</a>



# OpenCV?

 OpenCV is a library of programming functions mainly aimed at real-time computer vision.

**Supported Languages**: C++, Python and Java



Staff Identity Card OCR Project

Example Project: "sahibinden.com"

# Project Architecture







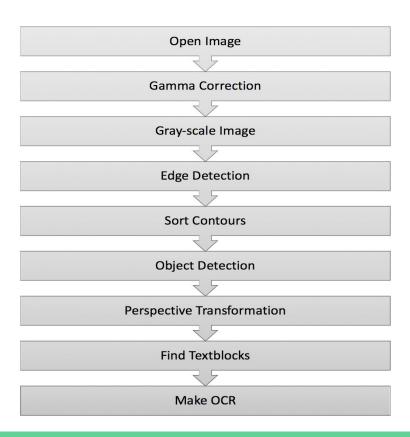






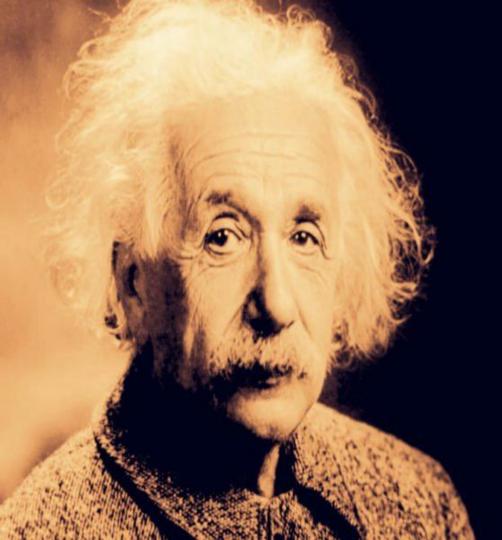


# Project Architecture





https://github.com/batux/staff\_identity\_card\_ocr\_project



"We now accept the fact that learning is a lifelong process of keeping abreast of change."

Albert Einstein

# References

#### OpenCV?

https://www.bogotobogo.com/python/OpenCV\_Python/python\_opencv3\_Image\_Gradient\_Sobel\_Laplacian\_Derivatives\_Edge\_Detection.php

https://docs.opencv.org/3.1.0/da/d22/tutorial\_py\_canny.html

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https://docs.opencv.org/3.1.0/da/d22/tutorial\_py\_canny.html

https://www.pyimagesearch.com/2017/07/17/credit-card-ocr-with-opency-and-python

# Thanks!



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