

# Disk graphs (provisional)

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# Chapter 1

## Graphs and disks

### 1.1 Graphs

A graph  $G$  is defined as  $G(V, E)$ , where  $V$  is the set of vertices and  $E$  the set of edges. A vertex  $v \in V$  is the fundamental unit of a graph. An edge  $e \in E$  is a structures that links two vertices. The vertices  $vw \in V$  that  $e \in E$  links are called the *endpoints*.

**Definition 1.1** *An embedding of a graph  $G$  is a representation of this graph on the plane.*

**Definition 1.2** *A graph  $G$  is planar iff there is an embedding of this graph that doesn't have any crossing between the edges.*

### 1.2 Intersection graphs

Given a geometric construction with multiple objects, an intersection graph is a graph that maps the objects into vertices and every intersection between objects is an edge between the corresponding vertices.

**Definition 1.3** *A graph  $G$  is a comparibility graph if there is a partial order... (check c-strip article, good definition).*

#### 1.2.1 Interval graphs

#### 1.2.2 Unit disk graphs



# Chapter 2

## Complexity

Problem solving is based on the complexity of a problem and not only a particular algorithm that solves it [?].

**Definition 2.1** Let  $\Sigma$  be a finite alphabet,  $\Sigma^*$  every word derived from  $\Sigma$ ,  $L \subseteq \Sigma^*$  is a decision problem.

**Definition 2.2** The algorithm  $A$  decides problem  $L \subseteq \Sigma^*$  if for all word  $w \in \Sigma^*$ :

- $A$  finishes and returns *TRUE* if  $w \in L$ .
- $A$  finishes and returns *FALSE* if  $w \notin L$ .

**Definition 2.3** A problem is decidable if there's an algorithm that decides it.

**Definition 2.4** A problem is decidable if there's an algorithm that decides it.

### 2.1 P vs NP

**Definition 2.5** A problem  $L \in \mathcal{P}$  if  $L$  can be decided in polynomial time  $\mathcal{O}(n^k)$ .

**Definition 2.6** A problem  $L \in \mathcal{NP}$  if  $L$  can be verified in polynomial time  $\mathcal{O}(n^k)$ . Thus,  $\mathcal{P} \subseteq \mathcal{NP}$ .

### 2.2 $\exists\mathbb{R}$ complexity class

$\exists\mathbb{R}$  is the class that describes the problems such that they can be reduced to *the existential theory of the reals*[?]. The existential theory of the reals

### 2.2.1 Problems in $\exists\mathbb{R}$

The art gallery problem is  $\exists\mathbb{R}$ -complete.[?]

Recognition of Unit Disk Graphs is  $\exists\mathbb{R}$ -complete. (corollary of graph realizability problem)[?]

Stretchability is  $\exists\mathbb{R}$ -complete.



# Chapter 3

## Geometry



# Chapter 4

## Disk Graph studies

### 4.1 Stabbing disks

Definition of stabbing.

Stabbing geometric structures.[?]

### 4.2 Thin Strip Graphs

$c$ -strip graphs are unit disk graphs such that the centers of the disks are delimited on the area  $\{(x, y) : -\infty < x < \infty, 0 < y \leq c\}$  and its class noted  $SG(c)$ . We can say that  $SG(0) = UIG$  and  $SG(\infty) = UDG$ . [?]

Thin strip graphs are defined as  $\bigcap_{c>0} SG(c)$