

Disk graphs (provisional)

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Contents

1	Graphs and disks	5
1.1	Graphs	5
1.2	Intersection graphs	5
1.2.1	Interval graphs	5
1.2.2	Unit disk graphs	6
2	Complexity	7
2.1	P vs NP	7
2.2	$\exists\mathbb{R}$ complexity class	7
2.2.1	Problems in $\exists\mathbb{R}$	8
3	Geometry	9
4	Disk Graph studies	11
4.1	Stabbing disks	11
4.2	Thin Strip Graphs	11

Chapter 1

Graphs and disks

1.1 Graphs

A graph G is defined as $G = (V, E)$, where V is the set of vertices and E the set of edges. A vertex $v \in V$ is the fundamental unit of a graph. An edge $e \in E$ is a structures that links two vertices. The vertices $vw \in V$ that $e \in E$ links are called the *endpoints*.

Definition 1.1 *An embedding of a graph G is a representation of this graph on the plane.*

Definition 1.2 *A graph G is planar iff there is an embedding of this graph that doesn't have any crossing between the edges.*

1.2 Intersection graphs

Given a geometric construction with multiple objects, an intersection graph is a graph that maps the objects into vertices and every intersection between objects is an edge between the corresponding vertices.

Definition 1.3 *A graph G is a comparability graph if there is a partial order... (check c-strip article, good definition).*

1.2.1 Interval graphs

Definition of interval Graphs

Properties

Definition of MIXED interval graphs

1.2.2 Unit disk graphs

Definition of UID.

Definition of a realization.

Chapter 2

Complexity

Problem solving is based on the complexity of a problem and not only a particular algorithm that solves it [6].

Definition 2.1 Let Σ be a finite alphabet, Σ^* every word derived from Σ , $L \subseteq \Sigma^*$ is a decision problem.

Definition 2.2 The algorithm A decides problem $L \subseteq \Sigma^*$ if for all word $w \in \Sigma^*$:

- A finishes and returns *TRUE* if $w \in L$.
- A finishes and returns *FALSE* if $w \notin L$.

Definition 2.3 A problem is decidable if there's an algorithm that decides it.

Definition 2.4 A problem is decidable if there's an algorithm that decides it.

2.1 P vs NP

Definition 2.5 A problem $L \in \mathcal{P}$ if L can be decided in polynomial time $\mathcal{O}(n^k)$.

Definition 2.6 A problem $L \in \mathcal{NP}$ if L can be verified in polynomial time $\mathcal{O}(n^k)$. Thus, $\mathcal{P} \subseteq \mathcal{NP}$.

2.2 $\exists\mathbb{R}$ complexity class

$\exists\mathbb{R}$ is the class that describes the problems such that they can be reduced to *the existential theory of the reals*[1]. The existential theory of the reals

2.2.1 Problems in $\exists\mathbb{R}$

The art gallery problem is $\exists\mathbb{R}$ -complete.[2]

Recognition of Unit Disk Graphs is $\exists\mathbb{R}$ -complete. (corollary of graph realizability problem)[4]

Stretchability is $\exists\mathbb{R}$ -complete.

Chapter 3

Geometry

Chapter 4

Disk Graph studies

4.1 Stabbing disks

Definition of stabbing.

Stabbing geometric structures.[5]

4.2 Thin Strip Graphs

c -strip graphs are unit disk graphs such that the centers of the disks are delimited on the area $\{(x, y) : -\infty < x < \infty, 0 < y \leq c\}$ and its class noted $SG(c)$. We can say that $SG(0) = UIG$ and $SG(\infty) = UDG$. [3]

Thin strip graphs are defined as $\bigcap_{c>0} SG(c)$.

$K_{1,3}$ in TSG, which is not possible for UIG.

$MUIG \subsetneq TSG$.

Denote that there's not constant t such that $SG(t) = TSG$.

Unfettered unit interval graphs = UUIF

Definition 4.1 *Find forbidden induced graphs for TSG.*

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