

## ICINCO 2025

22nd International Conference on Informatics in Control, Automation and Robotics

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To whom it may concern,

We are happy to inform that the paper submitted by Ahmed Hassan, Abdelaziz Essam Serour, Ahmed Gamea and Walid Gomaa to ICINCO 2025 with number 24, entitled "ALEX-GYM-1 : A Novel Dataset and Hybrid 3D Pose Vision Model for Automated Exercise Evaluation.", has been accepted as a Full Paper, to be presented in Marbella - Spain, October 20 to 22, 2025.

All papers accepted to ICINCO 2025 were peer reviewed by at least two experts from the international program committee, in a double-blind review process.

The paper will be published in the conference proceedings with up to 12 pages, and after being presented at ICINCO 2025 it will be included in the SCITEPRESS Digital Library under a specific DOI to be specified after the proceedings are published, and submitted for indexation to SCOPUS, Google Scholar, DBLP, Semantic Scholar, EI and Web of Science / Conference Proceedings Citation Index.

Best Regards,

A handwritten signature in blue ink, appearing to read "D. Filev".

Dimitar Filev  
(ICINCO Conference Chair)