# Course 1: Deep Learning



### Global formalism

## Input/output

- Goal: infer a function from an input (often tensor) space to an output (often tensor) space, y = f(x),
- **Example:** input can be an image, output a vector where the largest value indicate the category the image belongs to.

### Error/Loss

- $\blacksquare$  Loss: nonnegative measure of the discrepancy between expected output  $\hat{y}$  and obtained output y.
- **Example:** output should be [0, 1] but is [0.2, 0.8].

#### Parameters

- $f = f_{\theta}$  contains **parameters**  $\theta$  to be trained,
- lacksquare In most cases, an ideal  $f_{ heta}$  exists but is **hard to find in practice**,
- Learning is a regression ill-posed problem.

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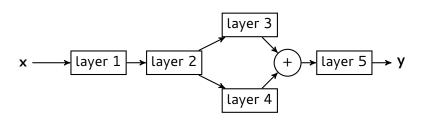
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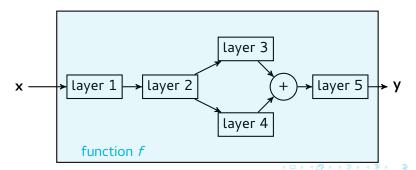
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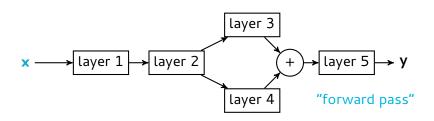
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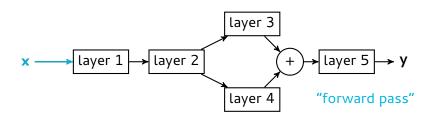
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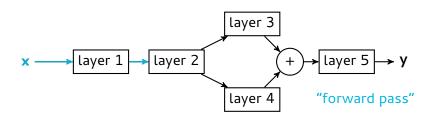
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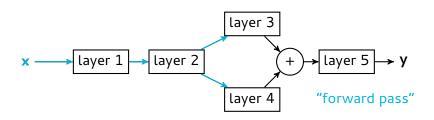
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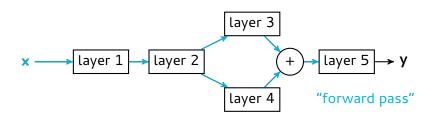
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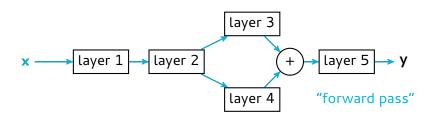
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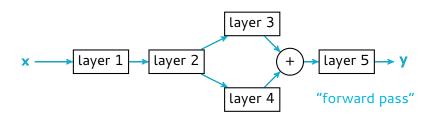
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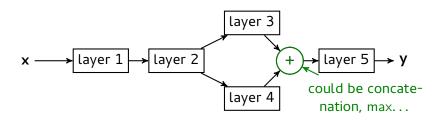
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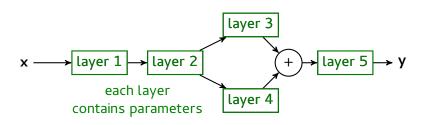
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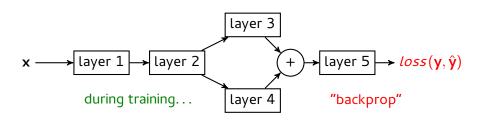
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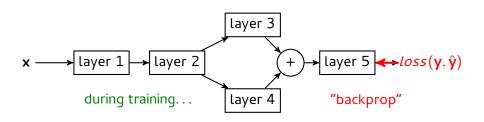
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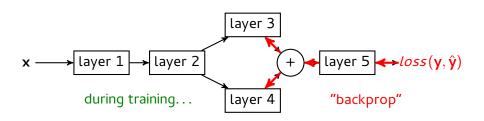
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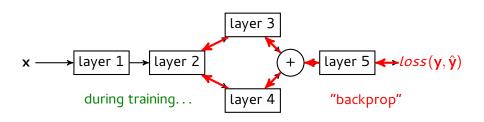
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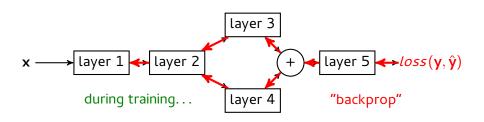
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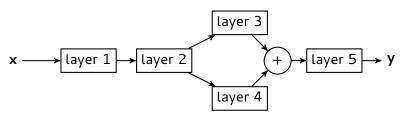


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#### Main idea

- Instead of directly mapping x to y, constructs a graph of intermediate representations, associated through very simple mathematical functions called layers,
- Training: Backpropagate the gradient of the loss throughout the architecture.



Number of layers, choice of the architecture are hyperparameters

## Layers

- $\mathbf{x} \mapsto h(\mathbf{W}\mathbf{x} + \mathbf{b}).$ 
  - h is a nonlinear parameterwise function (often without parameters),
  - W is a tensor:
    - Can be agnostic of the structure: fully-connected layers,
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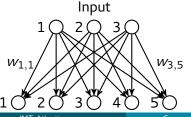
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### Fully connected layer

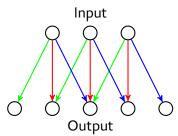


$$\begin{pmatrix} w_{1,1} & w_{1,2} & w_{1,3} & w_{1,4} & w_{1,5} \\ w_{2,1} & w_{2,2} & w_{2,3} & w_{2,4} & w_{2,5} \\ w_{3,1} & w_{3,2} & w_{3,3} & w_{3,4} & w_{3,5} \end{pmatrix}$$

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### Convolutional layer



$$\begin{pmatrix} \begin{pmatrix} w_{10} & w_{8} & w_{9} & 0 & 0 \\ w_{10} & w_{2} & w_{3} & 0 & 0 & 0 \\ 0 & w_{10} & w_{2} & w_{3} & 0 & 0 \\ 0 & 0 & w_{1} & w_{2} & w_{3} & 0 & 0 \\ 0 & 0 & w_{1} & w_{2} & w_{3} \end{pmatrix}$$

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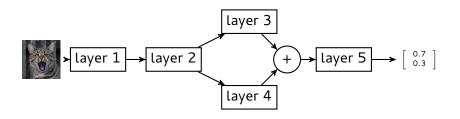
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### **Batches**

Inputs are often treated concurrently using small batches.

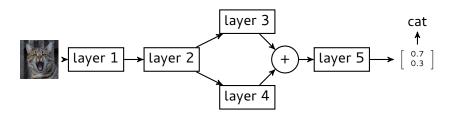
### Inputs/outputs

- Often: inputs are raw signals or feature vectors,
- Often: outputs are vectors which highest value indicate the category of the input.



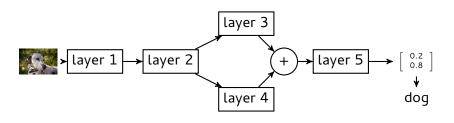
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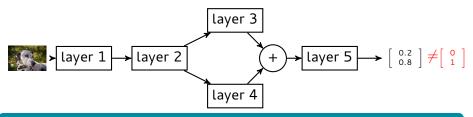
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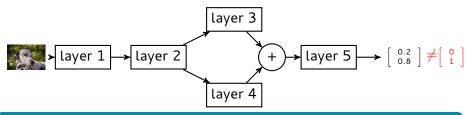


## Loss and targets

- Labels are encoded as one-hot-bit vectors and called targets,
- Outputs are **softmaxed**:  $\mathbf{y}_i \leftarrow \exp(\mathbf{y}_i) / \sum_j \exp(\mathbf{y}_j)$ ,
- Loss is typically **cross-entropy**:  $-\log(\hat{\mathbf{y}}^{\top}\mathbf{y})$

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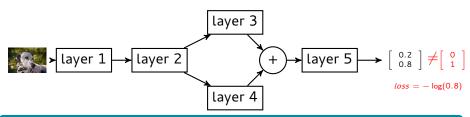


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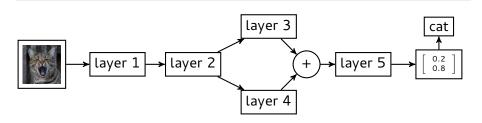


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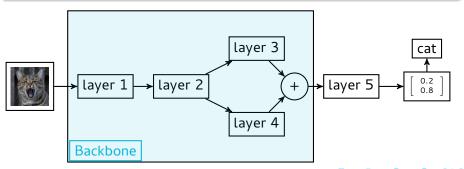
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- Fine-tuning: both the backbone and downstream networks are trained,
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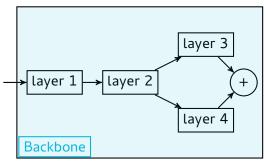
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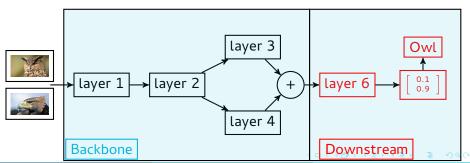
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### Architecture

- Number of layers
- Architecture choice (e.g. ResNet, DenseNet, VGG, ...)

### Training

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# Lab Session 1 and assignment

## Introduction to Deep Learning

- Introduction to Deep Learning in Pytorch
- Train a full DL model from scratch
- Train a small model using tranfer learning

## Project 1 (oral presentation)

Explore one of the following architectures : ResNet, DenseNet, PreActResNet, VGG.

You have to prepare a 10 minutes (+5 min Q&A) presentation for session 2, in which you explain :

- Description of the architecture
- Hyperparameter search and results
- Study the compromise between architecture size, performance and training time.