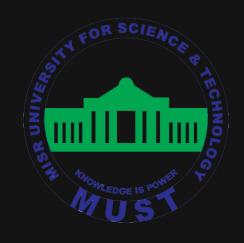
## MISR UNIVERSITY FOR SCIENCE AND TECHNOLOGY COLLEGE OF ENGINEERING MECHATRONICS DEPARTMENT



## MTE 405 SENSORS AND MEASUREMENTS

LAB 2 - SPRING 2020

Goals Of The Lab

Introduction to Sensors and Signal Conditioning with Virtual Prototyping





Introduction to temperature sensors



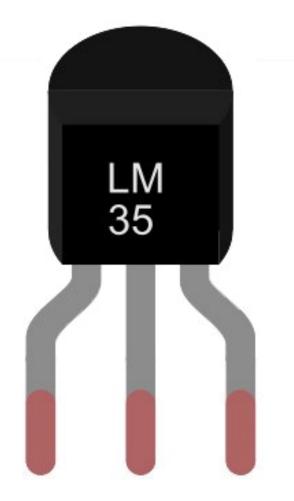
Spreading signal ouput range

## Lab 2 Sensing Temperature

Analog sensors

## Learning outcome

- LM35 characteristics.
- Simulation of LM35 on Proteus.
- Improving LM35 range.
- Practical implementation

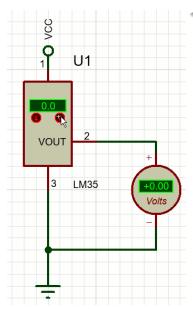


## Sensing Temperature

LM35



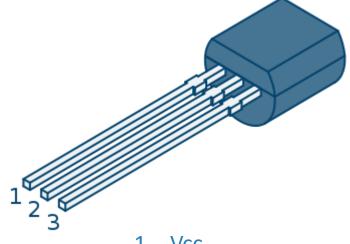
- Sensitivity: 10 mV / °C
- Useful range : 2 − 150 °C
- Less then 50 µA



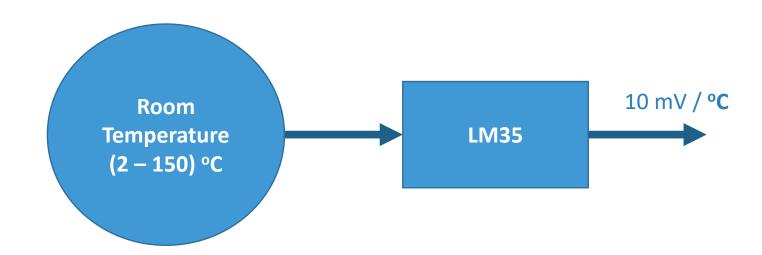
#### LM35 Precision Centig

#### 1 Features

- Calibrated Directly in Celsius (Centigrade)
- Linear + 10-mV/°C Scale Factor
- 0.5°C Ensured Accuracy (at 25°C)
- Rated for Full -55°C to 150°C Range
- Suitable for Remote Applications
- Low-Cost Due to Wafer-Level Trimming
- Operates From 4 V to 30 V
- Less Than 60-μA Current Drain
- Low Self-Heating, 0.08°C in Still Air
- Non-Linearity Only ±1/4°C Typical
- Low-Impedance Output, 0.1  $\Omega$  for 1-mA Load

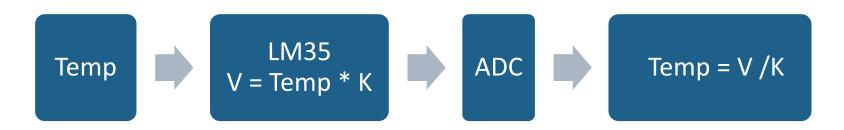


- Vcc
- Output
- 3. Gnd



## Sensing Temperature

LM35



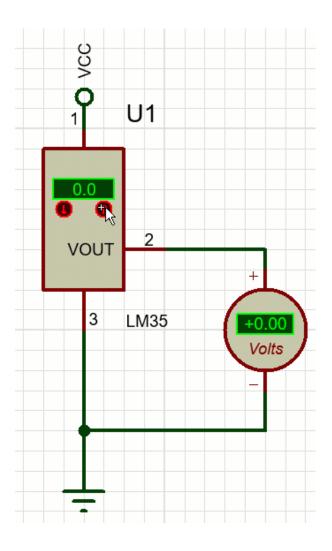
## Acquisition Transfer Function



K .... Conversion factor

And

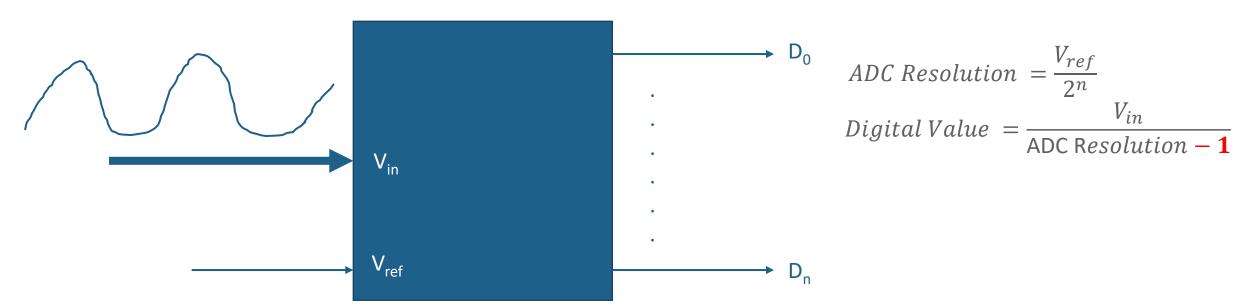
K = (10 mV / 1000 mV)



Case Study

#### **PROBLEM DEFINITION**

- You wish to build an embedded system for monitoring **temperature** using LM35.
- Your temperature range is expected to vary from 5 45 °C
- You have built-in 10-bit ADC with reference voltage of 5V (resolution?).
- You are **assigned** to **improve the voltage range of LM35** to match ADC input voltage range for the input temperature range

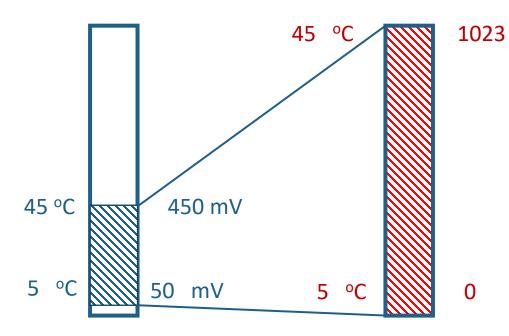


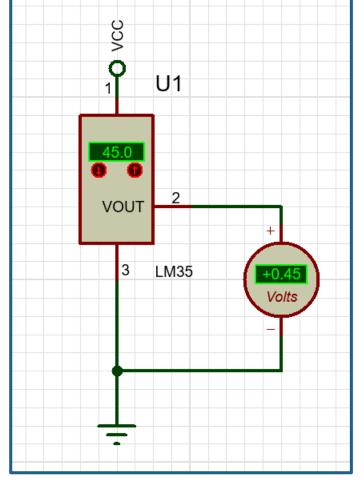
Lab 2

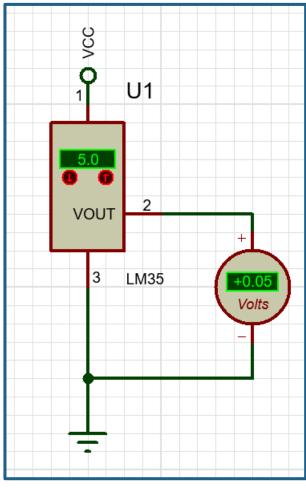
Case Study

#### FOR LM35

- At 5  ${}^{0}\text{C} \rightarrow V_{\text{Im}35} = 5 * 10 \text{mV} = 50 \text{ mV}$
- At 5  $^{\circ}$ C  $\rightarrow$  V<sub>Im35</sub> = 45 \* 10mV = 450 mV







What is the loss percentage in ADC range?

## Improving Sensor Range

Case Study

#### FOR LM35

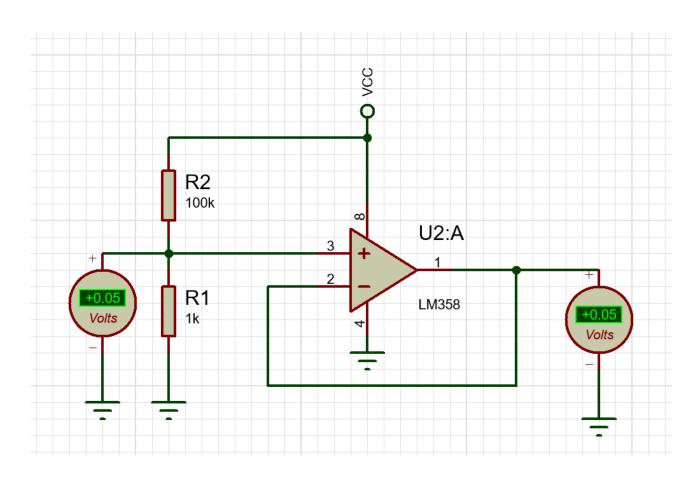
- At 5  ${}^{0}\text{C} \rightarrow V_{\text{Im}35} = 5 * 10 \text{mV} = 50 \text{ mV}$
- At 5  $^{0}C \rightarrow V_{lm35} = 45 * 10 mV = 450 mV$

## STEP 1 (Range Mapping)

- 50 mV  $\rightarrow$  0V (ADC Vin min)
- 450 mV  $\rightarrow$  5V (ADC Vin max) =  $V_{ref}$

## STEP 2 (Shifting)

 50 mV → 0V (Voltage Divider + Buffer "why?")



## Improving Sensor Range

Case Study

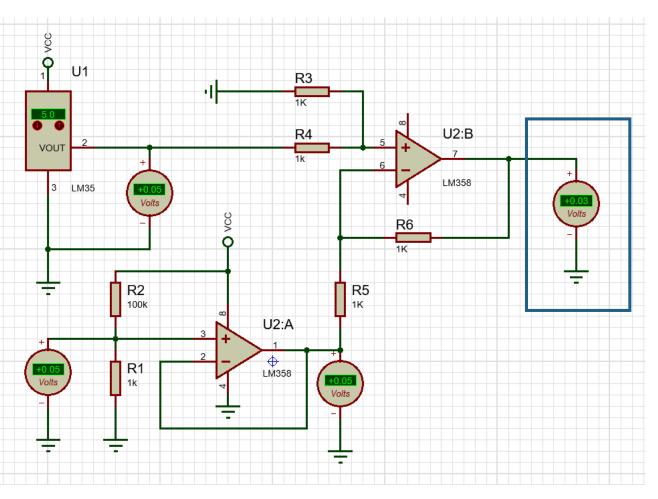
$$V(offset) = 5 * \frac{100k}{1k} = 50 mV$$

$$V(out) = V_{LM \to 50^{\circ}C} - V(offset) = 0V(Theoretical)$$

$$V(out) = 0.05 - 0.05 = 0V + Amplifier DC offset$$

## STEP 2 (Shifting)

 50 mV → 0V (Voltage Divider + Buffer "why?")



Read about amplifier DC offset

## Improving Sensor Range

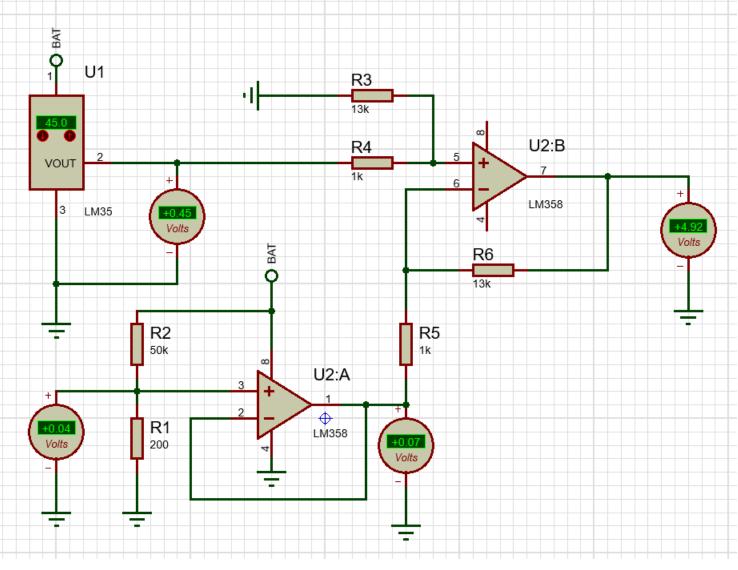
Case Study

## After min voltage removal

$$V(450) = 0.45 - 0.05 = 0.$$

### Gain

$$G = \frac{5}{0.4} = 12.5$$



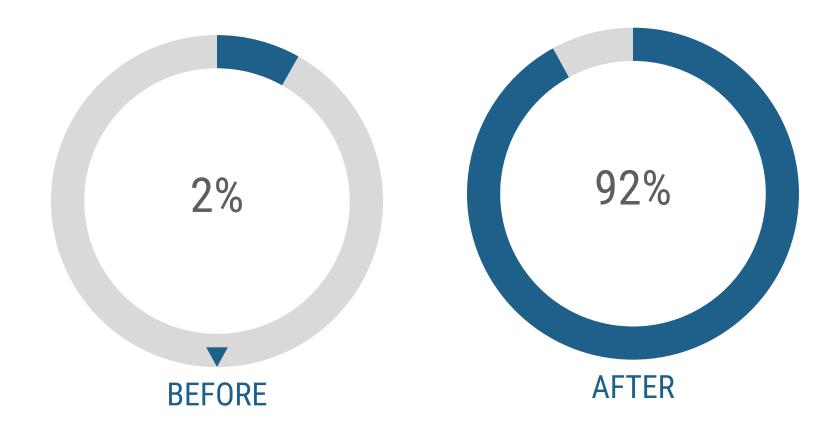
## **STEP 3 (Amplification)**

450 mV → 5V (Gain of differential amplifier)

$$V_{bat} = 12V$$
 (why changed?)

Improving Sensor Range

Case Study



## Improving Sensor Range

Case Study

#### PROBLEM DEFINITION

- You wish to build an embedded system for monitoring temperature using LM35.
- Your temperature **range** is expected to vary from **10 100** °C
- You have built-in 10-bit ADC with reference voltage of 5V.
- You are assigned to improve the voltage range of LM35 to match ADC input voltage range for the input temperature range

# APPLY THE DESIGN IN SIMULATION AND PRACTICAL CIRCUIT

## Improving Sensor Range

Case Study

#### **SOLUTION Steps**

1. Get sensor minimum and maximum voltages corresponding to given range

$$T_{min} = 10^o \rightarrow V_{min} = T * sensor sensitivity = 10^o * \frac{10mV}{C} = 0.1 V$$

$$T_{max} = 100^o \rightarrow V_{max} = T * sensor sensitivity = 100^o * \frac{10mV}{C} = 1.0 V$$

$$V_{min} = 0.1 V$$
  $V_{max} = 1.0 V$ 

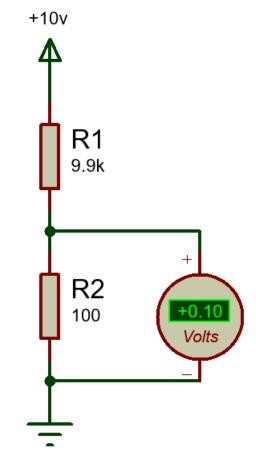
Case Study

### **SOLUTION Steps**

2. Remove min voltage offset  $V_{\min}$  by subtracting it from the same voltage created by a voltage divider

Desired voltage divider output =  $V_{min} = 0.1 V$ 

$$V_o = V_s \frac{R_2}{R_1 + R_2} \rightarrow R_1 = R_2 \left(\frac{V_s}{V_o} - 1\right)$$
 (Derive it if you like)



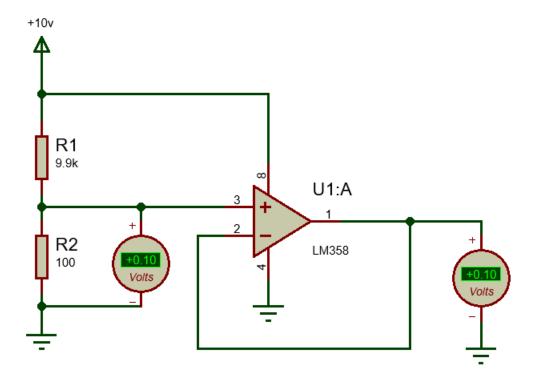
Assuming 
$$V_s = 10V$$
,  $R_2 = 100 \rightarrow R_1 = 100 \left( \frac{10}{0.1} - 1 \right) = 9.9k$ 

Lab 2

Case Study

## **SOLUTION Steps**

3. Apply buffering stage (as discussed in the lab)



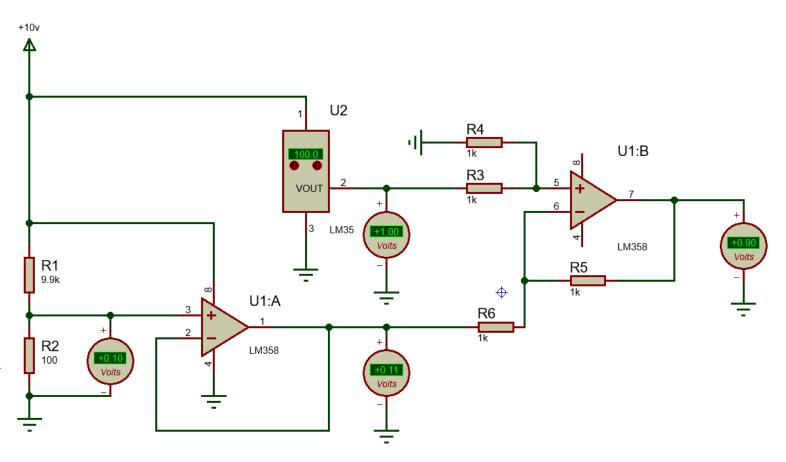
Case Study

## **SOLUTION Steps**

4. Subtract sensor min and max output voltage from buffer and check new  $V_{min}$  and  $V_{max}$  after subtraction. (use differential amplifier for subtraction with G = 1

$$V_{min-new} = 0.1 - 0.1 = 0V$$

$$V_{max-new} = 1.0 - 0.1 = 0.9V$$



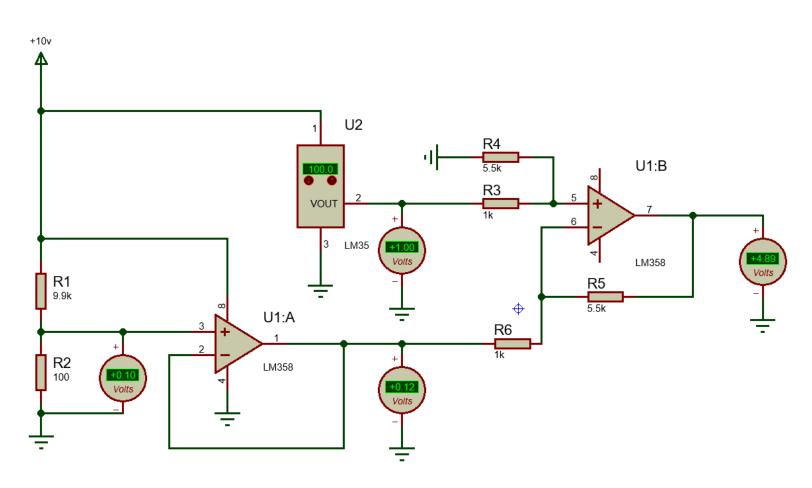
Case Study

## **SOLUTION Steps**

5. To maximize the sensor voltage to ADC  $V_{ref}$ , the amplifier gain is set to:

$$G = \frac{V_{\text{ref}(ADC)}}{V_{\text{max-new(sensor)}}}$$
$$= \frac{5.0}{0.9} = 5.56 \approx 5.5$$

If 
$$R_f$$
 is  $5.5k \rightarrow R_1 = 1k$ 



: @  $T = 10 \, {}^{\circ}C \rightarrow V = (0.1 \, {}^{\circ}0.1) \, {}^{*} \, 5.5 = 0V$  and @  $T = 100 \, {}^{\circ}C \rightarrow V = (1.0 \, {}^{\circ}0.1) \, {}^{*} \, 5.5 = 4.95V$ 

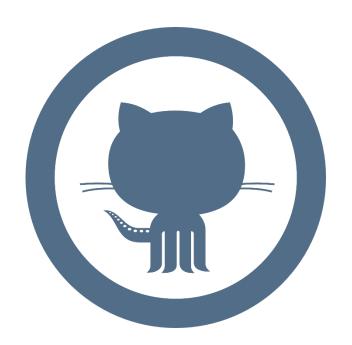
## SENSITIVITY IMPROVEMENT

Before and After

Sensor sensitivity = 
$$\frac{10mV}{^{\circ}C}$$
 (before signal conditioning)

Sensor sensitivity = 
$$\frac{10mV}{^{\circ}C}$$
 \* 5.5 =  $\frac{55.5mv}{^{\circ}C}$  (After)

Sensor sensitivity is improved 5.5 times the original sensitivity



Don't forget to pull the lab update from.

http://github.com/wbadry/mte405

# END OF LAB 2