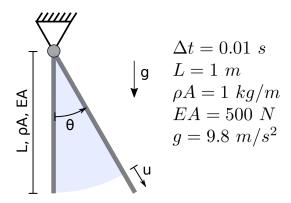
## Homework 2: Generalized-Alpha method



Equations of motion for an elastic pendulum with length L, mass density  $\rho$ , cross-sectional area A, elasticity modulus E and acceleration due to gravity g are given by:

$$\frac{\rho A L^3}{3} \ddot{\theta} + \frac{\rho A g L^2}{2} sin(\theta) = 0 \tag{1}$$

$$\frac{\rho AL}{3}\ddot{u} + \frac{EA}{L}u = 0\tag{2}$$

Assuming small amplitude vibrations, perform the following tasks for the given initial conditions.

$$u_0 = -\frac{L}{5}, \ \dot{u}_0 = 0, \ \theta_0 = 0, \ \dot{\theta}_0 = \sqrt{\frac{g}{6L}}$$

## Tasks:

- 1. Write the semi-discrete equation of motion in the matrix form, assuming Rayleigh damping ( $\mathbf{C} = \alpha_1 \mathbf{M} + \alpha_2 \mathbf{K}$ ).
- 2. Implement the generalized-alpha scheme in Matlab, where  $\alpha_f, \alpha_m, \beta$  and  $\gamma$  are computed using  $\rho_{\infty}$ .
- 3. Solve the system for 5 s and plot the dynamic response of the system for the following set of parameters:

(a) 
$$\alpha_1 = 1$$
,  $\alpha_2 = 0$  and  $\rho_{\infty} = 1.0$ 

(b) 
$$\alpha_1 = 0, \, \alpha_2 = 0 \text{ and } \rho_{\infty} = 0.1$$

Explain briefly the differences and the sources of the differences obtained in the dynamic response for the two cases.

- 4. Using the error indicator (e) by Zienkiewicz and Xie, extend your implementation to compute and store the error norm (||e||), cumulative error norm, and the relative error ( $\eta$ ) for each time step.
- 5. Extend your implementation of the generalized-alpha scheme to update the time step ( $\Delta t$ ) at the end of each step depending on the relative error ( $\eta$ ). Lower and upper bounds of the relative error are defined as  $\nu_1 \eta_e$  and  $\nu_2 \eta_e$ , where  $\nu_1 = 1.0, \nu_2 = 10.0$  and  $\eta_e = 1.0 \times 10^{-3}$ . The new time step has to be computed as  $\Delta t_{new} = \Delta t_{old} \cdot \sqrt{\eta_e/\eta}$ .
- 6. Solve the system for 5 s using the adaptive time stepping algorithm with  $\alpha_1 = 1$ ,  $\alpha_2 = 0$ , and  $\rho_{\infty} = 1.0$ . Plot and compare the dynamic response as well as the evolution of the time step, relative error, and cumulative error norm with the one obtained in task-3a. For both cases, what is the cumulative error norm after 5 s and how many time steps did the algorithm?

Note: The solution has to be submitted in hardcopy by Monday, 17th June, in IC-6/173. Additionally, the Matlab files must be uploaded in moodle.