
```
function [lambda,phi,n] = inverse_iter(K,M,x,TOL)

% K: stiffness matrix
% M: mass matrix
% x: initial guess
% TOL: convergence tolerance

y = M*x;

% any number above the tolerance in order not to converge
% from the first step.
err = TOL*2 ;
rho_new = 0;
rho_old = 0;
n = 0; % counter to count number of loops before convergence.

while err >= TOL
    n = n+1;
    xbar = K\y;
    ybar = M*xbar;
    rho_old = rho_new;
    rho_new = (xbar'*y)/(xbar'*ybar);
    err = abs(rho_new - rho_old) / rho_new;
    y = ybar/sqrt(xbar' * ybar);
end

lambda = rho_new;
phi = M\y;
phi = phi/norm(phi);

end
```