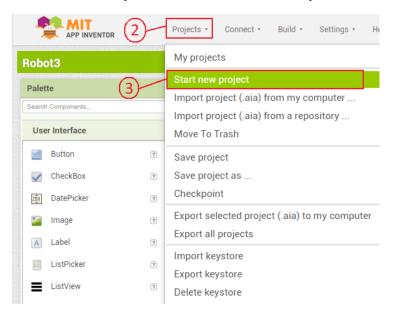
This paper shows the steps needed to import application program from existing (.aia) file.

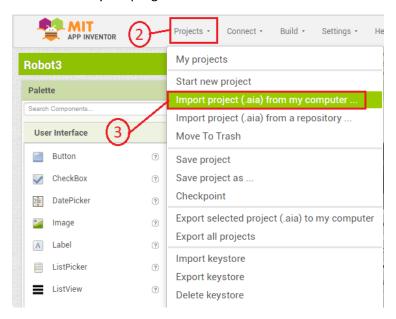
- 1. Use the following link to access the MIT app inventor web page. http://appinventor.mit.edu/
- 2. Click on "Create Apps!", and sign in using your email.



3. From "Projects" list chose "Start New Project", to start new project



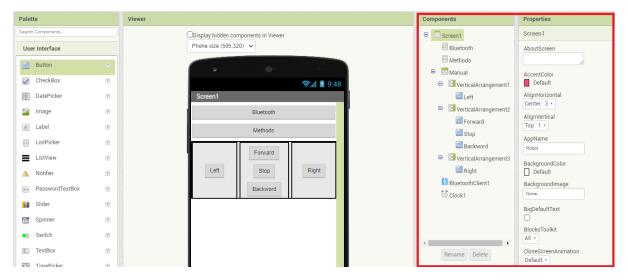
4. Or from "Projects" list chose "Import project (.aia) from your computer...", to view and modify old program.



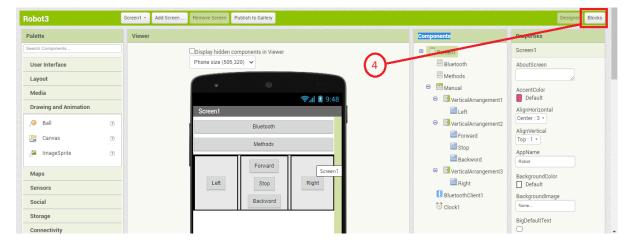
5. On your left hand side, you can add "User interface Components" (ex. Buttons, lists, etc..).



- 6. It is good to use "Layout" on the left side to organize them
- 7. On your right side you can view and modify properties of your Components.



8. To start programing, click on "Blocks" on the upper right corner.



In the following part, explanation of the code is provided as captions for the pictures.

This is for the file "Robooot.aia".

```
when Bluetooth . BeforePicking
do set Bluetooth . Elements to BluetoothClient1 . AddressesAndNames
```

Figure AP-B 1 To include the available devices into the Bluetooth list

```
when Bluetooth . After Picking
    set Bluetooth . Selection to
                                      call BluetoothClient1 . Connect
                                                            address
                                                                      Bluetooth •
                                                                                   Selection •
            BluetoothClient1 •
                                IsConnected •
    🗱 if
    then
          set Bluetooth •
                           Text ▼ to
                                         Connected 1
           set Choose_Method_List •
                                    Visible to true
          set Bluetooth . Text to (
                                        " Try Again!
           set Choose Method List
                                    . Visible v to false v
```

Figure AP-B 2 To make sure that the robot is connected to the chosen device successfully. If not, the user will not be able to view "methods" list.

```
initialize global Methods to make a list Manual "
"Coordinates"

when Choose_Method_List . BeforePicking
do set Choose_Method_List . Elements to get global Methods
```

Figure AP-B 3 To set the elements in "Methods" list to be "Manual" and "Coordinates"

```
when Choose_Method_List . AfterPicking
    🔯 if
               Choose Method List
                                     Selection •
                                                         Manual
          set Coordinates . Visible to false
    then
             Manual . Visible to
    else if
               Choose Method List •
                                     Selection •
                                                         Coordinates
    then
          set Coordinates . Visible to true
             Manual 🕶
                        Visible ▼
                                      false
          set
```

Figure AP-B 4 After picking the movement method, the user will be able to view only the related block. (ex. If user choses "Manual", only Forward, Backward, Right, Left, Stop, Restart and home buttons will be visible)

```
when X_Y · .Click
do call BluetoothClient1 · .SendText
text ( ° 0 "
```

Figure AP-B 5 Code to call first method (it only sends "0" to the robot, read Arduino code to understand it)

```
when Direct · .Click
do call BluetoothClient1 · .SendText
text ( 1 "
```

Figure AP-B 6 Code to call second method (it sends "1" to the robot)

```
when confirm v.Click

do vif vifactory interview in the call BluetoothClient1 v.SendBytes

list vifactory interview interview
```

Figure AP-B 7 Code to send the coordinates when confirm button is clicked. (it sends two numbers to Arduino). If user didn't enter any values, it notifies the user.

```
when Forward . TouchDown
do call BluetoothClient1 . SendText
text . 2 " when Forward . TouchUp
do call BluetoothClient1 . SendText
text . 6 "
```

Figure AP-B 8 Code to call Forward move, (it sends "2" to the robot if the button is touched down, and sends "6" to the robot when the button is touched up)

Figure AP-B 9 Code to call Backward move

```
when Right .TouchDown
do call BluetoothClient1 .SendText
text 4 "

when Right .TouchUp

do call BluetoothClient1 .SendText
text 6 "
```

Figure AP-B 10 Code to call turn Right

```
when Left TouchDown

do call BluetoothClient1 SendText
text 5 "

when Left TouchUp

do call BluetoothClient1 SendText
text 6 "
```

Figure AP-B 11 Code to call turn Left

```
when Stop v .Click
do call BluetoothClient1 v .SendText
text ( " 6 "
```

Figure AP-B 12 Code to call Stop

```
when Home .Click
    call BluetoothClient1 .SendText
                                     7
    set Coordinates . Visible to false
    set Manual . Visible to false
             BluetoothClient1 . IsConnected .
          set Bluetooth . Text to
                                     " Connected
    then
          set Choose_Method_List •
                                  . Visible 🔻
                                                 true 🔻
          set Bluetooth . Text to !
                                        Try Again!
          set Choose_Method_List •
                                   Visible ▼
                                                 false 🔻
```

Figure AP-B 13 Code to call Home (it sends "7" to the robot, and send the user back to "Methods" list again. If the device losses its connection, it sends the user back to Bluetooth list

```
when Restart . Click
    call BluetoothClient1 . SendText
                               text
                                       8
    set Coordinates . Visible to
                                     false •
                 . Visible • to
                                 false •
    set Manual *
    🔯 if
              BluetoothClient1 IsConnected
    then
          set Bluetooth . Text .
                                  to
                                       Connected
          set Choose Method List *
                                     Visible ▼
    else
          set Bluetooth . Text to
                                        Try Again!
          set Choose Method List •
                                    Visible ▼
```

Figure AP-B 14 Code to call Restart (Similar to last one, the difference in Arduino code)

