

## Chapter 6: Frequency Response.

### ① Poles and Zeros.

- Any System Transfer Function  $H(s) = \frac{N(s)}{D(s)}$

- Zeros: roots of numerator.

Poles: roots of denominator

- Freq Response:  $s \rightarrow j\omega$

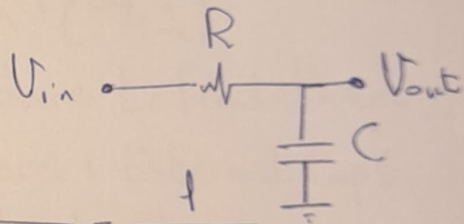
$$H(j\omega) = \frac{V_{out}(j\omega)}{V_{in}(j\omega)} = |H(j\omega)| e^{j\phi}$$

$$* \text{Mag of } a + jb = r = \sqrt{a^2 + b^2}$$

$$* \text{Phase of } (a + jb) = \phi = \tan^{-1} \frac{b}{a}$$

- Example 1

$$H(s) = \frac{V_{out}(s)}{V_{in}(s)}$$



$$= \frac{1/sC}{R + 1/sC} = \frac{1}{1 + sRC} = \frac{1}{1 + s\tau}$$

$$\rightarrow H(j\omega) = \frac{1/j\omega C}{R + 1/j\omega C} = \frac{1}{1 + j\omega RC} = \frac{1}{1 + \frac{j\omega}{\omega_c}}$$

$$\rightarrow \tau = RC = \text{time Constant}$$

$$\rightarrow \omega_c = \frac{1}{\tau} = \frac{1}{RC} \text{ : Cut-off / Corner freq.}$$

$$\rightarrow \text{Poles: } s_p = -1/\tau = -\omega_c, \text{ no zeros.}$$

$$\rightarrow |H(j\omega)| = \frac{1}{\sqrt{1 + (\omega/\omega_c)^2}}$$

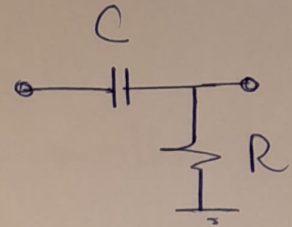
$$\angle H(j\omega) = -\tan^{-1} \frac{\omega}{\omega_c}$$

↳ denominator

Example 2:

$$H(s) = \frac{R}{R + 1/sC} = \frac{sRC}{1 + sRC}$$

$$= \frac{sRC}{1 + s\tau}$$



$$H(j\omega) = \frac{j\omega\tau}{1 + j\omega\tau}$$

→ Poles:  $s_p = -\frac{1}{\tau} = -\omega_c$

Zeros:  $s_z = 0$

$$|H(j\omega)| = \frac{\omega/\omega_c}{\sqrt{1 + (\omega/\omega_c)^2}}$$

$$\angle H(j\omega) = 90^\circ - \tan^{-1}(\omega/\omega_c)$$

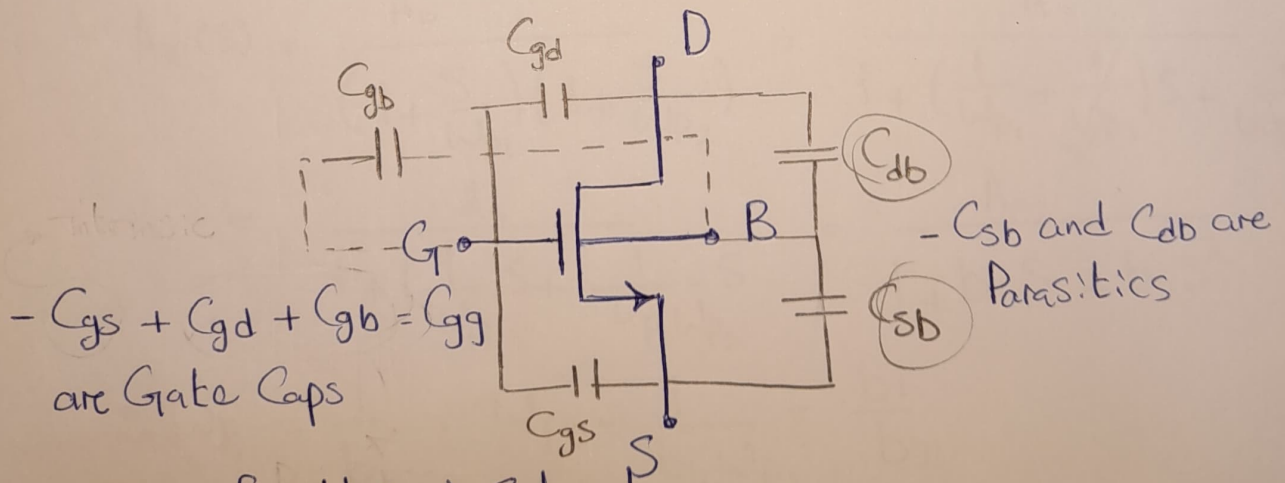
## ② MOSFET Capacitors and where to find them

- Coupling and Bypass Capacitors: External Caps.

\* Not Common in CMOS technology.

\* Acts as a HPF

- Internal Capacitors



\* For MOS in Sat.

→  $C_{gb} = 0$  due to Channel formation

Not Valid For 2  $\downarrow \downarrow$

→  $C_{gs} \gg C_{gd}$  due to Channel Pinched off at drain, So Most of Channel goes to S

→  $C_{sb} > C_{db}$

### ③ SCTC and OCTC techniques.

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#### \* SCTC

↳ for (LFR) not Common in Analog IC

↳ Only Consider one Cap at a time → other SC

↳  $\omega_{L,3dB} = \omega_{L1} + \omega_{L2} + \dots$   
# Highest Pole dominants (LIN dominants)

#### \* OCTC

↳ For High frequency range → more Common.

↳ Only Consider one Cap at a time → other O.C

↳  $\omega_{H,3dB} = \omega_{H1} \parallel \omega_{H2} \parallel \dots$   
# Lowest Pole dominants (HIN dominants)

\* Both gives good approx if only one pole dominants and Poles are real.

### ④ Dominant pole Approx.

- Assume: Poles are real and  $\omega_{p1} \ll \omega_{p2}$

$$\begin{aligned} A_v(s) &= \frac{A_o}{\left(1 + \frac{s}{\omega_{p1}}\right)\left(1 + \frac{s}{\omega_{p2}}\right)} = \frac{A_o}{1 + \left(\frac{1}{\omega_{p1}} + \frac{1}{\omega_{p2}}\right)s + \frac{s^2}{\omega_{p1}\omega_{p2}}} \\ &\approx \frac{A_o}{1 + \left(\frac{1}{\omega_{p1}}\right)s + \frac{1}{\omega_{p1}\omega_{p2}}s^2} = \frac{A_o}{1 + b_1s + b_2s^2} \end{aligned}$$

$$\therefore \omega_{p1} = \frac{1}{b_1}, \quad \omega_{p2} \approx \frac{1}{b_2\omega_{p1}} = \frac{b_1}{b_2}$$

- gives good approx for both dominant and non-dominant.

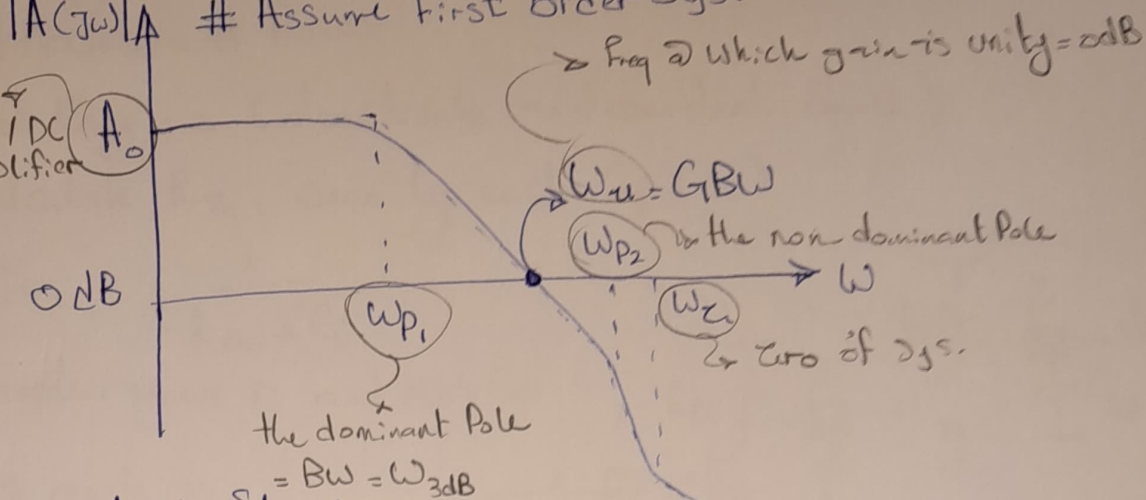


## ⑤ IC Amplifiers Freq response.

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$|A(j\omega)|$  # Assume first order Sys.

is the low / DC gain of amplifier



$$A_v(s) = \frac{A_0(1 + s/\omega_z)}{(1 + s/\omega_{p1})(1 + s/\omega_{p2})}$$

$$- \text{GBW} = A_v \times \text{BW} = A_0 \omega_{p1}$$

- We usually design amplifiers such that  $\omega_{p2}$  and  $\omega_{z1} > \omega_{u1}$

## ⑥ Calculating Poles by Inspection.

1. Set  $V_{sig} = 0$ , deactivate independent source.

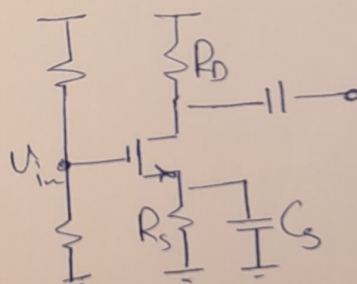
2. Calculate thevenin resistance. Seen by each Cap

$$3. \text{Sp}, i = - \frac{1}{R_{thi} C_i}$$

Example

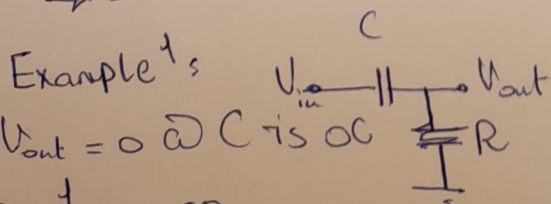
$$\text{at } C_1: R_{th} = R_s \parallel \frac{1}{g_m}$$

$$\text{Sp} = \frac{-1}{(R_s \parallel \frac{1}{g_m}) C_1}$$



## ⑦ Calculating Zeros by Inspection

1. Find  $S$  that makes  $V_{out} = 0$  for each Cap



$V_{out} = 0$  at  $C$  is  $\infty$

$$\frac{1}{sC} = \infty$$

$$s = 0$$

Example 2,

for  $C_s$  in circuit above

$V_{out} = 0$  at  $Z_s$  is  $\infty$

$$Z_s = \frac{R_s}{1 + sR_s C_s} \rightarrow s = -\frac{1}{R_s C_s}$$

## ② Associating Poles with nodes

- # nodes = # Poles

1 Set  $V_{sig} = 0$  (deactivate independent source)

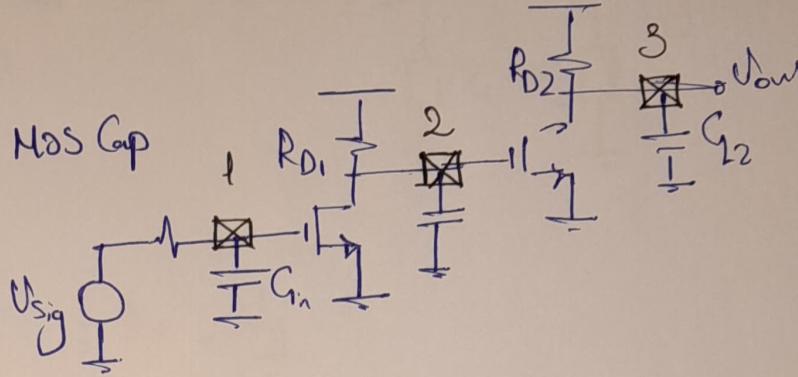
2 Calculate  $R_{th,i}$  seen by each Cap ( $C_i$ )

$$\omega_{pi} = - \frac{1}{R_{th,i} * C_i}$$

- Example: ignore  $r_o$  and MOS Cap

∴ each node is associated with pole

∴  $HIN$  dominates



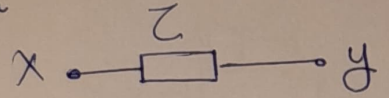
$$\therefore H(s) = \frac{(g_{m1} R_{D1}) (g_{m2} R_{D2})}{(1 + s R_{sig} C_{in}) (1 + s R_{D1} C_{L1}) (1 + s R_{D2} C_{L2})}$$

$$(1 + s R_{sig} C_{in}) (1 + s R_{D1} C_{L1}) (1 + s R_{D2} C_{L2})$$

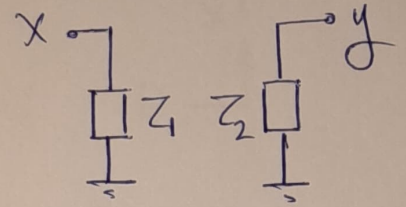
## ⑨ Miller Effect

↳ Miller theorem

if we have a floating impedance  $Z$  between two points  $x, y$



it can be converted to  $Z_1$  and  $Z_2$  not floating components



where,

$$Z_1 = \frac{Z}{1 - A_v}$$

$$Z_2 = \frac{Z}{1 - A_v^{-1}} \quad ; \quad A_v = \frac{V_y}{V_x}$$

Proof: if the two circuits are equivalent  $\rightarrow I_Z = I_{Z_1}$

$$\frac{V_x - V_y}{Z} = \frac{V_x}{Z_1} \rightarrow Z_1 = \frac{Z V_x}{V_x - V_y} = \frac{Z}{1 - \frac{V_y}{V_x}}$$

Similarly

$$Z_2 = \frac{Z}{1 - \frac{V_x}{V_y}}$$

- this decomposition of a "floating" impedance  $Z$  into two "grounded" impedances proves useful in analysis and design

- if the impedance  $Z$  forms the only path between  $x$  and  $y$ , then the conversion is often invalid

- Miller's theorem proves useful in cases where the impedance  $Z$  appears in parallel with the main signal



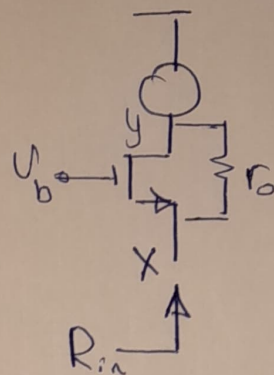
### Example 3. Calc. $R_{in}$

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from direct shortcuts

$$\infty R_{in} = R_{LFS} = \frac{1}{g_m + g_{ub}} \left( 1 + \frac{R_{drain}}{r_o} \right)$$

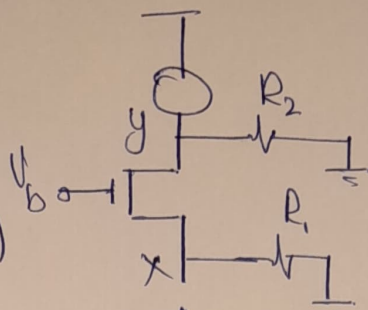
$$R_{drain} = \infty \rightarrow R_{in} = \infty$$



using miller's.

$$R_{in} = R_{LFS} \parallel R_1$$

$$R_{LFS} = \frac{1}{g_m + g_{ub}} \left( 1 + \frac{R_2}{r_o} \right)$$



$$= \frac{1}{g_m + g_{ub}} \left( 1 + \frac{r_o / r_o}{1 - \frac{1}{A_v}} \right) R_{in}$$

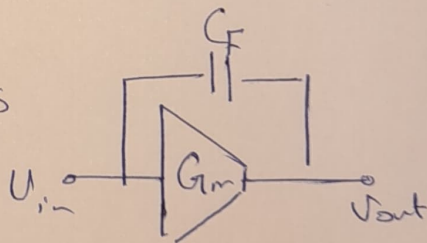
$$= \frac{1}{g_m + g_{ub}} \left( 1 + \frac{1}{1 - 1/A_v} \right) = \frac{1}{g_m + g_{ub}}$$

$$\infty R_1 = \frac{r_o}{1 - A_v} = \frac{r_o}{1 - (g_m + g_{ub}) r_o} = \frac{r_o}{-(g_m + g_{ub}) r_o} = \frac{-1}{g_m + g_{ub}}$$

$$\infty R_{in} = \infty$$

### # the feedforward zero

- Miller's theorem eliminate zeros
- it may predict additional poles
- it does not correctly compute the output impedance



$$v_{out} = 0 \rightarrow i_{out} = 0$$

$$v_{in} s C_F = -G_m v_{in}$$

$$s_z = -G_m / C_F$$