06 project

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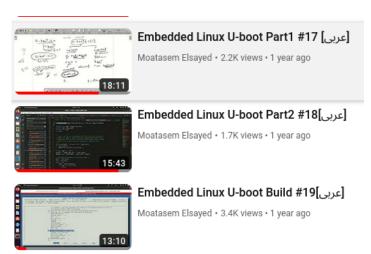
Content

- 1-u-boot tftp
- 2-rootfs ntfs
- 3-bringup driver
- 4-application with design

U-boot TFTP

Normal for u-boot _

U-boot loads kernel and dtb from tftp



How to start through yocto?

Who is responsible to start u-boot on my board

```
moatasem@DellLab:~/poky/build/out$ ^C
moatasem@DellLab:~/poky/build/out$ devtool find-recipe u-boot
NOTE: Starting bitbake server...
NOTE: Reconnecting to bitbake server...
NOTE: Retrying server connection (#1)...
WARNING: Host distribution "ubuntu-22.04" has not been validated with this ve
Loaded 287 entries from dependency cache.
Parsing of 829 .bb files complete (183 cached, 646 parsed). 1383 targets, 65
Summary: There was 1 WARNING message shown.
/home/moatasem/poky/meta/recipes-bsp/u-boot/u-boot 2020.01.bb
moatasem@DellLab:~/poky/build/out$ bitbake-layers show-appends u-boot
NOTE: Starting bitbake server...
WARNING: Host distribution "ubuntu-22.04" has not been validated with this ve
Loaded 1379 entries from dependency cache.
Parsing of 829 .bb files complete (825 cached, 4 parsed). 1383 targets, 65 sk
Summary: There was 1 WARNING message shown.
=== Matched appended recipes ===
u-boot 2020.01.bb:
 /home/moatasem/poky/meta-raspberrypi/recipes-bsp/u-boot/u-boot %.bbappend
moatasem@DellLab:~/poky/build/out$
```

Search

```
moatasem@DellLab:~/poky/meta-raspberrypi$ git grep u-bot^C
moatasem@DellLab:<u>~/poky/meta-raspberrypi</u>$ git grep u-boot-default-script
classes/sdcard_image-rpi.bbclass: ${@bb.utils.contains('RPI_USE_U_B00T', '1', 'u-boot-default-script:do_deploy', '',d)}
conf/machine/include/rpi-default-providers.inc:PREFERRED_PROVIDER_u-boot-default-script ??= "rpi-u-boot-scr"
recipes-bsp/rpi-u-boot-scr/rpi-u-boot-scr.bb:PROVIDES += "u-boot-default-script"
recipes-bsp/u-boot/u-boot_%.bbappend:DEPENDS_append_rpi = " u-boot-default-script"
moatasem@DellLab:~/poky/meta-raspberrypi$ []
```

```
y rpi-base.inc
y rpi-default-providers.inc
y rpi-default-settings.inc
y rpi-default-versions.inc
y rpi-default-versions.inc
y tune-arm1176jzf-s.inc
y rpi-default-versions.inc
y tune-arm1176jzf-s.inc
11
PREFERRED_PROVIDER_virtual/libomxil ?= "userland"
VIRTUAL-RUNTIME_libomxil = "userland"
PREFERRED_PROVIDER_u-boot-default-script ??= "rpi-u-boot-scr"
```

Boot.scr Mechanism

```
y rpi-u-boot-scr.t ▷

    recipes-bsp

                                            SUMMARY = "U-boot boot scripts for Raspberry Pi"
                                                                                                                                               fdt addr ${fdt addr} && fdt get value bootargs /chosen bootargs
 > armstubs
                                                                                                                                               fatload mmc 0:1 ${kernel addr r} @@KERNEL IMAGETYPE@@
                                            LIC FILES CHKSUM = "file://${COMMON LICENSE DIR}/MIT;md5=0835ade698e0bcf8506ecda2f7b4f302
                                                                                                                                            3 if test ! -e mmc 0:1 uboot.env; then saveenv; fi;
                                            COMPATIBLE MACHINE = "^rpi$"
 > bootfiles
                                                                                                                                               @@KERNEL BOOTCMD@@ ${kernel addr r} - ${fdt addr}
                                            DEPENDS = "u-boot-mkimage-native"
 > common
                                            INHIBIT DEFAULT DEPS = "1"
 > formfactor

∨ rpi-u-boot-scr

                                            SRC URI = "file://boot.cmd.in"

√ files

                                            do compile() {
                                               sed -e 's/@@KERNEL IMAGETYPE@@/${KERNEL IMAGETYPE}/' \

    ■ boot.cmd.in

                                                    -e 's/@@KERNEL BOOTCMD@@/${KERNEL BOOTCMD}/' \
                                                    "${WORKDIR}/boot.cmd.in" > "${WORKDIR}/boot.cmd"
  y· rpi-u-boot-scr.bb
                                                bbwarn $(cat ${WORKDIR}/boot.cmd)
                                                mkimage -A arm -T script -C none -n "Boot script" -d "${WORKDIR}/boot.cmd" boot.scr
 u-boot
```

We need to update this file

/home/moatasem/poky/meta-diploma/recipes-bsp/rpi-u-boot-scr/rpi-u-boot-scr.bbappend

rpi-u-boot-scr.bb:

Make changes

```
ta-diploma > recipes-bsp > rpi-u-boot-scr > Y· rpi-u-boot-scr.bbappend

1    FILESEXTRAPATHS_prepend := "${THISDIR}/files:"
2
3    SRC_URI = "file://boot.cmd.in"
4
```

Test

Check tftp commands

```
ta-diploma > recipes-bsp > rpi-u-boot-scr > files > \( \) boot.cmd.in

1    fdt addr ${fdt_addr} && fdt get value bootargs /chosen bootargs

2    fatload mmc 0:1 ${kernel_addr_r} @@KERNEL_IMAGETYPE@@

3    setenv serverip 10.42.0.1;

4    setenv ipaddr2 10.42.0.3

5    if test ! -e mmc 0:1 uboot.env; then saveenv; fi;

6    @@KERNEL_BOOTCMD@@ ${kernel_addr_r} - ${fdt_addr}

7
```

```
J-Boot> printenv ipaddr2
Lpaddr2=10.42.0.3
J-Boot> printenv ser
serial# serverip
J-Boot> printenv serverip
serverip=10.42.0.1
J-Boot>
```

```
erverip=10.42.0.1
|-Boot> help tftp
|ftpboot - boot image via network using TFTP protocol
|sage:
|ftpboot [loadAddress] [[hostIPaddr:]bootfilename]
|-Boot> [
```

Test commands before updating recipe

```
-Boot> setenv ipaddr 10.42.0.2
-Boot> ping 10.42.0.1
an78xx_eth Waiting for PHY auto negotiation to complete.... done
Jsing lan78xx eth device
an78xx_eth Waiting for PHY auto negotiation to complete.... done
from server 10.42.0.1; our IP address is 10.42.0.2
ilename 'zImage'.
oad address: 0x80000
## 0 Bytes
```

done

Update your cmd file And build image

Start Your Server

```
fdt addr ${fdt_addr} && fdt get value bootargs /chosen bootargs
# fatload mmc 0:1 ${kernel_addr_r} @@KERNEL_IMAGETYPE@@
setenv serverip 10.42.0.1;
setenv ipaddr 10.42.0.2
tftp $kernel_addr_r uImage
tftp $fdt_addr_r bcm2710-rpi-3-b-plus.dtb

if test ! -e mmc 0:1 uboot.env; then saveenv; fi;
@@KERNEL_BOOTCMD@@ ${kernel_addr_r} - ${fdt_addr_r}
```

Setting up a TFTP server

```
Install the following packages on your host PC:
```

```
$ sudo apt-get update && sudo apt-get install xinetd tftpd tftp
```

Create file \direction /etc/xinetd.d/tftp' with the following contents:

```
service tftp
{
    protocol = udp
    port = 69
    socket_type = dgram
    wait = yes
    user = nobody
    server = /usr/sbin/in.tftpd
    server_args = /tftpboot
    disable = no
}
```

Create directory \diffpboot/\(\text{'(this matches the \server-args' above)}\) and set its permissions:

```
$ sudo mkdir /tftpboot/
$ sudo chmod -R 777 /tftpboot/
$ sudo chown -R nobody /tftpboot/
```

Restart the `xinetd' service:

```
$ sudo service xinetd restart
```

TEST

Script to automate

```
#!/bin/bash
case $1 in

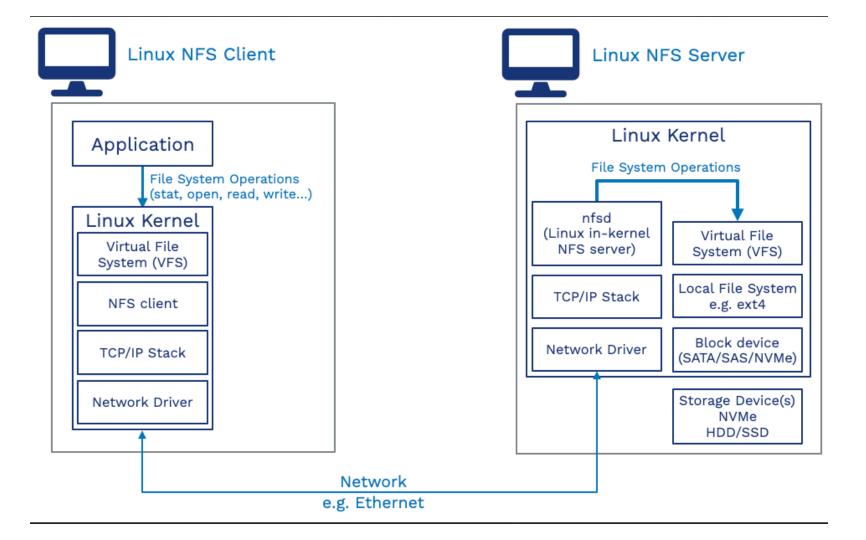
flash)
flash)
echo " flash"
set -ex
DIR="/home/moatasem/poky/output/build_raspi/tmp/deploy/images/diploma-machine/"
IMAGE='readlink /home/moatasem/poky/output/build_raspi/tmp/deploy/images/diploma-machine/diploma-machine.wic.bz:
#update u-boot,zImage
UIMAGE='readlink /home/moatasem/poky/output/build_raspi/tmp/deploy/images/diploma-machine/uImage)
sudo cp "$DIR$UIMAGE" /fftpboot/uImage
#update ditb
DTB=S(readlink /home/moatasem/poky/output/build_raspi/tmp/deploy/images/diploma-machine/uImage)
sudo cp "$DIR$UIMAGE" /fftpboot/uImage
#update ditb
DTB=S(readlink /home/moatasem/poky/output/build_raspi/tmp/deploy/images/diploma-machine/bcm2710-rpi-3-b-plus.dtb)
FULLPATH="$DIR$IMAGE" /fftpboot/bcm2710-rpi-3-b-plus.dtb

FULLPATH="$DIR$IMAGE" /fftpboot/bcm2710-rpi-3-b-plus.dtb

TO "$FULLPATH" |
bzip2 -d $IMAGE
IMAGE="$[IMAGE bz2]"
sudo dd if=$IMAGE of=/dev/mmcblk0 bs=100M
rm $IMAGE
$SET HAGE SET HAGE
SET HAGE
SET HAGE
SET HAGE
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SE
```

```
switch to partitions #0, OK
888 bytes read in 1 ms (378.9 KiB/s)
## Executing script at 02400000
an78xx eth Waiting for PHY auto negotiation to complete.... done
Jsing lan78xx eth device
oad address: 0x80000
############## 0 Bytes
       3.8 MiB/s
Bytes transferred = 6094312 (5cfde8 hex)
an78xx eth Waiting for PHY auto negotiation to complete.... done
 sing lan78xx eth device
TFTP from server 10.42.0.1; our IP address is 10.42.0.2
Filename 'bcm2710-rpi-3-b-plus.dtb'.
Load address: 0x2600000
oading: ###### 0 Bytes
aving Environment to FAT... OK
## Booting kernel from Legacy Image at 00080000 ...
  Image Name: Linux-5.4.72-v7
  Image Type: ARM Linux Kernel Image (uncompressed)
  Data Size: 6094248 Bytes = 5.8 MiB
  Load Address: 00008000
 # Flattened Device Tree blob at 02600000
```

NTFS



Install server

1- install nfs-kernel-server

```
moatasem@DellLab:~/board/raspberry/image_scratch/boot$ sudo apt-get install nfs-kernel-server
Reading package lists... Done
Building dependency tree... Done
Reading state information... Done
nfs-kernel-server is already the newest version (1:2.6.1-1ubuntu1.2).
0 to upgrade, 0 to newly install, 0 to remove and 0 not to upgrade.
moatasem@DellLab:~/board/raspberry/image_scratch/boot$
```

2- prepare file system

```
noatasem@DellLab:~$ mkdir nfsroot
noatasem@DellLab:~$ cd nfsroot/
noatasem@DellLab:~/nfsroot$ pwd
'home/moatasem/nfsroot
noatasem@DellLab:~/nfsroot$
```

3-Extract diploma-minimal-diploma-machine.tar.bz2 to your ntfs location

```
matasem@DellLab:~/nfsroot$ sudo tar --same-owner -xvf /home/moatasem/poky/output/build_raspi/tmp/deploy/images/diploma-machine//diploma-minimal-diploma-machine.tar.bz2 -C
oatasem@DellLab:~/nfsroot$
oatasem@DellLab:~/nfsrootS ls
in boot dev etc home lib media mnt proc run sbin sys 🚾 usr var
noatasem@DellLab:~/nfsroot$ ls -1
total 60
rwxr-xr-x 2 root root 4096 Mar
          2 root root 4096 Mar 9 2018 boot
          2 root root 4096 Mar 9 2018 dev
          19 root root 4096 Mar 9 2018 etc
           3 root root 4096 Mar
           4 root root 4096 Mar 9 2018 lib
           2 root root 4096 Mar 9 2018 media
          2 root root 4096 Mar 9 2018 mnt
           2 root root 4096 Mar 9 2018 proc
           2 root root 4096 Mar 9 2018 sbin
          2 root root 4096 Mar 9 2018 sys
rwxrwxrwt 2 root root 4096 Mar 9 2018
rwxr-xr-x 10 root root 4096 Mar 9 2018 usr
irwxr-xr-x 8 root root 4096 Mar 9 2018 var
```

4- export your location

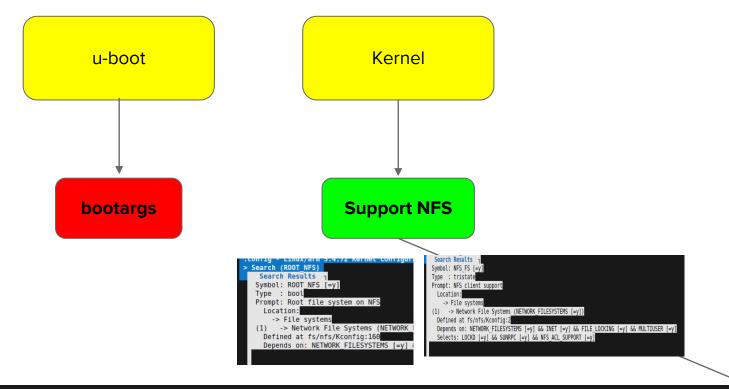
```
noatasem@DellLab:~/nfsroot$ sudo vim /etc/exports
```

```
# /srv/homes hostname1(rw,sync,no_subtree_check) hostname2(ro,sync/
home/moatasem/nfsroot *(rw,sync,no_subtree_check,no_root_squash)
```

5- restart nfs daemon

```
noatasem@DellLab:~/nfsroot$ sudo systemctl restart nfs-kernel-server
oatasem@DellLab:~/nfsroot$ sudo systemctl status nfs-kernel-server
nfs-server.service - NFS server and services
    Loaded: loaded (/lib/systemd/system/nfs-server.service; disabled; vendor preset: enabled)
   Drop-In: /run/systemd/generator/nfs-server.service.d
            └order-with-mounts.conf
    Active: active (exited) since Thu 2024-02-08 15:51:03 EET; 3s ago
   Process: 289435 ExecStartPre=/usr/sbin/exportfs -r (code=exited, status=0/SUCCESS)
   Process: 289436 ExecStart=/usr/sbin/rpc.nfsd (code=exited, status=0/SUCCESS)
  Main PID: 289436 (code=exited, status=0/SUCCESS)
       CPU: 6ms
eb 08 15:51:02 DellLab systemd[1]: Starting NFS server and services...
Feb 08 15:51:03 DellLab systemd[1]: Finished NFS server and services.
noatasem@DellLab:~/nfsroot$ ps -aux | grep nfs
        289433 0.0 0.0
                          5516 2164 ?
                                              Ss 15:51
                                                           0:00 /usr/sbin/nfsdcld
oot
        289442 0.0 0.0
                                                   15:51 0:00 [nfsd]
oot
        289443 0.0 0.0
                                                   15:51 0:00 [nfsd]
        289444 0.0 0.0
                                                   15:51
                                                           0:00 [nfsd]
        289445 0.0 0.0
                                                           0:00 [nfsd]
        289446 0.0 0.0
                                                           0:00 [nfsd]
        289447 0.0 0.0
                                                           0:00 [nfsd]
        289448 0.0 0.0
                                                   15:51 0:00 [nfsd]
                                                   15:51 0:00 [nfsd]
oot
        289449 0.0 0.0
noatasem 289477 0.0 0.0 17744 2200 pts/6 S+ 15:51 0:00 grep --color=auto nfs
oatasem@DellLab:~/nfsroot$
```

Raspberrypi



```
CONFIG_NFS_COMMON=y
moatasem@DellLab:~/poky/output/build_raspi/tmp/work-shared/diploma-machine/kernel-build-artifacts$ cat .config | grep -i NFS_FS
CONFIG_NFS_FS=y
CONFIG_NFS_FSCACHE=y
moatasem@DellLab:~/poky/output/build_raspi/tmp/work-shared/diploma-machine/kernel-build-artifacts$ cat .config | grep -i ROOT_NFS
CONFIG_ROOT_NFS=y
moatasem@DellLab:~/poky/output/build_raspi/tmp/work-shared/diploma-machine/kernel-build-artifacts$
```

Test bootargs before updating recipe

```
otargs-coherent_pool=1M 8250.nr_warts=1 snd_bcn2835.enable_compat_alsa=0 snd_bcn2835.enable_hdmi=1 snd_bcn2835.enable_headphones=1 video=MDMI-A-1:640x480MQ60 vc_men.men_base=0x3ec000000 vc_men.men_size=0x400000000 dwc_otg.lpm_enable=0 console=tty50,115200 root=/dev/mmcblk8p2 rootfstype=ext4 rootwait logo.nologo otargs-coherent_pool=1M 8250.nr_warts=1 snd_bcn2835.enable_compat_alsa=0 snd_bcn2835.enable_hdmi=1 snd_bcn2835.enable_headphones=1 video=MDMI-A-1:640x480MQ60 vc_men.men_base=0x3ec000000 vc_men.men_size=0x400000000 dwc_otg.lpm_enable=0 console=tty50,115200 root=/dev/mmcblk8p2 rootfstype=ext4 rootwait logo.nologo dvc_otg.lpm_enable=0 console=tty50
```

```
console=ttyS0,115200 root=/dev/mmcblk0p2 rootfstype=ext4 rootwait
```

Need to update file

```
conerent_pool=1M 8250.nr_Uarts=1 snd_bcm2835.enable_compat_alsa=0 snd_bcm2835.enable_ndml=1 snd_bcm2835 root@mydiploma:~# cat /boot/cmdline.txt
dwc_otg.lpm_enable=0 console=serial0,115200 root=/dev/mmcblk0p2 rootfstype=ext4 rootwait logo.nologo
root@mydiploma:~#
root@mydiploma:~#
```

update

```
moatasem@DellLab:~238x56
wc_otg.lpm_enable=0 console=serial0,115200 root=/dev/nfs ip=dhcp nfsroot=10.42.0.1:/home/moatasem/nfsroot,v3,tcp rootwait logo.nologo
```

reboot

```
root@mydiploma:~#
root@mydiploma:-# mount

10.42.0.1:/home/moatasem/nfsroot on / type nfs (rw,relatime,vers=3,rsize=4096,wsize=4096,namlen=255,hard,nolock,proto=tcp,timeo=600,retrans=2,sec=sys,mountaddr=10.42.0.1,mountvers=3,mountproto=tcp,loca
devtmpfs on /dev type devtmpfs (rw,relatime,size=440212k,nr_inodes=110053,mode=755)
broc on /proc type proc (rw,relatime)
sysfs on /sys type sysfs (rw,relatime)
debugfs on /sys/kernel/debug type debugfs (rw,relatime)
tonfigfs on /sys/kernel/config type configfs (rw,relatime)
tmpfs on /run type tmpfs (rw,nosuid,nodev,mode=755)
tmpfs on /run type tmpfs (rw,relatime)
devpts on /dev/pts type devpts (rw,relatime)
devpts on /dev/pts type devpts (rw,relatime,gid=5,mode=620,ptmxmode=000)
root@mydiploma:-# []
```

TEST

```
boot dev etc home lib medla mnt proc run sbin sys tmp usr var
t@mvdiploma:~# []
:30:15.641063 IP 10.42.0.55.953 > DellLab.nfs: Flags [P.], seq 1524:1644, ack 14:
tattr fh Unknown/910907018F483A0000000000AC9D3D1D89124915B8C082D2986C8661709C4200
:30:15.641145 IP DellLab.nfs > 10.42.0.55.953: Flags [P.], seq 1417:1533, ack 164
```

Which recipe is responsible on cmdline.txt?

```
moatasem@DellLab:~/poky/bulld$ cd ../meta-raspberryp1/
moatasem@DellLab:~/poky/meta-raspberrypi$ git grep cmdline.txt
recipes-kernel/linux/linux-raspberrypi.inc:
                                                # Deploy cmdline.txt only for the main kernel package
recipes-kernel/linux/linux-raspberrypi.inc:
                                                     echo "${CMDLINE}${PITFT PARAMS}" > ${DEPLOYDIR}/${BOOTFILES DIR NAME}/cmdline.txt
moatasem@DellLab:~/poky/meta-raspberrypi$ code recipes-kernel/linux/linux-raspberrypi.inc
moatasem@DellLab:~/poky/meta-raspberrypi$
linux-raspberrypi-rt 4.14.bb
                                           KBUILD DEFCONFIG raspberrypi4 ?= "bcm2711 defconfig"
      linux-raspberrypi-rt 4.19.bb
                                           KBUILD DEFCONFIG raspberrypi4-64 ?= "bcm2711 defconfig"
   > linux-firmware-rpidistro
                                           LINUX VERSION EXTENSION ?= ""
   > recipes-multimedia
   > wic
                                           # CMDLINE for raspberrypi
  gitignore
                                           SERIAL = "${@oe.utils.conditional("ENABLE UART", "1", "console=serial0,115200", "", d)}"

    ≡ COPYING.MIT

                                           CMDLINE ?= "dwc otg.lpm enable=0 ${SERIAL} root=/dev/mmcblk0p2 rootfstype=ext4 rootwait"
                                      30
   ! kas-poky-rpi.yml
  (i) README.md
```

bbappend to overwrite this one

TEST

```
echo "flash"
set -ex
DIR="/home/moatasem/poky/output/build_raspi/tmp/deploy/images/diploma-machine/"
IMAGE='readlink /home/moatasem/poky/output/build_raspi/tmp/deploy/images/diploma-machine/diploma-minimal-diploma-machine.wic.bz2'
#Update u-boot,zImage
UIMAGE=$(readlink /home/moatasem/poky/output/build_raspi/tmp/deploy/images/diploma-machine/uImage)
sudo cp "$DIR$UIMAGE" /tftpboot/uImage
#Update dtb
DTB=$(readlink /home/moatasem/poky/output/build_raspi/tmp/deploy/images/diploma-machine/bcm2710-rpi-3-b-plus.dtb)
sudo cp "$DIR$DIB" /tftpboot/bcm2710-rpi-3-b-plus.dtb
#Update rootfs
sudo rm -rf /home/moatasem/nfsroot/*
sudo tar --same-owner -pxvf /home/moatasem/poky/output/build_raspi/tmp/deploy/images/diploma-machine/diploma-minimal-diploma-machine.tar.bz2 -C /home/moatasem/nfsro
#flash image
FULLPATH="$DIR$IMAGE"
# cp "$FULLPATH" .
# bzip2 -d SIMAGE
# IMAGE="${IMAGE="${IMAGE}.bz2}"
# sudo dd if=$IMAGE of=/dev/mmcblk0 bs=100M
# rm SIMAGE
# rm SIMAGE
# rm SIMAGE
# rm SIMAGE
set +ex
```

test exist

noatasem@DellLab:~/nfsroot\$ sudo touch test_exist [sudo] password for moatasem:

```
ياعم انا عمدة افتح
```

dev/pts type devpts (rw,relatime,gid=5,mode=620,ptmxmode=000)

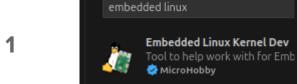
No Flashing anymore



```
bin boot dev etc hom root@mydiploma:~# hello_ hello_c hello_makefile root@mvdiploma:~# hello_ hello_c hello_makefile root@mvdiploma:~# hello_ hello_c hello_makefile root@mvdiploma:~# hello_ hello_makefile root@mvdiploma:~# hello_ hello_makefile root@mvdiploma:~# hello_ hello_makefile root@mvdiploma:~# hello_makefile root@mvdiploma:~# hello_makefile root@mvdiploma:~# hello-makefile root@mvdiploma:~# hello-makefile root@mvdiploma:~# hello-makefile root@mvdiploma:~# hello-cmake hello-cmake hello-cmake root@mvdiploma:~# hello-cmake root@mvdiploma:~# hello-makefile root@mvdiploma:~# hello-makefile root@mvdiploma:~# hello-cmake root@mvdiploma:~# hello-cmake root@mvdiploma:~# hello_makefile root@mvdiploma:~# hello_makefile
```

```
noatasem@DellLab:~/poky/build/out$ sync
                                                                                  home
                                                                                          lib
                                                                                                 media
moatasem@DellLab:~/poky/build/out$ bitbake diploma-minimal
                                                       oot@mydiploma:~# hello
WARNING: Host distribution "ubuntu-22.04" has not been valid
                                                       ello c hello makefile
                                                       oot@mydiploma:~# hello
                                                       ello c
                                                                      hello cmake
                                                                                       hello makefile
                                 Now
                                                       oot@mydiploma:~# hello cmake
                                                       ello cmake
                                                        ot@mvdiploma:~#
```

bringup







VS Code Extension for Embedded Linux Kernel Dev - New Version v0.4.9

2 sudo apt-get install universal-ctags

```
EMBEDDED LINUX DEV: COMMANDS

Device Tree Doc from compatible
Device Driver from compatible
ARM dts/dtsi from include
ARM dts/dtsi from include
ARM64 dts/dtsi from include
ARM64 dts/dtsi from project

Comparison
ARM64 dts/dtsi from include
Comparison
C
```

```
/soc/gpto@7e200000/
gpio: gpio@7e200000 {
    compatible = "brcm, bcm2835-gpio";
    reg = <0x7e200000 0xb4>;
    interrupts = <2 17>, <2 18>;
    gpio-controller;
    #gpio-cells = <2>;
    interrupt-cells = <2>;
    interrupt-cells = <2>;
    pinctrl-names = "default";

**Gepio {
        notro,10 years ago|1 author (notro)
        spi0_pins: spi0_pins {
            brcm,pins = <9 10 11>;
```

```
Planc Lude "born?18.dts1"
Planc Lude "born?19.rpl.ids1"
Planc Lude "born?39.rpl.ids1"
Planc Lude "born?39.rpl.ids1"
Planc Lude "born?39.rpl.ids71.39.soc.#rs1"
Planc Lude "born?39.rpl.ids71.39.soc.#rs1"
Planc Lude "born?39.rpl.ids71.39.soc.#rs1"
Planc Lude "born?39.rpl.ids1.dts1"
Planc Lude "born?39.rpl.ids1.dts1"
```

4

Generating CTags index (--languages=C,CH,Kconfig,Make)

Lets add i2c-tools

```
root@mydiploma:~#
root@mydiploma:~# i2cdetect -y 1
Error: Could not open file `/dev/i2c-1' or `/dev/i2c/1': No such file or directory
root@mydiploma:~#
```

Lets enable i2c

```
moatasem@Delllab!/tftpboots dtc -I dtb -O dts -o file.dts bcm2710-rpi-3-b.plus.dtb
file.dts: Warning (dma_ranges_format): /soc/firmware:dma-ranges: empty "dma-ranges" property but its #address-cells (2) did
file.dts: Warning (unit_address_vs_reg): /soc: node has a reg or ranges property, but no unit name
file.dts: Warning (unit_address_vs_reg): /soc/axiperf: node has a reg or ranges property, but no unit name
file.dts: Warning (unit_address_vs_reg): /soc/axiperf: node has a reg or ranges property, but no unit name
file.dts: Warning (simple_bus_reg): /soc/cdpmux: missing or empty reg/ranges property
file.dts: Warning (simple_bus_reg): /soc/axiperf: simple-bus unit address format error, expected "7e009800"
file.dts: Warning (simple_bus_reg): /soc/firmware/clocks: missing or empty reg/ranges property
file.dts: Warning (simple_bus_reg): /soc/firmware/clocks: missing or empty reg/ranges property
file.dts: Warning (simple_bus_reg): /soc/power: missing or empty reg/ranges property
file.dts: Warning (simple_bus_reg): /soc/power: missing or empty reg/ranges property
file.dts: Warning (simple_bus_reg): /soc/firmware/expected unit_address format error, expected "7e200000"
file.dts: Warning (simple_bus_reg): /soc/firmware/expected unit_address format error, expected "7e200000"
file.dts: Warning (simple_bus_reg): /soc/cound: missing or empty reg/ranges property
file.dts: Warning (simple_bus_reg): /soc/cound: missing or empty reg/ranges property
file.dts: Warning (unique_unit_address): /soc/ound: missing or empty reg/ranges property
file.dts: Warning (unique_unit_address): /soc/mc@7e300000: duplicate unit-address (also used in node /soc/mmcn@7e300000)
file.dts: Warning (gloups_property): /_symbols_:glocks: property size (19) is invalid, expected multiple of 4
file.dts: Warning (interrupt_provider): /soc/gircwarestreamer.evells in interrupt provider
file.dts: Warning (interrupt_provider): /soc/gircwarestreamer.evells in interrupt provider
file.dts: Warning (interrupt_provider): /soc/gircwarestreamer.evells in interrupt p
```

```
GPIO 2 (12C1 SDA) 3
GPIO 3 (12C1 SCL) 5
```

```
i2c10 = "/ccc/i2c0muy/i2c01":

i2c07e804000 {
    compatible = "brcm,bcm2835-i2c";
    reg = <0x7e804000 0x1000>;
    interrupts = <0x02 0x15>;
    clocks = <0x07 0x14>;
    #address-cells = <0x01>;
    #size-cells = <0x00>;
    status = "disabled";
    pinctrl-names = "default";
```

pinctrl-0 = <0x17>:

Then compile Then reboot

```
moatasem@DellLab:/tftpboot$ sudo dtc -I dts -O dtb -o bcm2710-rpi-3-b-plus.dtb file.dts
file.dts:997.4-15: Warning (dma_ranges_format): /soc/firmware:dma-ranges: empty "dma-ranges"
file.dts:79.6-1061.4: Warning (unit_address_vs_reg): /soc: node has a reg or ranges property
file.dts:986.11-992.5: Warning (unit_address_vs_reg): /soc/apiperf: node has a reg or ranges
file.dts:1038.11-1041.5: Warning (unit_address_vs_reg): /soc/gpiomem: node has a reg or ranges
file.dts:579.11-603.5: Warning (simple_bus_reg): /soc/i2c0mux: missing or empty reg/ranges p
file.dts:889.7-893.5: Warning (simple bus reg): /soc/apu: missing or empty reg/ranges proper
```

```
Proodcast mossage from contAmydialoma (+tys
```

oot@mydiploma:~# reboot

INIT: Sending processes configured via /etc/root@mydiploma:~# Stopping Dropbear SSH serv

dropbear. Stopping syslogd/klogd: stopped syslogd (pid stopped klogd (pid 320) done

not deconfiguring network interfaces: network Sending all processes the TERM signal... Configure kernel

```
MOTHERING TO GO. USE DELDAKE WOLLD TO DUELD EVERYTHING, OF THE DELDAKE --HELP
moatasem@DellLab:~/poky/build$ bitbake -c menuconfig virtual/kernel
 WARNING: Host distribution "ubuntu-22.04" has not been validated with this version
Loaded 1377 entries from dependency cache.
 Parsing of 826 .bb files complete (823 cached, 3 parsed). 1380 targets, 65 skipped
 NOTE: Resolving any missing task queue dependencies
 Build Configuration:
 BB VERSION
                  = "1.46.0"
 BUILD SYS
                  = "x86 64-linux"
 NATIVELSBSTRING
                  = "universal"
 TARGET SYS
                  = "arm-poky-linux-gnueabi"
 MACHINE
                  = "diploma-machine"
DISTRO
                  = "diploma"
                  = "1.0"
DISTRO VERSION
                  = "arm vfp cortexa7 neon vfpv4 thumb callconvention-hard"
TUNE FEATURES
TARGET FPU
                  = "hard"
 meta
```

Change dts manually

```
i2c@7e804000 {
    compatible = "brcm,bcm2835-i2c";
    reg = <0x7e804000 0x1000>;
    interrupts = <0x02 0x15>;
    clocks = <0x07 0x14>;
    #address-cells = <0x01>;
    #size-cells = <0x00>;
    status = "okay";
    pinctrl-names = "default";
    pinctrl-0 = <0x17>;
    clock-frequency = <0x186a0>;
    phandle = <0x2a>;
    [temp-sensor@5a {
        compatible = "melexis,mlx90614";
        reg = <0x5a>;
};
};
```

< > MLX90632 contact-less infrared sensor with medical

M> MLX90614 contact-less infrared sensor

TMPAGE infrared thermonile concer

```
uploma > recipes-kernel > linux > y · linux-raspberrypi_%.bbappend
   You, 1 second ago | 1 author (You)

FILESEXTRAPATHS_prepend := "${THISDIR}/${PN}:"

SRC_URI = "file://defconfig"   You, 1 second ago * Uncommitted changes

CMDLINE_remove = "root=/dev/mmcblk0p2 rootfstype=ext4"

CMDLINE_append = " root=/dev/nfs ip=dhcp nfsroot=10.42.0.1:/home/moatasem/nfsroot,v3,tcp "
```



kernel-modules is just a package, so you can include it in IMAGE_INSTALL just like any other package name (although this may not be the most appropriate solution), alternatively, add them to MACHINE_ESSENTIAL_EXTRA_RRECOMMENDS.

IMAGE_INSTALL_append = " kernel-modules"

or

MACHINE_ESSENTIAL_EXTRA_RRECOMMENDS_append = "kernel-modules"

```
pv6 466944 18 [permanent], Live 0x7f28000
RC_dev 20480 8 - Live 0x7f9dc000
RC_dev 20480 1 shc256_0eneric, Live 0x7f95000
RC_dev 20480 1 shc256_generic, Live 0x7f95000
RC_dev 20480 1 shc285_codec, Live 0x7f95000
RC_dev 20480 1 shc285_codec, Live 0x7f95000
RC_dev 20480 1 shc285_codec, Live 0x7f95000
RC_dev 20480 2 shc285_codec, Lore2835_v412, Lore2835_isp, Live 0x7f95000
RC_dev 20480 2 shc285_codec, Lore2835_isp, Live 0x7f947000
RC_dev 20480 2 shc285_codec, V412_men2men, Lore2835_v412, Lore2835_isp, Live 0x76947000
RC_dev 20480 3 shc285_codec, V412_men2men, Lore2835_v412, Lore2835_isp, Live 0x76947000
RC_dev 20480 3 shc285_codec, V412_men2men, Lore2835_v412, Lore2835_isp, V1deobx_dillore24001 shc28610 shc28610
```

12c and mlx are working fine now

```
root@mydiploma:~# i2cdetect -y 1
          MLX90614
```

Test MLX90614

```
14687 *0.02 - 273
root@mydiploma:/sys/devices/platform/soc/3f804000.i2c/i2c-1/1-005a/iio:device0# echo "$(cat in_temp_object_raw) *0.02 - 273" | bc
20.76
root@mydiploma:/sys/devices/platform/soc/3f804000.i2c/i2c-1/1-005a/iio:device0# | |
CTRL-A Z for help | 115200 8N1 | NOR | Minicom 2.8 | VT102 | Offline | ttyUSB0
```

Patch devicetree → Devtool modify

before

```
LINUX-RASPBERRYPI [SSH: MOATASEMOLDDELL]

    ■ bcm283x-rpi-i2c0mux 0 28.dtsi

                                                                          compatible = "spidev";
   rea = <0>: /* CE0 */

    bcm283x-rpi-lan7515.dtsi

    bcm283x-rpi-lan7515.dtsi

                                                                          #address-cells = <1>:
   #size-cells = <0>;

    bcm283x-rpi-smsc9514.dtsi

                                                                          spi-max-frequency = <1250000000>;

    □ bcm283x-rpi-usb-host.dtsi

    ■ bcm283x-rpi-usb-otg.dtsi

   enidev1. enidev@1 /

    bcm283x.dtsi

                                                                    /soc/i2c@7e804000/
   i2c1: i2c@7e804000 {

    bcm2708-rpi-b-rev1.dts

                                                                       compatible = "brcm,bcm2835-i2c";
   reg = <0x7e804000 0x1000>;
   interrupts = <2 21>:
   clocks = <&clocks BCM2835 CLOCK VPU>;

    bcm2708-rpi-cm.dtsi

                                                                       #address-cells = <1>;

    □ bcm2708-rpi-zero-w.dts

                                                                       #size-cells = <0>;
   status = "disabled":
   pinctrl-names = "default";

    bcm2708.dtsi

                                                                       pinctrl-0 = <&i2c1 pins>;

    bcm2709-rpi-2-b.dts

                                                                       clock-frequency = <100000>:

    bcm2709-rpi.dtsi

                                                            135 &i2c1 {

    bcm2709.dtsi

                                                                      pinctrl-names = "default":

    bcm2710-rpi-2-b.dts

                                                                      pinctrl-0 = <&i2c1 pins>:
                                                                      clock-frequency = <100000>;

    bcm2710-rpi-3-b.dts
```

After

```
&i2c1 {
            pinctrl-names = "default";
            pinctrl-0 = <&i2c1 pins>:
            clock-frequency = <100000>;
            status = "okay";
            temp-sensor@5a -
                compatible = "melexis,mlx90614";
                 reg = <0x5a>;
On branch rpi-5.4.v
Your branch and 'origin/rpi-5.4.y' have diverged,
and have 2 and 1370 different commits each, respectively
  (use "git pull" to merge the remote branch into yours)
Changes not staged for commit:
  (use "git add <file>..." to update what will be committed)
   (use "git restore <file>..." to discard changes in working directory)
no changes added to commit (use "git add" and/or "git commit -a")

    moatasem@DellLab:~/poky/build/workspace/sources/linux-raspberrypi$ git diff

diff --qit a/arch/arm/boot/dts/bcm2710-rpi-3-b-plus.dts b/arch/arm/boot/dts/bcm2710-rpi-3-b-plus.dts
 index 4e4e47100831..d800e15fa72b 100644
--- a/arch/arm/boot/dts/bcm2710-rpi-3-b-plus.dts
+++ b/arch/arm/boot/dts/bcm2710-rpi-3-b-plus.dts
        pinctrl-names = "default";
        pinctrl-0 = <&i2cl pins>:
        clock-frequency = <100000>
```

IMAGE INSTALL += "bc

Update-recipe Test

```
fa-diploma > recipes-kernel > linux > = linux-raspberrypi_%.bbappend

| FILESEXTRAPATHS_prepend := "${THISDIR}/${PN}:"

| SRC_URI = "file://defconfig \
| file://0001-add-temp-sensor.patch \
| "

| CMDLINE_remove = "root=/dev/mmcblk0p2 rootfstype=ext4"
| CMDLINE_append = " root=/dev/nfs ip=dhcp nfsroot=10.42.0.1:/home/moatasem/nfsroot,v3,tcp "
```

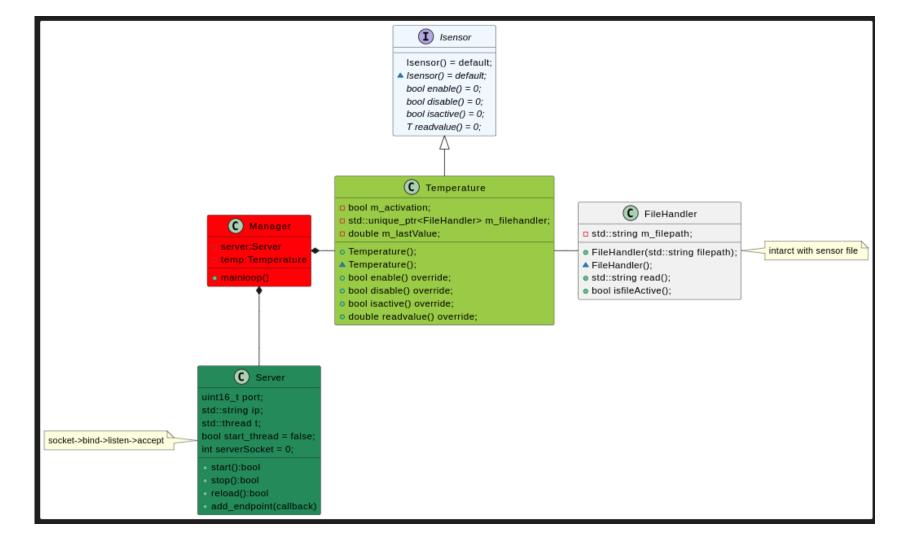
```
237568 6 bcm2835_isp,bcm2835_codec,videobuf2_common,bcm2835_v4l2,v4l2_mem2mem
```

```
$ buildme.sh
                                                       ≣ linux-raspberrypi_%.bbappend м

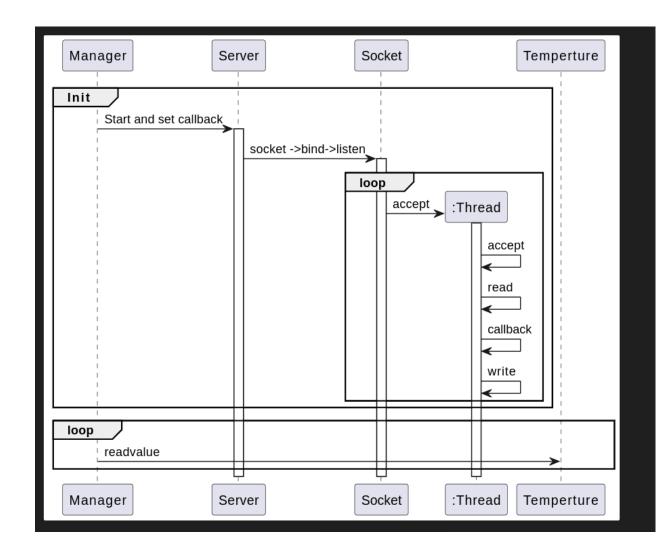
≡ 0001-add-temp-sensor.patch ×

meta-diploma > recipes-kernel > linux > linux-raspberrypi > ₹ 0001-add-temp-sensor.patch
      From aa03181c9737c71592b90a242dcfa4626b3e3875 Mon Sep 17 00:00:00 2001
      From: Moatasem-Elsayed <eng.moatasem.8@gmail.com>
      Date: Sat. 10 Feb 2024 21:58:26 +0200
      Subject: [PATCH] add temp sensor
       arch/arm/boot/dts/bcm2710-rpi-3-b-plus.dts | 5 +++++
       1 file changed, 5 insertions(+)
      diff --qit a/arch/arm/boot/dts/bcm2710-rpi-3-b-plus.dts b/arch/arm/boot/dts/bcm2710-rpi-3-b-plus
      index 4e4e47100831..d800e15fa72b 100644
      --- a/arch/arm/boot/dts/bcm2710-rpi-3-b-plus.dts
      +++ b/arch/arm/boot/dts/bcm2710-rpi-3-b-plus.dts
      @@ -136,6 +136,11 @@
          pinctrl-names = "default";
          pinctrl-0 = <&i2c1 pins>;
           clock-frequency = <100000>;
     + status = "okay";
          temp-sensor@5a {
               compatible = "melexis,mlx90614";
               req = <0x5a>;
       &i2c2
```

Application



Sequence Diagram



FileHandler

```
mespace live monitor {
oublic:
 FileHandler(std::string filepath);
                                                           date :Sat Feb 10 10:58:06 PM EET 2024
 std::string read();
 bool isfileActive();
private:
                                                       13 #include <filesystem>
std::string m filepath;
                                                           #include <fstream>
                                                           #include <iostream>
                                                           #include <unistd.h>
                                                       18  namespace live monitor {
                                                       19 FileHandler::FileHandler(std::string filepath) : m_filepath(filepath) {
                                                           if (!std::filesystem::exists(p:m filepath)) {
                                                               exit(status: EXIT FAILURE);
                                                           bool FileHandler::isfileActive() {
                                                            if (!std::filesystem::exists(p:m filepath)) {
                                                             return false;
                                                       35 std::string FileHandler::read() {
                                                           std::string result;
                                                             std::ifstream file;
                                                            file.open(s: m filepath);
                                                             file >> result;
                                                             std::cout << "Value:" << result << std::endl;</pre>
                                                             file.close();
                                                              return result;
```

Temperature

```
*/
Mamespace live_monitor {
template <typename T> class Isensor {

public:
    Isensor() = default;
    virtual ~Isensor() = default;
    virtual bool enable() = 0;
    virtual bool disable() = 0;
    virtual bool isactive() = 0;
    virtual T readvalue() = 0;
};
} // namespace live_monitor
```

```
13 #include "FileHandler.hpp"
#include "FileHandler.hpp"
#include "Isensor.hpp"
                                                        14 #include <iostream>
#include <memorv>
                                                        15 #include <memory>
namespace live monitor {
                                                            #include <string>
constexpr const char *PATH =
"/sys/class/i2c-dev/i2c-1/device/1-005a/iio:device
                                                        18  namespace live monitor {
class Temperature : public Isensor<double> {
                                                                : m filehandler(std::make unique<FileHandler>(filepath: PATH)) {}
                                                        22 bool Temperature::enable() {
                                                             if (m filehandler->isfileActive()) {
 bool disable() override;
                                                                m activation = false;
                                                              return m activation;
 bool m activation;
 std::unique ptr<FileHandler> m filehandler;
                                                            bool Temperature::isactive() { return m activation; }
 double m lastValue;
                                                            double Temperature::readvalue() {
// namespace live monitor
                                                              if (m activation) {
                                                               std::string result = m filehandler->read();
                                                                m lastValue = std::stod(str: result);
                                                                std::cout << "[warning] the sensor is not enabled " << std::endl;</pre>
                                                              return (m lastValue * 0.02 - 273);
                                                        45 bool Temperature::disable() {
                                                              m activation = false;
```

```
25 namespace live monitor {
#include <cstdint>
                                                          26 ServerHandler::ServerHandler(std::string ip, uint16 t port)
#include <functional>
                                                                   : ip(ip), port(port) {}
#include <string>
#include <thread>
                                                                 start thread = false;
namespace live monitor {
                                                                if (t.joinable()) {
class ServerHandler {
                                                                 close(fd: serverSocket);
  ServerHandler(std::string ip, uint16 t port);
                                                               bool ServerHandler::Start(std::function<std::string()> callback) {
  bool Start(std::function<std::string()> callback);
                                                                 bool status = false:
 bool Stop();
                                                                 signal(sig: SIGINT, handler: [](int signal)-> void { exit(status: 0); });
  bool Reload();
                                                                 serverSocket = socket(domain: AF INET, type: SOCK STREAM, protocol: 0);
                                                                 if (serverSocket == -1) {
 uint16 t port;
                                                                   exit(status: EXIT FAILURE):
  std::string ip;
 std::thread t;
                                                                 sockaddr in address{
  bool start thread = false;
                                                                     .sin family = AF INET,
  int serverSocket = 0;
                                                                     .sin port = htons(hostshort: port),
                                                                     .sin addr{.s addr = INADDR ANY},
                                                                 if (bind(fd: serverSocket, addr: reinterpret cast<sockaddr *>(&address),
                                                                         len: sizeof(address)) == -1) {
                                                                   perror(s: "bind failed");
                                                                 if (listen(fd: serverSocket, n: 10) == -1) {
                                                                  perror(s: "listen failed"):
                                                                 std::cout << "Server listening on Ip:Port " << ip << port << std::endl;</pre>
                                                                   std::cout << "Thread for server will launch now " << std::endl;</pre>
                                                                   start thread = true;
                                                                   while (start thread) {
                                                                     sockaddr in clientAddr:
                                                                     socklen t clientAddrLen = sizeof(clientAddr):
                                                                     int clientSocket =
                                                                         accept(fd: serverSocket. addr: (struct sockaddr *)&clientAddr. addr len: &clientAddrLe
                                                                     if (clientSocket == -1) {
                                                                       std::cerr << "Error accepting connection" << std::endl:</pre>
                                                                     char httprequest[1024];
                                                                     ssize t bytesRead = read(fd: clientSocket, buf: httprequest, nbytes: sizeof(httprequest));
                                                                     std::cout << "Request from address:" << inet ntoa(in: clientAddr.sin addr)</pre>
                                                                               << httprequest << std::endl;</pre>
                                                                     std::string body = callback();
```

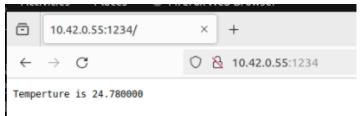
Server

```
// Send a response back to the client
std::string body = callback();
write(fd:clientSocket, buf: body.c_str(), n: body.length());
std::this thread::sleep_for(rtime: std::chrono::seconds(rep: 1));
close(fd:clientSocket);
}// Close the client socket
});
return status;
// namespace live_monitor
```

main

Please implement Manager and startup recipe

```
int main() {
 live monitor::Temperature test;
  live monitor::ServerHandler server(ip: std::string(s: "10.42.0.55"), port: 1234);
 test.enable();
  double temp = test.readvalue();
  server.Start(callback: [&temp]()-> std::string {
    std::string result =
        "Temperture is " + std::to string(val: temp) + std::string(s: " ");
    return result;
 });
 while (1) {
    temp = test.readvalue();
    std::this thread::sleep for(rtime: std::chrono::seconds(rep: 1));
  return 0;
```



End