

Documentation

Implemented classes :

```
1- class matrix
{
public:
double arr[5][5];
int row;
int col;};
```

used operator overloading to assign and sum 2 matrices

```
2 - class particle
{
public:
    matrix position1; // 5 x 2
    matrix position2; // 2 x 5
    matrix best_pos1; // 5 x 2
    matrix best_pos2; // 2 x 5
    matrix velocity1; // 5 x 2
    matrix velocity2; // 2 x 5
};
```

Note:

I didn't put all particle's elements in one matrix. I divided them into 2 matrices and the number of elements of the particle is the same and the same goes for the velocity matrices

important functions

- `particle Optimize_Particles(int dimensions):`

it contains the entire algorithm. (I advice you to take a look at it first)

- `void update_velocity(particle& P):`
updated velocity matrices using the formula

$$\mathbf{v}_i \leftarrow \omega \mathbf{v}_i + \phi_p r_p (\mathbf{p}_i - \mathbf{x}_i) + \phi_g r_g (\mathbf{g} - \mathbf{x}_i)$$

$\omega = 1$, r_p and r_g are random numbers in $[0,1)$, $\phi_p = \phi_g = 2$

- `double cost_function(matrix X1, matrix X2):`
using the square mean square error

$$\text{RMSD} = \sqrt{\frac{\sum_{t=1}^n (\hat{\mathbf{y}}_t - \mathbf{y}_t)^2}{n}}.$$

- `void generate_random_and_assign(particle&P,string choice,int dimension):`
this function generates random values and assign it to either the velocity matrices or the position matrices in a particle.

Random values generated according to normal distribution with mean = 0 , variance = 0.1