# Agenda



Basic Linear Series Regulators

Basic Linear Shunt Regulators

Intro. to Switching Regulators

**IC Voltage Regulator** 





# Intro.

- Two basic categories of voltage regulation are:
  - Line regulation
  - Load regulation
- The purpose of line regulation is to maintain a nearly constant output voltage when the input voltage varies.
- The purpose of load regulation is to maintain a nearly constant output voltage when the load varies.





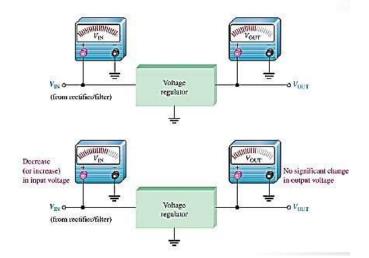
# Line Regulation

- When the ac input (line) voltage of a power supply changes, an electronic circuit called a regulator maintains a nearly constant output voltage.
- Line regulation can be defined as the percentage change in the output voltage for a given change in the input voltage

$$Line regulation = \left(\frac{\Delta V_{\text{OUT}}}{\Delta V_{\text{IN}}}\right) 100 \%$$

 Line regulation can also be expressed in units of %/V

$$\text{Line regulation } = \frac{(\Delta V_{\text{OUT}}/V_{\text{OUT}})100\%}{\Delta V_{\text{IN}}}$$

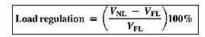




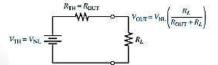


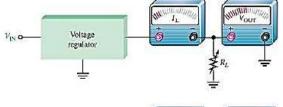
# Load Regulation

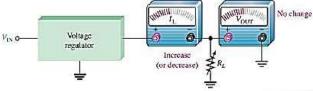
- Load regulation can be defined as the percentage change in output voltage for a given change in load current.
- One way to express load regulation is as a percentage change in output voltage from no-load (NL) to full-load (FL).

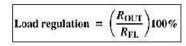


- The load regulation can be expressed as a percentage change in output voltage for each mA change in load current.
- Using R<sub>OUT</sub>, Thevenin equivalent circuit for a power supply with a load resistor.













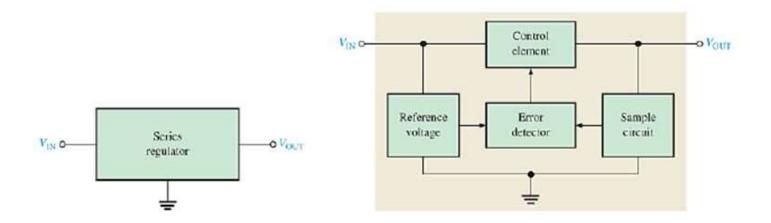
# **Types of Voltage Regulators:**

- Series Voltage Regulator
- Shunt Voltage Regulator
  - Switching Regulator





# 1. Series Voltage Regulator



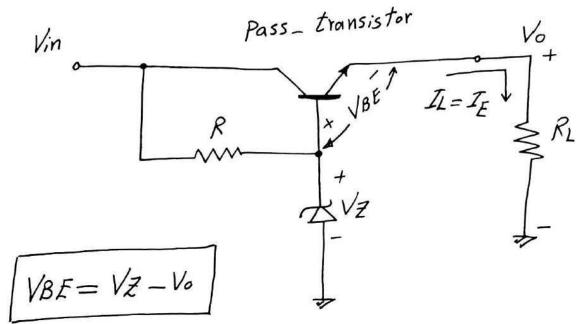
Block Diagram of Series Regulator





- As Vo increased, the comparator circuit compares Vo with a reference voltage and since there a deference, generates a control signal to the control element to reduce Vo till Vo reaches the reference voltage and vice-versa.
- Series regulator
   The control element is connected in series
   between Vo and Vin.

### (a) Transistor Voltage Regulator:







\* As Vo decreased, VBE increased So, IB increased

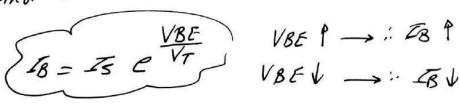
and IE Asso increased but Vo = IZ. RL

so, Vo increased again.

\* As Vo increased, VBE decreased so, ZB

decreased and Also ZE decreased, ZE=ZL

and Vo = ZL.RL decreased again.







#### **Example:**

$$V_{in} = 20V$$

$$Z_{in} = 20V$$

$$R Z_{i} Z_{in} + V_{in} = Z_{in} + V_{in} + V_{in} = Z_{in} + V_{in} = Z_{in} + V_{in} = Z_{in} + V_{in} =$$

$$V_0 = V_Z - V_B E = 12 - 0.65$$
  
 $V_0 = 11.35 V$ 

$$V_{in} = V_{CE} + V_{o}$$

$$V_{CE} = V_{in} - V_{o} = V_{C} - V_{E}$$

$$V_{o} = V_{o} + V_{o} = V_{o} + V_{o}$$

$$V_{o} = V_{o} + V_{o} V_{o} + V_{o} + V_{o} = V_{o} + V_{o} +$$

$$= 20 - 11.35$$

$$V(E = 8.65V) (Not V(E) 0.7V : Active)$$

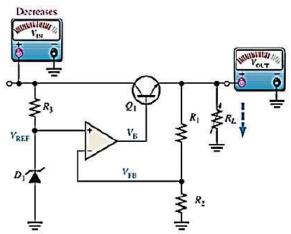
$$mode$$





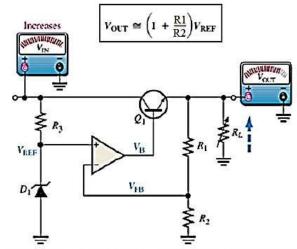
### (c) Op-Amp series Regulator

 Illustration of series regulator action that keeps V<sub>OUT</sub> constant when V<sub>IN</sub> or R<sub>L</sub> changes.



(a) When V<sub>IN</sub> or R<sub>L</sub> decreases, V<sub>OUT</sub> attempts to decrease. The feedback voltage, V<sub>FB</sub>, also attempts to decrease, and as a result, the op-amp's cotput voltage V<sub>B</sub> attempts to increase, thus compensating for the attempted decrease in V<sub>OUT</sub> by increasing the Q<sub>1</sub> emitter voltage. Changes in V<sub>OUT</sub> are exaggerated for illustration.

When  $V_{\rm IN}$  (or  $R_I$ ) stabilizes at its new lower value, the voltages return to their original values, thus keeping  $V_{\rm OUT}$  constant as a result of the negative feedback.

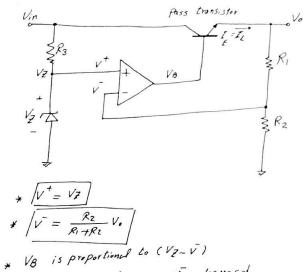


(b) When V<sub>IN</sub> or R<sub>L</sub> increases, V<sub>OUT</sub> attempts to increase. The feedback voltage, V<sub>FB</sub>, also attempts to increase, and as a result, V<sub>B</sub>, applied to the base of the control transistor, attempts to decrease, thus compensating for the attempted increase in V<sub>OUT</sub> by decreasing the Q<sub>1</sub> emitter voltage.

When  $V_{\rm IN}$  (or  $R_{\rm c}$ ) stabilizes at its new higher value, the voltages return to their original values, thus keeping  $V_{\rm OUT}$  constant as a result of the negative feedback.







\* As Vo decreased : V decreased

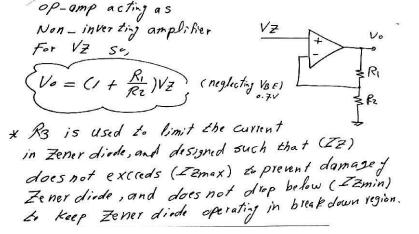
: (VZ-V) Increased : VB Increased

Se, IE(IL) is Increased : Vo Increased

\* As Vo Increased wir V increased and
then, (VZ-V) was decreased in VB decreased

. IE (II) Lechord

i Vo decreased.





#### Example:

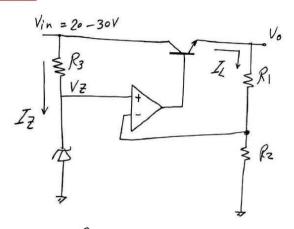
Design a series Regulator using op-amp and a 6-V Zener diode to maintain a regulated output of 18V.

Assuming that the unregulated input varies between 20V and 30V and the current through the Zener-diode must be at Least 20 MA to keep; t in its breakdown region.





### **Solution:**



\* 
$$V_0 \stackrel{\sim}{=} (1 + \frac{R_1}{R_2}) V_{\overline{Z}}$$
  
 $18 = (1 + \frac{R_1}{R_2}) 6$ 

$$I + \frac{R_1}{R_2} = 3 \Rightarrow \frac{R_1}{R_2} = 2$$

$$Let \quad \begin{cases} R_2 = lo \, k \, \Omega \\ R_1 = 2 \, o \, k \, \Omega \end{cases}$$

$$\vdots \quad R_1 = \frac{V_{in} - V_2}{R_3} \quad , \quad I_{2min} = \frac{V_{in}(m_{in}) - V_2}{R_3}$$

$$\vdots \quad 20 \, mA = \frac{20 - 6}{R_3}$$

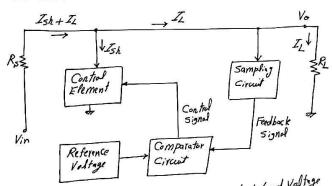
$$R_3 = \frac{20 - 6}{20 \, mA} = 0.7 \, k \, \Omega$$

$$\begin{cases} R_3 = 0.7 \, k \, \Omega = 700.52 \end{cases}$$



# 2. Shunt Voltage Regulator

#### Block-diagram



\* The Control element maintains a constant Lord Vallage by Shunting more or less current from the Load.

\* Control element acts as a Valiable resistance.

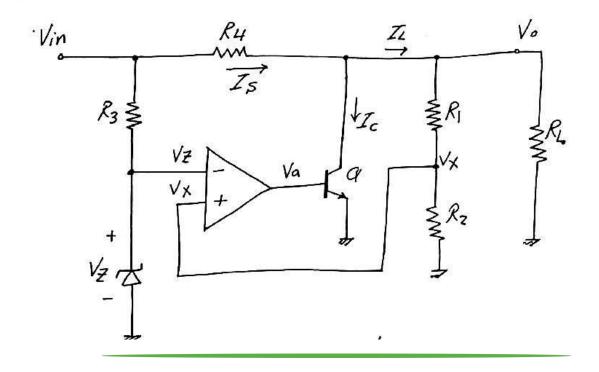
When the Load Voltage decreases, resistance of Control

When the Load Voltage decreases, resistance or control the lement increases so that less current is diverted from the Load So, IL increased, increasing Vo again and vice - versa.





# **Op-Amp Shunt Regulator**



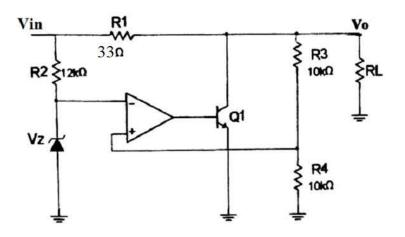




\* Ri and Rz acts as a Voltage divider  $VX = \frac{R_2}{R_1 + R_2} V_0$ \* Va = A(Vx - Vz), A = op-amp gain \* As Vo incleased > : Vx increased : Va increased : BJT (4) Conduct heavly and draws much current from Is So, Zz decreased : Vo decreased. \* As Vo decreased (Lower than VZ), Va = - we value : BJT will be off ( Zc = 0) so, more current is driven into the Load \* short circuit current Is.c = Vin | as Vo=0

### **Example:**

The circuit shown in Figure represents a voltage regulator.



- 1. What is the type of this regulator?
- 2. What is the power rating must  $R_1$  have if the maximum input voltage is 18V?





### **Solution:**

- What is the type of this regulator?
   Shunt Regulator
- 2. What is the power rating must R<sub>1</sub> have if the maximum input voltage is 12.5 V?

what is the power rating mass 
$$R_1$$
 have it the maximum input voltage is  $12.5 \text{ V}$ ?

$$V_0 = 0$$

$$E_1 = I_5 \cdot c = \frac{V_{in-6}}{R_1} = \frac{18}{33} = 0.54545A$$

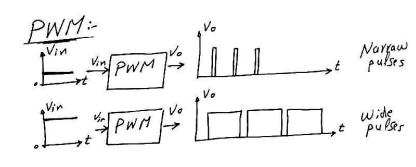
$$\frac{R_1 = I_{SC}R_1}{R_1 = 9.82 \text{ Walts}}$$





# 3. Switching Regulator

\* The main disadvantage of scries and shunt \* The Control element must dissipate Regulators:-Large amount of power in order for the transistor to operate in its active region (Low power efficiency). \* Switching Regulators \* The control element is switched on and o FF at a rapid rate and is therefore either in saturation or cut-off modes So, very Low power Consumption is obtained. \* The Fundamental Component in switching Regulators is the pulse width modulator [PWM] that produces a train of pulses having widths that are proportional to the device input.



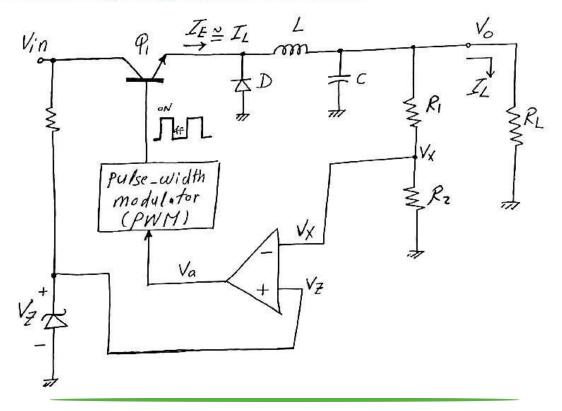


 $Vd.c = VH(\frac{TH}{T})$  Average (d.c) value of pulse train \* The switching Regulator uses a pulse-width modulator (PWM) to produce a pulse train whose duty cycle is automatically adjusted as ness necessary to increase or decrease the d.c Value of the train

Note:- $Vd.c = \frac{1}{7} \int_{0}^{TH} VH.dt$   $= \frac{VH}{7} \left[ t \right]_{0}^{TH}$   $= \frac{VH}{7} \left( \frac{TH}{7} - 0 \right)$   $\left[ Vd.c = VH. \frac{TH}{7} \right]$ 



# **Switching Regulator Circuit:**







\* The Zener diode provides the reference voltage (VZ) to the op-amp that compared with (VX) obtained from the Voltage divider Ri and Rz. \* As Vo decleases, VX decleases

: (Vz-Vx) increased i Va incleased >> pulse-width incleased

(TH increased) >: Vd.c increased

: Q, conduct more current and increasing

IE(≅ IL) : Vo Increased.

\* As Vo increased > Vx increased > :(VZ-VX) decimed

: Va decreased >> Vd.c decreased

: 9, conducts Less current po ZECZUI " Vo decreased.

Aductor (L) and Capacitar (c) acting as Low pass Filter (LPF) that recovers the d.c Value of the pulse wave form supplied by Q1.

(removing Harmonics).

L. Diode > supless the negative Voltage transient (catcher) generated by the inductor when 9, off diode





#### Example:

Aswitching Regulator is designed to maintain 12 V-d.c output when the unregulated input voltage Vasies from 15V to 24V. VCECsaturation of Qis 0.5V Assuming that the Load is constant, Find Assuming that maximum duty cycle of PWM.

Sol.  

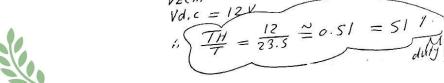
$$V_{in} = 15V (minimum)$$

$$V_{in} = 15V$$

$$Vd.c = VH. \frac{TH}{T} \rightarrow \frac{TH}{T} = \frac{Vd.c}{VH} = \frac{12}{14.5}$$

$$\frac{TH}{T} = 0.828 = 82.8 \% \frac{m coh.}{duty cycle}$$

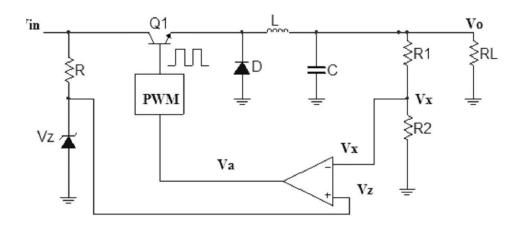
\* 
$$Vin = 24V \ (maximum)$$
 $VECH = 24 - 0.5 = 23.5V$ 
 $Vd.c = 12V$ 
 $Vd.c = 12V$ 
 $Vd.c = 12V$ 





#### **Example:**

A regulator circuit is shown in Figure:



- 1. What is the type of this regulator?
- 2. What are the functions of Diode (D), inductor (L) and capacitor (C)?
- 3. If this regulator is designed to maintain 12 V-DC output when the unregulated input voltage varies from 15V to 24V, V<sub>CE</sub>(saturation) of Q1 is 0.2V and assuming that the load is constant, Calculate the Minimum and Maximum Duty cycle of the PWM.





### **Solution:**

- 1. What is the type of this regulator? Switching Regulator.
- 2. What are the functions of Diode (D), inductor (L) and capacitor (C)?

  Diode supress regative Voltage Transient generated by
  inductor when Qi . F.F.

  (L, C) Low pars Filter to recover the d.c Valued the pulse
  waveform supplied by Qi (remove Harmonics).
- If this regulator is designed to maintain 12 V-DC output when the unregulated input voltage varies from 15V to 24V, V<sub>CE</sub>(saturation) of Q1 is 0.2V and assuming that the load is constant, Calculate the Minimum and Maximum Duty cycle of the PWM.

\* 
$$Vin = 15V (Minimum)$$
 $Vo(d \cdot c) = 12V$ 
 $VE(H) = Vin - VcE(sa + 1)$ 
 $VE(H) = 15 - 0.2 = 14.8V$ 
 $Vd \cdot c = VH \cdot \frac{TH}{T}$ 

$$TH = D = \frac{Vd \cdot c}{VH}$$

$$D(Max) = \frac{Vd \cdot c}{VHmin} = \frac{12}{14.8}$$

$$D(Max) = 0.8108$$

$$= 81.08 \%$$

$$V_{in} = 24V (maximum)$$

$$V_{E}(H) = 24 - 0.2 = 23.8V$$

$$V_{d.c} = 12V$$

$$D(min) = \frac{V_{d.c}}{V_{E}Hn} = \frac{12}{23.8}$$

$$D(min) = 0.5642$$

$$= 50.42 \text{ } / .$$





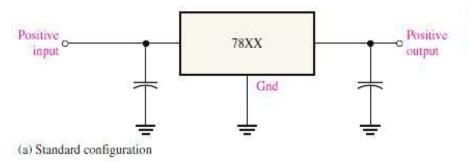
## 4. Integrated Circuit Voltage Regulator

### Fixed Positive Linear Voltage Regulators

Although many types of IC regulators are available, the 78XX series of IC regulators is representative of three-terminal devices that provide a fixed positive output voltage. The three terminals are input, output, and ground as indicated in the standard fixed voltage configuration in Figure 17–26(a). The last two digits in the part number designate the output voltage. For example, the 7805 is a +5.0 V regulator. For any given regulator, the output voltage can be as much as  $\pm 4\%$  of the nominal output. Thus, a 7805 may have an output from 4.8 V to 5.2 V but will remain constant in that range. Other available output voltages are given in Figure 17–26(b) and common packages are shown in part (c).

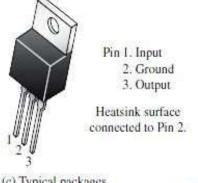






Type number	Output voltage
7805	+5.0 V
7806	+6.0 V
7808	+8.0 V
7809	+9.0 V
7812	+12.0 V
7815	+15.0 V
7818	+18.0 V
7824	+24.0 V

(b) The 78XX series





Heatsink surface (shown as terminal 4 in case outline drawing) is connected to Pin 2.





The 78XX series three-terminal fixed positive voltage regulators.





Capacitors, although not always necessary, are sometimes used on the input and output as indicated in Figure 17–26(a). The output capacitor acts basically as a line filter to improve transient response. The input capacitor filters the input and prevents unwanted oscillations when the regulator is some distance from the power supply filter such that the line has a significant inductance.

The 78XX series can produce output currents up to in excess of 1 A when used with an adequate heat sink. The input voltage must be approximately 2.5 V above the output voltage in order to maintain regulation. The circuits have internal thermal overload protection and short-circuit current-limiting features. **Thermal overload** occurs when the internal

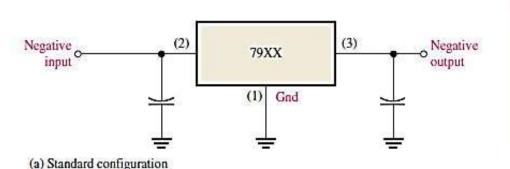
power dissipation becomes excessive and the temperature of the device exceeds a certain value. Almost all applications of regulators require that the device be secured to a heat sink to prevent thermal overload.





#### **Fixed Negative Linear Voltage Regulators**

The 79XX series is typical of three-terminal IC regulators that provide a fixed negative output voltage. This series is the negative-voltage counterpart of the 78XX series and shares most of the same features and characteristics except the pin numbers are different than the positive regulators. Figure 17–27 indicates the standard configuration and part numbers with corresponding output voltages that are available.



Type number	Output voltage
7905	-5.0 V
7905.2	-5.2 V
7906	-6.0 V
7908	-8.0 V
7912	-12.0 V
7915	-15.0 V
7918	−18.0 V
7924	-24.0 V

(b) The 79XX series

#### ▲ FIGURE 17-27

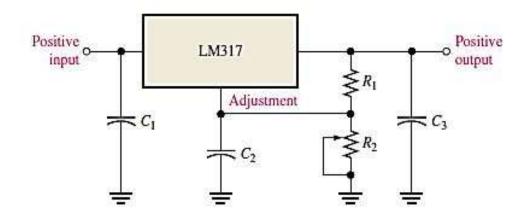
The 79XX series three-terminal fixed negative voltage regulators.





### Adjustable Positive Linear Voltage Regulators

The LM317 is an example of a three-terminal positive regulator with an adjustable output voltage. The standard configuration is shown in Figure 17–28. The capacitors are for decoupling and do not affect the dc operation. Notice that there is an input, an output, and an adjustment terminal. The external fixed resistor  $R_1$  and the external variable resistor  $R_2$  provide the output voltage adjustment.  $V_{\text{OUT}}$  can be varied from 1.2 V to 37 V depending on the resistor values. The LM317 can provide over 1.5 A of output current to a load.







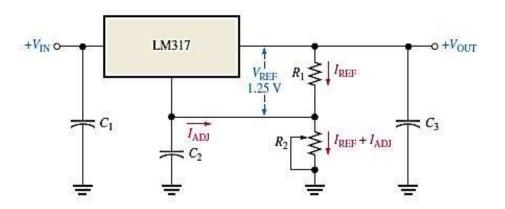
The LM317 is operated as a "floating" regulator because the adjustment terminal is not connected to ground, but floats to whatever voltage is across  $R_2$ . This allows the output voltage to be much higher than that of a fixed-voltage regulator.

**Basic Operation** As indicated in Figure 17–29, a constant 1.25 V reference voltage ( $V_{\text{REF}}$ ) is maintained by the regulator between the output terminal and the adjustment terminal. This constant reference voltage produces a constant current ( $I_{\text{REF}}$ ) through  $R_1$ , regardless of the value of  $R_2$ .  $I_{\text{REF}}$  is also through  $R_2$ .

$$I_{\text{REF}} = \frac{V_{\text{REF}}}{R_1} = \frac{1.25 \text{ V}}{R_1}$$







There is a very small constant current at the adjustment terminal of approximately  $50 \,\mu\text{A}$  called  $I_{\text{ADJ}}$ , which is through  $R_2$ . A formula for the output voltage is developed as follows.

$$\begin{split} V_{\rm OUT} &= V_{R1} + V_{R2} = I_{\rm REF} R_1 + I_{\rm REF} R_2 + I_{\rm ADJ} R_2 \\ &= I_{\rm REF} (R_1 + R_2) + I_{\rm ADJ} R_2 = \frac{V_{\rm REF}}{R_1} (R_1 + R_2) + I_{\rm ADJ} R_2 \\ V_{\rm OUT} &= V_{\rm REF} \bigg( 1 + \frac{R_2}{R_1} \bigg) + I_{\rm ADJ} R_2 \end{split}$$

As you can see, the output voltage is a function of both  $R_1$  and  $R_2$ . Once the value of  $R_1$  is set, the output voltage is adjusted by varying  $R_2$ .

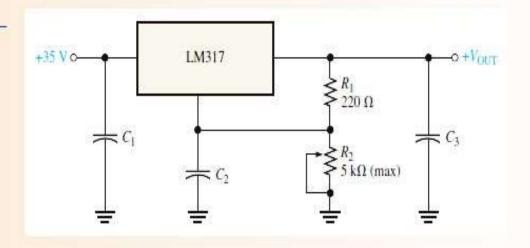




#### EXAMPLE 17-6

Determine the minimum and maximum output voltages for the voltage regulator in Figure 17–30. Assume  $I_{ADJ} = 50 \,\mu\text{A}$ .

#### FIGURE 17-30







#### Solution

$$V_{R1} = V_{REF} = 1.25 \text{ V}$$

When  $R_2$  is set at its minimum of  $0 \Omega$ ,

$$V_{\text{OUT(min)}} = V_{\text{REF}} \left( 1 + \frac{R_2}{R_1} \right) + I_{\text{ADJ}} R_2 = 1.25 \text{ V}(1) = 1.25 \text{ V}$$

When  $R_2$  is set at its maximum of  $5 k\Omega$ ,

$$V_{\text{OUT(max)}} = V_{\text{REF}} \left( 1 + \frac{R_2}{R_1} \right) + I_{\text{ADJ}} R_2 = 1.25 \text{ V} \left( 1 + \frac{5 \text{ k}\Omega}{220 \Omega} \right) + (50 \mu\text{A}) 5 \text{ k}\Omega$$
$$= 29.66 \text{ V} + 0.25 \text{ V} = 29.9 \text{ V}$$



