### **LED Sequence V2.0 Design**

#### **Outline**

This document shows a design of an application that uses ATmega32 to control some LEDs lighting sequence according to button pressing.

#### **Hardware Requirements:**

- Four LEDs (LED0, LED1, LED2, LED3)
- One button (BUTTON0)

#### **Software Requirements:**

- 1. Initially, all LEDs are OFF
- 2. Once BUTTON0 is pressed, LED0 will be ON
- 3. Each press further will make another LED is ON
- 4. At the fifth press, LED0 will changed to be OFF
- 5. Each press further will make only one LED is OFF
- 6. This will be repeated forever
- 7. The sequence is described below
  - a. Initially (OFF, OFF, OFF, OFF) f. Press 5 (OFF, ON, ON, ON)
  - b. Press 1 (ON, OFF, OFF, OFF)
  - c. Press 2 (ON, ON, OFF, OFF)
  - d. Press 3 (ON, ON, ON, OFF)
  - e. Press 4 (ON, ON, ON, ON)

- g. Press 6 (OFF, OFF, ON, ON)
- h. Press 7 (OFF, OFF, OFF, ON)
- i. Press 8 (OFF, OFF, OFF, OFF)
- j. Press 9 (ON, OFF, OFF, OFF)

8. Use External Interrupts

### State Machine Diagram

### Definition

A state machine diagram (Figure 1) models the behavior of a single object, specifying the sequence of events that an object goes through during its lifetime in response to events.

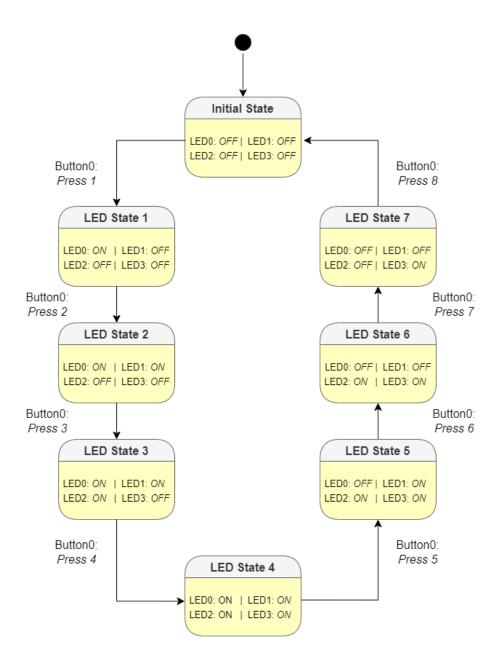


Figure 1. State Machine Diagram

### **Layered Architecture**

#### Definition

Layered Architecture (Figure 2) describes an architectural pattern composed of several separate horizontal layers that function together as a single unit of software.

*Microcontroller Abstraction Layer* (*MCAL*) is a software module that directly accesses on-chip MCU peripheral modules and external devices that are mapped to memory, and makes the upper software layer independent of the MCU.

Hardware Abstraction Layer (HAL) is a layer of programming that allows a computer OS to interact with a hardware device at a general or abstract level rather than at a detailed hardware level.

### Design

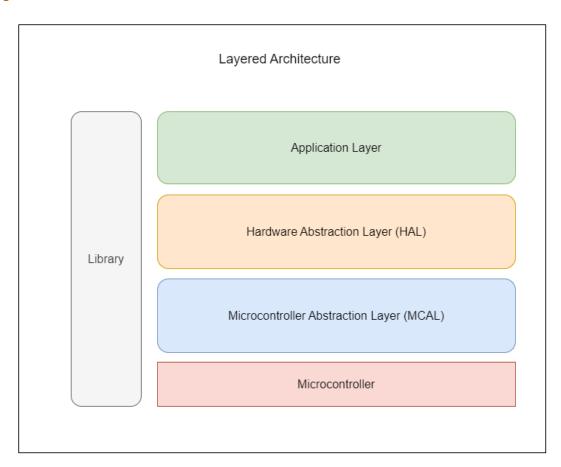


Figure 2. Layered Architecture Design

## **System Modules**

### Definition

A *Module* is a distinct assembly of components that can be easily added, removed or replaced in a larger system. Generally, a *Module* is not functional on its own.

In computer hardware, a *Module* is a component that is designed for easy replacement.

## Design

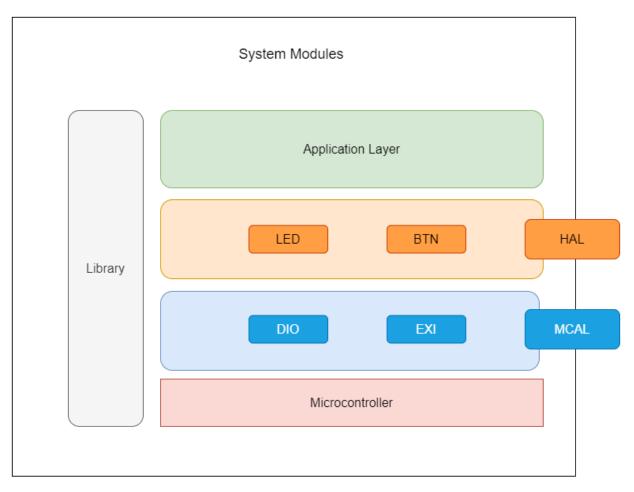


Figure 3. System Modules Design

### Application Programming Interfaces (APIs)

#### Definition

An *API* is an *Application Programming Interface* that defines a set of *routines*, *protocols* and *tools* for creating an application. An *API* defines the high level interface of the behavior and capabilities of the component and its inputs and outputs.

An *API* should be created so that it is generic and implementation independent. This allows for the API to be used in multiple applications with changes only to the implementation of the API and not the general interface or behavior.

#### MCAL APIs

#### A. DIO APIS

vd DIO\_vdInitialization (void)

Name: DIO vdInitialization

*Input*: void *Output*: void

Description: Function to initialize DIO peripheral.

u8 DIO\_u8SetPinDirection (u8 Cpy\_u8PortId, u8 Cpy\_u8PinId, u8 Cpy\_u8PinDirection)

Name: DIO u8SetPinDirection

Input: u8 Portld, u8 Pinld, and u8 PinDirection

Output: u8 Error or No Error

Description: Function to set Pin direction.

u8 DIO\_u8SetPinValue (u8 Cpy\_u8PortId, u8 Cpy\_u8PinId, u8 Cpy\_u8PinValue)

Name: DIO u8SetPinValue

Input: u8 PortId, u8 PinId, and u8 PinValue

Output: u8 Error or No Error

**Description**: Function to set Pin value.

u8 DIO\_u8GetPinValue (u8 Cpy\_u8PortId, u8 Cpy\_u8PinId, u8 \*Cpy\_pu8ReturnedPinValue)

Name: DIO\_u8GetPinValue

Input: u8 Portld, u8 PinId, and Pointer to u8 ReturnedPinValue

Output: u8 Error or No Error

**Description**: Function to get Pin value.

#### u8 DIO u8TogglePinValue (u8 Cpy u8PortId, u8 Cpy u8PinId)

Name: DIO\_u8TogglePinValue Input: u8 Portld and u8 PinId Output: u8 Error or No Error

Description: Function to toggle Pin value.

#### B. EXI APIS

### u8 EXI u8EnablePIE (u8 Cpy u8InterruptId, u8 Cpy u8SenseControl)

Name: EXI u8EnablePIE

Input: u8 InterruptId and u8 SenseControl

Output: u8 Error or No Error

**Description**: Function to enable and configure Peripheral Interrupt Enable (PIE), by setting relevant bit for each interrupt in GICR register, then configuring Sense Control in MCUCR (case interrupt 0 or 1) or MCUCSR (case interrupt 2) registers.

#### u8 EXI u8DisablePIE (u8 Cpy u8InterruptId)

Name: EXI\_u8DisablePIE

Input: u8 InterruptId

Output: u8 Error or No Error

Description: Function to disable Peripheral Interrupt Enable (PIE), by clearing

relevant bits for each interrupt in GICR register.

u8 EXI\_u8INTSetCallBack (u8 Cpy\_u8InterruptId, void (\*Cpy\_pfINTInterruptAction) (void))

Name: EXI\_u8SetCallBack

Input: u8 InterruptId and Pointer to Function that takes void and returns void

Output: u8 Error or No Error

**Description**: Function to receive an address of a function (in APP Layer) to be called back in ISR function of the passed Interrupt (InterruptId), the address is passed through a pointer to function (INTInterruptAction), and then pass this address to ISR function.

#### **HAL APIs**

### A. LED APIS

### vd LED\_vdInitialization( void )

Name: LED vdInitialization

*Input:* void *Output:* void

Description: Function to initialize LED peripheral, by initializing DIO peripheral.

#### u8 LED u8SetLEDPin (u8 Cpy u8LEDId, u8 Cpy u8Operation)

Name: LED u8SetLEDPin

*Input*: u8 LedId and u8 Operation *Output*: u8 Error or No Error

**Description**: Function to switch LED on, off, or toggle.

### B. BTN APIs

### u8 BTN\_u8GetBTNState (u8 Cpy\_u8BTNId, u8 \*Cpy\_pu8ReturnedBTNState)

Name: BTN u8GetBTNState

Input: u8 BTNId and Pointer to u8 ReturnedBTNState

Output: u8 Error or No Error

**Description**: Function to get BTN state.

# Flowchart Diagram

#### Definition

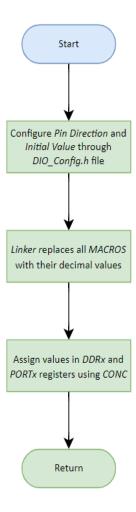
A Flowchart (or Flow Chart) is a diagram that shows the steps in a process.

*Flowcharts* are often used for visualizing the sequence of actions or information needed for training, documenting, planning, and decision-making. They often use symbols, shapes, and arrows to illustrate how one step leads to another.

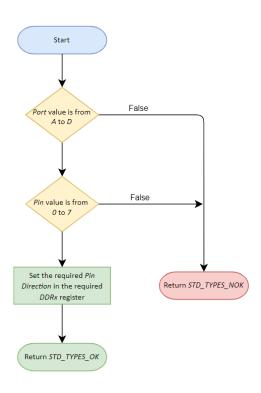
### **MCAL Flowcharts**

#### A. DIO Flowcharts

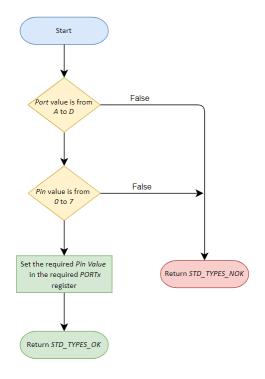
# a. DIO\_vdInitialization



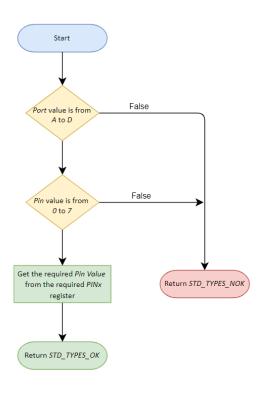
# b. DIO\_u8SetPinDirection



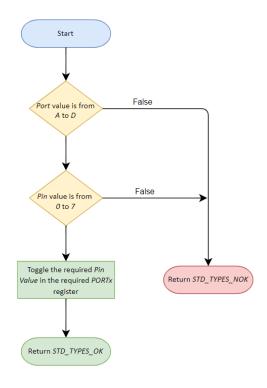
# c. DIO\_u8SetPinValue



# d. DIO\_u8GetPinValue

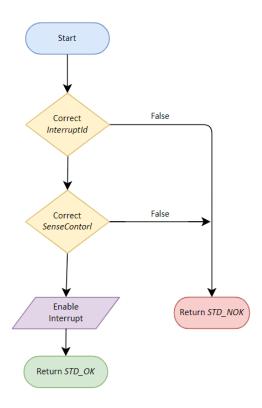


# e. DIO\_u8TogglePinValue

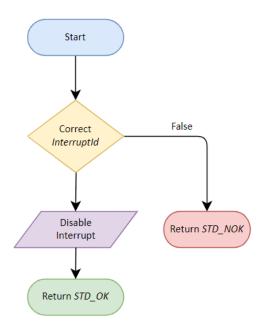


## B. EXI Flowcharts

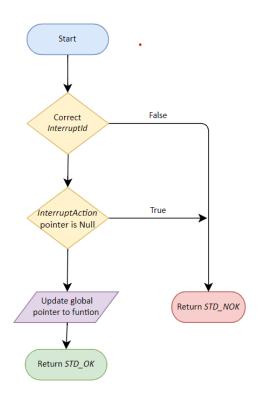
# a. EXI\_u8EnablePIE



# b. EXI\_u8DisablePIE



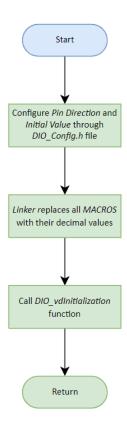
# c. EXI\_u8INTSetCallBack



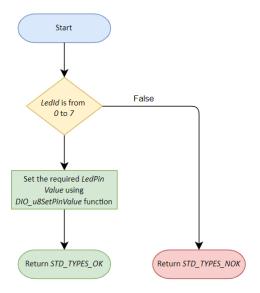
## **HAL Flowcharts**

## A. LED Flowcharts

# a. LED\_vdInitialization

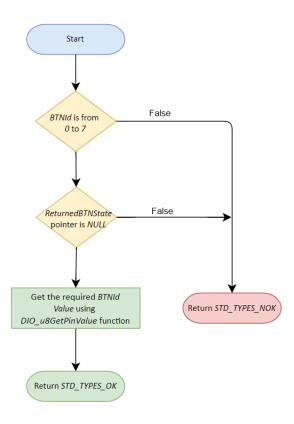


# b. LED\_u8SetLEDPin



## B. BTN Flowcharts

# a. BTN\_u8GetBTNState



#### References:

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- 2. State Machine Diagram UML 2 Tutorial | Sparx Systems
- 3. Layered Architecture | Baeldung on Computer Science
- 4. <u>Microcontroller Abstraction Layer (MCAL) | Renesas</u>
- 5. Hardware Abstraction Layer an overview | ScienceDirect Topics
- 6. What is a module in software, hardware and programming?
- 7. Embedded Basics API's vs HAL's