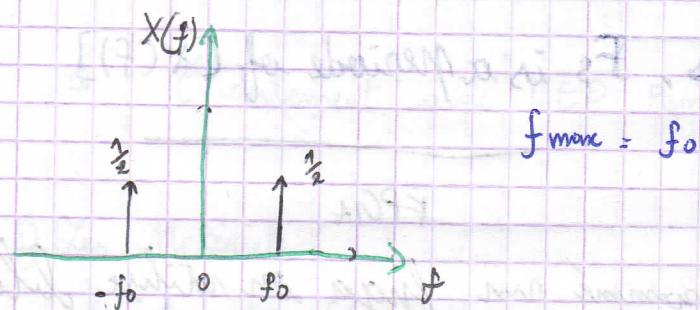


SAP // TAS

EXO 1: $x(t) = \cos(2\pi f_0 t)$ $f_{0, \text{rate}} \leq 0,1$

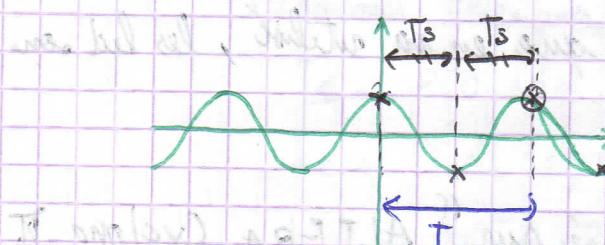
- 1) Sample this signal with respecting the Shannon Condition in order to avoid loosing information
- 2) What is the minimum number of samples that can be used to represent $x(t)$ without loosing information?

1) $x(t) \xrightarrow{\text{FT}} X(f) = \frac{1}{2} [\delta(f-f_0) + \delta(f+f_0)]$



$$T_s \leq \frac{1}{2f_{\max}} \Rightarrow T_s \leq \frac{1}{2f_0}$$

2)



$$T_s \leq \frac{1}{2f_{\max}} \Rightarrow T_s \leq \frac{T}{2}$$

$$T \geq 2T_s$$

2 points

- Fourier transfer

Analog

digital

$$\left\{ \begin{array}{l} x(t) \xrightarrow{\text{FT}} X(f) = \int_{-\infty}^{\infty} x(t) e^{-j2\pi ft} dt \dots (1) \\ X(f) \xrightarrow{\text{IDFT}} x(t) = \int_{-\infty}^{+\infty} X(f) e^{j2\pi ft} dt \dots (2) \end{array} \right.$$

$$\left\{ \begin{array}{l} \text{We transform (1) with Sampling, } x(t) \text{ with } T_s = \text{const} \\ t = n T_s \Rightarrow x(nT_s) \Rightarrow X(f) = \sum_{n=-\infty}^{+\infty} x(nT_s) e^{-j2\pi f n T_s} \end{array} \right.$$

$$\left\{ \begin{array}{l} \text{if } T_s = 1 \\ X(f) = \sum_{n=-\infty}^{+\infty} x(n) e^{-j2\pi f n} \end{array} \right.$$

Exo 2 : Show that $\frac{1}{T_s} = f_s$ is a period of $X(f)$
 " " " $X(f)$ is periodic with $\frac{1}{T_s} = f_s$ if $X(f+f_s) = X(f)$?

f_s = sampling frequency

$$\begin{aligned} X(f) &= \sum x(nT_s) e^{-2\pi j fnT_s} \\ X(f+f_s) &= \sum x(nT_s) e^{-2\pi j (f+f_s)nT_s} \\ &= \sum x(nT_s) e^{-2\pi j fnT_s} \cancel{e^{-2\pi j f_s nT_s}}^{\rightarrow 1} \\ &= \sum x(nT_s) e^{-2\pi j fnT_s} = X(f) \end{aligned}$$

- Yes, f_s is a period of $[X(f)]$

FPGA

Pour programmer un FPGA on utilise Blaster
 et utilise " " comme un esclave
 on utilise Device Drivers

Dans la carte développement que j'en ai utilisé, les LED sont activées en 0,

La carte développement est basée sur "ALTERA Cyclone II
 EP2C8CE144C8N"

VHDL, VERILOG, QUARTUS WEB MB-D

↓ PC

TD1 EXO1

- Etape 1: I) Les besoins fonctionnels

I ₂	I ₁	Commande
0	0	Tous les Led éteints
0	1	LED(1, 3, 5, 7) allumés
1	0	LED(2, 4, 6, 8)
1	1	Clignotement avec LED Pair/Impair ((Temps 500ms))

- Etape 2: II) Les Matériaux

- 1 interrupteur (I₂, I₁)
- 8 LEDs

- Etape 3:

I) Schémas Électriques

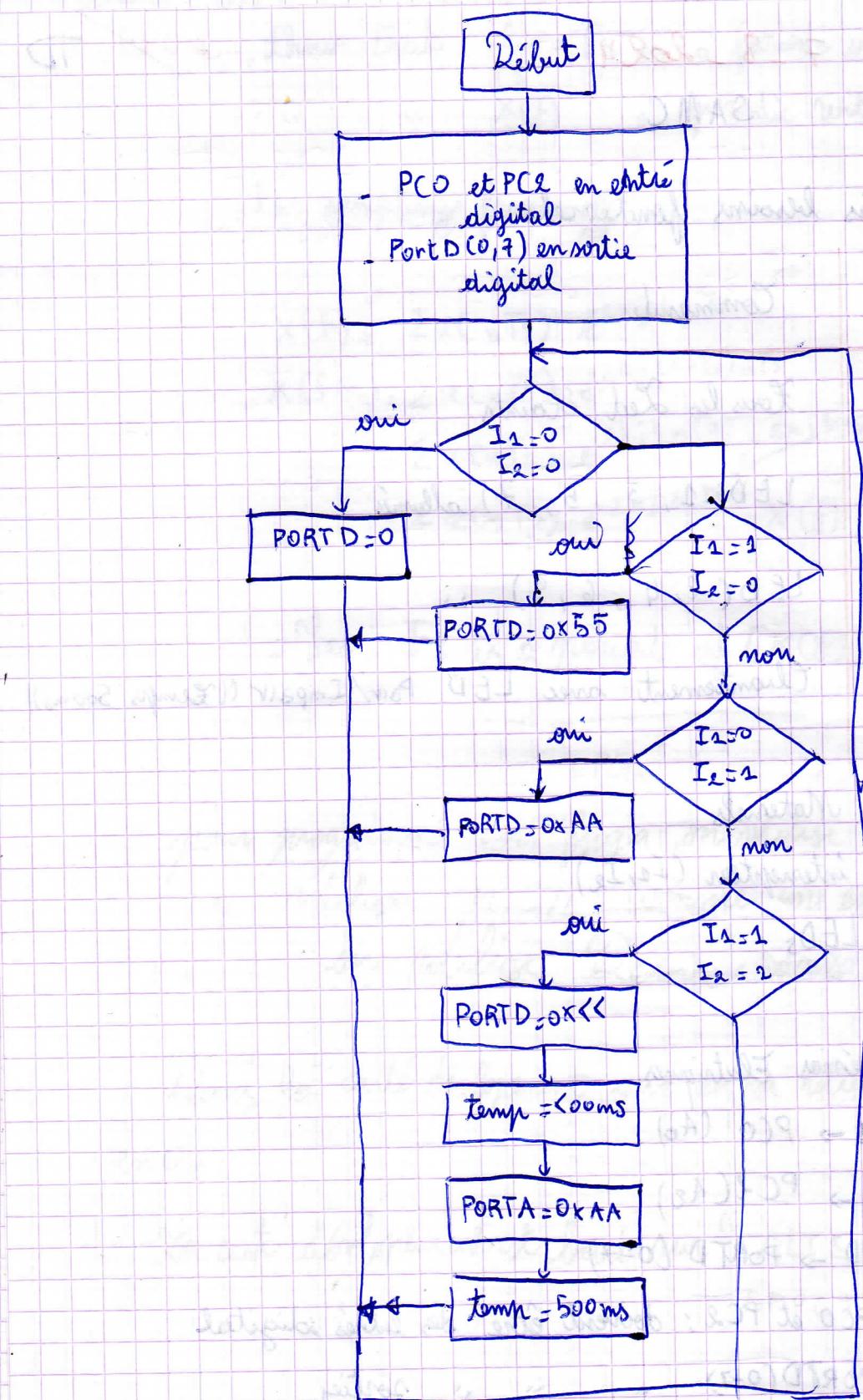
 $I_1 \rightarrow \text{PC0 } (A_0)$ $I_2 \rightarrow \text{PC2 } (A_2)$ LED $\rightarrow \text{PORTD } (0-7)$

II) - PC0 et PC2: doivent être des entrées digital

- PORTD(0-7): " " " sorties

- Etape 3: Organigramme

Langage suivant →



9-10-2024

P

SAP // TAS

filter

$$X(f) = Y(f) = H(f) \cdot X(f) \quad (1)$$

Filtration operation in Fourier space

From frequency space (FS) to time space (TS) use IFT, (1) becomes

$$\begin{aligned} y(n) &= h(n) * x(n) \\ \text{output} &= \underbrace{\text{IR}}_{\text{impulse response}} * \text{input} \end{aligned} \quad \left. \right\} \quad h(n) = \mathcal{F}^{-1}[H(f)]$$

$$= \sum_{i=-\infty}^{+\infty} h(i) x(n-i)$$

IR $h(i)$ is the principal characteristic of the filter, it must have been known

- if $h(i)$ has infinite duration, then we must truncate it to produce one that has a finite duration P , so the equation becomes

$$y(n) = \sum_{i=-\frac{P}{2}}^{\frac{P}{2}} h(i) x(n-i)$$

EXO 1 : Show $h(i)$ of a low pass is even

SAN

TD1, EXO1: $s(t) = 5 \sin(3\pi t)$

1) $f_e \geq 2f_{\max}$

$$s(t) = 5 \sin(3\pi t) \quad -2 < t < 2 \\ = 5 \sin(2\pi f_e t)$$

$$\Rightarrow 2\pi f_e t = 3\pi t$$

$$2f_e = 3 \Rightarrow f_e = \frac{3}{2} = 1,5 \text{ Hz}$$

$$f_e \geq 2 \cdot 1,5 = \boxed{3 \text{ Hz}}$$

2) L'allure de signal $f_e = 4 \text{ Hz}$

L'allure de signal reconstruit est la même que le signal $s(t)$

- donc, nous n'avons pas une perte d'information

3) L'allure de signal $f_e = 1,6 \text{ Hz}$

L'allure de signal reconstruit n'est pas la même que le signal $s(t)$

- donc, nous avons une perte d'information

TD1, EXO2:

$$x(t) = 2 \cos(100\pi t) + 5 \sin(2\cos t + \frac{\pi}{6}) - 4 \cos(380\pi t)$$

$$+ 16 \sin(600\pi t + \frac{\pi}{4}) \quad f_e \geq 2f_{\max}$$

$$x = 2 \cos(2\pi f_1 t) + 5 \sin(2\pi f_2 t + \frac{\pi}{6}) - 4 \cos(2\pi f_3 t) + 16 \sin(2\pi f_4 t + \frac{\pi}{4})$$

$$100\pi t = 2\pi f_1 t \Rightarrow f_1 = 50 \text{ Hz}$$

$$2\cos t + \frac{\pi}{6} = 2\pi f_2 t + \frac{\pi}{6} \Rightarrow f_2 = 182 \text{ Hz}$$

$$380\pi t = 2\pi f_3 t \Rightarrow f_3 = 190 \text{ Hz}$$

$$600\pi t + \frac{\pi}{4} = 2\pi f_4 t + \frac{\pi}{4} \Rightarrow f_4 = 300 \text{ Hz}$$

on a $f_4 > f_3 > f_2 > f_1$ donc $\boxed{f_{\max} = f_4 = 300 \text{ Hz}}$

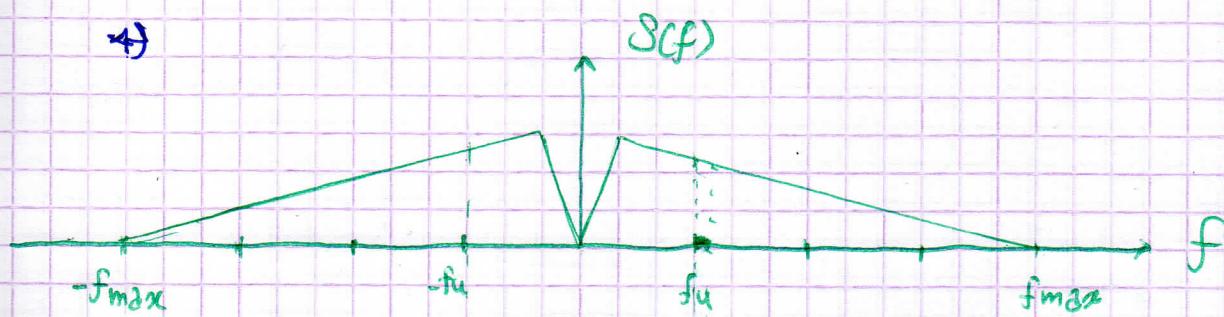
cad. unir-masta-dz / fac/fst/

/ filtre anti-répliement = éliminer le bruit
Inuti = haut fréquence

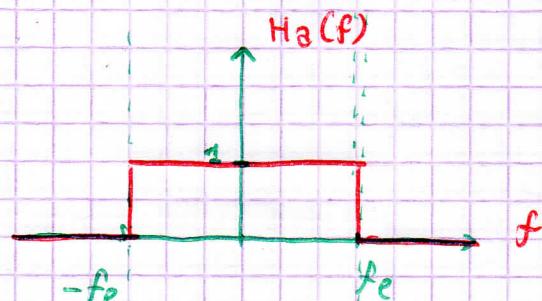
done $f_e \geq 2f_{max}$
 $f_e \geq 600\text{Hz}$ $\Rightarrow f_{min} = 600\text{Hz}$

TD1. EX03

4)

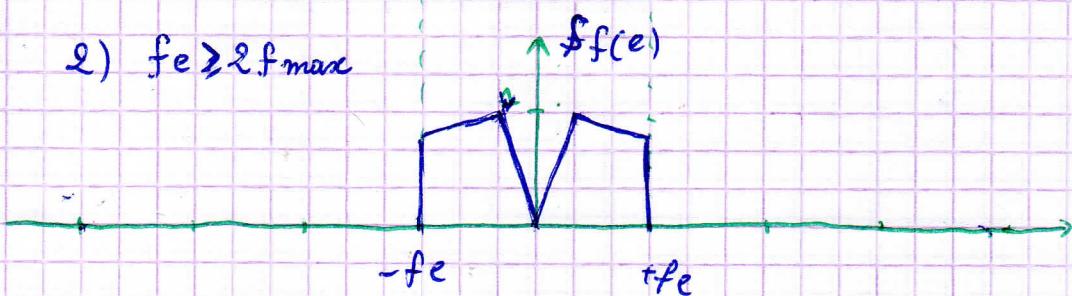


1)



$$H_a(f) = \begin{cases} 1 & -f_e < f < f_e \\ 0 & \text{ailleurs} \end{cases}$$

2) $f_e \geq 2f_{max}$



on a la fréquence maximale est f_e donc $f_e \geq 2f_{max}$

$$\text{alors } f_{min} = 2f_{max} = \frac{2f_{max}}{4} = \frac{f_{max}}{2}$$

$S_{fe}(f)$

