

*Lecture 08*

**Interfacing Fundamentals**

# Issues

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- ❖ Definition of interface
- ❖ Components of an interface
- ❖ Interface types
- ❖ Data transfer Schemes

# Definitions

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## Interface

- A shared boundary between system elements defined by:
  - ✓ *common physical interconnection characteristics*
  - ✓ *signal characteristics and*
  - ✓ *meanings of interchanged signals.*

# Definitions...*cntd*

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## Interface Device

- A device that meets the interface specifications on one side of an interface.
- Usually refers to a device through which a system or equipment works to meet the interface specifications.

*e.g. data terminal equipment(DTE), such as a modem*

# Definitions...*cntd*

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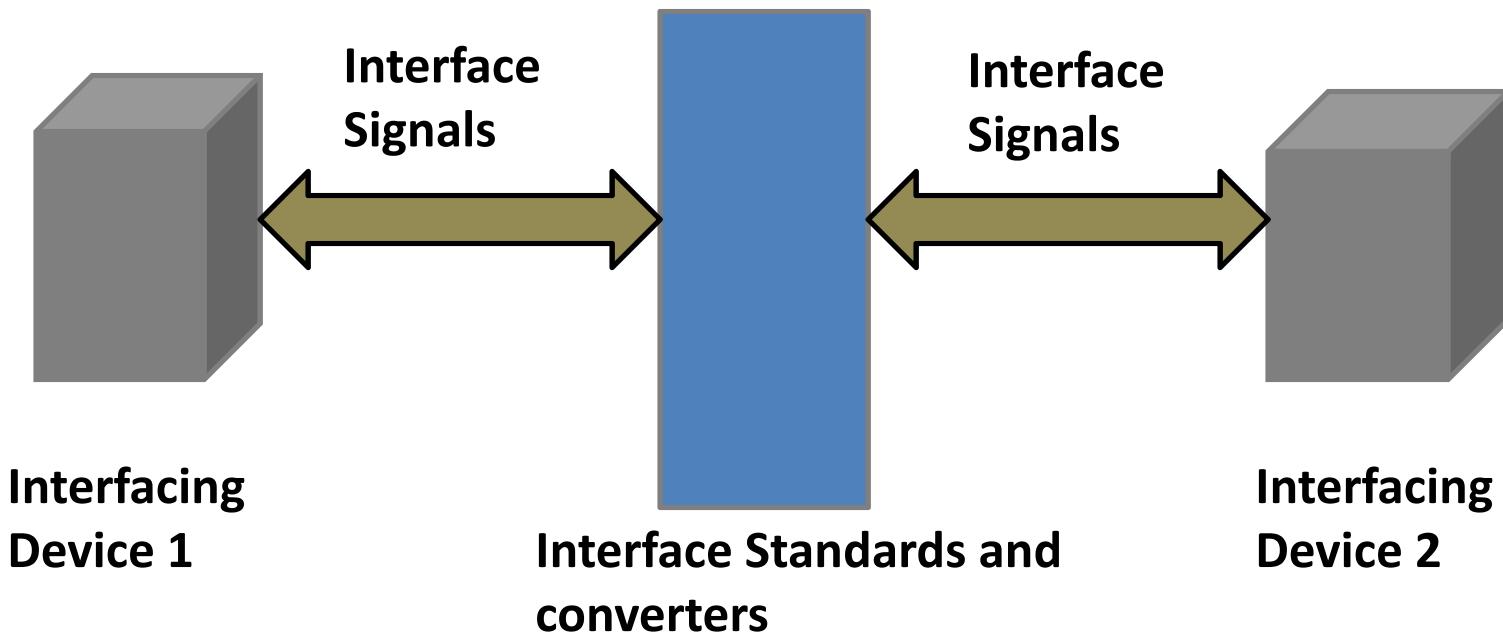
## Interface Specification

- Also referred to as Interface standard or protocol
- A set of technical requirements that must be met at an interface.

*These standards are usually set by international Associations and institutions.*

# Components of an interface

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# Components...*cntd*

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Interfacing of two devices require processing the interfacing signals based on the type of devices used.

*e.g consider the EIA standard RS-232 interface :*

- ✓ *It's usually used if the interfacing devices are computer terminals:*
- ✓ *The RS-232 standard uses a positive voltage (+10V) for logic '1' and a negative voltage (-10V) for logic '0'*

# Components...*cntd*

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- These signals are called as standard CMOS signals.
- ✓ But most of the other motherboard signals and interfacing circuit signals use TTL signals.
  - A CMOS to TTL converter is mandatory at these interfaces.
- ✓ The interfacing devices should make use of standard **data transfer schemes** for the efficient exchange of data.

# Data Transfer Schemes

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- In a typical microcomputer, data transfer takes place between any two devices:
  - microprocessor and memory
  - microprocessor and I/O devices
  - memory and I/O devices
- For effective data transfer between these devices, the timing parameters of the devices should be matched.

## Data Transfer Schemes...II

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*For example:*

- ✓ an I/O device may be slower than the processor due to which, it cannot send data to the processor at the expected time.
  
- ✓ slow memories can be interfaced using additional hardware to introduce wait states in machine cycles.

**Several data transfer schemes have been developed to solve these interfacing problems.**

# Data Transfer Schemes...III

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*Broadly, we can have two types of data transfer*

- Programmed data transfer
  
- Direct Memory Access (DMA) data transfer

*Both schemes require hardware and software for their implementation.*

# Data Transfer Schemes...IV

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## *Programmed data transfer*

- ✓ a memory resident subroutine requests the device for data transfer to or from one of the processor registers.
- ✓ Used when a relatively small amount data are to be transferred.
  - *usually one byte or word of data is transferred at a time.*

*E.g. Hex keyboard, 7-segment LED, ADC, etc.*

# Data Transfer Schemes...V

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## *Programmed data transfer...II*

✓ We can divide programmed data transfer in to three categories

- ❑ Asynchronous data transfer
- ❑ Synchronous data transfer
- ❑ Interrupt driven data transfer

# Programmed Data Transfer

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## *Asynchronous data transfer*

- ✓ These are transfers taking place at irregular intervals.
- ✓ Mostly used in low speed data transmission.

Data transfer between the microprocessor and the Peripherals is primarily asynchronous.

*Since devices are not synchronized, the data transfer takes place under several conditions:*

# **Programmed Data Transfer...II**

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## ***Asynchronous data transfer...II***

### **1. Unconditional:**

The microprocessor assumes that a peripheral is always available.

### **2. Polling**

The microprocessor is kept in a loop to check whether data are available.

### **3. Interrupt**

The microprocessor is interrupted from its normal execution of program by an I/O device.

# Programmed Data Transfer...III

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## *Asynchronous data transfer...III*

### 4. With ready signal:

When peripheral response time is slower than the microprocessor execution time, READY signal is used.

### 5. With handshake signals

- Handshake signals are signals exchanged prior to data transfer.
- Ensure readiness of the peripheral and to synchronize timing of data transfer

# Programmed Data Transfer...IV

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## *Synchronous data transfer*

- ✓ Is the simplest of all data transfer schemes.
- ✓ The processor does not check the readiness of the device. The I/O device or peripheral should have matched timing parameters.
- ✓ Mostly used in high speed data transfers

# Programmed Data Transfer...V

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## *Interrupt-driven data transfer*

- ✓ Is the best method of data transfer for effectively utilizing the processor time.
- ✓ When the IO device is ready, it will interrupt the processor.
- ✓ Upon receiving an interrupt request the processor will complete the current instruction execution and serve the request after the acknowledge cycle.

## DMA Data Transfer

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- ✓ DMA is preferred when a large block of data is to be transferred.
- ✓ The processor is forced to hold state by an I/O device until the data transfer between the device and the memory is completed.
- ✓ Usually employed for transferring data between the microprocessor and peripheral mass storage devices like hard disk and CRT controller.

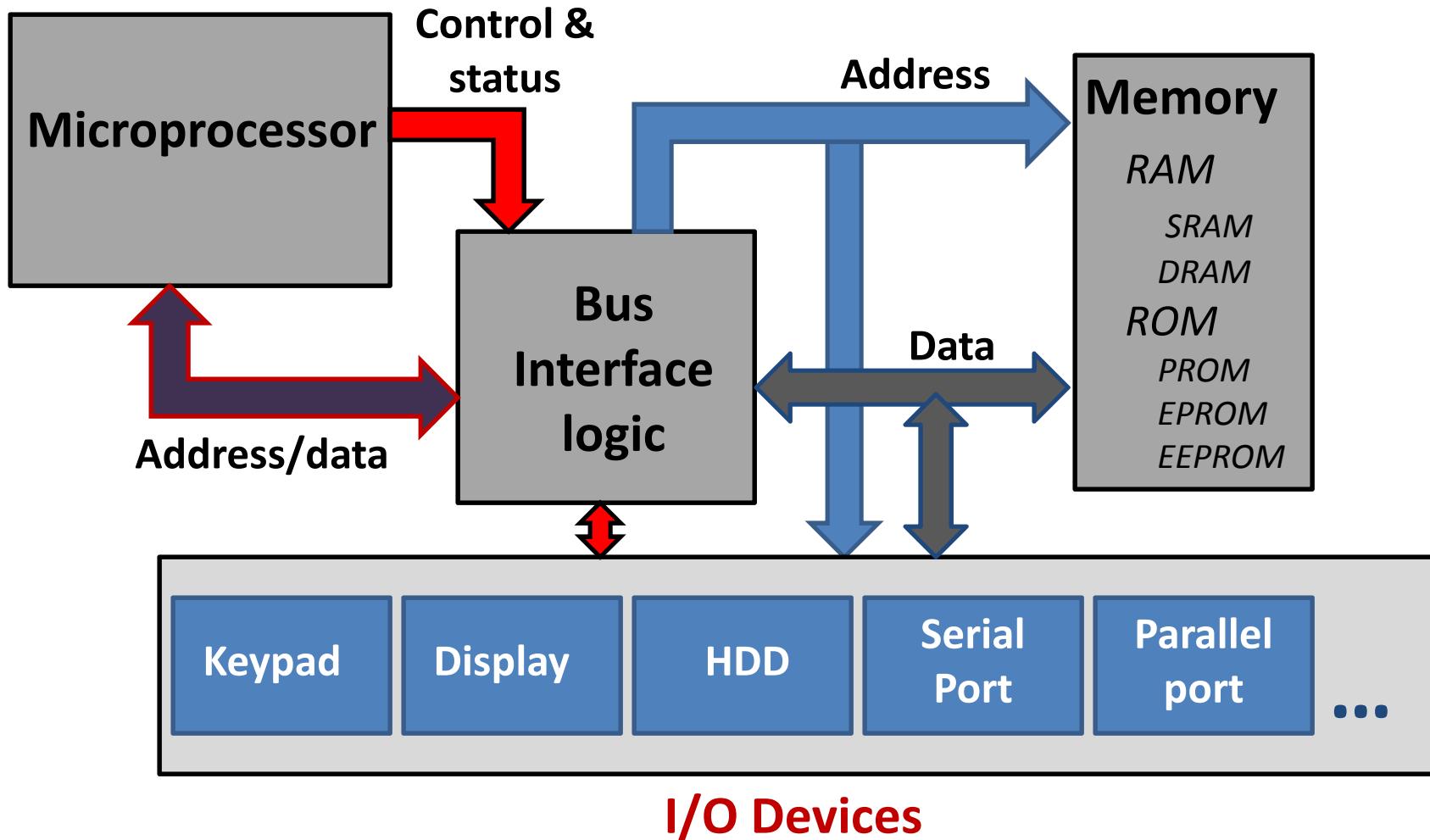
# DMA Data Transfer

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We can have 3 types of DMA data transfer schemes:

1. *Cycle stealing DMA.*
2. *Block or Burst mode DMA.*
3. *Demand transfer mode DMA.*

# Typical Microcomputer BD



# Microcomputer

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The figure shows the complete microcomputer board:

- ✓ Microprocessor (8086, 8088,...)
- ✓ Semiconductor memory (RAM, ROM,...)
- ✓ I/O devices and their controllers
- ✓ Bus interface controller  
*made of gates, buffers, decoders, muxs ...*

*In the coming lectures we will discuss the details of interfacing these different devices with the microprocessor*