

# Embedded Systems

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## Lecture 3

# Analog to Digital Converters

# Outlines

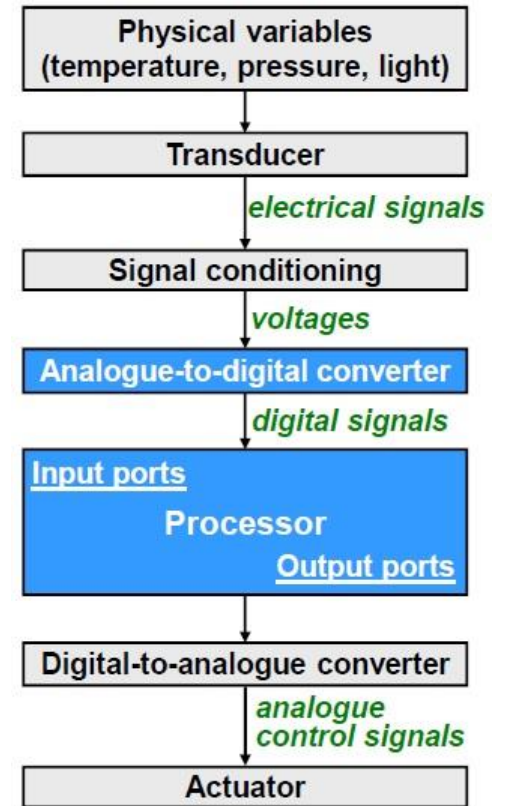
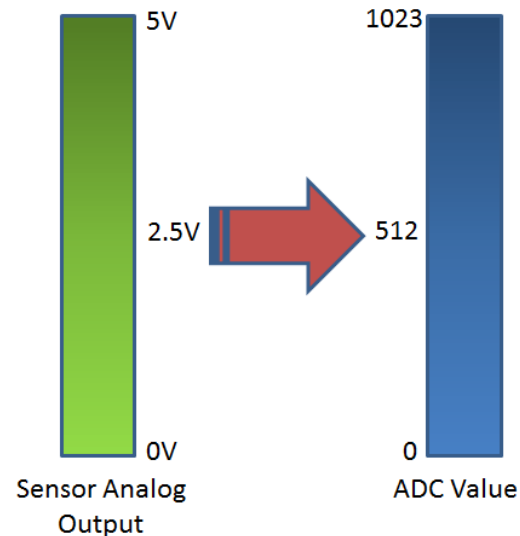
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1. Introduction
2. ATmega16 ADC
3. ADC Register
4. ADC Example
5. ADC Arduino



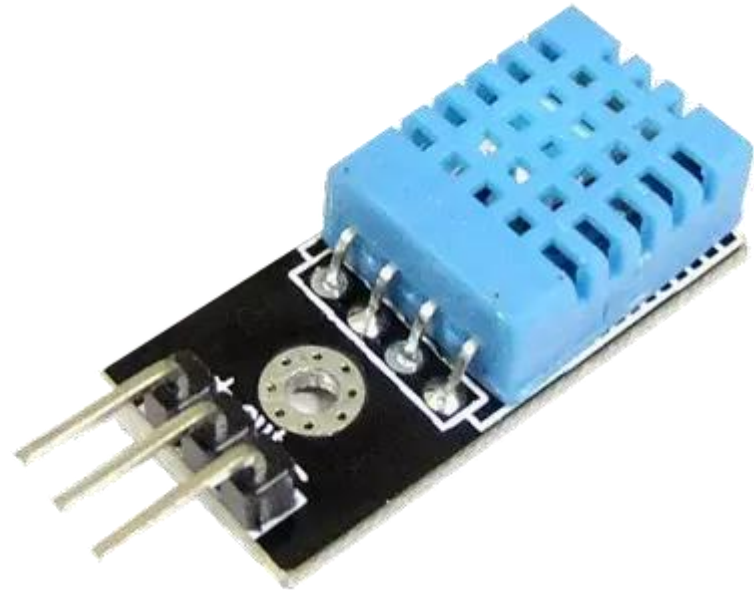
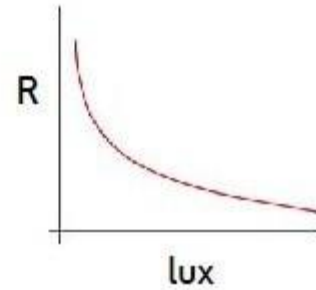
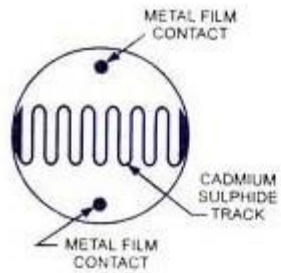
# Introduction

ADC (Analog to Digital converter) is the most widely used device in embedded systems which is designed especially for data acquisition. In the AVR ATmega series normally 10-bit ADC is inbuilt in the controller.



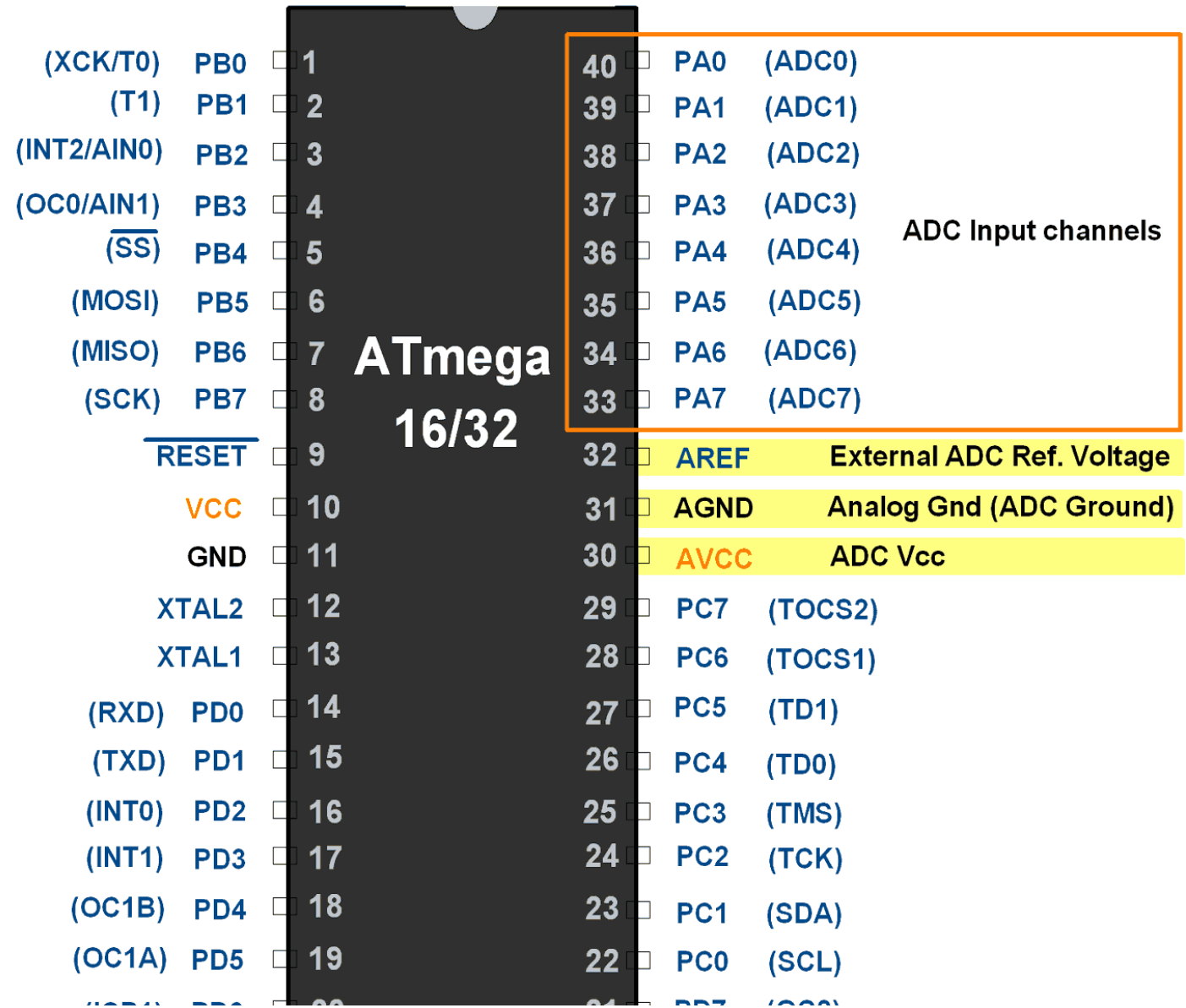
# Introduction

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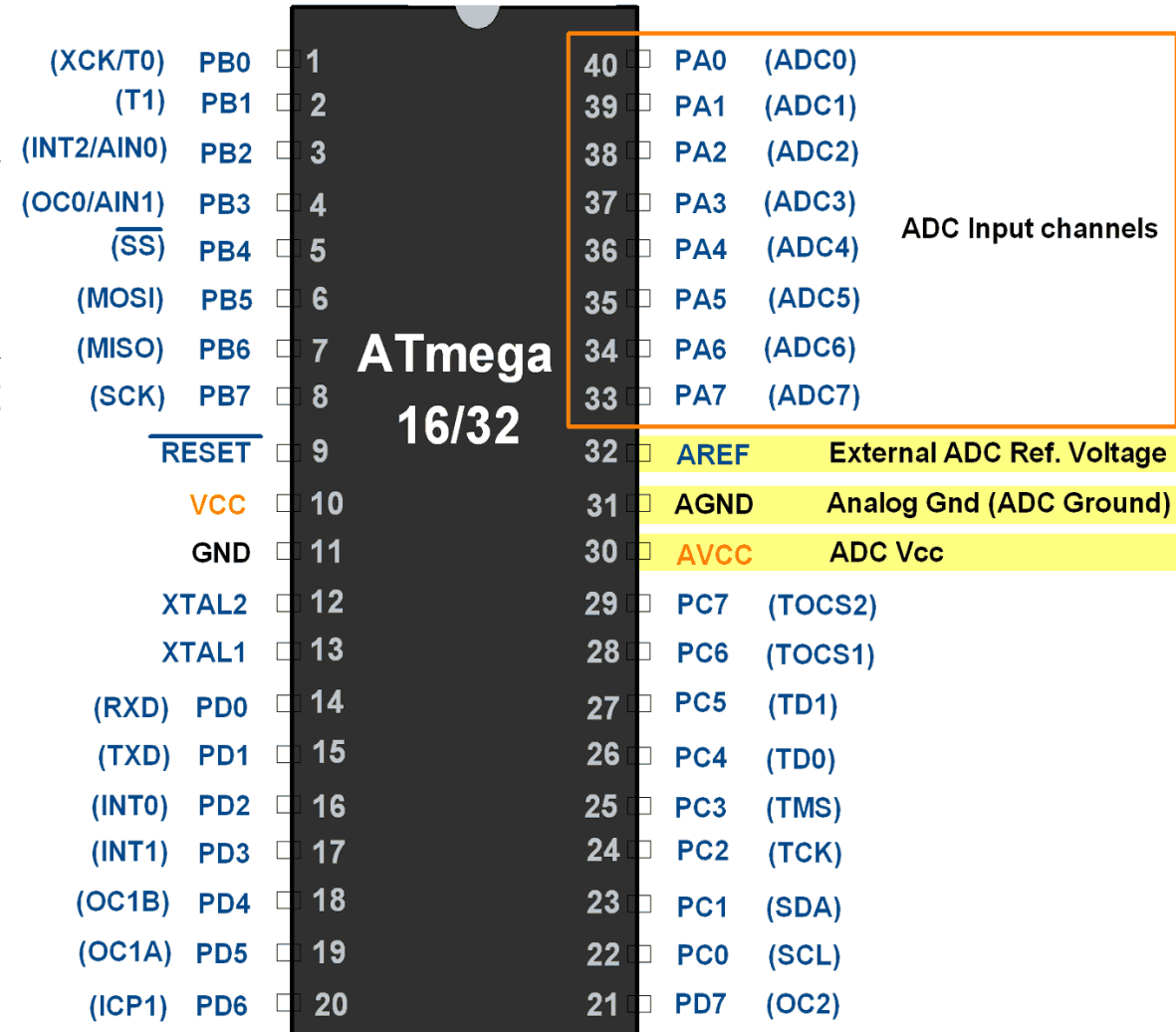
## ATmega16 ADC

- ATmega16 supports eight ADC channels, which means we can connect eight analog inputs at a time.
- ADC channel 0 to channel 7 are present on PORTA. i.e. Pin no.33 to 40.



# ATmega16 ADC

- The controller has 10 bit ADC, which means we will get digital output 0 to 1023.
  - i.e. When the input is 0V, the digital output will be 0V & when input is 5V (and Vref=5V), we will get the highest digital output corresponding to 1023 steps, which is 5V.
- So controller ADC has 1023 steps and
  - Step size with Vref=5V :  $5/1023 = 4.88 \text{ mV}$ .
  - Step size with Vref=2.56 :  $2.56/1023 = 2.5 \text{ mV}$ .
- So Digital data output will be  $D_{out} = V_{in} / \text{step size}$ .



# ATmega16 ADC

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- ❑ It is 10-bit ADC
- ❑ Converted output binary data is held in two special functions 8-bit register **ADCL** (result Low) and **ADCH** (result in High).
- ❑ ADC gives 10-bit output, so (ADCH: ADCL) **only 10-bits** are useful out of 16-bits.
- ❑ We have options to use this 10-bits as upper bits or lower bits.
- ❑ We also have three options for Vref.
  1. **AVcc (analog Vcc)**, 2. **Internal 2.56 v**, 3. **External Aref. Pin**.
- ❑ The total conversion time depends on **crystal frequency** and ADPS0: 2 (**frequency divisor**)
- ❑ If you decided to use AVcc or Vref pin as ADC voltage reference, you can make it more stable and increase the precision of ADC **by connecting a capacitor between that pin and GND.**



# ADC Register

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In AVR ADC, we need to understand four main register -

- 1.**ADCH**: Holds digital converted data higher byte
- 2.**ADCL**: Holds digital converted data lower byte
- 3.**ADMUX**: ADC Multiplexer selection register
- 4.**ADCSRA**: ADC Control and status register

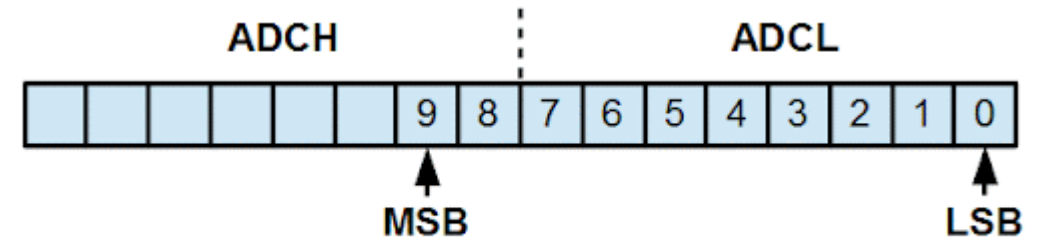
# ADC Register

## ADCH: ADCL register

First, two-register holds the digital converted data, which is 10-bit.

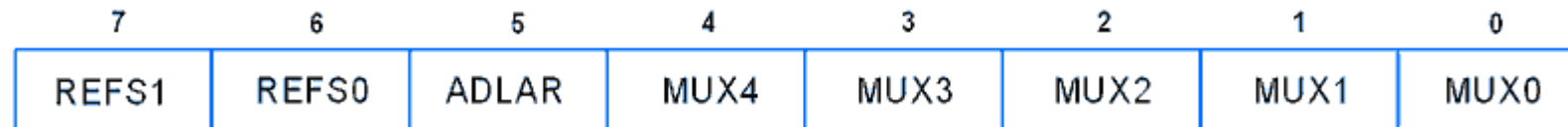
**ADCH:** Holds digital converted data higher byte

**ADCL:** Holds digital converted data lower byte



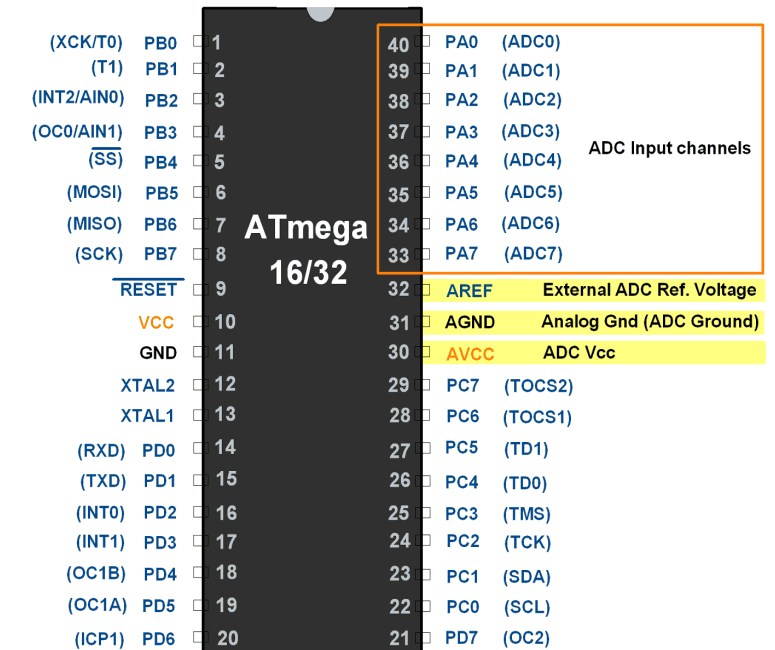
# ADC Register

## ADMUX Register



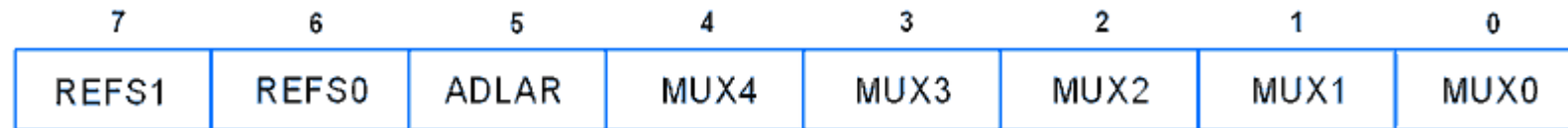
### Bit 7: 6 – REFS1 : 0: Reference Selection Bits

REFS1	REFS0	Vref to ADC
0	0	AREF pin
0	1	AVCC pin i.e. Vcc 5 V
1	0	Reserved
1	1	Internal 2



# ADC Register

## ADMUX Register



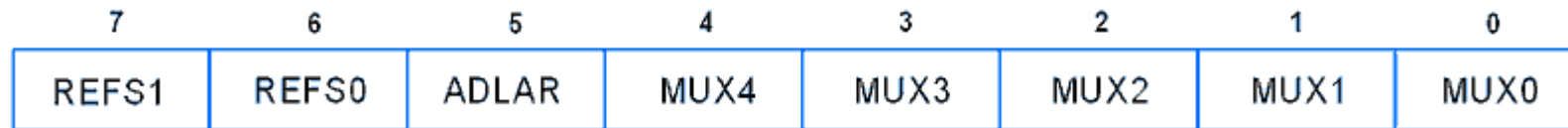
### Bit 5 – ADLAR: ADC Left Adjust Result

Use 10-bits output as upper bits or lower bits in ADCH & ADCL.



# ADC Register

## ADMUX Register



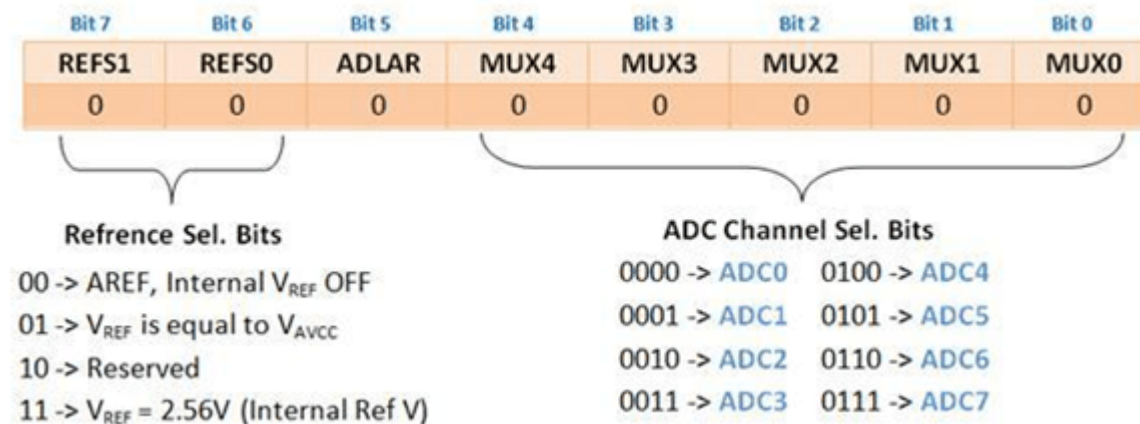
### Bits 4 : 0 – MUX4 : 0: Analog Channel and Gain Selection Bits

We can select input channel ADC0 to ADC7 by using these bits.

Selecting a channel is very easy, just put the channel number in MUX4 : 0.

Suppose you are connecting the input to ADC channel 2 then put 00010 in MUX4 : 0.

Suppose you are connecting the input to ADC channel 5 then put 00101 in MUX4 : 0.





# ADC Register

## ADMUX Register

7	6	5	4	3	2	1	0
REFS1	REFS0	ADLAR	MUX4	MUX3	MUX2	MUX1	MUX0

### Bits 4 : 0 – MUX4 : 0: Analog Channel and Gain Selection Bits

We can select input channel ADC0 to ADC7 by using these bits.

Selecting a channel is very easy, just put the channel number in MUX4 : 0.

Suppose you are connecting the input to ADC channel 2 then put 00010 in MUX4 : 0.

Suppose you are connecting the input to ADC channel 5 then put 00101 in MUX4 : 0.

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
REFS1	REFS0	ADLAR	MUX4	MUX3	MUX2	MUX1	MUX0
0	0	0	0	0	0	0	0

Reference Sel. Bits			ADC Channel Sel. Bits			
00	->	AREF, Internal $V_{REF}$ OFF	0000	->	ADC0	0100 -> ADC4
01	->	$V_{REF}$ is equal to $V_{AVCC}$	0001	->	ADC1	0101 -> ADC5
10	->	Reserved	0010	->	ADC2	0110 -> ADC6
11	->	$V_{REF} = 2.56V$ (Internal Ref V)	0011	->	ADC3	0111 -> ADC7

# ADC Register

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## Single Conversion or Auto triggering !!

- In a single conversion mode you manually trigger the ADC process each time you want.

Auto Triggering is enabled by setting the ADC Auto Trigger Enable bit.

- Provides a method of starting conversions at fixed intervals.
- Using the ADC Interrupt Flag as a trigger source makes the ADC start a new conversion as soon as the ongoing conversion has finished. (Free running mode).
- At the end of each conversion the ADIF should be cleared by writing one !! So automatically the next conversion starts

# ADC Register

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## ADCSRA Register:

7	6	5	4	3	2	1	0
ADEN	ADSC	ADATE	ADIF	ADIE	ADPS2	ADPS1	ADPS0

- **Bit 7 – ADEN: ADC Enable**

Writing one to this bit enables the ADC. By writing it to zero, the ADC is turned off. Turning the ADC off while a conversion is in progress, will terminate this conversion.

- **Bit 6 – ADSC: ADC Start Conversion**

Writing one to this bit starts the conversion.

- **Bit 5 – ADATE: ADC Auto Trigger Enable**

Writing one to this bit, results in Auto Triggering of the ADC is enabled.

# ADC Register

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## ADCSRA Register:



- **Bit 4 – ADIF: ADC Interrupt Flag**

This bit is set when an ADC conversion completes and the Data Registers are updated.

- **Bit 3 – ADIE: ADC Interrupt Enable**

Writing one to this bit, the ADC Conversion Complete Interrupt is activated.

# ADC Register

## ADCSRA Register:

7	6	5	4	3	2	1	0
ADEN	ADSC	ADATE	ADIF	ADIE	ADPS2	ADPS1	ADPS0

**ADC clock frequency = XTAL frequency / Prescaler**

### •Bits 2 : 0 – ADPS2 : 0: ADC Prescaler Select Bits

These bits determine the division factor between the XTAL frequency and the input clock to the ADC

ADPS2	ADPS1	ADPS0	Division Factor
0	0	0	2
0	0	1	2
0	1	0	4
0	1	1	8
1	0	0	16
1	0	1	32
1	1	0	64
1	1	1	128



# ADC Register

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## ADCSRA Register:



- **Bits 2 : 0 – ADPS2 : 0: ADC Prescaler Select Bits**

These bits determine the division factor between the XTAL frequency and the input clock to the ADC

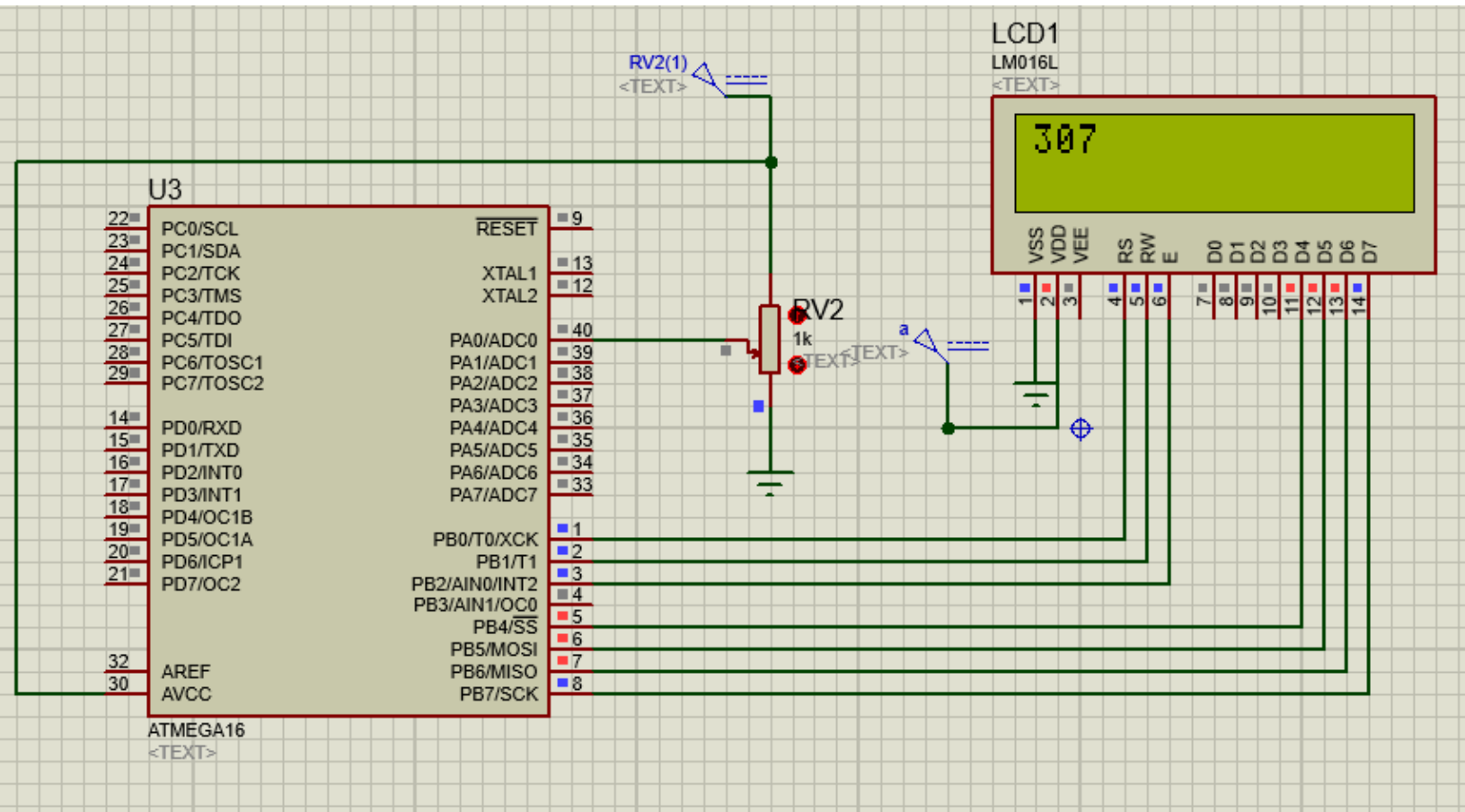
ADC clock frequency = XTAL frequency / Prescaler

The ADC clock frequency must lie somewhere between 50 kHz to 200 kHz to get maximum resolution.

Suppose your clock frequency of AVR is 8MHz, then we must have to use divisor 64 or 128. Because it gives  $8\text{MHz}/64 = 125\text{KHz}$ , which is lesser than 200KHz.

# ADC Example

LCD16x2 is used to show digital converted value from channel 0.



# ADC Example

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## Steps to Program ADC

1. Make the ADC channel pin as an input.

```
DDRA=0x0; /* Make ADC port as input */
```

# ADC Example

## Steps to Program ADC

2. Set ADC enable bit in ADCSRA, select the conversion speed using ADPS2 : 0. For example, we will select divisor 128.

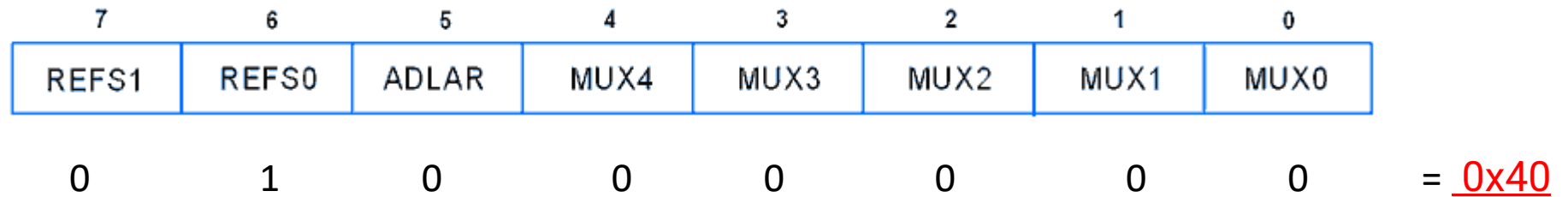


```
ADCSRA = 0x87; /* Enable ADC, fr/128 */
```

# ADC Example

## Steps to Program ADC

3. Select ADC reference voltage using REFS1: REFS0 in ADMUX register, for example, we will use AVcc as a reference voltage.
4. Select the ADC input channel using MUX4 : 0 in ADMUX, for example, we will use channel 0.



```
ADMUX = 0x40; /* Vref: Avcc, ADC channel: 0*/
```



# ADC Example

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## Steps to Program ADC

5. Start conversion by setting bit ADSC in ADCSRA. E.g. `ADCSRA |= (1<<ADSC);`

```
ADCSRA |= (1<<ADSC); /* Start conversion */
```

6. Wait for conversion to complete by polling ADIF bit in ADCSRA register.

```
while((ADCSRA&(1<<ADIF))!=0); ///* Monitor end of conversion interrupt */
```

7. After the ADIF bit gone high, read `ADCL` and `ADCH` register to get digital output.

```
AinLow = (int)ADCL; /* Read lower byte*/  
Ain = (int)ADCH*256; /* Read higher 2 bits and Multiply with weight */  
Ain = Ain + AinLow;
```

Notice that read `ADCL` before `ADCH`; otherwise result will not be valid

# ADC Example

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## Steps to Program ADC

1. Make the ADC channel pin as an input.
2. Set ADC enable bit in ADCSRA, select the conversion speed using ADPS2 : 0. For example, we will select divisor 128.
3. Select ADC reference voltage using REFS1: REFS0 in ADMUX register, for example, we will use AVcc as a reference voltage.
4. Select the ADC input channel using MUX4 : 0 in ADMUX, for example, we will use channel 0. So our value in register ADCSRA = 0x87 and ADMUX = 0x40.
5. Start conversion by setting bit ADSC in ADCSRA. E.g. ADCSRA |= (1<<ADSC);
6. Wait for conversion to complete by polling ADIF bit in ADCSRA register.
7. After the ADIF bit gone high, read ADCL and ADCH register to get digital output.

Notice that read ADCL before ADCH; otherwise result will not be valid

# ADC Example

```
#include <mega16.h>
#include <delay.h>
#include <stdlib.h>
#include <alcd.h>
int read_adc(char channel);

void main(void)
{
    int value;
    char String[5];
    DDRA=0x0; /* Make ADC port as input */
    lcd_init(16);
    while (1)
    {
        value= read_adc(0); /* Read ADC channel 0 */
        itoa(value,String); /* Integer to string conversion */
        lcd_puts(String);
        delay_ms(500);
        lcd_clear();
    }
}
```

```
int read_adc(char channel)
{
    int AinLow, Ain;
    ADCSRA = 0x87; /* Enable ADC, fr/128 */
    ADMUX = 0x40; /* Vref: Avcc, ADC channel: 0 */
    ADMUX=ADMUX|(channel & 0x0f); // Set input channel to read
    delay_ms(10);

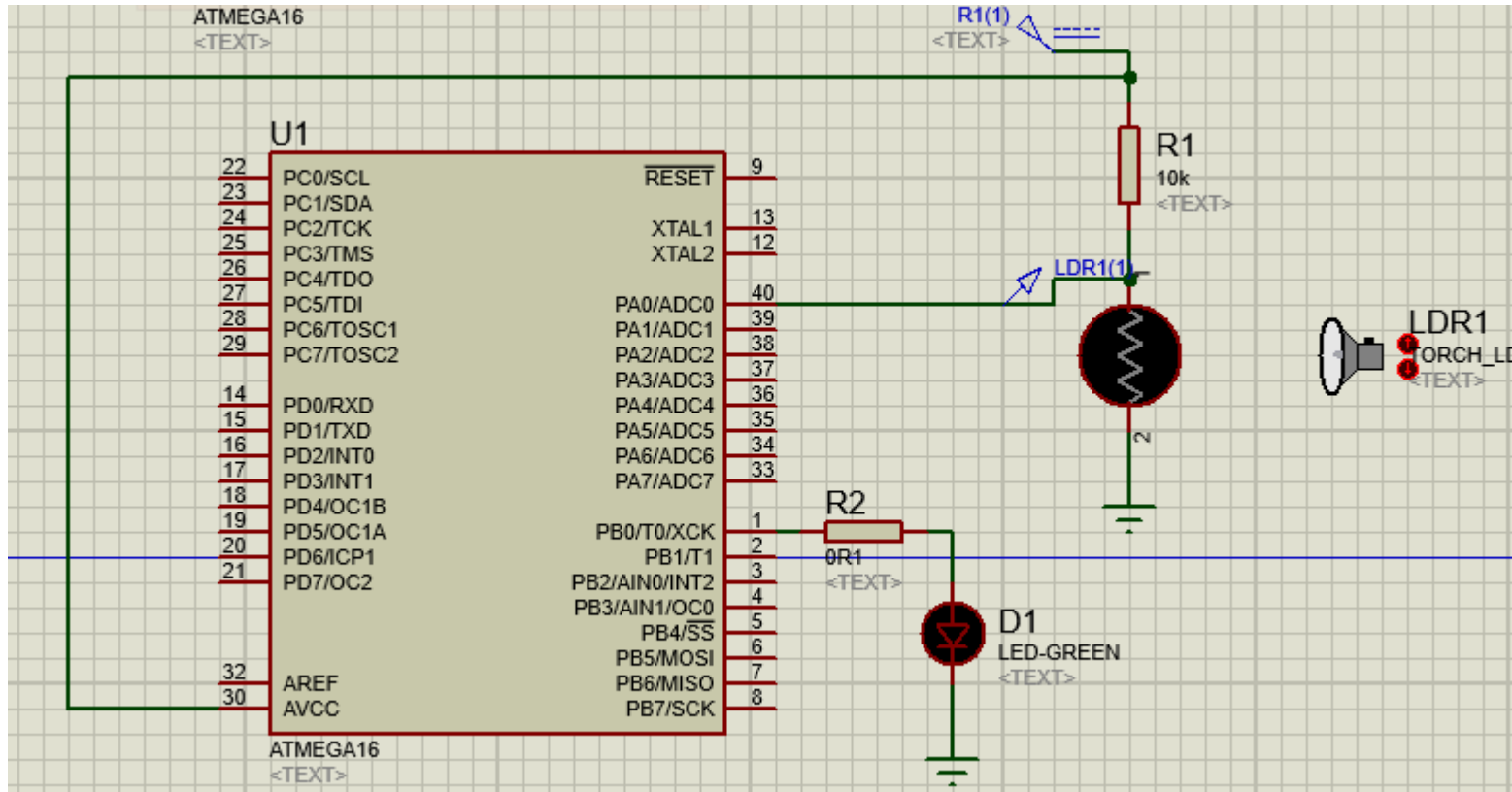
    ADCSRA |= (1<<ADSC); /* Start conversion */

    /* Monitor end of conversion interrupt */
    while((ADCSRA&(1<<ADIF))==0);
    delay_ms(10);

    AinLow = (int)ADCL; /* Read lower byte*/

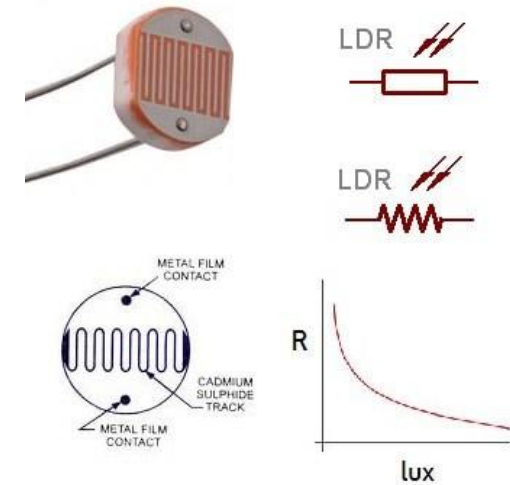
    /* Read higher 2 bits and Multiply with weight */
    Ain = (int)ADCH*256;

    Ain = Ain + AinLow;
    return(Ain); /* Return digital value*/
}
```



# ADC Example 2

Automatic Street Light Controller using Atmega and LDR as Light sensor



# ADC Example 2

```
#include <mega16.h>
#include <delay.h>
int read_adc(char channel);

void main(void)
{
    int value;
    DDRA=0x0; /* Make ADC port as input */
    PORTB=0x00;
    DDRB=0x01; //LED pin as a output

    while (1)
    {
        value= read_adc(0); /* Read ADC channel 0 */
        if(value> 512)
            PORTB=0x01;
        else
            PORTB=0x00;
    }
}
```

```
int read_adc(char channel)
{
    int AinLow, Ain;
    ADCSRA = 0x87; /* Enable ADC, fr/128 */
    ADMUX = 0x40; /* Vref: Avcc, ADC channel: 0 */
    ADMUX=ADMUX|(channel & 0x0f); // Set input channel to read
    delay_ms(10);

    ADCSRA |= (1<<ADSC); /* Start conversion */

    /* Monitor end of conversion interrupt */
    while((ADCSRA&(1<<ADIF))==0);
    delay_ms(10);

    AinLow = (int)ADCL; /* Read lower byte*/

    /* Read higher 2 bits and Multiply with weight */
    Ain = (int)ADCH*256;

    Ain = Ain + AinLow;
    return(Ain); /* Return digital value*/
}
```



# Arduino ADC

Arduino boards contain a multichannel, 10-bit analog to digital converter.

This means that it will map input voltages between 0 and the operating voltage(5V or 3.3V) into integer values between 0 and 1023.

On an Arduino UNO, for example, this yields a resolution between readings of: 5 volts / 1024 units or, 0.0049 volts (4.9 mV) per unit

## Syntax

```
analogRead(pin)
```



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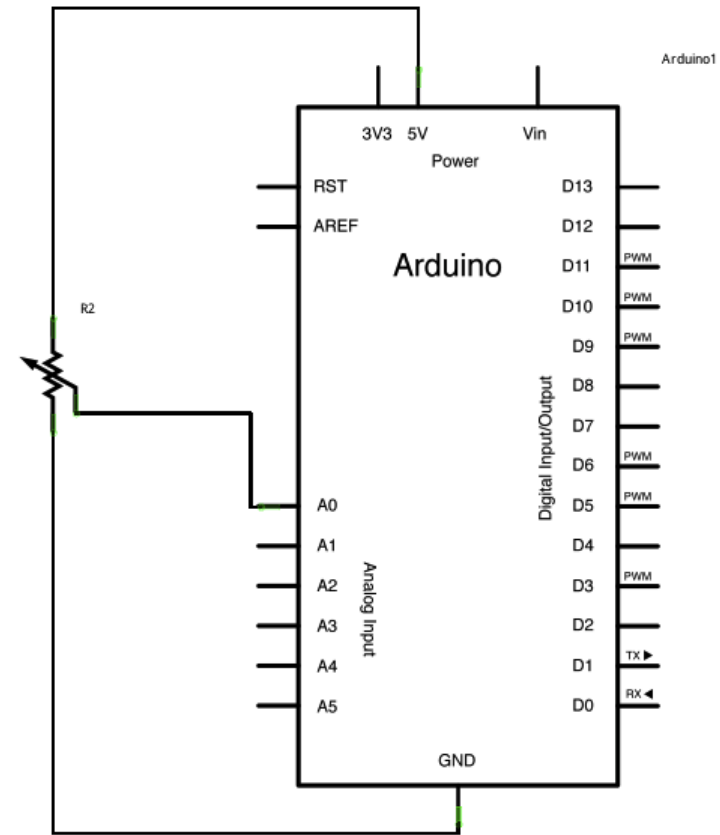
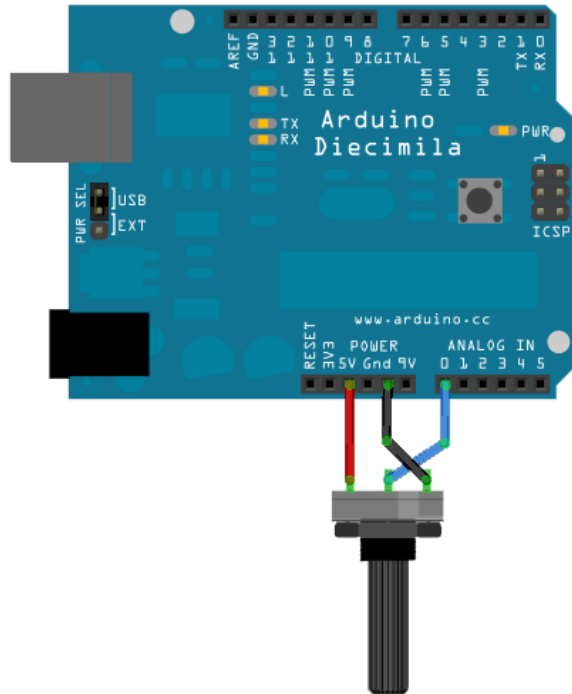
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## Syntax

```
analogRead(pin)
```



# Arduino ADC



# Arduino ADC

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```
int sensorPin = A0;    // select the input pin for the potentiometer
int ledPin = 13;       // select the pin for the LED
int sensorValue = 0;   // variable to store the value coming from the sensor

void setup() {
  // declare the ledPin as an OUTPUT:
  pinMode(ledPin, OUTPUT);
}

void loop() {
  // read the value from the sensor:
  sensorValue = analogRead(sensorPin);
  // turn the ledPin on
  digitalWrite(ledPin, HIGH);
  // stop the program for <sensorValue> milliseconds:
  delay(sensorValue);
  // turn the ledPin off:
  digitalWrite(ledPin, LOW);
  // stop the program for for <sensorValue> milliseconds:
  delay(sensorValue);
}
```

---

# Thanks

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