

LU-Factorization/Decomposition:

Augmented Matrix \Rightarrow Upper Triangular Matrix \Rightarrow Solve for unknowns

$$A = \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix}$$

Through tracking our scaling factors when performing Gauss Elimination we can find the solution to this 'A' matrix no matter what values are put in the 'b' (or constant) matrix

$$\text{lower-triangle matrix } L \cdot \text{upper-triangle matrix } U = A$$

scaling factor $\begin{bmatrix} 1 & 0 & 0 \\ S.F_1 & 1 & 0 \\ S.F_2 & S.F_3 & 1 \end{bmatrix} \cdot \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ 0 & a_{22} & a_{23} \\ 0 & 0 & a_{33} \end{bmatrix} = \text{original Matrix}$

$$A \cdot \vec{x} = \vec{b}$$

upper-triangular matrix $U \cdot \vec{x} = \vec{c}$ After Gauss elimination
new constant vector

$$L \cdot U \cdot \vec{x} = L \cdot \vec{c}$$

Through this we can easily solve for \vec{c} (Forward substitution)

$$L \cdot \vec{c} = \vec{b}$$

$U \cdot \vec{x} = \vec{c}$ then plug \vec{c} in this equation to get the unknown variables \vec{x} (Backward substitution)

- In Summary, LU factorization is similar to Gauss Elimination, however, it is much more versatile and much faster computation wise (If more than one constant vector \vec{b} is needed to be solved for).

Partial pivoting

If $|a_{i,i}| < |a_{j,i}|$ then switch our rows i & j

Solve the following SLE using LU Decomposition

$$A \xrightarrow{\vec{x}} \vec{b}$$

$$\begin{bmatrix} 1 & 3 & 2 \\ 3 & 2 & 6 \\ 2 & 4 & 8 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$$

$$\left[\begin{array}{ccc|ccc} 1 & 0 & 0 & 1 & 3 & 2 \\ 0 & 1 & 0 & 3 & 2 & 6 \\ 0 & 0 & 1 & 2 & 4 & 8 \end{array} \right] \xrightarrow{\text{II} - 3\text{I}} \xrightarrow{\text{III} - 2\text{I}}$$

$$\left[\begin{array}{ccc|ccc} 1 & 0 & 0 & 1 & 3 & 2 \\ 3 & 1 & 0 & 0 & -7 & 0 \\ 2 & 0 & 1 & 0 & -2 & 4 \end{array} \right] \xrightarrow{\text{III} - \frac{2}{7}\text{II}}$$

$$\xrightarrow{\quad \quad \quad L \quad \quad \quad U \quad \quad \quad}$$

$$\left[\begin{array}{ccc|ccc} 1 & 0 & 0 & 1 & 3 & 2 \\ 3 & 1 & 0 & 0 & -7 & 0 \\ 2 & \frac{2}{7} & 1 & 0 & 0 & 4 \end{array} \right]$$

$$L \cdot \vec{c} = \vec{b} \rightarrow \boxed{\text{Forward substitution}}$$

$$C_1 = 1$$

$$C_2 = 2 - 3 = -1$$

$$C_3 = 3 - 2(1) - \frac{2}{7}(-1)$$

$$\Rightarrow C_3 = \frac{9}{7} \approx 1.2857$$

$$U \cdot \vec{x} = \vec{c} \rightarrow \boxed{\text{Backward substitution}}$$

$$\begin{bmatrix} 1 & 3 & 2 \\ 0 & -7 & 0 \\ 0 & 0 & 4 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 1 \\ -1 \\ \frac{9}{7} \end{bmatrix}$$

$$4x_3 = \frac{9}{7} \Rightarrow x_3 = \frac{9}{28}$$

$$-7x_2 = -1 \Rightarrow x_2 = \frac{1}{7}$$

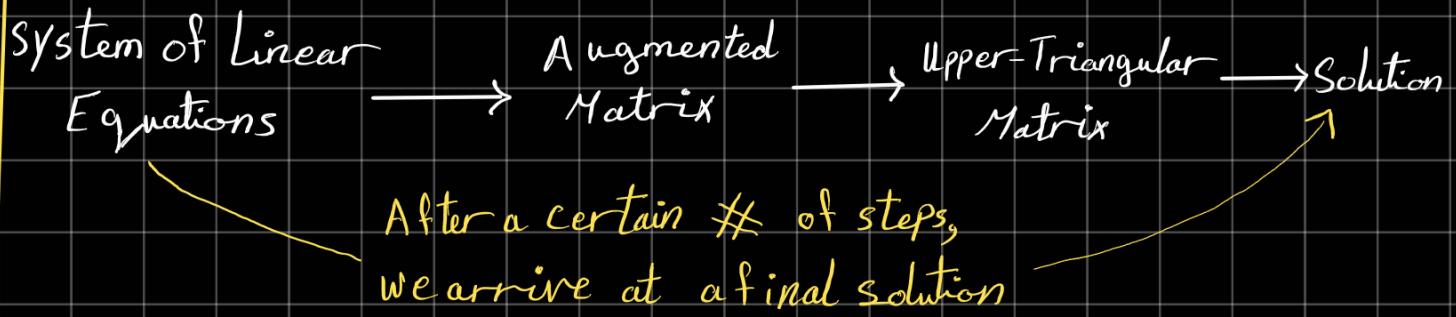
$$x_1 = 1 - 3x_2 - 2x_3 = 1 - \frac{3}{7} - \frac{9}{14} = 1 - \frac{15}{14}$$

$$\Rightarrow x_1 = -\frac{1}{14}$$

Iterative Vs. Direct Numerical Methods:

→ Direct: Ways of solving systems of linear equations through a finite # of steps.

Ex: Gaussian Elimination (LU Factorization/Decomposition)



→ Iterative: Do not necessarily stop after a certain # of steps! Will continue to iterate until a sufficient amount of error is achieved.

Ex: Bisection Method, Newton's Method, and Jacobi Iteration.

★ These need an initial guess to begin the solving!

Direct	Iterative
<ul style="list-style-type: none">• Can't stop after a certain # of steps $\begin{bmatrix} 1 & 2 & 5 \\ 2 & 1 & 1 \\ 4 & 3 & 4 \end{bmatrix}$ <p>↓ all to zero, then backward sub. to solve.</p>	<ul style="list-style-type: none">• We can choose to stop whenever we want. It's just a tradeoff between accuracy and computation time!

What are iterative methods and can they be used to solve systems of linear equations?

$$\begin{pmatrix} a_{1,1} & a_{1,2} & a_{1,3} \\ a_{2,1} & a_{2,2} & a_{2,3} \\ a_{3,1} & a_{3,2} & a_{3,3} \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} b_1 \\ b_2 \\ b_3 \end{pmatrix}$$

- We could use direct numerical methods to solve this, However, Direct numerical methods are not ideal for very large SLE and in non-linear equations direct methods don't work.

How do we develop an iterative method to solve the matrix above?

$$\begin{array}{l} \sum_{j=1}^n a_{1,j} \cdot x_j = b_1 \\ \sum_{j=1}^n a_{2,j} \cdot x_j = b_2 \\ \sum_{j=1}^n a_{3,j} \cdot x_j = b_3 \end{array}$$

$$(a_{1,1} \cdot x_1 + a_{1,2} \cdot x_2 + a_{1,3} \cdot x_3)$$

constant · variable = linear equation

$$(b_1 - a_{1,2} \cdot x_2 - a_{1,3} \cdot x_3) = a_{1,1} \cdot x_1$$

Then divide by $a_{1,1}$!

* Our goal is to find some x -values that will give us the proper b -values!

For a single row which we will call i : $\sum_{j=1}^n a_{i,j} \cdot x_j = b_i$

$$x_i = \frac{b_i - \sum_{j=1, j \neq i}^n a_{i,j} \cdot x_j}{a_{i,i}}$$

← We took $a_{i,i} \cdot x_i$ out of the summation, think of this as taking and isolating say $a_{1,1} \cdot x_1$ above.

- We have no way of solving this problem currently as we still don't know our x -values that satisfy our equation.

$$x_i^{(k+1)} = \frac{b_i - \sum_{j=1, j \neq i}^n a_{i,j} \cdot x_j^{(k)}}{a_{i,i}}$$

These are the n -equations that we use to iterate.

our guess number. $x_i^{(k+1)}$ ← so we are using our old x -values guesses to find our new one!

$$x_i^{(k+1)} = x_i^{(k)} + \frac{b_i - \sum_{j=1}^n a_{i,j} \cdot x_j^{(k)}}{a_{i,i}}$$

$$x_i^{(k+1)} = x_i^{(k)} + \frac{b_i - A_i \cdot x^{(k)}}{a_{i,i}}$$

This was solved through \oplus the $x_i^{(k)}$

Remember: $A \cdot x = b \rightarrow$ $A_i \cdot x^{(k)}$ is the b -value based on our guesses for the x -values! Therefore, it's basically a R emainder term.

- Iterative methods are ways to solve our matrix (so find the x -values) without performing all the steps in direct numerical methods!

$$\underbrace{b_i - A_i \cdot x^{(k)}}_{\text{as } k \uparrow \text{ then } R \rightarrow 0} \quad \text{as # of iterations } \uparrow$$

= "Remainder" (i.e. how far off we were from the real x -values!) Thus, our goal is to turn this to zero! as close as we could get!

Just Note: Direct method gives an EXACT answer, where, iterative methods are APPROXIMATE!

Why did we go through all the work above?

↳ Iterative methods can be quicker for large zero matrices, which can be a problem for direct numerical methods.

The problem is we can never be certain about the number of iterations that are required.

↳ Only Perform when you have no choice or you're certain that the matrix converges.

Note:

1: ↓ iterations (K) needed if good/educated guesses are used initially.

2: Convergence is guaranteed if matrix is Diagonally dominant.

What is a Diagonally Dominant Matrix?

Condition of a diagonally dominant matrix ; $|a_{i,i}| \geq \sum_{j=1, j \neq i}^n |a_{i,j}|$ for all rows with at least one row being strictly greater than ($>$)!

• This is important as we are guaranteed using iterative methods if our square matrix of interest is Diagonally Dominant.

$\boxed{\quad} \geq \sum \boxed{\quad}$
for every row

 $\& \quad > \sum \boxed{\quad}$
for at least 1 row

$$\begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix}$$

* To ensure no mistakes are made, strictly focus on one row at a time!

Performing Jacobi Iteration (by hand) example:

↳ Requirements:

① Square Matrix

② Linear

③ Ideally Diagonally Dominant

→ Ensure convergence

→ If not, we either need a better starting guess, or it won't converge.

→

$$\left[\begin{array}{ccc|c} 9 & 2 & 3 & 7 \\ 1 & 12 & 9 & 2 \\ 4 & 6 & 14 & 1 \end{array} \right]$$

check for diagonally dominance:

$$9 \geq |2| + |3|$$

$9 \geq 5$ yes

$$12 \geq |1| + |9|$$

$12 \geq 10$ yes

$$14 \geq |4| + |6|$$

$14 \geq 10$ yes

∴ Matrix is diagonally dominant

① Assume an initial guess for the x -vector:

$$x_1^0 = 0, x_2^0 = 0, x_3^0 = 0$$

② Rewrite system of equations to solve for an x -value.

$$9x_1 + 2x_2 + 3x_3 = 7 \rightarrow x_1^{k+1} = \frac{7 - [2x_2^k + 3x_3^k]}{9}$$

$$x_1 + 12x_2 + 9x_3 = 2 \rightarrow x_2^{k+1} = \frac{2 - [x_1^k + 9x_3^k]}{12}$$

$$4x_1 + 6x_2 + 14x_3 = 1 \rightarrow x_3^{k+1} = \frac{1 - [4x_1^k + 6x_2^k]}{14}$$

	0	1	2	3	4	
x_1	0	$\frac{7}{9}$	$\frac{271}{378}$	$\frac{5723}{6804}$	$\frac{4481}{5832}$	≈ 0.826
x_2	0	$\frac{1}{6}$	$\frac{73}{1512}$	$\frac{1241}{4536}$	$\frac{4949}{23328}$	≈ 0.3172
x_3	0	$\frac{1}{14}$	$-\frac{2}{9}$	$-\frac{233}{1512}$	$-\frac{0.286145}{14}$	≈ -0.239

• Validate we are converging:

$$0 \leq 7 - 9x_1 - 2x_2 - 3x_3$$

$$0 \leq 2 - 1x_1 - 12x_2 - 9x_3$$

$$0 \leq 1 - 4x_1 - 6x_2 - 14x_3$$

iteration	Error in Equation 1
1	$= 7 - 9(0.777) - 2(0.166) - 3(0.714) \approx -0.5476$
2	$= 7 - 9(0.7169) - 2(0.04828) - 3(-0.222) = 1.1177$
3	$= -0.65498$
4	$= 0.5140$
5	$= -0.3515$
6	$= 0.2648$
7	$= -0.1839$

if we kept going earlier {

Converging
(error is decreasing!)

Gauss-Seidel Method: An iterative numerical method that can aide us in solving Linear systems of equations!
 ↳ very similar to Jacobi Method.

Jacobi Method

Solve for all new x -values
before implementing

vs.

Gauss-Seidel Method

use newly found x -values
immediately.

Gauss-Seidel procedure:

- ① Make a guess for all values in our systems x -matrix

$$\begin{aligned} x_1^0 &= 0 \\ x_2^0 &= 0 \\ x_3^0 &= 0 \\ \vdots & \end{aligned} \quad \left. \begin{array}{l} \text{We typically use a zero} \\ \text{matrix as an initial guess,} \\ \text{unless we have additional information} \\ \text{about the problem.} \end{array} \right\} \begin{array}{l} \text{Better starting guess} \\ \Rightarrow \\ \text{faster and more likely} \\ \text{to converge} \end{array}$$

- ② Write all independant equations to solve for different x -values.

$$\begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix} \rightarrow a_{11} \cdot x_1 + a_{12} \cdot x_2 + a_{13} \cdot x_3 = b_1$$

$$x_1 = \frac{b_1 - [a_{12} \cdot x_2 + a_{13} \cdot x_3]}{a_{11}}$$

* Repeat for all independent equations

- ③ Create a summary table

variable	iter. 0	iter. 1	iter. 2	---
x_1	$x_1^0 = 0$			
x_2		$x_2^0 = 0$		
x_3			$x_3^0 = 0$	

- ④ Solve for iteration 1:

$$x_1^1 = \frac{b_1 - [a_{12} \cdot x_2^0 + a_{13} \cdot x_3^0]}{a_{11}}$$

$$x_2^1 = \frac{b_2 - [a_{21} \cdot x_1^1 + a_{23} \cdot x_3^0]}{a_{22}}$$

$$x_3^1 = \frac{b_3 - [a_{31} \cdot x_1^1 + a_{32} \cdot x_2^1]}{a_{33}}$$

* Always using our most recent value of x_i to solve for the next $x_i^{(i+1)}$ value

- (5) Repeat step 4 for iteration 2 using same method!
- (6) Keep iterating until the difference between the left hand side of your independent equations & the right hand side of your independent equations

$$\text{Absolute value} \left[\frac{\text{LHS of Eqn}}{\text{RHS of Eqn}} - 1 \right] \leq \text{acceptable Error}$$