

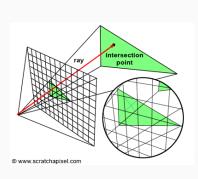
COMS 30115

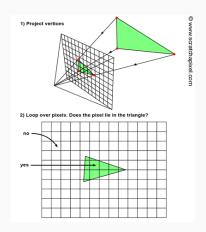
Rasterisation

Carl Henrik Ek - carlhenrik.ek@bristol.ac.uk March 1st, 2019

http://www.carlhenrik.com

Rasterisation vs Raytracing





Line Drawing

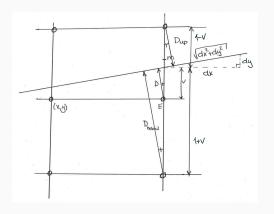
Breshenham

- Create a decision function f(x, y) (called implicit surface)
 - f(x, y) > 0 point below line
 - f(x, y) < 0 point above line
- Write decision function on integer form
 - $f(x, y) = \Delta y \cdot x \Delta x \cdot y + \Delta x \cdot c$
- Reuse previous computations and make iterative update of decision

Breshenham

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- Write decision function on integer form
 - $f(x, y) = \Delta y \cdot x \Delta x \cdot y + \Delta x \cdot c$
- Reuse previous computations and make iterative update of decision
- Can extend to anti-aliasing using value of decision function

Gupta-Sproull



- Area that pixel covers important
- Weight pixels with perpendicular distance

Gupta-Sproull

Code

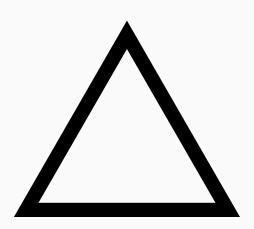
```
//compute constants A,B
//1. Run Breshenham and get d
if(d<0) //E pixel
{
    D = A*(d+dx);
    Dup = B-D;;
    Dbelow = B+D;
    // look-up shading based on D</pre>
```

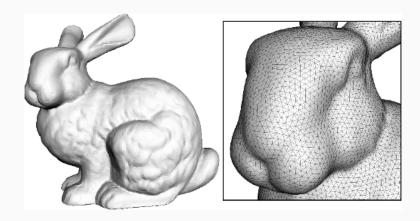
Today

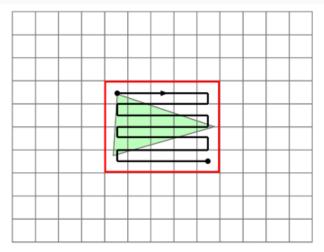
- Filled Triangles
- Prespective Correct Interpolation

The Book

- Paper on line drawing algorithms URL
- Prespective Correct Interpolation URL
- Most of Part II is covered URL

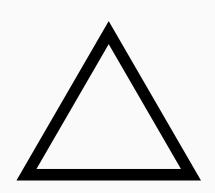






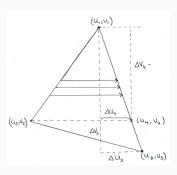
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- 1. compute number of ROWS
- compute left and right x-values
- 3. fill left->right

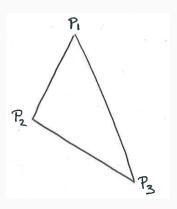


```
Code
vector<ivec2> leftPixel(ROWS);
vector<ivec2> rightPixel(ROWS);
/*draw outer lines to fill*/
for(uint32_t i=0;i<ROWS;i++)</pre>
    drawline(leftPixels[i],y0+i,
             rightPixel[i],y0+i);
```

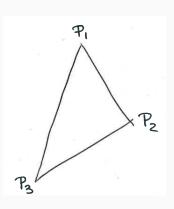
- Drawing Flat triangle is easy
- Split triangle into two flat ones
- special cases
- Draw lines



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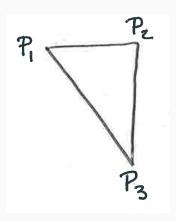
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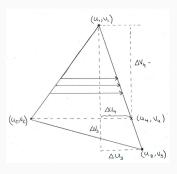
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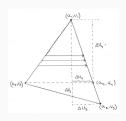
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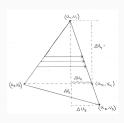
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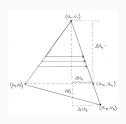
$$\frac{\Delta v_3}{\Delta u_3} = \frac{\Delta v_4}{\Delta u_4}$$



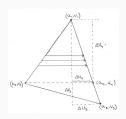
$$\frac{\Delta v_3}{\Delta u_3} = \frac{\Delta v_4}{\Delta u_4} \Rightarrow \Delta u_4 = \frac{\Delta v_4}{\Delta v_3} \Delta u_3$$



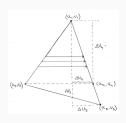
$$\frac{\Delta v_3}{\Delta u_3} = \frac{\Delta v_4}{\Delta u_4} \Rightarrow \Delta u_4 = \frac{\Delta v_4}{\Delta v_3} \Delta u_3$$
$$= \{ \Delta v_4 = v_4 - v_1, v_4 = v_2 \}$$



$$\frac{\Delta v_3}{\Delta u_3} = \frac{\Delta v_4}{\Delta u_4} \Rightarrow \Delta u_4 = \frac{\Delta v_4}{\Delta v_3} \Delta u_3$$
$$= \{ \Delta v_4 = v_4 - v_1, v_4 = v_2 \}$$
$$= \frac{v_2 - v_1}{v_3 - v_1} (u_3 - u_1)$$



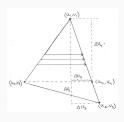
$$\begin{split} \frac{\Delta v_3}{\Delta u_3} &= \frac{\Delta v_4}{\Delta u_4} \Rightarrow \Delta u_4 = \frac{\Delta v_4}{\Delta v_3} \Delta u_3 \\ &= \{\Delta v_4 = v_4 - v_1, v_4 = v_2\} \\ &= \frac{v_2 - v_1}{v_3 - v_1} (u_3 - u_1) = \Delta u_4 = u_4 - u_1 \end{split}$$



$$\frac{\Delta v_3}{\Delta u_3} = \frac{\Delta v_4}{\Delta u_4} \Rightarrow \Delta u_4 = \frac{\Delta v_4}{\Delta v_3} \Delta u_3$$

$$= \{ \Delta v_4 = v_4 - v_1, v_4 = v_2 \}$$

$$= \frac{v_2 - v_1}{v_3 - v_1} (u_3 - u_1) = \Delta u_4 = u_4 - u_1$$
Solve for: u_4

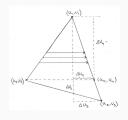


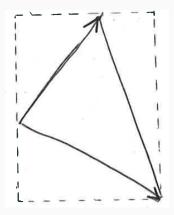
$$\frac{\Delta v_3}{\Delta u_3} = \frac{\Delta v_4}{\Delta u_4} \Rightarrow \Delta u_4 = \frac{\Delta v_4}{\Delta v_3} \Delta u_3$$

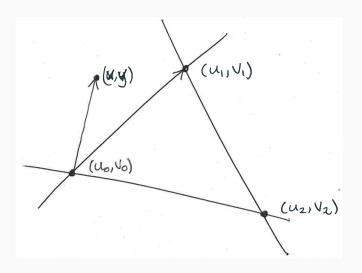
$$= \{ \Delta v_4 = v_4 - v_1, v_4 = v_2 \}$$

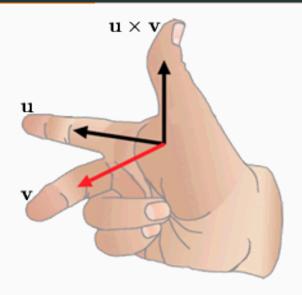
$$= \frac{v_2 - v_1}{v_3 - v_1} (u_3 - u_1) = \Delta u_4 = u_4 - u_1$$
Solve for: u_4

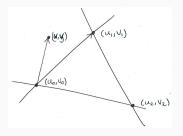
$$\Rightarrow u_4 = \frac{v_2 - v_1}{v_3 - v_4} (u_3 - u_1) + u_1$$



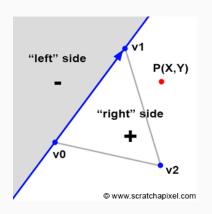


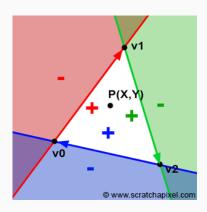




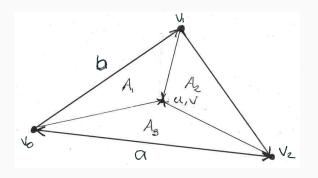


$$((u_1 - u_0, v_1 - v_0, 0 - 0) \times (u - u_0, v - v_0, 0 - 0)) = ((0, 0, (u - u_0)(v_1 - v_0) - (u_1 - u_0)(v - v_0))) = f_{01}(u, v)$$



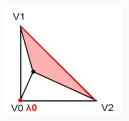


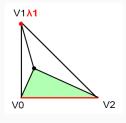
Barycentric coordinates

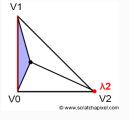


$$\mathbf{p} = \lambda_0 \mathbf{v}_0 + \lambda_1 \mathbf{v}_1 + \lambda_2 \mathbf{v}_2$$

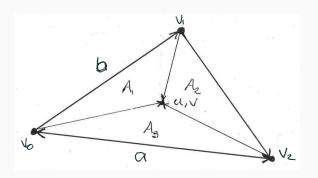
Barycentric coordinates (Area)





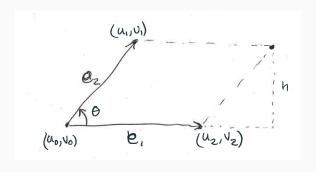


Barycentrinc coordinates



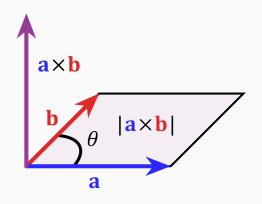
$$A = A_1 + A_2 + A_3$$

Paralellogram



$$A = ||\mathbf{e}_1|| \cdot ||\mathbf{e}_2|| \sin(\theta)$$

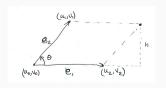
Cross-product

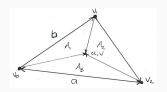


Definition (Cross-product)

$$\mathbf{a} \times \mathbf{b} = \underbrace{||\mathbf{a}|| \cdot ||\mathbf{b}|| \cdot \sin(\theta)}_{\mathsf{length}} \cdot \mathbf{n}$$

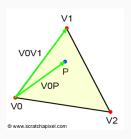
Paralellogram

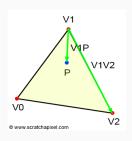




$$A = A_1 + A_2 + A_3 = \frac{1}{2}f_{01}(u,v) + \frac{1}{2}f_{12}(u,v) + \frac{1}{2}f_{20}(u,v)$$

Barycentric Coordinates





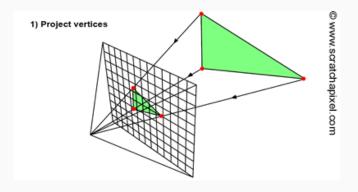


Triangle filling

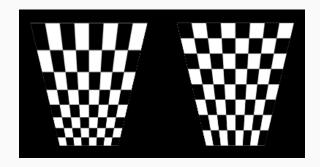
- The triangle filler in a rasteriser is like your closest intersection in the raytracer
 - make sure that it handles all the special cases
 - optimise
- There are many more methods
 - Möller-Trumbore

Perspective Correct

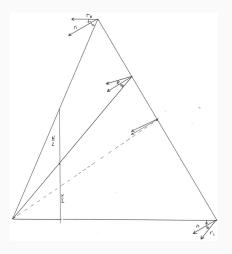
Rasterisation



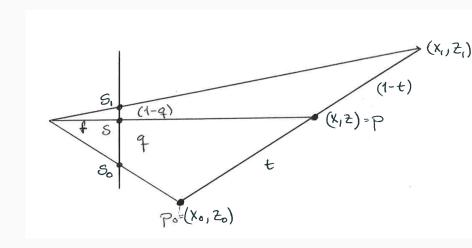
Perspective Error

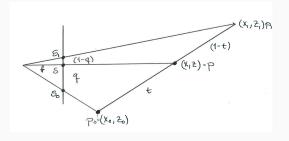


Perspective Correct



Perspective Correct





$$[x,z]^{\mathrm{T}} = \left[egin{array}{c} x_0 \ z_0 \end{array}
ight] (1-t) + \left[egin{array}{c} x_1 \ z_1 \end{array}
ight] t = \left[egin{array}{c} x_0 \ z_0 \end{array}
ight] + t \left(\left[egin{array}{c} x_1 - x_0 \ z_1 - z_0 \end{array}
ight]
ight) \ s = s_0(1-q) + s_1q = s_0 + q(s_1-s_0) \end{array}$$

can we write t as a function of q?

• s is a projected point

$$\left[s = \frac{x}{z}, \quad s_0 = \frac{x_0}{z_0}, \quad s_1 = \frac{x_1}{z_1} \right]$$

• Write in terms of interpolated quantities

$$s = \frac{X}{Z}$$

• s is a projected point

$$\left[s = \frac{x}{z}, \quad s_0 = \frac{x_0}{z_0}, \quad s_1 = \frac{x_1}{z_1} \right]$$

• Write in terms of interpolated quantities

$$s = \frac{x}{z} \Rightarrow z = \frac{x}{s}$$

• s is a projected point

$$\left[s = \frac{x}{z}, \quad s_0 = \frac{x_0}{z_0}, \quad s_1 = \frac{x_1}{z_1} \right]$$

Write in terms of interpolated quantities

$$s = \frac{x}{z} \Rightarrow z = \frac{x}{s} = \frac{x_0 + t(x_1 - x_0)}{s_0 + q(s_1 - s_0)}$$

• s is a projected point

$$\left[s = \frac{x}{z}, \quad s_0 = \frac{x_0}{z_0}, \quad s_1 = \frac{x_1}{z_1} \right]$$

• Write in terms of interpolated quantities

$$s = \frac{x}{z} \Rightarrow z = \frac{x}{s} = \frac{x_0 + t(x_1 - x_0)}{s_0 + q(s_1 - s_0)}$$
$$= \{x = s \cdot z\}$$

• s is a projected point

$$s = \frac{x}{z}, \quad s_0 = \frac{x_0}{z_0}, \quad s_1 = \frac{x_1}{z_1}$$

Write in terms of interpolated quantities

$$s = \frac{x}{z} \Rightarrow z = \frac{x}{s} = \frac{x_0 + t(x_1 - x_0)}{s_0 + q(s_1 - s_0)}$$
$$= \{x = s \cdot z\} = \frac{s_0 z_0 + t(s_1 z_1 - s_0 z_0)}{s_0 + q(s_1 - s_0)}$$

• s is a projected point

$$s = \frac{x}{z}, \quad s_0 = \frac{x_0}{z_0}, \quad s_1 = \frac{x_1}{z_1}$$

Write in terms of interpolated quantities

$$s = \frac{x}{z} \Rightarrow z = \frac{x}{s} = \frac{x_0 + t(x_1 - x_0)}{s_0 + q(s_1 - s_0)}$$
$$= \{x = s \cdot z\} = \frac{s_0 z_0 + t(s_1 z_1 - s_0 z_0)}{s_0 + q(s_1 - s_0)}$$
$$= z_0 + t(z_1 - z_0)$$

$$z_0 + t(z_1 - z_0) = \frac{s_0 z_0 + t(s_1 z_1 - s_0 z_0)}{s_0 + q(s_1 - s_0)}$$

$$z_0 + t(z_1 - z_0) = \frac{s_0 z_0 + t(s_1 z_1 - s_0 z_0)}{s_0 + q(s_1 - s_0)}$$

Multiply denominator

$$z_0s_0 + z_0q(s_1 - s_0) + ts_0(z_1 - z_0) + tq(z_1 - z_0)(s_1 - s_0)$$

= $s_0z_0 + t(s_1z_1 - s_0z_0)$

$$z_0 + t(z_1 - z_0) = \frac{s_0 z_0 + t(s_1 z_1 - s_0 z_0)}{s_0 + q(s_1 - s_0)}$$

Multiply denominator

$$z_0s_0 + z_0q(s_1 - s_0) + ts_0(z_1 - z_0) + tq(z_1 - z_0)(s_1 - s_0)$$

= $s_0z_0 + t(s_1z_1 - s_0z_0)$

Collect terms with the different "interpolants"

$$t(s_0(z_1-z_0)+q(z_1-z_0)(s_1-s_0)-(s_1z_1-s_0z_0))=-qz_0(s_1-s_0)$$

$$z_0 + t(z_1 - z_0) = \frac{s_0 z_0 + t(s_1 z_1 - s_0 z_0)}{s_0 + q(s_1 - s_0)}$$

Multiply denominator

$$z_0s_0 + z_0q(s_1 - s_0) + ts_0(z_1 - z_0) + tq(z_1 - z_0)(s_1 - s_0)$$

= $s_0z_0 + t(s_1z_1 - s_0z_0)$

Collect terms with the different "interpolants"

$$t(s_0(z_1-z_0)+q(z_1-z_0)(s_1-s_0)-(s_1z_1-s_0z_0))=-qz_0(s_1-s_0)$$

Identify square on LHS

$$t(s_1-s_0)(-z_1+q(z_1-z_0))=-qz_0(s_1-s_0)$$

• Simplify

$$t(z_1-q(z_1-z_0))=qz_0$$

Simplify

$$t(z_1-q(z_1-z_0))=qz_0$$

• Result 1

$$\Rightarrow t = \frac{qz_0}{z_1 - q(z_1 - z_0)}$$

Simplify

$$t(z_1 - q(z_1 - z_0)) = qz_0$$

• Result 1

$$\Rightarrow t = \frac{qz_0}{z_1 - q(z_1 - z_0)}$$

ullet We have written t in terms of q, now replace and write z in terms of q

$$z=z_0+t(z_1-z_0)$$

$$z = z_0 + t(z_1 - z_0) = z_0 + \frac{qz_0}{z_1 - q(z_1 - z_0)}(z_1 - z_0)$$

$$z = z_0 + t(z_1 - z_0) = z_0 + \frac{qz_0}{z_1 - q(z_1 - z_0)}(z_1 - z_0)$$
$$= z_0 + \frac{qz_1z_0 - qz_0^2}{qz_0 + z_1(1 - q)}$$

$$z = z_0 + t(z_1 - z_0) = z_0 + \frac{qz_0}{z_1 - q(z_1 - z_0)}(z_1 - z_0)$$

$$= z_0 + \frac{qz_1z_0 - qz_0^2}{qz_0 + z_1(1 - q)} = \frac{qz_0^2 + z_0z_1(1 - q) + qz_1z_0 - qz_0^2}{qz_0 + z_1(1 - q)}$$

$$z = z_0 + t(z_1 - z_0) = z_0 + \frac{qz_0}{z_1 - q(z_1 - z_0)}(z_1 - z_0)$$

$$= z_0 + \frac{qz_1z_0 - qz_0^2}{qz_0 + z_1(1 - q)} = \frac{qz_0^2 + z_0z_1(1 - q) + qz_1z_0 - qz_0^2}{qz_0 + z_1(1 - q)}$$

$$= \frac{z_0z_1}{qz_0 + z_1(1 - q)}$$

$$z = z_0 + t(z_1 - z_0) = z_0 + \frac{qz_0}{z_1 - q(z_1 - z_0)}(z_1 - z_0)$$

$$= z_0 + \frac{qz_1z_0 - qz_0^2}{qz_0 + z_1(1 - q)} = \frac{qz_0^2 + z_0z_1(1 - q) + qz_1z_0 - qz_0^2}{qz_0 + z_1(1 - q)}$$

$$= \frac{z_0z_1}{qz_0 + z_1(1 - q)} = \frac{1}{\frac{qz_0}{z_0z_1} + \frac{z_1(1 - q)}{z_0z_1}}$$

$$z = z_0 + t(z_1 - z_0) = z_0 + \frac{qz_0}{z_1 - q(z_1 - z_0)}(z_1 - z_0)$$

$$= z_0 + \frac{qz_1z_0 - qz_0^2}{qz_0 + z_1(1 - q)} = \frac{qz_0^2 + z_0z_1(1 - q) + qz_1z_0 - qz_0^2}{qz_0 + z_1(1 - q)}$$

$$= \frac{z_0z_1}{qz_0 + z_1(1 - q)} = \frac{1}{\frac{qz_0}{z_0z_1} + \frac{z_1(1 - q)}{z_0z_1}}$$

$$= \frac{1}{\frac{q}{z_1} + \frac{1 - q}{z_0}}$$

$$z = z_0 + t(z_1 - z_0) = z_0 + \frac{qz_0}{z_1 - q(z_1 - z_0)}(z_1 - z_0)$$

$$= z_0 + \frac{qz_1z_0 - qz_0^2}{qz_0 + z_1(1 - q)} = \frac{qz_0^2 + z_0z_1(1 - q) + qz_1z_0 - qz_0^2}{qz_0 + z_1(1 - q)}$$

$$= \frac{z_0z_1}{qz_0 + z_1(1 - q)} = \frac{1}{\frac{qz_0}{z_0z_1} + \frac{z_1(1 - q)}{z_0z_1}}$$

$$= \frac{1}{\frac{q}{z_1} + \frac{1 - q}{z_0}} = \frac{1}{\frac{1}{z_1} + q(\frac{1}{z_1} - \frac{1}{z_0})}$$

$$z = z_0 + t(z_1 - z_0) = z_0 + \frac{qz_0}{z_1 - q(z_1 - z_0)}(z_1 - z_0)$$

$$= z_0 + \frac{qz_1z_0 - qz_0^2}{qz_0 + z_1(1 - q)} = \frac{qz_0^2 + z_0z_1(1 - q) + qz_1z_0 - qz_0^2}{qz_0 + z_1(1 - q)}$$

$$= \frac{z_0z_1}{qz_0 + z_1(1 - q)} = \frac{1}{\frac{qz_0}{z_0z_1} + \frac{z_1(1 - q)}{z_0z_1}}$$

$$= \frac{1}{\frac{q}{z_1} + \frac{1 - q}{z_0}} = \frac{1}{\frac{1}{z_1} + q(\frac{1}{z_1} - \frac{1}{z_0})} = z$$

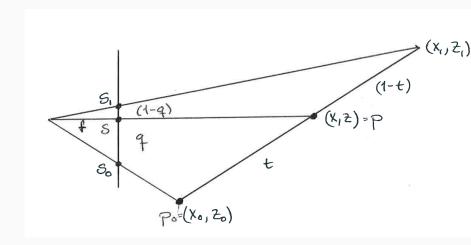
$$z = \frac{1}{\frac{1}{z_1} + q(\frac{1}{z_1} - \frac{1}{z_0})}$$

This leads to the final result

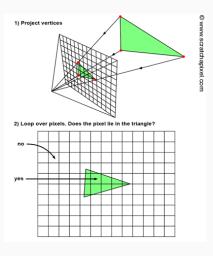
$$\frac{1}{z} = \frac{1}{z_0} + q \left(\frac{1}{z_1} - \frac{1}{z_0} \right)$$

- If you interpolate in screen space, you need to interpolate the inverse of the depth
- This is most likely the most important result in rasterisation

Perspective Correct



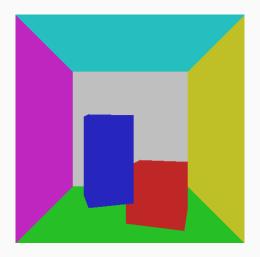
Perspective Correct



Summary

Summary

- Primitives
 - Lines
 - Triangles
- Perspective Correct
 - why is interpolation a bit challenging in image space
 - most likely the most important part of rasterisation



Next Time

Lecture interpolation of quantities

- Perspective correct interpolation
- Shading

Lab continue with Lab 2

• material is up to part 4

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