


## National University of Computer and Emerging Sciences, Lahore Campus

	<b>Course Name:</b>	Deep Learning	<b>Course Code:</b>	CS5102
	<b>Program:</b>	MS(DS)	<b>Semester:</b>	Fall 2018
	<b>Duration:</b>	180 Minutes	<b>Total Marks:</b>	100
	<b>Paper Date:</b>	26 Dec 18	<b>Weight</b>	40
	<b>Section:</b>	ALL	<b>Page(s):</b>	11
	<b>Exam Type:</b>	Final		

**Student : Name:** \_\_\_\_\_

**Roll No.** \_\_\_\_\_

**Section:** \_\_\_\_\_

### Instructions

- 1: Please show all your work. Please write answers on the question paper. You can attach extra sheet to the exam if needed.
- 2: This is an open book exam.
- 3: All questions are explained clearly. If you find some question's statement ambiguous, you can make reasonable assumptions as long as you state them clearly.
- 4: All problems carry equal marks.

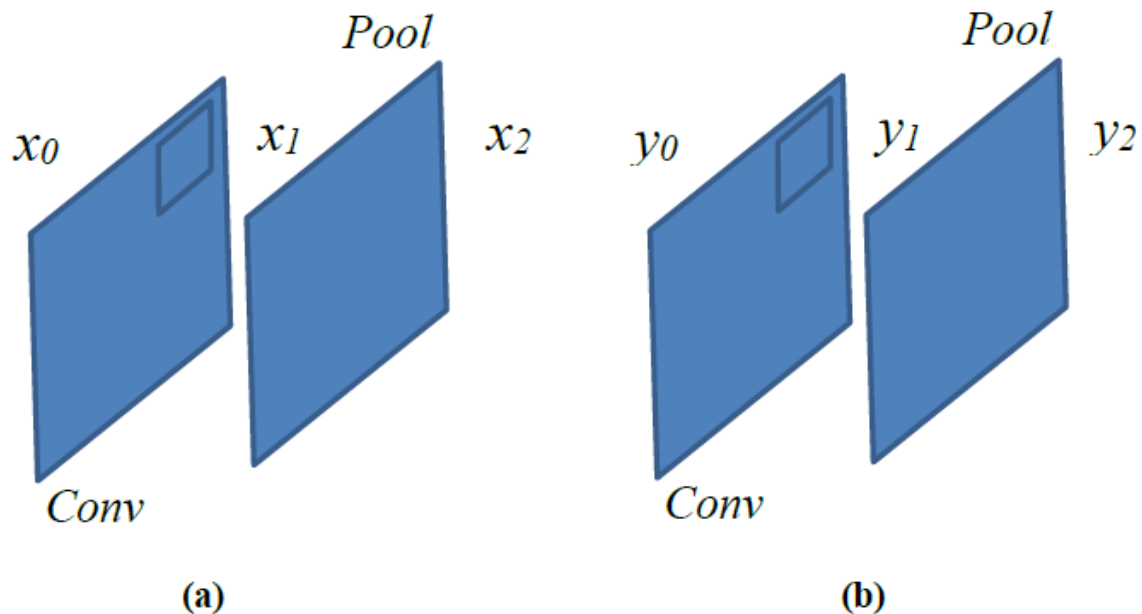
Good luck!

**Problem 1:** The following training patterns are given:

$x$  such that  $[-3,-2] \in C_1$ ,  $[0,1] \in C_2$  and  $[3,2] \in C_1$

- a) Plot the data points.
- b) You have a single neuron with threshold activation and a single input  $x$  to classify this data. Can we achieve 100% accuracy? Find the weight that gives you the best performance.
- c) Can you transform  $x$  such that you can classify this data with a single neuron? What input transformation  $y = f(x)$  makes the data linearly separable?

## Problem 2:



A CNN is being used for a classification task, and one part of the CNN is shown above in (a). The input image is passed through a convolutional layer followed by a max-pooling layer to produce outputs  $x_1$  and  $x_2$  respectively.

The same CNN is passed another input  $y_0 = cx_0$  where  $c > 0$  as shown in (b).

(a): How is  $y_1$ , the output of convolutional layer with new input, related to  $x_1$ ? Justify your answer. In the light of this, what can you say about effect of scaling a convolutional layer's input by a positive constant?

(b): How is  $y_2$ , the output of pooling layer with new input, related to  $x_2$ ? Justify your answer. In the light of this, what can you say about effect of scaling a max-pooling layer's input by a positive constant?

(c) : As a result of (a) and (b), can you say that a CNN containing convolutional and pooling layers only will have no effect on scaling the input by  $c > 0$ .

(d) : What if the input is scaled by  $c < 0$ ? Will  $y_2$  and  $x_2$  still maintain the same relationship? If not, which layer will change?





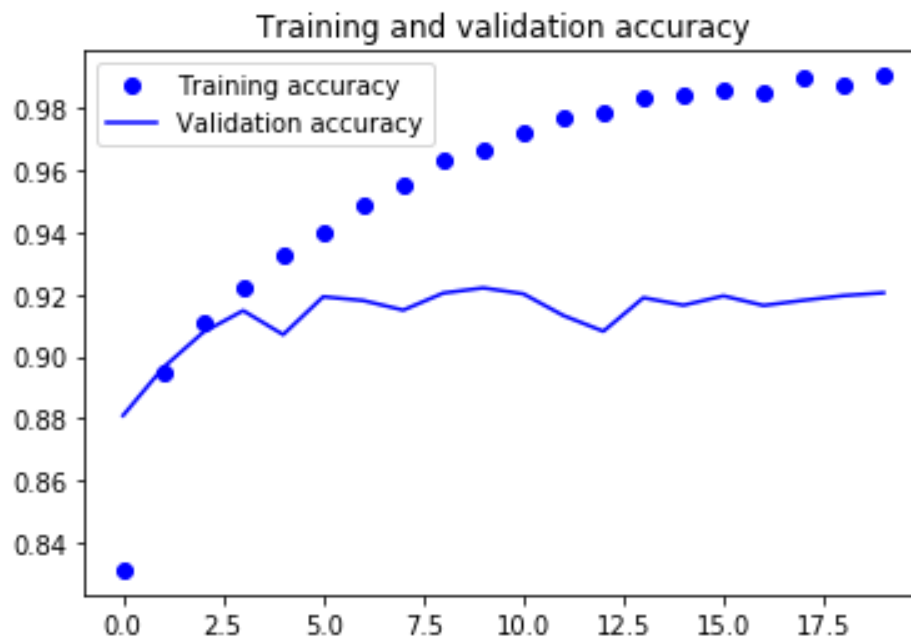
### Problem 3:

(a): In the generator/discriminator two player game discussed in class, we intend to make a modification.

We have a pre-trained MNIST classifier (discriminator) which can give us the probability of input character *not being* 6 ( $p(x_i)$  is not equal to 6 ). We need to use the generator to create new images of character 6 which look like actual 6 images.

Write the generator-discriminator adversarial cost function for this problem. Also write the generator and discriminator updates.

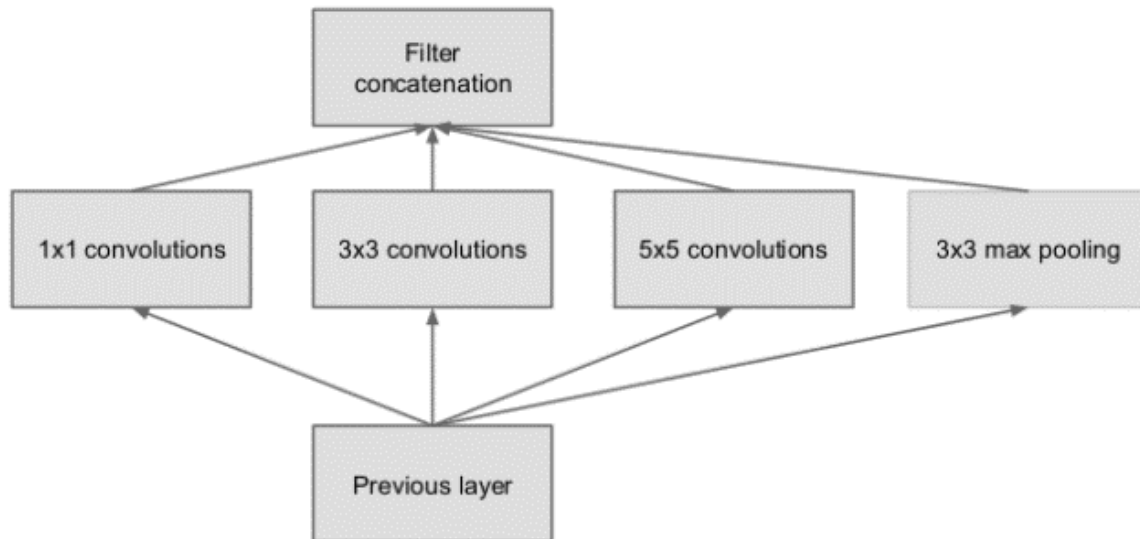
(b): For a given neural network, training produces the following plot.



What is most likely wrong with this training?

#### Problem 4:

A single inception module (shown below) is given an input of size  $(128 \times 128 \times 32)$ . Each convolution layer has 32 filters in it.



(a): Find the values of  $P$  (zero padding),  $S$  (stride) and  $F$  (filter size) and  $K$  (number of filters) for each layer so that each layer produces an output of  $(64 \times 64 \times 32)$ .



(b): What is the size of the total output after filter concatenation? How can we reduce the depth of the inception module output if we require an input of  $(64 \times 64 \times 24)$  in next stage?

**Problem 5:** In a video processing problem, you intend to predict the next scene type (action, drama, conversation, scene change) in a movie, based on the previous video frames.

The classification depends not just on the current frame, but also the movie type (T), cast likelihood(C) and previous scene (P).

(a): Out of VGG, GoogleNet, ResNet, RNN and LSTM, what type of convolutional neural network will you use to model this problem and why? Draw a rough diagram of where each input will go (T, C, P,  $x_i$ ) in your model.

(b): For the LSTM shown below, modify the machine for a problem with memory delay. Specifically, change the LSTM machine such that current input  $x_i$  does not have an effect on current output but only affects the output after  $n$  instances.

