

Course:
Program:
Duration:
Paper Date:
Object-oriented Programming
BS (Computer Science)
90 Minutes
'19-Oct-20

Section:

Exam:

90 Minutes '19-Oct-20 ALL Midterm-I Course Code: Semester: Total Marks: Weight Page(s):

Reg. No.

CS-217 Spring 2020 35 12.5 %

Instruction/Notes: Please solve the exam on paper. No answer sheets to be attached.

Question 1 (5+5=10 points)

For code segments given below identify **output or error**. In case of error **highlight the line** that will cause the error and describe the error in few lines. If a code segment produces garbage value represent it with "G". Note: There is no syntax error in following code segments.

```
Part (i)
                                                       1000 600
void function B(int* &p, int *q)
                                                       1000 800
{
       q = new int;
                                                       800 800
       *q = *p - 100;
       *p = *q - 100;
       delete q;
void function_A(int * p, int* &q)
       p = new int;
       *p = *q + 100;
       *q = *p + 100;
       function_B(p, q);
       delete p;
}
int main()
{
       int x = 1000;
       int* ptr1=&x;
       int* ptr2 =new int;
       *ptr2 = 600;
       cout << *ptr1 << " " << *ptr2 << endl;</pre>
       function_A(ptr1, ptr2);
       cout << *ptr1 << " " << *ptr2 << endl;</pre>
       function_B(ptr1, ptr2);
       cout << *ptr1 << " " << *ptr2;</pre>
       delete ptr2;
       return 0;
}
```



int main(){

Sessional-I";

cout << str2;
return 0;</pre>

Mystery(str2, str1);

Course:
Program:
Duration:
Paper Date:
Section:

Exam:

char str1[] = "Object Oriented Programming

char str2[] = "Winter is Coming!";

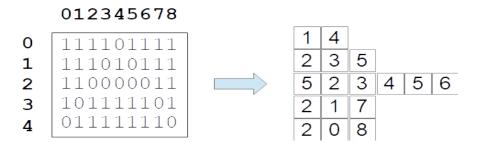
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ALL

Midterm-I

Question 2 (10 points)

Consider a black and white image that is represented as a matrix of 1's and 0's. We would like to compress the image by storing the index location of a specific value (either 0 or 1) for each row. For instance, the figure below shows transformation of an image in our desired encoding by storing location of 0's:



The first cell in each row of the result shows the number of locations with the specific value (0 or 1) in that row of the original matrix. Write a function that uses the following prototype for this transformation:

int** compress(int** image, int rows, int columns, int value);

Use dynamic memory allocation for the result. The parameter **value** specifies the value to use for compression (either 0 or 1).



Course:
Program:
Duration:
Paper Date:
Section:

Exam:

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Midterm-I

Course Code: Semester: Total Marks: Weight Page(s): Reg. No. CS-217 Spring 2020 35 12.5 %

```
int** compress(int** image, int rows, int columns, int value){
    int** compressedImage = new int*[rows];
    for(int i=0; i < rows; i++) {
        int count = 0;
        for (int j=0; j < columns; j++) {
             if (image[i][j] == value){
                count++;
            }
        }
        compressedImage[i] = new int[count+1];
        compressedImage[i][0] = count;
        for (int j=0, k=1; j < columns; j++) {
            if (image[i][j] == value) {
                compressedImage[i][k] = j;
                k++;
            }
        }
    return compressedImage;
```



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Question 3 (15 points)

Consider a polyline that comprises of multiple line segments connected together. Each line segment can be represented as a pair of x-y coordinates and two adjacent segments share a common coordinate i.e. a new line segment starts where the previous ends. A sample polyline is depicted below. Length of a polyline can be computed by summing up the length of each segment. Provide implementation for a C++ class such that it may be used to instantiate objects as given in the following driver program:

```
int main()
{
    int coordinates[][2] =
        {{1,0},{3,4},{2,4},{4,9}};
    Polyline line(coordinates,4);
    cout << line.length() << endl;
        // prints 10.85

    return 0;
}</pre>
```

Fig 3(a): A sample driver program

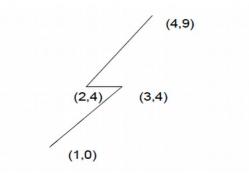


Fig 3(b): An illustration of an actual polyline

You must ensure the following in your answer:

- header and implementation are separate
- provide implementation of necessary constructor(s), destructor and member functions as given in the driver program
- use dynamic memory allocation to avoid unnecessary space.

Note: Length of a line segment can be calculated using Euclidean distance: $\sqrt{(x_2-x_1)^2 + (y_2-y_1)^2}$. You can use standard math library for your implementation.



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// provide header definition here

```
class Polyline
{
    private:
        int (*coordinates)[2];
        int size;

    public:
        Polyline();
        Polyline(int coordinates[][2],int size);
        float length();
        ~Polyline();
};
```

// provide implementation here



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```
Polyline::Polyline()
    coordinates = 0;
    size = 0;
Polyline::Polyline(int coordinates[][2], int size)
    this->size = size;
   this->coordinates = new int[size][2];
   for(int i=0; i < this->size; i++){
        this->coordinates[i][0] = coordinates[i][0];
        this->coordinates[i][1] = coordinates[i][1];
    }
float Polyline::length() {
   float result = 0;
    for (int i=0; i < this -> size -1; i++) {
        result += sqrt(pow(this->coordinates[i+1][0] - this->coordinates[i][0],2)+
                        pow(this->coordinates[i+1][1] - this->coordinates[i][1],2));
   return result;
Polyline::~Polyline()
    if (this->coordinates != 0) {
        delete [] this->coordinates;
    }
```