

In the grading of the exercises special attention will be paid to check that answers are substantiated and that the procedure of calculations is well documented. When results are achieved using a calculator or a pc it should be noted in the paper. All 6 problems are weighted equally in the grading. Your solution to the problem set can be written in Danish or English as you prefer.

### PROBLEM 1.

Consider the following matrix and vector

$$A = \begin{bmatrix} 2 & 1 & 4 \\ -1 & 0 & -3 \\ 3 & 2 & 5 \\ 1 & -2 & 7 \end{bmatrix}, \quad \mathbf{b} = \begin{bmatrix} 4 \\ -4 \\ 4 \\ 12 \end{bmatrix}.$$

1. Is  $\mathbf{x} = [1 \ 2 \ 1]^T$  a solution of  $A\mathbf{x} = \mathbf{b}$ ?
2. Determine the general solution of  $A\mathbf{x} = \mathbf{b}$ .
3. How many vectors are there in the solution set?

### PROBLEM 2.

In the following two equations  $A$ ,  $B$ ,  $C$ ,  $I$  and  $X$  are all  $n \times n$  matrices.

$$(i) \quad A(X + I) = B, \quad (ii) \quad XA = XB + C.$$

1. Solve equations (i) and (ii) for  $X$  and account for any assumptions made.

Next, consider an invertible  $n \times n$  matrix  $A$  with the following property

$$A^2 = 5A + 2I.$$

2. Show that  $A^3 = 27A + 10I$  and  $A^{-1} = \frac{1}{2}(A - 5I)$ .

### PROBLEM 3.

For the statements given below, state whether they are true or false and justify your answer for each statement.

1. For an  $2 \times 3$  matrix  $A$  with rank 2 and a  $2 \times 1$  vector  $\mathbf{b}$  the equation  $A\mathbf{x} = \mathbf{b}$  will always have a solution.
2. The rotation matrix  $\begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$  where  $\theta$  is a real scalar is an orthogonal matrix.
3. Eigenvalues must be nonzero scalars.

**PROBLEM 4.**

Consider the  $3 \times 3$  matrix  $A$  given as

$$A = \begin{bmatrix} 1 & 6 & 2 \\ 1 & 6 & 4 \\ 1 & 3 & 2 \end{bmatrix}.$$

1. Show that the column vectors of  $A$  are linearly independent and span  $\mathbb{R}^3$ .
2. Show that no pair of column vectors from  $A$  is orthogonal.
3. Calculate an orthogonal basis for  $\mathbb{R}^3$  using the column vectors from  $A$  and the Gram-Schmidt procedure.

**PROBLEM 5.**

This problem is based on the case “Error-Detecting and Error-Correcting Codes”. All calculations must therefore be done using  $\mathbb{Z}_2$  arithmetics, i.e. with binary numbers. Let the matrix  $A$  and the vector  $\mathbf{x}$  be given by

$$A = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 0 \\ 1 & 1 & 0 \end{bmatrix}, \quad \mathbf{x} = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}.$$

1. Calculate  $A\mathbf{x}$ .
2. Determine the rank of  $A$  and calculate a basis for the null space of  $A$ .

**PROBLEM 6.**

Consider the set of all solutions to the differential equation

$$y'(x) + y(x) = 0,$$

where the prime denotes the derivative, i.e.  $y'(x) = \frac{dy}{dx}$ . In this problem it will be shown that the set of solutions to the differential equation fulfil the necessary properties to form a vector space.

1. Show that the zero function  $y_0(x) = 0$  is in the set.
2. Show that if a function  $y_1(x)$  is in the set, then  $cy_1(x)$  is also in the set, where  $c$  is a scalar.
3. Show that if two functions  $y_1(x)$  and  $y_2(x)$  each are in the set, then  $y_1(x) + y_2(x)$  is also in the set.