

Problem 1

Let the matrix A and vector \mathbf{b} be given by:

$$A = \begin{bmatrix} 2 & -1 & 2 & 1 \\ 4 & -3 & 0 & 7 \\ -1 & 0 & -3 & 2 \end{bmatrix} \text{ and } \mathbf{b} = \begin{bmatrix} 0 \\ 6 \\ \alpha \end{bmatrix}$$

- a) Determine α so the system of equations $A\mathbf{x} = \mathbf{b}$ are consistent.
- b) Determine all solutions to the consistent system of equations $A\mathbf{x} = \mathbf{b}$.

Solution:

- a) Row reduction of the augmented matrix:

$$[A|\mathbf{b}] = \left[\begin{array}{cccc|c} 2 & -1 & 2 & 1 & 0 \\ 4 & -3 & 0 & 7 & 6 \\ -1 & 0 & -3 & 2 & \alpha \end{array} \right] \sim \left[\begin{array}{cccc|c} 1 & 0 & 3 & -2 & -\alpha \\ 0 & 1 & 4 & -5 & -6 \\ 0 & 0 & 0 & 0 & \alpha - 3 \end{array} \right]$$

Third row: The system is consistent only for $\alpha = 3$.

- b) For $\alpha = 3$:

$$[A|\mathbf{b}] = \left[\begin{array}{cccc|c} 2 & -1 & 2 & 1 & 0 \\ 4 & -3 & 0 & 7 & 6 \\ -1 & 0 & -3 & 2 & 3 \end{array} \right] \sim \left[\begin{array}{cccc|c} 1 & 0 & 3 & -2 & -3 \\ 0 & 1 & 4 & -5 & -6 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right] \rightarrow \text{Two free variables: } x_3, x_4$$

From the row reduction it is seen, that the general solution to:

$$\left[\begin{array}{cccc} 2 & -1 & 2 & 1 \\ 4 & -3 & 0 & 7 \\ -1 & 0 & -3 & 2 \end{array} \right] \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 0 \\ 6 \\ 3 \end{bmatrix} \Rightarrow \mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} -3 \\ -6 \\ 0 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} -3 \\ -4 \\ 1 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} 2 \\ 5 \\ 0 \\ 1 \end{bmatrix}$$

Problem 2

The following four vectors are given by:

$$\mathbf{v}_1 = \begin{bmatrix} 2 \\ 1 \\ -1 \\ 0 \end{bmatrix}, \quad \mathbf{v}_2 = \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}, \quad \mathbf{v}_3 = \begin{bmatrix} 1 \\ 2 \\ 2 \\ 1 \end{bmatrix}, \quad \mathbf{b} = \begin{bmatrix} 0 \\ 9 \\ 13 \\ 4 \end{bmatrix}$$

- a) Determine whether the set of vectors $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$ is linearly independent.
- b) Write – if possible – \mathbf{b} as a linear combination of $\mathbf{v}_1, \mathbf{v}_2$ and \mathbf{v}_3 .

Solution:

- a) Linear independence is checked by forming the matrix $V = [\mathbf{v}_1 \mathbf{v}_2 \mathbf{v}_3]$ and row reducing:

$$V = [\mathbf{v}_1 \mathbf{v}_2 \mathbf{v}_3] = \begin{bmatrix} 2 & 1 & 1 \\ 1 & 1 & 2 \\ -1 & 1 & 2 \\ 0 & 1 & 1 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}$$

Since there are three pivot columns the three vectors are linearly independent.

- b) Finding the possible linear combination of $\mathbf{v}_1, \mathbf{v}_2$ and \mathbf{v}_3 to give the vector $\mathbf{b} = c_1\mathbf{v}_1 + c_2\mathbf{v}_2 + c_3\mathbf{v}_3$ is equivalent to row reduction of the augmented matrix:

$$[V|\mathbf{b}] = \left[\begin{array}{ccc|c} 2 & 1 & 1 & 0 \\ 1 & 1 & 2 & 9 \\ -1 & 1 & 2 & 13 \\ 0 & 1 & 1 & 4 \end{array} \right] \sim \left[\begin{array}{ccc|c} 1 & 0 & 0 & -2 \\ 0 & 1 & 0 & -3 \\ 0 & 0 & 1 & 7 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

So: $\mathbf{b} = -2\mathbf{v}_1 - 3\mathbf{v}_2 + 7\mathbf{v}_3 = -2 \begin{bmatrix} 2 \\ 1 \\ -1 \\ 0 \end{bmatrix} - 3 \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} + 7 \begin{bmatrix} 1 \\ 2 \\ 2 \\ 1 \end{bmatrix} = \begin{bmatrix} -4 - 3 + 7 \\ -2 - 3 + 14 \\ 2 - 3 + 14 \\ 0 - 3 + 7 \end{bmatrix} = \begin{bmatrix} 0 \\ 9 \\ 13 \\ 4 \end{bmatrix}$ o.k.

Problem 3

For the statements given below, state whether they are true or false and justify your answer for each statement:

- a) If A and B are two symmetric $n \times n$ matrices, then $C = A - 2B$ is also symmetric.

- b) The determinant of $\begin{vmatrix} 3a & 3b & 3c \\ 3c & 3a & 3b \\ 3b & 3c & 3a \end{vmatrix}$ is nine times the determinant of $\begin{vmatrix} a & b & c \\ c & a & b \\ b & c & a \end{vmatrix}$.

- c) If A is a real $n \times n$ matrix with n odd ($3, 5, 7, \dots$) and A has a complex eigenvalue, then A will also have a real eigenvalue.

Solution:

- a) **True**, since $(A - 2B)^T = A^T - 2B^T = A - 2B$ (A and B symmetric $\Leftrightarrow A^T = A$ and $B^T = B$)

- b) **False**. Multiplying a row with a constant, the determinant is multiplied with the same

constant (Theorem 3.3c). So $\begin{vmatrix} 3a & 3b & 3c \\ 3c & 3a & 3b \\ 3b & 3c & 3a \end{vmatrix} = 3 \cdot 3 \cdot 3 \cdot \begin{vmatrix} a & b & c \\ c & a & b \\ b & c & a \end{vmatrix} = 27 \begin{vmatrix} a & b & c \\ c & a & b \\ b & c & a \end{vmatrix}$.

- c) **True.** Complex eigenvalues of real matrices always comes in conjugate pairs $(\lambda, \bar{\lambda})$ (see the paragraph preceding Example 5 in Chap.5.5). So with n odd at least one eigenvalue of A must be real.

Problem 4

In the following two equations A, B, C and I are all $n \times n$ matrices.

$$(i) \quad A(X + 2I)B = BA \qquad (ii) \quad XA = C + XB$$

- a) Solve equation (i) and (ii) for X and account for any assumptions made.

Next, consider an invertible $n \times n$ matrix A with the following property:

$$A^2 = A - I$$

- b) Show that $A^3 = -I$ and $A^{-1} = -A^2$.

Solution:

- a) (i) $A(X + 2I)B = BA \Leftrightarrow X + 2I = A^{-1}BAB^{-1} \Leftrightarrow X = A^{-1}BAB^{-1} - 2I$
(ii) $XA = C + XB \Leftrightarrow X(A - B) = C \Leftrightarrow X = C(A - B)^{-1}$
Assuming that in (i) A and B and in (ii) $(A - B)$ are invertible.

b) $A^3 = AA^2 = A(A - I) = A^2 - A = A - I - A = -I$
 $A = A^{-1}A^2 = A^{-1}(A - I) = A^{-1}A - A^{-1} = I - A^{-1} \Rightarrow A^{-1} = I - A = -A^2$

Problem 5

Let the matrix A and vector x be given by:

$$A = \begin{bmatrix} -1 & -1 & -2 & 3 \\ 2 & 6 & 4 & -14 \\ 1 & 5 & 2 & -11 \\ 4 & 1 & 8 & -6 \end{bmatrix} \quad \text{and} \quad x = \begin{bmatrix} 2 \\ -3 \\ 2 \\ 1 \end{bmatrix}$$

- a) Determine $\text{rank } A$ and $\dim \text{Nul } A$.
b) Find a orthonormal basis for $\text{Nul } A$.
c) Is x in $\text{Nul } A$?

Solution:

a) Row reduction of A : $\left[\begin{array}{cccc} -1 & -1 & -2 & 3 \\ 2 & 6 & 4 & -14 \\ 1 & 5 & 2 & -11 \\ 4 & 1 & 8 & -6 \end{array} \right] \sim \left[\begin{array}{cccc} 1 & 0 & 2 & -1 \\ 0 & 1 & 0 & -2 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$, shows that A has two pivot

columns and therefore $\text{rank } A = 2$.

From the Rank Theorem 4.14: $\dim \text{Nul } A = \text{Number of columns} - \text{rank } A = 4 - 2 = 2$

b) From the row reduction of A it is seen that $\text{Nul } A$ is spanned by the two vectors:

$$\boldsymbol{v}_1 = \begin{bmatrix} -2 \\ 0 \\ 1 \\ 0 \end{bmatrix} \quad \text{and} \quad \boldsymbol{v}_2 = \begin{bmatrix} 1 \\ 2 \\ 0 \\ 1 \end{bmatrix}.$$

Since $\boldsymbol{v}_1 \cdot \boldsymbol{v}_2 = -2$, they are not orthogonal, and we find an orthonormal set by using the Gram-Schmidt process with \boldsymbol{v}_1 as the first vector and the orthogonal complement of \boldsymbol{v}_2 :

$$\hat{\boldsymbol{v}}_2 = \boldsymbol{v}_2 - \frac{\boldsymbol{v}_1 \cdot \boldsymbol{v}_2}{\boldsymbol{v}_1 \cdot \boldsymbol{v}_1} \boldsymbol{v}_1 = \begin{bmatrix} 1 \\ 2 \\ 0 \\ 1 \end{bmatrix} - \frac{-2}{5} \begin{bmatrix} -2 \\ 0 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 1/5 \\ 2 \\ 2/5 \\ 1 \end{bmatrix}$$

as the second vector.

Normalizing we get:

$$\boldsymbol{u}_1 = \frac{\boldsymbol{v}_1}{\|\boldsymbol{v}_1\|} = \frac{1}{\sqrt{5}} \begin{bmatrix} -2 \\ 0 \\ 1 \\ 0 \end{bmatrix} = \frac{1}{\sqrt{5}} \begin{bmatrix} -2 \\ 0 \\ 1 \\ 0 \end{bmatrix} \quad \text{and} \quad \boldsymbol{u}_2 = \frac{\hat{\boldsymbol{v}}_2}{\|\hat{\boldsymbol{v}}_2\|} = \sqrt{\frac{5}{26}} \begin{bmatrix} 1/5 \\ 2 \\ 2/5 \\ 1 \end{bmatrix} = \frac{1}{\sqrt{130}} \begin{bmatrix} 1 \\ 2 \\ 2 \\ 5 \end{bmatrix}$$

as an orthonormal basis of $\text{Nul } A$.

c) Since $A \cdot \boldsymbol{x} = \left[\begin{array}{cccc} -1 & -1 & -2 & 3 \\ 2 & 6 & 4 & -14 \\ 1 & 5 & 2 & -11 \\ 4 & 1 & 8 & -6 \end{array} \right] \begin{bmatrix} 2 \\ -3 \\ 2 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ -20 \\ -20 \\ 15 \end{bmatrix} \neq \mathbf{0}$, \boldsymbol{x} is NOT in $\text{Nul } A$.

Problem 6

A quadric form is given by: $Q(\mathbf{x}) = 3x_1^2 + 4x_2^2 - 2x_3^2 - 6x_1x_2 + 2x_1x_3 - 8x_2x_3$

- Determine the matrix A , so $Q(\mathbf{x}) = \mathbf{x}^T A \mathbf{x}$
- Find the principal axes and rewrite the quadratic form in the coordinate system of the principal axes.
- Find the maximum and minimum values of $Q(\mathbf{x})$ subject to the constraint $\|\mathbf{x}\| = 1$.

Solution:

a) The symmetric matrix of the quadratic form is: $A = \begin{bmatrix} 3 & -3 & 1 \\ -3 & 4 & -4 \\ 1 & -4 & -2 \end{bmatrix}$

b) The eigenvalues of A: $\lambda := \text{eigenvals}(A) = \begin{bmatrix} 7.976 \\ 1.057 \\ -4.033 \end{bmatrix}$

Diagonal matrix: $D = \begin{bmatrix} 7.976 & 0 & 0 \\ 0 & 1.057 & 0 \\ 0 & 0 & -4.033 \end{bmatrix}$

The corresponding eigenvectors: $P := \text{eigenvecs}(A) = \begin{bmatrix} 0.534 & 0.842 & 0.074 \\ -0.765 & 0.444 & 0.466 \\ 0.36 & -0.305 & 0.881 \end{bmatrix}$

Diagonalization: $P \cdot D \cdot P^{-1} = \begin{bmatrix} 3 & -3 & 1 \\ -3 & 4 & -4 \\ 1 & -4 & -2 \end{bmatrix} = A \quad \text{o.k.}$

The Principal axis (= eigenvectors): $e_1 = \begin{bmatrix} 0.534 \\ -0.765 \\ 0.36 \end{bmatrix} \quad e_2 = \begin{bmatrix} 0.842 \\ 0.444 \\ -0.305 \end{bmatrix} \quad e_3 = \begin{bmatrix} 0.074 \\ 0.466 \\ 0.881 \end{bmatrix}$

Quadratic form: $Q(\mathbf{y}) = \lambda_1 y_1^2 + \lambda_2 y_2^2 + \lambda_3 y_3^2 = 7.976y_1^2 + 1.057y_2^2 - 4.033y_3^2$

- c) Subject to constraint $\|\mathbf{x}\| = 1$: $Q(\mathbf{x})_{\max} = \lambda_{\max} = 7.976$

$$Q(\mathbf{x})_{\min} = \lambda_{\min} = -4.033$$