

My Project

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Chapter 1

Namespace Index

1.1 Namespace List

Here is a list of all namespaces with brief descriptions:

matrix	7
----------------------------------	---

Chapter 2

Class Index

2.1 Class List

Here are the classes, structs, unions and interfaces with brief descriptions:

[matrix::Matrix](#)

A class for performing operations on 2D matrices such as addition, subtraction, and multiplication 9

[matrix::vector](#)

A class for performing vector operations such as addition, subtraction, scaling, dot product, magnitude, and cosine similarity 11

Chapter 3

File Index

3.1 File List

Here is a list of all files with brief descriptions:

vector.cpp	15
vector.h	16

Chapter 4

Namespace Documentation

4.1 matrix Namespace Reference

Classes

- class [Matrix](#)
A class for performing operations on 2D matrices such as addition, subtraction, and multiplication.
- class [vector](#)
A class for performing vector operations such as addition, subtraction, scaling, dot product, magnitude, and cosine similarity.

Chapter 5

Class Documentation

5.1 matrix::Matrix Class Reference

A class for performing operations on 2D matrices such as addition, subtraction, and multiplication.

```
#include <vector.h>
```

Static Public Member Functions

- static std::vector< std::vector< int > > [add2D](#) (const std::vector< std::vector< int > > &firstMatrix, const std::vector< std::vector< int > > &secondMatrix)
Adds two 2D matrices element-wise.
- static std::vector< std::vector< int > > [subtract2D](#) (const std::vector< std::vector< int > > &firstMatrix, const std::vector< std::vector< int > > &secondMatrix)
Subtracts the second 2D matrix from the first 2D matrix element-wise.
- static std::vector< std::vector< int > > [multiply2D](#) (const std::vector< std::vector< int > > &firstMatrix, const std::vector< std::vector< int > > &secondMatrix)
Multiplies two 2D matrices.

5.1.1 Detailed Description

A class for performing operations on 2D matrices such as addition, subtraction, and multiplication.

Definition at line [138](#) of file [vector.h](#).

5.1.2 Member Function Documentation

5.1.2.1 add2D()

```
static std::vector< std::vector< int > > matrix::Matrix::add2D (  
    const std::vector< std::vector< int > > & firstMatrix,  
    const std::vector< std::vector< int > > & secondMatrix) [inline], [static]
```

Adds two 2D matrices element-wise.

Parameters

<i>firstMatrix</i>	The first matrix.
<i>secondMatrix</i>	The second matrix.

Returns

The resultant matrix after addition.

Exceptions

<i>std::invalid_argument</i>	if the matrices have different dimensions.
------------------------------	--

Definition at line 147 of file [vector.h](#).

5.1.2.2 multiply2D()

```
static std::vector< std::vector< int > > matrix::Matrix::multiply2D (
    const std::vector< std::vector< int > > & firstMatrix,
    const std::vector< std::vector< int > > & secondMatrix) [inline], [static]
```

Multiplies two 2D matrices.

Parameters

<i>firstMatrix</i>	The first matrix.
<i>secondMatrix</i>	The second matrix.

Returns

The resultant matrix after multiplication.

Exceptions

<i>std::invalid_argument</i>	if the number of columns in the first matrix is not equal to the number of rows in the second matrix.
------------------------------	---

Definition at line 205 of file [vector.h](#).

5.1.2.3 subtract2D()

```
static std::vector< std::vector< int > > matrix::Matrix::subtract2D (
    const std::vector< std::vector< int > > & firstMatrix,
    const std::vector< std::vector< int > > & secondMatrix) [inline], [static]
```

Subtracts the second 2D matrix from the first 2D matrix element-wise.

Parameters

<i>firstMatrix</i>	The first matrix.
<i>secondMatrix</i>	The second matrix.

Returns

The resultant matrix after subtraction.

Exceptions

<code>std::invalid_argument</code>	if the matrices have different dimensions.
------------------------------------	--

Definition at line 176 of file [vector.h](#).

The documentation for this class was generated from the following file:

- [vector.h](#)

5.2 `matrix::vector` Class Reference

A class for performing vector operations such as addition, subtraction, scaling, dot product, magnitude, and cosine similarity.

```
#include <vector.h>
```

Static Public Member Functions

- static `std::vector< int > add` (`std::vector< int > firstVector`, `std::vector< int > secondVector`)
Adds two vectors element-wise.
- static `std::vector< int > subtract` (`std::vector< int > firstVector`, `std::vector< int > secondVector`)
Subtracts the second vector from the first vector element-wise.
- static `std::vector< int > scale` (`std::vector< int > vector`, `int scale`)
Scales a vector by a given factor.
- static `int dotProduct` (`const std::vector< int > &firstVector`, `const std::vector< int > &secondVector=std::vector< int >()`)
Computes the dot product of two vectors.
- static `double magnitude` (`const std::vector< int > &firstVector`, `const std::vector< int > &secondVector=std::vector< int >()`)
Computes the magnitude of the difference between two vectors.
- static `double cosineSimilarity` (`const std::vector< int > &firstVector`, `const std::vector< int > &secondVector`)
Computes the cosine similarity between two vectors.

5.2.1 Detailed Description

A class for performing vector operations such as addition, subtraction, scaling, dot product, magnitude, and cosine similarity.

Definition at line 15 of file [vector.h](#).

5.2.2 Member Function Documentation

5.2.2.1 add()

```
static std::vector< int > matrix::vector::add (
    std::vector< int > firstVector,
    std::vector< int > secondVector) [inline], [static]
```

Adds two vectors element-wise.

Parameters

<i>firstVector</i>	The first vector.
<i>secondVector</i>	The second vector.

Returns

The resultant vector after addition.

Definition at line 23 of file [vector.h](#).

5.2.2.2 cosineSimilarity()

```
static double matrix::vector::cosineSimilarity (
    const std::vector< int > & firstVector,
    const std::vector< int > & secondVector) [inline], [static]
```

Computes the cosine similarity between two vectors.

Parameters

<i>firstVector</i>	The first vector.
<i>secondVector</i>	The second vector.

Returns

The cosine similarity between the two vectors.

Exceptions

<i>std::invalid_argument</i>	if the vectors are of different lengths.
------------------------------	--

Definition at line 122 of file [vector.h](#).

5.2.2.3 dotProduct()

```
static int matrix::vector::dotProduct (
    const std::vector< int > & firstVector,
    const std::vector< int > & secondVector = std::vector<int>()) [inline], [static]
```

Computes the dot product of two vectors.

Parameters

<i>firstVector</i>	The first vector.
<i>secondVector</i>	The second vector. Defaults to an empty vector (treated as a zero vector).

Returns

The dot product of the two vectors.

Exceptions

<i>std::invalid_argument</i>	if the vectors are of different lengths.
------------------------------	--

Definition at line 73 of file [vector.h](#).

5.2.2.4 magnitude()

```
static double matrix::vector::magnitude (  
    const std::vector< int > & firstVector,  
    const std::vector< int > & secondVector = std::vector<int>()) [inline], [static]
```

Computes the magnitude of the difference between two vectors.

Parameters

<i>firstVector</i>	The first vector.
<i>secondVector</i>	The second vector. Defaults to an empty vector (treated as a zero vector).

Returns

The magnitude of the difference between the two vectors.

Exceptions

<i>std::invalid_argument</i>	if the vectors are of different lengths.
------------------------------	--

Definition at line 99 of file [vector.h](#).

5.2.2.5 scale()

```
static std::vector< int > matrix::vector::scale (  
    std::vector< int > vector,  
    int scale) [inline], [static]
```

Scales a vector by a given factor.

Parameters

<i>vector</i>	The vector to scale.
<i>scale</i>	The scaling factor.

Returns

The resultant scaled vector.

Definition at line 59 of file [vector.h](#).

5.2.2.6 subtract()

```
static std::vector< int > matrix::vector::subtract (
    std::vector< int > firstVector,
    std::vector< int > secondVector) [inline], [static]
```

Subtracts the second vector from the first vector element-wise.

Parameters

<i>firstVector</i>	The first vector.
<i>secondVector</i>	The second vector.

Returns

The resultant vector after subtraction.

Definition at line 41 of file [vector.h](#).

The documentation for this class was generated from the following file:

- [vector.h](#)

Chapter 6

File Documentation

6.1 vector.cpp File Reference

```
#include "vector.h"
```

Functions

- `int main ()`

The main function demonstrating various vector and matrix operations.

6.1.1 Function Documentation

6.1.1.1 `main()`

```
int main ()
```

The main function demonstrating various vector and matrix operations.

This function performs the following operations:

- Addition and subtraction of two vectors.
- Addition, subtraction, and multiplication of 2D matrices.
- Calculation of the dot product of a vector.
- Calculation of the cosine similarity between two vectors.

Returns

`int` Returns 0 on successful execution.

Definition at line [44](#) of file [vector.cpp](#).

6.2 vector.cpp

[Go to the documentation of this file.](#)

```

00001
00031 #include "vector.h"
00032
00044 int main() {
00045     // Vectors for addition and subtraction
00046     std::vector<int> firstVector = {1, 3, 6, 9};
00047     std::vector<int> secondVector = {1, 3, -6, 9};
00048
00049     // Perform vector addition
00050     std::vector<int> resultant = matrix::vector::add(firstVector, secondVector);
00051
00052     // Perform vector subtraction
00053     std::vector<int> resultantt = matrix::vector::subtract(firstVector, secondVector);
00054
00055     // 2D matrices for addition and subtraction
00056     std::vector<std::vector<int>> firstMatrix = {{1, 3, 6, 9},
00057                                                  {5, 9, 8, 0},
00058                                                  {1, 9, 7, 5}};
00059     std::vector<std::vector<int>> secondMatrix = {{1, 3, 6, 9},
00060                                                  {5, 9, 8, 0},
00061                                                  {1, 9, 7, 5}};
00062
00063     // Perform 2D matrix addition
00064     matrix::Matrix::add2D(firstMatrix, secondMatrix);
00065
00066     // Perform 2D matrix subtraction
00067     matrix::Matrix::subtract2D(firstMatrix, secondMatrix);
00068
00069     // 2D matrices for multiplication
00070     std::vector<std::vector<int>> firstMatrixForMultiplication = {{1, 3, 6, 9},
00071                                                                  {5, 9, 8, 0},
00072                                                                  {1, 9, 7, 5}};
00073     std::vector<std::vector<int>> secondMatrixForMultiplication = {{1, 3, 6, 9},
00074                                                                    {5, 9, 8, 0},
00075                                                                    {1, 9, 7, 5},
00076                                                                    {1, 18, 9, 8}};
00077
00078     // Perform 2D matrix multiplication
00079     matrix::Matrix::multiply2D(firstMatrixForMultiplication, secondMatrixForMultiplication);
00080
00081     // Vector for dot product calculation
00082     std::vector<int> vec1 = {1, 2, 3};
00083
00084     // Calculate dot product of a vector with a zero vector (default)
00085     int result2 = matrix::vector::dotProduct(vec1);
00086
00087     // Calculate cosine similarity between two vectors
00088     std::cout << matrix::vector::cosineSimilarity(firstVector, secondVector) * 100 << " %" << std::endl;
00089
00090     return 0;
00091 }

```

6.3 vector.h File Reference

```

#include <utility>
#include <vector>
#include <iostream>
#include <cmath>

```

Classes

- class `matrix::vector`
A class for performing vector operations such as addition, subtraction, scaling, dot product, magnitude, and cosine similarity.
- class `matrix::Matrix`
A class for performing operations on 2D matrices such as addition, subtraction, and multiplication.

Namespaces

- namespace `matrix`

6.4 vector.h

[Go to the documentation of this file.](#)

```

00001 #ifndef VECTOR_VECTOR_H
00002 #define VECTOR_VECTOR_H
00003
00004 #include <utility>
00005 #include <vector>
00006 #include <iostream>
00007 #include <cmath>
00008
00009 namespace matrix {
00010
00011     class vector {
00012     public:
00023         static std::vector<int> add(std::vector<int> firstVector, std::vector<int> secondVector) {
00024             std::vector<int> resultant(firstVector.size());
00025             for (int i = 0; i < firstVector.size(); i++) {
00026                 resultant[i] = firstVector[i] + secondVector[i];
00027             }
00028             for (int i = 0; i < firstVector.size(); i++) {
00029                 std::cout << resultant[i] << " ";
00030             }
00031             std::cout << std::endl;
00032             return resultant;
00033         }
00034
00041         static std::vector<int> subtract(std::vector<int> firstVector, std::vector<int> secondVector)
00042         {
00043             std::vector<int> resultant(firstVector.size());
00044             for (int i = 0; i < firstVector.size(); i++) {
00045                 resultant[i] = firstVector[i] - secondVector[i];
00046             }
00047             for (int i = 0; i < firstVector.size(); i++) {
00048                 std::cout << resultant[i] << " ";
00049             }
00050             std::cout << std::endl;
00051             return resultant;
00052         }
00059         static std::vector<int> scale(std::vector<int> vector, int scale) {
00060             for (int i = 0; i < vector.size(); i++) {
00061                 vector[i] *= scale;
00062             }
00063             return vector;
00064         }
00065
00073         static int dotProduct(const std::vector<int> &firstVector, const std::vector<int>
&secondVector = std::vector<int>()) {
00074             std::vector<int> adjustedSecondVector = secondVector;
00075
00076             if (adjustedSecondVector.empty()) {
00077                 adjustedSecondVector.resize(firstVector.size(), 0);
00078             }
00079
00080             if (firstVector.size() != adjustedSecondVector.size()) {
00081                 throw std::invalid_argument("Vectors must be of same length");
00082             }
00083
00084             int result = 0;
00085             for (size_t i = 0; i < firstVector.size(); ++i) {
00086                 result += firstVector[i] * adjustedSecondVector[i];
00087             }
00088
00089             return result;
00090         }
00091
00099         static double magnitude(const std::vector<int> &firstVector, const std::vector<int>
&secondVector = std::vector<int>()) {
00100             std::vector<int> adjustedSecondVector = secondVector;
00101
00102             if (adjustedSecondVector.empty()) {
00103                 adjustedSecondVector.resize(firstVector.size(), 0);
00104             }
00105             if (firstVector.size() != adjustedSecondVector.size()) {
00106                 throw std::invalid_argument("Vectors must be of same length");

```

```

00107         }
00108         int result = 0;
00109         for (int i = 0; i < firstVector.size(); i++) {
00110             result += (adjustedSecondVector[i] - firstVector[i]) * (adjustedSecondVector[i] -
firstVector[i]);
00111         }
00112         return sqrt((double) result);
00113     }
00114
00122     static double cosineSimilarity(const std::vector<int> &firstVector, const std::vector<int>
&secondVector) {
00123         if (firstVector.size() != secondVector.size()) {
00124             throw std::invalid_argument("Vectors must be of same length");
00125         }
00126         int dotProduct = matrix::vector::dotProduct(firstVector, secondVector);
00127         double magnitudeOfA = matrix::vector::magnitude(firstVector);
00128         double magnitudeOfB = matrix::vector::magnitude(secondVector);
00129         double cosineSimilarity = dotProduct / (magnitudeOfA * magnitudeOfB);
00130         return cosineSimilarity;
00131     }
00132 };
00133
00138     class Matrix {
00139     public:
00147         static std::vector<std::vector<int> > add2D(const std::vector<std::vector<int> > &firstMatrix,
const std::vector<std::vector<int> > &secondMatrix) {
00148             if (firstMatrix.size() != secondMatrix.size() || firstMatrix[0].size() !=
secondMatrix[0].size()) {
00149                 throw std::invalid_argument("Matrices must have the same dimensions");
00150             }
00151
00152             std::vector<std::vector<int> > resultant(firstMatrix.size(),
std::vector<int>(firstMatrix[0].size()));
00153
00154             for (size_t i = 0; i < firstMatrix.size(); ++i) {
00155                 for (size_t j = 0; j < firstMatrix[i].size(); ++j) {
00156                     resultant[i][j] = firstMatrix[i][j] + secondMatrix[i][j];
00157                 }
00158             }
00159             for (const auto &row: resultant) {
00160                 for (const int element: row) {
00161                     std::cout << element << " ";
00162                 }
00163                 std::cout << std::endl;
00164             }
00165
00166             return resultant;
00167         }
00168
00176         static std::vector<std::vector<int> > subtract2D(const std::vector<std::vector<int> >
&firstMatrix, const std::vector<std::vector<int> > &secondMatrix) {
00177             if (firstMatrix.size() != secondMatrix.size() || firstMatrix[0].size() !=
secondMatrix[0].size()) {
00178                 throw std::invalid_argument("Matrices must have the same dimensions");
00179             }
00180
00181             std::vector<std::vector<int> > resultant(firstMatrix.size(),
std::vector<int>(firstMatrix[0].size()));
00182
00183             for (size_t i = 0; i < firstMatrix.size(); ++i) {
00184                 for (size_t j = 0; j < firstMatrix[i].size(); ++j) {
00185                     resultant[i][j] = firstMatrix[i][j] - secondMatrix[i][j];
00186                 }
00187             }
00188             for (const auto &row: resultant) {
00189                 for (const int element: row) {
00190                     std::cout << element << " ";
00191                 }
00192                 std::cout << std::endl;
00193             }
00194
00195             return resultant;
00196         }
00197
00205         static std::vector<std::vector<int> > multiply2D(const std::vector<std::vector<int> >
&firstMatrix, const std::vector<std::vector<int> > &secondMatrix) {
00206             if (firstMatrix[0].size() != secondMatrix.size()) {
00207                 throw std::invalid_argument("The number of columns in the first matrix must be equal
to the number of rows in the second matrix");
00208             }
00209             std::vector<std::vector<int> > resultant(firstMatrix.size(),
std::vector<int>(secondMatrix[0].size()));
00210             for (size_t i = 0; i < firstMatrix.size(); ++i) {
00211                 for (size_t j = 0; j < firstMatrix[i].size(); ++j) {
00212                     resultant[i][j] = 0;
00213                     for (size_t k = 0; k < secondMatrix.size(); ++k) {
00214                         resultant[i][j] += firstMatrix[i][k] * secondMatrix[k][j];

```

```
00215         }
00216     }
00217 }
00218
00219     for (const auto &row: resultant) {
00220         for (const int element: row) {
00221             std::cout << element << " ";
00222         }
00223         std::cout << std::endl;
00224     }
00225
00226     return resultant;
00227 }
00228 };
00229 }
00230
00231 #endif //VECTOR_VECTOR_H
```


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