

Γ.	$c\theta_i$	$-s\theta_i$	0	a_{i-1}
$i-1 \atop i T =$	$s\theta_i c\alpha_{i-1}$ $s\theta_i s\alpha_{i-1}$	$c\theta_i c\alpha_{i-1}$ $c\theta_i s\alpha_{i-1}$	$-s\alpha_{i-1}$ $c\alpha_{i-1}$	$-s\alpha_{i-1}d_{i}$ $c\alpha_{i-1}d_{i}$

i	α_{i-1}	a_{i-1}	d_i	$ heta_i$
1	0	0	0	$ heta_1$
2	90°	0	d_2	0
3	0	0	L_2	$ heta_3$

$$_{1}^{0}T = \begin{bmatrix} c\theta_{1} & -s\theta_{1} & 0 & 0 \\ s\theta_{1} & c\theta_{1} & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$${}_{3}^{2}T = \begin{bmatrix} c\theta_{3} & -s\theta_{3} & 0 & 0 \\ s\theta_{3} & c\theta_{3} & 0 & 0 \\ 0 & 0 & 1 & l_{2} \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

i	$\alpha_i - 1$	$a_i - 1$	d_i	heta i
1	0	0	0	$ heta_1$
2	-90°	0	0	θ_2
3	0	a_2	d_3	θ_3
4	-90°	a_3	d_4	θ_4
5	90°	0	0	θ_5
6	-90°	0	0	θ_6

$${}_{1}^{0}T = \begin{bmatrix} c\theta_{1} & -s\theta_{1} & 0 & 0 \\ s\theta_{1} & c\theta_{1} & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}, \quad {}_{4}^{3}T = \begin{bmatrix} c\theta_{4} & -s\theta_{4} & 0 & a_{3} \\ 0 & 0 & 1 & d_{4} \\ -s\theta_{4} & -c\theta_{4} & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix},$$

$${}_{2}^{1}T = \begin{bmatrix} c\theta_{2} & -s\theta_{2} & 0 & 0 \\ 0 & 0 & 1 & 0 \\ -s\theta_{2} & -c\theta_{2} & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}, \qquad {}_{5}^{4}T = \begin{bmatrix} c\theta_{5} & -s\theta_{5} & 0 & 0 \\ 0 & 0 & -1 & 0 \\ s\theta_{5} & c\theta_{5} & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix},$$

$${}^{2}_{3}T = \begin{bmatrix} c\theta_{3} & -s\theta_{3} & 0 & a_{2} \\ s\theta_{3} & c\theta_{3} & 0 & 0 \\ 0 & 0 & 1 & d_{3} \\ 0 & 0 & 0 & 1 \end{bmatrix}, \qquad {}^{5}_{6}T = \begin{bmatrix} c\theta_{6} & -s\theta_{6} & 0 & 0 \\ 0 & 0 & 1 & 0 \\ -s\theta_{6} & -c\theta_{6} & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}.$$

$${}_{6}^{4}T = {}_{5}^{4}T {}_{6}^{5}T = \begin{bmatrix} c_{5}c_{6} & -c_{5}s_{6} & -s_{5} & 0 \\ s_{6} & c_{6} & 0 & 0 \\ s_{5}c_{6} & -s_{5}s_{6} & c_{5} & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$${}_{6}^{3}T = {}_{4}^{3}T {}_{6}^{4}T = \begin{bmatrix} c_{4}c_{5}c_{6} - s_{4}s_{6} & -c_{4}c_{5}s_{6} - s_{4}c_{6} & -c_{4}s_{5} & a_{3} \\ s_{5}c_{6} & -s_{5}s_{6} & c_{5} & d_{4} \\ -s_{4}c_{5}c_{6} - c_{4}s_{6} & s_{4}c_{5}s_{6} - c_{4}c_{6} & s_{4}s_{5} & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$${}_{6}^{7}T = {}_{1}^{0}T {}_{6}^{1}T = \begin{bmatrix} r_{11} & r_{12} & r_{13} & p_{x} \\ r_{21} & r_{22} & r_{23} & p_{y} \\ r_{31} & r_{32} & r_{33} & p_{z} \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$${}_{3}^{1}T = {}_{2}^{1}T {}_{3}^{2}T = \begin{bmatrix} c_{23} & -s_{23} & 0 & a_{2}c_{2} \\ 0 & 0 & 1 & d_{3} \\ -s_{23} & -c_{23} & 0 & -a_{2}s_{2} \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$${}_{6}^{0}T = {}_{1}^{0}T {}_{6}^{1}T = \begin{bmatrix} r_{11} & r_{12} & r_{13} & p_{x} \\ r_{21} & r_{22} & r_{23} & p_{y} \\ r_{31} & r_{32} & r_{33} & p_{z} \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$c_{23} = c_2c_3 - s_2s_3,$$

 $s_{23} = c_2s_3 + s_2c_3.$

$$\begin{split} r_{11} &= c_1[c_{23}(c_4c_5c_6 - s_4s_5) - s_{23}s_5c_5] + s_1(s_4c_5c_6 + c_4s_6), \\ r_{21} &= s_1[c_{23}(c_4c_5c_6 - s_4s_6) - s_{23}s_5c_6 - c_1(s_4c_5c_6 + c_4s_6), \\ r_{31} &= -s_{23}(c_4c_5c_6 - s_4s_6) - c_{23}s_5c_6, \end{split}$$

$$\begin{split} r_{12} &= c_1[c_{23}(-c_4c_5s_6 - s_4c_6) + s_{23}s_5s_6] + s_1(c_4c_6 - s_4c_5s_6), \\ r_{22} &= s_1[c_{23}(-c_4c_5s_6 - s_4c_6) + s_{23}s_5s_6] - c_1(c_4c_6 - s_4c_5s_6), \\ r_{32} &= -s_{23}(-c_4c_5s_6 - s_4c_6) + c_{23}s_5s_6, \end{split}$$

$$\begin{split} r_{13} &= -c_1(c_{23}c_4s_5 + s_{23}c_5) - s_1s_4s_5, \\ r_{23} &= -s_1(c_{23}c_4s_5 + s_{23}c_5) + c_1s_4s_5, \\ r_{33} &= s_{23}c_4s_5 - c_{23}c_5, \end{split}$$

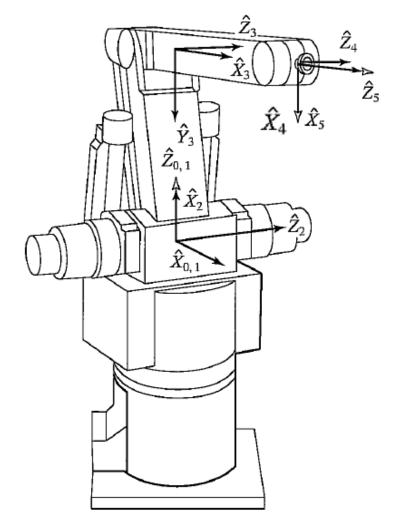
$$\begin{split} p_x &= c_1[a_2c_2 + a_3c_{23} - d_4s_{23}] - d_3s_1, \\ p_y &= s_1[a_2c_2 + a_3c_{23} - d_4s_{23}] + d_3c_1, \\ p_z &= -a_3s_{23} - a_2s_2 - d_4c_{23}. \end{split}$$

 $a_{i-1} = The \ distance \ from \ \hat{Z}_{i-1} \ to \ \hat{Z}_i \ measured \ along \ \hat{X}_{i-1};$

 $\alpha_{i-1} = The \ angle \ from \ \hat{Z}_{i-1} \ to \ \hat{Z}_i \ measured \ along \ \hat{X}_{i-1};$

 d_i = The distance from \hat{X}_{i-1} to X_i measured along \hat{Z}_i ;

 θ_i = The angle from \hat{X}_{i-1} to X_i measured along \hat{Z}_i ;



i	$\alpha_i - 1$	$a_i - 1$	d_i	θ_i
1	0	0	0	θ ₁
2	-90	0	0	θ_2
3	0	L ₂	0	θ_3
4	0	L ₃	0	θ_4
5	90	0	0	θ_5

i	$\alpha_i - 1$	$a_i - 1$	d_i	θ_i
1	0	0	0	θ_1
2	-90°	0	0	θ_2
3	0	L_2	0	θ_3
4	0	L_3	0	θ_4
5	90°	0	. 0	θ_5

$${}_{1}^{0}T = \begin{bmatrix} c\theta_{1} & -s\theta_{1} & 0 & 0 \\ s\theta_{1} & c\theta_{1} & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \qquad {}_{5}^{4}T = \begin{bmatrix} c\theta_{5} & -s\theta_{5} & 0 & 0 \\ 0 & 0 & -1 & 0 \\ s\theta_{5} & c\theta_{5} & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$${}_{2}^{1}T = \begin{bmatrix} c\theta_{2} & -s\theta_{2} & 0 & 0\\ 0 & 0 & 1 & 0\\ -s\theta_{2} & -c\theta_{2} & 0 & 0\\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$${}_{3}^{2}T = \begin{bmatrix} c\theta_{3} & -s\theta_{3} & 0 & l_{2} \\ s\theta_{3} & c\theta_{3} & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$${}_{4}^{3}T = \begin{bmatrix} c\theta_{4} & -s\theta_{4} & 0 & l_{3} \\ s\theta_{4} & c\theta_{4} & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$${}_{5}^{4}T = \begin{bmatrix} c\theta_{5} & -s\theta_{5} & 0 & 0\\ 0 & 0 & -1 & 0\\ s\theta_{5} & c\theta_{5} & 0 & 0\\ 0 & 0 & 0 & 1 \end{bmatrix}$$