

An Overview of Mechanics

Mechanics: The study of how bodies react to forces acting on them.

Statics: The study of bodies in equilibrium.

Dynamics:

- 1. **Kinematics** concerned with the geometric aspects of motion
- 2. **Kinetics** concerned with the forces causing the motion

Today's Objectives:

- Students will be able to:
- ❖ Find the kinematic quantities (position, displacement, velocity, and acceleration) of a particle traveling along a straight path.

Rectilinear means position given in Cartesian (x, y, and z) coordinates.

❖ We will stat with motion in a straight line

Introduction

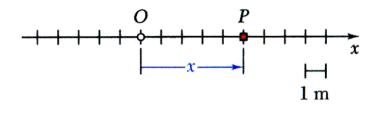
- Particle kinetics includes:
- **Rectilinear motion**: position, velocity, and acceleration of a particle as it moves along a straight line.

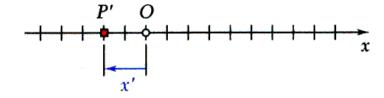


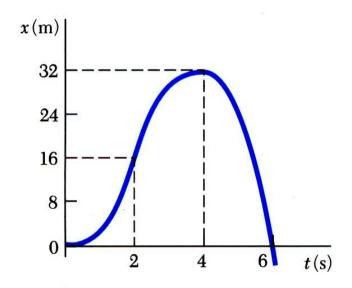


• <u>Curvilinear motion</u>: position, velocity, and acceleration of a particle as it moves along a curved line in two or three dimensions.

Rectilinear Motion: Position, Velocity & Acceleration

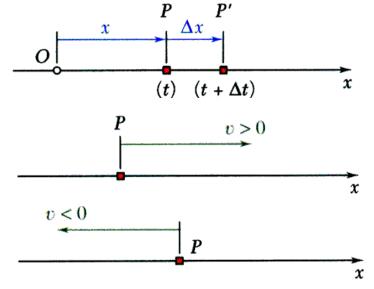






- *Rectilinear motion:* particle moving along a straight line
- *Position coordinate:* defined by positive or negative distance from a fixed origin on the line.
- The *motion* of a particle is known if the position coordinate for particle is known for every value of time *t*.
- May be expressed in the form of a function, e.g., $x = 6t^2 t^3$ or in the form of a graph x vs. t.

Rectilinear Motion: Position, Velocity & Acceleration



v (m/s)

12

0

2

t (s)

-12

-24

-36

• Consider particle which occupies position P at time t and P at $t+\Delta t$,

$$Average \ velocity = \frac{\Delta x}{\Delta t}$$

$$Instantaneous \ velocity = v = \lim_{\Delta t \to 0} \frac{\Delta x}{\Delta t}$$

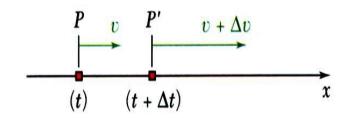
- Instantaneous velocity may be positive or negative. Magnitude of velocity is referred to as *particle speed*.
 - From the definition of a derivative,

$$v = \lim_{\Delta t \to 0} \frac{\Delta x}{\Delta t} = \frac{dx}{dt}$$

e.g.,
$$x = 6t^2 - t^3$$

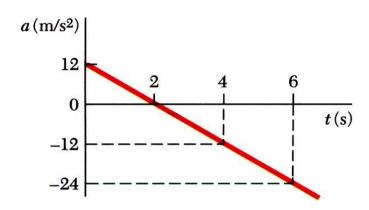
 $v = \frac{dx}{dt} = 12t - 3t^2$

Rectilinear Motion: Position, Velocity & Acceleration



• Consider particle with velocity v at time t and v at $t+\Delta t$,

Instantaneous acceleration =
$$a = \lim_{\Delta t \to 0} \frac{\Delta v}{\Delta t}$$



• From the definition of a derivative,

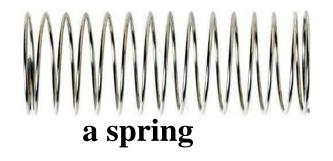
$$a = \lim_{\Delta t \to 0} \frac{\Delta v}{\Delta t} = \frac{dv}{dt} = \frac{d^2x}{dt^2}$$

e.g.
$$v = 12t - 3t^2$$

$$a = \frac{dv}{dt} = 12 - 6t$$

Determination of the Motion of a Particle

- We often determine accelerations from the forces applied (kinetics will be covered later)
- Generally, have three classes of motion
 - acceleration given as a function of *time*, a = f(t)
 - acceleration given as a function of position, a = f(x)
 - acceleration given as a function of *velocity*, a = f(v)





SUMMARY OF KINEMATIC RELATIONS: RECTILINEAR MOTION

· Differentiate position to get velocity and acceleration.

$$v = ds/dt$$
; $a = dv/dt$ or $a = v dv/ds$

Integrate acceleration for velocity and position.

Velocity: Position:
$$\int_{v_0}^{v} dv = \int_{0}^{t} a \, dt \text{ or } \int_{v_0}^{v} v \, dv = \int_{s_0}^{s} a \, ds \qquad \int_{s_0}^{s} ds = \int_{0}^{t} v \, dt$$

• Note that s_o and v_o represent the initial position and velocity of the particle at t = 0.

CONSTANT ACCELERATION

The three kinematic equations can be integrated for the special case when acceleration is constant ($a = a_c$) to obtain very useful equations. A common example of constant acceleration is gravity; i.e., a body freely falling toward earth. In this case, $a_c = g = 9.81 \text{ m/s}^2 = 32.2 \text{ ft/s}^2$ downward. These equations are:

$$\int_{v_o}^{v} dv = \int_{o}^{t} a_c dt \quad \text{yields} \quad v = v_o + a_c t$$

$$\int_{s_o}^{s} ds = \int_{o}^{t} v dt \quad \text{yields} \quad s = s_o + v_o t + (1/2) a_c t^2$$

$$\int_{s_o}^{v} v dv = \int_{o}^{s} a_c ds \quad \text{yields} \quad v^2 = (v_o)^2 + 2a_c (s - s_o)$$

Acceleration as a function of time, position, or velocity

If	Kinematic relationship	Integrate	
a = a(t)	$\frac{dv}{dt} = a(t)$	$\int_{v_0}^{v} dv = \int_{0}^{t} a(t) dt$	
a = a(x)	$dt = \frac{dx}{v} \text{ and } a = \frac{dv}{dt}$ $v dv = a(x) dx$	$\int_{v_0}^{v} v dv = \int_{x_0}^{x} a(x) dx$	
a = a(v)	$\frac{dv}{dt} = a(v)$ $v\frac{dv}{dx} = a(v)$	$\int_{v_0}^{v} \frac{dv}{a(v)} = \int_{0}^{t} dt$ $\int_{x_0}^{x} dx = \int_{v_0}^{v} \frac{v dv}{a(v)}$	

Examples

- **EX1:** The car in Fig. 1.4 moves in a straight line such that for a short time its velocity is defined by $v=(3t^2+2t)$ ft/s, where t is in seconds. Determine its position and acceleration when t=3 s. Noting that s=0 when t=0
- SOLUTION

•
$$s = \int v \, dt$$

•
$$s = \int_0^t (3t^2 + 2t) dt$$

•
$$(S)_0^S = (t^3 + t^2)_0^t$$

•
$$S = t^3 + t^2$$

$$a = \frac{dv}{dt}$$

$$a = \frac{d}{dt}(3t^2 + 2t)$$

$$= 6t + 2$$

$$= 6 * 3 + 2 = 20$$

• EX2- A particle begins its motion in a straight line such that its position relative to fixed point on that straight line is given by $s=t^3-9t^2+15t+5\,m$. Find the position of the particle when the acceleration vanished

•
$$s = t^3 - 9t^2 + 15t + 5$$
,

•
$$v = \frac{dx}{dt} = 3t^2 - 18t + 15$$
,

•
$$a = \frac{dv}{dt} = 6 t - 18$$
,

- when the acceleration vanished
- a = 0

• Example 3: A particle moves in a straight line with acceleration inversely proportional with square distance from the origin. Find the velocity of the particle as a function of the distance knowing that the motion begins from rest when the particle is at a distance (a) from the origin.

Solution

- We find that the motion is in straight line.
- **Velocity:** the acceleration is a function in x, then, the velocity can be obtained from a relation $a=\frac{vdv}{dx}$ by separating variables and integrating

•
$$a = v \frac{dv}{dx} = \frac{k}{x^2}$$

•
$$\int_0^v v dv = \int_a^x \frac{k}{x^2} dx$$
, $\frac{v^2}{2} = -\frac{k}{x} + \frac{k}{a}$, $v^2 = 2\left(\frac{k}{a} - \frac{k}{x}\right)$

EXAMPLE

Given: The acceleration of a body is a = 5v. At t = 0, s = 0, and $v_0 = 2$ m/s. (a) Find v(t). (b) Find v(s).

(a) Need the equation with a, v, and t.

$$a = \frac{dv}{dt}$$

Rearrange. Terms with t on one side and v on the other.

$$dt = \frac{dv}{a}$$

Create integrals

$$\int_0^t dt = \int_2^v \frac{dv}{5v}$$

EXAMPLE (continued)

Result is

$$t \Big|_0^t = \frac{1}{5} \ln(v) \Big|_2^v$$
$$t = \frac{1}{5} \ln(\frac{v}{2})$$
$$v = 2e^{5t}$$

(b) Need the equation with a, v, and s.

$$a = v \frac{dv}{ds}$$

$$ds = v \frac{dv}{a}$$

EXAMPLE (continued)

Result is

$$\int_0^s ds = \int_2^v v \frac{dv}{5v}$$

$$s\Big|_0^s = \frac{1}{5}v\Big|_2^v$$

$$s = \frac{1}{5}(v-2)$$

$$v = 5s + 2$$

Expression for the distance travelled in nth second

Let a body move with an initial velocity u and travel along a straight line with uniform acceleration a.

Distance travelled in the nth second of motion is, sn = distance travelled during first n seconds – distance travelled during (n-1) seconds Distance travelled during n seconds

$$Dn = un + 1/2an2$$

Distance travelled during (n -1) seconds

$$D_{(n-1)} = u(n-1) + \frac{1}{2} \alpha(n-1)^2$$

the distance travelled in the n^{th} second =

(i.e)
$$s_n = \left(un + \frac{1}{2}an^2\right) - \left[u(n-1) + \frac{1}{2}a(n-1)^2\right]$$

$$s_n = u + a \left(n - \frac{1}{2} \right)$$

$$s_n = u + \frac{1}{2}\alpha(2n - 1)$$

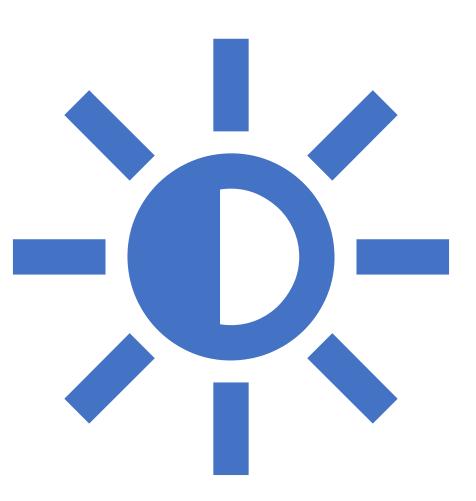
Special Cases

<u>Case (i)</u>: For downward motion For a particle moving downwards, a = g, since the particle moves in the direction of gravity.

<u>Case (ii)</u>: For a freely falling body

For a freely falling body, a = g and u = 0, since it starts from rest.

<u>Case (iii)</u>: For upward motion For a particle moving upwards, a = -g, since the particle moves against the gravity



Coding using Python program

```
• import numpy as np
 import matplotlib.pyplot as plt
 finalTime=20 #Seconds
 H=0
 velocity=np.zeros(finalTime+1) #Initialize Velocity Array
 height=np.zeros(finalTime+1) #Initialize Height Array
 q=10 \# m/s^2 you may change to 9.81 m/s^2
 initialVelocity=100 #Initial Velocity in m/s
 # calculate velocity and distance/height at each second
 # Time=1; so not appearing in expressions v=u-gt and
 H = ut - 0.5 * qt^2
 for i in range (0, finalTime+1):
      if i==0:
          velocity[i]=initialVelocity
     else:
          velocity[i] = velocity[i-1]-q
          deltaH= velocity[i-1]-0.5*q
          H=H+deltaH
          height[i]=H
          # initialVelocity=velocity[i]
      #print(i, initialVelocity, H)
```

```
• timePoints=np.linspace(
   0, finalTime,
   finalTime+1)

print("velocity",
   velocity)
   print("\n")
   print("height", height)
```

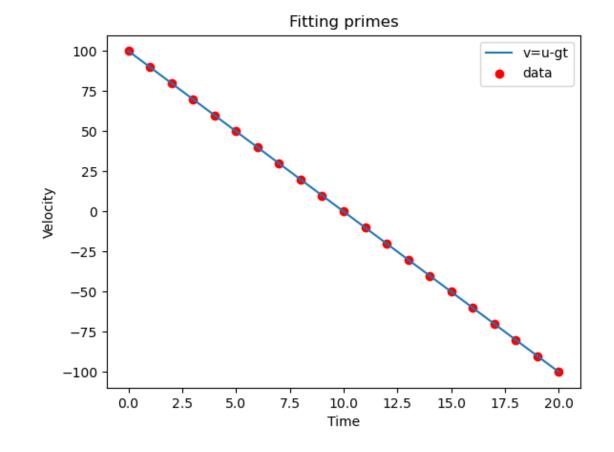
```
velocity [ 100. 90. 80. 70. 60. 50. 40. 30.
20. 10. 0. -10.

-20. -30. -40. -50. -60. -70. -80. -90. -100.]

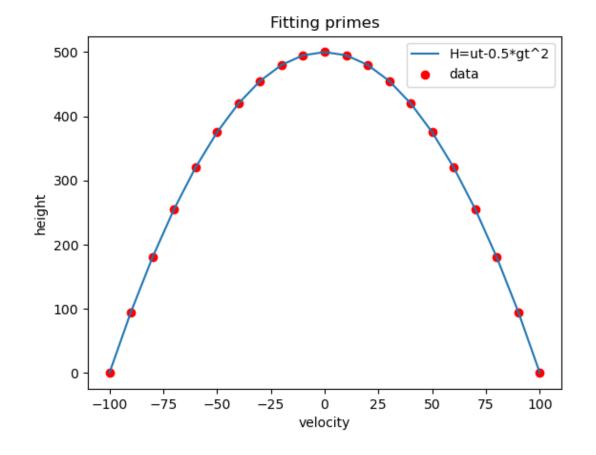
height [ 0. 95. 180. 255. 320. 375. 420. 455. 480. 495.
500. 495. 480. 455.

420. 375. 320. 255. 180. 95. 0.]
```

```
• plt.scatter(timePoints,
    velocity, c='r',
    label='data')
    plt.plot(timePoints,
    velocity, label='v=u-
    gt')
    plt.xlabel('Time')
    plt.ylabel('Velocity ')
    plt.title('Fitting
    primes')
    plt.legend()
    plt.show()
```



```
• plt.scatter(velocity,
  height, c='r',
  label='data')
  plt.plot(velocity,
  height, label='H=ut-
  0.5*gt^2')
  plt.xlabel('velocity')
  plt.ylabel('height')
  plt.title('Fitting
  primes')
  plt.legend()
  plt.show()
```



Thank you