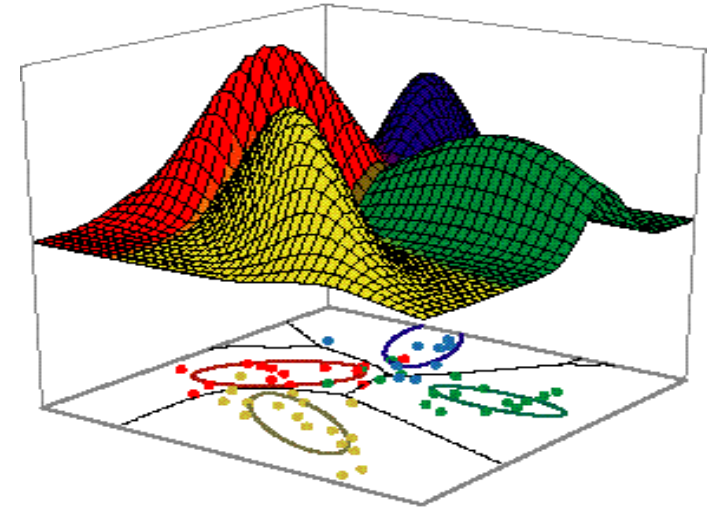


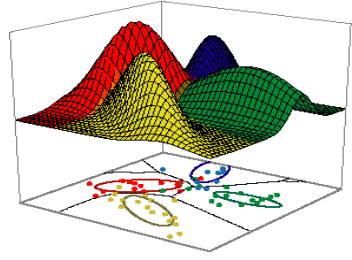
Part 1: Introduction to Pattern Recognition



Machine Perception
The Big Picture
An Example
Pattern Recognition Systems
The Design Cycle
Learning and Adaptation
Course Objectives

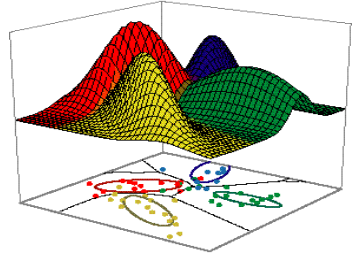
Some materials in these slides were taken from *Pattern Classification* (2nd ed) by
R. O. Duda, P. E. Hart and D. G. Stork, John Wiley & Sons, 2000; Chapter 1

Machine Perception



- Humans naturally recognize patterns
 - Feel objects in your pocket
 - Judge ripeness of an apple by smell
 - Guess at emotion from facial expression
 - Reading handwriting
- These are all extremely difficult for a machine!
- Build a machine that can recognize patterns:
 - Speech recognition
 - Fingerprint identification
 - OCR (Optical Character Recognition)
 - DNA sequence identification

The big picture (supervised learning)

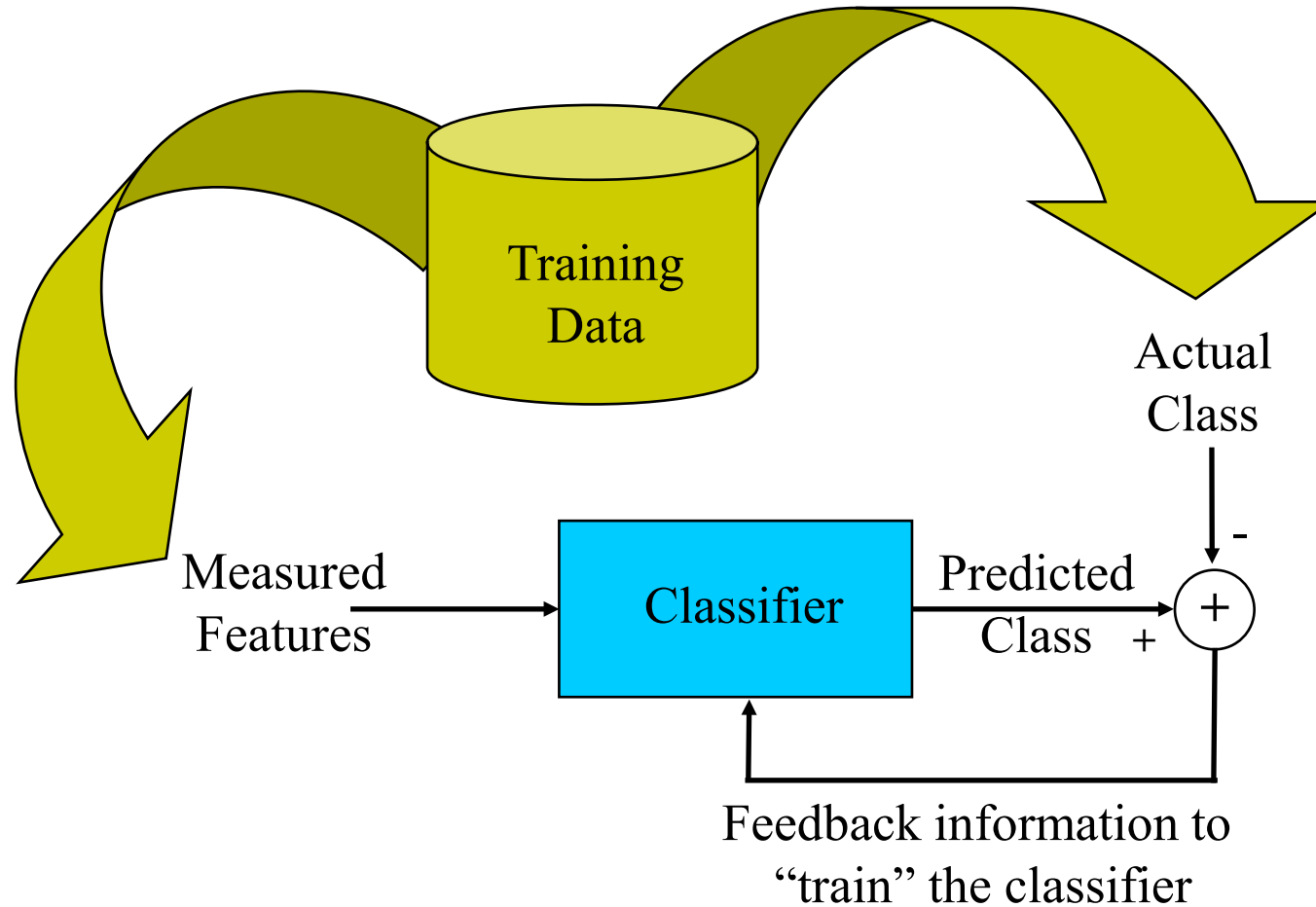


- Training
 - Collect some training samples where the class is known
 - Make some measurements to extract features
 - Train a classifier using measured features and known class
- Testing
 - Evaluate the accuracy of the classifier on test data that was not used to train the classifier.
- Operation
 - Ultimately, system will work for NEW data
 - i.e. examine features for a new sample, guess at class

The big picture (supervised learning)

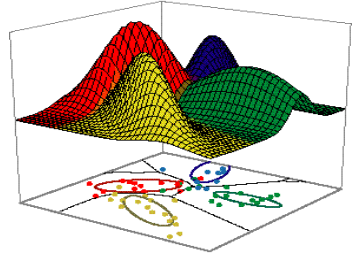
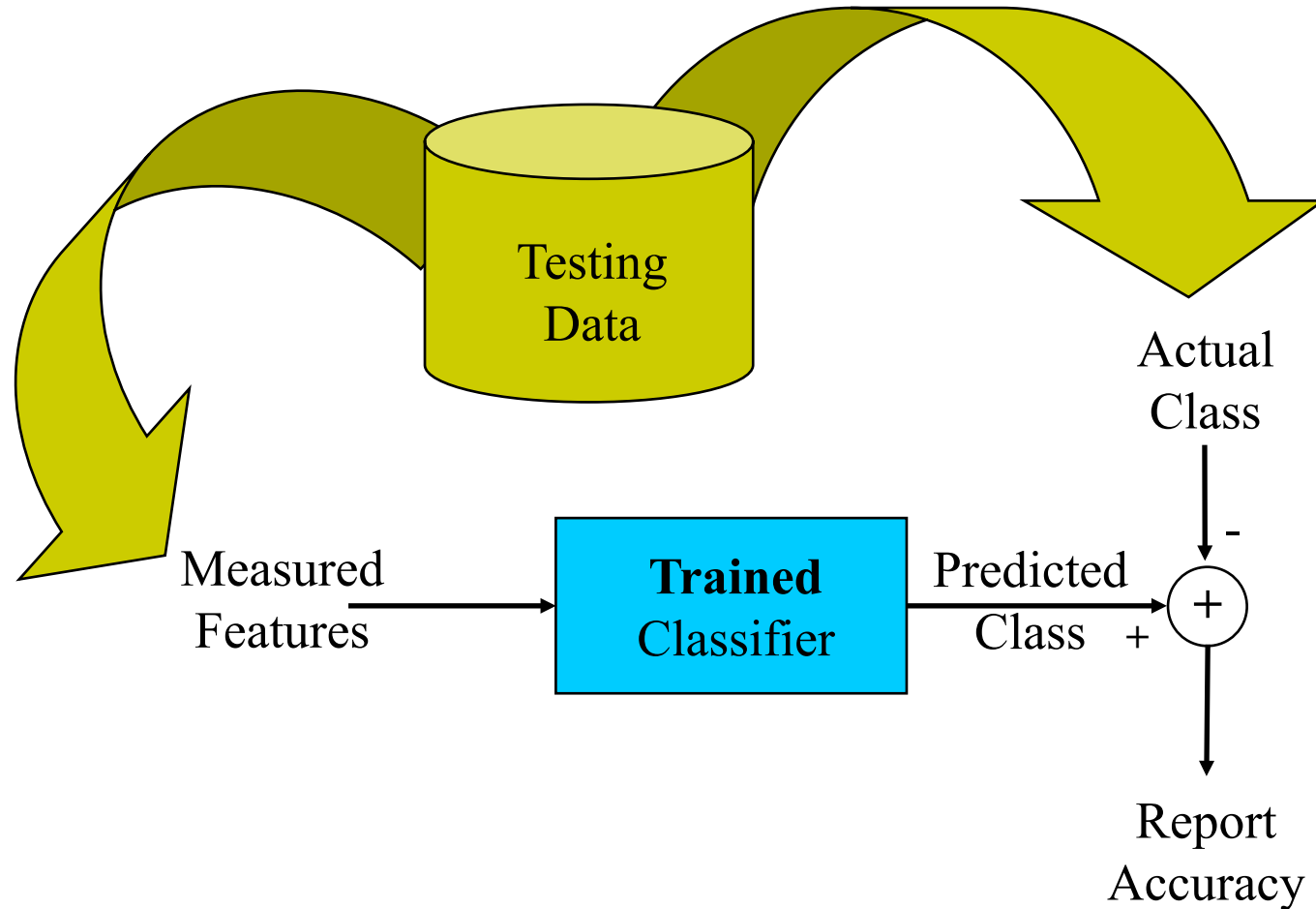


- Training:

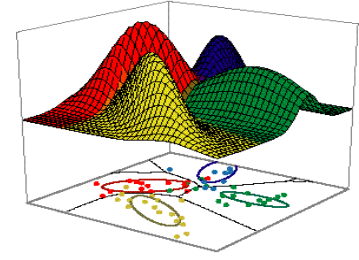


The big picture (supervised learning)

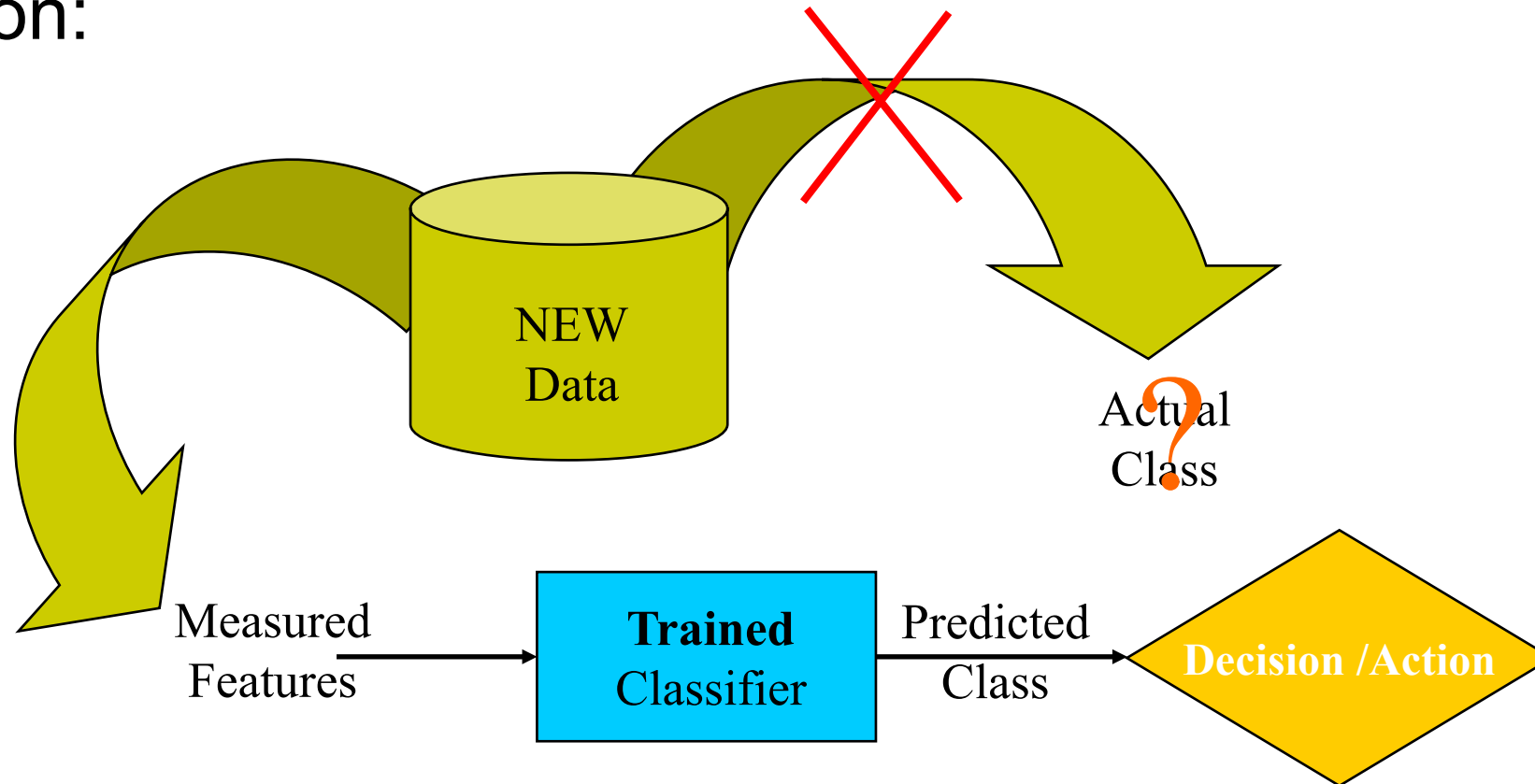
- Testing:



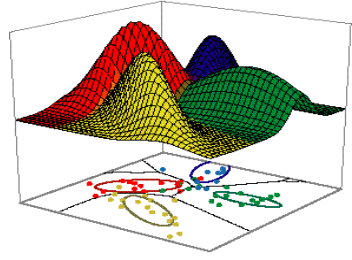
The big picture (supervised learning)



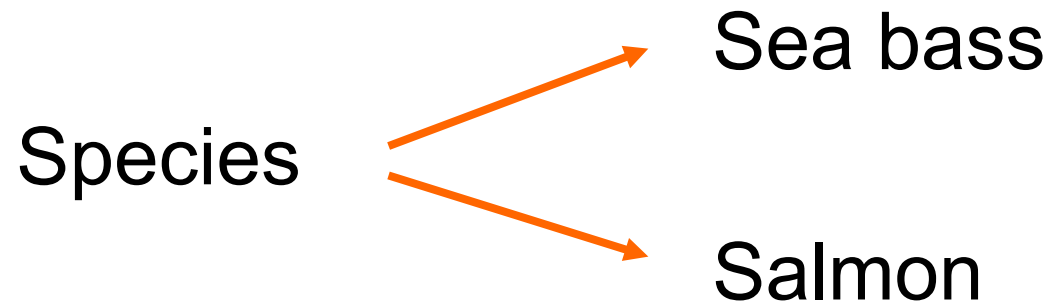
- Operation:



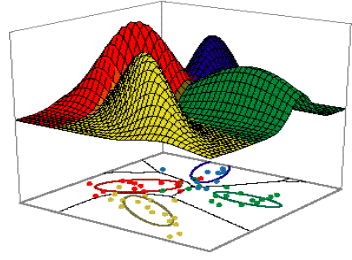
An Example – fish sorter



- “Sorting incoming fish on a conveyor according to species using optical sensing”

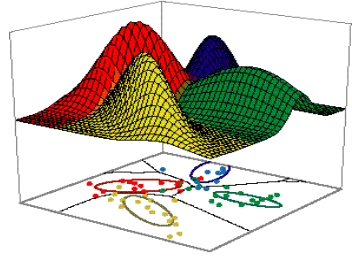


An Example – fish sorter



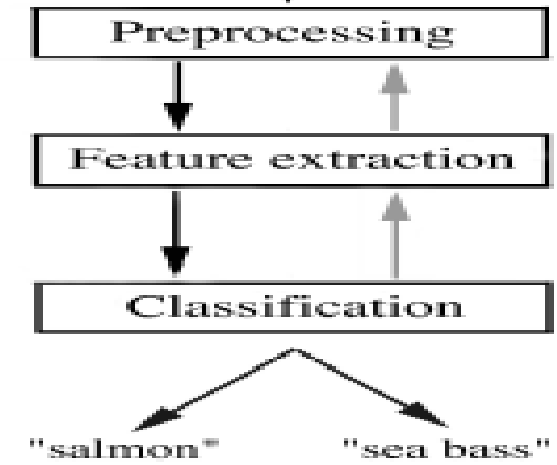
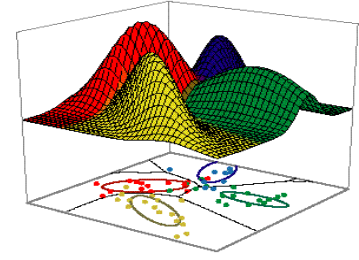
- Problem Analysis
 - Set up a camera and take some sample images to extract features
 - Length
 - Lightness
 - Width
 - Number and shape of fins
 - Position of the mouth, etc...
 - May be continuous, nominal/categorical, ordinal
 - We may use only a subset of these features in our classifier!

An Example – fish sorter

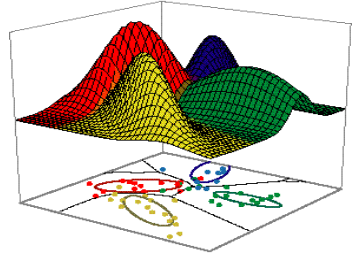


- Preprocessing
 - Use a segmentation operation to isolate fishes from one another and from the background
- Information from a single fish is sent to a feature extractor whose purpose is to reduce the data by measuring certain features
 - ‘Features’ vs. ‘measurements’
- The features are passed to a classifier

An Example – fish sorter

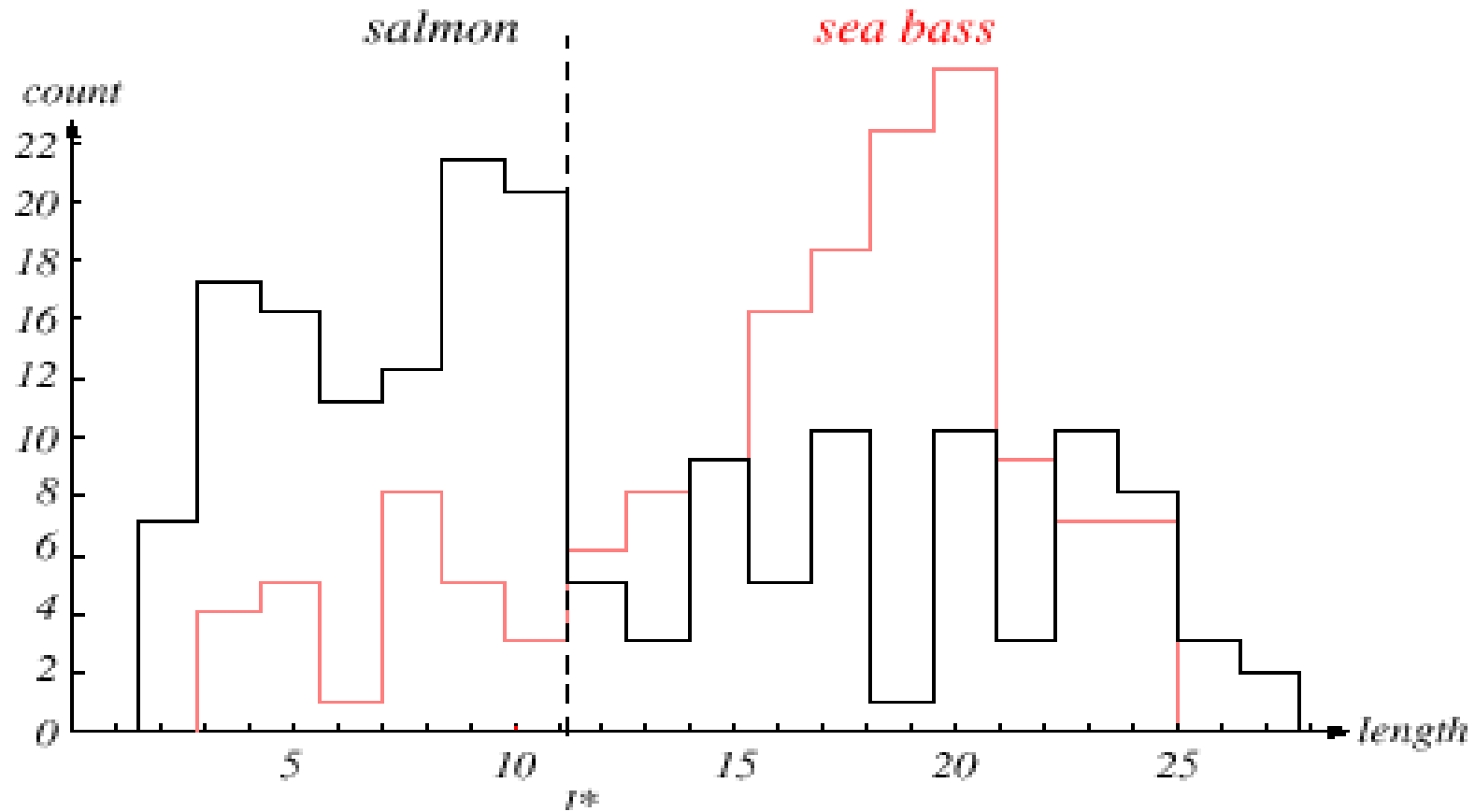
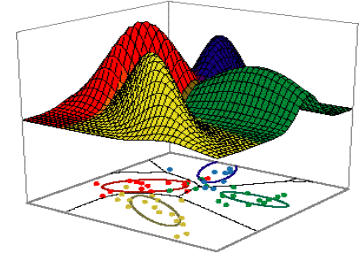


An Example – fish sorter



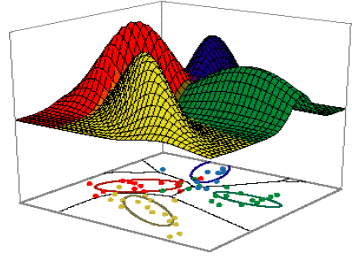
- Classification
 - Get some prior information:
 - Told that salmon are generally shorter than sea bass
 - Select the length of the fish as a possible feature for discrimination

Histogram of fish length



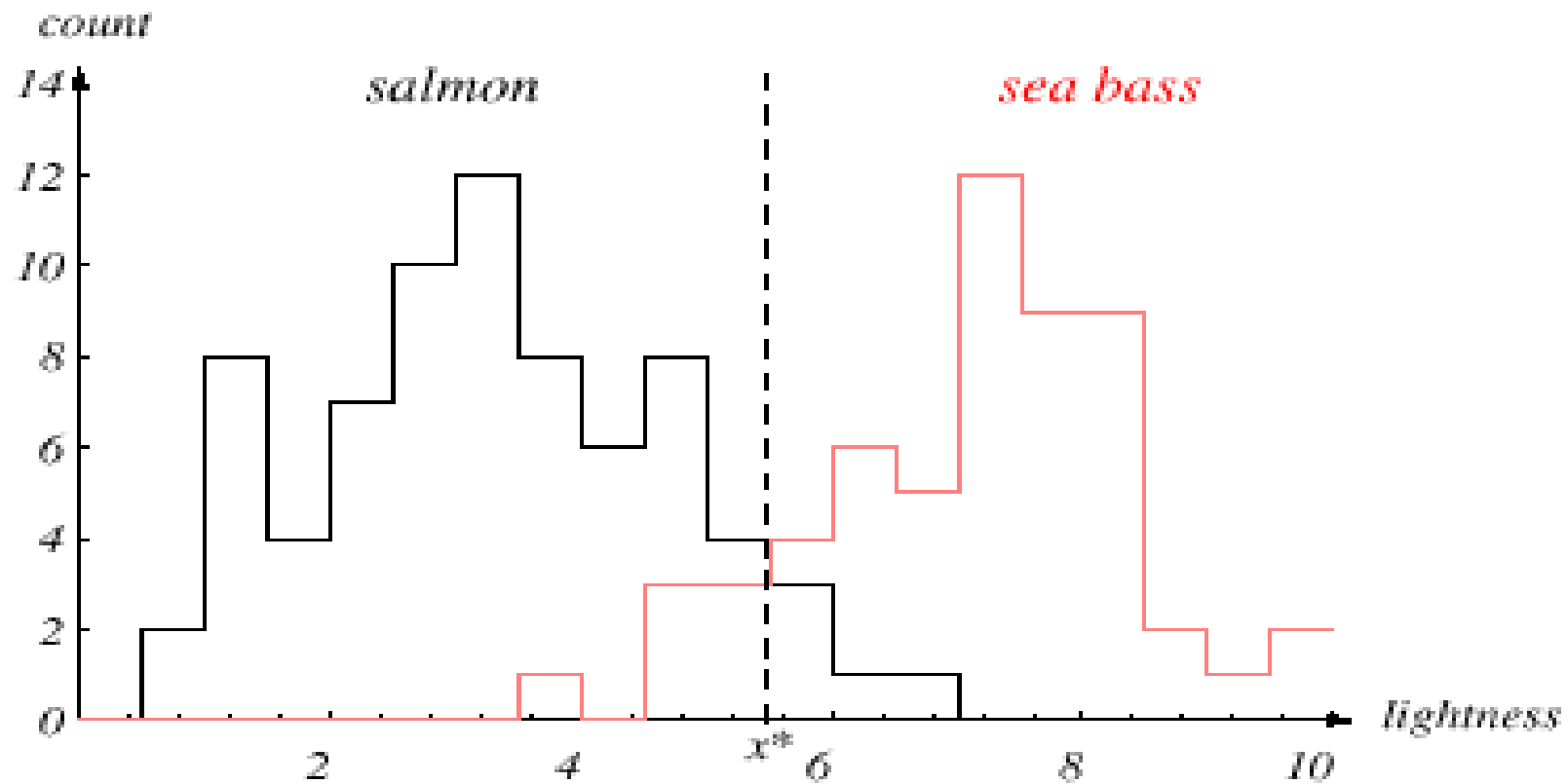
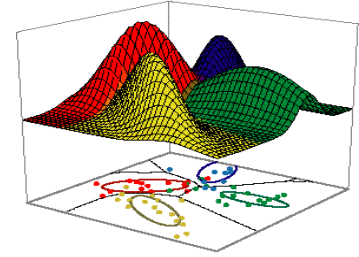
L^* , Optimal decision boundary placement

An Example – fish sorter



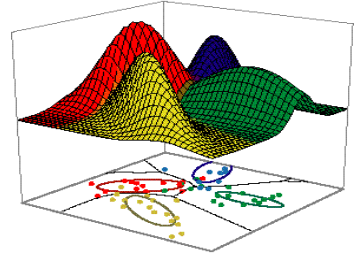
- Although, on average, salmon are shorter than sea bass, **length** is a poor feature alone!
- Try selecting **lightness** as a possible feature.

Histogram of fish lightness

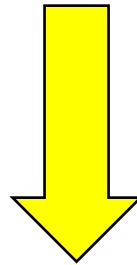


x^* , Optimal decision boundary placement

Threshold decision boundary & cost relationship

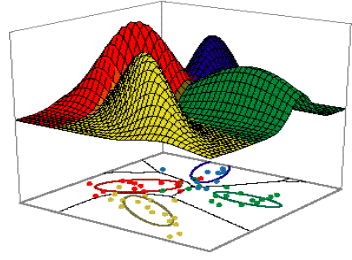


- Not all errors are equal
 - Some misclassifications can have higher costs
 - E.g. missed cancer diagnosis (false negative/missed positive) vs. false positive diagnosis (false positive)
- In this case, selling salmon as sea bass is not a problem, but selling sea bass as salmon will aggravate customers!
 - Move our decision boundary toward smaller values of lightness in order to minimize the cost
 - Reduce the number of sea bass that are classified salmon!

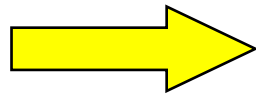


Task of decision theory

A new feature vector



- No single feature provides a good separation of the two fish types (classes)
- Try combining multiple features:
 - Adopt the lightness and add the width of the fish



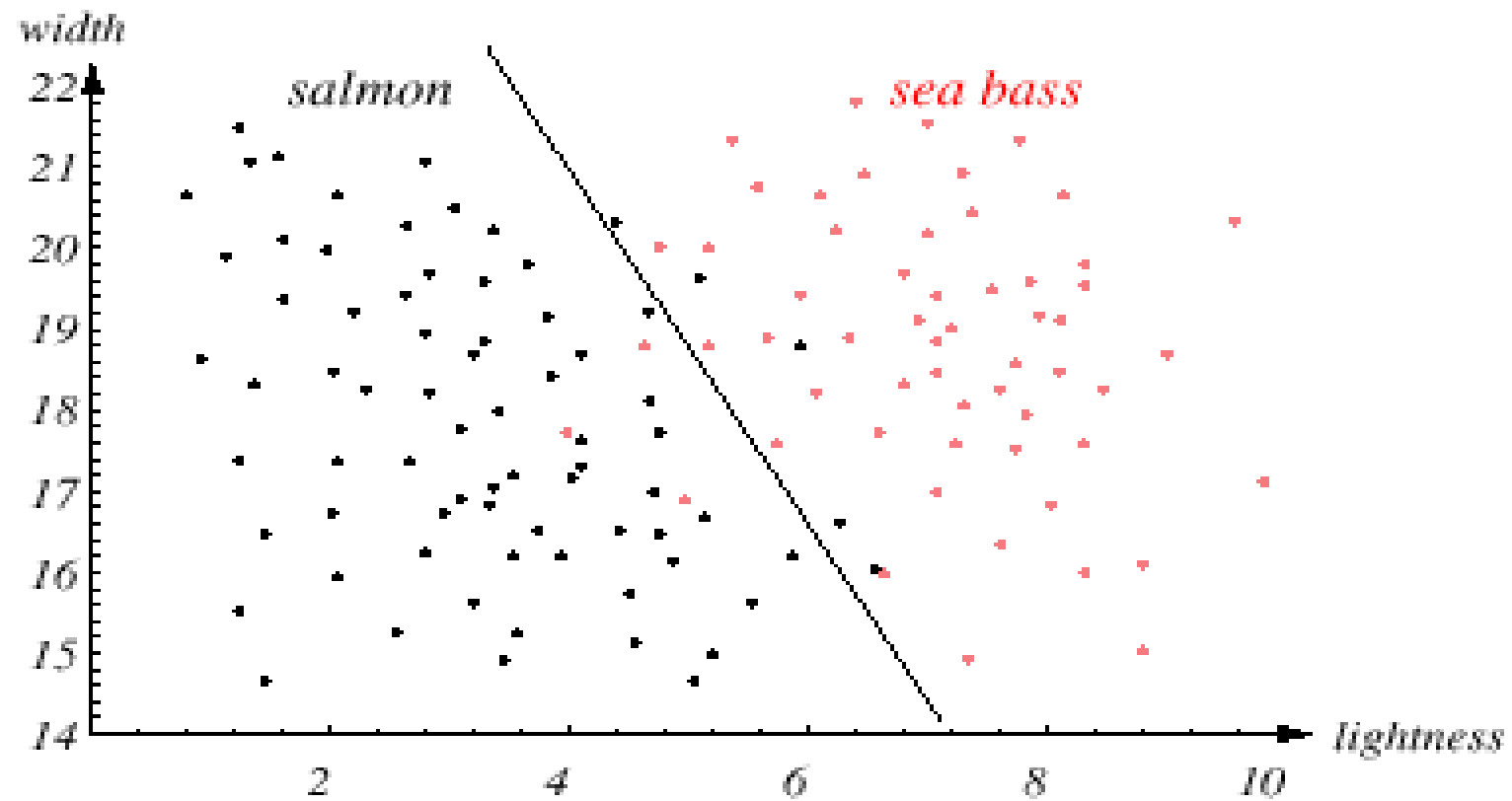
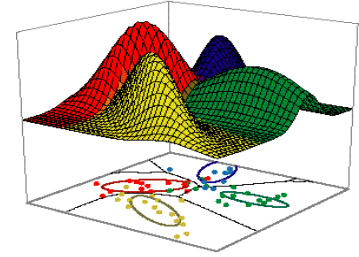
$$\mathbf{x}^T = [x_1, x_2]$$

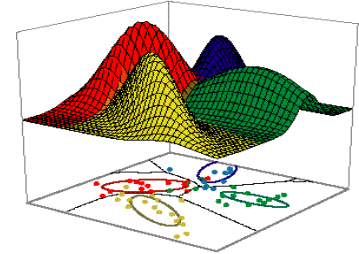
Lightness

Width

The real object 'fish' is now represented by a feature vector

Scatter plot of fish width vs. lightness

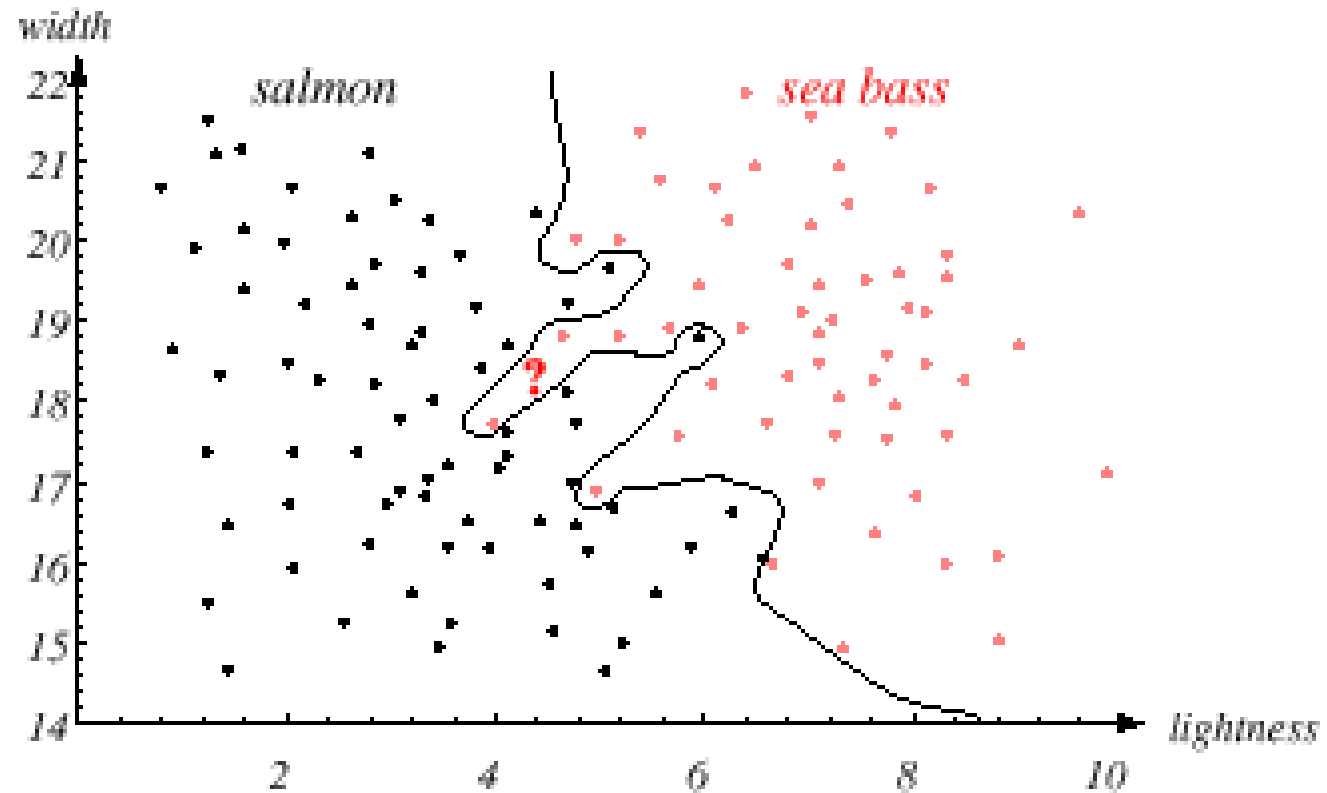
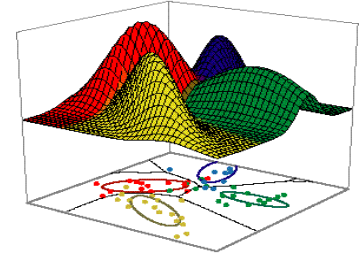




Make the classifier more complex?

- We might add other features that are not correlated with the ones we already have.
 - A precaution should be taken not to reduce the performance by adding “noisy features”
- We are tempted to believe that the best decision boundary should be the one which provides an optimal performance such as in the following figure:

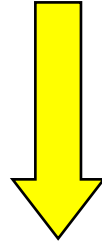
An 'optimal' decision boundary?



Overfitting and generalization



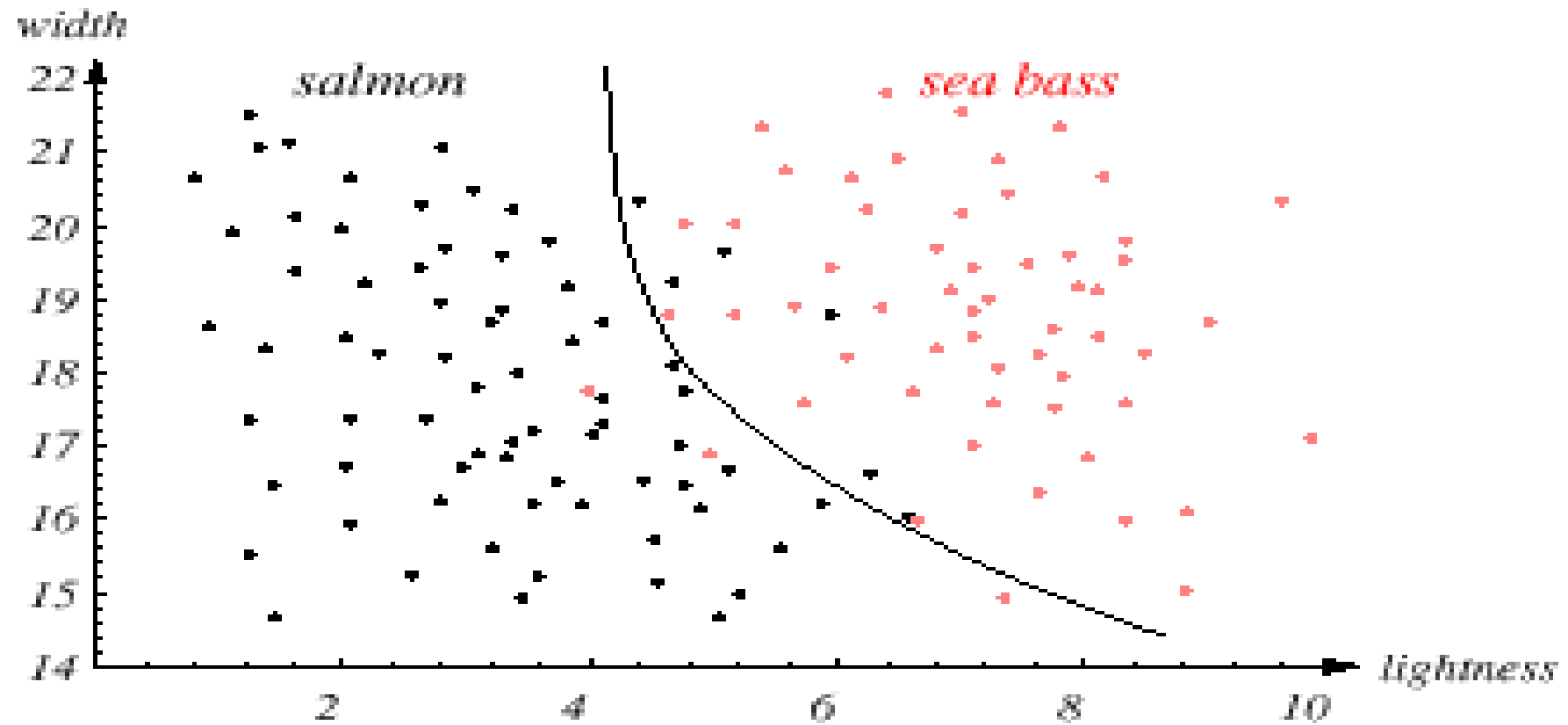
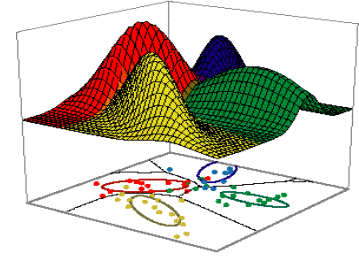
- However, our satisfaction is premature because the central aim of designing a classifier is to correctly classify novel input, not just training example inputs.



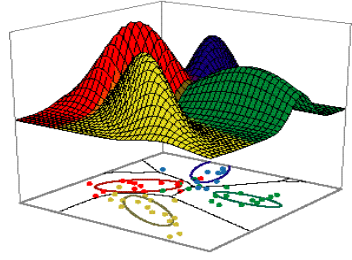
Issue of generalization!

- Performance on the training data is not always indicative of performance on future test data

An improved decision boundary

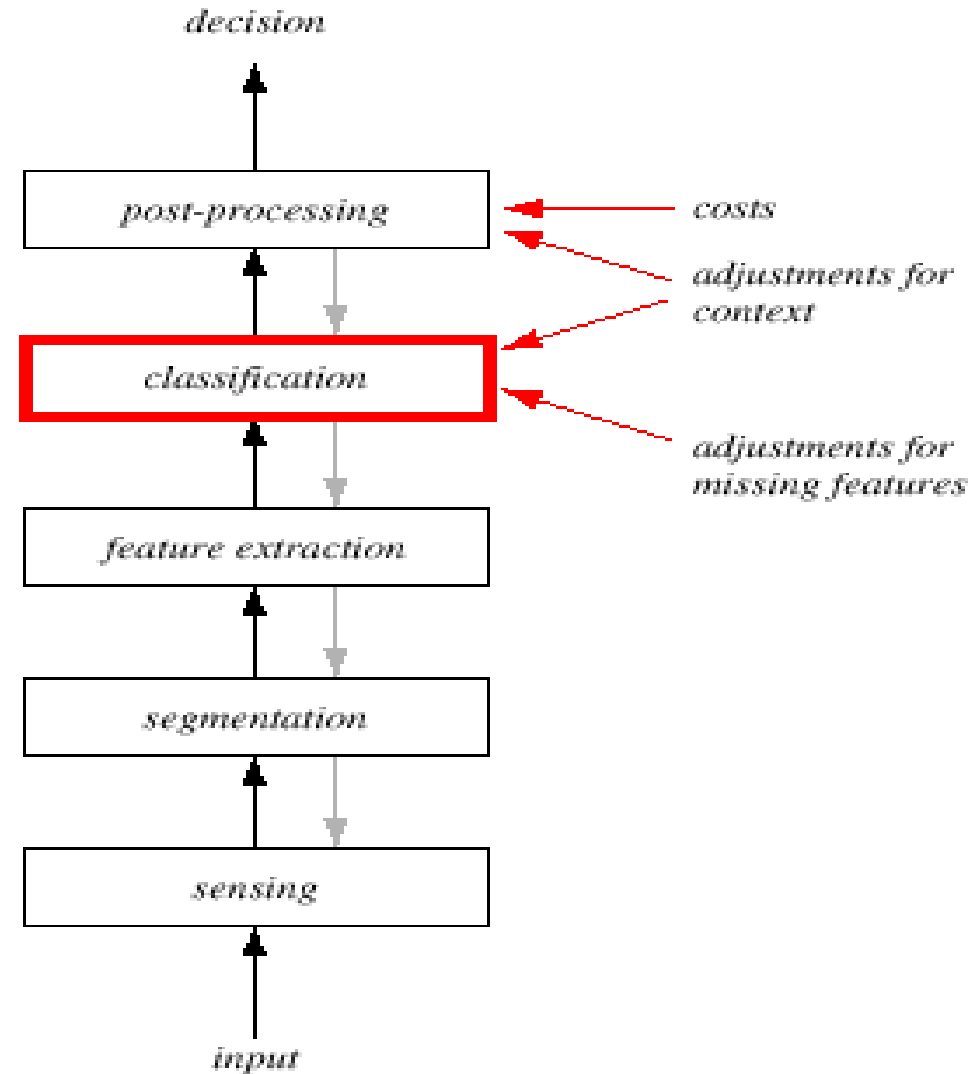


Pattern Recognition Systems

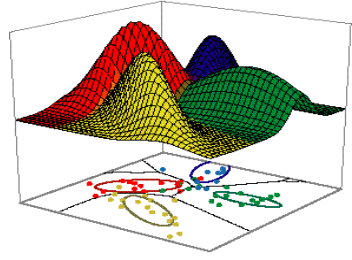


- Sensing

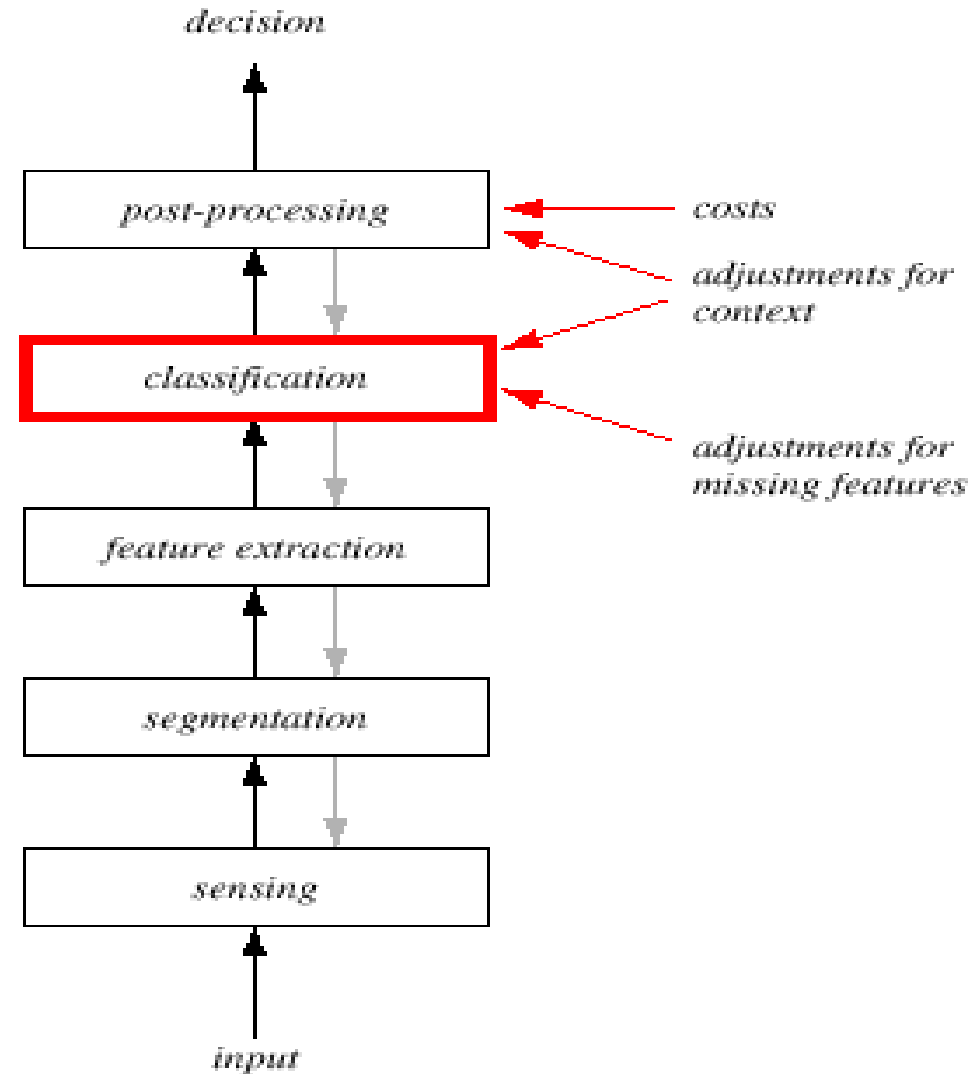
- Use of a transducer (e.g. camera or microphone)
- PR system depends of the bandwidth, the resolution, sensitivity, distortion, and noise of the transducer



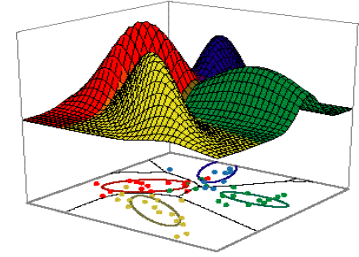
Pattern Recognition Systems



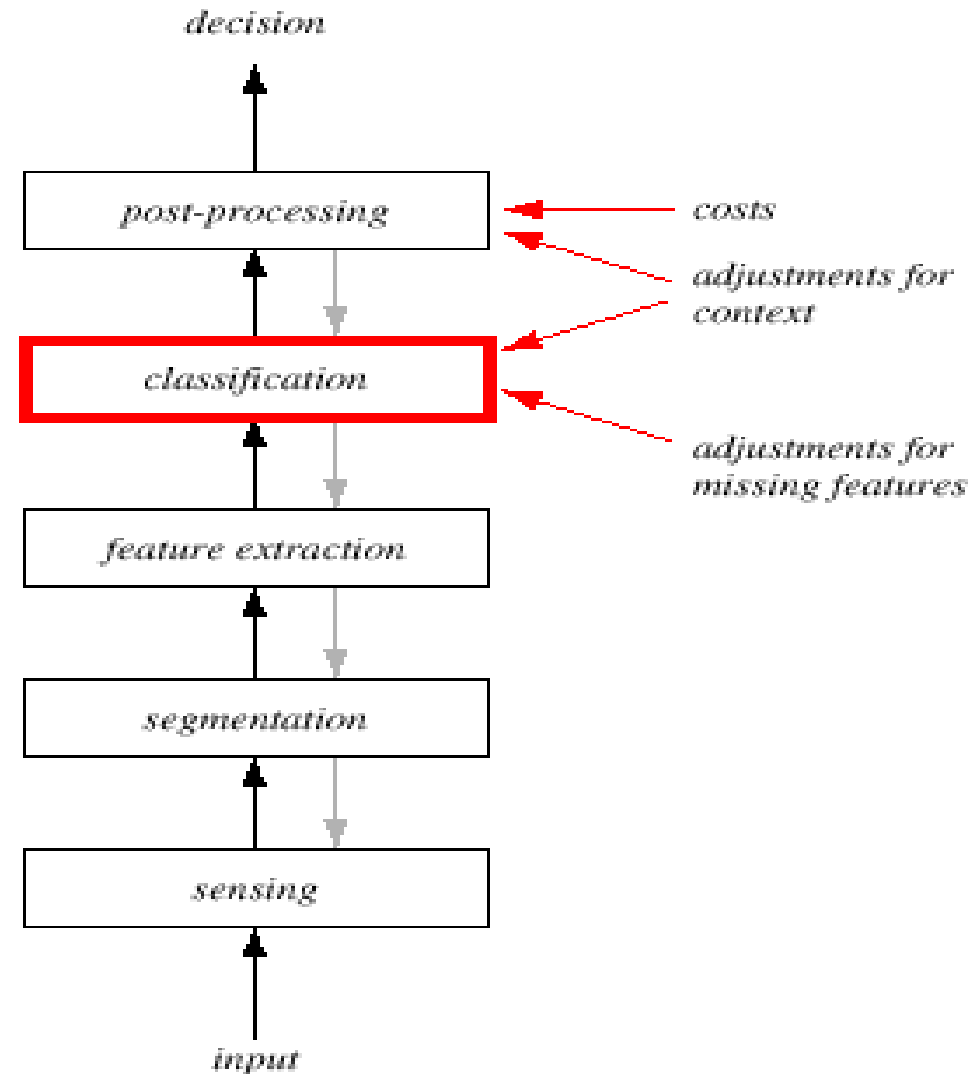
- Segmentation
 - Extract object of interest from background.
 - Patterns should be well separated and should not overlap



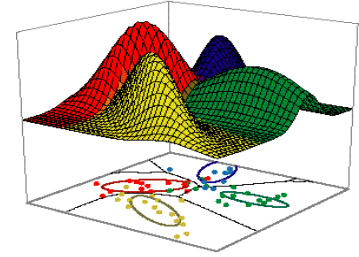
Pattern Recognition Systems



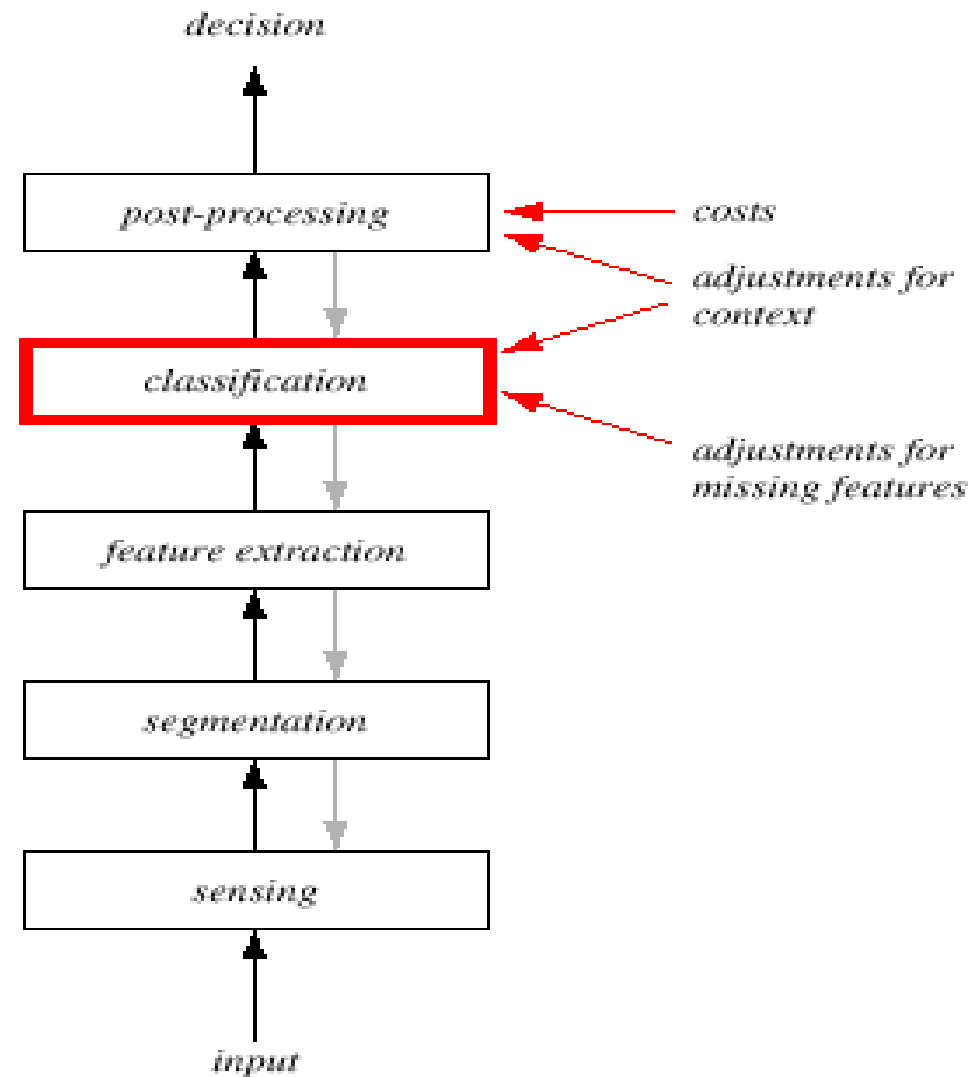
- Feature extraction
 - Discriminative features
 - May require invariant features with respect to translation, rotation and scale.
 - If features are powerful, then classifier can be trivial.



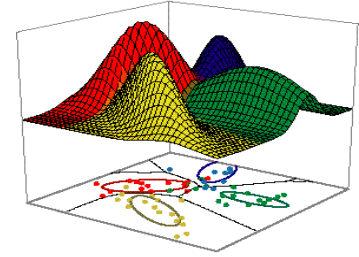
Pattern Recognition Systems



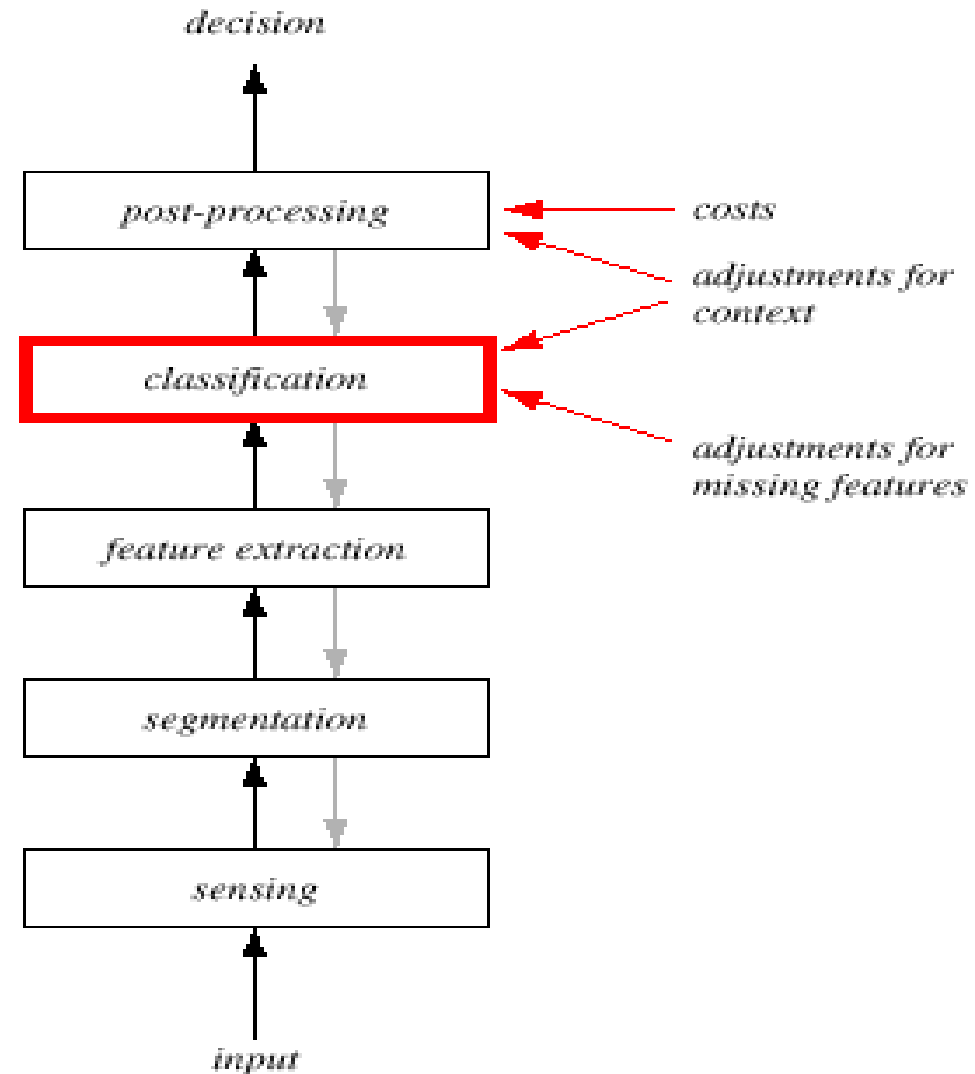
- Classification
 - Use a feature vector provided by a feature extractor to assign the object to a category



Pattern Recognition Systems

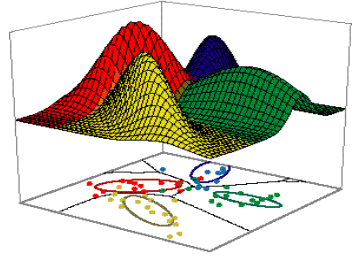
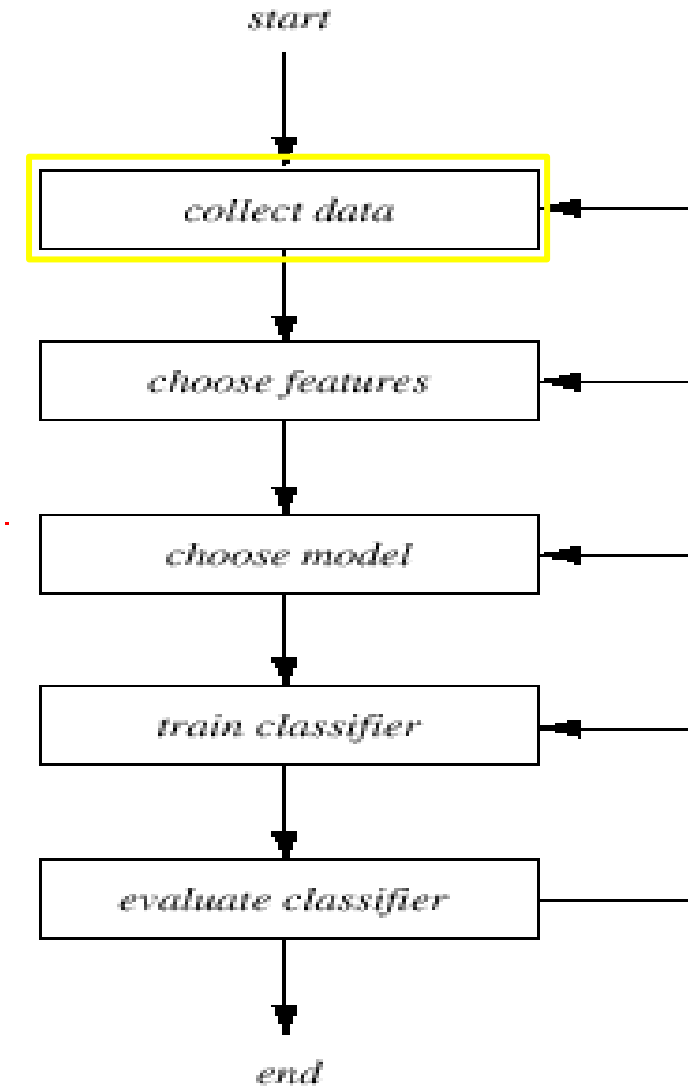


- Post Processing
 - Exploit **context** dependent information other than from the target pattern itself to improve performance
 - May also adjust for costs
 - Can combine multiple classifiers



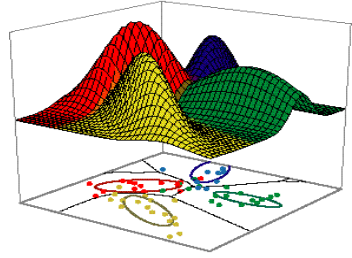
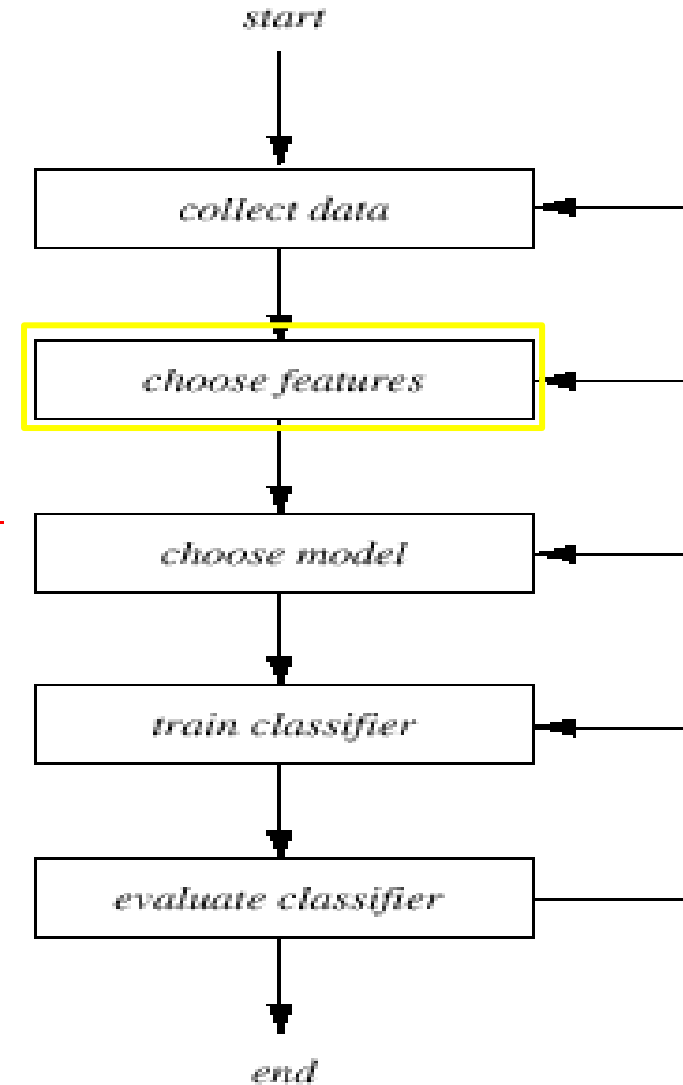
The Design Cycle

- Data Collection
 - How do we know when we have collected an adequately large and representative set of examples for training and testing the system?

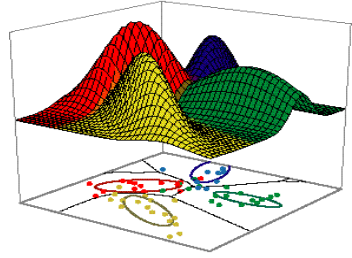


The Design Cycle

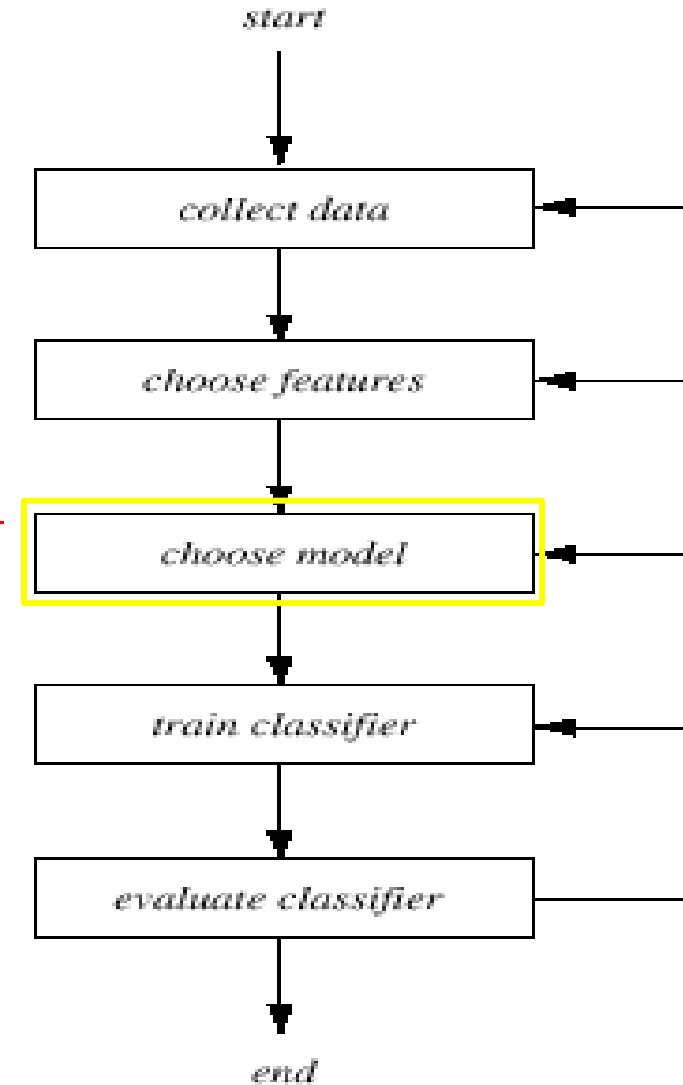
- Feature Choice
 - Depends on the characteristics of the problem domain. Simple to extract, invariant to irrelevant transformation insensitive to noise.
 - Use prior information about the problem.
 - E.g. fishermen tell you salmon are shorter.



The Design Cycle

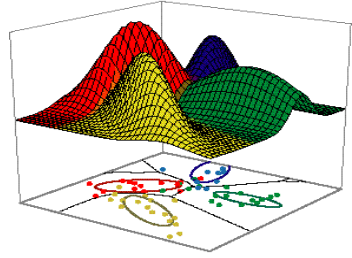
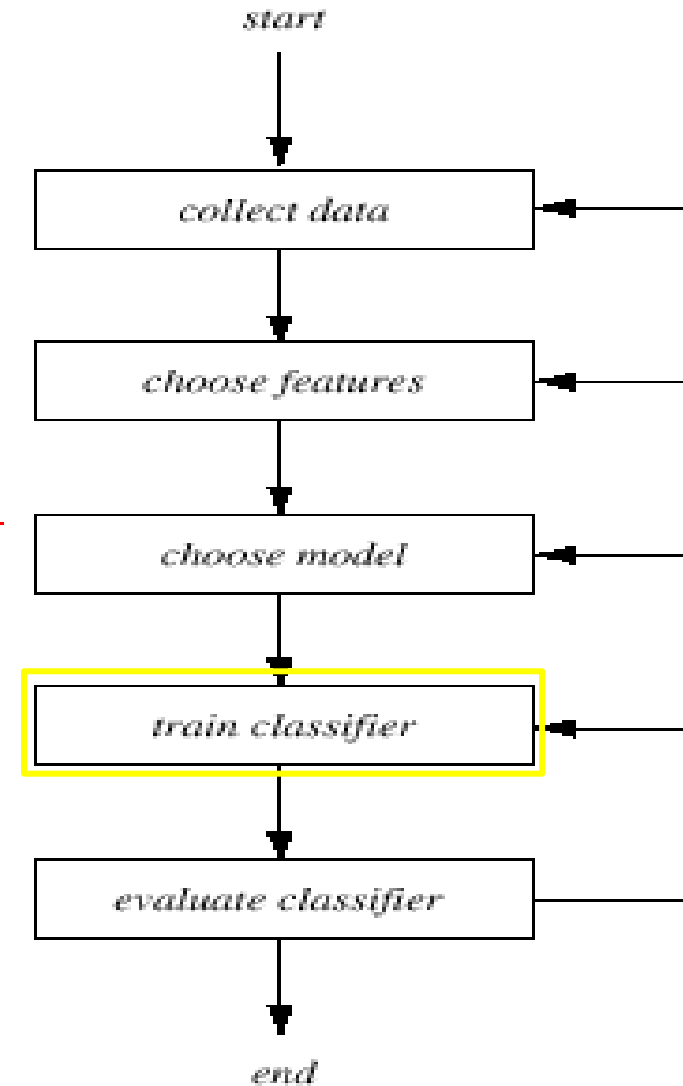


- Model Choice
 - Model is our representation of a fish (width and lightness)
 - If unsatisfied with the performance of our fish classifier and want to jump to another class of model (different features)
 - Use prior information about the problem.

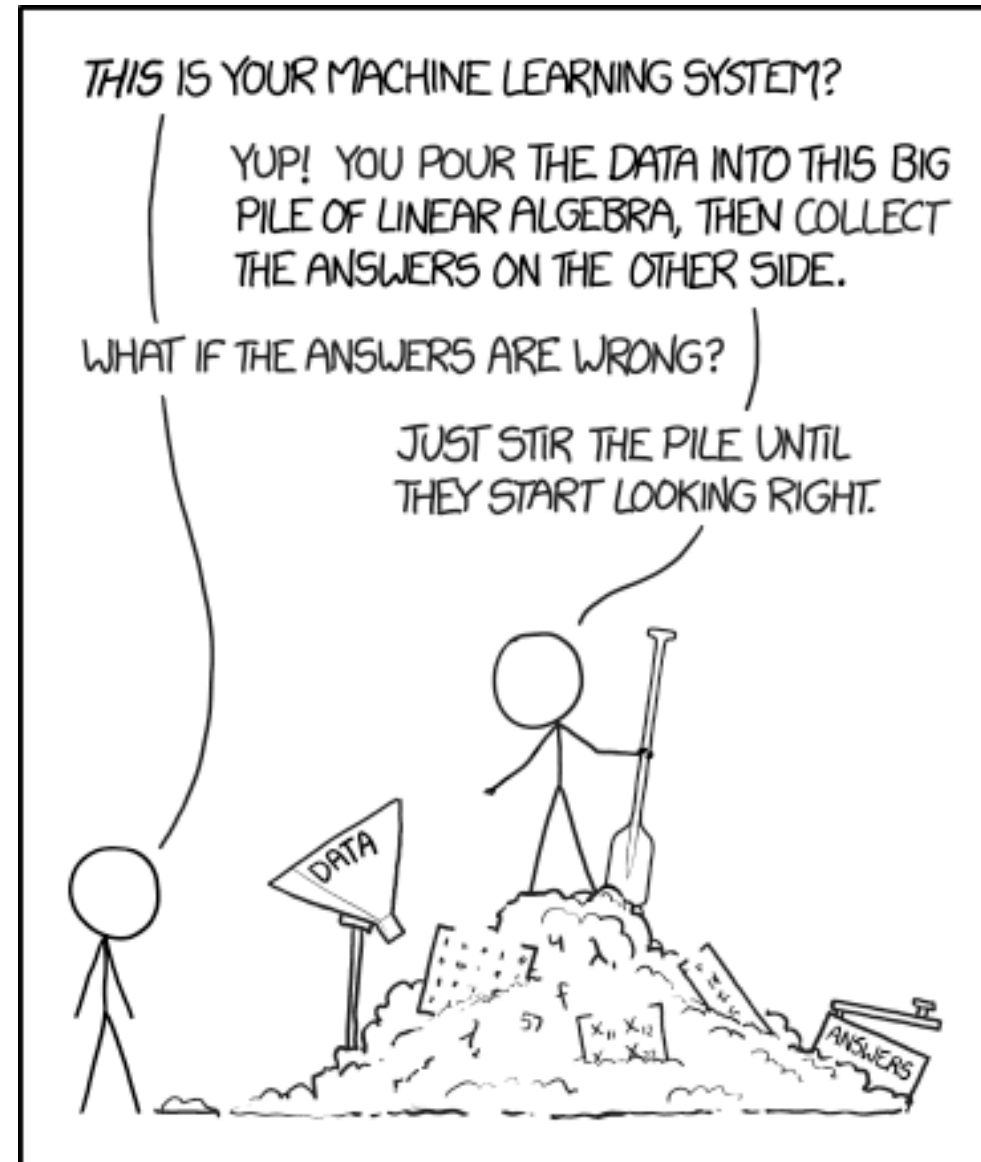
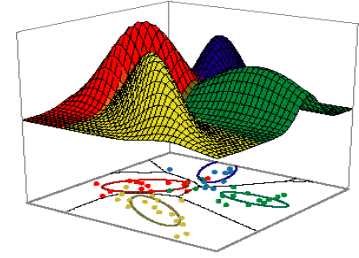


The Design Cycle

- Training
 - Use data to determine the classifier. Many different procedures for training classifiers and choosing models

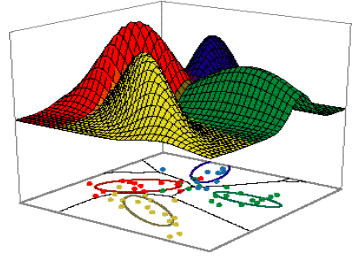
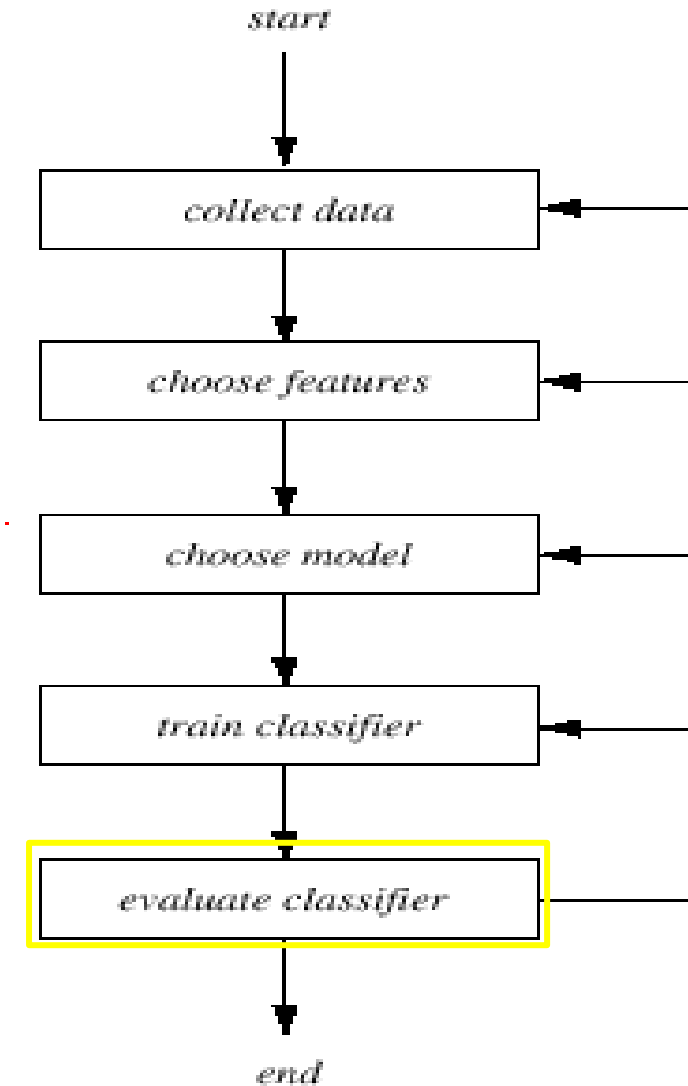


Training = “Just keep stirring”

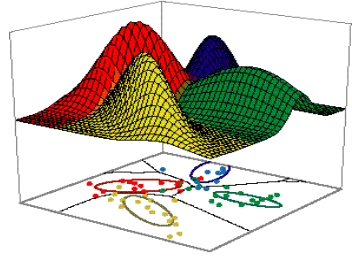


The Design Cycle

- Evaluation
 - Measure the error rate (or performance) and switch model, features, classifier, training algorithm, etc.



Computational Complexity



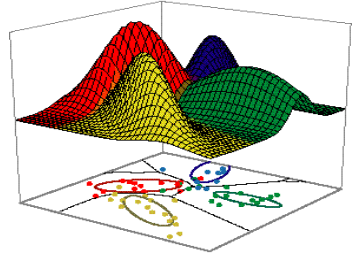
- What is the trade-off between computational ease and performance?
 - How an algorithm scales as a function of the number of features, patterns or categories...
 - Not the focus of this course.

Unsupervised Learning

- Cluster these items:



Learning and Adaptation



- Supervised learning
 - A teacher provides a category label or cost for each pattern in the training set
 - Classifier is given features (inputs) and also answers (outputs)
 - Comparing the input and the output lets the training algorithm see what it needs to learn
 - Task is to learn a function converting inputs to their corresponding outputs
- Unsupervised learning
 - Learner receives only input features, but no classification output values
 - During training, classifier is not told “what to do”
 - It looks at the data and tries to find patterns
 - Useful for figuring out what types of inputs are likely to occur
 - The system forms clusters or “natural groupings” of the input patterns
- Semi-supervised learning
 - Learn from both labelled and unlabelled data

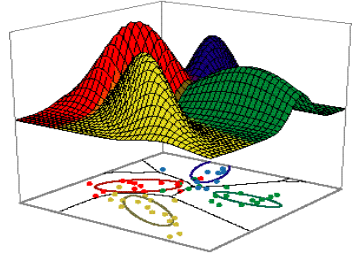
Learning and Adaptation



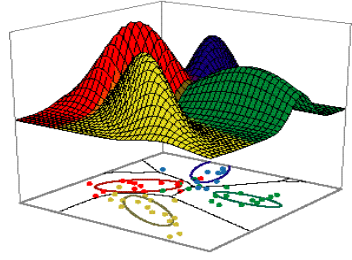
- Parametric models
 - Feature data for each class can be described by some parameterized distribution
 - Decision boundary a function of those parameters
 - Goal is to estimate the parameters correctly
- Nonparametric
 - No assumptions made about the data
 - Decision boundary directly depends on data
 - Goal is to determine decision boundary directly

Related Fields

- Image Processing
- Associative Memory
- Regression
- Interpolation
- Density Estimation
- Data Mining
- Machine Learning
- Deep Learning
- Natural Language Processing
- Artificial Intelligence



Course Goals



- Be familiar with a variety of pattern classification approaches
 - Statistical
 - Machine learning
 - Nonparametric
 - Unsupervised
- Understand how to set up your experiment such that you will obtain valid conclusions from your results
 - Construction of datasets & partitioning
 - Hypothesis testing and statistical tests
- Be able to critically assess the claims of others