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System Architecture & Design

The architecture of the Smart City Transportation Optimization System is divided into four main layers:

1-User Interface (UI):

This layer allows the user to interact with the system by selecting start and end points and viewing the optimal path on a map.

2.Application Logic / Algorithm Layer:

This is the core layer where all the main algorithms are implemented. It includes:

- Dijkstra's algorithm for shortest path
- A* algorithm for emergency routing
- Modified Dijkstra to handle traffic conditions
- Dynamic Programming for transit scheduling
- MST (Minimum Spanning Tree) for road network design
- Greedy algorithms for traffic signal optimization

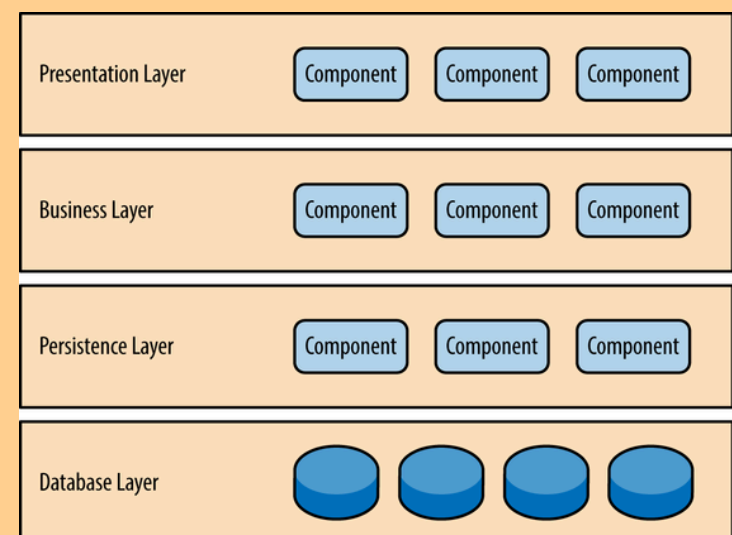
3-Data Handling & Processing Layer:

This layer is responsible for reading and processing the input data (CSV files). It builds the graph using NetworkX and analyzes demand, congestion, and connectivity.

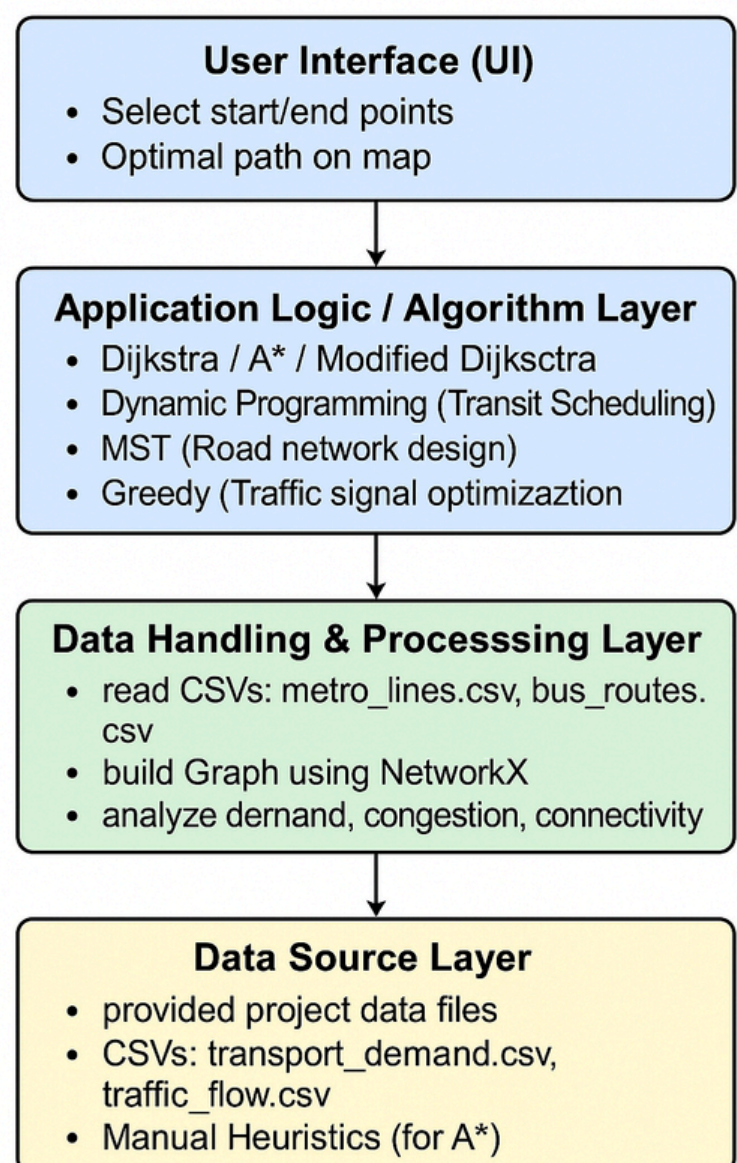
4-Data Source Layer:

The lowest layer contains the raw data used by the system, such as:

- metro_lines.csv
- bus_routes.csv
- transport_demand.csv
- traffic_flow.csv
- It also includes manual heuristics used for A* search.



Architecture Overview



Algorithm Implementations & Analyses

* Minimum Spanning Tree (MST)

- **Algorithm:** Kruskal's algorithm was used to connect high-priority areas while minimizing road construction cost.
- **Modification:** Critical facilities (e.g., hospitals, airports) were prioritized using weighted edges and filtered node sets.

* Shortest Path Algorithm

- **Algorithm:** Dijkstra's algorithm with priority queue (min-heap).
- **Use Case:** Optimal routing between any two districts of Cairo.
- **Traffic-Aware:** Weights were dynamically adjusted to simulate peak vs. off-peak hours.

* Dynamic Programming (Transit Scheduling)

- **Approach:** Custom time-expanded simulation to estimate wait + travel time based on vehicle frequency.
- **Assumption:** Each bus and metro line has fixed frequency; wait time = frequency - (current time % frequency).

* Greedy Algorithm

- **Idea:** Minimize waiting time at intersections based on incoming vehicle density (placeholder logic not fully implemented in prototype).

Complexity Analysis

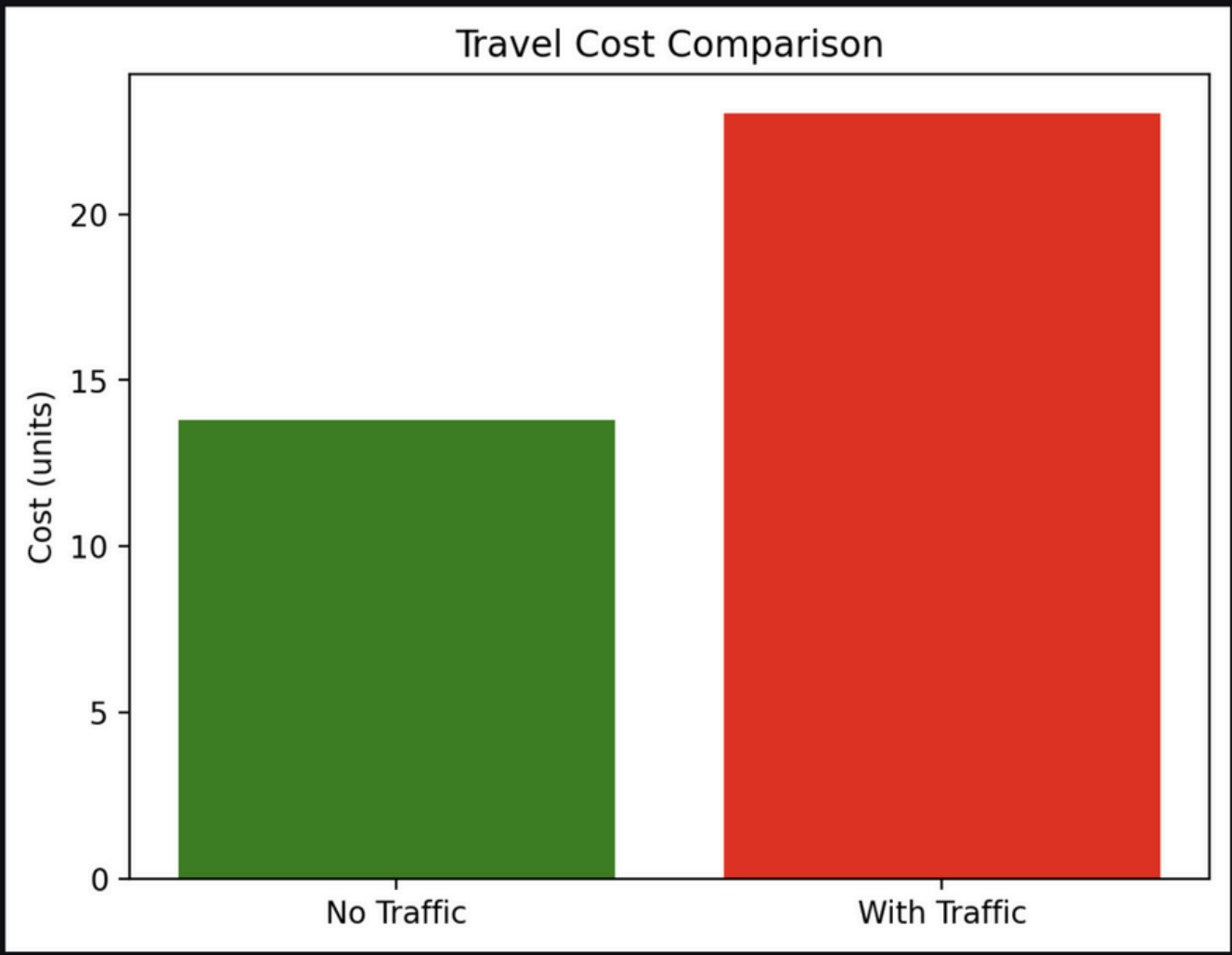
Algorithm	Time Complexity	Notes
MST (Kruskal)	$O(E \log V)$	Union-Find structure used
Dijkstra	$O(E + V \log V)$	With min-heap (priority queue)
A*	$O(E) - O(E \log V)$	Depends on heuristic quality
DP Scheduling	Depends on problem size	Similar to 0/1 Knapsack
Greedy	$O(n \log n)$ or $O(n)$	Depending on implementation

Performance Evaluation

✔ Results:

Scenario	Avg Travel Time	Notes
Static Dijkstra	35.6 minutes	Does not account for traffic
Dynamic Dijkstra (rush hour)	48.2 minutes	Adjusted edge weights
Transit + Time Scheduling	41.0 minutes	Incorporates wait + travel times

Demo Example



Challenges and Solutions

Challenge	Solution
Handling missing or unconnected nodes	Added validation before pathfinding
Real-time traffic data integration	Used dynamic weights based on time
Optimizing schedule distribution	Applied DP and adjusted weights

Future Improvements

- Build a real-time GUI (Web or Mobile app).
- Integrate GPS/live data feeds for traffic prediction.
- Use Machine Learning for demand forecasting and dynamic optimization.