

# **Programming Paradigms CSI2120 – Winter 2018**

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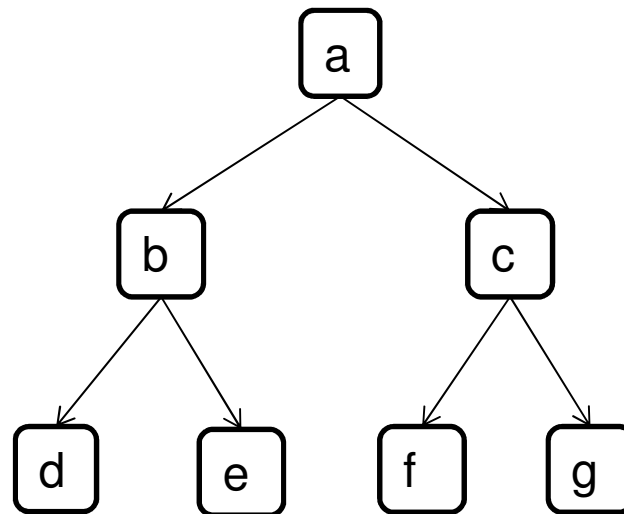
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# Logic Programming in Prolog

- **Data structures**
- **Trees**
  - Representation
  - Examples
  - Binary search tree
- **Graphs**
  - Representation
  - Graph problems

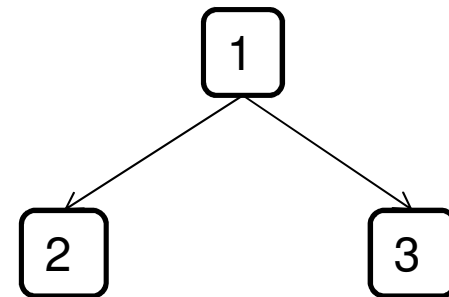
# Binary Trees

- **Tree where each element has one parent and up to two children**
  - Common data structure



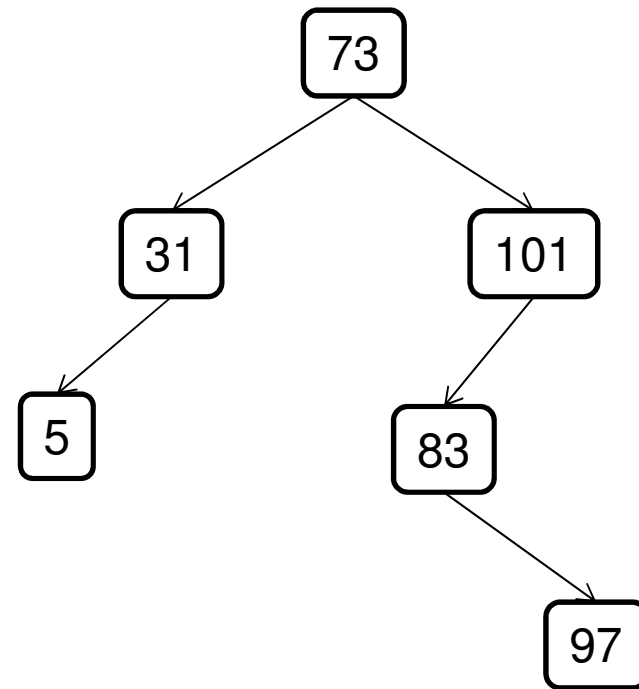
# Binary Trees in Prolog

- **Define a fact for a node in the data structure**  
`t(element, left, right)`
  - `element` is the value stored at the node
  - `left` is the left subtree
  - `right` is the right subtree
  - an empty subtree can be marked with a `'nil'`
- **A tree with only the root node is `t(1, nil, nil)`**
- **A balanced binary tree with three nodes**  
`t(1, t(2, nil, nil), t(3, nil, nil)) .`



# A Binary Tree

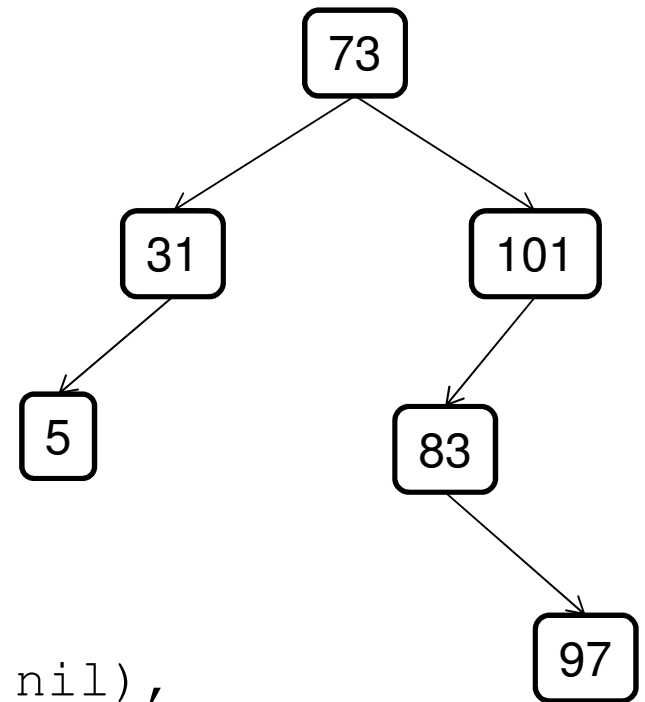
```
treeA(X) :- X=  
t(73,  
  t(31,  
    t(5,nil,nil),  
    nil),  
  t(101,  
    t(83,nil  
      t(97,nil,nil)),  
    nil)).
```



# Inorder Traversal

```
inorder(nil).  
inorder(t(Root, Left, Right)) :-  
    inorder(Left),  
    write(Root),  
    write(' '),  
    inorder(Right).
```

```
?- treeB(X), inorder(X).  
5 31 73 83 97 101  
X = t(73, t(31, t(5, nil, nil), nil),  
t(101, t(83, nil, t(97, nil, nil)),  
nil)).
```



# Binary Search Tree

- **Sort predicate (assuming no duplicates)**

```
precedes(Key1, Key2) :- Key1 < Key2.
```

- **Boundary case: Searched for node found**

```
binarySearch(Key, t(Key, _, _)).
```

- **Search in left subtree**

```
binarySearch(Key, t(Root, Left, _)) :-  
    precedes(Key, Root),  
    binarySearch(Key, Left).
```

- **Search in right subtree**

```
binarySearch(Key, t(Root, _, Right)) :-  
    precedes(Root, Key),  
    binarySearch(Key, Right).
```

# Element Insertion in a BST

- **Boundary case insert new leaf node**

```
insert(Key, nil, t(Key, nil, nil)).
```

- **Insert new node on the left**

```
insert(Key, t(Root, Left, Right),  
        t(Root, LeftPlus, Right)) :-  
    precedes(Key, Root),  
    insert(Key, Left, LeftPlus).
```

- **Insert new node on the right**

```
insert(Key, t(Root, Left, Right),  
        t(Root, Left, RightPlus)) :-  
    precedes(Root, Key),  
    insert(Key, Right, RightPlus).
```



# Deleting a Key at the Root

- **Boundary case replace key with the right subtree**

```
deleteBST(Key, t(Key, nil, Right), Right).
```

- **Boundary case replace key with the left subtree**

```
deleteBST(Key, t(Key, Left, nil), Left).
```

- **Delete root and replace with maximum left key**

```
deleteBST(Key, t(Key, Left, Right),  
           t(NewRoot, NewLeft, Right)) :-  
    removeMax(Left, NewLeft, NewRoot).
```

– arguments of removeMax

```
% removeMax(Tree, NewTree, Max)
```

# Deleting any Key

- **Search on the left subtree for key to delete**

```
deleteBST(Key, t(Root, Left, Right),  
          t(Root, LeftSmaller, Right)) :-  
    precedes(Key, Root),  
    deleteBST(Key, Left, LeftSmaller).
```

- **Search on the right subtree for key to delete**

```
deleteBST(Key, t(Root, Left, Right),  
          t(Root, Left, RightSmaller)) :-  
    precedes(Root, Key),  
    deleteBST(Key, Right, RightSmaller).
```

# Deleting the Maximum Element

- **boundary case right-most node is maximum**

```
removeMax(t(Max, Left, nil), Left, Max).
```

- **recursion on the right of the root node (for tree nodes sorted with less than).**

```
removeMax(t(Root, Left, Right),  
          t(Root, Left, RightSmaller), Max) :-  
    removeMax(Right, RightSmaller, Max).
```

# General Graphs

- **A binary tree is a tree, and a tree is a (restricted) graph**
- **Graph representation**

`g ([Node, ...] , [edge (Node1, Node2, Weight) , ...]) .`

- **directed edge**

`edge (g (Ns, Edges) , N1, N2, Weight) :-`

`member (edge (N1, N2, Weight) , Edges) .`

- **undirected edge**

`edge (g (Ns, Edges) , N1, N2, Weight) :-`

`member (edge (N1, N2, Weight) , Edges) ;`

`member (edge (N2, N1, Weight) , Edges) .`

# Neighbors of a Node

- Find all neighboring nodes and the connecting edge (use with edge/4 predicate).

```
neighbors(Graph,Node,Neighbors):-  
    setof((N,Edge),edge(Graph,Node,N,Edge),Neighbors).
```

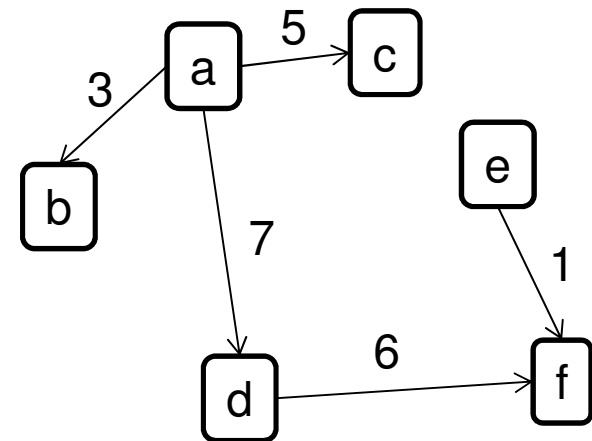
– Define a graph

```
graphA(X) :- X=g([a,b,c,d,e,f],  
                 [edge(a,b,3), edge(a,c,5), edge(a,d,7),  
                 edge(e,f,1), edge(d,f,6)]).
```

– Example queries

```
?- graphA(X), neighbors(X,c,V).  
V = [ (a, 5) ].
```

```
?- graphA(X), neighbors(X,a,V).  
V = [ (b, 3), (c, 5), (d, 7) ].
```



# Graph Coloring

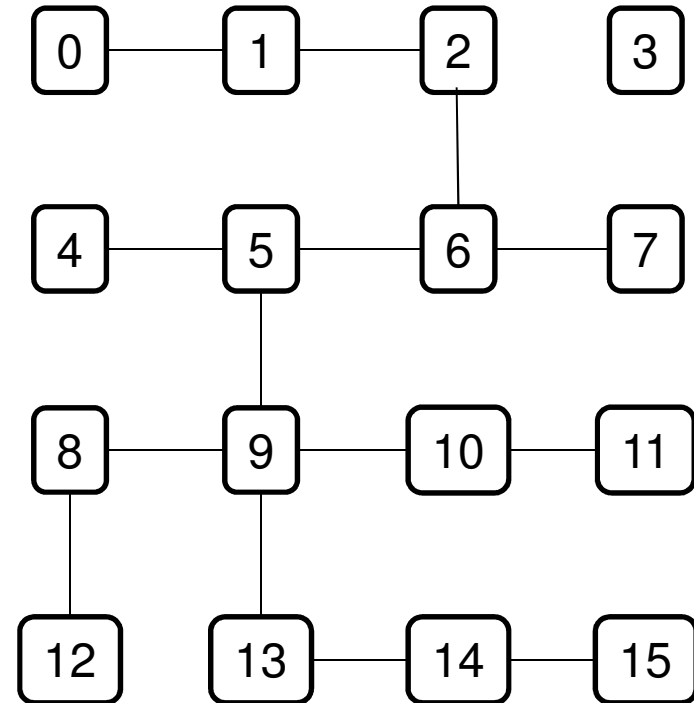
```
color(g(Ns,Edges),Colors,GC):-  
    generate(Ns,Colors,GC),  
    test(Edges,GC).  
generate([],_,[]).  
generate([N|Ns],Colors,[(N,C)|Q]):-  
    member(C,Colors),  
    generate(Ns,Colors,Q).  
test([],_).  
test([edge(N1,N2,_)|Ns],GC):-  
    member((N1,C1),GC),  
    member((N2,C2),GC),  
    C1\=C2,  
    test(Ns,GC).
```

# Graph Coloring Queries

```
?- graphA(X), color(X, [red, blue, white, green], V) .  
X = g([a, b, c, d, e, f], [edge(a, b, 3), edge(a, c, 5), edge(a, d, 7), edge(e, f, 1), edge(d, f, 6)]),  
V = [ (a, red), (b, blue), (c, blue), (d, blue), (e, red), (f, white)] ;  
X = ...,  
V = [ (a, red), (b, blue), (c, blue), (d, blue), (e, red), (f, green)] ;  
X = ...,  
V = [ (a, red), (b, blue), (c, blue), (d, blue), (e, blue), (f, red)] ;  
...
```

# Graph Problem: Labyrinth

```
link(0,1). % start = 0
link(1,2).
link(2,6).
link(6,5).
link(6,7).
link(5,4).
link(5,9).
link(9,8).
link(8,12).
link(9,10).
link(10,11).
link(9,13).
link(13,14).
link(14,15). % finish = 15
```





# Labyrinth Solution

- **Predicate generating undirected edges**

```
successor(A,B) :- link(A,B).
```

```
successor(A,B) :- link(B,A).
```

- **Define the finish node**

```
finish(15).
```

- **Boundary case if finish is reached**

```
pathFinder([Last|Path],[Last|Path]) :-  
    finish(Last).
```

- **Go to the next node in a depth first manner unless it is a loop**

```
pathFinder([Curr|Path],Solution) :-  
    successor(Curr,Next),  
    \+member(Next,Path),write(Next),nl,  
    pathFinder([Next,Curr|Path],Solution).
```

# Example: Labyrinth

```
?- pathFinder([0],S).
```

```
1
```

```
2
```

```
6
```

```
5
```

```
4
```

```
9
```

```
8
```

```
12
```

```
10
```

```
11
```

```
13
```

```
14
```

```
15
```

```
S = [15, 14, 13, 9, 5, 6, 2, 1, 0] ;
```

```
7
```

```
false.
```

# Summary

- **Binary tree**
  - tree representation
  - binary search tree
  - insert an element
  - delete an element
- **Graphs**
  - graph representation
  - graph search
  - graph coloring
  - labyrinth