```
In [2]: from google.colab import drive
        drive.mount('/content/drive')
       Mounted at /content/drive
In [3]: pip install telepot
       Collecting telepot
         Downloading telepot-12.7.tar.gz (73 kB)
                                                    - 73.1/73.1 kB 2.8 MB/s eta 0:00:00
         Preparing metadata (setup.py) ... done
       Requirement already satisfied: urllib3>=1.9.1 in /usr/local/lib/python3.10/dist-p
       ackages (from telepot) (2.0.7)
       Requirement already satisfied: aiohttp>=3.0.0 in /usr/local/lib/python3.10/dist-p
       ackages (from telepot) (3.9.5)
       Requirement already satisfied: aiosignal>=1.1.2 in /usr/local/lib/python3.10/dist
       -packages (from aiohttp>=3.0.0->telepot) (1.3.1)
       Requirement already satisfied: attrs>=17.3.0 in /usr/local/lib/python3.10/dist-pa
       ckages (from aiohttp>=3.0.0->telepot) (23.2.0)
       Requirement already satisfied: frozenlist>=1.1.1 in /usr/local/lib/python3.10/dis
       t-packages (from aiohttp>=3.0.0->telepot) (1.4.1)
       Requirement already satisfied: multidict<7.0,>=4.5 in /usr/local/lib/python3.10/d
       ist-packages (from aiohttp>=3.0.0->telepot) (6.0.5)
       Requirement already satisfied: yarl<2.0,>=1.0 in /usr/local/lib/python3.10/dist-p
       ackages (from aiohttp>=3.0.0->telepot) (1.9.4)
       Requirement already satisfied: async-timeout<5.0,>=4.0 in /usr/local/lib/python3.
       10/dist-packages (from aiohttp>=3.0.0->telepot) (4.0.3)
       Requirement already satisfied: idna>=2.0 in /usr/local/lib/python3.10/dist-packag
       es (from yarl<2.0,>=1.0->aiohttp>=3.0.0->telepot) (3.7)
       Building wheels for collected packages: telepot
         Building wheel for telepot (setup.py) ... done
         Created wheel for telepot: filename=telepot-12.7-py3-none-any.whl size=57940 sh
       a256=bbbc3f69b5708c2b28ddfbfc40a12115bb6ebecfdc3a1f24e146183251811258
         Stored in directory: /root/.cache/pip/wheels/9f/9a/92/2e34a093e40a09338847e54dc
       9fcaab4ce01a59ba17c784c6c
       Successfully built telepot
       Installing collected packages: telepot
       Successfully installed telepot-12.7
In [4]: from keras.models import load_model
        from collections import deque
        import matplotlib.pyplot as plt
        import numpy as np
        import argparse
        import pickle
        import cv2
        import telepot
        from datetime import datetime
        import pytz
In [5]: def getTime():
          IST = pytz.timezone('Asia/Kolkata')
          timeNow = datetime.now(IST)
          return timeNow
          curr date = timeNow.strftime("%d-%m-%Y")
          curr_time = timeNow.strftime("%H:%M:%S")
```

```
In [ ]: import cv2
        import numpy as np
        import requests
        from collections import deque
        import matplotlib.pyplot as plt
        def print_results(video, limit=None):
            trueCount = 0
            imageSaved = 0
            filename = 'demo.jpg'
            finalImage = 'finaImage.jpg'
            sendAlert = 0
            location = "Bangalore"
            print("Loading model ...")
            model = load_model('/content/drive/MyDrive/DLSIP/data/modelnew.h5')
            Q = deque(maxlen=128)
            vs = cv2.VideoCapture(video)
            writer = None
            (W, H) = (None, None)
            count = 0
            while True:
                (grabbed, frame) = vs.read()
                if not grabbed:
                    break
                if W is None or H is None:
                     (H, W) = frame.shape[:2]
                output = frame.copy()
                frame = cv2.cvtColor(frame, cv2.COLOR_BGR2RGB)
                frame = cv2.resize(frame, (128, 128)).astype("float32")
                frame = frame.reshape(128, 128, 3) / 255
                preds = model.predict(np.expand_dims(frame, axis=0))[0]
                Q.append(preds)
                results = np.array(Q).mean(axis=0)
                i = (preds > 0.50)[0]
                label = i
                text_color = (0, 255, 0)
                if label:
                    text_color = (0, 0, 255)
                    trueCount += 1
                text = "Accident: {}".format(label)
                FONT = cv2.FONT HERSHEY SIMPLEX
                cv2.putText(output, text, (35, 50), FONT, 1.25, text_color, 3)
                if writer is None:
                    fourcc = cv2.VideoWriter_fourcc(*"MJPG")
                    writer = cv2.VideoWriter("/content/drive/MyDrive/DLSIP/data/recorded
```

```
writer.write(output)
         plt.imshow(cv2.cvtColor(output, cv2.COLOR_BGR2RGB))
         plt.show()
         if trueCount == 50:
             if imageSaved == 0:
                 if label:
                     cv2.imwrite(filename, output)
                     imageSaved = 1
             if sendAlert == 0:
                 timeMoment = getTime()
                 bot_token = '6995313518:AAEk75VKT4joXvDpiDeeLudi4h7S_zaej3o'
                 msg = f"Accident Detection!!\nLOCATION: {location}\nTIME: {timeM
                 send_msg_on_telegram(msg, bot_token, filename)
                 sendAlert = 1
         key = cv2.waitKey(1) & 0xFF
         if key == ord("q"):
             break
     print("[INFO] cleaning up...")
     writer.release()
     vs.release()
 def send_msg_on_telegram(msg, bot_token, image_path):
     telegram_api_url = f"https://api.telegram.org/bot{bot_token}/sendPhoto"
     files = {'photo': open(image_path, 'rb')}
     params = {
         'chat_id': '@violence_detect',
         'caption': msg
     tel resp = requests.post(telegram api url, params=params, files=files)
     if tel_resp.status_code == 200:
         print("Notification has been sent on Telegram")
     else:
         print("Could not send Message")
 V path = "/content/drive/MyDrive/DLSIP/data/videoplayback (online-video-cutter.
 print_results(V_path)
Loading model ...
1/1 [======= ] - 1s 941ms/step
```



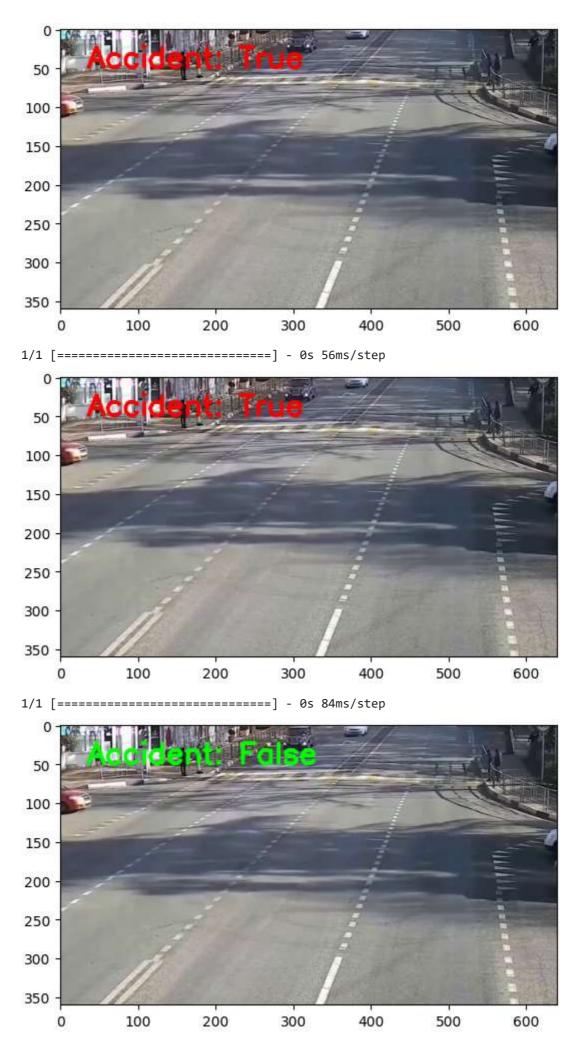








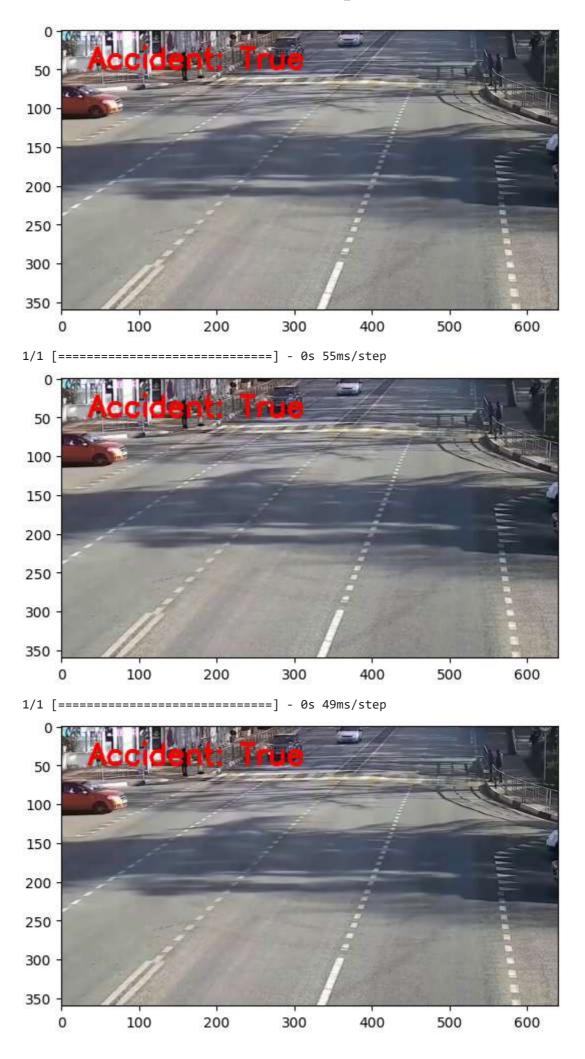






































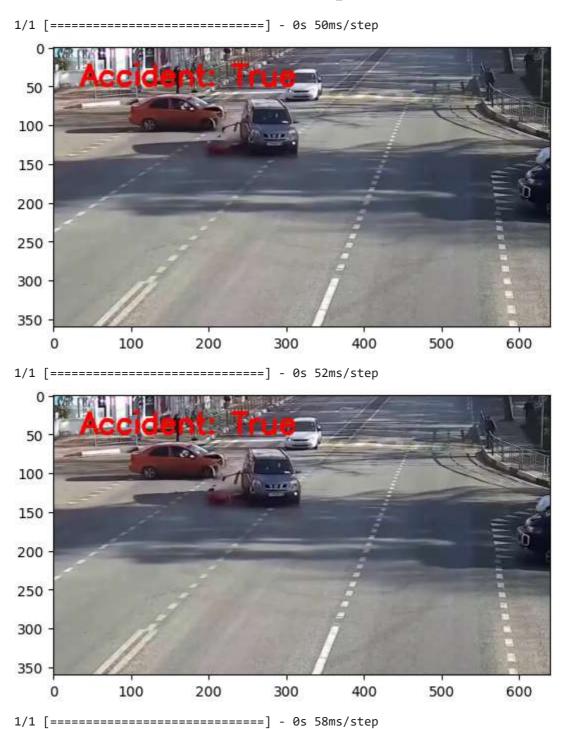










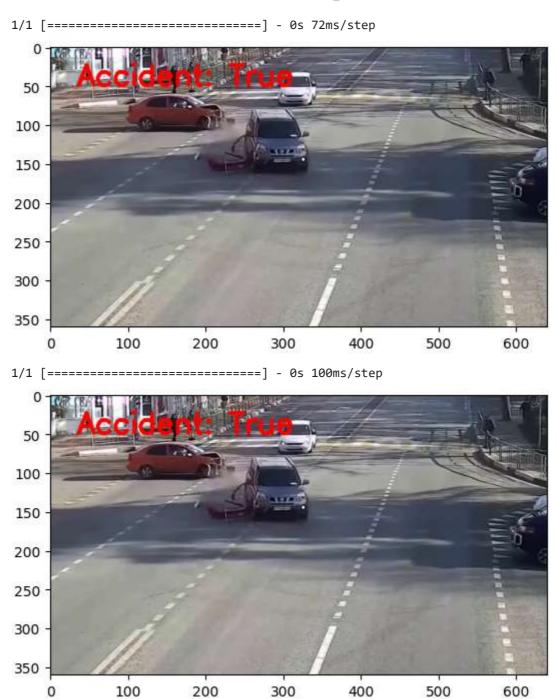




Notification has been sent on Telegram 1/1 [======] - 0s 52ms/step







========] - 0s 70ms/step





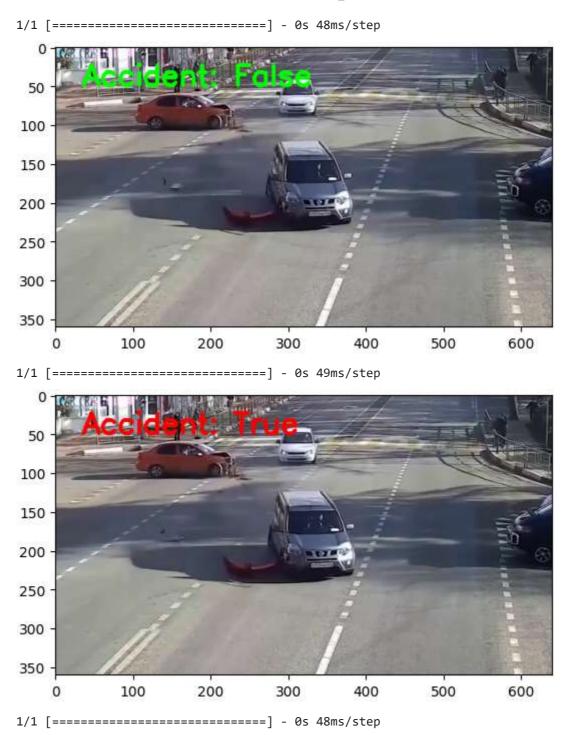




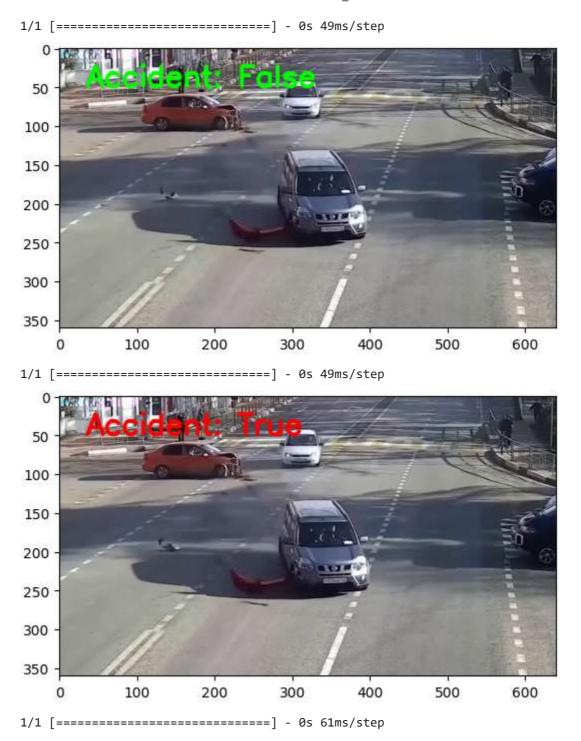












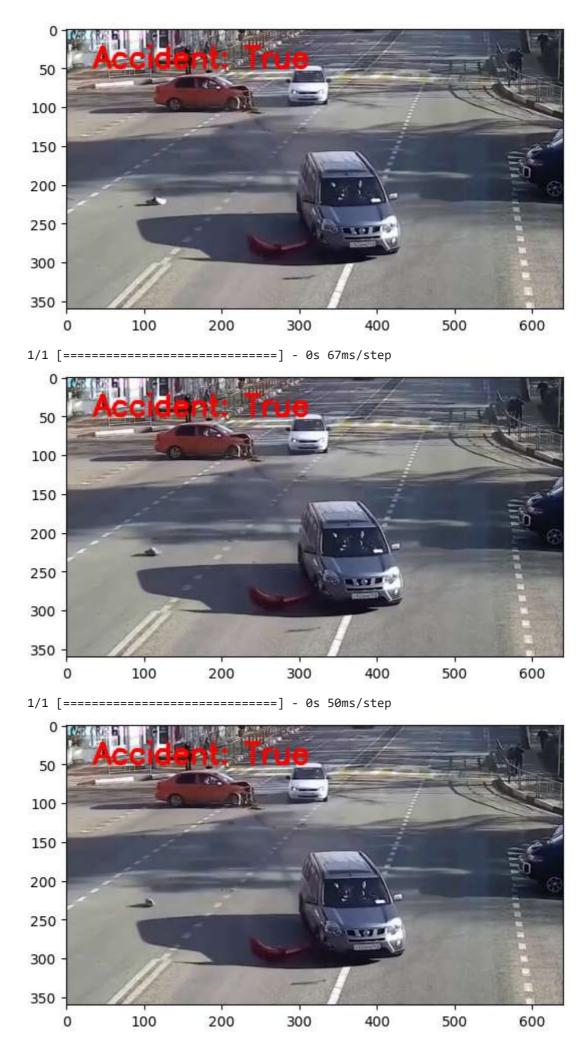










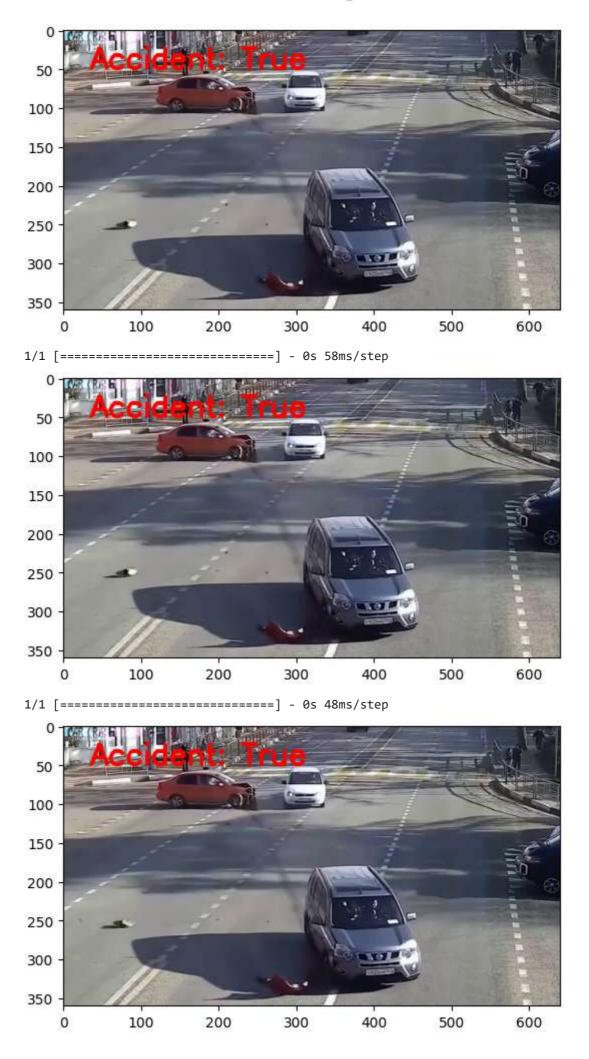


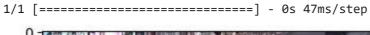












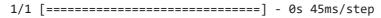


1/1 [=====] - 0s 50ms/step



1/1 [=======] - 0s 74ms/step



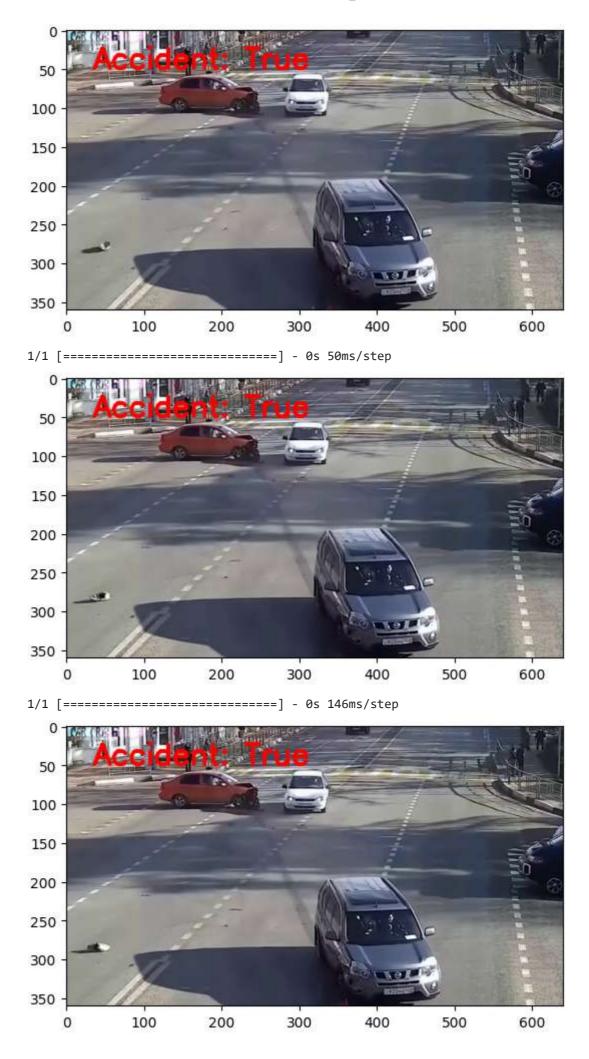


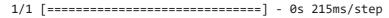


1/1 [======] - 0s 52ms/step



1/1 [======] - 0s 50ms/step







1/1 [======= ] - 0s 146ms/step



1/1 [======] - 0s 64ms/step





=======] - Øs 49ms/step







1/1 [=======] - 0s 50ms/step

