dog_app

July 9, 2020

1 Convolutional Neural Networks

1.1 Project: Algorithm for a Dog Identification App

In this project, you will follow along on how to make dog breed classifier

1.1.1 The Road Ahead

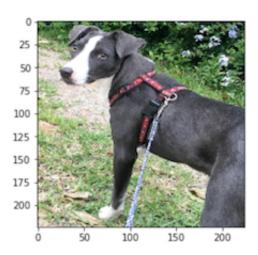
- Section ??: Import Datasets
- Section ??: Detect Humans
- Section ??: Detect Dogs
- Section ??: Create a CNN to Classify Dog Breeds (from Scratch)
- Section ??: Create a CNN to Classify Dog Breeds (using Transfer Learning)
- Section ??: Write your Algorithm
- Section ??: Test Your Algorithm

```
## Step 0: Import Datasets
```

Step 1: Detect Humans

In this section, I'll use OpenCV's implementation of Haar feature-based cascade classifiers to detect human faces in images.

hello, dog! your predicted breed is ... American Staffordshire terrier

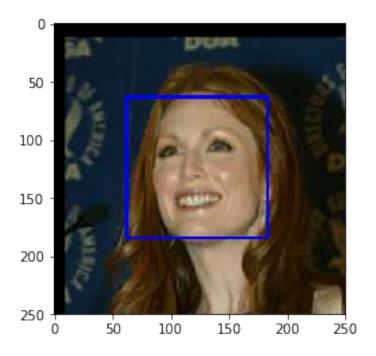


Sample Dog Output

```
In [3]: import cv2
        import matplotlib.pyplot as plt
        %matplotlib inline
        # extract pre-trained face detector
        face_cascade = cv2.CascadeClassifier('haarcascades/haarcascade_frontalface_alt.xml')
        # load color (BGR) image
        img = cv2.imread(human_files[52])
        # convert BGR image to grayscale
        gray = cv2.cvtColor(img, cv2.COLOR_BGR2GRAY)
        # find faces in image
        faces = face_cascade.detectMultiScale(gray)
        # print number of faces detected in the image
        print('Number of faces detected:', len(faces))
        # get bounding box for each detected face
        for (x,y,w,h) in faces:
            # add bounding box to color image
            cv2.rectangle(img,(x,y),(x+w,y+h),(255,0,0),2)
        # convert BGR image to RGB for plotting
        cv_rgb = cv2.cvtColor(img, cv2.COLOR_BGR2RGB)
        # display the image, along with bounding box
        plt.imshow(cv_rgb)
```

```
plt.show()
```

Number of faces detected: 1



1.1.2 Assess the Human Face Detector

Question 1: Use the code cell below to test the performance of the face_detector function.

- What percentage of the first 100 images in human_files have a detected human face?
- What percentage of the first 100 images in dog_files have a detected human face?

Ideally, we would like 100% of human images with a detected face and 0% of dog images with a detected face. You will see that our algorithm falls short of this goal, but still gives acceptable performance. We extract the file paths for the first 100 images from each of the datasets and store them in the numpy arrays human_files_short and dog_files_short.

Answer:

98% of human faces are detected. 17% of dogs are detected.

In [5]: from tqdm import tqdm

```
human_files_short = human_files[:100]
dog_files_short = dog_files[:100]
#-#-# Do NOT modify the code above this line. #-#-#
## TODO: Test the performance of the face_detector algorithm
## on the images in human_files_short and dog_files_short.
h_counter = 0
d_counter = 0 # Initialize both a counter of human and dogs.
list_h = []
list_d = []
for i in range(len(human_files_short)):
    if face_detector(human_files_short[i]) == True: h_counter += 1 # Counter the number
    else: list_h.append(human_files_short[i])
for i in range(len(dog_files_short)):
    if face_detector(dog_files_short[i]) == True: d_counter += 1 # Counter the number of
    else: list_d.append(dog_files_short[i])
print(h_counter)
print(d_counter)
```

Now just for curiosity, I'll do some investigation about the undeducted faces, also the detected faces in the dog photos.

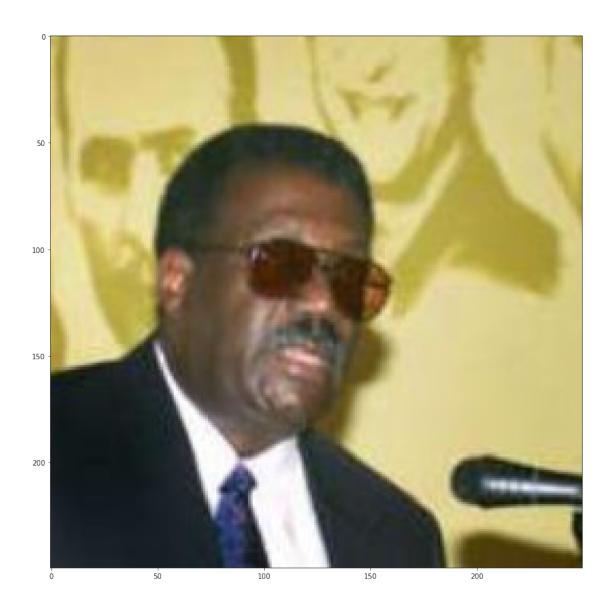
First the undeducted faces:

98 17

```
In [6]: def face_print(z):
    # method to print the photos, same as the one above
    fig=plt.figure(figsize=(14, 14))
    columns = 5
    rows = 4

for i, mg in enumerate(z):
    i += 1
    img = cv2.imread(mg)
    # convert BGR image to grayscale
    gray = cv2.cvtColor(img, cv2.COLOR_BGR2GRAY)

# find faces in image
    faces = face_cascade.detectMultiScale(gray)
```



1.1.3 It's very strange that the algorithm did not pick up on the faces in the images. Now I'll take a look at the undeducted images of dogs

In [9]: face_print(list_d)

/opt/conda/lib/python3.6/site-packages/matplotlib/cbook/deprecation.py:106: MatplotlibDeprecation warnings.warn(message, mplDeprecation, stacklevel=1)



1.1.4 Some images have faces in it, so I wouldn't really consider them failures, others are just failures.

Step 2: Detect Dogs In this section, I'll use a pre-trained model to detect dogs in images.

1.1.5 Obtain Pre-trained VGG-16 Model

```
# check if CUDA is available
use_cuda = torch.cuda.is_available()
```

Downloading: "https://download.pytorch.org/models/vgg16-397923af.pth" to /root/.torch/models/vgg100%|| 553433881/553433881 [00:06<00:00, 81888608.70it/s]

Given an image, this pre-trained VGG-16 model returns a prediction (derived from the 1000 possible categories in ImageNet) for the object that is contained in the image.

1.1.6 Making Predictions with a Pre-trained Model

In the next code cell, I'll write a function that accepts a path to an image (such as 'dogImages/train/001.Affenpinscher/Affenpinscher_00001.jpg') as input and returns the index corresponding to the ImageNet class that is predicted by the pre-trained VGG-16 model.

1.1.7 Write a Dog Detector

1.1.8 Assess the Dog Detector

Question 2: Use the code cell below to test the performance of your dog_detector function.

- What percentage of the images in human_files_short have a detected dog?
- What percentage of the images in dog_files_short have a detected dog?

Answer:

90 % of dogs images are detected as dogs 1 % of humen images are detected as dogs

Step 3: Create a CNN to Classify Dog Breeds (from Scratch)
In this step I will create CNN to classify dog Breeds from scratch

```
In [17]: import os
         from torchvision import datasets
         ## TODO: Specify data loaders
         import numpy as np
         import torch
         import torchvision
         import torchvision.transforms as transforms
         import torch.optim as optim
         from torchvision import datasets
         use_cuda = torch.cuda.is_available()
         num_workers = 0
         batch size = 20
         transform ={'train': transforms.Compose([transforms.RandomResizedCrop(224),
                                         transforms.RandomRotation(25),
                                        transforms.ToTensor(),
                                        transforms.Normalize(mean=[0.485, 0.456, 0.406],
                                        std=[0.229, 0.224, 0.225]),
                                        'valid':transforms.Compose([transforms.CenterCrop(224),
                                        transforms.ToTensor(),
                                        transforms.Normalize(mean=[0.485, 0.456, 0.406],
                                        std=[0.229, 0.224, 0.225])
                                        ]),
```

```
transforms.Normalize(mean=[0.485, 0.456, 0.406],
                                        std=[0.229, 0.224, 0.225])
                                        1)}
         dog_train = datasets.ImageFolder(root='/data/dog_images/train',transform=transform['tra
         dog_valid = datasets.ImageFolder(root='/data/dog_images/valid',transform=transform['val
         dog_test = datasets.ImageFolder(root='/data/dog_images/test',transform=transform['test'
         train_loader = torch.utils.data.DataLoader(dog_train, batch_size=batch_size, num_worker
         valid_loader = torch.utils.data.DataLoader(dog_valid, batch_size=batch_size, num_worker
         test_loader = torch.utils.data.DataLoader(dog_test, batch_size=batch_size, num_workers=
         loaders = {'train':train_loader,
                    'valid': valid_loader,
                    'test': test_loader}
1.1.9 Display some of the images from the loader.
In [24]: import matplotlib.pyplot as plt
         %matplotlib inline
         # helper function to un-normalize and display an image
         def imshow(img):
             img = (1/(2*3)) * img + 0.5 # unnormalize
             plt.imshow(np.transpose(img, (1, 2, 0))) # convert from Tensor image
In [25]: # obtain one batch of training images
         dataiter = iter(train_loader)
         images, labels = dataiter.next()
         images = images.numpy()
         # convert images to numpy for display
         # plot the images in the batch, along with the corresponding labels
         fig = plt.figure(figsize=(25, 4))
         # display 20 images
         for idx in np.arange(20):
             ax = fig.add_subplot(2, 20/2, idx+1, xticks=[], yticks=[])
             imshow(images[idx])
```

transforms.ToTensor(),

'test': transforms.Compose([transforms.CenterCrop(224),

```
In [26]: # obtain one batch of training images
         dataiter = iter(valid_loader)
         images, labels = dataiter.next()
         images = images.numpy()
         # convert images to numpy for display
         # plot the images in the batch, along with the corresponding labels
         fig = plt.figure(figsize=(25, 4))
         # display 20 images
         for idx in np.arange(20):
             ax = fig.add_subplot(2, 20/2, idx+1, xticks=[], yticks=[])
             imshow(images[idx])
In [27]: # obtain one batch of training images
         dataiter = iter(test_loader)
         images, labels = dataiter.next()
         images = images.numpy()
         # convert images to numpy for display
         # plot the images in the batch, along with the corresponding labels
         fig = plt.figure(figsize=(25, 4))
         # display 20 images
         for idx in np.arange(20):
             ax = fig.add_subplot(2, 20/2, idx+1, xticks=[], yticks=[])
             imshow(images[idx])
```

Question 3: Describe your chosen procedure for preprocessing the data. - How does your code resize the images (by cropping, stretching, etc)? What size did you pick for the input tensor, and why? - Did you decide to augment the dataset? If so, how (through translations, flips, rotations, etc)? If not, why not?

Answer: - I did a random resize chop to size 224, also I normalize it to fit VGG because I am planning to use it for prediction. - I did a random chop and rotation to help the NN accuracy, because image data augmentation proved to help the training.

1.1.10 Model Architecture

Create a CNN to classify dog breed.

```
In [2]: # define the CNN architecture3
        import torch
        import torch.nn as nn
        import torch.nn.functional as F
        class Net(nn.Module):
            ### TODO: choose an architecture, and complete the class
            def __init__(self):
                super(Net, self).__init__()
                ## Define layers of a CNN
                # input: 224*224*3
                self.conv1 = nn.Conv2d(3, 16, 3, padding = 1) #224*224*16
                self.pool = nn.MaxPool2d(2, 2)
                #pool: 112*112*16
                self.conv2 = nn.Conv2d(16, 32, 3, padding = 1) #112*112*32
                #pool: 56*56*16
                self.conv3 = nn.Conv2d(32, 64, 3, padding = 1) #56*56*64
                #pool: 32*32*64
                self.conv4 = nn.Conv2d(64, 128, 3, padding = 1) #28*28*128
                #pool: 14*14*128
                #FCL
                self.fc1 = nn.Linear(14*14*128, 133)
            def forward(self, x):
                ## Define forward behavior
                # add sequence of convolutional and max pooling layers
                x = self.pool(F.relu(self.conv1(x)))
                x = self.pool(F.relu(self.conv2(x)))
                x = self.pool(F.relu(self.conv3(x)))
```

```
x = self.pool(F.relu(self.conv4(x)))
                # flatten image input
                x = x.view(-1, 14*14*128)
                # add dropout layer
                # add second hidden layer
                x = self.fc1(x)
                return x
        # instantiate the CNN
        model_scratch = Net()
        print (model_scratch)
        # check if CUDA is available
        use_cuda = torch.cuda.is_available()
        # move tensors to GPU if CUDA is available
        if use_cuda:
            model_scratch.cuda()
Net(
  (conv1): Conv2d(3, 16, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
  (pool): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1, ceil_mode=False)
  (conv2): Conv2d(16, 32, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
  (conv3): Conv2d(32, 64, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
  (conv4): Conv2d(64, 128, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
  (fc1): Linear(in_features=25088, out_features=133, bias=True)
)
```

Question 4: Outline the steps you took to get to your final CNN architecture and your reasoning at each step.

Answer: I started with 4 conventional layers and maxpooling layer after each layer, and 1 fully-connected layer to predect one of the 133 classes

1.1.11 Specify Loss Function and Optimizer

in the next cell, I'll specify a loss function and optimizer.

1.1.12 Train and Validate the Model

```
In [32]: from PIL import ImageFile
         ImageFile.LOAD_TRUNCATED_IMAGES = True
         def train(n_epochs, loaders, model, optimizer, criterion, use_cuda, save_path):
             # initialize tracker for minimum validation loss
             valid_loss_min = np.Inf
             for epoch in range(1, n_epochs+1):
                 # initialize variables to monitor training and validation loss
                 train_loss = 0.0
                 valid_loss = 0.0
                 ###################
                 # train the model #
                 ##################
                 model.train()
                 for batch_idx, (data, target) in enumerate(loaders['train']):
                     # move to GPU
                     if use_cuda:
                         data, target = data.to('cuda'), target.to('cuda')
                     ## find the loss and update the model parameters accordingly
                     ## record the average training loss, using something like
                     \#\# train_loss = train_loss + ((1 / (batch_idx + 1)) * (loss.data - train_loss)
                     # clear the gradients of all optimized variables
                     optimizer.zero_grad()
                     # forward pass: compute predicted outputs by passing inputs to the model
                     output = model(data)
                     # calculate the batch loss
                     loss = criterion(output, target)
                     # backward pass: compute gradient of the loss with respect to model paramet
                     loss.backward()
                     # perform a single optimization step (parameter update)
                     optimizer.step()
                     # update training loss
                     train_loss = train_loss + (1 / (batch_idx + 1)) * (loss.data - train_loss)
                 ######################
                 # validate the model #
                 #####################
                 model.eval()
```

```
for batch_idx, (data, target) in enumerate(loaders['valid']):
                     # move to GPU
                     if use cuda:
                         data, target = data.to('cuda'), target.to('cuda')
                     ## update the average validation loss
                     # forward pass: compute predicted outputs by passing inputs to the model
                     output = model(data)
                     # calculate the batch loss
                     loss = criterion(output, target)
                     # update average validation loss
                     valid_loss = valid_loss + (1 / (batch_idx + 1)) * (loss.data - valid_loss)
                 # print training/validation statistics
                 print('Epoch: {} \tTraining Loss: {:.6f} \tValidation Loss: {:.6f}'.format(
                     epoch,
                     train_loss,
                     valid_loss
                     ))
                 ## TODO: save the model if validation loss has decreased
                 if valid_loss <= valid_loss_min:</pre>
                     print('Validation loss decreased ({:.6f} --> {:.6f}). Saving model ...'.fc
                     valid_loss_min,
                     valid_loss))
                     torch.save(model.state_dict(), save_path)
                     valid_loss_min = valid_loss
             # return trained model
             return model
In [314]: # train the model
          model_scratch = train(21, loaders, model_scratch, optimizer_scratch,
                                criterion_scratch, use_cuda, 'mode11_scratch.pt')
          # load the model that got the best validation accuracy
          \#model\_scratch.load\_state\_dict(torch.load('model\_scratch.pt'))
Epoch: 1
                 Training Loss: 3.817332
                                                  Validation Loss: 3.994675
Validation loss decreased (inf --> 3.994675).
                                                Saving model ...
Epoch: 2
                 Training Loss: 3.767670
                                                  Validation Loss: 4.002237
Epoch: 3
                 Training Loss: 3.691598
                                                  Validation Loss: 4.006469
Epoch: 4
                 Training Loss: 3.652674
                                                  Validation Loss: 4.114274
Epoch: 5
                 Training Loss: 3.585432
                                                  Validation Loss: 4.027638
Epoch: 6
                 Training Loss: 3.527893
                                                  Validation Loss: 4.073727
Epoch: 7
                 Training Loss: 3.482253
                                                  Validation Loss: 4.027990
Epoch: 8
                 Training Loss: 3.416155
                                                  Validation Loss: 4.055351
                                                  Validation Loss: 3.963725
Epoch: 9
                 Training Loss: 3.377621
```

```
Validation loss decreased (3.994675 --> 3.963725). Saving model ...
                                                  Validation Loss: 4.006460
Epoch: 10
                  Training Loss: 3.324858
Epoch: 11
                  Training Loss: 3.275381
                                                  Validation Loss: 4.033025
Epoch: 12
                  Training Loss: 3.233689
                                                  Validation Loss: 4.005313
Epoch: 13
                  Training Loss: 3.190840
                                                  Validation Loss: 4.095656
Epoch: 14
                  Training Loss: 3.157285
                                                  Validation Loss: 4.290526
Epoch: 15
                  Training Loss: 3.136892
                                                  Validation Loss: 4.028389
Epoch: 16
                  Training Loss: 3.065481
                                                  Validation Loss: 4.106514
Epoch: 17
                  Training Loss: 3.014201
                                                  Validation Loss: 4.225411
Epoch: 18
                  Training Loss: 2.967736
                                                  Validation Loss: 4.007470
Epoch: 19
                  Training Loss: 2.947862
                                                  Validation Loss: 4.100077
Epoch: 20
                  Training Loss: 2.930635
                                                  Validation Loss: 4.169955
                                                  Validation Loss: 4.058319
Epoch: 21
                  Training Loss: 2.857903
In [33]: model_scratch.load_state_dict(torch.load('model_scratch.pt'))
1.1.13 Test the Model
In [315]: def test(loaders, model, criterion, use_cuda):
              # monitor test loss and accuracy
              test_loss = 0.
              correct = 0.
              total = 0.
              model.eval()
              for batch_idx, (data, target) in enumerate(loaders['test']):
                  # move to GPU
                  if use_cuda:
                      data, target = data.cuda(), target.cuda()
                  # forward pass: compute predicted outputs by passing inputs to the model
                  output = model(data)
                  # calculate the loss
                  loss = criterion(output, target)
                  # update average test loss
                  test_loss = test_loss + ((1 / (batch_idx + 1)) * (loss.data - test_loss))
                  # convert output probabilities to predicted class
                  pred = output.data.max(1, keepdim=True)[1]
                  # compare predictions to true label
                  correct += np.sum(np.squeeze(pred.eq(target.data.view_as(pred))).cpu().numpy()
                  total += data.size(0)
              print('Test Loss: {:.6f}\n'.format(test_loss))
              print('\nTest Accuracy: %2d%% (%2d/%2d)' % (
                  100. * correct / total, correct, total))
```

```
In [316]: # call test function
          test(loaders, model_scratch, criterion_scratch, use_cuda)
Test Loss: 3.990614
Test Accuracy: 13% (117/836)
   ## Step 4: Create a CNN to Classify Dog Breeds (using Transfer Learning)
   Create CNN to predict dog breeds but this time using transfer learning
In [35]: import numpy as np
         import torch
         import torchvision
         import torchvision.transforms as transforms
         import torch.optim as optim
         from torchvision import datasets
         use_cuda = torch.cuda.is_available()
         num workers = 0
         batch_size = 20
         transform = { 'train': transforms.Compose([transforms.RandomResizedCrop(224),
                                          transforms.RandomRotation(25),
                                         transforms.ToTensor(),
                                         transforms.Normalize(mean=[0.485, 0.456, 0.406],
                                         std=[0.229, 0.224, 0.225]),
                                        'valid':transforms.Compose([transforms.CenterCrop(224),
                                         transforms.ToTensor(),
                                         transforms.Normalize(mean=[0.485, 0.456, 0.406],
                                         std=[0.229, 0.224, 0.225])
                                         ]),
                                        'test':transforms.Compose([transforms.CenterCrop(224),
                                         transforms.ToTensor(),
                                         transforms.Normalize(mean=[0.485, 0.456, 0.406],
                                         std=[0.229, 0.224, 0.225])
                                         ])}
         dog_train = datasets.ImageFolder(root='/data/dog_images/train',transform=transform['tra
         dog_valid = datasets.ImageFolder(root='/data/dog_images/valid',transform=transform['val
         dog_test = datasets.ImageFolder(root='/data/dog_images/test',transform=transform['test'
         train_loader = torch.utils.data.DataLoader(dog_train, batch_size=batch_size, num_worker
         valid_loader = torch.utils.data.DataLoader(dog_valid, batch_size=batch_size, num_worker
```

1.1.14 (IMPLEMENTATION) Model Architecture

Use transfer learning to create a CNN to classify dog breed. Use the code cell below, and save your initialized model as the variable model_transfer.

```
In [36]: import torchvision.models as models
         import torch.nn as nn
         model_transfer = models.vgg19(pretrained=True) # load the model pretrained to save time
Downloading: "https://download.pytorch.org/models/vgg19-dcbb9e9d.pth" to /root/.torch/models/vgg
100%|| 574673361/574673361 [00:12<00:00, 44288126.06it/s]
In [37]: print(model_transfer.classifier)
Sequential(
  (0): Linear(in_features=25088, out_features=4096, bias=True)
  (1): ReLU(inplace)
  (2): Dropout (p=0.5)
  (3): Linear(in_features=4096, out_features=4096, bias=True)
  (4): ReLU(inplace)
  (5): Dropout(p=0.5)
  (6): Linear(in_features=4096, out_features=1000, bias=True)
)
In [38]: for x in model_transfer.features.parameters():
             x.requires_grad = False #stop the training from changing the weights of the feature
In [39]: # remove the last layer in the classifier
         model_transfer.classifier = nn.Sequential(*list(model_transfer.classifier.children())[:
In [40]: model_transfer.classifier
Out[40]: Sequential(
           (0): Linear(in_features=25088, out_features=4096, bias=True)
           (1): ReLU(inplace)
           (2): Dropout(p=0.5)
           (3): Linear(in_features=4096, out_features=4096, bias=True)
           (4): ReLU(inplace)
           (5): Dropout(p=0.5)
         )
```

```
In [41]: model_transfer.classifier.add_module("6", nn.Linear(4096,133)) # add new last layer wit
In [42]: model_transfer
Out [42]: VGG(
           (features): Sequential(
             (0): Conv2d(3, 64, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
             (1): ReLU(inplace)
             (2): Conv2d(64, 64, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
             (3): ReLU(inplace)
             (4): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1, ceil_mode=False)
             (5): Conv2d(64, 128, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
             (6): ReLU(inplace)
             (7): Conv2d(128, 128, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
             (8): ReLU(inplace)
             (9): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1, ceil_mode=False)
             (10): Conv2d(128, 256, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
             (11): ReLU(inplace)
             (12): Conv2d(256, 256, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
             (13): ReLU(inplace)
             (14): Conv2d(256, 256, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
             (15): ReLU(inplace)
             (16): Conv2d(256, 256, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
             (17): ReLU(inplace)
             (18): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1, ceil_mode=False)
             (19): Conv2d(256, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
             (20): ReLU(inplace)
             (21): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
             (22): ReLU(inplace)
             (23): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
             (24): ReLU(inplace)
             (25): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
             (26): ReLU(inplace)
             (27): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1, ceil_mode=False)
             (28): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
             (29): ReLU(inplace)
             (30): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
             (31): ReLU(inplace)
             (32): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
             (33): ReLU(inplace)
             (34): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
             (35): ReLU(inplace)
             (36): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1, ceil_mode=False)
           )
           (classifier): Sequential(
             (0): Linear(in_features=25088, out_features=4096, bias=True)
             (1): ReLU(inplace)
             (2): Dropout(p=0.5)
```

```
(3): Linear(in_features=4096, out_features=4096, bias=True)
    (4): ReLU(inplace)
    (5): Dropout(p=0.5)
    (6): Linear(in_features=4096, out_features=133, bias=True)
 )
)
```

Question 5: Outline the steps you took to get to your final CNN architecture and your reasoning at each step. Describe why you think the architecture is suitable for the current problem.

Answer: I choose VGG19 to do the dog's breed image classification, I stopped the grads from changing in the feature level, and I change the last fully-connected layer to predict 133 class instead of 1000 class.

1.1.15 Specify Loss Function and Optimizer

```
In [43]: criterion_transfer = nn.CrossEntropyLoss()
         optimizer_transfer = optim.SGD(model_transfer.classifier.parameters(), lr= 0.0025)
```

Epoch: 8

```
1.1.16 Train and Validate the Model
In [44]: if use_cuda:
            model_transfer = model_transfer.to('cuda')
        print(use_cuda)
True
In []: # train the model
        model_transfer = train(25, loaders, model_transfer, optimizer_transfer, criterion_trans
        # load the model that got the best validation accuracy (uncomment the line below)
        \# model\_transfer.load\_state\_dict(torch.load('model\_transfer.pt'))
Epoch: 1
                 Training Loss: 3.556074
                                                 Validation Loss: 1.790756
Validation loss decreased (inf --> 1.790756). Saving model ...
                 Training Loss: 1.952480
Epoch: 2
                                                 Validation Loss: 1.182509
Validation loss decreased (1.790756 --> 1.182509). Saving model ...
Epoch: 3
                 Training Loss: 1.585505
                                               Validation Loss: 1.038430
Validation loss decreased (1.182509 --> 1.038430). Saving model ...
Epoch: 4
                 Training Loss: 1.459008
                                               Validation Loss: 0.964366
Validation loss decreased (1.038430 --> 0.964366). Saving model ...
                Training Loss: 1.351333
Epoch: 5
                                                Validation Loss: 0.935441
Validation loss decreased (0.964366 --> 0.935441). Saving model ...
Epoch: 6
                 Training Loss: 1.319573
                                                 Validation Loss: 0.901578
Validation loss decreased (0.935441 --> 0.901578). Saving model ...
                 Training Loss: 1.275779
                                                Validation Loss: 0.888911
Epoch: 7
Validation loss decreased (0.901578 --> 0.888911). Saving model ...
                 Training Loss: 1.219185
                                                 Validation Loss: 0.879810
```

Validation loss decreased (0.888911 --> 0.879810). Saving model ...

```
Validation loss decreased (0.879810 --> 0.865470). Saving model ...
1.1.17 Test the Model
In [45]: model_transfer.load_state_dict(torch.load('model_transfer.pt'))
In [25]: test(loaders, model_transfer, criterion_transfer, use_cuda)
Test Loss: 0.915118
Test Accuracy: 74% (626/836)
In [296]: # list of class names by index, i.e. a name can be accessed like class_names[0]
          class_names = [item[4:].replace("_", " ") for item in dog_train.classes]
          def predict_breed_transfer(img_path):
              img = Image.open(img_path)
              transform = transforms.Compose([transforms.CenterCrop(224),
                                             transforms.ToTensor(),
                                             transforms.Normalize(mean=[0.485, 0.456, 0.406],
                                             std=[0.229, 0.224, 0.225])
                                             1)
              img = transform(img)
              img = torch.unsqueeze(img,0)
              if use_cuda:
                              img = img.to('cuda')
              output = model_transfer(img)
              _, pred = torch.max(output, 1)
              output = class_names[pred]
              return print(output.replace("'",""), end=" ")
```

Training Loss: 1.195473 Validation Loss: 0.865470

Step 5: Write your Algorithm

Write algorithm that's return the following:

- if a **dog** is detected in the image, return the predicted breed.
- if a **human** is detected in the image, return the resembling dog breed.
- if **neither** is detected in the image, provide output that indicates an error.

1.1.18 Write your Algorithm

Epoch: 9

```
plt.figure(figsize=(4,4))
plt.imshow(img)
plt.show()
if face_detector(img_path) == True:
    print ("A human face dedected, and it's looks like a",end=" "),predict_breed_trelif dog_detector(img_path) == True:
    print("A dog dedected in the image and, it's breed is", end=" " ), predict_breedelse:
    return print('The image has no human or dog in it.')
```

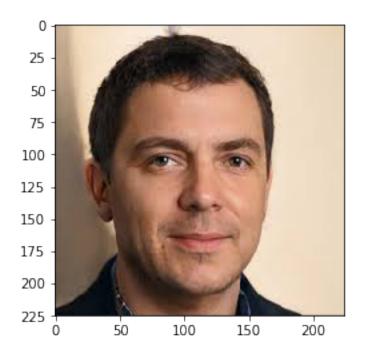
Step 6: Test Your Algorithm

1.1.19 Test Your Algorithm on Sample Images!

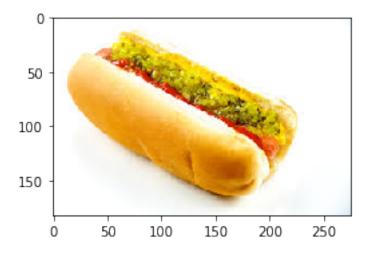
Question 6: Is the output better than you expected:)? Or worse:(? Provide at least three possible points of improvement for your algorithm.

Answer:

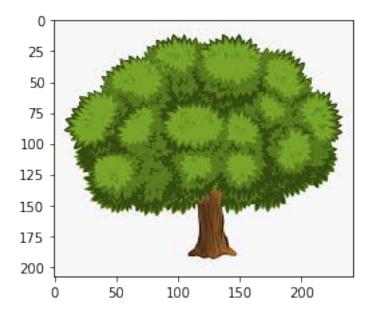
- The training time is very short, I would train it more if I want a better result
- I need more images of dogs and human to improve the accuracy, what I have know is very small dataset.
- Test other models and compare the accuracy and pick the best one for this task.



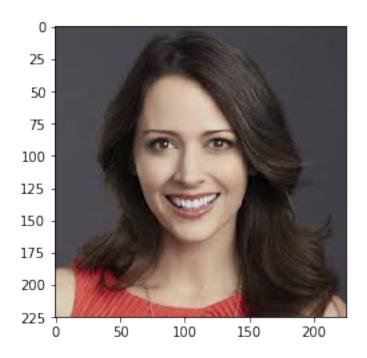
A human face dedected, and it's looks like a Basenji dog



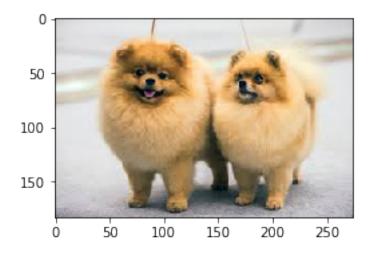
The image has no human or \log in it.



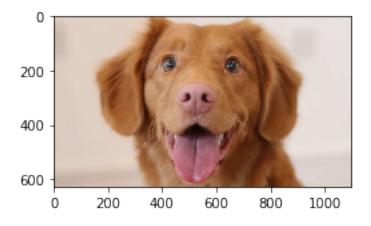
The image has no human or \log in it.



A human face dedected, and it's looks like a Papillon $\ensuremath{\operatorname{dog}}$



A dog dedected in the image and, it's breed is Pomeranian



A human face dedected, and it's looks like a Nova scotia duck tolling retriever dog