Box Intersection

```
In[1031]:= boxIntersection[θ_, size_, shape_, cornerRadius_] :=
           Module [{list, circleOrigin, lineEquations, edge, rx,
               ry, r, circleEquation, combinedEquation, x, y, R, cutRadius},
             If shape == True,
               (*Circle*)
               (*Easy: Just get the point on the circle at the given angle.*)
                     list = \left\{\frac{\text{size}}{2} + \frac{\text{size}}{2} \cos[\theta], \frac{\text{size}}{2} - \frac{\text{size}}{2} \sin[\theta]\right\};
                     (*Square*)
               (*Calculate if the point ends up on the top edge, corner, or right edge.*)
                     circleOrigin = {size - cornerRadius, 0 + cornerRadius};
                     lineEquations = \left\{\frac{\text{size}}{2} + r \cos[\theta], \frac{\text{size}}{2} + r \sin[\theta]\right\};
                     rx = Solve[0 == lineEquations[[2]], r][[1]];
                     ry = Solve[size == lineEquations[[1]], r][[1]];
                    edge = \left\{ \left( \frac{\text{size}}{2} - r * \text{Cos}[\theta] \right) / . rx, \left( \frac{\text{size}}{2} - r * \text{Sin}[\theta] \right) / . ry \right\};
                     If [edge[[1]] < circleOrigin[[1]],</pre>
                             (*On the top edge*)
                             list = {edge[[1]], 0};
                             If[edge[[2]] > circleOrigin[[2]],
                                      (*On the right edge*)
                                      list = {size, edge[[2]]};
                                      (*On the corner*)
                                      circleEquation =
                      (x - circleOrigin[[1]])^2 + (y - circleOrigin[[2]])^2 = cornerRadius^2;
                                      combinedEquation = circleEquation /.
                       \left\{x \rightarrow \frac{\text{size}}{2} + R \cos \left[\theta\right], y \rightarrow \frac{\text{size}}{2} - R \sin \left[\theta\right]\right\};
                                      cutRadius = R /. Solve[combinedEquation, R][[2]];
                                      list = \left\{\frac{\text{size}}{2} + \left(\text{cutRadius Cos}[\theta]\right), \frac{\text{size}}{2} - \left(\text{cutRadius Sin}[\theta]\right)\right\};
                                ];
                       ];
             ];
             list
            ];
```

```
In[441]:= circleOrigin = {size - cornerRadius, 0 + cornerRadius};
            lineEquations = \left\{\frac{\text{size}}{2} + r \cos[\theta], \frac{\text{size}}{2} + r \sin[\theta]\right\};
            rx = Solve[0 == lineEquations[[2]], r][[1]];
            ry = Solve[size == lineEquations[[1]], r][[1]];
            edge = \left\{ \left( \frac{\text{size}}{2} - r * \text{Cos}[\theta] \right) / . rx, \left( \frac{\text{size}}{2} - r * \text{Sin}[\theta] \right) / . ry \right\}
            circleEquation = (x - circleOrigin[[1]])<sup>2</sup> + (y - circleOrigin[[2]])<sup>2</sup> == cornerRadius<sup>2</sup>;
            combinedEquation = circleEquation /. \{x \to \frac{\text{size}}{2} + R \cos[\theta], y \to \frac{\text{size}}{2} - R \sin[\theta]\};
            cutRadius = R /. Solve[combinedEquation, R][[2]];
            list = \left\{\frac{\text{size}}{2} + \left(\text{cutRadius Cos}[\theta]\right), \frac{\text{size}}{2} - \left(\text{cutRadius Sin}[\theta]\right)\right\};
            output = \{FullSimplify[list[[1]], Assumptions \rightarrow assumptions], \}
                  FullSimplify[list[[2]], Assumptions → assumptions]}
             output = output /. \{ size (3 + Cos[2 \theta] + Sin[2 \theta]) \rightarrow a \};
            output = output /. \{-2 \text{ cornerRadius } (\cos[\theta] + \sin[\theta]) \rightarrow b\};
             output =
                  output /. \{(4 \text{ cornerRadius - size}) \text{ size + } (-2 \text{ cornerRadius + size})^2 \text{ Sin}[2 \theta] \rightarrow c\};
            output = output /. \{ size Cos[\theta] (Cos[\theta] - Sin[\theta]) \rightarrow d \};
            output = output /. \{2 \text{ cornerRadius Sin}[\theta] (\cos[\theta] + \sin[\theta]) \rightarrow e\}
Out[445]= \left\{\frac{\text{size}}{2} + \frac{1}{2} \text{ size } \text{Cot}[\theta], \frac{\text{size}}{2} - \frac{1}{2} \text{ size } \text{Tan}[\theta]\right\}
\text{Out}[450] = \left\{ \frac{1}{a} \left( \text{size} \left( 3 + \text{Cos} \left[ 2 \Theta \right] + \text{Sin} \left[ 2 \Theta \right] \right) + 2 \text{ Cos} \left[ \Theta \right] \left( -2 \text{ cornerRadius} \left( \text{Cos} \left[ \Theta \right] + \text{Sin} \left[ \Theta \right] \right) + 2 \text{ Cos} \left[ \Theta \right] \right) \right\} \right\}
                              \sqrt{\left(4\, {	t cornerRadius} - {	t size}
ight)\, {	t size} + \left(-\, 2\, {	t cornerRadius} + {	t size}
ight)^2\, {	t Sin}\, [\, 2\,\, 	heta\,]}\,\, 
ight)} ,
               \frac{1}{2}\left(\operatorname{size} \operatorname{Cos}\left[\theta\right]\left(\operatorname{Cos}\left[\theta\right]-\operatorname{Sin}\left[\theta\right]\right)+2\operatorname{cornerRadius}\operatorname{Sin}\left[\theta\right]\left(\operatorname{Cos}\left[\theta\right]+\operatorname{Sin}\left[\theta\right]\right)-\operatorname{Sin}\left[\theta\right]\right)\right)
                      Sin[\Theta] \sqrt{\left(4 \text{ cornerRadius - size}\right) \text{ size} + \left(-2 \text{ cornerRadius + size}\right)^2 Sin[2\Theta]}
Out[455]= \left\{\frac{1}{4}\left(a+2\left(b+\sqrt{c}\right)\cos\left[\theta\right]\right), \frac{1}{2}\left(d+e-\sqrt{c}\sin\left[\theta\right]\right)\right\}
```

Middle Point

```
 \begin{cases} \frac{\text{size}}{2.0}, & \frac{\text{size}}{2.0} + \text{size} * \text{radius} \end{cases} := \text{Module} [\{\}\}, \\ \begin{cases} \frac{\text{size}}{2.0}, & \frac{\text{size}}{2.0} + \text{size} * \text{radius} \end{cases}
```

Short Point

```
In[87]:= shortPoint[size_, radius_] := Module[{}},
               \left\{\frac{\text{size}}{2.0} - \text{size} * \text{radius}, \frac{\text{size}}{2.0}\right\}
```

Long Arm End Point

```
log(1359) := logArmEndPoint[\Theta_, size_, r_, boxIntersectionEndPoint_, middleEndPoint_] :=
       Module [{lineEquation, circleEquation, circleX, circleY, lineX, lineY, x, y},
         (*The line between the middle and long end points.*)
         lineEquation = y - middleEndPoint[[2]] ==
           boxIntersectionEndPoint[[2]] - middleEndPoint[[2]]
boxIntersectionEndPoint[[1]] - middleEndPoint[[1]]);
         (*The circle where the mid-point needs to lie.*)
         circleEquation = \left(x - \frac{\text{size}}{2.0}\right)^2 + \left(y - \frac{\text{size}}{2.0}\right)^2 = r^2;
         (*Calculate the intersection of the circle and line.*)
         circleX = NSolve[circleEquation, x][[2]];
         Print["CX: ", circleX];
         circleY = NSolve[circleEquation, y][[1]];
         Print["CY: ", circleY];
         lineY = NSolve[lineEquation /. circleX, y];
         Print["LY: ", lineY[[1]]];
         lineX = NSolve[lineEquation /. circleY, x];
         Print["LX: ", lineX[[1]]];
         Print["LA: " , {x /. lineX[[1]], y /. lineY[[1]]}];
         {x /. lineX[[1]], y /. lineY[[1]]}
```

```
ln[1416]:= Clear[x, y, x1, y1, x2, y2, lineEquation,
                    circleEquation, size, r, circleX, circleY, lineY, lineX]
                lineEquation = y - y1 = \frac{y2 - y1}{x2 - x1} (x - x1);
                 (*The circle where the mid-point needs to lie.*)
                circleEquation = \left(x - \frac{\text{size}}{2.0}\right)^2 + \left(y - \frac{\text{size}}{2.0}\right)^2 = r^2;
                 (*Calculate the intersection of the circle and line.*)
                circleX = NSolve[circleEquation, x][[2]];
                circleY = NSolve[circleEquation, y][[1]];
                lineY = NSolve[lineEquation /. circleX, y];
                lineX = NSolve[lineEquation /. circleY, x];
                assumptions = \left\{ \text{size} > 0, \ 0 < \theta < \frac{\pi}{2}, \ x1 > x2 > 0, \ y1 > y2 > 0 \right\};
                (*Note: The order of the solutions
                      to lineX is different when computed in this case.*)
                output = \{FullSimplify[x /. lineX[[2]], Assumptions \rightarrow assumptions],
                      FullSimplify[y /. lineY[[1]], Assumptions → assumptions]}
                output = output /.
                          \{1. \text{ `size x1}^2 - 2. \text{ `size x1 x2 + 1. ` size x2}^2 + 1. \text{ `size x1 y1 - 1. ` size x2 y1 } \rightarrow a1\};
                output = output /. \{2. \times 2 \text{ y1}^2 - 1. \times \text{size } x1 \text{ y2} + 1. \times \text{size } x2 \text{ y2} - 1. \times \text{size } x2 \text{ y2} + 1. \times \text{size } x2 \text{ y2} - 1. \times \text{size } x2 \text{ y2} + 1. \times \text{size } x2 \text{ y2} - 1. \times \text{size } x2 \text{ y2} + 1. \times \text{size } x2 \text{ y2} - 1. \times \text{size } x2 \text{ y2} + 1. \times \text{size } x2 \text{ y2} - 1. \times \text{size } x2 \text{ y2} + 1. \times \text{size } x2 \text{ y2} - 1. \times
                                    2. x1 y1 y2 - 2. x2 y1 y2 + 2. x1 y2^2 \rightarrow a2;
                output = output /. \{-16. (1. x1^2 - 2. x1 x2 + 1. x2^2 + 1. y1^2 - 2. y1 y2 + 1. y2^2) \rightarrow b\};
                output = output /. \{r^2 (-1. x1^2 + 2. x1 x2 - 1. x2^2) \rightarrow c1\};
                output = output /. \{size^2 (0.5 \times 1^2 - 1. \times 1 \times 2 + 0.5 \times 2^2) \rightarrow c2\};
                output = output /. \{1. x2^2 y1^2 - 2. x1 x2 y1 y2 + 1. x1^2 y2^2 \rightarrow d1\};
                output = output /. \{ size (1. x1 x2 y1 - 1. x2^2 y1 - 1. x1^2 y2 + 1. x1 x2 y2) \rightarrow d2 \};
                output = output /. \{c1 + c2 + d1 + d2 \rightarrow cd\};
                output = output /. \{x1 (4. y1 - 4. y2) y2 + x2 y1 (-4. y1 + 4. y2) \rightarrow e1\};
                output = output /.
                          {size(-2. x1^2 + x2(-2. x2 + 2. y1 - 2. y2) + x1(4. x2 - 2. y1 + 2. y2)) \rightarrow e2};
                output = output /. \{1. x1^2 - 2. x1 x2 + 1. x2^2 + 1. y1^2 - 2. y1 y2 + 1. y2^2 \rightarrow f\};
                output = output /.
                          \{0.5^{\circ} \text{ size x1 y1} - 0.5^{\circ} \text{ size x2 y1} - 1.^{\circ} \text{ x1 x2 y1} + 1.^{\circ} \text{ x2}^{2} \text{ y1} + 0.5^{\circ} \text{ size y1}^{2} \rightarrow \text{g1}\};
                output = output /. \{-0.5^{\circ} \text{ size x1 y2 + 1.} \times 1^{2} \text{ y2 + 0.5} \text{ size x2 y2 - }
                                    1. x1 x2 y2 - 1. size y1 y2 + 0.5 size y2^2 \rightarrow g2;
                output = output /. \{-4. \times 2^2 \text{ y1} - 4. \times 1^2 \text{ y2} + \text{x1} \times 2 (4. \times \text{y1} + 4. \times \text{y2}) \rightarrow \text{h1}\};
                output = output /.
                          size(-2. x1y1 + 2. x2y1 - 2. y1^2 + 2. x1y2 - 2. x2y2 + 4. y1y2 - 2. y2^2) \rightarrow h2;
                output = output /. \{r^2 (-1. y1^2 + 2. y1 y2 - 1. y2^2) +
                                    size^{2} (0.5 y1^{2} - 1. y1 y2 + 0.5 y2^{2}) \rightarrow i;
                output = output /. \{\text{size } (x1 (1. y1 - 1. y2) y2 + x2 y1 (-1. y1 + 1. y2)) \rightarrow j\}
```

```
\frac{1}{1. x1^{2}-2. x1 x2+1. x2^{2}+1. y1^{2}-2. y1 y2+1. y2^{2}}
0.5 (1. size x1^2 - 2. size x1 x2 + 1. size x2^2 + 1. size x1 y1 - 1. size x2 y1 + 1
                 2. x2 y1<sup>2</sup> - 1. size x1 y2 + 1. size x2 y2 - 2. x1 y1 y2 - 2. x2 y1 y2 +
                 2. x1 y2^2 + 0.5 \sqrt{-16.(1. x1^2 - 2. x1 x2 + 1. x2^2 + 1. y1^2 - 2. y1 y2 + 1. y2^2)}
                                              (r^2 (-1.x1^2 + 2.x1x2 - 1.x2^2) + size^2 (0.5x1^2 - 1.x1x2 + 0.5x2^2) + (0.5x1^2 - 1.x1x2 
                                                          1. x2^2 y1^2 - 2. x1 x2 y1 y2 + 1. x1^2 y2^2 + size (1. x1 x2 y1 - 1. x2^2 y1 - 1
                                                                             1. x1^2 y2 + 1. x1 x2 y2)) + (x1 (4. y1 - 4. y2) y2 + x2 y1 (-4. y1 + 4. y2) +
                                                          size (-2.x1^2 + x2(-2.x2 + 2.y1 - 2.y2) + x1(4.x2 - 2.y1 + 2.y2)))^2),
  1. x1^2 - 2. x1 x2 + 1. x2^2 + 1. y1^2 - 2. y1 y2 + 1. y2^2
         (0.5 \text{ size x1 y1} - 0.5 \text{ size x2 y1} -
                 1. x1 x2 y1 + 1. x2^2 y1 + 0.5 size y1^2 -
                 0.5 \text{ size } x1 \text{ y2} + 1. x1^2 \text{ y2} + 0.5 \text{ size } x2 \text{ y2} -
                 1. x1 x2 y2 - 1. size y1 y2 + 0.5 size y2^2 -
                 0.25\sqrt{\left(-4. x2^2 y1 - 4. x1^2 y2 + x1 x2 (4. y1 + 4. y2) + \right)}
                                        1. x1^2 y2^2 + r^2 (-1. y1^2 + 2. y1 y2 - 1. y2^2) + size^2 (0.5 y1^2 - 1. y1 y2 + 0.5 y2^2) +
                                                          size (x1 (1.y1 - 1.y2) y2 + x2 y1 (-1.y1 + 1.y2)))))
\frac{0.5 \left( a1 + a2 + 0.5 \sqrt{b cd + (e1 + e2)^2} \right)}{}, \frac{1. \left( g1 + g2 - 0.25 \sqrt{(h1 + h2)^2 + b (d1 + i + j)} \right)}{}
```

Testing

```
In[1442]:= Manipulate
         angle = \frac{\theta \pi}{180};
         {\tt Graphics} \lceil
             Thick, Black,
             If circle,
              \mathtt{Circle}\big[\big\{\frac{\mathtt{size}}{\mathtt{2.0}},\,\frac{\mathtt{size}}{\mathtt{2.0}}\big\},\,\frac{\mathtt{size}}{\mathtt{2.0}}\big],
              Rectangle \ [\{0,\,0\}\,,\, \{size,\,size\}\,,\, Rounding \ Radius \rightarrow corner \ Radius * size]
             PointSize[Medium],
             Point\left[\left\{\frac{size}{2.0}, \frac{size}{2.0}\right\}\right],
             Red, Point[boxIntersection[angle, size, circle, size * cornerRadius]],
             Green, Point[middlePoint[size, .135]],
             Blue, Point[shortPoint[size, .185]],
             Orange, Point[longArmEndPoint[angle, size, size.33, boxIntersection[
                  angle, size, circle, size * cornerRadius], middlePoint[size, .135]]]
           PlotRange → All,
           Axes → True
          , \{\{\theta, 36\}, 0, 90, 0.1\}, \{\text{size}, 1, 100, 1\},
          {circle, {True, False}}, {cornerRadius, 0, 0.5, 0.01}]
```

